

9408

II

The image shows the front cover of an old, heavily damaged book. The cover is primarily a light cream or off-white color, but it is covered in numerous dark brown and black spots, likely from mold or foxing. A large, irregular section of the top right corner is missing, revealing a yellowish-brown, textured material underneath, possibly a different layer of the binding or a repair. The edges of the cover are frayed and darkened, especially along the top and bottom. In the top left corner, there is a small, rectangular white paper label with the number '9408' printed in black, and the Roman numeral 'II' printed below it. The overall appearance is one of significant age and wear.



E HANDLU  
STANISŁAWA KOHLERA  
we Lwowie.

ae



II 1

Desy ty z abranie

z 14  
z 14

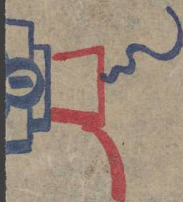
(z 13)

proszę z 13

teraz nam się



11A





<sup>These</sup>  
Nernst *Uly. Chem.* N. 185 p. 5-8  
D. M. Zurep) 202 E. 6

Georgi, *Volta* *Wied. Ann.* 57 p. 783

1852

Maxwell *Physic. Papers*

1

Helmholtz { *Wied. Ann.* 7 p. 337 (1878)  
= *Ses. Abhandl. I* p. 855  
Dorn *Wied. Ann.* 9 p. 513 (1880)  
10 p. 46 } *Stimmungstöne*  
etc.

Hardy *Journ. ph. Chem.* 4 p. 335 (1900)  
*Z. ph. Chem.* 33 p. 385



Stieltjes  $x$ :

$$x! = x^x e^{-x} \sqrt{2\pi x}$$



Jżeli gaz ma ciśnienie  $p$  i temp  $\theta$ ; jkżi prędkość zderzenia z normalną  
 gęstości  $\bar{p} = \frac{p}{R\theta}$  \* w jednym  $\text{mm}^3$ ?

N.p. prędkość gęstości  $\propto \bar{p}$ ?

$\propto \bar{p}$  będzie jkżi w owym  $\text{mm}^3$  hdy  $\propto \bar{N}$  cząstek

Prędkość zderzenia prędkość drabina znajduje się w owym  $\omega = W = \frac{W}{v}$

zderzenia  $v = \alpha \frac{\omega}{v}$  n znajduje się  $= \left(\frac{\omega}{v}\right)^n = \left(\frac{\omega}{v}\right)^{\alpha n \frac{\omega}{v}}$

Jżeli Nie chodzi o indywidualności tych drabiny, jkżi jakakolwiek kombinacja możliwa

to należy owe wyrażenie pomnożyć przez ilość możliwych kombinacji

bez post.  $\propto n \frac{\omega}{v}$  2 n elementów  $= \frac{n!}{(\alpha n \frac{\omega}{v})!}$

$$\text{Wzrost w ciele: } \left(\frac{\omega}{v}\right)^{\alpha n \frac{\omega}{v}} \cdot \frac{n \cdot (n-1) \cdot (n-2) \cdot \dots \cdot (n - \alpha n \frac{\omega}{v} + 1)}{1 \cdot 2 \cdot 3 \cdot \dots \cdot \alpha n \frac{\omega}{v}}$$

$$\left(\frac{n}{\alpha n \frac{\omega}{v}}\right) = \frac{n!}{(\alpha n \frac{\omega}{v})! (n - \alpha n \frac{\omega}{v})!} = \frac{\Gamma(n)}{\Gamma(\alpha n \frac{\omega}{v}) \cdot \Gamma(n - \alpha n \frac{\omega}{v})}$$

$$\frac{\alpha n \frac{\omega}{v} \sim 3, 2, 1}{(n - \alpha n \frac{\omega}{v} + 1) \dots (n - \alpha n \frac{\omega}{v} + 1 + \alpha n \frac{\omega}{v} - 1)} = \frac{\Gamma(n - \alpha n \frac{\omega}{v})}{(\alpha n \frac{\omega}{v})!}$$

$$W = \frac{\left(\frac{\omega}{v}\right)^{\alpha n \frac{\omega}{v}} (\alpha n \frac{\omega}{v})^n}{(\alpha n \frac{\omega}{v})^{\alpha n \frac{\omega}{v}} \Gamma(n - \alpha n \frac{\omega}{v})} = \frac{(\alpha n \frac{\omega}{v})^n}{(\alpha n)^{\alpha n \frac{\omega}{v}} \Gamma(n - \alpha n \frac{\omega}{v})}$$



$$W = \frac{\omega}{v} \frac{n}{\left(\frac{\omega v}{c}\right)^{\alpha + \frac{1}{2}} e^{-\frac{\omega v}{c}} \sqrt{\ln \frac{\omega v}{c}}} = \left(\frac{c}{\alpha}\right)^{\alpha \frac{\omega}{v}} \frac{1}{\sqrt{2\pi \alpha \frac{\omega}{v}}}$$

vize omazgje lisek czstotk --

$$W = \left(\frac{c}{\alpha}\right)^{\alpha} \frac{1}{\sqrt{2\pi \alpha}}$$

$$\frac{\partial W}{\partial v} = \left(\frac{c}{\alpha}\right)^{\alpha} \left[ \frac{1}{\sqrt{2\pi \alpha}} \log \frac{c}{\alpha} - \frac{\frac{1}{2}}{(\sqrt{2\pi \alpha})^3} \right] \cdot \frac{c^{\alpha}}{\alpha^{\alpha}} \cdot \frac{1}{\sqrt{2\pi \alpha}} = 0$$

$$\log \frac{c}{\alpha} = \frac{1}{4\pi v} = 1 - \log \alpha$$

$$\log \alpha = 1 - \frac{1}{4\pi v}$$

~~for~~

$$\int_0^{\infty} W d\alpha = \frac{c^{\alpha}}{\sqrt{2\pi \alpha}} \int \frac{d\alpha}{\alpha^{\alpha}} = \left[ -\frac{c^{\alpha}}{\sqrt{2\pi \alpha}} \frac{1}{\alpha^{\alpha-1}} \right]_0^{\infty}$$

$$\log \frac{c}{\alpha} = \frac{1}{4\pi v} + 1 = 1 - \log \alpha$$

joint value to ~~for~~  $\log \alpha = -\frac{1}{4\pi v}$

$$\alpha = e^{-\frac{1}{4\pi v}} \neq 1$$

naprawdę  $\alpha = 1$



Równie prawdy, jeżeli będzie  $n!$  Permutacji  $= \bar{W}_1$

z tych będzie  $\binom{n}{\alpha n \frac{w}{v}}$  takich par, których dane elementy znajdują się w określonych

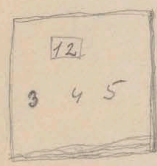
a to prawdy  $\bar{W}_1 \frac{n!}{\binom{n}{\alpha n \frac{w}{v}}}$  równa się zatem  $(\frac{w}{v})^v$

z czego otrzymamy się prawdy.  $\bar{W}_1$  dla jednej z pierwszych możliwych Permutacji:

$$\bar{W}_1 = \left(\frac{w}{v}\right)^v \frac{\binom{n}{\alpha n \frac{w}{v}}}{n!} = \left(\frac{w}{v}\right)^v \frac{1}{(\alpha n \frac{w}{v})! (n - \alpha n \frac{w}{v})!}$$

$$1 = \int_0^{\infty} W d\alpha = \int_0^{\infty} \left(\frac{w}{v}\right)^{\alpha m} \frac{1}{\sqrt{2\pi \alpha m}} d\alpha \quad \alpha m = v$$

$$= \frac{1}{m} \int_0^{\infty} \left(\frac{w}{v}\right)^v \frac{1}{\sqrt{2\pi v}} dv$$



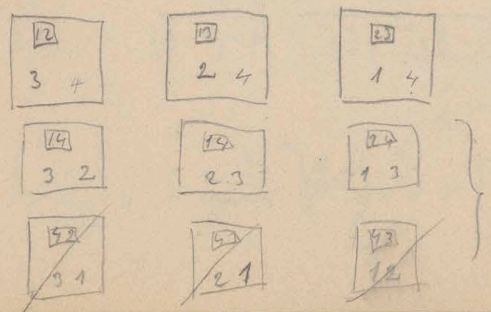
$\left(\frac{w}{v}\right)^v$  prawdy po utworzeniu pierwszych  $v$  elementów  
 składamy  $v+1$  ; prawdy, że ona ~~nie~~ będzie porażką:  $\frac{v-w}{v}$

teraz nam nie chodzi o identyfikację, ale już będzie

nie prawdy ich ~~nie~~ jeżeli kocham  $v$  być wzmogła ~~nie~~ wzmożona:  $\left(\frac{w}{v}\right)^v \frac{v-w}{v} \cdot (v+1)$

składamy  $v+2$  ; prawdy, że będzie wzmożona o nim wzmożona:  $\left(\frac{w}{v}\right)^v \left(\frac{v-w}{v}\right)^2 (v+1)$

możemy zamienić z  $v$  będącymi wzmożona



$$\left(\frac{w}{v}\right)^v \left(\frac{v-w}{v}\right)^2 (v+1)$$



(No.)  
 $N \text{ w } 1 \text{ cm}^3 = 21 \cdot 10^{18}$   
 przewidyw. że w jednym mm<sup>3</sup>:  $21 \cdot 10^{15}$   
 $W_0 = e^{21 \cdot 10^{15}}$

Przewidyw. że w każdej chwili  $\frac{nW}{v} = W_0$

zatem  
 że w każdej chwili  $v$ :  $W_0 = 1$

w  $v$ -chw:  $dW =$

Zobacz Pascal & Kestin p. 518:

$n = n$      $p = \frac{\omega}{v}$      $q = \frac{v-\omega}{v}$

$n = v$

$W = \frac{n!}{v! (n-v)!} \left(\frac{\omega}{v}\right)^v \left(\frac{v-\omega}{v}\right)^{n-v}$

$x! = \frac{x!}{e^x} \sqrt{2\pi x}$

$= \frac{\left(\frac{n}{e}\right)^n \sqrt{2\pi n}}{\left(\frac{v}{e}\right)^v \sqrt{2\pi v} \left(\frac{n-v}{e}\right)^{n-v} \sqrt{2\pi(n-v)}} \left(\frac{\omega}{v}\right)^v \left(1 - \frac{\omega}{v}\right)^{n-v}$

$= \frac{n^n}{v^v (n-v)^{n-v}} \sqrt{\frac{n}{2\pi v(n-v)}} \left(\frac{\omega}{v}\right)^v \left(1 - \frac{\omega}{v}\right)^{n-v}$

$= \frac{n^{n-v} \cdot n^v}{(n-v)^{n-v} v^v} \dots = \frac{1}{\left(1 - \frac{v}{n}\right)^{n-v} \left(\frac{v}{n}\right)^v} \sqrt{\frac{1}{2\pi v \left(1 - \frac{v}{n}\right)}}$

$\lim \left(1 - \frac{v}{n}\right)^n = \left(1 - \frac{v}{n}\right)^{\frac{n}{v} \cdot v} = e^v$

$= \left(\frac{n}{e v}\right)^v \frac{1}{\sqrt{v \cdot 2\pi}}$





$$\alpha = 1 + \delta$$

$$W = \frac{1}{[e(1+\delta)]^v e^{\frac{v}{1+\delta}} \sqrt{2\pi v}}$$

$$(1+\delta)^v = (1+\delta)^{\frac{1}{\delta} \cdot v\delta} = e^{v\delta}$$

$$= \frac{1}{e^{v+v\delta + \frac{v}{1+\delta}} \sqrt{2\pi v}} = \frac{1}{e^{2v} \sqrt{2\pi v}}$$

$$z! = \left(\frac{z}{e}\right)^z \sqrt{2\pi z}$$

$$\frac{\mu!}{n! (\mu-n)!} p^n q^{\mu-n} = \frac{\left(\frac{\mu}{e}\right)^\mu \sqrt{2\pi \mu}}{\left(\frac{n}{e}\right)^n \left(\frac{\mu-n}{e}\right)^{\mu-n} \sqrt{2\pi n} \sqrt{2\pi (\mu-n)}}$$

$$= \frac{\mu^\mu}{n^n (\mu-n)^{\mu-n} \sqrt{2\pi n} \sqrt{2\pi (\mu-n)}} = \frac{\mu^\mu}{n^{n-\mu} n^\mu (\mu-n)^{\mu-n}}$$

$$n < \mu$$

$$= \frac{\left(\frac{\mu}{n}\right)^\mu}{\left(\frac{\mu-n}{n}\right)^{\mu-n}} = \left(\frac{\mu}{\mu-n}\right)^\mu$$

$$= \mu^\mu \left(\frac{\mu}{n}\right)^n \left(\frac{n}{\mu-n}\right)^{\mu-n} \sqrt{2\pi n} \sqrt{2\pi (\mu-n)}$$

$$= \mu^\mu \left(\frac{\mu}{n}\right)^n \left(\frac{1}{\mu + \frac{n}{\mu-n}}\right)^{\mu-n}$$

$$\mu - n = h$$

$$\mu - n = \mu - \mu p + h$$

$$= \mu(1-p) + h$$

$$= \mu q + h$$



$$\frac{\partial}{\partial x} \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \nu \Delta^2 u$$

$$\frac{\partial}{\partial y} \quad u \frac{\partial v}{\partial x}$$

$$\frac{\partial u}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} + \frac{\partial w}{\partial x} \right) + u \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 w}{\partial x^2} \right) + \dots = -\frac{1}{\rho} \Delta^2 p$$

$$\left[ \left( \frac{\partial u}{\partial x} \right)^2 + \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \frac{\partial u}{\partial z} \frac{\partial w}{\partial x} \right] + \dots$$

$$\frac{1}{\rho} \Delta^2 p = \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 + 2 \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + 2 \frac{\partial v}{\partial z} \frac{\partial w}{\partial y} + 2 \frac{\partial w}{\partial x} \frac{\partial u}{\partial z}$$

$$2 \frac{\Delta^2 p}{\rho} = 2 \left[ \dots \right] + 4 \dots$$

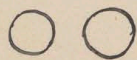
$$\left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 - \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right)^2$$

$$\xi^2$$

2 typy  $\Phi$  dla nichże nabożnych:

$$= \mu \left[ 2 \frac{\Delta^2 p}{\rho} + \xi^2 + \eta^2 + \zeta^2 \right]$$

Dwie kulki spadają w ciemnym mieszkaniu: czy one są przyciągane?



Jaka siła działa między nimi?

$$-\frac{c}{2} \left[ 1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3} \right] \omega^2 = \text{const}$$

$$\omega^2 = a \mid r=0$$

$$\frac{\partial}{\partial r} = -\frac{c}{2} \left[ +\frac{3}{2} \frac{a}{r^2} - \frac{3}{2} \frac{a^3}{r^4} \right] \Big|_{r=0}$$

$$\frac{\partial^2}{\partial r^2} = -\frac{c}{2} \left[ -\frac{3a}{r^3} + 3 \cdot 2 \cdot \frac{a^3}{r^5} \right] \Big|_{r=a} = -\frac{3c}{2a^2}$$

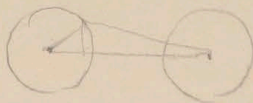
$$+ \text{const} = \omega^2 \left[ -\frac{3}{2} \frac{c}{a^2} \left( \frac{a-a}{2} \right)^2 + \dots \right]$$



$$u = A \frac{\partial \Omega}{\partial x^2} + B \left[ x \frac{\partial \chi}{\partial x} - \chi \right] + C \quad \left| \begin{aligned} &= -\frac{B}{6\mu r^3} (r^2 - 3xy) + \frac{2B}{3\mu r} + \frac{A}{r^5} (r^2 - 3xy) + C \\ v &= A \frac{\partial \Omega}{\partial x \partial y} + B x \frac{\partial \chi}{\partial y} \end{aligned} \right. \quad \left| \begin{aligned} &= \frac{B}{3\mu r^3} xy - \frac{3A}{r^5} xy \\ &= \frac{B}{3\mu r^3} xy - \frac{3A}{r^5} xy \end{aligned} \right.$$

$$-\frac{x}{r^3} = -\frac{1}{r^3} + \frac{3x^2}{r^5} = \frac{r^2 - 3x^2}{r^5}$$

$$\frac{1}{2} \left( \frac{1}{r} - \frac{x^2}{r^3} \right) \quad \chi = \frac{1}{r}$$



$$u = B \left( \frac{1}{r^3} - \frac{3x^2}{r^5} \right) + \frac{A}{2\mu} \left( \frac{1}{r} - \frac{x^2}{r^3} \right) + C \left( \frac{1}{r^3} - \frac{3x^2}{r^5} \right) + \frac{A_0}{\mu} \left( \right) + C$$

$$r_1 = a \quad r_2^2 = (b-x_1)^2 + y_1^2 \quad x_2 = x_1 \quad y_2 = y_1 - b \quad r_2 = r_1$$

$$\frac{\partial_2}{r_2^5} [r_2^2 - 3x_2^2] = \frac{\partial_2}{r_2^5} [y_1^2 + a^2 - 2(bx_1)^2]$$

$$\frac{\partial \varphi}{\partial z} = -4\pi b$$

$$\frac{\partial u}{\partial r} = \frac{1}{r^5} [x_1^2 + y_1^2 + (y_1 - b)^2 - 3x_1^2] = \frac{1}{r^5} [$$

$$\varepsilon = -\frac{\partial \varphi}{\partial r}$$

$$u = -\frac{\mu}{4\pi L} (r^2 - R^2)$$

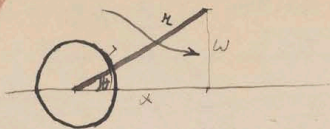
$$\frac{2\pi R}{\mu L} \int \varepsilon d\sigma = \frac{2\pi R^2 \mu}{4\pi \mu L} \frac{\partial \varphi}{\partial r} \Big|_R$$

$$\frac{\partial u}{\partial r} = -\frac{\mu R}{2\pi L}$$

$$= \frac{2\pi R^2 \mu}{4\pi \mu L} \frac{\partial \varphi}{\partial r} \Big|_R = \frac{E R^2 \mu}{L \mu b}$$

$$\text{Then } E = \frac{\mu R^2}{4\pi \mu} \left( \frac{\partial \varphi}{\partial r} \right)_R$$





$$u = -\frac{1}{\omega} \frac{\partial \psi}{\partial \omega}$$

$$v = \frac{1}{\omega} \frac{\partial \psi}{\partial x}$$

$$u = c \left[ 1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} - \frac{3}{4} \frac{a}{r^3} \left( 1 - \frac{a^2}{r^2} \right) x^2 \right]$$

$$v = -c \frac{3}{4} \frac{a}{r^3} \left( 1 - \frac{a^2}{r^2} \right) x \omega$$

$$u = c \left[ 1 - \frac{3}{4} \frac{a}{r} (1 + \cos^2 \theta) - \frac{1}{4} \frac{a^3}{r^3} (1 - 3 \cos^2 \theta) \right]$$

$$v = -\frac{3}{4} \frac{ac}{r} \left( 1 - \frac{a^2}{r^2} \right) \sin \theta \cos \theta$$

$$u = u_{r=a} + \frac{\partial u}{\partial r} \bigg|_{r=a} \rho + \dots$$

$$\frac{\partial u}{\partial r} = c \left[ \frac{3}{4} \frac{a}{r^2} (1 + \cos^2 \theta) + \frac{3a^3}{4r^4} (1 - 3 \cos^2 \theta) \right]$$

$$= \frac{3}{4} \frac{c}{a} \left[ 1 + \cos^2 \theta + 1 - 3 \cos^2 \theta \right] \bigg|_{r=a} = \frac{3}{2} \frac{c}{a} \sin^2 \theta$$

$$\frac{\partial v}{\partial r} = -\frac{3}{4} ac \sin \theta \cos \theta \left[ \left( 1 - \frac{a^2}{r^2} \right) \frac{-1}{r^2} + \frac{2a^2}{r^4} \right] = \frac{3}{4} \frac{c}{a} \left[ \frac{1 - \frac{3a^2}{r^2}}{r^2} \right]$$

$$= -\frac{3}{2} \frac{c}{a} \sin \theta \cos \theta$$

$$u = \frac{3}{2} \frac{c}{a} \sin^2 \theta \cdot \rho$$

$$v = -\frac{3}{2} \frac{c}{a} \sin \theta \cos \theta \cdot \rho$$

$$vel_{\perp} = \sqrt{u^2 + v^2} = \frac{3}{2} \frac{c}{a} \sin \theta \cdot \rho$$

$$vel_{\perp} = -(u \sin \theta + v \cos \theta) = -\frac{3}{2} \frac{c}{a} \sin \theta \cdot \rho (\sin^2 \theta + \cos^2 \theta)$$

$$= \frac{3}{2} \frac{c}{a} \sin \theta \cdot \rho$$

všecky prvek ~~je~~ v blízkosti povrchu rovnoběžný do něj

całkowity  
 potencjał elektryczny spowodowany do powierzchni (w punkcie p.p.  $\theta$ ):  
 (prosto do środka)

$$\vec{E} = \int u \vec{e}_r dp = -\frac{1}{4\pi} \int u \frac{\partial \varphi}{\partial \rho} dp$$

pot. elektryczny z grubości warstwy  
 nie uwzględniamy do  $d\theta$

$$= -\frac{1}{4\pi} \cdot \frac{3}{2} \cdot \frac{c}{a} \cdot r \cdot \theta \int \frac{\partial \varphi}{\partial \rho} \rho dp$$

$$= -\frac{\partial \varphi}{\partial \rho} \cdot \rho \Big|_0^\infty - \int \frac{\partial \varphi}{\partial \rho} dp = \varphi_i - \varphi_e$$

$$= \frac{3}{2} \cdot \frac{c}{a} \cdot \frac{\sin \theta}{4\pi} (\varphi_e - \varphi_i)$$

Wzrost pot. elektrycznej z  $\theta$  jest taki sam jak w przypadku:

$$\frac{3}{2} \cdot \frac{c}{a} \cdot \frac{\sin \theta}{4\pi} \frac{\varphi_e - \varphi_i}{\rho}$$

~~zatem zadanie~~ ~~całkowity~~ ~~potencjał~~ ~~zatem~~ ~~wzrost~~ ~~potencjału~~

$$J = \lambda \frac{\partial U}{\partial \lambda} = \lambda \frac{\partial U}{\partial \theta}$$

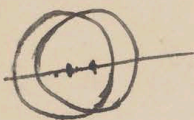
~~E = \frac{1}{2} \epsilon\_0 E^2~~

$$U = \int \frac{1}{2} \cdot \frac{3}{2} \cdot \frac{c}{a} \cdot \frac{\varphi_e - \varphi_i}{4\pi} a \int r \theta d\theta$$

Potencjał  $U$  na powierzchni:  $\frac{3}{2} \cdot \frac{c}{4\pi a} \cdot \frac{\varphi_e - \varphi_i}{2} \cos \theta = \rho$

Jaki system pól powstanie wskutek ~~potencjału~~  $U = A \cos \theta$ ?

$$\int \rho \cos \theta d\theta = \frac{\rho \sin \theta}{2}$$



$$U_1 = \frac{M_1}{r_1}$$

$$U_2 = -\frac{M_2}{r_2}$$

$$U = U_1 + U_2 = M_1 \left( \frac{1}{r_1} - \frac{1}{r_2} \right) = \frac{M_1}{r_2} \cos \theta$$

Wzrost  $J$  i  $M_1$ :  $\frac{M_1^2}{a^2} = \frac{3}{2} \cdot \frac{c}{4\pi a} (\varphi_e - \varphi_i)$

$$J_1 = \frac{2M_1}{r^2} \quad J_2 = \frac{\partial J}{\partial \dots} = \frac{2\lambda M_1}{r^2} \cos \theta$$

to będzie wyglądało  $U = \frac{3}{2} \cdot \frac{c}{4\pi a} (\varphi_e - \varphi_i) \frac{a^2}{r^2} \cos \theta$  ~~stąd~~  $J_2 = \frac{3}{2} \cdot \frac{c}{4\pi a} \frac{(\varphi_e - \varphi_i) \cos \theta}{a^2}$

$$\int a^2 \sin \theta d\theta J_2 =$$

Energia związana  $\sum i (U_{i0} - U_{-0}) =$

$$\frac{3ac}{4\pi} \frac{(\varphi_e - \varphi_i) \cos \theta}{2}$$



$$d\vec{r} = \frac{3}{2} \frac{c}{a} \frac{r_e - r_i}{4\pi} \omega \theta d\theta$$

$$W = \int_0^{\pi/2} 2\pi a \sin\theta \frac{3}{2} \frac{c}{a} \frac{r_e - r_i}{4\pi} \omega \theta \cdot 2 \frac{3}{2} \frac{c}{4\pi} \frac{r_e - r_i}{\lambda} \omega \theta d\theta$$

$$= 4\pi \left( \frac{3}{2} \frac{c}{4\pi} \right)^2 \frac{1}{\lambda} (r_e - r_i)^2 \int_0^{\pi/2} \underbrace{\omega \theta \omega \theta d\theta}_{= \frac{\omega^3 \theta}{3}}$$

$$= \frac{3c^2}{16\pi^2} \frac{(r_e - r_i)^2}{\lambda}$$

zatem opór przeciwny ruchowi  $\frac{W}{c} = \frac{3c}{\lambda} \left( \frac{r_e - r_i}{4\pi} \right)^2$

(który doświadczył do oporu tarcia):

opór tarcia:  $6\pi\mu ac$

$$\frac{1 - \frac{6x^4}{r^2} + \frac{9x^4}{r^4} + \frac{9x^2\omega^2}{r^4}}{\frac{9x^2}{r^2} + \frac{1 + \frac{3x^2}{r^2}}{r^2}} \quad v = \frac{Ca^2}{r^3} \sqrt{1 + \frac{3x^2}{r^2}}$$

$$C \frac{a^2}{r^2} \omega \theta = U = C \frac{a^2 x}{r^3}$$

$$\frac{dx}{d\omega} = - \frac{\frac{\partial U}{\partial \omega}}{\frac{\partial U}{\partial x}} = - \frac{\frac{\partial U}{\partial \omega}}{\frac{\partial U}{\partial x}}$$

$$U = \frac{Ca^2 x}{(x^2 + \omega^2)^{3/2}}$$

$$\frac{\partial U}{\partial x} = - \frac{Ca^2}{r^3} \left[ 1 - \frac{3x^2}{r^2} \right]$$

$$- \frac{3x\omega}{r^2} \frac{\partial x}{\partial \omega} + \left[ 1 - \frac{3x^2}{r^2} \right] \frac{\partial x}{\partial x} = 0$$

$$v = - \frac{\partial U}{\partial \omega} = + \frac{3Ca^2 x \omega}{r^5}$$

$$\frac{\partial x}{\partial \omega} = - \frac{3x}{r^2} \left( \frac{\partial x}{\partial \omega} \frac{\omega}{x} + \frac{\partial x}{\partial x} \frac{x}{\omega} \right) = 0$$

$$\left( 1 - \frac{3x^2}{r^2} \right) \frac{dx}{d\omega} + \frac{3x\omega}{r^2} = 0$$

$$\frac{dx}{d\omega} + \left( 1 - \frac{3x^2}{r^2} \right) \frac{dx}{d\omega} = 0$$

$$\left( 1 - \frac{3x^2}{r^2} \right) d\omega + \frac{3x\omega}{r^2} dx = 0$$

$$(\omega^2 - 2x^2) d\omega + 3\omega x dx = 0$$

$$\frac{\partial x}{\partial \omega} = \frac{\partial x}{\partial x}$$

$$\frac{\partial U}{\partial \omega} = \frac{3Ca^2}{r^5} \left( \omega - \frac{3x^2\omega}{r^2} \right) = \frac{3Ca^2}{r^5} (\omega^2 - 2x^2)$$

$$d\left(\frac{\omega^2}{r^3}\right) = \left(\frac{2\omega}{r^3} - \frac{3\omega^3}{r^5}\right) d\omega - \frac{3\omega^2}{r^5} dx$$

$$= \frac{\omega}{r^5} \left[ (2x^2 + 2\omega^2 - 3\omega^2) d\omega - 3\omega x dx \right]$$

$$= \frac{\omega}{r^5} \left[ 4\omega(2x^2 - \omega^2) d\omega - 3\omega x dx \right]$$

These lines are given by:  $\frac{\omega^2}{r^3} = \text{const}$

$$U = \frac{c a^2 x}{r^3} = \frac{c a^2}{r^2} \cos \theta$$

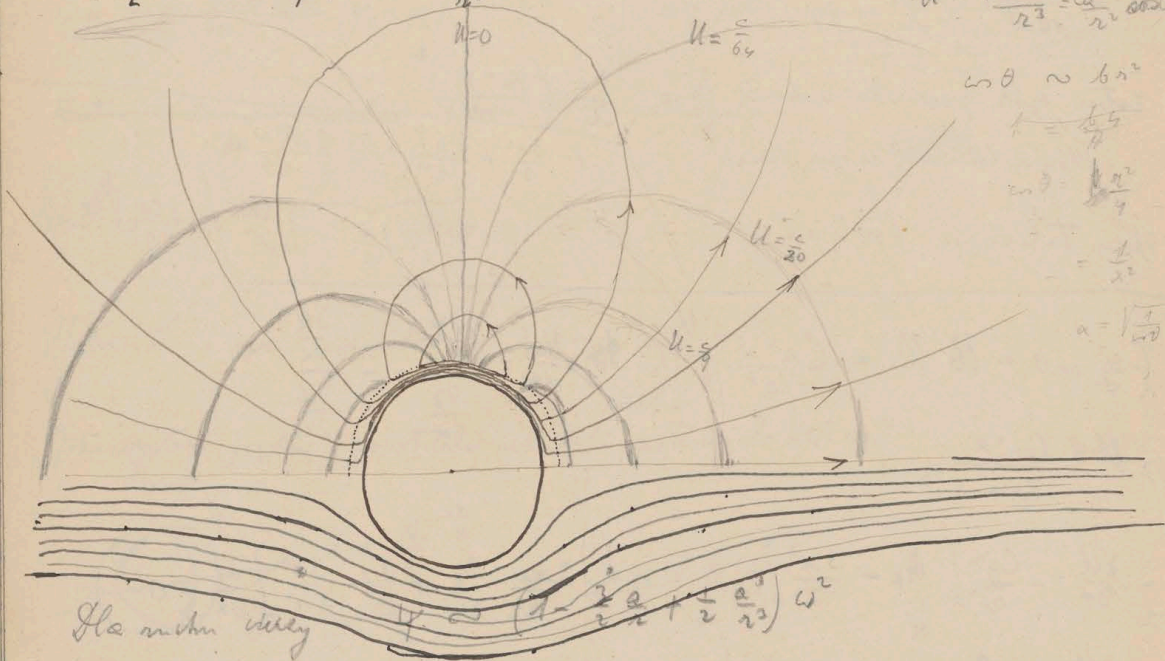
$$\cos \theta \sim \frac{1}{r^2}$$

$$r = \frac{1}{r^2}$$

$$\cos \theta = \frac{1}{r^2}$$

$$= \frac{1}{r^2}$$

$$r = \frac{1}{\cos \theta}$$



$$\text{The motion velocity } U \sim \left(1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3}\right) \omega^2$$

$$r = 2a \quad \left(1 - \frac{3}{2} \frac{1}{2} + \frac{1}{2} \frac{1}{8}\right) = 1 \cdot \frac{16 - 12 + 1}{16} = \frac{5}{16}$$

$$r = 3a$$

$$1 - \frac{1}{2} + \frac{1}{2} \frac{1}{27} = 1 - \frac{1}{2} + \frac{1}{54} = \frac{19}{27}$$

$$r = 4a$$

$$\psi = 1 \quad \omega^2 = \frac{16}{8} - \omega^2 = \frac{2}{15}$$



$$1 - \frac{3}{2} \frac{a}{r} \quad \text{typ. point} = \frac{v}{u} = \frac{-\frac{3}{4} \frac{ca}{r^3} \left(1 - \frac{a^2}{r^2}\right) x \omega}{-\frac{3}{4} \frac{ca}{r^3} \left(1 - \frac{a^2}{r^2}\right) x^2 + c \left(1 - \frac{1}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3}\right)}$$

$$= \frac{\omega}{x - \frac{4}{3ax} \frac{1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3}}{1 - \frac{a^2}{r^2}}} = \frac{\omega}{x - \frac{4r^3 - 3ar^2 - a^3}{3ax \left(1 - \frac{a^2}{r^2}\right)}}$$

$$\frac{m}{\omega^2} = 1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3}$$

$x=0 \quad r=a$	$\frac{m}{\omega^2} = 1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3}$	$m=1$	$m=\frac{1}{4}$	$m=\frac{1}{9}$
$r = 1a$	$\frac{m}{\omega^2} = 0$	$\omega = \sqrt{\frac{1}{4}} \approx 0.5$		
$r = \frac{3}{2}a$	$\frac{m}{\omega^2} = 1 - 1 + \frac{1}{2} \frac{8}{27} = \frac{4}{27}$	$1.3$	$0.87$	
$r = 2a$	$= 1 - \frac{3}{2} \frac{1}{2} + \frac{1}{2} \frac{1}{8} = \frac{16-12+1}{16} = \frac{5}{16}$	$1.8$	$0.9$	$0.6$
$r = 3a$	$= 1 - \frac{3}{2} \frac{1}{3} + \frac{1}{2} \frac{1}{27} = \frac{14}{27}$	$1.4$	$0.7$	$0.47$
$r = 4a$	$= 1 - \frac{3}{2} \frac{1}{4} + \frac{1}{2} \frac{1}{64} = \frac{81}{128}$	$1.26$	$0.63$	$0.42$

$$m=1$$



Przy przepływie prądu przez

$$U = \frac{\pi P R^4}{8 k L}$$

$$E = \frac{P \cdot 6 (\varphi_1 - \varphi_2)}{4 \pi k^2}$$

$$J = \frac{E R \pi}{6 L}$$

$$Praca = EJ = \frac{P^2 R^2 \cdot 6 (\varphi_1 - \varphi_2)^2}{4 k^2 L \cdot 4 \pi k^2} = U \cdot \frac{(\varphi_1 - \varphi_2)^2 \cdot 6 P}{2 R \pi^2 k^2}$$

$$\Delta \varphi = \frac{1.3 \cdot 10^9 \cdot 4 \cdot 10^8}{3 \cdot 10^{10}} = \Delta \varphi \cdot U$$

Wzrost ciśnienia dołatkowe, spowodowane elektrycznością:

$$\Delta p = \frac{(\varphi_1 - \varphi_2)^2 \cdot 6 P}{2 R \pi^2 k^2}$$

$$\Delta \varphi_1 \cdot \varphi_1 - \varphi_2 = 4 V = 4$$

$$\frac{10^3 \cdot 10^9}{(3 \cdot 10^{10})^2} = \frac{10^6}{10^{20}} = 10^{-14}$$

$$\frac{l^3}{t^4} \cdot \frac{l^2}{t} = \frac{l^5}{t^5}$$

Conventions:

$$S_{\text{to}} \text{ przy } = c \cdot 4 \pi \frac{\delta \varphi \cdot q}{2 \pi^2} = \frac{l}{t} \cdot \frac{l}{t^2} \cdot \frac{l^{\frac{1}{2}} m^{\frac{1}{2}}}{t} = \frac{l^{\frac{3}{2}} m^{\frac{1}{2}}}{t^{\frac{5}{2}}} = \frac{\text{ibid.}}{\text{cos}}$$

slow nie chce to zrobic  
a po numerze jak !!

$$H_f = \frac{10^4 \cdot 10^9}{9 \cdot 10^{20}} = \frac{1}{9 \cdot 10^7} \text{ (est)} \quad \tau = \frac{6}{1.17} \cdot 10^{16}$$

$$\frac{4 \cdot 6 \cdot 10^{-8} \cdot 10^{16}}{1.17} =$$

$$\frac{4 \cdot 6}{1.17} \cdot 10^8 \text{ (Hf =)}$$

4.16

$$6 \cdot 10^8$$

$$\frac{1.3 \cdot 4.7 \cdot 4 \cdot 10^{18}}{3.1 \cdot 3.24} \cdot \frac{1}{4 \cdot 10^{20}} =$$



$$I_{H=1} = 10^{16} \cdot \frac{11111.6}{1.17} = 4 \cdot 10^8 = \frac{4 \cdot 10^8 \cdot 10^{-14}}{9} = \frac{4 \cdot 10^{-6}}{9} \text{ (CSS)}$$

$$k = 0.018$$

$$\frac{4\pi (0.018) \cdot 2.2}{\frac{4 \cdot 10^{-7} \cdot 10^6 \cdot 1.3}} =$$

$$\frac{1}{\epsilon} 10^9 = 2.5$$

$$\tau = \frac{10^9}{2.5} = 4 \cdot 10^8 \text{ (H=1)}$$

$$\mu \cdot \epsilon \cdot H = 10^{-4} \frac{\text{Ohm}}{\text{cm}} = \frac{10^{-15}}{9} \text{ (CSS)}$$

$$= 1.1 \cdot 10^{-16} \text{ (CSS)}$$

$$\frac{9\pi \cdot 2.2 \cdot 0.00032}{9 \cdot 2.2 \cdot 0.01} = 0.2$$

$$\frac{9\pi \cdot 2.2 \cdot 0.18}{1.3 \cdot 1.8} = \frac{9 \cdot 2.2 \cdot 0.18}{1.3 \cdot 1.8} = 1.9$$

$$\begin{array}{r} 1 \quad 0.033.21 \quad 0.000244.441 \\ 0.696 \quad \underline{663} \quad 976 \\ 0.11 \quad \underline{1076} \\ 180 \end{array}$$

$$4\pi \mu = \pi \cdot \frac{2}{1.3} = 6$$

$$\frac{4\pi \cdot \frac{1.78}{1.80} \cdot 2.113}{4.65 \cdot 10^{-8} \cdot 1.33 \cdot 10^8} = \frac{3.14 \cdot 2.11}{1.16 \cdot 1.33} = \frac{3.14 \cdot 2.11}{1.5} = 4$$

$$\frac{\Delta P}{P} = \frac{(V_1 - V_2)^2 \cdot \delta}{2 R^2 \pi \cdot \gamma}$$

$$V_1 - V_2 = 4V = \frac{4}{300} \text{ (CSS)}$$

$$\delta = \frac{4}{9} \cdot 10^{-7} = 4.6 \cdot 10^{-8}$$

$$\gamma = 0.010$$

$$R = 0.2294 \text{ mm}$$

$$= \left( \frac{4}{300 \cdot 0.0229 \cdot 3.14} \right)^2 \frac{4.6 \cdot 10^{-8}}{2 \cdot 0.01}$$

$$= \left( \frac{4}{3.14 \cdot 3 \cdot 10^{-23}} \right)^2 2.3 \cdot 10^{-4} = \left( \frac{4}{2.2} \right)^2 \cdot 2.3 \cdot 10^{-4} = \frac{4}{1.21} \cdot 2.3 \cdot 10^{-4} = 0.8 \cdot 10^{-3}$$



Kelhi

$$\frac{\text{Opin elektrostat.}}{\text{Opin tarva}} = \frac{\frac{3a}{\lambda} \left( \frac{\varphi_2 - \varphi_1}{4\pi} \right)^2}{6\pi \mu a c} = \frac{\frac{1}{\lambda} \left( \frac{\varphi_2 - \varphi_1}{4\pi} \right)^2}{2\pi \mu a c \eta}$$

Ny.  $\varphi_2 - \varphi_1 = 4V = \frac{4}{300} \text{ CGS}$

$$\frac{1}{\lambda} = 6 = 4.6 \cdot 10^{-8}$$

$$\mu \eta = 0.010$$

$$\frac{4.6 \cdot 10^{-8} \cdot \left( \frac{4}{300 \cdot 4.344} \right)^2}{2.314 \cdot 0.01 \cdot a} = \frac{2.9 \cdot 10^{-6} \cdot \left( \frac{1}{1000} \right)^2}{3.14 \cdot a}$$

Wks. opid. = opin tarva jnli  $a = 10^{-12} \text{ cm} !$

Ny. opid. = opin tarva jnli:

$$\left( \frac{1}{4.300 \cdot 3.14} \right)^2 \cdot \frac{4.6 \cdot 10^{-8}}{0.01 \cdot a^2} = 1 = \left( \frac{1}{0.942} \right)^2 \cdot \frac{4.6 \cdot 10^{-12}}{a^2}$$

$$a^2 = \frac{4.6}{0.88} \cdot 10^{-12} = 5 \cdot 10^{-12}$$

$$a \neq 2 \cdot 10^{-6} \text{ cm} = 2 \cdot 10^{-2} \mu = 0.02 \mu$$



Robota zlozenie  $U = \frac{M \cos \theta}{r^2}$  stupena

10

na pred a krumku  $z$ :  $J_z = 2\lambda \frac{M \cos \theta}{r^3}$  na površini:  $J_a = 2\lambda \frac{M \cos \theta}{a^3}$

zatem całkujemy pod od  $\theta = 0$  do  $\theta$ :

$$\int 2\lambda^2 \pi \cos \theta d\theta \quad \frac{2\lambda M \cos \theta}{a^3} = \frac{4\pi\lambda M}{a} \int_0^\theta \underbrace{\cos \theta}_{\frac{1}{4} \int_0^\theta 2 \cos \theta d\theta = \frac{1 - \cos 2\theta}{4} = \frac{2 \sin^2 \theta}{4}} d\theta$$

$$= \frac{2\pi\lambda M}{a} \sin^2 \theta$$

to musimy przechodzić przez równoleżnik  $\theta$

zatem natężenie pada prosto 1 cm odległości równoleżnika:  $\frac{2\pi\lambda M \sin^2 \theta}{a} = \frac{\lambda M \sin^2 \theta}{a^2}$

jeżeli to ma być równe  $\frac{3}{2} \frac{c}{a} \sin^2 \theta \frac{p_c - p_i}{4\pi}$

to musimy być:  $M = \frac{3}{2} \frac{ac}{\lambda} \frac{p_c - p_i}{4\pi}$  zatem:  $U = \frac{3}{2} \frac{ac}{\lambda} \frac{p_c - p_i}{4\pi} \frac{\cos \theta}{r^2}$

Praca całkujemy:

$$\frac{\partial U}{\partial z} = \frac{3}{2} \frac{c}{\lambda a^2} \frac{p_c - p_i}{4\pi} \cos \theta$$

$$W = 2 \int_0^{\frac{\pi}{2}} 2\lambda^2 \pi \cos \theta d\theta \cdot U_{a0} \lambda \frac{\partial U_{a0}}{\partial z}$$

$$= 4\pi^2 \lambda \frac{3}{2} \frac{c}{\lambda a} \frac{p_c - p_i}{4\pi} \cdot \lambda \frac{3c}{\lambda a^2} \frac{p_c - p_i}{4\pi} \int_0^{\frac{\pi}{2}} \underbrace{\cos^2 \theta}_{\frac{1}{3}} d\theta = \frac{1}{3}$$

$$= \frac{9c^2 (p_c - p_i)^2}{8\pi a \lambda} \cdot \frac{1}{3} = \frac{3c^2 (p_c - p_i)^2}{8\pi a \lambda}$$

$$\frac{W}{c} = \Delta f = \frac{3c (p_c - p_i)^2}{8\pi a \lambda}$$

$$\frac{\partial f}{\partial \lambda} = \frac{3 (p_c - p_i)^2}{8\pi a \lambda} = \frac{(p_c - p_i)^2}{16\pi^2 a^2 \lambda} = \left( \frac{p_c - p_i}{4\pi} \right)^2 \frac{1}{\lambda a^2}$$

$$= \left( \frac{p_c - p_i}{4\pi} \right)^2 \frac{1}{\lambda a^2}$$



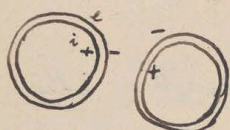
Jaki bezpośredni wpływ ładunku elektrycznego?

jużi wiemy, że pot. dana to ładunek prop.  $a^2$

zatem  $U \sim \frac{a^2 \cdot a^2}{r^2}$  najniższym  $k$  malarce  $= 2a$

$\therefore f \sim a^2$  zatem przy zmniejszeniu rozmiarów ciała zmniejszą się też  
wpływy. Zatem teoretycznie w rachubę wchodzić nie może.

Teraz, że, 'Dyppelschert' zatem z takim ładunkiem prądem równym



$Energie = \frac{1}{2} \sum \phi V$

$\phi_i = -\phi_e$  zatem wpływ na zero,  $U = 0$

N pole elektryczne rozważamy:

gdzie  $\phi_i$  i  $\phi_e$  były stałe, więc, żeby składowe było  $= 0$ ,

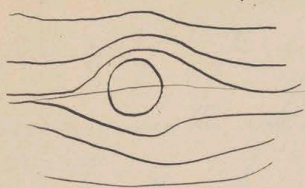
toż, jeżeli  $\phi_e$  ma być stałe, musi być stałe i  $\phi_i$  w drugim

$$\left. \begin{aligned} \left( \nabla^2 u \frac{\partial u}{\partial x} \right) &= \frac{\partial}{\partial x} (u \nabla^2 u) - u \nabla^2 \frac{\partial u}{\partial x} \\ \frac{\partial}{\partial x} \left( \frac{1}{4\pi} u \nabla^2 u - \frac{1}{2} \right) &= u \nabla^2 \frac{\partial u}{\partial x} - \frac{1}{2} \nabla^2 u \\ \frac{\partial}{\partial y} ( &= u \nabla^2 \frac{\partial u}{\partial y} - \frac{1}{2} \nabla^2 u \end{aligned} \right\} \begin{aligned} \frac{\partial u}{\partial y} &= -\frac{3}{2} c \frac{a^3 x y}{r^5} \\ \frac{\partial u}{\partial z} &= -\frac{3}{2} c \frac{a^3 x z}{r^5} \\ \frac{\partial u}{\partial x} &= -\frac{3}{2} c \frac{a^3 x^2}{r^5} \end{aligned}$$

$n = a \left\| \frac{\partial u}{\partial x} = \frac{3}{2} c \left[ 1 - \frac{x^2}{a^2} \right] \right\|$



Jaki wykład przy drabaniu zarysujemy tylko  $X$



$$\nabla^2 u = 0$$

$$\frac{\partial u}{\partial r} \Big|_{r=a} = 0$$

$$r^2 = x^2 + y^2$$

$$\frac{\partial u}{\partial r} = \frac{x}{r} \frac{\partial u}{\partial x} + \frac{y}{r} \frac{\partial u}{\partial y}$$

$$\frac{\partial u}{\partial r} \Big|_{r=a} = \frac{x}{a} \frac{\partial u}{\partial x} + \frac{y}{a} \frac{\partial u}{\partial y}$$

$$u = c x \left[ 1 + \frac{a^3}{2r^3} \right] = c r \cos \theta \left[ 1 + \frac{a^3}{2r^3} \right]$$

$$\frac{\partial u}{\partial x} = c \left[ 1 + \frac{a^3}{2r^3} \right] - \frac{3cx^2 a^3}{2r^5} \Big|_{r=a} = c$$

~~Właściwość~~

$$\frac{\partial u}{\partial r} = c \cos \theta \left[ 1 + \frac{a^3}{2r^3} \right] - c r \cos \theta \frac{3a^3}{2r^4} = c \cos \theta \left[ 1 + \frac{a^3}{2r^3} - \frac{3a^3}{2r^3} \right] \Big|_{r=a} = 0$$

$$= c \cos \theta \left[ 1 - \frac{a^3}{r^3} \right]$$

Na powierzchni kuli:

$$\frac{\partial u}{\partial \theta} = \frac{-1}{a} c r \sin \theta \left[ 1 + \frac{a^3}{2r^3} \right] \Big|_{r=a} = -\frac{3c}{2} \sin \theta$$

$$\frac{\partial u}{\partial \theta} = c \cos \theta \left[ \frac{3a^3}{2r^4} \right] \Big|_{r=a} = \frac{3c \cos \theta}{a}$$

Opisane zadanie:

Ruch cząstki:

$$X - \frac{\partial \mu}{\partial x} = -k \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$X = \mu \nabla^2 u \in \mathcal{G}$$

$\mathcal{G}$  = przestrzeń wektorowa

(zamiast tego możemy użyć wektora  
składowych)

opisane pole:

$$\bar{X} = \varepsilon \frac{\partial \mu}{\partial x} =$$

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial x} - \frac{\partial \mu}{\partial x} = -k \nabla^2 u$$

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial y} - \frac{\partial \mu}{\partial y} = -k \nabla^2 u$$

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial z} - \frac{\partial \mu}{\partial z} = -k \nabla^2 u$$

$$\frac{\partial}{\partial x}$$

$$\frac{\partial}{\partial y}$$

$$\frac{\partial}{\partial z}$$

~~Właściwość~~

$$\nabla^2 u = \frac{1}{4\pi} \left( (\nabla^2 u)^2 + \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} + \dots \right)$$

$$\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} = 0$$

$\nabla^2 u = 0$  wynika z ogólnego warunku, że na powierzchni



Wir wandeln perinschreibung:

$$\frac{\partial^2 U}{\partial r^2} = \frac{\partial}{\partial r} \left\{ c \cos \theta \left[ 1 - \frac{a^3}{r^3} \right] \right\}$$

$$= c \cos \theta \frac{3a^3}{r^4} \Big|_{r=a} = \frac{3c \cos \theta}{a}$$

$$\frac{\partial^3 U}{\partial r^3} = -c \cos \theta \frac{12a^3}{r^5} \Big|_{r=a} = -\frac{12c \cos \theta}{a^2}$$

$$\text{Zunächst } U = U_0 + \left( \frac{\partial U}{\partial r} \right)_a \rho + \frac{\rho^2}{1 \cdot 2} \left( \frac{\partial^2 U}{\partial r^2} \right)_a + \dots$$

$$= \frac{\rho^2}{1 \cdot 2} \frac{3c \cos \theta}{a} - \frac{\rho^3}{1 \cdot 2 \cdot 3} \frac{12c \cos \theta}{a^2} - \dots$$

$$U = \frac{3c \cos \theta}{2a} \rho^2 - \frac{2c \cos \theta}{a^2} \rho^3 + \dots$$

Bed. v. Krümmungsänderungen (pro cm oberer Krümmung):

$$\lambda \frac{\partial U}{\partial (2\theta)} \Big|_{r=\cos \theta} = \frac{\lambda}{2} \frac{\partial U}{\partial \theta} = -\lambda c \sin \theta \left[ 1 + \frac{a^3}{2r^3} \right]$$

$$= -\lambda c \sin \theta \left[ 1 + \dots \right]$$

$$= -\frac{3}{2} \lambda c \sin \theta \left[ 1 + \frac{a^3}{a^3} \right]$$



Wizn zwich mechanizmy c pprzodyjacy przed

$$i = \frac{3}{2} \frac{c}{a} \frac{\varphi_c - \varphi_i}{4\pi} \sin \theta \quad [\text{pro c na dystansie } r \text{ od osi } \theta]$$

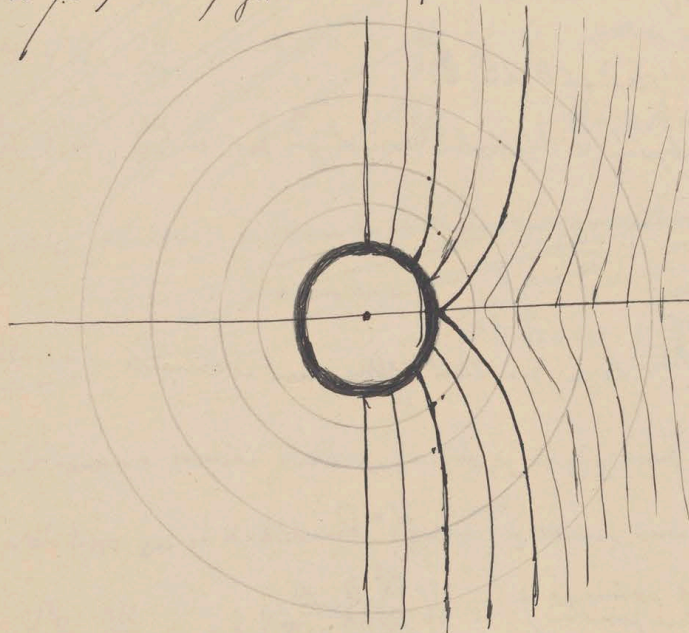
zgodzi puzie to uklad potencjalow.

$$-\frac{3}{2} \alpha \lambda \sin \theta = \frac{3}{2} \frac{c}{a} \frac{\varphi_c - \varphi_i}{4\pi} \sin \theta$$

$$\therefore \alpha = - \frac{c}{a} \frac{\varphi_c - \varphi_i}{4\pi \lambda}$$

$$\therefore U = - \frac{c}{a} \frac{\varphi_c - \varphi_i}{4\pi \lambda} r \cos \theta \left[ 1 + \frac{a^3}{2r^3} \right]$$

Albo tu obrotami: jizeli mamy



$$r = a \quad \cos \theta = \frac{m}{\frac{3}{2}} = \frac{2}{3} m$$

$$r = \frac{3}{2} a \quad \cos \theta = \frac{18m}{37} + \frac{5}{10}$$

$$r = 2a \quad \cos \theta = \frac{8m}{17} = 0.47$$

$$r = 3a \quad \cos \theta = \frac{18m}{55} + \frac{1}{3} m$$

$$r = 4a \quad \cos \theta = \frac{1}{4} m$$

Wiz. składowi zadani:

Trólini potu yd  $U$ :

$$\Delta U = 0 \quad \text{a na powierzchni kuli} \quad \text{dane wartości dla } \frac{\partial U}{\partial r}$$

Ponieważ przed 2 kuli przepływa do czołgu 2 dany zinteg

$$\frac{d}{dt} \frac{d}{dt} = \frac{1}{a} \frac{d}{dt} = \frac{3}{2} \frac{c}{a^2} \frac{r_2 - r_1}{4\pi} \cos \theta$$

Przed tym czołgu uśredniał:  $\frac{d}{dt} \frac{d}{dt} = \frac{3}{2} \frac{c}{a^2} (r_2 - r_1) \sin^2 \theta$

Wówczas  $\frac{dT}{dt} = \frac{3}{2} \frac{c}{a^2} (r_2 - r_1) \sin^2 \theta \cos \theta \, d\theta$

podobnie jak podaliśmy:  $\frac{dT}{dt} = \frac{3}{2} \frac{c}{a^2} \sin^2 \theta \, d\theta$

zatem w tym ujęciu v kierunku normalnego po  $u^2$ :

$$\frac{3c}{4\pi} \frac{r_2 - r_1}{a^2} \cos \theta = \lambda \left( \frac{\partial U}{\partial r} \right)_{r=a, \theta}$$

Wiz. zadani znowy  $U$  dane na kuli  $\frac{\partial U}{\partial r}$  jak w poprzednim

$$\left( \frac{\partial U}{\partial r} \right)_{r=a} = m \cos \theta \quad \text{a u wórk. } r \rightarrow \infty \quad U = 0$$

toż  $U$  jest n.p.: (jakieś p.m.d.t.) :  $U = \frac{M \cos \theta}{r^2}$

$$\lambda \left( \frac{\partial U}{\partial r} \right)_{r=a} = - \frac{2\lambda M \cos \theta}{a^3} = \frac{3c}{4\pi} \frac{r_2 - r_1}{a^2} \cos \theta$$

$$M = - \frac{3ca}{8\lambda} \frac{r_2 - r_1}{a^2}$$

zatem:  $U = - \frac{3ca}{2\lambda} \frac{r_2 - r_1}{4\pi} \frac{\cos \theta}{r^2}$



$$u = u_0 + u_1$$

$$-\frac{\partial u}{\partial x} = -k \nabla^2 u_0$$

$$-\frac{\partial u}{\partial y} = -k \nabla^2 u_0$$

$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial x} = -k \nabla^2 u_1$$

$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial y} = -k \nabla^2 u_2$$

$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial z} = -k \nabla^2 u_3$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial u_0}{\partial x} + \frac{\partial v_0}{\partial y} = 0$$

$$\frac{\partial u_1}{\partial x} + \frac{\partial v_1}{\partial y} = 0$$

~~$$\int u \nabla^2 v = \int u \nabla^2 v dV = \int \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} dV$$~~

Przyjmujemy teraz dla  $u$ : superpozycję

rozkładu przy działaniu zewnętrznego pola  $X$   
i rozkładu pt. wewnątrz podłoża:

$$u = A \times \left[ 1 + \frac{a^3}{2r^3} \right] + u_0$$

przekładki składowe: w kierunku promienia  $(r = \text{const})$   $\frac{\partial u}{\partial r}$

$$\frac{\partial u}{\partial r} = 0 \quad \frac{\partial u}{\partial \theta} = 0 \quad \int \nabla^2 u \cdot dV = \int \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) dV = \int \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} dV$$

Jedną naszą uwagę przenieśmy na warunki na granicy między  
to właściwie jest o' x kierunku stykamy  $\frac{\partial u}{\partial r}$   $\frac{\partial u}{\partial \theta}$

$$\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial r} = -k \nabla^2 u_1 \quad \text{w kierunku } r \left( \frac{\partial u}{\partial r} \right) \frac{\partial u}{\partial r}$$

A całkowite to  $\int \rho dV \frac{\partial u}{\partial r}$   $\frac{\partial u}{\partial r}$

$$\frac{\partial^2 u}{\partial r^2} = \rho \frac{\partial u}{\partial r} - \int \frac{\partial u}{\partial r} = \rho - \rho_0$$

$$= -\frac{3}{2} A \sin \theta \left[ 1 + \frac{a^3}{r^3} \right]$$

$\frac{\partial u}{\partial r}$  takie przybliżenie stało się  $\rho$

$$\text{zatem } \int \rho dV \frac{\partial u}{\partial r} = \frac{\partial u}{\partial r} \frac{\rho^2}{2} \neq 0$$

$$\frac{3}{2} A \sin \theta \frac{\rho_0 - \rho_1}{4\pi} = k (\rho_1 - \rho_0) + \rho \frac{\partial u}{\partial r}$$

zatem to stało się  $-\rho_0 k$   
zatem  $\lim_{\rho \rightarrow 0} \rho \frac{\partial u}{\partial r} = 0$  [co kiedyś było naszymi  $\rho$  a posteriori  
i składowymi]



To odnosi się do wartości potencjałowej, bo w naszym przypadku

$$z=0 \quad \text{zatem } \nabla^2 u_1 = 0$$

$$k \nabla u = \frac{\partial f}{\partial x} \text{ etc.}$$

Zadanie będzie takie ~~jak~~ znaleźć taką funkcję z danymi na granicach

$$\text{Kiedy potrzebujemy: } v_0|_{z=a} = \frac{3}{2} \frac{A}{k} \sin \theta \frac{\varphi_1 - \varphi_0}{4a}$$

$$\text{t.j. } u = -\frac{3}{2} \frac{A}{k} \frac{\varphi_1 - \varphi_0}{\pi} \left(1 - \frac{x^2}{a^2}\right)$$

$$\sin \theta \cos \theta \sin \varphi = \frac{4x}{a^2}$$

$$\sin \theta \cos \theta \sin \varphi =$$

$$v = \frac{xy}{a^2}$$

$$w = \frac{xz}{a^2}$$

$$\text{Próbując znaleźć: } u = \frac{M}{2\mu a^3} (z^2 + x^2) + \frac{N}{2a^5} (z^2 - 3xy) + C \quad \left| \begin{array}{l} \frac{3C}{2} \left(1 - \frac{x^2}{a^2}\right) \\ -\frac{3}{2} C \frac{xy}{a^2} \end{array} \right.$$

$$v = \frac{M}{2\mu a^3} xy - \frac{3N}{2a^5} xy$$

$$w = \frac{M}{2\mu a^3} xz - \frac{3N}{2a^5} xz$$

$$\text{Dla } z=a: \quad \frac{M}{2\mu a^3} (a^2 + x^2) + \frac{N}{a^5} (a^2 - 3x^2) + C = -\frac{3}{2} \frac{A}{k} \left(1 - \frac{x^2}{a^2}\right)$$

$$\frac{M}{2\mu a^3} - \frac{3N}{a^3} = \frac{3}{2} \frac{A}{k}$$

$$\frac{M}{2\mu a^3} + \frac{N}{a^3} = -\frac{3}{2} \frac{A}{k}$$

$$\frac{4N}{a^3} + C = -3 \frac{A}{k}$$

$$\left| \frac{4M}{2\mu a^3} + 3C = -2 \frac{3}{2} \frac{A}{k} \right.$$



$$M = - \frac{3A}{2} \frac{\varphi_0 - \varphi_i}{4n} + c \mu a$$

$$N = - \left[ \frac{3A}{2} \frac{\varphi_0 - \varphi_i}{4n} + c \right] \frac{Q^2}{4} \quad 14$$

~~W~~ Wzrostek  $c = 0$   $r = \infty$

$$M = 0$$

$$N = \frac{c a^3}{2}$$

$$u = -\frac{3}{4} A \frac{\varphi_0 - \varphi_i}{4n} \frac{(r^2 + x^2) Q}{r^3} - \frac{3}{4} A \frac{\varphi_0 - \varphi_i}{4n} \frac{4(r^2 - 3x^2) Q^3}{r^5}$$

$$u = -\frac{3}{4} A \frac{\varphi_0 - \varphi_i}{4n} \frac{a}{r^3} \left[ 1 + \frac{x^2}{r^2} + \frac{a^2}{r^2} - \frac{3a^2 x^2}{r^4} \right] \quad \left\| \frac{\partial u}{\partial n} = \dots = \frac{1}{r^2} \left[ 1 + \frac{2a^2 x^2}{r^2} - \frac{4.3a^2 x^2}{r^4} \right] \right.$$

$$v = -\frac{3A}{4} \frac{\varphi_0 - \varphi_i}{4n} \frac{Q x y}{r^3} \left[ 1 - \frac{3a^2}{r^2} \right]$$

$$w =$$

Jaka odkształcenie będzie miało kółko w środku cięwej nienakładanej?

Dajmy nam to że odkształcenie wynikać może z przemieszczenia  $q$

to odkształcenie to przemieszczenie w tym samym kierunku i odkształcenie:

kółko nakładające w cięwej która w środku ma ruch  $-q$

$$A \text{ na powierzchni kółka } v_s/r = \frac{3}{2} \frac{A}{k} r \theta \frac{\varphi_i - \varphi_0}{4n}$$

i odkształcenie wypadkowe  $= 0$

Chodzi o to o odkształcenie  $p$



$$ux + vy + uz = \frac{M}{2\mu r^2} \underbrace{[x(r^2 + x^2) + xy^2 + xz^2]}_{2r^2x} + \frac{N}{r^5} \underbrace{(r^4 - 3x^2 - 3xy^2 - 3xz^2)}_{-2r^2x} + cx$$

$$= \frac{M}{\mu} \frac{x}{r} - \frac{2N}{r^3} \frac{x}{r^2} + cx$$

$$p = p_0 + \frac{M}{2\mu} \frac{x}{r^2}$$

$$u = \frac{M}{2\mu} \left( \frac{1}{r} + \frac{x^2}{r^3} \right) + \frac{N}{r^5} \left( \frac{1}{r^3} - \frac{3x^2}{r^5} \right) + c$$

$$r \frac{\partial}{\partial r} = -\frac{M}{2\mu} \left( \frac{1}{r^2} + \frac{3x^2}{r^3} \right) - N \left( \frac{3}{r^3} - \frac{15x^2}{r^5} \right) + \text{etc}$$

$$+ \left( \frac{M}{2\mu} \frac{1}{r^3} - \frac{3N}{r^5} \right) r \frac{d(x^2)}{dr}$$

$$\underbrace{\quad}_{= x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} + z \frac{\partial}{\partial z} = 2x^2}$$

$$= \frac{M}{2\mu} \left[ -\frac{1}{r^2} - \frac{3x^2}{r^3} + \frac{2x^2}{r^3} \right] + 3N \left[ -\frac{1}{r^3} + \frac{5x^2}{r^5} - \frac{2x^2}{r^5} \right]$$

$$r \frac{du}{dr} = -\frac{M}{2\mu} \left[ \frac{1}{r} + \frac{x^2}{r^3} \right] - 3N \left[ \frac{1}{r^3} - \frac{3x^2}{r^5} \right]$$

$$-u = -\frac{M}{2\mu} [ \dots ] - N [ \dots ] - c$$

$$\left. \begin{aligned} \mu \left[ \dots \right] &= -\frac{M}{2\mu} \left[ \frac{1}{r} + \frac{x^2}{r^3} \right] - 3N \left[ \frac{1}{r^3} - \frac{3x^2}{r^5} \right] - c \\ \mu \frac{\partial}{\partial x} (ux + vy + uz) &= \frac{M}{2\mu} \left[ \frac{1}{r^2} - \frac{x^2}{r^3} \right] - 2N \left[ \frac{1}{r^3} - \frac{3x^2}{r^5} \right] + c \end{aligned} \right\}$$

$$-px = -p_0x - \frac{M}{2\mu} \frac{x^2}{r^3}$$

$$r \frac{\partial}{\partial x} = -p_0x - 3M \frac{x^2}{r^3} - 6N \left[ \frac{1}{r^3} - \frac{3x^2}{r^5} \right]$$



$$p_{rx} \Big|_{r=a} = -p_0 \frac{x}{a} - \frac{6N\mu}{a^2} - 3 \frac{x^2}{a^2} \left[ M - \frac{6N\mu}{a^2} \right]$$

$$= -p_0 \frac{x}{a} + \frac{3\mu}{2a} \left[ 3 \frac{A}{\mu} \frac{\varphi_0 - \varphi_i}{4\pi} + c \right] - 3 \frac{x^2}{a^2} \frac{\mu}{a} \left[ -\frac{3}{2} \left( \frac{A}{\mu} \frac{\varphi_0 - \varphi_i}{4\pi} \right) + \frac{3}{2} \frac{3A}{\mu} \frac{\varphi_0 - \varphi_i}{4\pi} \right]$$

$$p_{rx} = -p_0 \frac{x}{a} + \frac{3}{2} \left[ 3 \frac{A}{a} \frac{\varphi_0 - \varphi_i}{4\pi} + c \frac{\mu}{a} \right] - \frac{3x^2}{a^3} 2A \frac{\varphi_0 - \varphi_i}{4\pi}$$

$$P = \iint p_{rx} dS = 2\pi$$

$$= -p_0 \cos \theta + \frac{3}{2a} \left[ 3A \frac{\varphi_0 - \varphi_i}{4\pi} + c\mu \right] - 6 \cos^2 \theta \frac{A}{a} \frac{\varphi_0 - \varphi_i}{4\pi}$$

$$P_x = 2\pi a^2 \int_0^\pi \sin \theta d\theta \cdot p_{rx}$$

$$= 2\pi a^2 \left\{ \frac{3}{2a} \left[ 3A \frac{\varphi_0 - \varphi_i}{4\pi} + c\mu \right] - 6 \frac{A}{a} \frac{\varphi_0 - \varphi_i}{4\pi} \frac{2}{3} \right\}$$

$$P_x = 2\pi a^2 \left[ 5A \frac{\varphi_0 - \varphi_i}{4\pi} + 3c\mu \right]$$

Jeżeli to ma być = 0 to wynika:  $c = - \frac{5A \frac{\varphi_0 - \varphi_i}{4\pi}}{3\mu}$

zatem 1). pytkon' niechciana od a

2). prop. A

3). odwr. prop.  $\mu$  zatem zależy przy podst. temp.

$$c = b A$$

$$i = A \lambda$$

$$J = A \lambda q$$

$$= b \frac{E}{l}$$

$$Q = i q t = \frac{E}{e} \lambda q t$$

$$d = ct = b \frac{E}{e} t = b \frac{Q}{\lambda q} = \frac{b}{\lambda q} \cdot Q$$

więc droga przesłana przez ogniwe równa jest ilości elektr. [mnoż.  $E$ , mnoż.  $l$ ]  
[dzieli  $q$ ]

$$c = b \frac{J}{\lambda q} = \frac{b}{\lambda q} \cdot J$$

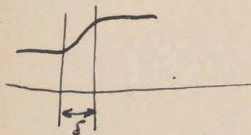
tak samo

porówn. Wronki, 503  
Ginske U. An-113 (1869)

Elektr. Doppelschichten

$$\int_0^{\delta} \nabla^2 V dx = V_2 - V_1 = \int_0^{\delta} 4\pi \epsilon dx$$

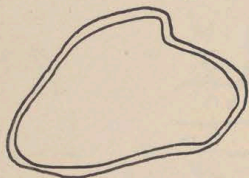
$$\int \epsilon dx = 6\delta$$



Można sobie wyobrazić  $6 = \frac{1}{4\pi} \frac{V_2 - V_1}{\delta}$

na dwóch zbieżach oddzielonych przez  $\delta$

~~jak to będzie gdy kątowania jest większe i większe~~



$$W = \frac{1}{2} \oint \phi dz = \frac{1}{2} \oint \left( \frac{\partial V}{\partial x} \right)^2$$

pro cm<sup>2</sup> powierzchni:

$$W = \frac{1}{2} \frac{1}{4\pi} \frac{(V_2 - V_1)^2}{\delta}$$

jakie jest to stąd równie mniej słowno.

α dla wody

= 80 C.SS.

dla wody / niekiedy trochę więcej



$$V_L - V_1 = N_1 \cdot \frac{4}{300} V = \frac{4}{300}$$

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$$80 = \frac{1}{8 \pi \epsilon_0}$$

$$S = \frac{1}{8 \pi} \frac{1}{80} \left( \frac{4}{300} \right)^2$$

$$= \frac{1}{31} \left( \frac{1}{600} \right)^2 = \frac{1}{31 \cdot 36} 10^{-6} = 10^{-7} \text{ cm}$$

To ni mniej by podobne identyczne

do n. p. dodanie  $\frac{1}{2}$  do Noll zmiana  $\varphi$  i  $\varphi_c$  od 0.1 V do 2.7 V. podlegają  
a wtedy wezmą inną. Doświadczenia!

W każdym razie należy przyjąć, że w tym przypadku, jeżeli mamy pewną ilość

Przy kondens. lub strumieniu emulacji poruszająca emulacja się gromadzi  
wtedy wykona pewną ilość.  
zatem energia elektryczna.

ilosci. S6 z jednej i z drugiej strony się wypracowuje



Przebieg i ewolucja zeta przed obrotami  
do mij

To stężenie się zwróci do każdej powierzchni:

Wtedy dla  $x, y, z$  powierzchni z normalnie

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial x} = -\mu \nabla^2 u + \frac{\partial u}{\partial x}$$

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial y} = -\mu \nabla^2 u + \frac{\partial u}{\partial y}$$

~~###~~

$$\frac{1}{4\pi} \nabla^2 u \cdot \frac{\partial u}{\partial z} = -\mu \nabla^2 u + \frac{\partial u}{\partial z}$$

$$\nabla^2 u = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2}$$

to samo

$$\frac{\partial u}{\partial x} \text{ i } \frac{\partial u}{\partial y} \text{ może zmienne w obszarze}$$

$$\text{zatem } \int_0^{\delta} \nabla^2 u \frac{\partial u}{\partial x} \cdot z dz = \left| \frac{\partial u}{\partial x} \right| \int_0^{\delta} \nabla^2 u \cdot z dz$$

! tutaj wartość!

Pierwszą równość do pow. bo  $u_0 = 0$   $v_0 = 0$   $w_0 = 0$

$$u = z \left( \frac{\partial u}{\partial x} \right)_0 + \frac{z^2}{2} \left( \frac{\partial^2 u}{\partial x^2} \right)_0$$

$$v = z \left( \frac{\partial v}{\partial z} \right)_0 + \frac{z^2}{2} \left( \frac{\partial^2 v}{\partial z^2} \right)_0$$

$$w = z \left( \frac{\partial w}{\partial z} \right)_0 + \frac{z^2}{2} \left( \frac{\partial^2 w}{\partial z^2} \right)_0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$z \left( \frac{\partial^2 u}{\partial x^2} \right)_0 + \frac{z^2}{2} \left( \frac{\partial^3 u}{\partial x^2 \partial z} \right)_0 + z \left( \frac{\partial^2 v}{\partial z^2} \right)_0 + \frac{z^2}{2} \left( \frac{\partial^3 v}{\partial y \partial z^2} \right)_0 + \frac{\partial w}{\partial z} + z \left( \frac{\partial^2 w}{\partial z^2} \right)_0 = 0$$

z tego wynika również z dost. m. że tutaj  $\left( \frac{\partial w}{\partial z} \right)_0 = 0$

Prócz tego:

$$\frac{\partial}{\partial x} \left( \frac{\partial u}{\partial z} \right)_0 + \frac{\partial}{\partial y} \left( \frac{\partial v}{\partial z} \right)_0 + \left( \frac{\partial^2 w}{\partial z^2} \right)_0 = 0$$

$$\frac{\partial}{\partial x} \left( \frac{\partial^2 u}{\partial z^2} \right)_0 + \frac{\partial}{\partial y} \left( \frac{\partial^2 v}{\partial z^2} \right)_0 + \left( \frac{\partial^3 w}{\partial z^3} \right)_0 = 0$$



$$\nabla^2 u = 2 \left[ \frac{\partial^2}{\partial x^2} \left( \frac{\partial u}{\partial z} \right) + \frac{\partial^2}{\partial y^2} \left( \frac{\partial u}{\partial z} \right) \right] + \frac{z^2}{2} \left[ \frac{\partial^2}{\partial x^2} \left( \frac{\partial^2 u}{\partial z^2} \right) + \frac{\partial^2}{\partial y^2} \left( \frac{\partial^2 u}{\partial z^2} \right) \right] + \left( \frac{\partial^2 u}{\partial z^2} \right)$$

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więc dla dotychczasowej metody 2:

$$\nabla^2 u = \left( \frac{\partial^2 u}{\partial z^2} \right)$$

W ten  
miedobedroś!

$$\frac{1}{4\pi} \frac{\partial u}{\partial x} \int_0^{\delta} \frac{\partial u}{\partial z^2} z dz = -\mu \int_0^{\delta} \left( \frac{\partial^2 u}{\partial z^2} \right) z dz + \frac{\partial u}{\partial x} \int_0^{\delta} z dz$$

$\frac{\partial u}{\partial z} z - \int \frac{\partial u}{\partial z} dz$

Sobowaz, tam gdzie  $\frac{\partial u}{\partial z} = 0$

$$\frac{1}{4\pi} \frac{\partial u}{\partial x} (u_i - u_a) = \mu \frac{(u_a - u_i)}{z} = \mu \frac{u_a}{z}$$

dla dot. metody 2:

$$\int z \frac{\partial^2 u}{\partial z^2} dz = z \frac{\partial u}{\partial z} - u$$

$$\frac{1}{4\pi} \frac{\partial u}{\partial y} (u_i - u_a) = \mu \frac{(u_a - u_i)}{z} = \mu \frac{u_a}{z} + \left( \frac{\partial^2 u}{\partial z^2} \right)$$

$$\int \nabla^2 u z dz = \frac{z^2}{2} \left( \frac{\partial^2 u}{\partial z^2} \right) + \frac{z^3}{3} \left[ \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left( \frac{\partial u}{\partial z} \right) \right] + \frac{z^4}{2 \cdot 4} \left[ \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left( \frac{\partial^2 u}{\partial z^2} \right) \right]$$



$$\frac{1}{4n} \nabla^2 u \frac{\partial u}{\partial x} = -k \nabla^2 u, \quad \left| \frac{\partial}{\partial x} \nabla^2 u \text{ behor tyko f. (2)} \right.$$

$$\frac{1}{4n} \nabla^2 u \frac{\partial u}{\partial y} = -k \nabla^2 u, \quad \left| \frac{\partial}{\partial y} \right.$$

$$\frac{1}{4n} \nabla^2 u \frac{\partial u}{\partial z} = -k \nabla^2 u,$$

$$\frac{1}{4n} \left[ \nabla^2 u \left( \nabla^2 u - \frac{\partial^2 u}{\partial z^2} \right) + \frac{\partial}{\partial z} \left( \nabla^2 u \frac{\partial u}{\partial z} \right) \right] = 0$$

$$\nabla^2 u \left( \nabla^2 u \right)^2 + \frac{\partial}{\partial z} \left( \nabla^2 u \right) \frac{\partial u}{\partial z} = 0$$

$$\text{Angli.:} \quad \left( \frac{\partial^2 u}{\partial z^2} \right)^2 + \frac{\partial u}{\partial z} \cdot \frac{\partial^3 u}{\partial z^3} = 0$$

$$\frac{\partial}{\partial z} \left( \frac{\partial u}{\partial z} \frac{\partial^2 u}{\partial z^2} \right) = 0$$

$$u = \left( \frac{\partial u}{\partial \rho_0} \right) \rho$$

$$\frac{\partial u}{\partial z} \frac{\partial^2 u}{\partial z^2} = \text{const}$$

$$\frac{\partial}{\partial z} \left( \frac{\partial^2 u}{\partial z^2} \right) =$$

$$\frac{1}{4n} \int \left( \frac{\partial^2 u}{\partial z^2} \right) \left( \frac{\partial u}{\partial \rho_0} \right) \rho d\rho$$

$$\left( \frac{\partial u}{\partial z} \right)^2 = cz + g$$

$$i = \frac{1}{4n} \left( \frac{\partial u}{\partial \rho_0} \right) (\varphi_2 - \varphi_1)$$

$$\frac{\partial u}{\partial y} - \frac{\partial u}{\partial z} = a$$

$$-\left[ \varphi + \frac{r^2}{2} \frac{\partial \varphi}{\partial r} \right] - \left[ \varphi + \frac{r^2}{2} \frac{\partial \varphi}{\partial r} \right] = 2\varphi + r \frac{\partial \varphi}{\partial r} = a$$



Rozwiązaj zadania

$$u = u_0 + u_1$$

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$$\left\{ \begin{array}{l} -\frac{\partial u}{\partial x} = \mu \nabla^2 u_0 \\ -\frac{\partial u}{\partial y} = \mu \nabla^2 u_0 \\ -\frac{\partial u}{\partial z} = \mu \nabla^2 u_0 \end{array} \right\} \left\{ \begin{array}{l} \frac{\partial u}{\partial x} = -\mu \nabla^2 u_1 \\ \frac{\partial u}{\partial y} = -\mu \nabla^2 u_1 \\ \frac{\partial u}{\partial z} = -\mu \nabla^2 u_1 \end{array} \right\}$$

$$\frac{\partial u_0}{\partial x} + \frac{\partial u_0}{\partial y} + \frac{\partial u_0}{\partial z} = 0$$

$$\frac{\partial u_1}{\partial x} + \frac{\partial u_1}{\partial y} + \frac{\partial u_1}{\partial z} = 0$$

~~Stwierdzenie~~  $u_1 = v_1 = w_1 = 0$  na powierzchni kuli  $|x| = a$

$$\frac{\partial u}{\partial x} \text{ (dla } r \rightarrow \infty) = A \quad \frac{\partial u}{\partial y} = \frac{\partial u}{\partial z} = 0$$

$$u = A \times \left[ 1 + \frac{a^3}{2r^3} \right] \quad \text{tylko } f(r + \Delta r)$$

~~Stwierdzenie~~

Wiemy tylko tyle że  $\int_0^r \rho dp = \varphi_2 - \varphi_1$

$$\int_0^r \frac{\partial v}{\partial r} \rho dp = \frac{\partial v}{\partial p} \cdot \rho \Big|_0^r - \int_0^r \frac{\partial v}{\partial p} dp = \frac{\partial v}{\partial p} \Big|_0^r - v \Big|_0^r$$

$$2 \left[ \left( \frac{\partial v}{\partial r} \right)_0 + 2 \left( \frac{\partial v}{\partial r} \right)_0 \right] - \left[ 2 \frac{\partial v}{\partial r} + 2 \left( \frac{\partial v}{\partial r} \right) \right]$$

$$= 2 \left( \frac{\partial v}{\partial r} \right)_0$$

$$\frac{\varphi_1 - \varphi_2}{4\pi} = \frac{Q}{4\pi} = \frac{Q}{4\pi} u_1$$

Przebieg elektryczności

$$\nabla^2 u_1 = 0 \quad \nabla^2 v_1 = 0 \quad \nabla^2 w_1 = 0$$

$$\nabla^2 v = 0$$

$$\frac{\partial u_1}{\partial x} + \frac{\partial u_1}{\partial y} + \frac{\partial u_1}{\partial z} = 0$$

$$\text{div } v = 0$$

$$v = \text{curl } A$$

$$\text{curl curl } v = \nabla \text{div } v - \nabla^2 v = 0$$

$$\text{curl } v = \nabla A = \nabla \text{div } A - \nabla^2 A$$

$$\nabla^2 \text{curl } v = \nabla^2 A = 0$$

dla nieskończoności i dla  $r \rightarrow \infty$  jest  $v = 0$   $\nabla A = 0$



Erster Beweis:

$$\cancel{\frac{\partial u}{\partial x}} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = X - \frac{1}{\rho} \frac{\partial \tau}{\partial x} - \frac{\mu}{\rho} \nabla^2 u$$

Hier v vom Kammerprinzip  
 Laplace'sch. dann  $u, v, w$   
 ist

$$u, v, w, p$$

$$u \frac{\partial u}{\partial x} + \dots - v \frac{\partial u}{\partial y} \dots = 0$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = v \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z}$$

$$u \frac{\partial w}{\partial x} + \dots =$$

$$\frac{\partial(u-u)}{\partial x} + \dots = 0$$

$$\frac{\partial u}{\partial x} = - \frac{\partial v}{\partial y} - \frac{\partial w}{\partial z}$$

$$u \left( v \frac{\partial u}{\partial y} - u \frac{\partial v}{\partial y} \right) + \left( w \frac{\partial u}{\partial z} - u \frac{\partial w}{\partial z} \right) = \dots$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \frac{\partial}{\partial x} \left( \frac{u^2}{2} \right) + \frac{\partial(uv)}{\partial y} + \frac{\partial(uw)}{\partial z} - \underbrace{u \frac{\partial v}{\partial y} - u \frac{\partial w}{\partial z}}$$

5

$$= + u \frac{\partial u}{\partial x} = \frac{1}{2} \frac{\partial u^2}{\partial x}$$

$$= \frac{\partial}{\partial x} (u^2) + \frac{\partial}{\partial y} (uv) + \frac{\partial}{\partial z} (uw)$$



Rozmianio i zausubamian "inertio terms"

19

Homogeneous; n.p. such kotory  $u = -\omega \frac{x}{r}$   $v = \omega \frac{y}{r}$

$$= -y \varphi \quad = x \varphi$$

$$\frac{\partial u}{\partial x} = y \frac{\partial \varphi}{\partial x}$$

$$\frac{\partial u}{\partial y} = \varphi + \frac{y}{r} \frac{\partial \varphi}{\partial r}$$

$$\frac{\partial^2 u}{\partial x^2} = y \left( \frac{1}{r} \frac{d\varphi}{dr} - \frac{x^2}{r^3} \frac{d\varphi}{dr} + \frac{x^2}{r^2} \frac{d^2 \varphi}{dr^2} \right)$$

$$\frac{\partial^2 u}{\partial y^2} = x \left( \frac{1}{r} \frac{d\varphi}{dr} - \frac{y^2}{r^3} \frac{d\varphi}{dr} + \frac{y^2}{r^2} \frac{d^2 \varphi}{dr^2} \right)$$

$$\frac{\partial^2 u}{\partial y^2} = 3 \frac{d\varphi}{dr} \frac{y}{r} - \frac{y^3}{r^3} \frac{d\varphi}{dr} + \frac{y^3}{r^2} \frac{d^2 \varphi}{dr^2}$$

$$\Delta^2 u = 3 \frac{y}{r} \frac{d\varphi}{dr} + y \frac{d^2 \varphi}{dr^2}$$

$$\mu = f(r) \quad \frac{\partial \mu}{\partial x} = \frac{x}{r} \frac{d\mu}{dr}$$

$$\frac{\partial \mu}{\partial x} = \mu \nabla^2 u$$

$$\frac{x}{r} \frac{d\mu}{dr} = -y \left[ \frac{3}{r} \frac{d\varphi}{dr} + \frac{d^2 \varphi}{dr^2} \right] x$$

$$\frac{y}{r} \frac{d\mu}{dr} = x \left[ \frac{3}{r} \frac{d\varphi}{dr} + \frac{d^2 \varphi}{dr^2} \right] y$$

$$r \frac{d\mu}{dr} = 0$$

$$\mu = \text{const}$$

$$r^3 \frac{d\varphi}{dr} = \text{const}$$

$$\varphi = \frac{1}{r^2} + \dots$$

Integ tylos pismu milera

*[Handwritten signature]*

Strung, ktorej dwa konce drgają harmonicznymi o różnym okresie:

$$\frac{\partial^2 \xi}{\partial t^2} = a^2 \frac{\partial^2 \xi}{\partial x^2}$$

$$\xi = \sum \left[ A_k \sin \frac{k\pi x}{l} \sin \left( \frac{k\pi a t}{l} + \delta_k \right) + B_k \cos \frac{k\pi x}{l} \right] \sin \left( \frac{k\pi a t}{l} + \delta_k \right)$$

$$x=0 \quad \xi = \sum_{k=1}^{\infty} B_k \frac{\sin \left( \frac{k\pi a t}{l} + \delta_k \right)}{l} M \sin \alpha t$$

$$x=l \quad \xi = \sum B_k \cos \frac{k\pi x}{l} \sin \left( \frac{k\pi a t}{l} + \delta_k \right) = N \sin \rho t$$

Porównanie

$$B_1 \sin \left( \frac{\alpha \pi t}{l} + \delta_1 \right) + B_2 \sin \left( \frac{2\alpha \pi t}{l} + \delta_2 \right) + B_3 \sin \left( \frac{3\alpha \pi t}{l} + \delta_3 \right) + \dots = M \sin \alpha t$$

Porównanie

$$-B_1 \sin \left( \frac{\alpha \pi t}{l} + \delta_1 \right) + B_2 \sin \left( \frac{2\alpha \pi t}{l} + \delta_2 \right) - B_3 \sin \left( \frac{3\alpha \pi t}{l} + \delta_3 \right) + \dots = N \sin \rho t$$

$$B_2 \sin \left( \frac{2\alpha \pi t}{l} + \delta_2 \right) + B_4 \sin \left( \frac{4\alpha \pi t}{l} + \delta_4 \right) + \dots = \frac{1}{2} [M \sin \alpha t + N \sin \rho t]$$

$$B_1 \sin \left( \frac{\alpha \pi t}{l} + \delta_1 \right) + B_3 \sin \left( \frac{3\alpha \pi t}{l} + \delta_3 \right) + \dots = \frac{1}{2} [M \sin \alpha t - N \sin \rho t]$$

$$B_k = \frac{2}{l} \int_0^l [M \sin \alpha t + N \sin \rho t] \sin \frac{k\pi x}{l} dx \quad \int_0^{\frac{2\pi}{\alpha}} m \sin \rho t \cdot \sin k \rho t$$

$$\begin{aligned} 2 \int_0^{\frac{2\pi}{\alpha}} \sin \alpha t \sin k \rho t dt &= \int_0^{\frac{2\pi}{\alpha}} [\sin(\alpha + k\rho)t - \sin(\alpha - k\rho)t] dt \\ &= \frac{\sin(\alpha + k\rho)t}{\alpha + k\rho} \Big|_0^{\frac{2\pi}{\alpha}} - \frac{\sin(\alpha - k\rho)t}{\alpha - k\rho} \Big|_0^{\frac{2\pi}{\alpha}} \end{aligned}$$



$$B_1 \omega \delta_1 \sin \frac{\omega t}{l} + B_3 \omega \delta_3 \sin \frac{3\omega t}{l} + \dots$$

$$\left. \vphantom{\int} \right\} = \frac{1}{2} [M \sin t - N \cos t] = F_2$$

$$+ B_1 \sin \delta_1 \cos \frac{\omega t}{l} + B_3 \sin \delta_3 \cos \frac{3\omega t}{l} + \dots$$

$$-2 \int_0^{\frac{2l}{a}} \sin \frac{m\pi t}{l} \sin \frac{n\pi t}{l} dt = \int_0^{\frac{2l}{a}} \left[ \cos \frac{(m+n)\pi t}{l} - \cos \frac{(m-n)\pi t}{l} \right] dt =$$

$$= \frac{\sin \frac{(m+n)\pi t}{l}}{\frac{(m+n)\pi}{l}} \Big|_0^{\frac{2l}{a}} - \frac{\sin \frac{(m-n)\pi t}{l}}{\frac{(m-n)\pi}{l}} \Big|_0^{\frac{2l}{a}} = 0$$

$$2 \int_0^{\frac{2l}{a}} \sin^2 \frac{m\pi t}{l} dt = \int_0^{\frac{2l}{a}} \left[ 1 - \cos \frac{2m\pi t}{l} \right] dt = \frac{2l}{a}$$

$$2 \int_0^{\frac{2l}{a}} \cos \frac{m\pi t}{l} \sin \frac{n\pi t}{l} dt = \int_0^{\frac{2l}{a}} \left[ \sin \frac{(m+n)\pi t}{l} - \sin \frac{(m-n)\pi t}{l} \right] dt =$$

$$= \frac{\cos \frac{(m+n)\pi t}{l}}{\frac{(m+n)\pi}{l}} \Big|_0^{\frac{2l}{a}} - \frac{\cos \frac{(m-n)\pi t}{l}}{\frac{(m-n)\pi}{l}} \Big|_0^{\frac{2l}{a}} = 0$$

$$B_k \omega \delta_k = \frac{a}{l} \int_0^{\frac{2l}{a}} F_2 \sin \frac{k\pi t}{l} dt \quad \parallel \quad B_k \sin \delta_k = \frac{a}{l} \int_0^{\frac{2l}{a}} F_2 \cos \frac{k\pi t}{l} dt$$

$$-2 \int_0^{\frac{2l}{a}} \sin \alpha t \sin \frac{k\pi t}{l} dt = \frac{\sin \left( \alpha + \frac{k\pi}{l} \right) t}{\alpha + \frac{k\pi}{l}} \Big|_0^{\frac{2l}{a}} - \frac{\sin \left( \alpha - \frac{k\pi}{l} \right) t}{\alpha - \frac{k\pi}{l}} \Big|_0^{\frac{2l}{a}}$$

$$= \frac{\sin \frac{2\alpha l}{a}}{\alpha + \frac{k\pi}{l}} - \frac{\sin \frac{2\alpha l}{a}}{\alpha - \frac{k\pi}{l}} = \sin \frac{2\alpha l}{a} \cdot \frac{-2 \frac{k\pi}{l}}{\alpha^2 - \left( \frac{k\pi}{l} \right)^2}$$

Jaka będzie praca wykonana na punkcie 0?

$$X = E \frac{\partial \xi}{\partial x}$$

$$\int \frac{\partial \xi}{\partial x} dx = \int \left( \frac{\partial \xi}{\partial x} \right) \left( \frac{\partial \xi}{\partial t} \right) dt$$

$$\left( \frac{\partial \xi}{\partial x} \right) = \sum A_k \frac{k\pi}{l} \sin\left(\frac{k\pi x}{l} + \delta_k\right)$$

$$\left( \frac{\partial \xi}{\partial t} \right) = \sum \cancel{A_k \omega \left( \frac{k\pi x}{l} + \delta_k \right)}$$

$$= \sum \left[ A_k \sin \frac{k\pi x}{l} + B_k \cos \frac{k\pi x}{l} \right] \frac{k\pi \omega}{l} \cos \delta_k$$

$$= \sum B_k \frac{k\pi \omega}{l} \cos\left(\frac{k\pi x}{l} + \delta_k\right)$$



$$\frac{\partial p}{\partial x} = \mu \nabla^2 u$$

$$\frac{\partial p}{\partial y} = \mu \nabla^2 v$$

$$\frac{\partial p}{\partial z} = \mu \nabla^2 w$$

$$\frac{\partial p}{\partial x} = \mu \nabla^2 u$$

$$\vdots$$

$$\vdots$$

$$\vdots$$

$$\frac{\partial(p-p_1)}{\partial x} = \mu \nabla^2 (u-u_1)$$

$$\frac{\partial(p-p_1)}{\partial y} = \mu \nabla^2 (v-v_1)$$

$$\frac{\partial(p-p_1)}{\partial z} = \mu \nabla^2 (w-w_1)$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\nabla^2 p = 0$$

$$\nabla^2 (p-p_1) = 0$$

$$\nabla p = \mu \nabla^2 \vec{v} = -\mu \text{curl}^2 \vec{v}$$

$$\text{div} \vec{v} = 0$$

$$\vec{v} = \nabla A + \text{curl} \vec{A}$$

$$\text{curl}^2 = \nabla \text{div} - \nabla^2$$

~~$$\text{curl} \nabla p = 0 = \mu \text{curl} \nabla^2 \vec{v} = \mu \nabla^2 \text{curl} \vec{v} = \mu \text{curl}^3 \vec{v} = 0$$~~

~~$$\vec{v} = \nabla \int \frac{\text{div} \vec{v}}{r} dv + \text{curl} \int \frac{\text{curl} \vec{v}}{r} dv$$~~

$$\vec{v} = \nabla A + \text{curl} \int \frac{\text{curl} \vec{v}}{r} dv$$

$$\nabla p = \text{curl}^3 \vec{A}$$

$$\mu_{xx} = - \int_0^x \Sigma \frac{\partial u}{\partial x} dx$$

$$= + \frac{1}{4n} \int \frac{\partial^2 \mathcal{H}}{\partial x^2} \frac{\partial \mathcal{H}}{\partial x} dx =$$

$$= \frac{1}{8\pi} \left( \frac{\partial u}{\partial x} \right)^2 \Big|_0^\infty = -\frac{1}{8\pi} \left( \frac{\partial u}{\partial x} \right)^2$$

$$\frac{\partial u}{\partial x} = \frac{u_2 - u_1}{\delta} = -4\pi b$$

$$\beta_{xx} = 2n\sigma^2$$

Tree polypore with Kollmansche

proji množi po  $1 \text{ mm}^2$

0.13  $\mu$  transfer

pro 1 cm<sup>2</sup>: 13 Mikrop. =  $13 \cdot 10^{-6} \frac{\text{Constant}}{\text{Voll}}$

$$\frac{1 \text{ Vm}}{6} = 13 \cdot 10^{-6} \text{ Coul.} = 13 \cdot 10^{-6} \cdot 3 \cdot 10^9 \text{ (eV)} = 39 \cdot 10^3 = 4 \cdot 10^2$$

$$p_{\text{ext}} = 2n \cdot (4 \cdot 10^2)^2 = 2 \cdot 32 \cdot 16 \cdot 10^4 = 10^6 \text{ dy} = 1 \text{ Atmosph. !}$$



Die Werte ~~von~~  $\rho$  sind gegeben; wir suchen nun die Funktion  $X$  zu finden?

$$\mu \frac{du}{dr} = \text{const}$$

$$\frac{du}{dr} = \frac{C}{r}$$

$$u - u_1 = C \log \frac{r}{r_1}$$

$$u_2 = 0$$

$$\frac{u - u_1}{u_1 - u_2} = \frac{\log \frac{r}{r_1}}{\log \frac{r_2}{r_1}}$$

$$\mu \frac{\partial u}{\partial x} =$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x}$$

Die Randbedingungen  $V$  müssen sein:

$$X_1 = Y_1 = Z_1 = 0$$

$$\text{zudem: } \mu - 2\mu \left( \frac{\partial v}{\partial y} \right) = 0$$

$$v \text{ muss bei } z=0 \text{ verschwinden, d.h. } \frac{\partial v}{\partial z} = 0, \rho = 0$$

$$\left( \frac{\partial u}{\partial y} \right) + \left( \frac{\partial v}{\partial x} \right) = 0$$

$$\left( \frac{\partial u}{\partial y} \right) = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

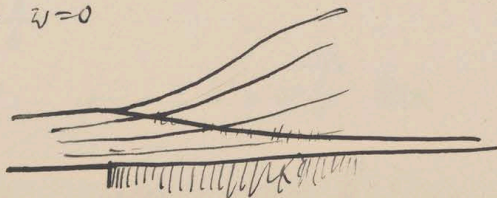
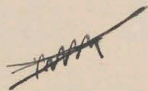
$$w = \frac{\partial v}{\partial z} = 0$$

$$\left( \frac{\partial u}{\partial y} \right) + \left( \frac{\partial v}{\partial z} \right) = 0$$

$$\left( \frac{\partial w}{\partial y} \right) = 0$$

$$u = \text{const}$$

Integration ergibt:  $w = 0$



Przykład 2 - teoria: rozkład prędkości w kierunku x

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = -\frac{\partial p}{\partial x} - \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\frac{\partial p}{\partial y} - \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \quad \left. \begin{array}{l} \text{zaniedbać i wyjąć } p = p(x), \\ \text{niższe!} \end{array} \right\}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

zakładamy nieprzerwaną:  $p = 0$  w yższym wyrażeniu  $p = 0$

$$\frac{\partial u}{\partial x} = 0$$

~~Upraszczamy przybliżenie  $u = a$~~

v w ogóle nie zależy od x, v = const

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = v \frac{\partial u}{\partial y} - u \frac{\partial v}{\partial y} = u^2 \frac{\partial}{\partial y} \left( \frac{1}{u} \right)$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = u \frac{\partial v}{\partial x} - v \frac{\partial u}{\partial x} = u^2 \frac{\partial}{\partial x} \left( \frac{v}{u} \right) = -u^2 \frac{\partial}{\partial x} \left( \frac{u}{v} \right)$$

$$\Delta^2 p =$$



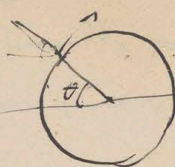
Recht kubi v souvislosti s logaritmami

$$u = c \cdot \frac{M}{2\pi} \left( \frac{1}{r} + \frac{3x^2}{r^3} \right) - N \left( \frac{3}{r^3} - \frac{15x^2}{r^5} \right)$$

$$p_{\theta r} = \lambda \cdot v_{\theta} = \lambda \cdot \frac{u}{r} \sin \theta$$

$$p_{rx} = \lambda \cdot \frac{u}{r} \cos \theta$$

$$p_{\theta r} = p_{rx} \sin \theta = p_{rx} \cos \theta + p_{ry}$$



Jak je příslušná křivka pro danou rovnici elektr.?

$$\psi = -\frac{c}{2} \left( 1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3} \right) \omega^2$$

u příslušné x=0:

$$r = a + \delta \quad \omega = \delta + \delta$$

$$\psi = -\frac{c a^2}{2} \left[ 1 - \frac{3}{2} \left( 1 - \frac{\delta}{a} \right) + \frac{1}{2} \left( 1 - \frac{3\delta}{a} \right) \right] \left( 1 + \frac{2\delta}{a} \right)$$

=0

$$= -\frac{c a^2}{2} \left[ 1 - \frac{3}{2} \left( 1 + \frac{\delta}{a} \right)^{-1} + \frac{1}{2} \left( 1 + \frac{\delta}{a} \right)^{-3} \right] \left( 1 + \frac{\delta}{a} \right)^2$$

$$= -\frac{c a^2}{2} \left[ \left( 1 + \frac{\delta}{a} \right)^2 - \frac{3}{2} \left( 1 + \frac{\delta}{a} \right) + \frac{1}{2} \left( 1 + \frac{\delta}{a} \right)^{-1} \right]$$

$$= -\frac{c a^2}{2} \left[ 1 + \frac{2\delta}{a} + \frac{\delta^2}{a^2} - \frac{3}{2} - \frac{3}{2} \frac{\delta}{a} + \frac{1}{2} \left( 1 - \frac{\delta}{a} - \frac{\delta^2}{a^2} \right) \right]$$

$$\psi = -\frac{c a^2}{2} \frac{\delta^2}{2a^2} = -\frac{c \delta^2}{4}$$

W Wilky: orbytní r=∞:  $\psi = -\frac{c}{2} \omega^2 = -\frac{c \delta^2}{4}$

rotaci:  $\omega = \frac{\delta}{\sqrt{2}}$



potencjał porażeniowy pól wzdłuż  
 Dotychczasowe obliczenia polegały na założeniu że równanie  $\nabla^2 u = -4\pi \varepsilon$   
 weźmie tylko w samą wartość, a natężenie przy wyjściu z jej obszaru jest  
 stępem  $\varepsilon = 0$

Jeżeli jednak prąd w  $\vec{u}$ , a  $\varepsilon$  duże, to musimy to być rozpraszane równaniem:

$$-\frac{\Delta \varepsilon}{\Delta t} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = -\lambda \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$= 4\pi \lambda \varepsilon$$

$$\downarrow$$

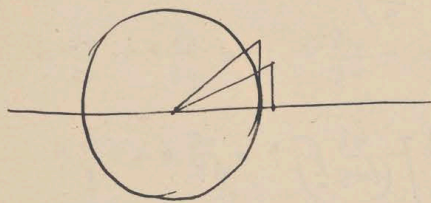
$$\frac{\partial \varepsilon}{\partial t} + u \frac{\partial \varepsilon}{\partial x} + v \frac{\partial \varepsilon}{\partial y} + w \frac{\partial \varepsilon}{\partial z}$$

Jeżeli się przyjmiemy  $x$  w kierunku linii prądu  $s$ :

$$-u \frac{\partial \varepsilon}{\partial s} = 4\pi \lambda \varepsilon$$

$$\frac{1}{\varepsilon} \frac{\partial \varepsilon}{\partial s} = -\frac{4\pi \lambda}{u}$$

$$\lg \varepsilon = -4\pi \lambda \int \frac{ds}{u}$$



$$u = r$$

$$-c \frac{\delta_0^2}{4} = -\frac{c(\delta_0 \sin \theta)^2}{4}$$

$$\delta_0 = \frac{\delta_0}{\sin^2 \theta}$$

opracujemy wartość  $\delta$  w punkcie  $\theta_1: \theta$

$$\delta_0 = \delta_1 \sin \theta_1 = \rho \sin \theta$$

zatem w każdej wartości

$$u = \text{const}$$

$$\int_0^{\theta} \frac{a d\theta}{\frac{3}{2} \frac{c}{a} \sin \theta_1 \delta_1} = \frac{2}{3} \frac{a^2}{c \delta_1} \frac{\theta_1 - \theta}{\sin \theta_1}$$



$$\varepsilon = \varepsilon_0 \quad -4\pi\lambda \frac{2}{3} \frac{a^2}{c\delta} \frac{\theta - \theta_1}{\sin\theta}$$

$$-4\pi\lambda \frac{2}{3} \frac{a^2}{c\delta} \frac{\theta_1 - \theta}{\sin\theta_1} = \lg \frac{\varepsilon}{\varepsilon_0}$$

$$\text{N.p. } \frac{\varepsilon}{\varepsilon_0} = \frac{1}{2}$$

$$\theta_1 = \frac{\pi}{2}$$

$$a = 10^{-5}$$

$$\delta = 10^{-6}$$

$$\lambda = \frac{1}{5} \cdot 10^8$$

Wstawiamy do a

$$\frac{2}{3} \cdot 4 \cdot \pi \cdot \frac{1}{5} \cdot 10^8 \cdot \frac{10^{-5}}{10^{-6} \cdot c} \left( \frac{\pi}{2} - \theta \right) = \lg 0.5 \cdot 2.3$$

zrobić w stole  $\lg \frac{\varepsilon}{\varepsilon_0} = -4\pi\lambda \frac{a}{u}$

u jest to minimalna wartość

$$\text{N.p. } a = 10^{-6}$$

$$0.5 \cdot 2.3 = -4\pi\lambda \frac{1}{5} \cdot 10^8 \cdot \frac{10^{-6}}{u}$$

$$u = \text{cca } 200 \frac{\text{cm}}{\text{sec}}!$$

zatem to są już wartości nie  
może być!

Należy odrzucić dest. (zwiększyć) to drobne ilości elekt. natężenia iść w kierunku

ale i lepszych izolatorów natępi znaczną deformację wartości elekt. natęż.



Jaki ruch ciału krótko białek powietrza przechodzących przez wodę?



Zdaje się że to będzie podobnie jak  
ruch kulki w cieczy i dedukuj!

bo tarcie na powierzchni można zaniedbać

Czy nie można by stworzyć kulki z białki n.p. koloidem, napęcznie  $H_2$   
ciężki równy cięciu jak powietrze i pociągnąć do wody, porównując z powietrzem?

z tego będzie silny ruch góra-przód

Podobnie dla ciał  
cięższych od wody!

Banki  $H_2$  będą powolniej przechodzić (z powodu mniejszego tarcia) niż  $O_2$ .

Analogia do „Spherical Vortex” Lamb. p. 265

Nauzumi i któryś przed ciałem z  $H_2$  tarciem

W bliskości powierzchni prędkości przepływu do odstępu; kierunek: system krzywych

$$v = \left( \frac{\partial v}{\partial n} \right)_0 N$$



to będzie rotacja także kierunkiem linii przepływu.

$$\text{prąd} \quad \frac{i}{\partial \beta} = \int \left( \frac{\partial v}{\partial n} \right)_0 N \, dM = \left( \frac{\partial v}{\partial n} \right)_0 \frac{(\varphi_0 - \varphi_i)}{4\pi}$$

Najpóźniej wreszcie będzie  $(di)i = \lambda \frac{\partial i}{\partial n}$

$$\lambda \frac{\partial i}{\partial n} = \frac{\partial i_\alpha}{\partial \alpha} + \frac{\partial i_\beta}{\partial \beta}$$

$$i \, d\beta - i' \, d\beta' = i \, (d\beta - d\beta') + (i - i') \, d\beta$$

$$= \left[ i \frac{\partial \beta}{\partial \alpha} + \lambda \, d\beta \frac{\partial i}{\partial \alpha} \right] d\alpha = \lambda \frac{\partial i}{\partial n} \, d\beta \, d\alpha$$



~~$$\int_{x_1}^{x_2} \frac{\partial u}{\partial n} d\sigma = 0$$~~



Leždy te komovkyjine mario zastepi' pries potynzel  
fkyjiny toki' jake by je porovad

~~$$\frac{\partial u}{\partial n} = \left( \frac{\partial u}{\partial n_0} \right) \frac{\varphi_2 - \varphi_1}{\varphi_2} = \lambda \delta' \frac{\partial u}{\partial \alpha}$$~~

~~$$\int d\alpha d\beta$$~~  
~~$$= \iint \delta$$~~

~~$$\frac{\partial p}{\partial x} = \mu \nabla^2 u$$~~

$$\iint \left( \frac{\partial u}{\partial n_0} \right) dF = \iiint \nabla^2 u \, dx dy dz = \frac{1}{\mu} \iint \frac{\partial p}{\partial x} \, dx dy dz = \frac{1}{\mu} \iint p \, dy dz$$

$$= \frac{1}{\mu} \iint p \cos \alpha \cdot dF$$

$$\iint \left[ \cos \alpha \cdot \left( \frac{\partial u}{\partial n} \right) + \cos \alpha_1 \left( \frac{\partial u}{\partial n} \right) + \cos \alpha_2 \left( \frac{\partial u}{\partial n} \right) \right] dF = \frac{1}{\mu} \iint p \, dF$$

Lež u = u\_1 i p = u\_2 se identityne!

$\Delta u = 0$        $\Delta p = 0$        $\Rightarrow$  jinde identityne v tomto proume to vyjde  
 $\text{tedy } \frac{\partial u}{\partial n} \sim \frac{\partial p}{\partial n}$

$$\lambda \frac{\partial u}{\partial n} = \frac{\partial u}{\partial x} + \frac{\partial p}{\partial y} = \frac{\varphi_2 - \varphi_1}{\varphi_2} \left[ \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial n_0} \right) + \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial n_0} \right) \right]$$

$$\frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial y} \right) = - \left( \frac{\partial^2 u}{\partial x^2} \right)_0 = \nabla_0^2 u = \frac{1}{\mu} \frac{\partial p}{\partial n}$$

Wize bytely vopole:

$$u_1 - u_2 = \frac{\varphi_2 - \varphi_1}{\varphi_2} \frac{1}{\lambda \mu} (p_1 - p_2) \quad (?)$$



Jaki procent <sup>elektrycznej</sup> pracy przy wytworzeniu things stoin ?

$$W_e = \frac{P^2 (\varphi_1 - \varphi_2)^2}{(4\pi\mu)^2} \frac{\phi \delta}{L}$$

$$W_f = \frac{\pi P^2 R^4}{8\mu L}$$

$$\frac{W_e}{W_f} = \frac{(\varphi_1 - \varphi_2)^2 \phi}{2\pi\mu \varphi} = \frac{\left(\frac{4}{300}\right)^2 \cdot 4 \cdot 6 \cdot 10^{-8}}{2 \cdot 3 \cdot 14 \cdot 0.010 \cdot 10^{-4}} = \frac{4 \cdot 10^{-8}}{10^{-6}}$$

powiększyć masy: podstawić  $\delta = \frac{1}{2}$

zmniejszyć  $\varphi$

Nie, więcej: przepływać i dobry izolator

Jaki ruch Browna powodowany przez zderzenia przynajmniej, jaka energia przy rozpraszaniu ?

$$N_f. \quad 2r = 0.001 \text{ mm} = 10^{-4} \text{ cm}$$

$$v = 0.003 \frac{\text{mm}}{\text{sec}} = 3 \cdot 10^{-4}$$

$$\sigma_{\text{pr}} = 6\pi a \mu v \quad \mu = 0.018$$

$$\text{praca po sec: } 6\pi a \mu v^2 = \frac{6^3 \cdot 3 \cdot 14 \cdot 10^{-4} \cdot 0.018 \cdot 9 \cdot 10^{-8}}{7}$$

$$= 10^{-12} \cdot \frac{0.17}{1.5} \cdot 9 = 1.5 \cdot 10^{-12} \text{ erg}$$

$$\text{objętość takiej kulki: } \frac{4\pi}{3} \cdot \frac{1}{8} 10^{-12} = \frac{1}{2} 10^{-12} \text{ cm}^3$$

$$\text{Zatem praca po } 1 \text{ cm}^3 \text{ młota wgi: } 3 \frac{\text{erg}}{\text{sec}}$$

$$\text{Pro dzień: } 60 \cdot 60 \cdot 24 = 86400 \text{ s}$$

$$260.000 \text{ erg} = \frac{260.000}{42 \cdot 10^6} \text{ cal} = \frac{1}{160} \text{ cal}$$



Energia Atkrostoni ogy kelki:  $\alpha \cdot 0 = 4\pi r^2 \alpha$

$$= 3.14 \cdot 80 \cdot 10^{-8} \text{ (gy)}$$

$$= 25 \cdot 10^{-7}$$

Zatm Enyia Atk <sup>ny. vady</sup> ystonyghy ds opsdmwa mda na  $\frac{25 \cdot 10^7}{1.5 \cdot 10^{12}} = 16 \cdot 10^5 \text{ sec.}$   
 $= \underline{\underline{2 \text{ dni}}}$

~~16.10<sup>5</sup>~~  
~~6.22~~

Prak kel v ciay, cy ni mozia mogly dni "inertia terms"  
 Dla tercio:

$$u = \frac{M}{2} \left( \frac{x_1}{2} + \frac{x_2}{2^3} \right) + \frac{N}{2^3} \left( 1 - \frac{3x_1}{2^2} \right) + c$$

$$v = \frac{M}{2} \frac{x_4}{2^3} - \frac{3N}{2^5} x_7$$

$$w = \frac{M}{2} \frac{x_8}{2^3} - \frac{3N}{2^5} x_2$$

Dla tercio:

$$u = \frac{N}{2^3} \left( 1 - \frac{3x_1}{2^2} \right) + c$$

$$v = - \frac{3N}{2^5} x_7$$

$$w = \frac{3N}{2^5} x_7$$

$$0 = \frac{\partial F}{\partial x} - \mu \nabla^2 u$$

$$0 = \frac{\partial F}{\partial y} - \mu \nabla^2 v$$

$$0 = \frac{\partial F}{\partial z} - \mu \nabla^2 w$$

$$(u_1 + u_2) \frac{\partial (u_1 + u_2)}{\partial x} + \dots = - \frac{\partial F}{\partial x} + \mu \left( \nabla^2 u_1 + \nabla^2 u_2 \right)$$

$$u_1 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial x} + u_1 \frac{\partial u_2}{\partial x} + u_2 \frac{\partial u_2}{\partial x} = - \frac{\partial F}{\partial x} + \frac{\partial F}{\partial x} + \mu \left( \nabla^2 u_1 + \nabla^2 u_2 \right)$$

$$= u_1 \frac{\partial (u_1 + u_2)}{\partial x} + u_2 \frac{\partial (u_1 + u_2)}{\partial x}$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = - \frac{\partial F}{\partial x}$$



$$u = \frac{M}{2} \left( \frac{1}{2} + \frac{x^2}{25} \right) + \frac{N}{25} \left( 1 - \frac{3x^2}{25} \right) + c$$

La forma:  $u = c + \frac{A}{6} \frac{\partial}{\partial x} \left( \frac{x}{25} \right) + \frac{B}{6} \frac{\partial}{\partial x} \left( \frac{x}{25} \right)$

$$\frac{\partial u}{\partial x} = M \left[ -\frac{x}{2^3} + \frac{2x}{2^3} - \frac{3x^3}{2^5} \right] + N \left[ -\frac{3x}{2^5} - \frac{6x}{2^5} + \frac{15x^3}{2^7} \right]$$

$$= M \left[ \frac{x}{2^3} - \frac{3x^3}{2^5} \right] + N \left[ -\frac{9x}{2^5} + \frac{15x^3}{2^7} \right]$$

$$\frac{\partial u}{\partial y} = M \left[ -\frac{y}{2^3} - \frac{3x^2 y}{2^5} \right] + N \left[ \frac{3y}{2^5} + \frac{15x^2 y}{2^7} \right]$$

$$\frac{\partial u}{\partial z} = M \left[ -\frac{2}{2^3} - \frac{3x^2 z}{2^5} \right] + N \left[ -\frac{3z}{2^5} + \frac{15x^2 z}{2^7} \right]$$

$$\begin{array}{c} \frac{1}{2} + \frac{x^2}{2^3} \\ \frac{x y}{2^3} \\ \frac{x z}{2^3} \end{array} \left| \begin{array}{c} \frac{N}{25} \left( 1 - \frac{3x^2}{25} \right) + c \\ - \frac{3N x y}{2^5} \\ - \frac{3N x z}{2^5} \end{array} \right.$$

$$M \left\{ \cancel{\frac{12}{2^6}} - \cancel{\frac{3x^3}{2^6}} + \cancel{\frac{15x^3}{2^6}} - \cancel{\frac{3x^5}{2^8}} - \cancel{\frac{x^3 y^2}{2^6}} - \cancel{\frac{3x^3 y^2}{2^8}} - \cancel{\frac{x^3 z^2}{2^6}} - \cancel{\frac{3x^3 z^2}{2^8}} \right\} +$$

$$+ N \left\{ -\frac{12}{2^6} + \frac{15x^3}{2^8} - \frac{9x^3}{2^8} + \frac{15x^3}{2^{10}} - \frac{3x^3 y^2}{2^8} + \frac{15x^3 y^2}{2^{10}} - \frac{3x^3 z^2}{2^8} + \frac{15x^3 z^2}{2^{10}} \right\}$$

$$= \cancel{M \left\{ -\frac{3x^3}{2^6} - \frac{3x^5}{2^8} \right\}} + \cancel{N \left\{ -\frac{12x}{2^6} - \frac{9x^3}{2^8} + \frac{15x^3}{2^{10}} \right\}} - \frac{12x}{2^6} + \frac{27x^3}{2^8}$$

$$v = \frac{x y}{2^3} \left[ M - \frac{3N}{2^2} \right]$$

$$\frac{\partial v}{\partial x} = \left[ \frac{y}{2^3} - \frac{3x^2 y}{2^5} \right] \left[ M - \frac{3N}{2^2} \right] + \frac{6N x^2 y}{2^7}$$

$$\frac{\partial v}{\partial x} = M \left[ \frac{y}{2^3} - \frac{3x^2 y}{2^5} \right] + \frac{3N}{2^2} \left[ -\frac{y}{2^5} + \frac{5x^2 y}{2^7} \right]$$

$$\frac{\partial v}{\partial y} = M \left[ \frac{x}{2^3} - \frac{3x^3 y^2}{2^5} \right] + 3N \left[ -\frac{x}{2^5} + \frac{5x^3 y^2}{2^7} \right]$$

$$\frac{\partial v}{\partial z} = \frac{M - 3x^2 y^2}{2^5} + 3N \frac{5x^2 y^2}{2^7}$$

$$\begin{array}{c} \frac{1}{2} + \frac{x^2}{2^3} \\ \frac{x y}{2^3} \\ \frac{x z}{2^3} \end{array} \left| \begin{array}{c} \frac{N}{25} \left( 1 - \frac{3x^2}{25} \right) + c \\ - \frac{3x y}{2^2} \\ - \frac{3x z}{2^2} \end{array} \right.$$



$$M \left\{ \frac{y}{2^4} - \frac{3x^2y}{2^6} + \frac{x^4}{2^6} - \frac{3x^2y}{2^8} + \frac{x^4}{2^6} - \frac{3x^2y}{2^8} - \frac{3x^2y}{2^8} \right\} \\ + 3N \left\{ -\frac{y}{2^6} + \frac{5x^2y}{2^8} - \frac{x^4}{2^8} + \frac{5x^2y}{2^{10}} - \frac{x^4}{2^8} + \frac{5x^2y}{2^{10}} + \frac{5x^2y}{2^{10}} \right\} =$$

$$\Pi = M \left\{ \frac{y}{2^4} - \frac{4x^2y}{2^6} \right\} + 3N \left\{ \frac{y}{2^6} + \frac{8x^2y}{2^8} \right\}$$

$$I = M \left\{ -\frac{4x^3}{2^6} \right\} + N \left\{ -\frac{12x}{2^6} + \frac{24x^3}{2^8} \right\}$$

For eq  $\frac{\partial I}{\partial y} = \frac{\partial \Pi}{\partial x} = 0$

$$-4M \left\{ \frac{-6x^3y}{2^8} \right\} + 12N \left\{ \frac{+6xy}{2^8} - \frac{16x^3y}{2^{10}} \right\} \parallel M \left\{ -\frac{4xy}{2^6} - \frac{8xy}{2^6} + \frac{24x^3y}{2^8} \right\} + \\ + 3N \left\{ -\frac{6xy}{2^8} + \frac{16xy}{2^8} - \frac{64x^3y}{2^{10}} \right\}$$

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$$M \left\{ \frac{12xy}{2^6} \right\} + N \left\{ \frac{42xy}{2^8} \right\} = \frac{\partial \Pi}{\partial y} - \frac{\partial I}{\partial x}$$

$$u_2 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial y} + u_2 \frac{\partial u_1}{\partial z} = M c \left( \frac{x}{2^3} - \frac{3x^3}{2^5} \right) + \frac{MN}{2^3} \left\{ \frac{x}{2^3} - \frac{3x^3}{2^5} - \frac{3x^3}{2^5} + \frac{9x^5}{2^7} \right. \\ \left. + \frac{3x^2y}{2^5} + \frac{9x^3y^2}{2^7} + \frac{3x^2z^2}{2^5} + \frac{9x^3z^2}{2^7} \right\} \quad \frac{7x}{2^3}$$

$$= M c \left( \frac{x}{2^3} - \frac{3x^3}{2^5} \right) + 4N \frac{4x}{2^6}$$



$$u_2 \frac{\partial v_1}{\partial x} + v_2 \frac{\partial v_1}{\partial y} + w_2 \frac{\partial v_1}{\partial z} = M_c \left( \frac{y}{z^3} - \frac{3x^2 y}{z^5} \right) + \frac{MN}{z^3} \left\{ \frac{y}{z^3} - \frac{3x^2 y}{z^5} - \frac{3x^2 y}{z^5} + \frac{9x^2 y}{z^7} - \frac{3x^2 y}{z^5} + \frac{9x^2 y}{z^7} + 9 \frac{x^2 y z^2}{z^7} \right\}$$

$$= M_c \left( \frac{y}{z^3} - \frac{3x^2 y}{z^5} \right) + \frac{MN}{z^6} y$$

$$\frac{\partial}{\partial y} \left\{ M_c \left( \frac{x}{z^3} - \frac{3x^3}{z^5} \right) + MN \frac{y}{z^6} \right\} - \frac{\partial}{\partial x} \left\{ M_c \left( \frac{y}{z^3} - \frac{3x^2 y}{z^5} \right) + MN \frac{y}{z^6} \right\} =$$

$$M_c \left\{ -\frac{3xy}{z^5} + \frac{15x^3 y}{z^7} + \frac{3xy}{z^5} - \frac{15x^3 y}{z^7} - \frac{6xy}{z^5} \right\} + MN \left\{ -\frac{24xy}{z^8} + \frac{6xy}{z^8} \right\}$$

$$= M_c \left( -\frac{6xy}{z^5} \right) + MN \left( \frac{18xy}{z^8} \right)$$

$$M^2 \frac{12xy}{z^6} + MN \frac{60xy}{z^8} * = ~~48~~ \geq 0 \quad \text{zote m'moin by'}$$

*m'moin*



$$0 = \frac{\partial p_1}{\partial x} - \mu \tilde{V}(u_1 + u_2)$$

$$u_2 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_2}{\partial y} + u_2 \frac{\partial u_2}{\partial z} = - \frac{\partial p_2}{\partial y}$$

$$0 = \frac{\partial p_1}{\partial y} - \mu \tilde{V}(u_1 + u_2)$$

$$u_2 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_2}{\partial y} + u_2 \frac{\partial u_2}{\partial z} = - \frac{\partial p_2}{\partial y}$$

$$0 = \frac{\partial p_1}{\partial z} - \mu \tilde{V}(u_1 + u_2)$$

$$\text{Total cry: } (u_1 + u_2) \frac{\partial (u_1 + u_2)}{\partial x} + \dots = - \frac{\partial p_1}{\partial x} + \mu \tilde{V}(u_1 + u_2)$$

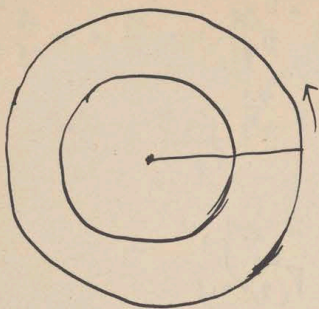
$$u_1 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial x} + u_1 \frac{\partial u_2}{\partial x} + u_2 \frac{\partial u_2}{\partial x} - = - \frac{\partial p}{\partial x} + \mu \tilde{V}(u_1 + u_2)$$

$$= - \frac{\partial (p - p_1)}{\partial x}$$

$$u_1 \frac{\partial u_1}{\partial x} + u_2 \frac{\partial u_1}{\partial x}$$

$$= \frac{\partial (p_1 + u_2 - p)}{\partial x}$$





Ruch wzdłuż okręgu

$$\frac{L}{2} = W = \text{pęd kinetyczny} = \varphi(2)$$

$$u = -\dot{\varphi} \frac{y}{r} = -\varphi y$$

$$v = \dot{\varphi} \frac{x}{r} = \varphi x$$

$$\frac{\partial u}{\partial x} = -\varphi' \frac{xy}{r}$$

$$\frac{\partial v}{\partial y} = \varphi' \frac{xy}{r}$$

$$\frac{\partial^2 u}{\partial x^2} = -\varphi'' \frac{x^2 y}{r^2} - \varphi' \frac{y}{r} + \varphi' \frac{x^2 y}{r^3}$$

$$\frac{\partial^2 v}{\partial y^2} = \varphi'' \frac{xy^2}{r^2} + \varphi' \frac{x}{r} - \varphi' \frac{xy^2}{r^3}$$

$$\frac{\partial u}{\partial y} = -\varphi - \varphi' \frac{y^2}{r}$$

$$\frac{\partial v}{\partial x} = \varphi + \varphi' \frac{x^2}{r}$$

$$\frac{\partial^2 u}{\partial y^2} = -3\varphi' \frac{y}{r} - \varphi'' \frac{y^3}{r^2} + \varphi' \frac{y^3}{r^3}$$

$$\frac{\partial^2 v}{\partial x^2} = 3\varphi' \frac{x}{r} + \varphi'' \frac{x^3}{r^2} - \varphi' \frac{x^3}{r^3}$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = -\varphi'' y - 3\varphi' \frac{y}{r}$$

$$\frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} = \varphi'' x + 3\varphi' \frac{x}{r}$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \varphi \varphi' \frac{xy^2}{r} - \varphi^2 x - \varphi \varphi' \frac{xy^2}{r} = -\varphi^2 x$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = -\varphi^2 y - \varphi \varphi' \frac{x^2 y}{r} + \varphi \varphi' \frac{x^2 y}{r} = -\varphi^2 y$$

I. Deszcz:  $\frac{\partial L}{\partial x} = 2\varphi \varphi' \frac{xy}{r} = 4\varphi \varphi' \frac{xy}{r}$  nie daję żadnego wniosku

$$\left. \begin{aligned} -\varphi^2 x &= -\frac{\partial L}{\partial x} \left| \frac{x}{2} \right. \\ -\varphi^2 y &= -\frac{\partial L}{\partial y} \left| \frac{y}{2} \right. \end{aligned} \right\} \text{nie}$$

$$\frac{dp}{dr} = \varphi^2 \frac{x^2 + y^2}{r} = r \cdot \varphi^2$$

$$p = \int \varphi^2 \cdot r \, dr$$

$\varphi$  niezmienne, dowolne  
mimo że dane mogą być  $\varphi$  na powierzchni



## II Rozwinięcie Taylor:

$$\frac{1}{\mu} \frac{\partial f}{\partial x} = -\varphi'' y - 3\varphi' \frac{y}{2} \quad \left\| \begin{array}{l} x \\ 2 \end{array} \right.$$

$$\frac{1}{\mu} \frac{\partial f}{\partial y} = \varphi'' x + 3\varphi' \frac{x}{2} \quad \left\| \begin{array}{l} y \\ 2 \end{array} \right.$$

$$\frac{1}{\mu} \frac{dp}{dr} = 0$$

$$p = \text{const}$$

$$\varphi'' + 3\frac{\varphi'}{2} = 0$$

$$\frac{d}{dr}(r^3 \varphi') = r^3 \varphi'' + 3r^2 \varphi' = r^2(\varphi'' + 3\frac{\varphi'}{2}) = 0$$

$$\frac{1}{\mu} \frac{\partial f}{\partial x \partial y} = -\varphi'' - 3\frac{\varphi'}{2} - \varphi'' \frac{xy}{2} - 3\varphi' \frac{xy}{2^2} + 3\varphi' \frac{xy}{2^3}$$

$$= \varphi'' + 3\frac{\varphi'}{2} + \varphi'' \frac{xy}{2} + 3\varphi' \frac{xy}{2^2} - 3\varphi' \frac{xy}{2^3} = 0$$

$$\frac{3}{2^4} - \frac{3xy}{2^3} - \frac{3}{2^4} - 9\frac{xy}{2^6} + 12\frac{xy}{2^6} = 0$$

wynikanie prosty  $\varphi'' = -\frac{3c}{2^4}$   
 $\varphi'' = -\frac{3c}{2^4}$

$$r^3 \varphi' = c$$

$$dp = \frac{c}{r^3} dr$$

$$\varphi = -\frac{c}{2r^2} + b$$

## III Szybkie rozwiązanie:

$$-\varphi^2 x = -\frac{\partial f}{\partial x} = \mu \left( \varphi'' y + 3\varphi' \frac{y}{2} \right) \quad \left\| \begin{array}{l} x \\ 2 \end{array} \right. \quad \frac{\partial}{\partial y}$$

$$-\varphi^2 y = -\frac{\partial f}{\partial y} = \mu \left( \varphi'' x + 3\varphi' \frac{x}{2} \right) \quad \left\| \begin{array}{l} y \\ 2 \end{array} \right. \quad -\frac{\partial}{\partial x}$$

$$-\varphi^2 \cdot \frac{x^2 + y^2}{2} = -\frac{dp}{dr} = -\varphi^2 r$$

$$-2\varphi \varphi' \frac{xy}{2} + 2\varphi \varphi' \frac{xy}{2} = \dots$$

zatem to samo rozwiązanie co przedtem

hydrozje p. tarcz hydrozje inne

$$\varphi = -\frac{c}{2r^2} + b$$

$$\varphi' = \frac{c}{r^3}$$

$$\varphi'' = -\frac{3c}{r^4}$$



Kinowicz:  $\frac{dp}{dr} = 2\varphi^2$

$$p = \int 2 \left( b - \frac{c}{2r^2} \right)^2 dr$$

$$b^2 - \frac{bc}{r^2} + \frac{c^2}{4r^2}$$

$$p = \left[ b^2 \frac{r^2}{2} - bc \ln r - \frac{c^2}{8r^2} \right] + p_0$$

Wzrost  
3 stadi: b, c, p<sub>0</sub>

Przy tym wszystkim spójrzmy teraz na wiele mi wychodzi i rachunki  
właściwie ten sam układ musi być w ustroniu (2 razem) dla ciężej i niskiej, niż dla

Właściwie przez warunki: "niskiej, niż dla" równoważenie hydrostatyczne z równowagą dla  
danych u

Wzrost:  $\left\{ \begin{aligned} u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} &= - \frac{\partial p}{\partial x} + \mu \nabla^2 u \end{aligned} \right.$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

Energia rozprężenia:  $\Phi = \mu \left\{ 2 \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 \right] + \left[ \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial z} + \frac{\partial w}{\partial y} \right)^2 \right] \right\}$

Dwa przypadki: albo u w w nie zmieniają się od x

albo ruch taki że  $\Phi = 0$

To ostatnie tylko możliwe jeżeli  $\frac{\partial u}{\partial x} = \dots = 0$  jeżeli  $\mu$  stała  
albo też  $\mu$  niskiej, male



Wzrosty pępeków rozpręci i potę  $\mu$  wolic' coraz mniejsze  
i myślenia:

zdeby rozwinę:  $u = u_0 + \mu u_1 + \frac{\mu^2}{2} u_2 + \dots$

zinde w głu mialin teli rozwinę

$$\frac{\partial u}{\partial x} = \frac{\partial u_0}{\partial x} + \mu \frac{\partial u_1}{\partial x}$$

zanisbać myśli wzia potę i z yj's th' pinnog: 0

$$u_0 \frac{\partial u_0}{\partial x} + v_0 \frac{\partial u_0}{\partial y} + w_0 \frac{\partial u_0}{\partial z} = - \frac{\partial p_0}{\partial x}$$

$$u_0 \frac{\partial u_1}{\partial x} + v_0 \frac{\partial u_1}{\partial y} + w_0 \frac{\partial u_1}{\partial z} + u_1 \frac{\partial u_0}{\partial x} + v_1 \frac{\partial u_0}{\partial y} + w_1 \frac{\partial u_0}{\partial z} = - \frac{\partial p_1}{\partial x} + \nabla^2 u_0$$

$$\frac{u_0 \frac{\partial (u_0 + u_1)}{\partial x} + v_0 \frac{\partial (u_0 + u_1)}{\partial y} + w_0 \frac{\partial (u_0 + u_1)}{\partial z} + (u_0 + u_1) \frac{\partial u_0}{\partial x} + (v_0 + v_1) \frac{\partial u_0}{\partial y} + (w_0 + w_1) \frac{\partial u_0}{\partial z}}{\partial x} = - \frac{\partial (p_0 + p_1)}{\partial x} + \nabla^2 u_0$$

$$u_\mu = (u)_0 + \mu \left( \frac{\partial u}{\partial \mu} \right)_0 + \frac{\mu^2}{1.2} \left( \frac{\partial^2 u}{\partial \mu^2} \right)_0 + \dots$$

$$u_1 = \left( \frac{\partial u}{\partial \mu} \right)_0 \text{ etc.}$$

$$\left( \frac{\partial}{\partial \mu} \left[ u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right] \right)_0 = - \left( \frac{\partial p}{\partial x \partial \mu} \right)_0 + \nabla^2 u$$



Ještě nutk vztahující od  $\mu$  k rovnováze:

$$\begin{array}{l|l|l} u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = - \frac{\partial p}{\partial x} & \Delta^2 u = 0 & \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \\ u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = - \frac{\partial p}{\partial y} & \Delta^2 v = 0 & \\ u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = - \frac{\partial p}{\partial z} & \Delta^2 w = 0 & \end{array}$$

$$\underbrace{v \frac{\partial^2 u}{\partial x^2} - u \frac{\partial^2 v}{\partial x^2}}_0 + \underbrace{v \frac{\partial^2 u}{\partial y^2} - u \frac{\partial^2 v}{\partial y^2}}_0 = 0$$

Rychlost  $\frac{\partial p}{\partial x}$ :

$$u \frac{\partial u}{\partial x} + v \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + w \left( \frac{\partial u}{\partial z} - \frac{\partial w}{\partial x} \right) + v \frac{\partial v}{\partial x} + w \frac{\partial w}{\partial x}$$

$$\frac{1}{2} \frac{\partial}{\partial x} (u^2 + v^2 + w^2) + v \xi - u \eta = - \frac{\partial p}{\partial x}$$

$$\frac{1}{2} \frac{\partial}{\partial y} (u^2 + v^2 + w^2) + w \xi - u \zeta = - \frac{\partial p}{\partial y}$$

$$\frac{1}{2} \frac{\partial}{\partial z} (u^2 + v^2 + w^2) + u \eta - v \zeta = - \frac{\partial p}{\partial z}$$

$$\begin{array}{l} \cancel{u \frac{\partial u}{\partial x} + u \frac{\partial v}{\partial y} + u \frac{\partial w}{\partial z}} \\ \cancel{v \frac{\partial u}{\partial x} - v \frac{\partial v}{\partial y} - w \frac{\partial v}{\partial z}} \end{array}$$

$$V(u, \text{curl } v) = -V(p + \frac{u^2 + v^2 + w^2}{2})$$

podle toho:  $\left\{ \begin{array}{l} \text{curl } V(u, \text{curl } v) = 0 \\ \text{vroubkami} \\ \text{má být rovnováha} \\ \text{istota?} \end{array} \right.$

$$\Delta^2 v = 0$$

$$\text{div } v = 0$$

$$\pm \frac{\partial v}{\partial z} \cdot \xi$$

$$\pm w \frac{\partial \xi}{\partial z}$$

$$\frac{\partial v}{\partial y} \cdot \xi - \frac{\partial u}{\partial y} \cdot \eta + v \frac{\partial \xi}{\partial y} - w \frac{\partial \eta}{\partial y} - \frac{\partial v}{\partial x} \cdot \xi + \frac{\partial u}{\partial x} \cdot \eta - w \frac{\partial \xi}{\partial x} + u \frac{\partial \eta}{\partial x} = 0$$

$$\xi \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - \left( \xi \frac{\partial u}{\partial x} + \eta \frac{\partial v}{\partial y} + \zeta \frac{\partial w}{\partial z} \right) - w \left( \frac{\partial \xi}{\partial x} + \frac{\partial \eta}{\partial y} + \frac{\partial \zeta}{\partial z} \right) + \left( u \frac{\partial \xi}{\partial x} + v \frac{\partial \eta}{\partial y} + w \frac{\partial \zeta}{\partial z} \right) = 0$$



~~$$\text{curl}(\nabla \psi) = \nabla \times \nabla \psi = 0$$~~

$$u \Delta u = u \frac{\partial^2 u}{\partial x^2} + u \frac{\partial^2 u}{\partial y^2} + u \frac{\partial^2 u}{\partial z^2} \neq$$

$$+ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 = \frac{\partial}{\partial x} \left( u \frac{\partial u}{\partial x} \right) + \frac{\partial}{\partial y} \left( u \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left( u \frac{\partial u}{\partial z} \right) - \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 \right]$$

$$= \frac{1}{2} \Delta(u^2) - \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 \right]$$

Strommische Ladung:

$$u = \frac{\partial}{\partial z} = f = g = 0$$

$$\left\{ \begin{array}{l} u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = - \frac{\partial f}{\partial x} \\ u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = - \frac{\partial f}{\partial y} \end{array} \right. \quad \left\{ \begin{array}{l} \Delta^2 u = 0 \\ \Delta^2 v = 0 \\ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0 \end{array} \right. \quad \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} = 0$$

$$u \left( \frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial x^2} \right) + v \left( \frac{\partial^2 u}{\partial y^2} - \frac{\partial^2 v}{\partial x \partial y} \right) = 0$$

$$u \left( \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^2 v}{\partial y^2} \right) - v \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} \right) = 0$$

$$u \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) - v \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = 0$$

wie to harmonie: tok spektrone just  $\uparrow$  spektrone



$$\Delta^2 u = 0$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = 0$$

$$\Delta^2 v = 0$$

$$u = f_1(x+iy) + \varphi(x,y) + \psi(x,y)$$

$$\frac{\partial u}{\partial x} = f_1' \quad \frac{\partial u}{\partial y} = i f_1'$$

$$\frac{\partial^2 u}{\partial x^2} = f_1'' \quad \frac{\partial^2 u}{\partial y^2} = -f_1''$$

$$v = i f_2(x+iy) = i \varphi_2(x,y) + \psi_2(x,y)$$

$$\frac{\partial v}{\partial x} = -i f_2' \quad \frac{\partial v}{\partial y} = f_2'$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$f_1' + f_2' = 0$$

$$f_1(z) = f_2(z) + c$$

$$f(x+iy) = \varphi(x,y) + i\psi(x,y)$$

$$\Delta^2 \varphi = 0 \quad \Delta^2 \psi = 0$$

$$u = \varphi(x,y)$$

$$\frac{\partial u}{\partial x} = \frac{\partial \varphi}{\partial x} = \frac{\partial \psi}{\partial y} = -\frac{\partial v}{\partial y}$$

$$\left. \begin{aligned} f' &= \frac{\partial \varphi}{\partial x} + i \frac{\partial \psi}{\partial x} \\ i f' &= \frac{\partial \varphi}{\partial y} + i \frac{\partial \psi}{\partial y} \end{aligned} \right\}$$

$$v = -\psi(x,y) + f_2(x)$$

$$\frac{\partial \varphi}{\partial x} = + \frac{\partial \psi}{\partial y}$$

$$\frac{\partial \varphi}{\partial y} = - \frac{\partial \psi}{\partial x}$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 \varphi}{\partial x^2} = - \frac{\partial^2 \psi}{\partial x^2} = \frac{\partial^2 \psi}{\partial y^2}$$

$$\frac{\partial v}{\partial x} = - \frac{\partial \psi}{\partial x} + \frac{df_2}{dx}$$

$$\frac{\partial^2 v}{\partial x^2} = - \frac{\partial^2 \psi}{\partial x^2} + \frac{d^2 f_2}{dx^2} = \frac{\partial^2 \psi}{\partial y^2} + \frac{d^2 f_2}{dx^2} = 0$$

$$\frac{\partial^2 v}{\partial y^2} = - \frac{\partial^2 \psi}{\partial y^2}$$



Pytanie: o ile warunki przeliczenia mogą być dowolniebrane?

$$e^{i\varphi} = x e^{i\varphi}$$

~~$$e^{i\varphi} = e^{i\varphi}$$~~

$$r(\cos\varphi + i\sin\varphi) = r e^{i\varphi}$$

~~$$\log(r e^{i\varphi}) = \log r + i\varphi$$~~

$$\log r(\cos\varphi + i\sin\varphi) = i\varphi + \log r$$

$$z^2 = r^2(\cos 2\varphi + i\sin 2\varphi)$$

$$= r^2 e^{2i\varphi} = r^2 \cos 2\varphi + i r^2 \sin 2\varphi$$

I.  $\log z = \log r + i\varphi$

$$u = \log r + b_1 y + c_1$$

$$v = -\varphi + b_2 x + c_2 = -\arctan \frac{y}{x} + b_2 x + c_2$$

$$\left. \begin{aligned} \frac{\partial u}{\partial x} &= \frac{x}{r^2} & \frac{\partial^2 u}{\partial x^2} &= \frac{1}{r^2} - \frac{2x^2}{r^4} \\ \frac{\partial u}{\partial y} &= \frac{y}{r^2} + b_1 & \frac{\partial^2 u}{\partial y^2} &= \frac{1}{r^2} - \frac{2y^2}{r^4} \end{aligned} \right\} \Sigma = 0$$

$$\frac{\partial v}{\partial x} = + \frac{\frac{y}{x^2} + b_2}{1 + \frac{y^2}{x^2}} = \frac{y}{x^2 + y^2} + b_2 = \frac{y}{r^2} + b_2$$

$$\frac{\partial v}{\partial y} = \frac{-\frac{1}{x}}{1 + \frac{y^2}{x^2}} = -\frac{1}{x} \frac{x^2}{y^2 + x^2} = -\frac{x}{r^2}$$

$$\frac{\partial^2 v}{\partial x^2} = -2 \frac{y x}{r^4}$$

$$\frac{\partial^2 v}{\partial y^2} = \frac{2y}{r^4}$$

$$\Sigma = 0$$



Jako krummke linje podesi nerazlozimo at mu

$$\frac{\partial}{\partial \mu} \left( \frac{u}{v} \right) = 0 \quad \frac{1}{v} \frac{\partial u}{\partial \mu} - \frac{u}{v^2} \frac{\partial v}{\partial \mu} = 0$$

$$\frac{1}{u} \frac{\partial u}{\partial \mu} = \frac{1}{v} \frac{\partial v}{\partial \mu} = \frac{1}{w} \frac{\partial w}{\partial \mu}$$

~~$$\frac{\partial}{\partial \mu} \left[ u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} \right] = \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \mu \left( \frac{\partial u}{\partial x} - \frac{\partial u}{\partial y} \right) \right) + \mu$$~~

~~$$\frac{\partial}{\partial \mu} \left[ u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} \right] = \frac{\partial}{\partial x} \left( \frac{\partial v}{\partial x} + \mu \frac{\partial v}{\partial y} \right)$$~~

$$\star \quad \frac{D u}{D \mu} = -\frac{\partial u}{\partial x} + \mu \nabla^2 u$$

$$D v = -\frac{\partial v}{\partial y} + \mu \nabla^2 v$$

$$D w = -\frac{\partial w}{\partial z} + \mu \nabla^2 w$$

$$\frac{\partial}{\partial y} D u - \frac{\partial}{\partial x} D v = \mu \nabla^2 \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right)$$

$$\text{curl } V(v \text{ curl } v) = \mu \nabla^2 \text{curl } v = -\mu \text{curl}^3 v$$

uže nerazlozimo at mu porotaj, tyklo varnik :

$$\mathcal{U} \text{curl } V(v \text{ curl } v) = \mathcal{U} \nabla^2 \text{curl } v$$

$$\frac{\partial}{\partial y} (v \xi - w \eta) - \frac{\partial}{\partial x} (u \xi - u \xi) : \frac{\partial}{\partial z} (w \xi - u \xi) - \frac{\partial}{\partial y} (u \eta - v \xi) : \dots$$

$$= \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial^2 \xi}{\partial y^2} + \frac{\partial^2 \xi}{\partial z^2} : \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial^2 \xi}{\partial y^2} + \frac{\partial^2 \xi}{\partial z^2} : \dots$$

ponovno hče stoma kontrola  $\frac{\partial}{\partial \mu}$  zati  $\frac{\partial}{\partial \mu}$

$$\frac{\partial}{\partial \mu} \left[ \frac{\partial}{\partial y} (v \xi - w \eta) - \frac{\partial}{\partial x} (w \xi - u \xi) \right] = \frac{\Delta^2 \xi}{\Delta^2 \eta}$$

$$\frac{\partial}{\partial \mu} \left[ \frac{\partial}{\partial z} (u \xi - u \xi) - \frac{\partial}{\partial y} (u \eta - v \xi) \right] = \frac{\Delta^2 \eta}{\Delta^2 \xi}$$



$$\Delta^2 \xi \left[ \frac{\partial^2}{\partial x \partial y} (\mu \tilde{v}_u) - \frac{\partial^2}{\partial y \partial x} (\mu \tilde{v}_u) \right] = -$$

$$\tilde{v}_u^2 \xi + \mu$$

Nawet bezprowadno:

$$\frac{\partial}{\partial \mu} (v \xi - v \eta) = - \frac{\partial \tilde{F}}{\partial x \partial \mu} + \tilde{v}_u^2 + \mu \frac{\partial \tilde{v}_u^2}{\partial \mu}$$

$$\tilde{v}_u^2 = \frac{\partial}{\partial \mu} \left[ \frac{\partial \tilde{F}}{\partial x} - (v \xi - v \eta) \right]$$

Powierzchnia, gdzie dwie cieple z tarciami graniczą zero:

$$\frac{D u_1}{D t} = - \frac{\partial p_1}{\partial x} + \mu_1 \tilde{v}_u^2$$

$$\frac{D v_1}{D t} = - \frac{\partial p_1}{\partial y} + \mu_1 \tilde{v}_u^2$$

$$\frac{D w_1}{D t} = - \frac{\partial p_1}{\partial z} + \mu_1 \tilde{v}_u^2$$

$$\frac{\partial u_1}{\partial x} + \frac{\partial v_1}{\partial y} + \frac{\partial w_1}{\partial z} = 0$$

$$D u_2 = - \frac{\partial p_2}{\partial x} + \mu_2 \tilde{v}_u^2$$

$$D v_2 = - \frac{\partial p_2}{\partial y} + \mu_2 \tilde{v}_u^2$$

$$D w_2 = - \frac{\partial p_2}{\partial z} + \mu_2 \tilde{v}_u^2$$

$$\frac{\partial u_2}{\partial x} + \frac{\partial v_2}{\partial y} + \frac{\partial w_2}{\partial z} = 0$$

Na powierzchni ~~gdzie dwie cieple z tarciami graniczą zero~~

$$u_1 = u_2$$

$$v_1 = v_2$$

$$w_1 = w_2$$

po upływie czasu  $\Delta t$  będzie

$$\frac{\partial}{\partial t} + u_1 \frac{\partial}{\partial x} + v_1 \frac{\partial}{\partial y} + w_1 \frac{\partial}{\partial z} = 0 \quad \left[ \frac{\partial}{\partial t} + u_2 \frac{\partial}{\partial x} + \dots = 0 \right]$$

co tylko możliwe jest

$$u_1 = u_2 \quad \parallel \quad v_1 = v_2 \quad \parallel \quad w_1 = w_2 \quad \text{na powierzchni}$$

oprac. typ. Tak samo:

$$l_{p_{xx}} + m_{p_{xy}} + n_{p_{xz}} = l_{p_{xx}} + m_{p_{xy}} + n_{p_{xz}} \quad \text{itd.}$$



Dečki poročila v črni

Tak samo jak poby parie bylo rohoram jako - 2

$$\frac{Du_1}{Dt} = -\frac{\partial p}{\partial x} + \mu_1 \nabla^2 u_1 \quad \Bigg| \quad \frac{Du_2}{Dt} = -\frac{1}{\rho_2} \frac{\partial p}{\partial x} + \frac{\mu_2}{\rho_2} \nabla^2 u_2$$

$$\mu_1 = \cancel{0.017} \\ = 0.017$$

$$\left. \begin{array}{l} \rho_2 = 0.0013 \\ \mu_2 = 0.00017 \end{array} \right\} \frac{\mu_2}{\rho_2} = \frac{0.17}{1.3} = 0.13$$

$$\left. \begin{array}{l} \text{Glede na } \rho_2 = 0.00009 \\ \mu_2 = 0.00009 \end{array} \right\} \frac{\mu_2}{\rho_2} = 1.0$$

Weniger:

Wic je poby porych wady udeginu u, ni udeginu, to jini fardes u  $H_2$

Na porychni:

Wkadyje os'  $Ox$  u  $z$

$Oy$  u  $z \perp$

$Oz$  u  $z \parallel$

$$z=a \quad \left. \begin{array}{l} u_1 = u_2 = 0 \end{array} \right\}$$

$$v_1 = v_2$$

$$w_1 = w_2 = 0$$

$$-p + 2\mu_1 \frac{\partial u_1}{\partial x} = -p + 2\mu_2 \frac{\partial u_2}{\partial x}$$

$$\mu_1 \left( \frac{\partial u_1}{\partial y} + \frac{\partial v_1}{\partial x} \right) = \mu_2 \left( \frac{\partial u_2}{\partial y} + \frac{\partial v_2}{\partial x} \right)$$

$$\mu_1 \left( \frac{\partial u_1}{\partial z} + \frac{\partial w_1}{\partial x} \right) = \mu_2 \left( \frac{\partial u_2}{\partial z} + \frac{\partial w_2}{\partial x} \right) \quad \Bigg| \quad v=0$$

Glavni:  $\mu_1 \frac{\partial v_1}{\partial x} = \mu_2 \frac{\partial v_2}{\partial x}$



$\mu_1 \dot{\theta}_1$  i  $\mu_2 \dot{\theta}_2$  będące rot. typ sążys ujęd. ułkon.

$$\frac{\partial p_1}{\partial x} \dots \frac{\partial p_2}{\partial x}$$

2. ten moży dnoję  $\frac{Dp_1}{Dt}$  mianu pręci zaniwku  $\rho_2 \frac{Dp_2}{Dt}$

1. to u typ sążys ujęd. ułkon.

Przebieg dla ułk:

$$\begin{aligned} u &= \frac{\partial \varphi}{\partial x} = c \left[ 1 + \frac{a^3}{2r^3} \left( 1 - \frac{3x^2}{r^2} \right) \right] \\ v_\omega &= -\frac{3c \cdot a^3}{2r^5} \times \omega \end{aligned} \quad \left. \begin{aligned} \varphi &= c \left( x + \frac{a^3 x}{2r^3} \right) = c x \left[ 1 + \frac{a^3}{2r^3} \right] \\ &= c r \cos \theta \left[ 1 + \frac{a^3}{2r^3} \right] \end{aligned} \right\}$$

Wzrostu poci dnoję:  $v_\theta = \left( \frac{\partial \varphi}{\partial \theta} \right)_{r=\text{const}} = -c r \sin \theta \left[ 1 + \frac{a^3}{2r^3} \right]$

$$\left. \frac{\partial v_\theta}{\partial r} \right|_{r=a} = -c \sin \theta \left[ 1 + \frac{a^3}{2r^3} - \frac{a^3}{r^3} \right] \bigg|_{r=a} = -\frac{c}{2} \sin \theta$$

$$\left. v_\theta \right|_{r=a} = -\frac{3}{2} a c \sin \theta$$



Jeżeli prędkość wzdłuż osi  $x$  jest mała, to

Np.  $\rho = 1 \text{ m}$

$\rho = 1.5 \cdot 10^{-6}$

$\mu = 0.00017$

$\frac{\mu}{\rho} = 100 !$

$\frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$

$\rho \frac{Du}{Dt} = - \frac{\partial p}{\partial x} + \mu \nabla^2 u$

gdzie  $p$  to ciśnienie

zatem przybliżenie:  $\nabla^2 u = 0$

$\nabla^2 v = 0$

$\nabla^2 w = 0$

$\nabla^2 v = 0$

ale to nie ma sensu

stąd  $\nabla^2 = 0$

czyli  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$

Nie zmienia się  $\frac{\partial}{\partial t}$

zatem przy dany warunek graniczny nie zmienia się z czasem

Wzrost nie zmienia się wzdłuż osi  $x$  (nie ma efektu składowego)

Patrz Lamb p. 526 (dla warunku  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$ )

Np. kula dla  $\mu = 0$  mamy  $u = c, v = w = 0$

$x = 0$

$u = v = w = 0$

W

Z tego wynika, że  $v = w = 0$  wszędzie

$u = c \left[ 1 - \frac{a}{r} \right]$

Wzrost jest mały i powstaje w kierunku przeciwnym do kierunku

wzrostu graniczne wartości

$u = c_1$

$v = c_2$

$w = c_3$

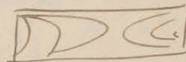
ale przy  $\mu = 0$  powstaje



rozpraszanie i odbicie fal:  $U$  i elektromagnetyczne warunki brzegowe na granicy potencjału

związek prądu i napięcia,  $E$  i potencjału i napięcia.

Przebieg prądu i napięcia wzdłuż linii i wzdłuż powierzchni bloku



W tamtych przykładach:

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = \frac{\mu_0 a x}{r^3}$$

$$S + AR = C$$

$$1 + \frac{AR}{\epsilon} = k$$

$$\frac{AR}{\epsilon} = k - 1$$

$$\frac{c}{A} \rho \frac{\partial \theta}{\partial t} + \rho \frac{\partial u}{\partial x} = 2\mu \left[ + \frac{2}{3} \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 \right] + \kappa \Delta^2 \theta$$

$$\frac{\partial \theta}{\partial t} + u \frac{\partial \theta}{\partial x}$$

$$\frac{c}{A} \rho \mu_0 \left[ 1 - \frac{a}{r} \right] \frac{\partial \theta}{\partial x} + \rho R \theta \frac{\mu_0 a x}{r^3} = 2\mu \frac{\mu_0^2 a^2}{r^6} \left[ r^2 + z^2 + \frac{2}{3} x^2 \right]$$

$$r^2 = \frac{x^2}{3}$$

$$\frac{\partial(\rho u)}{\partial x} = 0$$

$$\frac{\mu \frac{\partial \rho}{\partial x} + \rho \frac{\partial \mu}{\partial x}}{\partial x} = 0$$

$$\rho u = \text{const} = \rho_0 u_0$$

$$\rho = \frac{\rho_0}{1 - \frac{x}{r}}$$

[zgodnie na podstawie naszego rozumowania]  
organizacji tej to zachodzi powstanie  
ruch v, v

$$\frac{c}{A} \rho_0 \mu_0 \frac{\partial \theta}{\partial x} + \theta \cdot R \cdot \rho_0 \mu_0 \frac{a x}{r^3 \left( 1 - \frac{a}{r} \right)} = 2\mu \frac{\mu_0^2 a^2}{r^6} \left( r^2 - \frac{x^2}{3} \right)$$

$$\frac{\partial \theta}{\partial x} + \theta (k-1) \frac{a}{r^2 - a r} \frac{x}{r} = 2\mu \frac{k-1}{R} \frac{\mu_0 a^2}{\rho_0} \frac{r^2 - \frac{x^2}{3}}{r^6}$$

$$\frac{a}{r^2 - a r} = -\frac{1}{r} + \frac{1}{r-a} \left[ \frac{\partial}{\partial x} \log \left( \frac{r-a}{r} \right) \right]$$



$$\frac{\partial \theta}{\partial x} + \theta X_1 = X_2$$

~~$$\theta = a e^{\int \dots}$$~~  $\theta = 2y$

$$y \frac{dz}{dx} + X_1 z y + 2 \frac{dy}{dx} = X_2$$

$$X_1 y + \frac{dy}{dx} = 0$$

$$\theta = e^{-\int X_1 dx} \left[ C + \int X_2 e^{\int X_1 dx} dx \right]$$

$$y = e^{-\int X_1 dx}$$

$$X_1 = (k-1) \frac{\partial}{\partial x} \ln \frac{r-a}{r}$$

$$\int X_1 dx = (k-1) \ln \frac{r-a}{r} \quad \text{so } \ln \left( \frac{r-a}{r} \right)^{k-1}$$

$$e^{\int \dots} = \left( \frac{r-a}{r} \right)^{k-1}$$

$$X_2 = \frac{2\mu(k-1)}{R} \frac{u_0 a^2}{\rho_0} \frac{r^2 - \frac{x^2}{3}}{r^6}$$

$$\theta = \left( \frac{r}{r-a} \right)^{k-1} \left[ C + \frac{2\mu(k-1) u_0 a^2}{R \rho_0} \int \frac{r^2 - \frac{x^2}{3}}{r^6} \left( \frac{r-a}{r} \right)^{k-1} dx \right]$$

~~concerns in this case is that the solution is not unique~~

So we assume steady state:

At  $x = -\infty$ :  $\theta = \theta_0$  instead of  $y, z$

$$\int_0^\infty \frac{r^2 - \frac{x^2}{3}}{r^6} \left( \frac{r-a}{r} \right)^{k-1} dx = \varphi(y, z)$$

$$\theta_{-\infty} = f(y, z) + \frac{2\mu(k-1) u_0 a^2}{R \rho_0} \varphi(y, z)$$

$$f(y, z) = \theta_{-\infty} + \frac{2\mu(k-1) u_0 a^2}{R} \varphi(y, z)$$



$$\theta = \left(\frac{r}{r-a}\right)^{k-1} \left[ \theta_{\infty} + \frac{2\mu(k-1)u_0 a^2}{2\rho_0} \int_{-\infty}^x \frac{r^2 - \frac{x^2}{3}}{r^6} \left(\frac{r-a}{r}\right)^{k-1} dx \right]$$

we need to use gamma  
to simplify

$$p_{xx} = \frac{4}{3}\mu \frac{\partial u}{\partial x}$$

$$p_{rz} = 0$$

$$p_{yy} = p_{zz} = -\frac{2}{3}\mu \frac{\partial u}{\partial x}$$

$$p_{xy} = \mu \frac{\partial u}{\partial y}$$

$$p_{xz} = \mu \frac{\partial u}{\partial z}$$

$$\frac{\partial u}{\partial x} = \frac{u_0 a x}{r^3}$$

$$\frac{\partial u}{\partial y} = \frac{u_0 a y}{r^3}$$

$$\frac{\partial u}{\partial z} = \frac{u_0 a z}{r^3}$$

$$p_{rx} = \frac{u_0 a \mu}{r^4} \left( \frac{4}{3} x^2 + y^2 + z^2 \right) = \frac{u_0 a \mu}{r^4} \left( r^2 + \frac{x^2}{3} \right)$$

$$p_{ry} = \frac{u_0 a \mu}{r^4} \left( xy - \frac{2}{3} yx \right) = \frac{u_0 a \mu}{r^4} \frac{xy}{3}$$

$$p_{rz} = \frac{u_0 a \mu}{r^4} \left( xz - \frac{2}{3} xz \right) = \frac{u_0 a \mu}{r^4} \frac{xz}{3}$$

$$\sum p_{ry} = 0 \quad \sum p_{rz} = 0$$

$$\sum p_{rx} = \frac{u_0 a \mu}{a^4} a^2 \int_0^{2\pi} \left( 1 + \frac{\cos^2 \theta}{3} \right) 2\pi a^2 \sin \theta d\theta$$

$$= u_0 a \mu \cdot 2\pi \left( -\cos \theta - \frac{\cos^3 \theta}{9} \right) \Big|_0^{2\pi} = 2\pi u_0 \mu \cdot \frac{20}{9} = \frac{40}{9} a \pi u_0 \mu$$

Wise up! konstanta predložena pod vplyvom gravitácie:

$$\frac{4}{3} a^3 \pi \rho g = \frac{40}{9} a \pi u_0 \mu$$

$$u_0 = \frac{3}{10} a^2 \frac{\rho g}{\mu}$$



Przy tym samym przybliżeniu nie wzięliśmy pod uwagę ruchu żwiru u v u na powierzchni  $z=0$ .

Niech w zarysowanym naszym otęgnięciu niech, niech uwzględnimy:  $\frac{\partial \rho}{\partial x}$  ~~stale~~  
 wtedy jednak żwir nie porusza się w kierunku  $\frac{\partial u}{\partial x}$  etc.

$$\rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x} + \mu \nabla^2 u \quad \left. \begin{array}{l} \rho = \rho_0 \end{array} \right\}$$

$$\rho \frac{\partial v}{\partial t} = -\frac{\partial p}{\partial y} + \mu \nabla^2 v \quad \left. \begin{array}{l} \text{z uwzględnieniem } \mu: \end{array} \right\}$$

$$\rho \frac{\partial w}{\partial t} = -\frac{\partial p}{\partial z} + \mu \nabla^2 w \quad \left. \begin{array}{l} \text{z uwzględnieniem } \mu: \end{array} \right\} \quad \frac{\partial}{\partial x}(\rho \frac{\partial u}{\partial t}) + \frac{\partial}{\partial y}(\rho \frac{\partial v}{\partial t}) + \frac{\partial}{\partial z}(\rho \frac{\partial w}{\partial t}) = \mu \nabla^2 (\frac{\partial u}{\partial x}) =$$

$$\frac{\partial \rho}{\partial t} + \frac{\partial (\rho u)}{\partial x} + \frac{\partial (\rho v)}{\partial y} + \frac{\partial (\rho w)}{\partial z} = 0$$

$$\rho \frac{\partial}{\partial t} \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] + \left[ \frac{\partial \rho}{\partial x} \frac{\partial u}{\partial t} + \frac{\partial \rho}{\partial y} \frac{\partial v}{\partial t} + \frac{\partial \rho}{\partial z} \frac{\partial w}{\partial t} \right] =$$

$$\frac{\partial \rho}{\partial t} + \rho \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] + \mu \frac{\partial \rho}{\partial x} + \mu \frac{\partial \rho}{\partial y} = 0$$

$$\frac{\partial \rho}{\partial t} + \rho \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] + \mu \frac{\partial \rho}{\partial x} + \mu \frac{\partial \rho}{\partial y} = 0$$

Sto: statystyczny stan:

$$\mu \nabla^2 u = \frac{\partial p}{\partial x}$$

$$\mu \nabla^2 v = \frac{\partial p}{\partial y}$$

$$\mu \nabla^2 w = \frac{\partial p}{\partial z}$$

$$\frac{c}{A} \rho \frac{D\theta}{Dt} + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 2\mu \left[ \dots \right]$$



$$\frac{1}{\rho} \frac{\partial \rho}{\partial t} + \left[ \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right] + \mu \left[ \frac{\partial}{\partial x} \left( \frac{\partial \rho}{\partial x} \right) + \frac{\partial}{\partial y} \left( \frac{\partial \rho}{\partial y} \right) \right] = 0$$

$$\frac{\partial}{\partial t} (\log \rho) \quad \log \rho = \log r - \log \theta - \log R$$

Jaka emansja  $\rho$  w ruchu i ruchach węzłach wskazuje drżenie  
 zmienną termiczną? Zauważymy: inercja termiczna:

$$v = u = 0$$

$$\mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) = \frac{\partial f}{\partial x}$$

$$\frac{\partial}{\partial x} (\rho u) = 0 \quad \rho u = \text{const} \quad f(y, z)$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + R \rho \theta \frac{\partial u}{\partial x} = 2\mu \left[ -\frac{1}{3} \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 \right]$$

Stąd mamy:

$$\mu \nabla^2 u = \frac{\partial f}{\partial x} \quad \rho = \rho(x)$$

$$\frac{\rho u}{\theta} = f(y, z)$$

$$\frac{c}{AR} u \frac{1}{\theta} \frac{\partial \theta}{\partial x} + \rho \frac{\partial u}{\partial x} = 2\mu \left[ \frac{2}{3} \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 \right]$$

$$\rho(x) \frac{u}{\theta} = f(y, z) \quad \rho = \frac{\theta}{u} f(y, z)$$

$$\frac{u}{\theta} \frac{\partial \rho}{\partial x} + \rho \frac{\partial}{\partial x} \left( \frac{u}{\theta} \right) = 0 \quad \mu \nabla^2 u = \frac{\partial f}{\partial x} = f(y, z) \frac{\partial}{\partial x} \left( \frac{\theta}{u} \right)$$

$$\mu \nabla^2 u = R \left( \theta \frac{\partial \rho}{\partial x} + \rho \frac{\partial \theta}{\partial x} \right)$$

$$\mu \left| \begin{array}{l} \rho u = f(y, z) \\ \rho \theta = \rho(x) \end{array} \right.$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + R \rho \theta \frac{\partial u}{\partial x} = 2\mu \left[ \frac{2}{3} \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 \right]$$

$$\left( \frac{c}{A} + R \right) \rho u \frac{\partial \theta}{\partial x} + R \left( \theta u \frac{\partial \rho}{\partial x} + \rho \theta \frac{\partial u}{\partial x} \right) = \mu \left[ u \nabla^2 u + 2 \left( \frac{2}{3} \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 \right) \right]$$



by motion equations from  $\theta = f(r)$  ?

$$\text{rot } \rho = \varphi(r) = \frac{k}{R f(r)}$$

$$\left. \begin{aligned} \mu \nabla^2 u &= \frac{\partial f}{\partial x} \\ \mu \nabla^2 v &= \frac{\partial f}{\partial y} \\ \mu \nabla^2 w &= \frac{\partial f}{\partial z} \end{aligned} \right\}$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$\downarrow$$

$$I) \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = 0$$

$$II) \frac{c}{A} \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + f \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 2\mu [ \dots ]$$

$$II) \frac{c}{A} \varphi(r) f(r) \left( u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) + f \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = \uparrow$$

$$I) \varphi(r) \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \varphi'(r) \left( u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) = 0$$

$$f(r) = \frac{k}{R \varphi(r)}$$

$$I) u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} = \mu (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w)$$

$$f(r) = \frac{1}{R} \left[ \frac{1}{\varphi(r)} - \frac{r \varphi'(r)}{\varphi(r)^2} \right]$$

$$\frac{\varphi'(r)}{\varphi(r)} = - \frac{\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}}{\mu (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w)}$$

$$\frac{c}{A} \varphi(r) f(r) \mu (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) \neq \mu \mu [u \Delta u + \dots] \frac{\varphi'(r)}{\varphi(r)} = 2\mu [ \dots ]$$

$$(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) \left[ \frac{c}{A} \varphi(r) f(r) - \mu \frac{\varphi'(r)}{\varphi(r)} \right] = 2\mu \left[ -\frac{1}{3} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + \frac{\partial^2 u}{\partial x^2} \mu \right]$$

$$\left[ \frac{c}{AR} \left( 1 - \frac{r \varphi'(r)}{\varphi(r)} \right) - \mu \frac{\varphi'(r)}{\varphi(r)} \right]$$

$$AR = C - c$$

$$\frac{c}{C - c} = \frac{1}{k - 1}$$

$$\left[ \frac{1}{k-1} - \frac{k}{k-1} \frac{r \varphi'(r)}{\varphi(r)} \right]$$



Łatwiej było się robić ~~z~~ w ten sposób:  $\theta = \text{const}$   
 $f = \theta_0$

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$$\varphi = \frac{f}{2\theta_0}$$

$$\varphi' = \frac{1}{2\theta_0}$$

$$f \cdot \varphi' = 1$$

$$\left[ \frac{1 - \frac{f}{k^2}}{k^2} \right]$$

Wtedy:

$$-(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) = 2 \left[ -\frac{1}{3} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + \dots \right]$$

$$\begin{aligned} & 3(u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) - 2 \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + 6 \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 \right] + \\ & + 3 \left[ \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial z} \right)^2 + \left( \frac{\partial u}{\partial z} + \frac{\partial v}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right] = 0 \end{aligned}$$

W jednowymiarowym przypadku  $v = w = 0$ :

$$3 u \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) - 2 \left( \frac{\partial u}{\partial x} \right)^2 + 6 \left( \frac{\partial u}{\partial x} \right)^2 + 3 \left( \frac{\partial u}{\partial z} \right)^2 + 3 \left( \frac{\partial u}{\partial y} \right)^2 = 0$$

$$4 \left( \frac{\partial u}{\partial x} \right)^2 + 3 u \frac{\partial^2 u}{\partial x^2} + 3 \left[ u \frac{\partial^2 u}{\partial y^2} + \left( \frac{\partial u}{\partial y} \right)^2 + u \frac{\partial^2 u}{\partial z^2} + \left( \frac{\partial u}{\partial z} \right)^2 \right] = 0$$

$$\frac{\partial}{\partial y} \left( u \frac{\partial u}{\partial y} \right) + \frac{\partial}{\partial z} \left( u \frac{\partial u}{\partial z} \right)$$

Jednowymiarowy przypadek:

$$4 \left( \frac{\partial u}{\partial x} \right)^2 + 3 u \frac{\partial^2 u}{\partial x^2} = 0$$

$$4 \frac{\frac{\partial u}{\partial x}}{u} + 3 \frac{\frac{\partial^2 u}{\partial x^2}}{\frac{\partial u}{\partial x}} = 0$$

$$\ln \left[ u^4 \cdot \left( \frac{\partial u}{\partial x} \right)^3 \right] = \text{const}$$

$$\frac{du}{dx} \cdot u^{\frac{16}{3}} = C$$

$$\frac{3}{7} u^{\frac{19}{3}} = Cx + C_0$$



podstawiając  
Prora i opł. nie jest oznaczona przez  $\iint_{\Sigma} p \, dS = \mu \int_V \nabla^2 u + \nabla u \cdot \mathbf{n} \, dV$

$$\frac{\partial p}{\partial x} = \mu \nabla^2 u$$

tylko przez  $\iint_{\Sigma} p \, dS$  nie da się.

$$\iiint_V \left( u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z} \right) dV = \iint_{\Sigma} u p \, dy \, dz + v p \, dx \, dz + w p \, dx \, dy -$$

$$- \iiint_V p \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dx \, dy \, dz$$

$$= \iint_{\Sigma} p (u \cos \alpha_x + v \cos \alpha_y + w \cos \alpha_z) dS - \iiint_V p \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dx \, dy \, dz$$

zatem:

$$\left( \frac{\partial u}{\partial x} + \dots \right) + u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z} = 0$$

$$\mu \iiint_V (\nabla^2 u + \dots) dV = W_p -$$

Ważne jest jednak pamiętać, że ciężar  $\mathbf{g}$  jest stały i skierowany pionowo w dół, natomiast ciśnienie hydrostatyczne zmienia się z głębokością.

$$W_{pI} = \mu \iiint_V (\nabla^2 u + \dots) dV + \iiint_V p \left( \frac{\partial u}{\partial x} + \dots \right) dV$$

$$= \iint_{\Sigma} p (u \cos \alpha_x + v \cos \alpha_y + w \cos \alpha_z) dS$$

albo też przez funkcję  $\Phi$ :

$$W_{pI} = \iiint_V \Phi \, dV \quad \text{to ostatnie zero widać}$$

$$W_{pI} \text{ jako } \int_1^2 p \, dV = p_2 \int_2 (u \cos \alpha_x + v \cos \alpha_y + w \cos \alpha_z) dS - p_1 \int_1 (u \cos \alpha_x + \dots) dS$$

zatem



Równanie wypłoni daje dla dowolnego przekroju prędkość upływu przez ten przekrój:

$$\int \rho(u l + v m + w n) dS = \text{const} = m$$

gdyż  $\rho = \rho(p)$  jest tylko funkcją  $p$ , wtedy ~~przekrój~~ dla tych samych przekrojów: (independ.)

$$\rho_1 \int_1 = \rho_2 \int_2$$

$$\rho_1 \int_1 - \rho_2 \int_2 = 0 \quad f(p_1) \int_1 - f(p_2) \int_2 = 0$$

skąd z tego wynika niezmienniczość:  $p_1 \int_1 - p_2 \int_2 = 0$

tylko wtedy jeżeli  $f(p) \propto p$ , to energia w układzie izolowanym

Inercyj równanie to musi być spełnione tylko w szczególnych przypadkach.

$$\int_1 = \frac{m}{\rho_1} = \cancel{m} m V_1$$

$$W_{p \mp} = m(p_2 V_2 - p_1 V_1) = m R(\theta_2 - \theta_1)$$

$$\delta Q = \cancel{dU} + dW$$

$W_{p \mp}$  jest praca, którą możemy zamienić, utrudniającą przepływ, musi wynosić.



$$W_{\Gamma\Sigma} = \int (u \nabla^2 u + \dots) dv + \int \left( \frac{\partial u}{\partial x} + \dots \right) dw$$

$$= \int \left[ \frac{\partial}{\partial x} (u v) + \frac{\partial}{\partial y} (u v) + \frac{\partial}{\partial z} (u v) \right] dv \quad \text{is this hypothesis!}$$

$$\rho = \rho_0 \theta = R \int \theta \left[ \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} \right] + \rho \left[ \frac{\partial(\theta u)}{\partial x} + \frac{\partial(\theta v)}{\partial y} + \frac{\partial(\theta w)}{\partial z} \right] dv$$

$$= R \int \rho \left[ u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} + \theta \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \right] dv$$

$$= \int \left[ R \rho \left( u \frac{\partial \theta}{\partial x} + \dots \right) + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \right] dv$$

$$= \int \left[ \Phi + \left( R - \frac{c}{A} \right) \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) \right] dv$$

$$= \int \Phi dv + \left( R - \frac{c}{A} \right) \int (\rho u \theta + \rho v \theta + \rho w \theta) dv -$$

$$- \left( R - \frac{c}{A} \right) \int \theta \left[ \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} \right] dv$$

$$= \int \Phi dv + \left( R - \frac{c}{A} \right) \int \theta \rho (u + v + w) dv$$

$$W_{\Gamma\Sigma} = \int \Phi dv + \underbrace{\left( 1 - \frac{c}{AR} \right) \int \rho (u + v + w) dv}_{= W_{\Gamma}}!$$

$$\frac{c}{AR} W_{\Gamma\Sigma} = \int \Phi dv$$

$$\frac{1}{k-1} W_{\Gamma\Sigma} = \int \Phi dv$$

$$W_{\Gamma\Sigma} = (k-1) \int \Phi dv$$



$$\iiint u \nabla^2 u \, d\tau = \iiint \underbrace{u \frac{\partial u}{\partial n}}_{\frac{1}{2} \frac{\partial (u^2)}{\partial n}} dS - \iiint \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 \right] d\tau$$

$$W_{PI} = \iiint \frac{1}{2} \frac{\partial (u^2 + v^2 + w^2)}{\partial n} dS - \iiint \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial v}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial x} \right)^2 + \left( \frac{\partial w}{\partial y} \right)^2 \right] d\tau$$

$$\int \Phi \, d\tau = \mu \int dx \, dy \, dz \left\{ -\frac{2}{3} \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 + 2 \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + 2 \frac{\partial u}{\partial x} \frac{\partial w}{\partial z} + 2 \frac{\partial v}{\partial y} \frac{\partial w}{\partial z} \right] + \right.$$

$$2 \left( \frac{\partial u}{\partial x} \right)^2 + 2 \left( \frac{\partial v}{\partial y} \right)^2 + 2 \left( \frac{\partial w}{\partial z} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + 2 \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \left( \frac{\partial v}{\partial x} \right)^2 +$$

$$+ \left( \frac{\partial u}{\partial z} \right)^2 + 2 \frac{\partial u}{\partial z} \frac{\partial w}{\partial x} + \left( \frac{\partial w}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial z} \right)^2 + 2 \frac{\partial v}{\partial z} \frac{\partial w}{\partial y} + \left( \frac{\partial w}{\partial y} \right)^2 \left. \right\}$$

$$+ \frac{1}{3} \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 \right] + \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 + \dots + \dots$$

$$+ 2 \left[ \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \frac{\partial u}{\partial z} \frac{\partial w}{\partial x} + \frac{\partial v}{\partial z} \frac{\partial w}{\partial y} - \frac{2}{3} \left( \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial v}{\partial y} \frac{\partial w}{\partial z} + \frac{\partial w}{\partial z} \frac{\partial u}{\partial x} \right) \right]$$

$$= \iiint \left( \frac{1}{3} \left( u \frac{\partial u}{\partial x} l + v \frac{\partial v}{\partial y} m + w \frac{\partial w}{\partial z} n \right) dS + \underbrace{u \left( \frac{\partial u}{\partial x} l + \frac{\partial u}{\partial y} m + \frac{\partial u}{\partial z} n \right) + \dots}_{= \iiint \frac{1}{2} \frac{\partial (u^2 + v^2 + w^2)}{\partial n} dS} \right) d\tau$$

$$+ 2 \left[ u \frac{\partial v}{\partial x} m + v \frac{\partial w}{\partial y} n + w \frac{\partial u}{\partial z} l - \frac{2}{3} \left( u \frac{\partial v}{\partial y} l + v \frac{\partial w}{\partial z} m + w \frac{\partial u}{\partial x} n \right) \right] dS$$

$$- \iiint \frac{1}{3} \left( u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 v}{\partial y^2} + w \frac{\partial^2 w}{\partial z^2} \right) d\tau + \iiint \left( u \nabla^2 u + v \nabla^2 v + w \nabla^2 w \right) d\tau -$$

$$- 2 \iiint \left[ u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 w}{\partial y \partial z} + w \frac{\partial^2 u}{\partial z \partial x} - \frac{2}{3} \left( u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 w}{\partial y \partial z} + w \frac{\partial^2 u}{\partial z \partial x} \right) \right] d\tau =$$



$$= \frac{1}{3} \iint \left( u \frac{\partial u}{\partial x} l + v \frac{\partial v}{\partial y} m + w \frac{\partial w}{\partial z} n \right) dS + \frac{1}{2} \iint \frac{\partial}{\partial n} (u^2 + v^2 + w^2) dS +$$

$$\iint \left[ u \frac{\partial v}{\partial x} m + v \frac{\partial u}{\partial y} l + u \frac{\partial w}{\partial z} n + v \frac{\partial u}{\partial y} l + u \frac{\partial v}{\partial z} m + u \frac{\partial w}{\partial x} n \right] dS$$

$$\iint -\frac{2}{3} \left[ u \frac{\partial v}{\partial y} l + v \frac{\partial v}{\partial z} m + u \frac{\partial u}{\partial x} n + v \frac{\partial u}{\partial x} m + u \frac{\partial v}{\partial y} n + u \frac{\partial w}{\partial z} l \right]$$

$$- \frac{1}{3} \iiint \left( u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 v}{\partial y^2} + w \frac{\partial^2 w}{\partial z^2} \right) dv - \iiint (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) dv -$$

$$- \iiint \left[ u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 u}{\partial y \partial x} + u \frac{\partial^2 w}{\partial x \partial z} + v \frac{\partial^2 u}{\partial x \partial y} + u \frac{\partial^2 v}{\partial y \partial z} + u \frac{\partial^2 w}{\partial x \partial z} \right]$$

$$- \frac{2}{3} \left[ u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 v}{\partial y \partial z} + u \frac{\partial^2 u}{\partial x \partial z} + v \frac{\partial^2 u}{\partial x \partial y} + u \frac{\partial^2 v}{\partial y \partial z} + u \frac{\partial^2 w}{\partial x \partial z} \right] dv$$

$$\iiint = -\frac{1}{3} \iiint \left[ u \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right) + v \left( \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^2 w}{\partial y \partial z} \right) + w \left( \frac{\partial^2 w}{\partial z^2} + \frac{\partial^2 u}{\partial x \partial z} + \frac{\partial^2 v}{\partial y \partial z} \right) \right]$$

$$- \iiint (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) dv$$

$$\iiint = -\frac{1}{3} \iiint \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dv$$

$$- \iiint (u \nabla^2 u + v \nabla^2 v + w \nabla^2 w) dv$$

$$\iiint = \frac{1}{2} \iint \frac{\partial}{\partial n} (u^2 + v^2 + w^2) dS + \iint \left[ u \left[ l \frac{\partial u}{\partial x} + m \frac{\partial v}{\partial x} + n \frac{\partial w}{\partial x} \right] + v \left[ l \frac{\partial u}{\partial y} + m \frac{\partial v}{\partial y} + n \frac{\partial w}{\partial y} \right] + w \left[ l \frac{\partial u}{\partial z} + m \frac{\partial v}{\partial z} + n \frac{\partial w}{\partial z} \right] \right] dS$$

$$- \frac{2}{3} \iiint \left[ u l \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + v m \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + w n \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \right] dS$$



$$\int \Phi d\omega = \frac{1}{2} \iint \frac{\partial}{\partial n} (u+v+w) d\omega + \iint (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}) (u+v+w) d\omega -$$

$$- \frac{2}{3} \iint (u+v+w) \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) d\omega -$$

$$- \iint (u \nabla u + v \nabla v + w \nabla w) d\omega - \frac{1}{3} \iint (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}) \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) d\omega$$

Die Lösung dieser Aufgabe ist:  $W_{PI} = W_{PE}$  für jedes  $\rho$  und  $\theta$ .

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = - \left[ u \frac{\partial(\log \rho)}{\partial x} + v \frac{\partial(\log \rho)}{\partial y} + w \frac{\partial(\log \rho)}{\partial z} \right]$$

$$\log \rho = \log r - \log R - \log \theta$$

$$\int \Phi d\omega = \iint \dots - \iint (u \nabla u + v \nabla v + w \nabla w) d\omega -$$

$$+ \frac{1}{3} \iint \frac{1}{r} \left( u \frac{\partial r}{\partial x} + v \frac{\partial r}{\partial y} + w \frac{\partial r}{\partial z} \right) d\omega - \frac{1}{\theta} u \frac{\partial \theta}{\partial x}$$

$$+ \frac{1}{3} \iint \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \left( u \frac{\partial(\log r - \log \theta)}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) d\omega$$

$$\frac{1}{r} \left( u \frac{\partial r}{\partial x} + v \frac{\partial r}{\partial y} + w \frac{\partial r}{\partial z} \right) - \frac{1}{\theta} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$$

$$= - \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)$$

$$\iint r \left( \frac{\partial u}{\partial x} + \dots \right) d\omega = - \iint \left( u \frac{\partial r}{\partial x} + v \frac{\partial r}{\partial y} + w \frac{\partial r}{\partial z} \right) d\omega + \iint \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) d\omega$$



$$W_{PI} = R \iiint \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) d\tau = \text{~~scribbles~~}$$

$$\begin{aligned} &= R \iint \rho (u \theta_l + v \theta_m + w \theta_n) dS - R \iiint \theta \left[ \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} \right] d\tau \\ &= R \iint \rho \theta (u_l + v_m + w_n) dS = \iint (\rho u_l + \dots) \end{aligned}$$

$$\rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \left( u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right) = R \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$$

$$\text{IV. } \rho \left( \frac{\partial u}{\partial x} + \dots \right) + \frac{c}{A} \rho \left( u \frac{\partial \theta}{\partial x} + \dots \right) = \Phi$$

$$\underbrace{\iint \rho \left( \frac{\partial u}{\partial x} + \dots \right) d\tau} + \underbrace{\frac{c}{A} \iint \rho \left( u \frac{\partial \theta}{\partial x} + \dots \right) d\tau} = \iiint \Phi d\tau$$

$$\begin{aligned} &= \iint \rho (u_l + v_m + w_n) dS + \frac{c}{A} \iint \rho \theta (u_l + v_m + w_n) dS \\ &- \iiint \left( u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right) d\tau - \frac{c}{A} \iiint \theta \left[ \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} \right] d\tau \end{aligned}$$

$$\left( 1 + \frac{c}{AR} \right) \iint \rho (u_l + v_m + w_n) dS = \iint (u \nabla u + v \nabla v + \dots) dS + \Phi d\tau$$

$$u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = \left( \frac{\partial \rho}{\partial t} + \dots \right) \rho$$

$$\begin{aligned} \frac{k}{k-1} W_{PI} &= \iiint (u \nabla u + v \nabla v + \dots) + \Phi d\tau \\ \frac{1}{k-1} W_{PI} &= \Phi_r \end{aligned}$$



$$W_{12} = - \iint (u \nabla u + v \nabla v + w \nabla w) d\mathbf{r} \quad || ?$$

$$\begin{aligned} \iint \Phi d\mathbf{r} &= \frac{1}{2} \iint \frac{\partial}{\partial x} (u^2 + v^2 + w^2) d\mathbf{r} + \iint (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}) v_x d\mathbf{r} - \frac{1}{2} \\ &- \iint (u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z}) (v_x^2 + v_y^2 + v_z^2) d\mathbf{r} - \\ &- \iint (u \nabla u + v \nabla v + w \nabla w) d\mathbf{r} + \frac{1}{3} \iint (\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z})^2 d\mathbf{r} \end{aligned}$$

$$\begin{aligned} V(v, \text{curl } v) &= -V\left(\mu + \frac{u^2 + v^2 + w^2}{2}\right) + \underbrace{\mu \nabla^2 v}_{= -\mu \text{curl}^2 v} \\ &= -\mu \text{curl}^2 v \end{aligned}$$

$$\text{curl } V(v, \text{curl } v) = -\mu \text{curl}^3 v = \cancel{\mu \text{curl}^3 v} = \mu \nabla^2 \text{curl } v$$

$$\text{div } V(v, \text{curl } v) = (\text{curl } v)^2 - \nabla v, \text{curl}^2 v = -V\left(\mu + \frac{v^2}{2}\right)$$

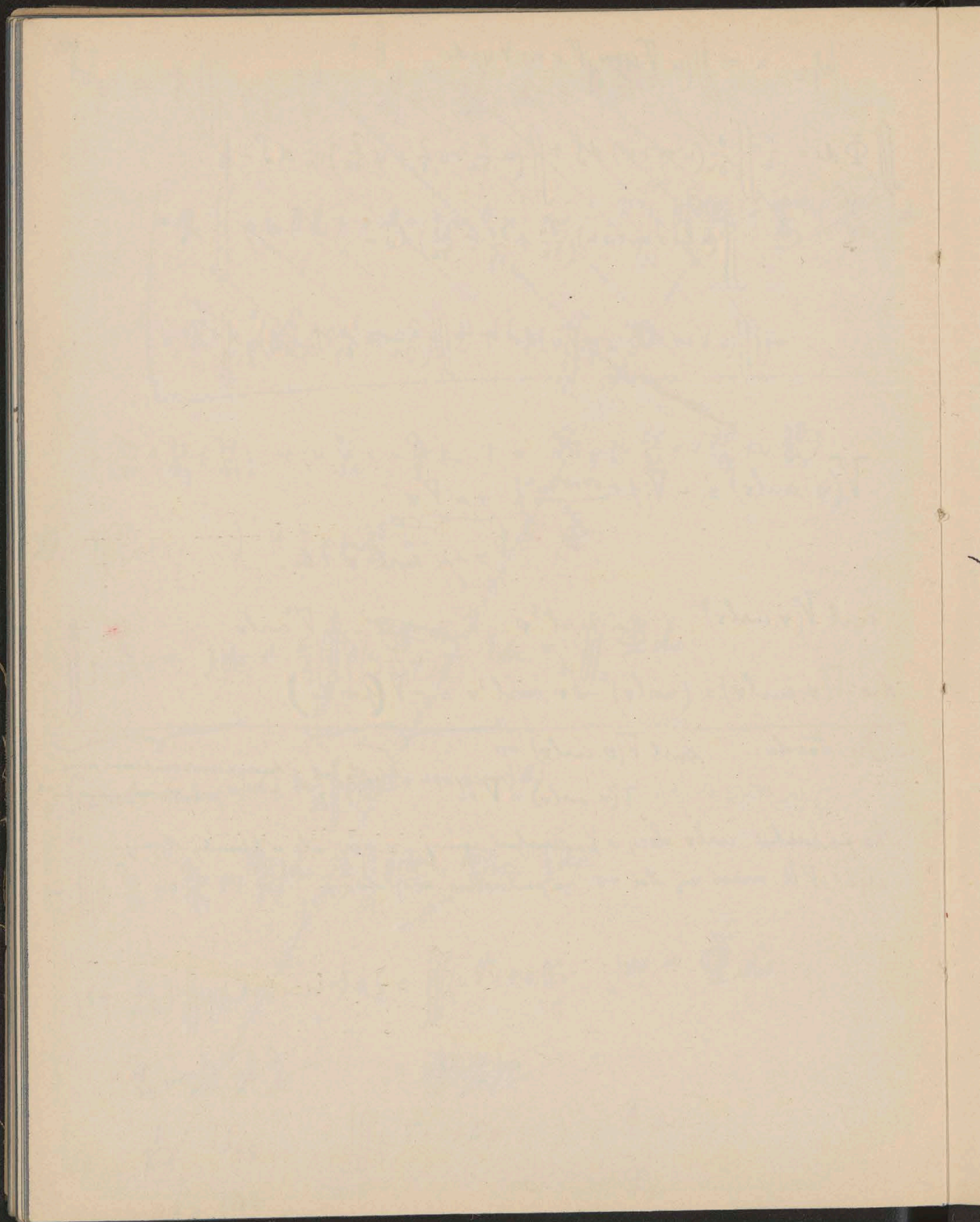
Ona twierdzenie:  $\text{curl } V(v, \text{curl } v) = 0$

$$V(v, \text{curl } v) = \nabla \mathcal{U}$$

czy to jest jedyną warunkiem koniecznym i wystarczającym?

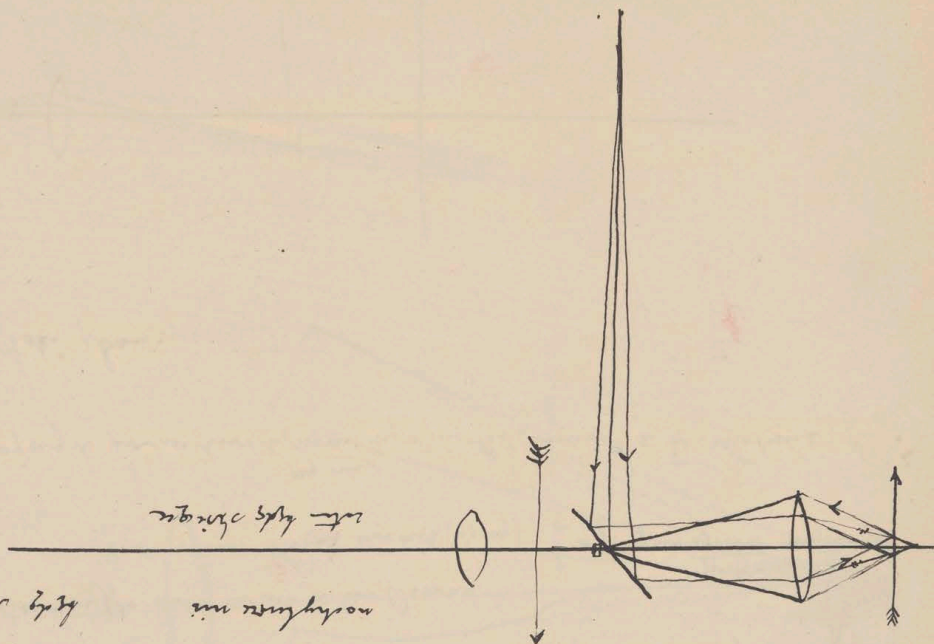
Na przykład: curl  $v$  jest w postaciach symetrycznej,  $v \in \mathbb{C}^0$ , ale w kierunku symetrycznym  
 gdzie  $\nabla \mathcal{U}$  musi się stać  $= 0$  na powierzchni nieliniowej



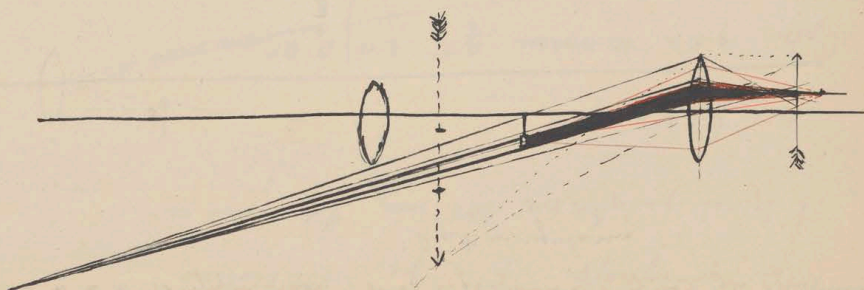




In einem bestimmten Punkt  
 nachher mit  
 der optischen  
 mit der Linse



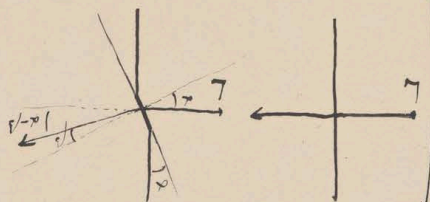
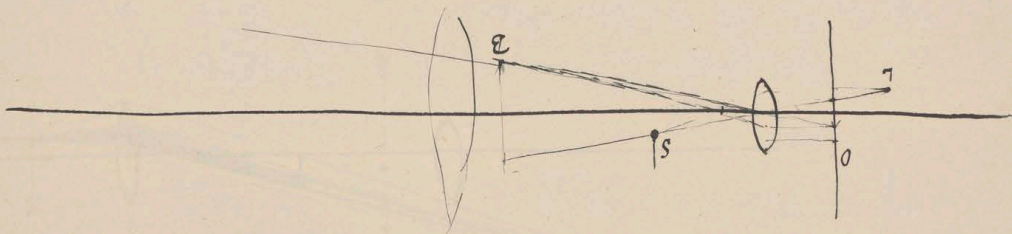
Bestimmung der:





then since  $L$  is a very sharp point, other points in  $O$  are not so sharp.

0 ist ungenau.



$$n \sin \alpha = n' \sin \alpha'$$

$$n \sin \alpha = n' \sin \alpha'$$

$$n \sin \alpha = n' \sin \alpha'$$

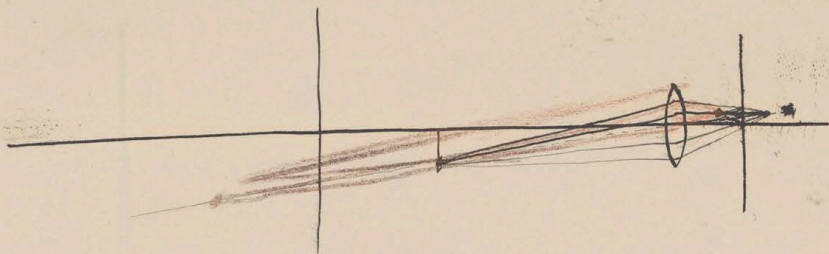
$$n \sin \alpha = n' \sin \alpha'$$

To do this, we will use the method of the previous section.

2. to show that the method is correct. [The method is correct.]

(my other eye is not so sharp, I can't see it.)

2. to show:



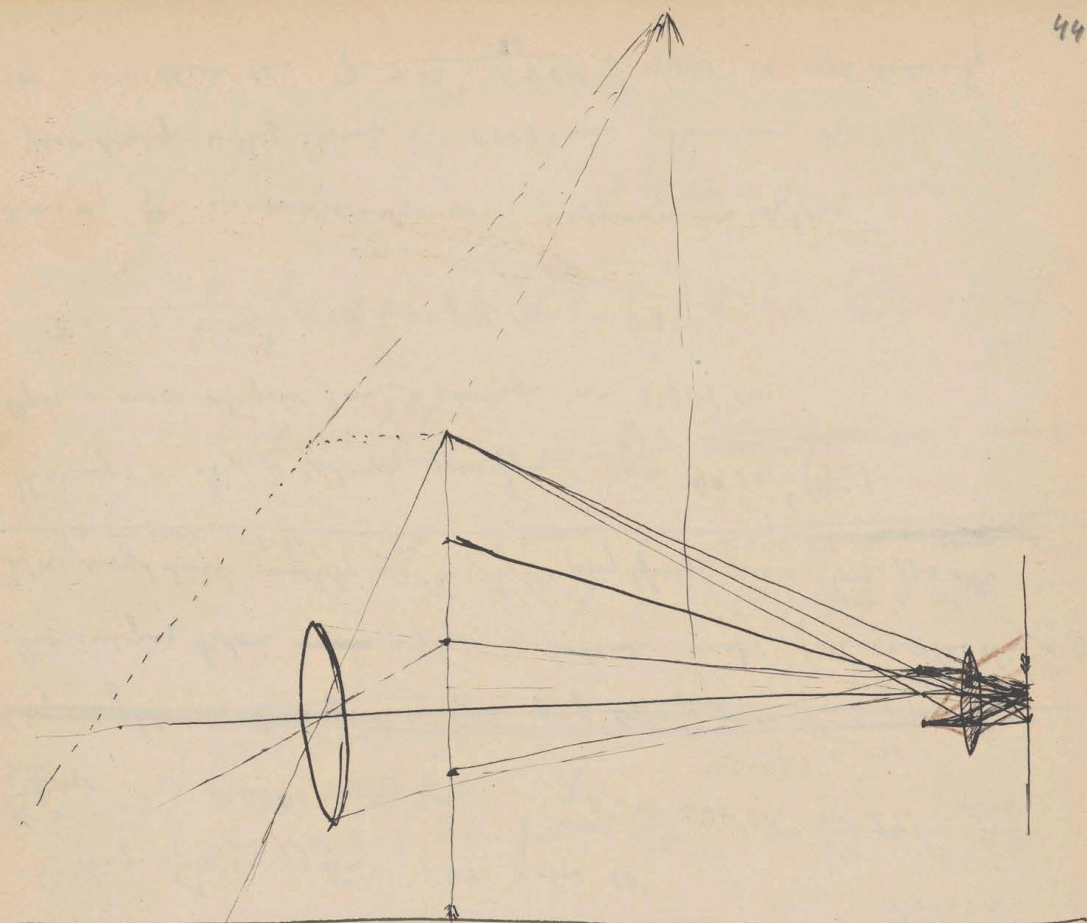


Nyct. annulatus p. 2 p. 2  
108 krone

$\rho_{\text{air}} \Delta u$  mass  $\frac{2}{2} = 10.0 \text{ g}$

$$= 204 \approx 200 \text{ sec} \quad \frac{20}{\sqrt{10}} = \frac{200}{9} \text{ sec}$$

With wide ranging effects & drugs, many other "feelings"





$N.p. \text{ pink! } 3 = \text{ ~~0.01 cm~~ } 0.01 \text{ cm}$

$$t_{1000.0} = 4$$

$$\alpha = 10$$

$$n_0 = a = 0.6 \text{ cm}$$

$$\Delta u = \Delta c = \frac{2a}{z_2} = \frac{1.2}{10^{-4}}$$

$$\gamma \Delta \tau = 0.00017 \cdot 12 \cdot 10^3 = 2.04$$

where  $\frac{\partial \epsilon}{\partial x} = 10^6$  the x-dimension is

$$m \cdot 100.0 = 3 \text{ g}$$

Stagnation  $\Delta u = 204$  wkt 10'

$\text{Kilg} = 0.0001 \text{ m} = 1 \mu$   
 $\gamma \delta_2 = 20400 = 2\%$

[illegible]

Uitgang:  $W_p$  is radonisch verspreid  $n = 4 \cdot 10^{-6} \left( \frac{\text{cm}^3}{\text{m}^3} \right)$

Opzet is meer afgeplat: 1 cm, omtrent  $n = 0.001$  cm

$$5 = \frac{9 \cdot 10^1}{9 \cdot 44 \cdot 4 \cdot 10} = 16.4 = 0.1816 = 8.0$$

27. April 1872  
 Wilmersdorf  
 Herrmannstrasse 17

1000.0 m (Munda - 0.0001)

Opportunitätskosten =  $\frac{4.10^6 \cdot 4.0.018}{3000} = 5.466,67$



$$u_0 = a = -c z^2 = \frac{2y^2}{z^2} \quad || \quad \frac{3}{2} u_0$$

$$\int_{-z}^z u dy = \frac{2y^2}{z^2} (y^2 - y^2) = \frac{2y^2}{z^2} \left( \frac{y^2}{2} - \frac{y^2}{2} \right) = \frac{2y^2}{z^2} \left( \frac{y^2}{2} - \frac{y^2}{2} \right) = \frac{2y^2}{z^2} \left( \frac{y^2}{2} - \frac{y^2}{2} \right)$$

$$u = \frac{2y^2}{z^2} (y^2 - y^2) = \frac{2y^2}{z^2} (y^2 - y^2)$$

$$\begin{cases} 0 = a - b + c z^2 \\ 0 = a + b + c z^2 \\ b = 0 \end{cases} \quad \begin{cases} 0 = a - b + c z^2 \\ 0 = a + b + c z^2 \end{cases}$$

$$u = 0 \quad y = \pm z$$

$$u = a + b y + c y^2 \quad \frac{\partial u}{\partial y} = 0 \quad \frac{\partial u}{\partial x} = 0$$

$$c = \begin{cases} r_1 = 2cyx + \text{const} \\ r_2 = 2cyx + \text{const} \end{cases}$$

$$\frac{\partial u}{\partial x} = y \quad \frac{\partial u}{\partial y} = x$$

$$u = f(x) \quad \frac{\partial u}{\partial x} = 0 \quad \frac{\partial u}{\partial y} = 0$$

$$u = f(y) \quad \frac{\partial u}{\partial x} = 0 \quad \frac{\partial u}{\partial y} = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = 0$$

$$\begin{cases} \frac{\partial u}{\partial x} = y \left( \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) \\ \frac{\partial u}{\partial y} = x \left( \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) \end{cases} \quad \begin{cases} \frac{\partial u}{\partial x} = y \\ \frac{\partial u}{\partial y} = x \end{cases}$$

$$p = \frac{r}{z^2} \quad r = R \theta p$$



This royal nurse who died a rich old woman  
 (overburdened) ~~was~~ <sup>had</sup> been a poor slave about thirty years or so.  
 These things are common among the slaves.

$$\frac{1}{\sqrt{c}} \frac{d}{dt} = \frac{d}{dt_e}$$

$$k = \frac{A_2 a_1 a_2 \tau_0}{k_0 \tau_2} \neq \frac{A_2 p_1 p_2}{k}$$

$$k \frac{1}{\frac{dx}{dt}} = u' - u$$

N. t. No. 272711 in pyrodo vinnice enuthony

Study  $u_1 = u_2 = -k$

N.Y.  $H_2$  - positive:  $k = 0.634 \frac{\text{cm}^2}{\text{sec}}$

also ich spreche in Wahrheit zu H<sup>errn</sup>: Herr? wann und wo? nicht

Wsktkt Tavis kommt per bp:  $u_1 = u_2 = 0$  no beam; odhine est magelungs  
 ophs 'mean' this is by random volatility up to order:  $\frac{2u}{2g}$  est: random

2000-10-10

Ansatz:  $\frac{\partial \psi}{\partial x} + (u_1 - u_2) A_{12} \rho_1 \rho_2 \Delta u = 0$

Wir losen nun die inhomogene Dgl. mit dem Ansatz  $u = a + by + cy^2$

$$\Delta^2 u = 2c \cdot \eta = \frac{\partial^2}{\partial x^2}$$

~~$u_0 = a$~~



Chaple

$$d = 0.3 \text{ mm}$$

$$p = \frac{0.3^2}{2} \cdot \frac{4}{28.26} = 0.07$$

$$l = 3 \text{ mm}$$

$$\frac{5}{4} \frac{d}{l} = 8\%$$

$$\frac{2}{3} \frac{d}{l} = 4\%$$

$$r = 3000$$

$$\text{Laplace: } d = 0.3 \text{ mm}$$

$$l = 2 \text{ mm}$$

$$\frac{5}{4} \frac{d}{l} = 12\%$$

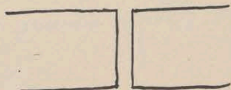
$$n = \frac{1000}{5.007} = 200$$

During spread minimum rate of change:  $\frac{d}{dt} \log \frac{1}{n} = 2\%$  more  
 Concentration maintained in network  
 During spread  $\log \frac{1}{n} = \log \frac{1}{200} = 2\%$  more  
 slightly more than 2% more



$$u_2 = 0$$

H<sub>2</sub>O



98% H<sub>2</sub>O + 10% Cu H<sub>2</sub>O  
u<sub>1</sub> ≠ 0.1

$$dS = k q \frac{\partial u}{\partial x} dt$$

$$\frac{\partial u}{\partial x} = \frac{u_1 - u_0}{x} = \frac{1}{0.1} = 0.1$$

$$dS = 0.01 \cdot 0.1 \cdot 40 \cdot 10^{-7} \cdot 60 \cdot 60 = 4.6 \cdot 6 \cdot 10^{-7} = \frac{144}{36.4} \cdot 10^{-7} \text{ g}$$

$$= 1.4 \cdot 10^{-5} \text{ g}$$

$$dS \text{ per division} = \frac{1.44 \cdot 10^{-5}}{576} = 3.5 \cdot 10^{-8} = 0.35 \text{ mg per 3 div} = 1.05 \text{ mg}$$

2 = "sawtooth" marks: 0.01 · 0.1 = 1 mg; also meaning that making very noisy measurements

$$\left( \frac{dS}{dt} = 100\% \right) \text{ then same rate mark (but very noisy measurements)}$$

All the above mentioned things are 15% of the above mentioned

the same as the "sawtooth" marks; pink diagonal = 1 mm to  $\frac{1}{2}$  psi (1% 1%)

which corresponds to a certain level in the measuring method by the marking operation

or, more precisely [Widely spaced] marks. At the point  $x + \frac{1}{2} \Delta$

$$\Delta x = 0.1 \text{ mm}; \quad \frac{1}{2} \Delta x = 8\% \quad \left( \text{very noisy measurements} \right)$$

which is not a constant value of the quantity of measurement, but

$$10^3 \cdot 10 = 10^4 \text{ marks}$$



2 types of lenses ok. 10 : 10

ok. 10 : 10

Don't know: ok. 567 ok. 1

1000

500

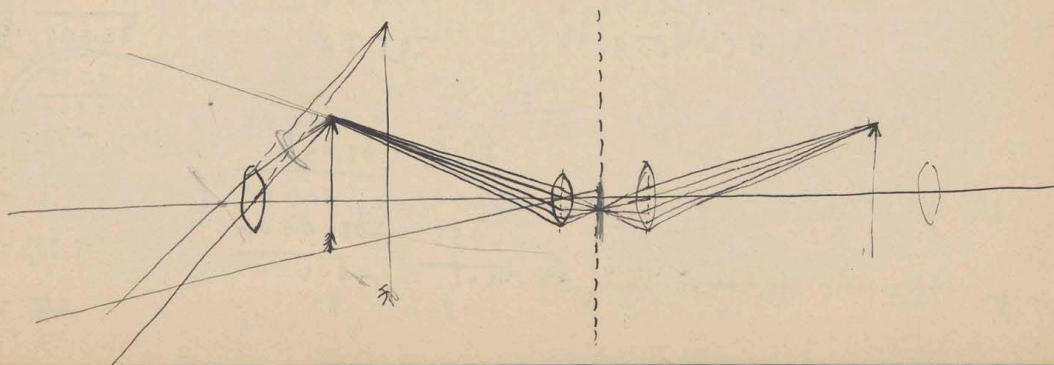
$\delta = 0.9 \text{ mm}$

$\alpha =$

$\alpha = 0.36 \text{ mm}$

$\gamma' = 0.08 \text{ mm}$

No solution 27 cm : 10 = 5 mm





The effluents x effluents = 1.6% probably the instrument  
(the good temperature line) slightly is : - 1.33%

$$\begin{aligned} 1.016 &= \frac{0.00682}{-2.51322} \\ 1 &= 2.52004 \end{aligned}$$

$$\begin{aligned} 96284-3 &+ 36212 \\ 0.22506-2 &- 0.84510 \\ 0.47996-3 & \end{aligned}$$

$$\begin{aligned} 82562 &- 41644 \\ 0.00918 & \end{aligned}$$

$$\begin{aligned} 1023 &2046 \\ 3069 &1046529 \\ 10416 &10416 \\ \hline 186 & \end{aligned}$$

$$\sqrt{49.29} = 7.02$$

$$\begin{aligned} 560 &1023 \\ 6623 &6623 \\ 6693 &6693 \\ 6553 & \end{aligned}$$

$$\begin{aligned} a &= 280 \\ b &= 1023 \\ c &= 93 \end{aligned}$$



Dr. K. S. Choudhary:

N.T.  $y = 0.002$  standard deviation  $1 - \frac{y}{x} = \frac{1}{2}$

$$1 + \rho \frac{y}{\theta} (1 - \frac{y}{x}) = 1 + 0.002 \cdot 100 \cdot \frac{1}{2} = 1 + 0.05$$

mg. amount  $\theta_1 = 93 \dots 98$

$\begin{array}{r} 98 \\ 325.5 \text{ by } 280 \\ \hline 57749 \\ - 44716 \\ \hline 13033 \end{array}$	$\begin{array}{r} 0.11504 - \\ 06222 \\ \hline 2.54388 \\ 0.06009 \end{array}$	$\begin{array}{r} 1-99114 \\ 1-99114 \end{array}$
---	--	---

Dr. K. S. Choudhary:

$$\int_0^1 \frac{dx}{280 + \frac{x}{\theta} \theta_1 \left[ 1 + \rho \frac{y}{\theta} (1 - \frac{y}{x}) \right]} \neq \int_0^1 \frac{dx}{280 + \frac{x}{\theta} \theta_1 \left[ 1 + 0.1 (1 - \frac{x}{2}) \right]}$$

$$= \int_0^1 \frac{dx}{280 + 1.1 \cdot \frac{x}{\theta} \theta_1 x - 0.1 \cdot \frac{x}{\theta} \theta_1 x^2} = k \int_0^1 \frac{dx}{280 + 1.1 \cdot \theta_1 x - 0.1 \cdot \theta_1 x^2}$$

93

$$\int \frac{dx}{a + bx - cx^2} = \frac{1}{\sqrt{b^2 - 4ac}} \log \frac{b + 2cx - \sqrt{b^2 - 4ac}}{b + 2cx + \sqrt{b^2 - 4ac}} = \frac{1}{\sqrt{b^2 - 4ac}} \log \frac{b + 2c + \sqrt{b^2 - 4ac}}{b - \sqrt{b^2 - 4ac}}$$

$$\frac{kx + 26c - 2c\sqrt{b^2 - 4ac}}{kx + 26c + 2c\sqrt{b^2 - 4ac}} = \frac{b - \sqrt{b^2 - 4ac}}{b + \sqrt{b^2 - 4ac}} + 2a$$



To log the various parts of the system.

$$h = 0.9932 \mu$$

$$\begin{array}{r} 1.96848 \\ -1.97144 \\ \hline 0.99704 \end{array}$$

$$\begin{array}{r} 0.9534 - 1 \\ 0.36222 \\ 2.51388 \\ \hline 1.97144 \end{array}$$

$$\begin{array}{r} 57.171 \\ 44.716 \\ \hline 0.12455 \end{array}$$

$$\begin{array}{r} 32.65 \\ 290 \\ \hline 32.65 \end{array}$$

$$\begin{array}{r} 93 \\ 32.657 \\ 373 \\ \hline 280 \end{array}$$

$$\theta_1 = 93$$

$$= \mu_0 \frac{1}{280+50} - \frac{1}{2} \frac{280}{\theta_1} + \dots$$

$$h = \mu_0 \frac{1}{\theta_1} \left[ \log \left( \frac{280+\theta_1}{280} \right) \right]$$

$$\frac{R}{\theta_1} \int \frac{dx}{280 + \frac{R}{\theta_1}} = \frac{R}{\theta_1} \log (280 + \frac{R}{\theta_1}) \Big|_0^R = \frac{R}{\theta_1} \log \left( \frac{280+\theta_1}{280} \right) = \mu_0 h$$

Inversion formulae  $p=0$ :

$$= \frac{R}{\theta_1} \int \frac{dx}{280 + \frac{R}{\theta_1}} = \frac{R}{\theta_1} \log (280 + 50)$$

$$\int_0^R p dx = \frac{R}{\theta_1} \int_0^R \frac{dx}{280 + \frac{R}{\theta_1}} = \frac{R}{\theta_1} \log \left( \frac{280+\theta_1}{280} \right)$$

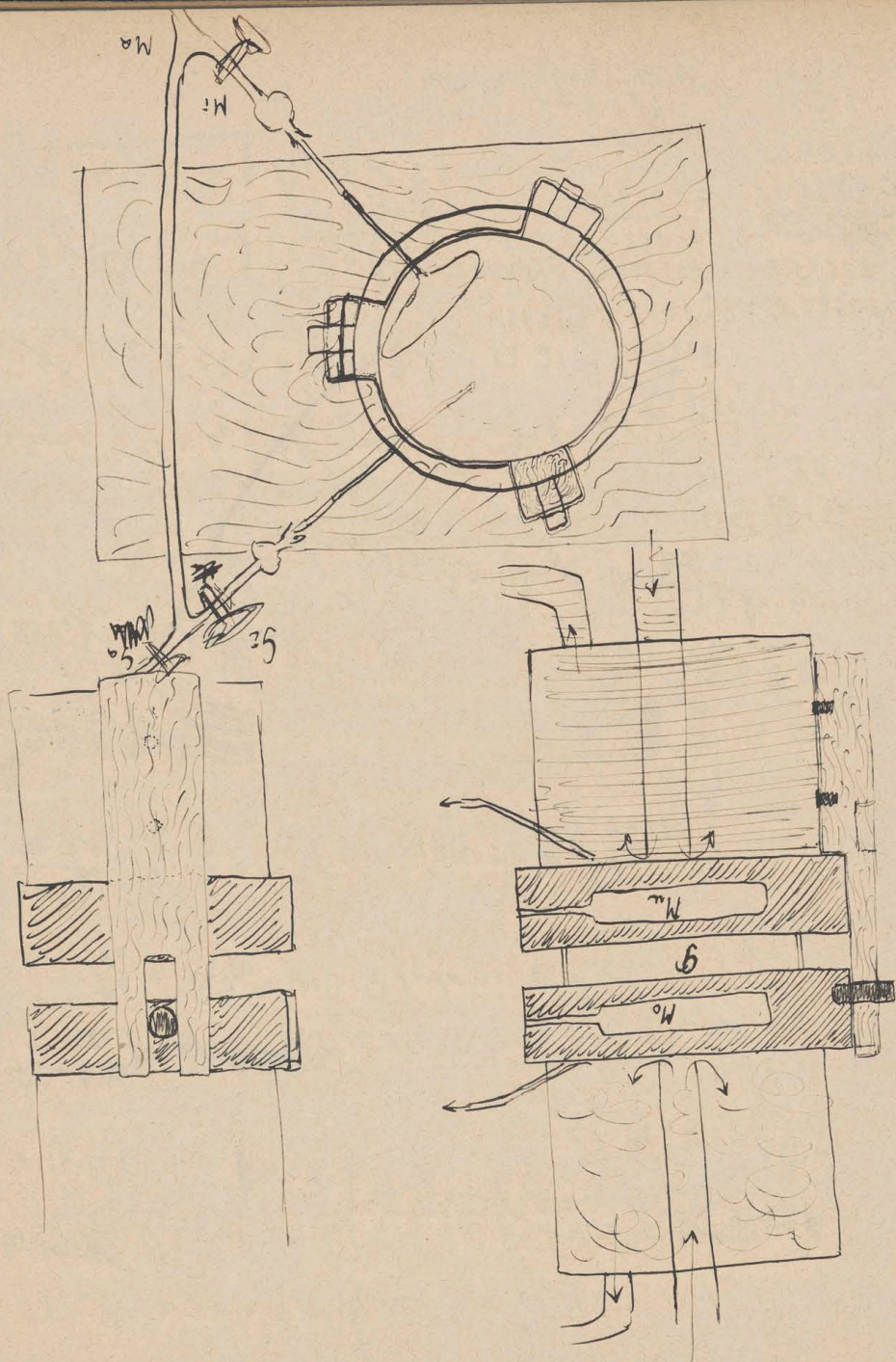
$$= \frac{R}{\theta_1} \theta_1 \left[ 1 + \log \left( \frac{280+\theta_1}{280} \right) \right]$$

$$\theta = \frac{R}{\theta_1} \left[ 1 + \log \left( \frac{280+\theta_1}{280} \right) \right]$$





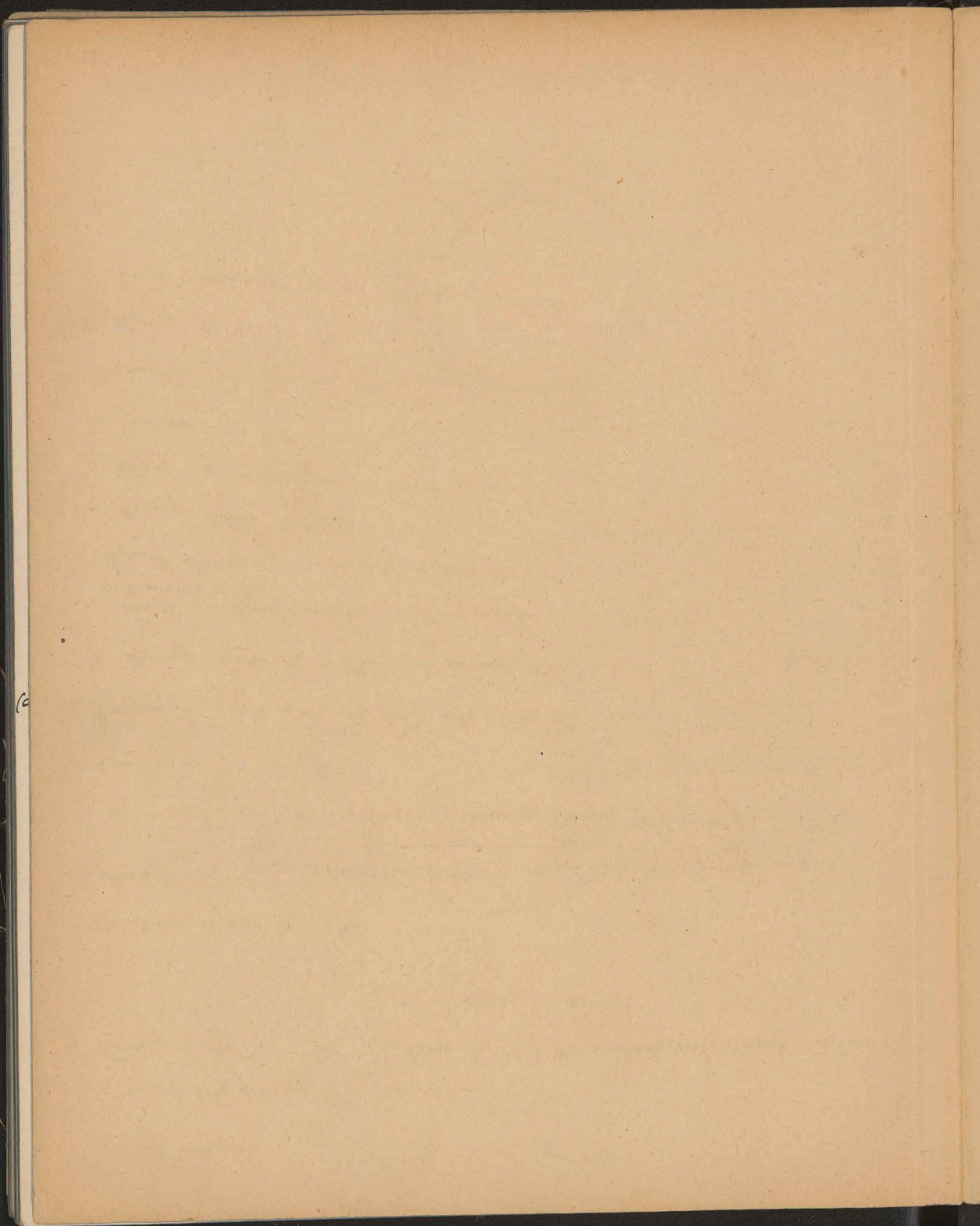






















9408

II



52



$\frac{g\alpha}{r} \sin \varphi = r \sin \varphi \omega^2$   
 $\frac{g\alpha}{r} = r \omega^2$   
 $\frac{g\alpha}{r} = \omega^2$   
 $\omega = \sqrt{\frac{g\alpha}{r}}$   
 $\omega = \sqrt{\frac{9.8 \times 0.01}{0.15}}$   
 $\omega = \sqrt{6.53}$   
 $\omega = 2.55 \text{ rad/s}$   
 $f = \frac{\omega}{2\pi} = \frac{2.55}{2\pi} = 0.405 \text{ Hz}$   
 $T = \frac{1}{f} = \frac{1}{0.405} = 2.47 \text{ s}$

$$e \frac{dr}{dt} = -(\alpha + \frac{1}{2}) \frac{dr}{dt} + \frac{1}{2} \frac{dr}{dt} + \frac{\alpha}{2} \frac{dr}{dt} = \frac{1}{2} \frac{dr}{dt}$$



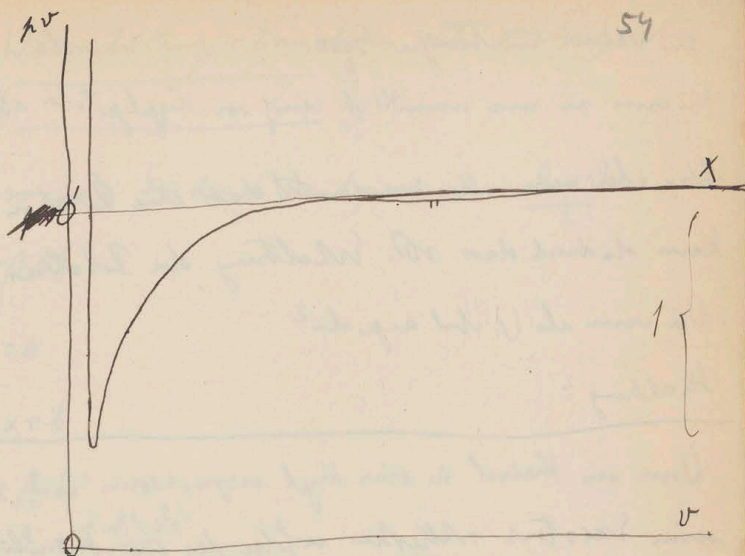
1  
1  
50  
75  
100  
15  
20  
30  
50  
100



CO<sub>2</sub>

$t = 40^\circ$

$r$	$rv$	$v$
1	1.000	1.000
50	0.8500	0.0170
75	0.6200	0.0082
100	0.3090	0.0031
150	0.3770	0.0025
200	0.4675	0.0023
300	0.6485	0.0021
500	0.9900	0.0019
1000	1.7800	0.0017



54

Wenn man die Sache auf  $0'x$  bezieht so hat man direkt den Wert von  $\sum Rr = \sum R\sqrt{v}$

<sup>in allen</sup> Die Curven werden <sup>bei verschiedenen</sup> Temperatur verschieden sein, denn bei gleichem  $v$  wird die Anzahl der

Summen der verschiedenen sein (wie  $\frac{1}{T}$  daher  $\sum$  wie  $\frac{1}{T^2}$ ) d.h. mittlere Distanzen ~~werden~~ <sup>werden</sup> wegen veränderten  $v$  wie  $T^{\frac{1}{2}}$

Wenn also  $R = f(r) = f(\sqrt{v})$  gesetzt wird so ist  $\sum Rr = \frac{1}{T^2} \sum T^{\frac{1}{2}} f(T^{\frac{1}{2}})$



Spez. Wärme inhomog. Gas.

Wie wenn sie nur unendlich wenig von Kugelgestalt abweichen? Dann wird k doch <sup>166</sup> sein

Was aber wenn man voraussetzt dass eine Rotation überhaupt nicht eintreten kann, dadurch dass v.d. Erhaltung der Rotations Ebene

Wie wenn als Virel angesehen?

Stechung?

---

Wenn ein Kreis in eine Kugel eingeschlossen wird, so kann man doch auf ~~die~~ seine Existenz schließen infolge des eigenthümlichen Verhaltens der Kugel.

Wenn aber zwei in entgegengesetzter Richtung rotirende Kreise von gleicher Trägheitsmoment in einander gesetzt werden so kann sich durch Wirkung nach aussen nicht bemerkbar machen

---



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Methode zur Messung der Wärmelitungszunahme mit der Temperatur.

2 unendliche Platten  $t \left\{ \begin{array}{l} \vartheta_1 \\ \vartheta_0 \end{array} \right.$

I). Falls  $\kappa$  constant wäre, so wäre Gasdruck entsprechend  $\frac{\vartheta_0 + \vartheta_1}{2}$

II) Dagegen wenn  $\kappa = \kappa_0 (1 + \beta \vartheta)$ :

$$\kappa_0 (1 + \beta \vartheta) \frac{d\vartheta}{dx} = \text{const.} = a$$

$$\vartheta + \beta \frac{\vartheta^2}{2} = ax + b$$

$$b = \vartheta_0 + \beta \frac{\vartheta_0^2}{2}$$

$$a = \frac{\vartheta_1 - \vartheta_0 + \beta \frac{\vartheta_1^2 - \vartheta_0^2}{2}}{h}$$

Oder wenn  $\vartheta_0 = 0$  gesetzt wird:

$$\vartheta + \beta \frac{\vartheta^2}{2} = \frac{\kappa}{h} (\vartheta_1 + \beta \frac{\vartheta_1^2}{2})$$

Mittlere Temperatur  $\Theta = \frac{1}{h} \int_0^h \vartheta dx = \frac{1}{h} \int_0^h \vartheta \frac{d\vartheta (1 + \beta \vartheta)}{a} = \frac{1}{h} \frac{\vartheta_1^2 + \beta \frac{\vartheta_1^3}{3}}{a}$

$$\Theta = \frac{1}{a h} \left( \frac{\vartheta_1^2}{2} + \beta \frac{\vartheta_1^3}{3} \right) = \frac{\frac{\vartheta_1^2}{2} + \beta \frac{\vartheta_1^3}{3}}{\vartheta_1 + \beta \frac{\vartheta_1^2}{2}} = \frac{\vartheta_1}{2} \frac{1 + \frac{2}{3} \beta \vartheta_1}{1 + \frac{1}{2} \beta \vartheta_1} \neq \frac{\vartheta_1}{2} [1 + \frac{1}{6} \beta \vartheta_1]$$

Wenn also z.B.  $\vartheta_0 = 0$

$\vartheta_1 = 100$

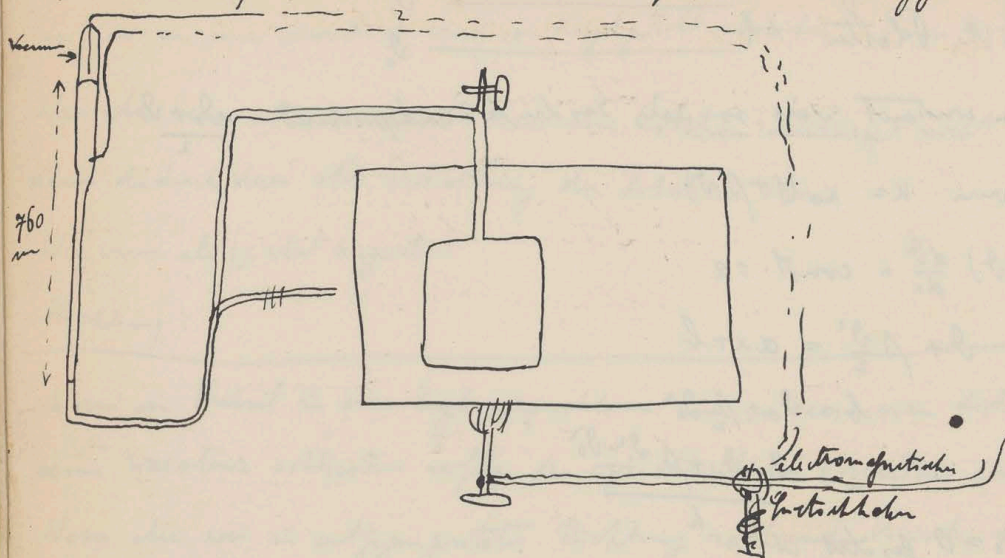
$\beta = 0.0018$

$$\Theta = 50 [1 + 0.03] = 50^\circ + 1.5^\circ$$

und zwar unabhängig von Distanz der Platten, unabhängig von Strahlung



Thermometer, welches von äusserem Luftdruck unabhängig ist:



Correctionsformel für Skaltend (Skliermarken)

$$w i^2 dx = \frac{2\pi dx}{\log \frac{R}{r}} K \log \frac{r}{\theta} + q \kappa' \frac{\partial^2 \theta}{\partial x^2}$$

$$C \# = \frac{\partial^3 \theta}{\partial x^3} = \frac{\partial}{\partial x} \left( \frac{\partial^2 \theta}{\partial x^2} \right) - \frac{\partial \theta}{\partial x} \frac{\partial^2 \theta}{\partial x^2} = \frac{\partial}{\partial x} \left[ \frac{\partial^2 \theta}{\partial x^2} - \frac{1}{2} \left( \frac{\partial \theta}{\partial x} \right)^2 \right]$$

$$C_x + C_1 = \frac{\partial^2 \theta}{\partial x^2} - \frac{1}{2} \left( \frac{\partial \theta}{\partial x} \right)^2 = \frac{\partial}{\partial x} \left( \frac{\partial^2 \theta}{\partial x^2} \right) - \left( \frac{\partial \theta}{\partial x} \right)^2$$



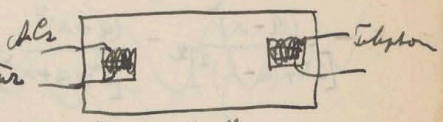
Scheinbarer Widerstand Verminderung von Wechselströmen in Umgebung von  $O_2$ ; wegen Arbeit die zur Oxidierung verbraucht wird.

Ob anderen Gasen nicht? Wie bei Erwärmung?

Hydrodynamik verdünnter Gase; Planetenatmosphären; Reibung verschiedener Gase, Diffusion, Stoney's Hypothesen; Sternschuppen; ~~Reibung~~ Druck unterbrochene in Gitter-Röhren; Druck im Funkenfelde; Schallfortpflanzung; Reibungsströme; Reibungsdrehmoment;

Strahlenbildung von Gasen

Hydrodynamik von Gasen bei kritischer Temperatur



Anwendung zur Bestimmung derselben dadurch dass kein Schallfortpflanz.

Thermal diffusion und ~~von~~ Thomson-Joule Effect hängen ~~zusammen~~ sind innere Phänomene? Gibt es thermal diffusion in Lösungen?

Die Connection von suspendirten Theilchen durch Strom; entsteht infolge Electricität infolge Flüssigkeitsreibung? ~~Die~~ Reibungselectr. entsteht bei großen Geschwindigkeitsgefälle? Wie wenn verschiedene Pulver gemischt und in elektrischem Felde geschüttelt werden? Ist Electrolyse nicht ein identischer Vorgang?

Selbstinductionen vergrößert bei Entladung von Kugeln etc. Schwärzungen die dadurch entstehen. ~~Stark~~

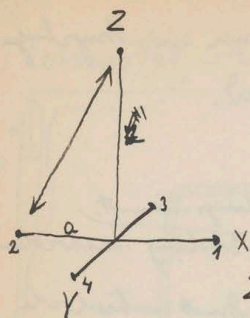
Scheinbare dielectriche Hysteresis, infolge electrischer Nachwirkung der Deformation im electrost. Felde

Quantitative Messungen über Absorption, Emission etc. von Dämpfen z.B. Joddampf,

$H_2$ -Dampf

Leduc's Facultés: Dalton's Gesetze zu verifiziren: dass Phosphor sich oxidiren. können? Kein Gas!?





$$V = \frac{1}{r_1} + \frac{1}{r_2} + \frac{1}{r_3} + \frac{1}{r_4}$$

$$\frac{\partial V}{\partial x} = -\frac{1}{r_1} \frac{\partial r_1}{\partial x} - \dots$$

$$\Sigma X = \frac{1}{r_1} \frac{\partial r_1}{\partial x} + \dots$$

$$r_1^2 = z^2 + (a-x)^2 + y^2$$

$$r_2^2 = x^2 + (a+x)^2 + y^2$$

$$r_3^2 = z^2 + (a+y)^2 + x^2$$

$$r_4^2 = z^2 + (a-y)^2 + x^2$$

$$\frac{\partial}{\partial x} \Sigma X = -\frac{\partial V}{\partial x} = -\frac{1}{r_1} \left( \frac{\partial r_1}{\partial x} \right)^2 + \frac{1}{r_1} \frac{\partial r_1}{\partial x} \dots$$

$$\frac{a-x}{2}$$

$$-\frac{x^2}{2^2} - \frac{1}{2}$$

$$= -\frac{(a-x)^2}{[z^2 + (a-x)^2]^2} - \frac{(a+x)^2}{[z^2 + (a+x)^2]^2} - \frac{x^2}{[z^2 + a^2 + x^2]^2} - \frac{x^2}{[z^2 + a^2 + x^2]^2} + \dots$$

$$\Sigma X = -\frac{(a-x)}{[z^2 + (a-x)^2]^{3/2}} + \frac{a+x}{[z^2 + (a+x)^2]^{3/2}} + \frac{2x}{[z^2 + a^2 + x^2]^{3/2}}$$

$$-\frac{\partial V}{\partial x} = -3 \frac{(a-x)^2}{[z^2 + (a-x)^2]^{5/2}} + 3 \frac{(a+x)^2}{[z^2 + (a+x)^2]^{5/2}} - \frac{6x^2}{[z^2 + a^2 + x^2]^{5/2}}$$

$$+ \frac{1}{[z^2 + (a-x)^2]^{3/2}} + \frac{1}{[z^2 + (a+x)^2]^{3/2}} + \frac{2}{[z^2 + a^2 + x^2]^{3/2}}$$

$$Z = -\frac{\partial V}{\partial z} = -\frac{2}{[z^2 + (a-x)^2]^{3/2}} + \frac{2}{[z^2 + (a+x)^2]^{3/2}} + \frac{2z}{[z^2 + a^2 + x^2]^{3/2}}$$

$$\frac{\partial Z}{\partial x} = -\frac{3 \cdot 2^2}{[z^2 + (a-x)^2]^{5/2}} + \frac{3 \cdot 2^2}{[z^2 + (a+x)^2]^{5/2}} - \frac{6 \cdot 2^2}{[z^2 + a^2 + x^2]^{5/2}} +$$

$$+ \frac{1}{[z^2 + (a-x)^2]^{3/2}} + \frac{1}{[z^2 + (a+x)^2]^{3/2}} + \frac{2}{[z^2 + a^2 + x^2]^{3/2}}$$



$$-\frac{\partial^2 V}{\partial x^2} + \frac{\partial^2 V}{\partial z^2} = \frac{-3}{[z^2 + (a-x)^2]^{3/2}} + \frac{3}{[z^2 + (a-x)^2]^{3/2}} + \dots$$

$$\begin{aligned} -\frac{\partial^2 V}{\partial x^2} &= -\frac{3}{[z^2 + a^2]^{5/2}} \left\{ \frac{(a-x)^2}{\left[1 + \frac{2ax + x^2}{a^2 + z^2}\right]^{5/2}} + \frac{(a+x)^2}{\left[1 + \frac{2ax + x^2}{a^2 + z^2}\right]^{5/2}} + \frac{2x^2}{\left[1 + \frac{x^2}{a^2 + z^2}\right]^{5/2}} \right\} + \\ &+ \frac{1}{[z^2 + z^2]^{3/2}} \left\{ \frac{1}{\left[1 + \frac{-2ax + x^2}{a^2 + z^2}\right]^{3/2}} + \dots \right\} \end{aligned}$$

für  $\lim x=0$ :  $-\frac{\partial^2 V}{\partial x^2} = \frac{-6a^2}{(a^2 + z^2)^{5/2}} + \frac{4}{(a^2 + z^2)^{3/2}}$

$$-\frac{\partial^2 V}{\partial z^2} = \frac{-12z^2}{(a^2 + z^2)^{5/2}} + \frac{4}{(a^2 + z^2)^{3/2}}$$

Stabilität  $< 0$ :  $-\frac{6a^2}{a^2 + z^2} + 4 < 0$

$$\frac{\partial^2 V}{\partial x^2}: \quad -2a^2 + 4z^2 < 0$$

$$2z^2 < a^2$$

$$-\frac{12z^2}{a^2 + z^2} + 4 < 0$$

$$-8z^2 + 4a^2 < 0$$

$$a^2 < 2z^2 \quad \text{daher höchstens:}$$

$$\frac{\partial^2 V}{\partial x^2} = 0 \quad \text{und} \quad \frac{\partial^2 V}{\partial z^2} = 0 \quad \text{für} \quad z^2 = \frac{a^2}{2}$$

$$\begin{aligned} -\frac{\partial^3 V}{\partial x^3} &= -15 \frac{(a-x)^3}{[z^2 + (a-x)^2]^{7/2}} + 15 \frac{(a+x)^3}{[z^2 + (a+x)^2]^{7/2}} + \frac{30x^3}{[2z^2 + x^2]^{7/2}} \\ &+ 9 \frac{(a-x)^3}{[z^2 + (a-x)^2]^{5/2}} - 9 \frac{(a+x)^3}{[z^2 + (a+x)^2]^{5/2}} - \frac{18x}{[z^2 + a^2 + x^2]^{5/2}} \end{aligned} \quad \left| \begin{array}{l} x=0 \\ \\ \end{array} \right. = ()$$



$$\begin{aligned}
 -\frac{\partial^4 V}{\partial x^4} &= -3.5.7 \frac{(a-x)^4}{[2^2+(a-x)^2]^{9/2}} - 3.5.7 \frac{(a+x)^4}{\dots} - 2.3.5.7 \frac{x^4}{\dots} \\
 &+ 45 \frac{(a-x)^2}{[2^2+(a-x)^2]^{7/2}} + 45 \frac{(a+x)^2}{\dots} + 2.45 \frac{x^2}{\dots} \\
 &+ 45 \frac{(a-x)^2}{[2^2+(a-x)^2]^{7/2}} + 45 \frac{(a+x)^2}{\dots} + 2.45 \frac{x^2}{\dots} \\
 &- 9 \frac{(a-x)}{[2^2+(a-x)^2]^{5/2}} - 9 \frac{(a+x)}{\dots} - 2.9 \frac{1}{\dots}
 \end{aligned}$$

$$\lim_{x \rightarrow 0}: -\frac{\partial^4 V}{\partial x^4} = -\frac{4.3.5.7 a^4}{(2^2+a^2)^{9/2}} + 2.90 \frac{a^2}{(a^2+2)^{7/2}} - \frac{36}{(a^2+2)^{5/2}}$$

$$= \frac{1}{(a^2+2)^{9/2}} \left\{ -\frac{420}{456} a^4 + 180(a^4 + a^2 \cdot 2) - 36(a^4 + 2a^2 \cdot 2 + 2^4) \right\}$$

$$= \frac{1}{(a^2+2)^{9/2}} \left\{ -276 a^4 + 108 a^2 \cdot 2 - 36 \cdot 2^4 \right\}$$

$$= \frac{12}{(a^2+2)^{9/2}} \left\{ -23 a^4 + 9 a^2 \cdot 2 - 3 \cdot 2^4 \right\} < 0$$

$$\text{Wenn } a^2 = 22^2 \quad \checkmark \quad = -92 + 18 - 3 = -77 \cdot 2^2$$

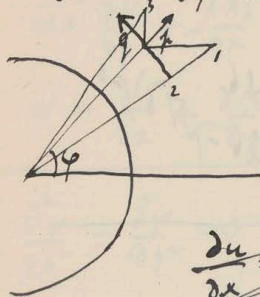


Two dimensional, incompressible

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$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + \cancel{w \frac{\partial u}{\partial z}} = u \left( \frac{\partial \tilde{u}}{\partial x} + \frac{\partial \tilde{u}}{\partial y} \right) + \cancel{\frac{\partial \tilde{u}}{\partial z}} - \frac{1}{\rho} \frac{\partial P}{\partial x} \quad \left| \frac{\partial}{\partial y} \right.$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + \cancel{w \frac{\partial v}{\partial z}} = u \left( \frac{\partial \tilde{v}}{\partial x} + \frac{\partial \tilde{v}}{\partial y} \right) + \cancel{\frac{\partial \tilde{v}}{\partial z}} - \frac{1}{\rho} \frac{\partial P}{\partial y} \quad \left| - \frac{\partial}{\partial x} \right.$$



$$u = r \cos \varphi + v \sin \varphi$$

$$u = r \cos \varphi - v \sin \varphi$$

$$v = -u \sin \varphi + v \cos \varphi$$

$$v = r \sin \varphi + v \cos \varphi$$

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial r} \frac{\partial r}{\partial x} + \frac{\partial u}{\partial \varphi} \frac{\partial \varphi}{\partial x}$$

$$x = r \cos \varphi$$

$$= \frac{\partial u}{\partial r} \frac{1}{\cos \varphi} - \frac{\partial u}{\partial \varphi} \frac{1}{r \sin \varphi}$$

$$\frac{\partial u}{\partial x} = \frac{u_1 - u_0}{\Delta x} = \frac{u_1 - u_2}{\Delta x} + \frac{u_2 - u_0}{\Delta x} = \frac{u_1 - u_2}{\Delta r \cancel{\cos \varphi}} + \frac{u_2 - u_0}{r \Delta \varphi}$$

$$= \frac{\partial u}{\partial r} \cos \varphi - \frac{\partial u}{\partial \varphi} \frac{\sin \varphi}{r} =$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial^2 u}{\partial r^2} \cos^2 \varphi - \frac{\partial^2 u}{\partial r \partial \varphi} \frac{\cos \varphi \sin \varphi}{r} + \frac{\partial^2 u}{\partial \varphi^2} \frac{\sin^2 \varphi}{r^2} - \frac{\partial^2 u}{\partial r \partial \varphi} \frac{\cos \varphi \sin \varphi}{r} -$$

$$+ \frac{\partial^2 u}{\partial r^2} \frac{\sin^2 \varphi}{r^2} + \frac{\partial^2 u}{\partial \varphi^2} \frac{\sin^2 \varphi}{r^2} + \frac{\partial^2 u}{\partial \varphi^2} \frac{\cos^2 \varphi}{r^2}$$

$$= \frac{\partial^2 u}{\partial r^2} \cos^2 \varphi - 2 \frac{\partial^2 u}{\partial r \partial \varphi} \frac{\sin \varphi \cos \varphi}{r} + \frac{\partial^2 u}{\partial \varphi^2} \frac{\sin^2 \varphi}{r^2} + \frac{\partial^2 u}{\partial r^2} \frac{\sin^2 \varphi}{r^2} + 2 \frac{\partial^2 u}{\partial \varphi^2} \frac{\sin \varphi \cos \varphi}{r^2}$$

$$\frac{\partial u}{\partial y} = \frac{u_3 - u_0}{\Delta y} = \frac{u_3 - u_4}{\Delta y} + \frac{u_4 - u_0}{\Delta y} = \frac{\partial u}{\partial r} \sin \varphi + \frac{\partial u}{\partial \varphi} \frac{\cos \varphi}{r}$$

$$\frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial r^2} \sin^2 \varphi + \frac{\partial^2 u}{\partial r \partial \varphi} \frac{\sin \varphi \cos \varphi}{r} - \frac{\partial^2 u}{\partial \varphi^2} \frac{\cos^2 \varphi}{r^2} + \frac{\partial^2 u}{\partial r \partial \varphi} \frac{\sin \varphi \cos \varphi}{r} + \frac{\partial^2 u}{\partial r^2} \frac{\cos^2 \varphi}{r^2} + \frac{\partial^2 u}{\partial \varphi^2} \frac{\cos^2 \varphi}{r^2} - \frac{\partial^2 u}{\partial \varphi^2} \frac{\sin^2 \varphi}{r^2}$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial r^2} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \varphi^2} + \frac{1}{r} \frac{\partial u}{\partial r}$$



$$\frac{\partial u}{\partial z} = \frac{\partial k}{\partial z} \sin \varphi - \frac{\partial \varphi}{\partial z} \sin \varphi \quad \left| \sin \varphi \right.$$

$$\frac{\partial u}{\partial \varphi} = \frac{\partial k}{\partial \varphi} \sin \varphi - \frac{\partial \varphi}{\partial \varphi} \sin \varphi - k \sin \varphi - \varphi \sin \varphi \quad \left| -\frac{\sin \varphi}{2} \right.$$

$$\frac{\partial u}{\partial x} =$$

$$\nabla \delta^2 - V \delta \text{ und } \delta \\ \text{und } (V \delta \text{ und } \delta - \mu \nabla \delta^2) = 0$$

Amir Ntelo!

$$\frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + u \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial v}{\partial y} \frac{\partial u}{\partial y} + v \frac{\partial^2 u}{\partial y^2} - \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} - u \frac{\partial^2 v}{\partial x^2} - \frac{\partial v}{\partial x} \frac{\partial v}{\partial y} - v \frac{\partial^2 v}{\partial x \partial y}$$

$$= \mu \left( \frac{\partial^3 u}{\partial x^2 \partial y} + \frac{\partial^3 u}{\partial y^3} - \frac{\partial^3 v}{\partial x^2 \partial y} - \frac{\partial^3 v}{\partial x \partial y^2} \right)$$

$$\zeta = \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x}$$

$$\frac{\partial \zeta}{\partial x} = \frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial x^2} = - \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 u}{\partial x^2}$$

$$u \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + v \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) = \mu \left( \frac{\partial}{\partial x^2} + \frac{\partial}{\partial y^2} \right) \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right)$$

$$u \frac{\partial \zeta}{\partial x} + v \frac{\partial \zeta}{\partial y} = \mu \left( \frac{\partial \zeta}{\partial x^2} + \frac{\partial \zeta}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial x} \frac{\partial \zeta}{\partial x} + \frac{\partial v}{\partial x} \frac{\partial \zeta}{\partial y} + u \frac{\partial^2 \zeta}{\partial x^2} + v \frac{\partial^2 \zeta}{\partial x \partial y} =$$

$$\frac{\partial(u\zeta)}{\partial x} + \frac{\partial(v\zeta)}{\partial y} = \nearrow$$

$$\frac{\partial}{\partial x} \left[ u \zeta - \mu \frac{\partial \zeta}{\partial x} \right] + \frac{\partial}{\partial y} \left[ v \zeta - \mu \frac{\partial \zeta}{\partial y} \right] = 0$$

$$\text{div } \delta \zeta = \mu \nabla^2 \zeta$$



$$\mathbf{a} = \nabla V + \text{curl } \mathbf{a}$$

$$u = \frac{\partial V}{\partial x} + -\frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z}$$

$$v = \frac{\partial V}{\partial y} + -\frac{\partial A_3}{\partial x} + \frac{\partial A_1}{\partial z}$$

$$w = \frac{\partial V}{\partial z} + -\frac{\partial A_1}{\partial y} + \frac{\partial A_2}{\partial x}$$

Also zweidimensional:

$$u = \frac{\partial \varphi}{\partial x} + \frac{\partial \psi}{\partial y}$$

$$v = \frac{\partial \varphi}{\partial y} + \frac{\partial \psi}{\partial x}$$

$$\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0$$

$$\psi = \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2}$$

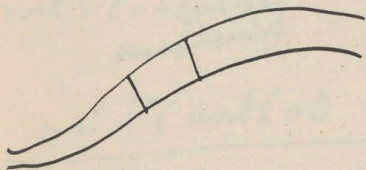
$\varphi$  und  $\psi$  ganz unabhängig

Wenn 2D.  $\varphi$  willkürlich gewählt, wie muss  $\psi$  gewählt werden?

$$\left(\frac{\partial \varphi}{\partial x} + \frac{\partial \psi}{\partial y}\right) \left(\frac{\partial^3 \varphi}{\partial x^3} + \frac{\partial^3 \varphi}{\partial x \partial y^2}\right) + \left(\frac{\partial \varphi}{\partial y} - \frac{\partial \psi}{\partial x}\right) \left(\frac{\partial^3 \varphi}{\partial x^2 \partial y} + \frac{\partial^3 \varphi}{\partial y^3}\right) = \mu \frac{\partial^4 \varphi}{\partial x^4} + \dots$$

Fluiddynamische Gleichungen bezogen auf ~~Dichte~~ Stromlinien  
(ohne Rotation)

In zwei Dimensionen:



$$F_n = \frac{\partial P}{\partial R} + \frac{P}{R}$$

$$F_n = \frac{1}{R} \frac{\partial(RP)}{\partial R}$$

$$R = 2 \frac{\int F_t ds}{F_n}$$

$$= 2 \frac{E}{F_n}$$

$$2E = P + R \frac{\partial P}{\partial R}$$

$$m \frac{dv}{dt} = F_t = m \frac{dv}{ds} \frac{ds}{dt} = m v \frac{dv}{ds}$$

$$m \frac{v^2}{R} = F_n = \frac{1}{2} \frac{d}{ds} (m v^2) = \frac{dE}{ds}$$

$$m v^2 = 2 \int F_t ds$$

$$F_t = \frac{1}{\eta} \frac{\partial(P\eta)}{\partial s}$$

$$\frac{\partial P}{\partial R} = \frac{2E - P}{R}$$



$$(\nabla \cdot) \vec{b} = \nabla P + \mu \nabla^2 \vec{b} = \nabla b^2 + \nabla \vec{b} \operatorname{curl} \vec{b}$$

$$\operatorname{curl} = \mu \nabla^2 \operatorname{curl} \vec{b} = \nabla \operatorname{curl} \vec{b} \operatorname{curl} \vec{b}$$

$$\nabla \frac{\partial P}{\partial \mu} + \nabla^2 \vec{b} + \mu \nabla^2 \frac{\partial \vec{b}}{\partial \mu} = \nabla \frac{\partial b^2}{\partial \mu} + \frac{\partial}{\partial \mu} \nabla \vec{b} \operatorname{curl} \vec{b}$$

Stationäre Strömung ohne Kräfte, mit Reibung

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right) - \frac{1}{\rho} \frac{\partial P}{\partial x}$$

$$\frac{x}{\mu} = \xi \quad \frac{\partial u}{\partial x} = \frac{1}{\mu} \frac{\partial u}{\partial \xi} \quad \frac{\partial^2 u}{\partial x^2} = \frac{1}{\mu^2} \frac{\partial^2 u}{\partial \xi^2}$$

$$u \frac{\partial u}{\partial \xi} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \frac{\partial^2 u}{\partial \xi^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} - \frac{1}{\rho} \frac{\partial P}{\partial \xi} \quad \text{etc.}$$

Wenn man also diese Strömung ableiten kann, so hat man auch die Lösung für ein beliebiges  $\mu$  und umgekehrt

Wenn die Änderung von  $\mu$  auf  $u, v, w$  ohne Einfluss sein soll, so muss

$$\nabla \frac{\partial P}{\partial \mu} + \nabla^2 \vec{b} = 0 \quad \text{sein.}$$

$$\text{Also: } \operatorname{curl} \nabla^2 \vec{b} = 0$$

$$\begin{aligned} (\nabla \cdot) \vec{b} &= \nabla P + \mu \nabla^2 \frac{\partial \vec{b}}{\partial \mu} = \nabla b^2 + \nabla \vec{b} \operatorname{curl} \vec{b} \\ &= \nabla \left[ P - \mu \frac{\partial P}{\partial \mu} \right] = - \nabla_{\mu^2} \frac{\partial}{\partial \mu} \left( \frac{P}{\mu} \right) = \nabla \Pi \end{aligned}$$

Also nur Druck wird geändert



$$f(x, y, z, \mu) - \mu \frac{\partial f(x, y, z, \mu)}{\partial \mu} = F(x, y, z)$$

$$\frac{\partial f}{\partial \mu} - \frac{\partial f}{\partial \mu} - \mu \frac{\partial^2 f}{\partial \mu^2} = 0$$

$$\frac{\partial f}{\partial \mu} = \varphi(x, y, z)$$

$$f = \mu \varphi(x, y, z) + \psi(x, y, z)$$

$$\mu \varphi(x, y, z) + \psi(x, y, z) - \mu \varphi(x, y, z) = F(x, y, z)$$

$$P = \mu \varphi(x, y, z) + \Pi$$

$$\nabla P = \mu \nabla \varphi + \nabla \Pi$$

$$(67) \delta = \nabla P + \mu \nabla^2 \delta = \mu \nabla \varphi + \nabla \Pi + \mu \nabla^2 \delta$$

$$(67) \delta = \nabla \Pi$$

$$[-\nabla \varphi = \nabla^2 \delta]$$

$\varphi = \text{willkürliche Funktion}$

$$\left. \begin{aligned} -\nabla^2 \delta &= \text{curl}^2 \delta \\ \text{curl} \nabla^2 \delta &= -\text{curl}^3 \delta \\ \text{curl}^3 \delta &= 0 \end{aligned} \right\} !$$

$$\text{curl} \nabla a b = a \text{div} b - b \text{div} a + \underbrace{(\nabla b) a - (a \nabla b)}$$

$$\begin{aligned} (\nabla b) a &= \nabla_a a b + \nabla \text{curl} a \cdot b \\ &= \nabla (\text{curl} a \cdot b - \text{curl} b \cdot a) + \\ &\quad + \underbrace{\nabla_a a b - \nabla_b a b} \end{aligned}$$



$$\delta = \nabla u + \text{curl } v$$

$$\text{curl } \delta = \text{curl}^2 v$$

$$\text{curl}^2 \delta = \text{curl}^3 v = + \nabla \varphi \quad \text{Somit: } \delta = \int \frac{\nabla \varphi \, dv}{4\pi k}$$

$$\nabla \delta \text{ curl } \delta = \nabla (\nabla u + \text{curl } v) \text{ curl}^2 v = \nabla \Phi$$

$$\text{curl } \delta = \text{curl} \int \frac{\nabla \varphi \, dv}{4\pi r} = \int \frac{\text{curl } \nabla \varphi \, dv}{4\pi r}$$

$$\left. \begin{aligned} \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} &= \frac{\partial \varphi}{\partial x} \\ \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} &= \frac{\partial \varphi}{\partial y} \\ \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} &= \frac{\partial \varphi}{\partial z} \end{aligned} \right|$$

$$u = \int \frac{\partial \varphi}{\partial x} \, dv$$

$$v =$$

$$w =$$

$$\text{curl}^4 v = \text{curl}^3 \delta = 0$$

$$\left. \begin{aligned} \text{curl } \delta &= i A_1 + j A_2 + k A_3 \\ \nabla^2 A_1 &= 0 = \nabla^2 A_2 = \nabla^2 A_3 \end{aligned} \right\} = \text{curl } \tilde{v} = i \nabla^2 \phi_1 + \dots$$

$$\nabla (i A_1 + j A_2 + k A_3)$$



wenn  $\text{curl } a = \nabla b$   $\nabla^2 b = 0$  ~~ANNE~~

$$\text{curl}^2 a = 0 = \nabla \text{div} a - \nabla^2 b$$

$$a = \nabla \int \frac{\text{div} a}{r} dr + \underbrace{\text{curl} \int \frac{\text{curl} a}{r} dr}_{\dots\dots\dots} + \dots\dots\dots \quad \nabla^2 A = 0$$

$$= \text{curl} \int \frac{\nabla b}{r} dr$$

ist dies = 0?

dann muss  $\nabla b = 0 = \text{curl} a = 0$

Somit in obigen Falle:  $\text{curl}^2 b = 0$

$$\text{curl} b = \nabla \text{pot} = 0$$

$b = \nabla \text{pot}$  also immer Potentialbewegung

Dann auch Druck derselbe

$$\nabla \phi^2 = \nabla P + \mu \nabla^2 \phi \quad \nabla^2 u = 0 = \nabla^2 v = \nabla^2 w$$

$$\nabla \phi^2 = \nabla P$$

$$u = \frac{\partial \phi}{\partial x}$$

$$\nabla^3 \phi = 0 \text{ mit } \nabla^2 \phi = 0$$

$\nabla^2 \phi = 0$  ~~ist~~ <sup>stationäre</sup> ~~ist~~ <sup>von</sup> nicht erfüllt

Somit besteht jede Potentialbewegung auch bei beliebigem inneren Reibung?

10.  $u = -\frac{a}{r^2} - \frac{ay}{r^2}$

$$\frac{\partial u}{\partial x} = 2 \frac{ax}{r^4}$$

$$\frac{\partial v}{\partial y} = \frac{2ax}{r^4}$$

$$v = \frac{ax}{r^2}$$

$$\frac{\partial u}{\partial y} = -\frac{a}{r^2} + \frac{2ay}{r^4}$$

$$\frac{\partial v}{\partial x} = \frac{a}{r^2} - \frac{2ax}{r^4}$$

$$\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} = 0$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{2ay}{r^4} - \frac{8ax^2}{r^6}$$

$$\frac{\partial^2 u}{\partial y^2} = +\frac{2ay}{r^4} + \frac{4ay}{r^4} - \frac{8ay^3}{r^6}$$

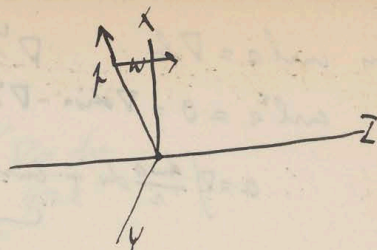
$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{8ay}{r^4} - \frac{8ay(x^2+y^2)}{r^6} = 0$$



2 = Rotations are  $\omega$

$$u = \rho \cos(\phi) = \rho \cos \varphi$$

$$v = \rho \sin(\phi) = \rho \sin \varphi$$



$$\mu \frac{\partial u}{\partial x} = \mu \left[ \frac{\partial u}{\partial \rho} \cos \varphi - \frac{\partial u}{\partial \varphi} \frac{\sin \varphi}{\rho} \right] = \frac{\partial u}{\partial \rho} \cos \varphi + \mu \frac{\sin \varphi}{\rho}$$

$$\frac{\partial u}{\partial x} = \frac{\partial \rho}{\partial x} \cos \varphi + \frac{\rho}{\rho} \sin \varphi$$

$$\left\| \frac{\partial v}{\partial x} = \frac{\partial \rho}{\partial x} \sin \varphi - \frac{\rho}{\rho} \cos \varphi \right\|$$

$$\frac{\partial u}{\partial x} = \frac{\partial \rho}{\partial x} \cos \varphi + \frac{\rho}{\rho} \sin \varphi = \frac{\partial \rho}{\partial x} \cos \varphi + \frac{\rho}{\rho} \sin \varphi$$

$$\frac{\partial u}{\partial y} = \frac{\partial u}{\partial \rho} \sin \varphi = \frac{\partial \rho}{\partial y} \sin \varphi - \frac{\rho}{\rho} \cos \varphi$$

$$\frac{\partial u}{\partial y} = \frac{\partial \rho}{\partial y} \sin \varphi + \frac{\rho}{\rho} \cos \varphi = \frac{\partial \rho}{\partial y} \sin \varphi + \frac{\rho}{\rho} \cos \varphi$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = \frac{\partial^2 \rho}{\partial x^2} \cos \varphi + \frac{\partial \rho}{\partial x} \frac{\cos \varphi}{\rho} + \frac{\partial^2 \rho}{\partial y^2} \sin \varphi + \frac{\partial \rho}{\partial y} \frac{\sin \varphi}{\rho}$$

$$\left\| \frac{\partial v}{\partial y} = \frac{\partial \rho}{\partial y} \cos \varphi + \frac{\rho}{\rho} \sin \varphi \right\|$$

$$\mu \left[ \frac{\partial^2 \rho}{\partial x^2} \cos \varphi + \frac{\partial \rho}{\partial x} \frac{\cos \varphi}{\rho} + \frac{\partial^2 \rho}{\partial y^2} \sin \varphi + \frac{\partial \rho}{\partial y} \frac{\sin \varphi}{\rho} \right] = \mu \left[ \frac{\partial^2 \rho}{\partial x^2} \cos \varphi + \frac{\partial \rho}{\partial x} \frac{\cos \varphi}{\rho} + \frac{\partial^2 \rho}{\partial y^2} \sin \varphi + \frac{\partial \rho}{\partial y} \frac{\sin \varphi}{\rho} \right]$$

$$\mu \left[ \frac{\partial^2 \rho}{\partial x^2} + \frac{1}{\rho} \frac{\partial \rho}{\partial x} \right] = \mu \left[ \frac{\partial^2 \rho}{\partial x^2} + \frac{1}{\rho} \frac{\partial \rho}{\partial x} \right] - \frac{1}{\rho} \frac{\partial \rho}{\partial x} \omega \varphi$$

$$\mu \frac{\partial \omega}{\partial x} \cos \varphi + \mu \frac{\partial \omega}{\partial y} \sin \varphi + \mu \frac{\partial \omega}{\partial z} =$$

$$\mu \left[ \frac{\partial \omega}{\partial x^2} + \frac{1}{\rho} \frac{\partial \omega}{\partial x} + \frac{\partial \omega}{\partial z^2} \right] - \frac{1}{\rho} \frac{\partial \rho}{\partial z} \omega \varphi$$



$$\frac{\partial p}{\partial r} \frac{\partial r}{\partial \rho} + \rho \frac{\partial \ddot{r}}{\partial r \partial z} - \frac{\partial p}{\partial r} \frac{\partial w}{\partial \rho} - \mu \frac{\partial w}{\partial r^2} + \frac{\partial w}{\partial z} \frac{\partial p}{\partial z} + \omega \frac{\partial p}{\partial z} - \frac{\partial w}{\partial r} \frac{\partial w}{\partial z} - \frac{\partial \ddot{w}}{\partial r \partial z} =$$

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~~Continuity Eqn:~~  $\frac{\partial p}{\partial r} \frac{\partial r}{\partial \rho} + \frac{\partial p}{\partial z} \frac{\partial z}{\partial \rho} + \frac{\partial w}{\partial z} = 0$

$$\frac{\partial p}{\partial r} + \frac{\partial w}{\partial z} = 0 \quad \frac{\partial p}{\partial z} + \frac{p}{r} + \frac{\partial w}{\partial z} = 0 \quad \frac{\partial}{\partial r}(r p) + \frac{\partial}{\partial z}(r w) = 0$$

$$= \frac{1}{r} \frac{\partial(r p)}{\partial r} = \frac{\partial}{\partial r} \frac{1}{r} \frac{\partial(r p)}{\partial r} = -\frac{\partial^2 w}{\partial z \partial r}$$

$$\mu \frac{\partial p}{\partial r} + \omega \frac{\partial p}{\partial z} = \mu \left[ \frac{\partial^2 p}{\partial r^2} + \frac{1}{r} \frac{\partial p}{\partial r} - \frac{p}{r^2} + \frac{\partial^2 p}{\partial z^2} \right] - \frac{1}{\rho} \frac{\partial p}{\partial z}$$

$$\mu \frac{\partial w}{\partial r} + \omega \frac{\partial w}{\partial z} = \mu \left[ \frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} + \frac{\partial^2 w}{\partial z^2} \right] - \frac{1}{\rho} \frac{\partial p}{\partial z}$$

Other Eqn:

$$\dot{r} = \frac{\partial}{\partial t}(p q)$$

Continuity:

$$\frac{\partial}{\partial t}(v q) = 0$$

$$= q \frac{\partial v}{\partial t} = \frac{\partial v}{\partial t} \cdot v = \frac{1}{2} \frac{\partial v^2}{\partial t}$$

$$v \frac{\partial q}{\partial t} + q \frac{\partial v}{\partial t} = 0$$

$$v_1 - v_2 = \int F_t dt =$$

$$v_1^2 - v_2^2 = 2 \int F_t dt = 2(P_1 q_1 - P_2 q_2)$$

Derive eqn:

$$P = P_0 + \frac{v^2}{2}$$

for Bernoulli's theorem

$$q = r \delta \varphi \delta s$$

$$p \delta s \frac{v^2}{R} = F_n = \frac{\partial(P r)}{\partial \Delta} \delta \varphi \delta s \delta \Delta$$

$$r \frac{v^2}{R} = \frac{\partial(P r)}{\partial \Delta} = \frac{\partial(P_2)}{\partial \Delta}$$

$$\frac{\partial(P r)}{\partial \Delta} = \frac{\partial(P_2)}{\partial r} \sin \vartheta$$

$$\Delta s = \frac{\Delta r}{\sin \vartheta}$$

$$R = \frac{\partial s}{\partial \vartheta} = \frac{\partial r}{\partial \vartheta} \frac{1}{\sin \vartheta}$$

$$r v^2 \frac{\partial \vartheta}{\partial s} = \frac{\partial(P_2)}{\partial r} \sin \vartheta = r v^2 \frac{\partial \vartheta}{\partial r} \sin \vartheta$$

$$r v^2 \frac{\partial \vartheta}{\partial r} = \frac{\partial(P_2)}{\partial r}$$



Nun die Richtung der Stromlinien gegeben ist:

$$\frac{f}{w} = f(r, z)$$

$$\rho = w f(r, z)$$

$$\frac{\partial w}{\partial r} f + w \frac{\partial f}{\partial r} + \frac{w}{r} f + \frac{\partial w}{\partial z} = 0$$

$$\frac{\partial w}{\partial r} f + \frac{\partial w}{\partial z} + w \frac{\partial f}{\partial r} + \frac{w}{r} f = 0$$

$$w f \left( w \frac{\partial f}{\partial r} + \frac{\partial w}{\partial r} f \right) + w \left( \frac{\partial w}{\partial z} f + w \frac{\partial f}{\partial z} \right) = -\frac{1}{\rho} \frac{\partial P}{\partial r} +$$

$$+ \mu \left[ \frac{\partial w}{\partial r} \frac{\partial f}{\partial r} + w \frac{\partial^2 f}{\partial r^2} + \frac{\partial^2 w}{\partial r^2} f + \frac{w}{r} \frac{\partial f}{\partial r} + \frac{f}{r} \frac{\partial w}{\partial r} - \frac{f}{r^2} w + \frac{\partial^2 w}{\partial r^2} f + 2 \frac{\partial w}{\partial z} \frac{\partial f}{\partial r} + w \frac{\partial^2 f}{\partial z^2} \right]$$

$$w f \frac{\partial w}{\partial r} + w \frac{\partial w}{\partial z} = \mu \left[ \frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} + \frac{\partial^2 w}{\partial z^2} \right] - \frac{1}{\rho} \frac{\partial P}{\partial r} \quad || f$$

$$w f \frac{\partial f}{\partial r} + w \frac{\partial f}{\partial z} = \mu \left[ w \frac{\partial^2 f}{\partial r^2} + 2 \frac{\partial w}{\partial z} \frac{\partial f}{\partial r} + \frac{w}{r} \frac{\partial f}{\partial r} - f \frac{w}{r^2} + 2 \frac{\partial w}{\partial z} \frac{\partial f}{\partial z} + w \frac{\partial^2 f}{\partial z^2} \right] + - \frac{1}{\rho} \left( \frac{\partial P}{\partial r} + f \frac{\partial P}{\partial z} \right)$$

$$\frac{\partial^2 w}{\partial r^2} f + 2 \frac{\partial w}{\partial r} \frac{\partial f}{\partial r} + w \frac{\partial^2 f}{\partial r^2} + \frac{\partial w}{\partial z} \frac{f}{r} + \frac{w}{r} \frac{\partial f}{\partial z} + - \frac{w f}{r^2} + \frac{\partial^2 w}{\partial z^2} = 0$$

$$\text{Hyp.} = \mu \left[ \frac{\partial^2 w}{\partial r^2} f + 2 \frac{\partial w}{\partial z} \frac{\partial f}{\partial r} - \frac{\partial^2 w}{\partial r^2} + w \frac{\partial^2 f}{\partial z^2} \right] - \frac{1}{\rho} \frac{\partial P}{\partial r} =$$

$$= w^2 \frac{\partial f}{\partial z^2} - \frac{w}{r} f^2 \quad \text{div} \nabla \text{ab} = \text{curl} \text{curl} \text{ab}$$

Für  $\mu = 0$ :

$$\frac{1}{\rho} \nabla^2 P = \mu \frac{\partial^2 u}{\partial x^2} + \left( \frac{\partial u}{\partial x} \right) + \frac{\partial v}{\partial x} \frac{\partial u}{\partial y} + v \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + u \frac{\partial^2 v}{\partial x \partial y} + \left( \frac{\partial v}{\partial y} \right) + v \frac{\partial^2 v}{\partial y^2}$$

$$= \text{div} \nabla \phi^2 + \text{div} (\nabla \phi \text{curl} \phi)$$

$$= \nabla^2 (\phi^2) + (\text{curl} \phi)^2 - \phi \text{curl}^2 \phi$$



In zwei Dimensionen:

$$f = \text{const}$$

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$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} = \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) - \frac{1}{\rho} \frac{\partial P}{\partial x}$$

$$u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} = \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) - \frac{1}{\rho} \frac{\partial P}{\partial y}$$

$$\frac{u}{v} = f \quad u = v f$$

$$\frac{\partial v}{\partial x} f + v \frac{\partial f}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$v f \left( \frac{\partial v}{\partial x} f + v \frac{\partial f}{\partial x} \right) + v \left( \frac{\partial v}{\partial y} f + v \frac{\partial f}{\partial y} \right) = \mu \left[ \frac{\partial^2 v}{\partial x^2} f + 2 \frac{\partial v}{\partial x} \frac{\partial f}{\partial x} + v \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} f + 2 \frac{\partial v}{\partial y} \frac{\partial f}{\partial y} + v \frac{\partial^2 f}{\partial y^2} \right] - \frac{1}{\rho} \frac{\partial P}{\partial x}$$

$$\underbrace{v f \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y}}_{= -v^2 \frac{\partial f}{\partial x}} = \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) - \frac{1}{\rho} \frac{\partial P}{\partial x}$$

$$\frac{\partial^2 v}{\partial x^2} f + 2 \frac{\partial v}{\partial x} \frac{\partial f}{\partial x} + v \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} = 0$$

$$\frac{\partial^2 v}{\partial x \partial y} f + \frac{\partial v}{\partial x} \frac{\partial f}{\partial y} + \frac{\partial v}{\partial y} \frac{\partial f}{\partial x} + v \frac{\partial^2 f}{\partial x \partial y} + \frac{\partial^2 v}{\partial y^2} = 0$$

$$\left\{ \begin{array}{l} v^2 \frac{\partial f}{\partial y} = \mu \left[ -\frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 v}{\partial y^2} f + 2 \frac{\partial v}{\partial y} \frac{\partial f}{\partial y} + v \frac{\partial^2 f}{\partial y^2} \right] - \frac{1}{\rho} \frac{\partial P}{\partial x} \\ -v^2 \frac{\partial f}{\partial x} = \mu \left[ \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} \right] - \frac{1}{\rho} \frac{\partial P}{\partial y} \end{array} \right\} \quad \left| \begin{array}{l} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \end{array} \right.$$

Wenn also  $\mu = 0$

Curven  $f = \text{const}$  stehen  $\perp$  auf  $P = \text{const}$

$$\frac{df}{dx} = - \frac{\frac{\partial P}{\partial x}}{\frac{\partial P}{\partial y}}$$



$$\frac{1}{\sqrt{1-M^2}} =$$

Strömlinie:  $\frac{u}{v} = f = \frac{\frac{\partial f}{\partial y}}{\frac{\partial f}{\partial x}}$

$$u^2 + v^2 = \varphi^2$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial x} = \varphi \frac{\partial \varphi}{\partial x}$$

$$u \frac{\partial u}{\partial y} + v \frac{\partial v}{\partial y} = \varphi \frac{\partial \varphi}{\partial y}$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + v \frac{\partial v}{\partial x} + \frac{v^2}{u} \frac{\partial v}{\partial y}$$

$$= v \frac{\partial v}{\partial x} - \frac{v^2}{u} \frac{\partial u}{\partial x}$$

$$= \frac{u}{u} \left( u \frac{\partial v}{\partial x} - v \frac{\partial u}{\partial x} \right)$$

$$= v^2 \frac{u}{u} \frac{\partial}{\partial x} \left( \frac{u}{v} \right)$$

$$\frac{1}{\rho} \left( \frac{\partial \rho}{\partial x} \frac{\partial f}{\partial x} + \frac{\partial \rho}{\partial y} \frac{\partial f}{\partial y} \right) =$$

$$= \mu \left[ \frac{\partial \tilde{v}}{\partial x} \frac{\partial f}{\partial y} + \frac{\partial \tilde{v}}{\partial y} \frac{\partial f}{\partial y} - \frac{\partial \tilde{v}}{\partial x \partial y} \frac{\partial f}{\partial x} + \frac{\partial \tilde{v}}{\partial y} - f \frac{\partial f}{\partial x} + 2 \frac{\partial v}{\partial y} \frac{\partial f}{\partial x} \frac{\partial f}{\partial y} + v \frac{\partial f}{\partial x} \frac{\partial f}{\partial y} \right]$$

$\phi$  sei eine Lösung

$$(\phi \nabla) \phi = \frac{1}{2} \nabla \phi^2 + \nabla \phi \text{ curl } \phi = \mu \nabla^2 \phi - \frac{1}{\rho} \nabla P$$

Dann ist  $\frac{1}{\rho} \nabla \phi^2$  auch eine Lösung für denselben Fall, aber hier  $\mu = 0$  und

$\frac{P_c^2}{\rho}$  ~~kleiner~~ <sup>großer</sup> Druck

$$\phi_c = \phi_c$$

$$\mu = \mu_c$$

$$P_c = P_c^2$$

$\nabla$

$$c \left( \frac{1}{2} \nabla \phi^2 + \nabla \phi \text{ curl } \phi \right) = c \mu_c \nabla^2 \phi - \frac{1}{\rho} \nabla P_c$$



Angenommen  $u, v, w$  sind eine Lösung, unter welchen Umständen wird  $u, v, w$  eine Lösung sein?

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} - \frac{1}{\rho} \frac{\partial P}{\partial x}$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} - \frac{1}{\rho} \frac{\partial P}{\partial x}$$

$$+ u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z}$$

Wenn  $u, v, w = \text{const}$  } a

$$-\frac{1}{\rho} \frac{\partial (P - P_1)}{\partial x} = \nabla^2 u_1$$

etc.

$$-\frac{1}{\rho} \nabla (P - P_1) = \nabla (a) \delta$$

$$u \left( \frac{\partial^2 u_1}{\partial x \partial y} - \frac{\partial^2 v_1}{\partial x^2} \right) + v \left( \frac{\partial^2 u_1}{\partial y^2} - \frac{\partial^2 v_1}{\partial y \partial x} \right) + w \left( \frac{\partial^2 u_1}{\partial y \partial z} - \frac{\partial^2 v_1}{\partial x \partial z} \right) = 0$$

$$u \frac{\partial}{\partial x} \left( \frac{\partial u_1}{\partial y} - \frac{\partial v_1}{\partial x} \right) + v \frac{\partial}{\partial y} \left( \frac{\partial u_1}{\partial y} - \frac{\partial v_1}{\partial x} \right) + w \frac{\partial}{\partial z} \left( \frac{\partial u_1}{\partial y} - \frac{\partial v_1}{\partial x} \right) = 0$$

$$\left\{ \begin{array}{l} u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} = 0 \\ u \frac{\partial}{\partial x} + \dots = 0 \\ u \frac{\partial}{\partial x} + \dots = 0 \end{array} \right\} \text{Daher } \left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \\ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} = 0 \\ \dots \end{array} \right.$$

in  $(x, y, z)$  dann:

$$(\delta, \nabla) \delta_1 = \frac{1}{2} \nabla \delta_1^2 + V \delta_1, \text{curl } \delta_1 = \nabla^2 \delta_1 - \frac{1}{\rho} \nabla P_1$$

$$\nabla (\delta_1 + \delta)^2 + V (\delta_1 + \delta) \text{curl } (\delta_1 + \delta) = \nabla (\delta_1 + \delta) - \frac{1}{\rho} \nabla P_1$$

~~27.6.6~~



$$\nabla \cdot \mathbf{b}_1^2 + \underbrace{\nabla(\mathbf{b}_1 \cdot \mathbf{b} + \mathbf{b} \cdot \mathbf{b}_1)}_{2 \nabla \cdot \mathbf{S} \mathbf{b} \mathbf{b}_1} + \nabla \cdot \mathbf{b}^2 + \nabla \mathbf{b}_1 \cdot \text{curl} \mathbf{b}_1 + \nabla \mathbf{b}_1 \cdot \text{curl} \mathbf{b} + \nabla \mathbf{b} \cdot \text{curl} \mathbf{b}_1 + \nabla \mathbf{b} \cdot \text{curl} \mathbf{b} \\ = \nabla \cdot \mathbf{b}^2 + \cancel{\nabla \cdot \mathbf{b}^2} - \frac{1}{\rho} \nabla(P - P_1)$$

Wenn auch  $\mathbf{b}_1$  ein Lsg ist:

$$2 \nabla \cdot \mathbf{b} \mathbf{b}_1 + \nabla(\mathbf{b}_1 \cdot \text{curl} \mathbf{b} + \mathbf{b} \cdot \text{curl} \mathbf{b}_1) = - \frac{1}{\rho} \nabla(P - P_1 - 0')$$

$P'$  kann daraus genügend bestimmt werden falls überhaupt:

$$\text{curl} \nabla(\mathbf{b}_1 \cdot \text{curl} \mathbf{b} + \mathbf{b} \cdot \text{curl} \mathbf{b}_1) = 0$$

Also wenn  $\underbrace{\quad}_{= \tau \text{curl} \tau}$  existiert und so muss  $\tau$  eine mögliche Flächystörung sein (Nebenproblem)

$$\text{curl} \nabla \mathbf{a} \mathbf{b} = \mathbf{a} \text{div} \mathbf{b} - \mathbf{b} \text{div} \mathbf{a} + (\mathbf{b} \cdot \nabla) \mathbf{a} - (\mathbf{a} \cdot \nabla) \mathbf{b}$$

$$(\text{curl} \mathbf{b} \cdot \nabla) \mathbf{b}_1 - (\mathbf{b}_1 \cdot \nabla) \text{curl} \mathbf{b} + (\text{curl} \mathbf{b}_1 \cdot \nabla) \mathbf{b} - (\mathbf{b} \cdot \nabla) \text{curl} \mathbf{b}_1 = 0$$



$$\begin{aligned}
 x &= \xi^{\frac{1}{2}} & y &= \eta^{\frac{1}{2}} & z &= \xi^{\frac{1}{2}} & P &= \pi^2 \\
 \frac{\partial u}{\partial x} &= \frac{\partial u}{\partial \xi} \frac{\partial \xi}{\partial x} & & & & & & \\
 &= 2\sqrt{\xi} \frac{\partial u}{\partial \xi} & & & & & & \\
 \frac{\partial^2 u}{\partial x^2} &= \left[ 2\sqrt{\xi} \frac{\partial^2 u}{\partial \xi^2} + \frac{1}{\sqrt{\xi}} \frac{\partial u}{\partial \xi} \right] 2\sqrt{\xi} = 4\xi \frac{\partial^2 u}{\partial \xi^2} + 2 \frac{\partial u}{\partial \xi}
 \end{aligned}$$

$$\frac{2n-1}{u^n} = \frac{n-2}{u^n}$$

$$n = -1$$

$$u = u^{-1} = \frac{1}{u}$$

$$\frac{\partial u}{\partial x} = -\frac{1}{u^2} \frac{\partial u}{\partial x}$$

$$P = \pi^{-2}$$

$$\frac{\partial^2 u}{\partial x^2} = + \frac{2}{u^3} \left( \frac{\partial u}{\partial x} \right)^2 - \frac{1}{u^4} \frac{\partial^2 u}{\partial x^2}$$

Wenn man also ein Läng der Kugel hat, so erhält man eine andere wenn man  $x, y, z$   $m$  mal größer macht, aber  $u, v, w$   $m$  mal kleiner und Drucktensor  $(m)^2$  mal kleiner (siehe darüber  $\mu$ ).

I	$x y z$	$u v w$	$\mu$	$P$	Daraus folgt $x y z \quad m \quad u v w \quad m \mu \quad m^2 P$ sind also nur zwei dann willkürliche Transformation
II	$m x y z$	$u v w$	$m \mu$	$P$	
III	$x y z$	$m u v w$	$m \mu$	$m^2 P$	
IV	$\frac{1}{m} x y z$	$\frac{1}{m} u v w$	$\mu$	$\frac{1}{m^2} P$	

III = letzter Ausdruck gezeigt



$$\rho(\nabla \cdot \mathbf{b}) = F - \frac{1}{\rho} \nabla P + \frac{\mu}{3\rho} \nabla^2 \text{div} \mathbf{b} + \frac{\mu}{\rho} \nabla^2 \mathbf{b}$$

$$\text{div}(\rho \mathbf{b}) = 0 = \rho \text{div} \mathbf{b} + \mathbf{S} \cdot \mathbf{b} \nabla \rho = 0$$

$$P = p(\rho) \quad \parallel \quad \text{div} \mathbf{b} \nabla \rho + \rho \nabla \text{div} \mathbf{b} + \nabla(\mathbf{S} \cdot \mathbf{b} \nabla \rho) = 0$$

~~$\nabla \cdot \mathbf{b} = a \text{div} \mathbf{b} + b \text{div} \mathbf{a}$~~   
 ~~$\left[ i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} \right] [a_1 \mathbf{e}_1 + a_2 \mathbf{e}_2] =$~~   
 ~~$a_1 (i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y}) \mathbf{e}_1 + \dots$~~   
 ~~$+ \left( \frac{\partial a_1}{\partial x} + \frac{\partial a_2}{\partial y} + \frac{\partial a_3}{\partial z} \right) (i \mathbf{e}_1 + j \mathbf{e}_2 + k \mathbf{e}_3)$~~

$$\text{curl}(\mathbf{A} \mathbf{b}) =$$

$$\rho \left[ \frac{1}{2} \nabla^2 \mathbf{b} + \nabla \mathbf{b} \text{curl} \mathbf{b} \right] = - \frac{1}{\rho} \nabla P + \frac{\mu}{\rho} \nabla^2 \mathbf{b} + \frac{\mu}{3\rho} \nabla \text{div} \mathbf{b}$$

curl:

$$\frac{1}{2} \left[ \rho \text{curl} \nabla^2 \mathbf{b} + \nabla \cdot \nabla^2 \mathbf{b} \nabla \rho \right] + \rho \text{curl} \nabla \mathbf{b} \text{curl} \mathbf{b} + \nabla(\nabla \rho \cdot \nabla \mathbf{b} \text{curl} \mathbf{b}) = \mu \text{curl} \nabla^2 \mathbf{b}$$

~~We can also do~~

$$-\nabla \cdot \nabla \rho \left[ \frac{1}{2} \nabla^2 \mathbf{b} + \nabla \mathbf{b} \text{curl} \mathbf{b} \right] + \rho \text{curl} (\nabla \mathbf{b} \text{curl} \mathbf{b}) = \mu \text{curl} \nabla^2 \mathbf{b}$$

$$= -\frac{\nabla P}{\rho} + \frac{\mu}{3\rho} \nabla \text{div} \mathbf{b} + \frac{\mu}{\rho} \nabla^2 \mathbf{b}$$

$$= -\nabla \cdot \nabla \rho \left[ -\frac{\nabla P}{\rho} + \frac{\mu}{3\rho} \nabla \text{div} \mathbf{b} + \frac{\mu}{\rho} \nabla^2 \mathbf{b} \right]$$

$$\text{curl} \cdot \nabla \mathbf{b} \text{curl} \mathbf{b} = \text{curl} \left[ -\frac{\nabla P}{\rho} + \frac{\mu}{3\rho} \nabla \text{div} \mathbf{b} + \frac{\mu}{\rho} \nabla^2 \mathbf{b} \right]$$

$$= \frac{\mu}{3\rho} \text{curl} \nabla \text{div} \mathbf{b} + \frac{\mu}{3\rho^2} \nabla \nabla \rho \nabla \text{div} \mathbf{b}$$

$$+ \frac{\mu}{\rho} \text{curl} \nabla^2 \mathbf{b} + \frac{\mu}{\rho^2} \nabla \nabla \rho \nabla^2 \mathbf{b}$$

$$= \frac{\mu}{\rho} \text{curl} \nabla^2 \mathbf{b} + \nabla \cdot \nabla \rho \left[ \frac{\mu}{3\rho^2} \nabla \text{div} \mathbf{b} + \frac{\mu}{\rho^2} \nabla^2 \mathbf{b} \right]$$



$$\nabla \cdot \mathbf{S}ab = \left( i \frac{\partial}{\partial x} + j \frac{\partial}{\partial y} + k \frac{\partial}{\partial z} \right) (a_1 b_1 + a_2 b_2 + a_3 b_3)$$

$$\text{curl } m \cdot b = \begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ m_1 b_1 + m_2 b_2 + m_3 b_3 \end{vmatrix} = i m \left( \frac{\partial b_3}{\partial y} - \frac{\partial b_2}{\partial z} \right) +$$

$$+ j \left( b_3 \frac{\partial m}{\partial y} - b_2 \frac{\partial m}{\partial z} \right) + \dots$$

$$= m \text{ curl } b + \nabla \cdot b \nabla m$$

$$\text{curl } \frac{\nabla P}{\rho} = \cancel{\frac{\text{curl } \nabla P}{\rho}} - \frac{1}{\rho^2} \nabla P \nabla P$$

$\nabla P$  und  $\nabla \rho$  sind gleichgerichtet

Angenommen  $\mathbf{b}$  genügt der Gleichung

$$\frac{1}{\rho} \nabla^2 \mathbf{b} + \nabla \mathbf{b} \text{ curl } \mathbf{b} = -\frac{\nabla P}{\rho} + \frac{\mu}{\rho} \nabla^2 \mathbf{b}$$

$$\text{dann ist } \rho \text{ curl } \nabla \text{ curl } \mathbf{b} = \frac{\mu}{\rho} \text{ curl } \nabla^2 \mathbf{b} + \frac{\nabla \cdot \nabla P}{\rho} \mathbf{b}$$

Dann genügt es auch demselben Gleichung  $+\frac{\mu}{\rho} \nabla \text{ div } \mathbf{b}$

falls  $\nabla \text{ div } \mathbf{b}$  und  $\nabla \rho$  gleichgerichtet sind

$$\text{also falls } \nabla \nabla \rho \nabla \text{ div } \mathbf{b} = 0$$

$$\nabla \text{ div } \mathbf{b} = -\frac{1}{\rho} \text{ div } \mathbf{b} \cdot \nabla \rho - \frac{1}{\rho} \nabla (\mathbf{S} \cdot \mathbf{b} \nabla \rho)$$

$$= \text{div } \mathbf{b} \nabla \log \rho$$

$$\text{also falls } \nabla \nabla \rho \nabla (\mathbf{S} \cdot \mathbf{b} \nabla \rho) = 0$$

$$\begin{aligned} \text{curl div } \mathbf{b} &= 0 \\ \frac{\partial u}{\partial x} + \dots &= -\frac{u \frac{\partial \log \rho}{\partial x} + \dots}{\rho} \end{aligned}$$

$$\text{div } \mathbf{b} = -\frac{\mathbf{S} \cdot \mathbf{b} \nabla \rho}{\rho} = -\mathbf{S} \cdot \mathbf{b} \nabla \log \rho$$

$$= -\mathbf{S} \cdot \mathbf{b} \frac{\nabla \rho}{\rho}$$



$$\operatorname{div} \sigma = -\nabla \sigma \cdot \nabla \log \rho$$

$$\sigma = \nabla \sigma \cdot \nabla \log \rho$$

$$\log \rho = \frac{1}{4\pi} \int \frac{\nabla^2 \log \rho}{r} dv \quad \frac{d^2}{dx^2} + \frac{2}{x} + \frac{2}{x^2}$$

$$\nabla \log \rho = \frac{\operatorname{div} \sigma}{\sigma} \nabla \sigma = \frac{\operatorname{div} \sigma}{\sigma} \nabla \sigma = \frac{\operatorname{div} \sigma}{\sigma} \nabla \sigma$$

$$\nabla^2 \log \rho = \operatorname{div} \nabla \log \rho =$$

$$\rho = F(P) \quad \nabla \rho = F'(P) \nabla P$$

$$\rho = F(P) \quad \nabla \rho = F'(P) \nabla P$$

$$\begin{aligned} \nabla A &= i \frac{\partial}{\partial x} A + i \frac{\partial}{\partial y} A + \dots \\ &= A \left( i \frac{\partial}{\partial x} + i \frac{\partial}{\partial y} + \dots \right) \\ &+ D \left( i \frac{\partial}{\partial x} + \dots \right) \\ &= A \nabla A + D \nabla A \end{aligned}$$

Kann das eine incompressible Stoff gelöst

$$\frac{1}{2} \nabla \sigma^2 + \nabla \sigma \cdot \nabla \sigma = -\nabla P + \mu \nabla^2 \sigma$$

Kann das auch eine compressible Stoff, wenn  $\sigma = \rho \varphi$  gelöst wird

$$\operatorname{div}(\rho \varphi) = 0$$

$$\mu = \mu(\rho)$$

$$\nabla \sigma^2 = \nabla \rho^2 \varphi^2 = 2\rho \nabla \rho \cdot \varphi^2 + 2\rho^2 \nabla \varphi \cdot \varphi$$

$$\operatorname{curl} \sigma = \rho \operatorname{curl} \varphi + \nabla \rho \cdot \varphi \nabla \rho$$

$$\nabla \sigma \cdot \operatorname{curl} \sigma = \rho^2 \nabla \varphi \cdot \operatorname{curl} \varphi + \rho \nabla \rho \cdot \varphi (\nabla \varphi \cdot \nabla \rho)$$

$$= -\nabla \rho \cdot \nabla \varphi^2 + \varphi \nabla \rho \cdot \nabla \rho$$

$$= \rho^2 \nabla \varphi \cdot \operatorname{curl} \varphi + \nabla \rho^2 \cdot \varphi^2 + \rho \varphi \nabla \rho \cdot \nabla \rho$$



$$\begin{array}{ccc|ccc}
 i & j & k & i & j & k \\
 \varphi_1 & \varphi_2 & \varphi_3 & \varphi_1 & \varphi_2 & \varphi_3 \\
 \hline
 a_1 & a_2 & a_3 & \left| \begin{array}{cc|cc|cc}
 \varphi_2 & \varphi_3 & \varphi_3 \varphi_1 & \varphi_1 \varphi_1 \\
 \frac{\partial \varphi}{\partial y} & \frac{\partial \varphi}{\partial z} & \frac{\partial}{\partial z} \frac{\partial \varphi}{\partial x} & \frac{\partial}{\partial x} \frac{\partial \varphi}{\partial z} \\
 a_2 & a_3 & a_2 & a_3
 \end{array} \right|
 \end{array}$$

$$i (\varphi_2 \varphi_1 a_2 - \varphi_2^2 a_1 - \varphi_3^2 a_1 + \varphi_3 \varphi_1 a_3)$$

$$ii [(\varphi_1 a_1 + \varphi_2 a_2 + \varphi_3 a_3) \varphi_1 - (\varphi_1^2 + \varphi_2^2 + \varphi_3^2) a_1]$$

$$\varphi \Delta \varphi - a \varphi^2$$

$$\nabla^2(\rho \varphi) = \Delta(\rho \varphi) = i \nabla^2 \rho \varphi_1 + j \nabla^2 \rho \varphi_2 +$$

$$-2i \nabla \rho \nabla \varphi_1$$

$$= i \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) \rho \varphi_1$$

$$= i \left( \nabla^2 \rho \cdot \varphi_1 + 2 \nabla \rho \cdot \nabla \varphi_1 + \rho \nabla^2 \varphi_1 + 2 \left( \frac{\partial \rho}{\partial x} \frac{\partial \varphi_1}{\partial x} + \frac{\partial \rho}{\partial y} \frac{\partial \varphi_1}{\partial y} + \frac{\partial \rho}{\partial z} \frac{\partial \varphi_1}{\partial z} \right) \right)$$

$$+ j \left( \nabla^2 \rho \cdot \varphi_2 + 2 \nabla \rho \cdot \nabla \varphi_2 + \rho \nabla^2 \varphi_2 \right) \frac{\partial \rho}{\partial x} \frac{\partial \varphi_2}{\partial x}$$

$$+ k \left( \right)$$

$$= \rho \nabla^2 \varphi + \rho \nabla^2 \varphi + 2 \left( \frac{\partial \rho}{\partial x} \frac{\partial \varphi}{\partial x} + \frac{\partial \rho}{\partial y} \frac{\partial \varphi}{\partial y} + \frac{\partial \rho}{\partial z} \frac{\partial \varphi}{\partial z} \right)$$

$$- \nabla(\rho \varphi) - \frac{\mu}{3} \rho \nabla \operatorname{div} \varphi$$

$$\left[ \frac{1}{2} (\rho^2 \nabla^2 \varphi + \rho \nabla^2 \rho \varphi) + \rho^2 \nabla \varphi \operatorname{div} \varphi - \frac{\rho^2 \nabla \rho^2}{2} + \rho \varphi \Delta \varphi \right] = - \frac{\mu}{3} \rho \nabla \operatorname{div} \varphi +$$

$$\mu \left[ \rho \nabla^2 \varphi + \rho \nabla^2 \rho + 2 \left( \frac{\partial \rho}{\partial x} \frac{\partial \varphi}{\partial x} + \dots \right) \right]$$

$$\frac{1}{2} \rho \nabla^2 \varphi^2$$

$$+ \rho \nabla \varphi \operatorname{div} \varphi$$

$$= -\nabla \mu + \frac{\mu}{3} \nabla \operatorname{div} \varphi + \mu \nabla^2 \varphi$$



Two dimensional with friction

$$\xi = \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial \xi}{\partial x} = \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) = \frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial x^2}$$

$$u \frac{\partial \xi}{\partial x} + v \frac{\partial \xi}{\partial y} = \mu \left( \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial^2 \xi}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial x} \frac{\partial \xi}{\partial x} + u \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial v}{\partial x} \frac{\partial \xi}{\partial y} + v \frac{\partial^2 \xi}{\partial x \partial y} = \mu \left( \frac{\partial^3 \xi}{\partial x^3} + \frac{\partial^3 \xi}{\partial x \partial y^2} \right)$$

$$\frac{\partial u}{\partial y} \frac{\partial \xi}{\partial x} + u \frac{\partial^2 \xi}{\partial x \partial y} + \frac{\partial v}{\partial y} \frac{\partial \xi}{\partial y} + v \frac{\partial^2 \xi}{\partial y^2} = \mu \left( \frac{\partial^3 \xi}{\partial x^2 \partial y} + \frac{\partial^3 \xi}{\partial y^3} \right)$$

for further simplification minus  $\left( \frac{\partial^2 \xi}{\partial x^2} \right) + \left( \frac{\partial^2 \xi}{\partial y^2} \right) = 0$  minus

$$= \left( \frac{\partial^4 \xi}{\partial x^4} \right) + 2 \left( \frac{\partial^4 \xi}{\partial x^2 \partial y^2} \right) + \left( \frac{\partial^4 \xi}{\partial y^4} \right) = 0$$

2D.  $\xi = x(y - \sqrt{a^2 - x^2})$

$$\frac{\partial \xi}{\partial x} = y - \sqrt{a^2 - x^2} + \frac{x^2}{\sqrt{a^2 - x^2}}$$

$$\frac{\partial \xi}{\partial y} = x$$

$$\frac{\partial^2 \xi}{\partial x^2} = \frac{x}{\sqrt{a^2 - x^2}} + \frac{2x}{\sqrt{a^2 - x^2}} + \frac{x^3}{\sqrt{a^2 - x^2}^3}$$

$$\frac{\partial^2 \xi}{\partial y^2} = 0$$

$$\xi = (y - \sqrt{a^2 - x^2})^n$$

$$\frac{\partial \xi}{\partial x} = \frac{x n}{\sqrt{a^2 - x^2}} (y - \sqrt{a^2 - x^2})^{n-1}$$

$$\frac{\partial^2 \xi}{\partial x^2} = \frac{n}{\sqrt{a^2 - x^2}} (y - \sqrt{a^2 - x^2})^{n-1} + \frac{x^2 n}{\sqrt{a^2 - x^2}^3} (y - \sqrt{a^2 - x^2})^{n-1} + \frac{n(n-1) x^2}{\sqrt{a^2 - x^2}} (y - \sqrt{a^2 - x^2})^{n-2}$$



but the  
div curl = 0

$$\frac{\partial f}{\partial x} + \frac{\partial g}{\partial y} + \frac{\partial h}{\partial z} = 0$$

$$\frac{\partial}{\partial x} \left( u f - \mu \frac{\partial f}{\partial x} \right) + \frac{\partial}{\partial y} \left( v f - \mu \frac{\partial f}{\partial y} \right) + \frac{\partial}{\partial z} \left( w f - \mu \frac{\partial f}{\partial z} \right) = 0 \quad k$$

$$\frac{\partial}{\partial x} \left( u f - \mu \frac{\partial f}{\partial x} \right) + \frac{\partial}{\partial y} \left( v f - \mu \frac{\partial f}{\partial y} \right) + \frac{\partial}{\partial z} \left( w f - \mu \frac{\partial f}{\partial z} \right) = 0 \quad i$$

$$\frac{\partial}{\partial x} \left( u g - \mu \frac{\partial g}{\partial x} \right) \dots \quad j$$

$$\frac{\partial f}{\partial y} = n (y - \sqrt{\dots})^{n-1}$$

$$\frac{\partial^2 f}{\partial y^2} = n(n-1) (y - \sqrt{\dots})^{n-2}$$

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = \frac{n(a^2 - x^2 + x^2)}{\sqrt{\dots}^3} (y - \sqrt{\dots})^{n-1} + \frac{n(n-1)x^2 (y - \sqrt{\dots})^{n-2}}{a^2 - x^2} + n(n-1) (y - \sqrt{\dots})^{n-2}$$

$$= n (y - \sqrt{\dots})^{n-2} \left[ \frac{a^2 y - a}{\sqrt{\dots}^3} + \frac{n x^2}{a^2 - x^2} + n - 2 \right]$$

$n > 2$

$$10. \quad y = x^2 (y - a)^3$$

$$f = 2(y - a)^3 + 6 x^2 (y - a)$$

$$\frac{\partial f}{\partial x} = 12 x (y - a) \quad \frac{\partial f}{\partial y} = 6(y - a)^2 + 6 x^2$$

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = 12(y - a) + 12(y - a) = 24(y - a)$$



$$\frac{\partial \varphi}{\partial x} [2x(y-a)] + \frac{\partial \varphi}{\partial y} [(y-a)^2 + x^2] = 4(y-a) - 3x^2(y-a)^2 + 2x(y-a)[(y-a)^2 + x^2]$$

$$\frac{\partial \varphi}{\partial x} 2x(y-a) + \frac{\partial \varphi}{\partial y} [(y-a)^2 + x^2] = 4(y-a) - 6x^3(y-a)^3 + 2x(y-a)^3 + 2x^3(y-a) \\ = 2(y-a)[2 + [(y-a)^2 + x^2 - 3x^2(y-a)^2]x]$$

$$P \frac{\partial \varphi}{\partial x} + Q \frac{\partial \varphi}{\partial y} = R$$

$$\frac{dx}{P} = \frac{dy}{Q} = \frac{d\varphi}{R}$$

$$\frac{dx}{2x(y-a)} = \frac{dy}{(y-a)^2 + x^2}$$

$$\left[ \frac{y-a}{2x} + \frac{x}{2(y-a)} \right] dx = dy$$

$$\frac{y-a}{x} = 2$$

$$y-a = 2x$$

$$dy = 2dx + x dx$$

$$(2 + \frac{1}{2}) dx = 2(2dx + x dx)$$

$$dx = 2x^2 dx + 2x dx$$

$$(1-2x^2) dx = 2x dx$$

$$\frac{dx}{x} = \frac{2x dx}{1-2x^2}$$

$$2 \ln x = \frac{1}{2} (1-2x^2)$$

$$\frac{1}{x} = \frac{1}{2} (1-2x^2)$$

$$A = x^2 - y^2 + 2xy - a^2$$

$$x^2 - (y-a)^2 = Ax$$

$$x dx = (y-a) dy$$

$$(2x - A) dx = 2(y-a) dy$$

$$\frac{dx}{dy} = \frac{y-a}{x}$$

$$\frac{dx}{dy} = \frac{(y-a)2x}{x^2 + (y-a)^2 + 2xy + a^2}$$



$$(y-a)^2 = x^2 - Ax \quad A = f(y)$$

$$R = 2\sqrt{x^2 - Ax} \left[ 2 + x \left[ -Ax - 3x^2(x^2 - Ax) \right] \right]$$

$$= 2\sqrt{x^2 - Ax} \left[ 2 - Ax^2 - 3x^5 + 3Ax^4 \right]$$

$$\frac{dx}{2x\sqrt{x^2 - Ax}} = \frac{dy}{\left[ 2 - \right]}$$

$$dy = dx \left[ \frac{2}{x} - Ax - 3x^4 + 3Ax^3 \right] \text{ weil } A = \text{const}$$

$$y = \ln x - \frac{Ax^2}{2} - \frac{3}{5}x^5 + \frac{3}{4}Ax^4 + B = f(y)$$

$$u = \frac{1}{x} + 3x^2(y-a)^2$$

$$\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0!$$

$$\text{Limit} := -\frac{1}{x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0$$

$$B = \frac{y^4}{2x^2}$$

$$\frac{v}{u} = \frac{\frac{y}{x^2} - 2x(y-a)^3}{\frac{1}{x} + 3x^2(y-a)^2} = \frac{y - 2x^3(y-a)^3}{x^2 + 3x^4(y-a)^2}$$

$$\sqrt{u} \cdot \sqrt{v} =$$



Angenommen  $u$  und  $v$  werden an der Kreiskothe  $= 0$  von ~~der~~ <sup>abwärts</sup> ~~der~~ <sup>Ordy</sup>

$$u = (a-r)^n f(x,y) \quad \text{f. p. in Rand}$$

$$v = (a-r)^m F(x,y) \quad \text{f. p. in Rand}$$

Für  $x, y = \infty$ :  $u = c$  somit  $f(x,y) = \frac{c}{a^n}$

$$v = 0$$

$$F(x,y) = \frac{1}{a^{m+k}}$$

$$\Delta \{ = \frac{\partial^2 u}{\partial y^2} - \frac{\partial^2 v}{\partial x^2}$$

$$\{ = -n(a-r)^{n-1} \frac{y}{n} f(x,y) + (a-r)^n \frac{\partial f}{\partial y} -$$

$$+ m(a-r)^{m-1} \frac{x}{n} F(x,y) - (a-r)^m \frac{\partial F}{\partial x}$$

2. Probe mit:  $n = m = 1$

$$\{ = -\frac{y}{n} f + (a-r) \frac{\partial f}{\partial y}$$

$$+ \frac{x}{n} F - (a-r) \frac{\partial F}{\partial x}$$

Da  $\{ \geq 0$  an der Oberkante  
 $\{ = 0$  für  $y = 0$

$$\frac{\partial \{ }{\partial x} = \frac{x y}{n^2} f - \frac{y}{n} \frac{\partial f}{\partial x} - \frac{x}{n} \frac{\partial f}{\partial y} + (a-r) \frac{\partial^2 f}{\partial x \partial y} +$$

$$+ \frac{1}{n} F - \frac{x^2}{n^2} F + 2 \frac{x}{n} \frac{\partial F}{\partial x} - (a-r) \frac{\partial^2 F}{\partial x^2}$$

$$\underbrace{\quad}_{\frac{x^2}{n^2} F}$$

$$\frac{\partial^2 \{ }{\partial x^2} = \frac{y}{n^3} f - 3 \frac{x^2 y}{n^5} f + \frac{x y}{n^3} \frac{\partial f}{\partial x} + \frac{x y}{n^3} \frac{\partial f}{\partial x} - \frac{y}{n} \frac{\partial^2 f}{\partial x^2} - \frac{1}{n} \frac{\partial^2 f}{\partial y^2} + \frac{x^2}{n^3} \frac{\partial^2 f}{\partial y^2} -$$

$$- \frac{x}{n} \frac{\partial^2 f}{\partial x \partial y} - \frac{x}{n} \frac{\partial^2 f}{\partial x \partial y} + (a-r) \frac{\partial^3 f}{\partial x^2 \partial y} - \frac{3 y^2 x}{n^5} F + \frac{y^2}{n^3} \frac{\partial F}{\partial x} + \frac{2}{n} \frac{\partial^2 F}{\partial x^2} -$$

$$- \frac{2 x^2}{n^3} \frac{\partial F}{\partial x} + \frac{2 x}{n} \frac{\partial^2 F}{\partial x^2} + \frac{x}{n} \frac{\partial^2 F}{\partial x^2} - (a-r) \frac{\partial^3 F}{\partial x^3}$$



$$= \frac{(y^2 - 2xy)}{n^5} f + \frac{2xy}{n^3} \frac{\partial f}{\partial x} - \frac{y}{n} \frac{\partial^2 f}{\partial x^2} - \frac{y^2}{n^3} \frac{\partial^2 f}{\partial y^2} - \frac{2x}{n} \frac{\partial^2 f}{\partial x \partial y} + (a-n) \frac{\partial^3 f}{\partial x^2 \partial y} -$$

$$- \frac{3y^2 x}{n^5} F + \frac{(x^2 + 2xy)}{n^3} \frac{\partial F}{\partial x} + \frac{3x}{n} \frac{\partial^2 F}{\partial x^2} - (a-n) \frac{\partial^2 F}{\partial x^2}$$


---

$$\frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} = -\frac{f}{n^3} + \frac{2xy}{n^3} \left( \frac{\partial f}{\partial x} + \frac{\partial f}{\partial y} \right) - \frac{y}{n} \frac{\partial^2 f}{\partial x^2} - \frac{x}{n} \frac{\partial^2 f}{\partial y^2} - \frac{y^2}{n^3} \frac{\partial^2 f}{\partial y^2} - \frac{x^2}{n^3} \frac{\partial^2 f}{\partial x^2} -$$

$$- \frac{2(x+y)}{n} \frac{\partial^2 f}{\partial x \partial y} + (a-n) \left( \frac{\partial^3 f}{\partial x^2 \partial y} + \frac{\partial^3 f}{\partial y^2 \partial x} \right) - \frac{3(y+x)xy}{n^5} F +$$

$$+ \frac{2y^2 - x^2}{n^3} \frac{\partial^2 F}{\partial x^2} + \frac{2x^2 - y^2}{n^3} \frac{\partial^2 F}{\partial y^2} + \frac{3x}{n} \frac{\partial^2 F}{\partial x^2} + \frac{3y}{n} \frac{\partial^2 F}{\partial y^2} - (a-n) \left( \frac{\partial^2 F}{\partial x^2} + \frac{\partial^2 F}{\partial y^2} \right)$$


---

$$u = (a-n) f \quad v = (a-n) F$$

$$= \frac{\partial \varphi}{\partial x} + \frac{\partial \psi}{\partial y} \quad = \frac{\partial \varphi}{\partial y} - \frac{\partial \psi}{\partial x}$$

$$(a-n) \left( \frac{\partial f}{\partial x} + \frac{\partial F}{\partial y} \right) = \frac{x f + y F}{n} \quad \left. \vphantom{\frac{x f + y F}{n}} \right\} \text{Incompressibility}$$

$$\varphi = \text{real part of } \Phi(x+iy)$$



~~General problem in two dimensions~~

$$\frac{\partial \varphi}{\partial x} = \underbrace{\mu \left( \frac{\partial^2 \varphi}{\partial x^2} + 2 \frac{\partial^2 \varphi}{\partial x \partial y} + \frac{\partial^2 \varphi}{\partial y^2} \right) - \frac{\partial \varphi}{\partial y} \left( \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial x \partial y} \right) + \frac{\partial \varphi}{\partial x} \left( \frac{\partial^2 \varphi}{\partial x \partial y} + \frac{\partial^2 \varphi}{\partial y^2} \right)}_{\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial x \partial y}^2} \Phi_1$$

$$- \frac{\partial \varphi}{\partial y} \frac{\frac{\partial^2 \varphi}{\partial x \partial y} + \frac{\partial^2 \varphi}{\partial y^2}}{\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial x \partial y}^2} \Phi_2$$

$$\frac{\partial^2 \varphi}{\partial x^2} = \frac{\partial \Phi_1}{\partial x} - \frac{\partial^2 \varphi}{\partial x \partial y} \Phi_2 - \frac{\partial \varphi}{\partial y} \frac{\partial \Phi_2}{\partial x}$$

$$u = \frac{\mu \left( \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} \right) - v \frac{\partial^2 \varphi}{\partial x \partial y}}{\frac{\partial \varphi}{\partial x}} = -\xi + \frac{\partial u}{\partial y}$$

$$\frac{\partial u}{\partial x} = \frac{\partial \Phi_1}{\partial x} - v \frac{\partial \Phi_2}{\partial x} - \Phi_2 \frac{\partial v}{\partial x}$$

$$\frac{\partial u}{\partial y} = \frac{\partial \Phi_1}{\partial y} - v \frac{\partial \Phi_2}{\partial y} - \Phi_2 \frac{\partial v}{\partial y}$$

$$\frac{\partial u}{\partial x} = \frac{\partial \Phi_1}{\partial x} - v \frac{\partial \Phi_2}{\partial x} + \Phi_2 \xi - \Phi_2 \frac{\partial \Phi_1}{\partial y} + v \Phi_2 \frac{\partial \Phi_2}{\partial y} - \Phi_2 \frac{\partial v}{\partial y} = -\frac{\partial u}{\partial x}$$

$$\frac{\partial u}{\partial x} [1 - \Phi_2] = \frac{\partial \Phi_1}{\partial x} + \Phi_2 \xi - \Phi_2 \frac{\partial \Phi_1}{\partial y} + v \left[ \Phi_2 \frac{\partial \Phi_2}{\partial y} - \frac{\partial \Phi_2}{\partial x} \right]$$



$$\nabla^2 v = 0$$

$$\zeta = \frac{\partial u}{\partial y}$$

$$\frac{\partial u}{\partial x} = 0$$

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~~$\nabla^2 u = 0$~~

$$u \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^3 u}{\partial x^2 \partial y} = 0$$

$$u = Ay^2 + By + C$$

With neglect of inertia terms:

$$\nabla p - \mu \nabla^2 \zeta = 0$$

$$\frac{\partial p}{\partial x} = \mu \left( \frac{\partial^2 \zeta}{\partial x^2} + \frac{\partial^2 \zeta}{\partial y^2} \right)$$

$$\frac{\partial p}{\partial y} = \mu \left( \frac{\partial^2 \zeta}{\partial x^2} + \frac{\partial^2 \zeta}{\partial y^2} \right)$$

$$\frac{\partial^3 \zeta}{\partial x^2 \partial y} + \frac{\partial^3 \zeta}{\partial y^3} - \frac{\partial^2 v}{\partial x^2} - \frac{\partial^2 v}{\partial y^2} = 0$$

$$= \frac{\partial^2 \zeta}{\partial x^2} + \frac{\partial^2 \zeta}{\partial y^2} = 0$$

$$\zeta = \text{Re } \Phi(x+iy) = \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y}$$

↑

well known

above:

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0$$

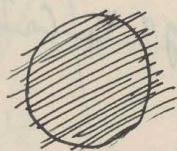
$$u = \frac{\partial \psi}{\partial y} \quad v = \frac{\partial \psi}{\partial x}$$

$$\frac{\partial \psi}{\partial x} = \int \frac{f(x,y)}{r^2} dx dy$$

$$(a-r)f = 2 \frac{\partial \psi}{\partial y} \quad \frac{\partial \psi}{\partial x} = (a-r) \frac{\partial f}{\partial x} + \frac{x}{2} f = (a-r) \frac{\partial f}{\partial y} - \frac{y}{2} f$$

$$F = \frac{\partial \psi}{\partial y}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y}$$



$$\int \frac{dx}{\sqrt{x^2 + r^2}} = \ln \left( \frac{dx}{\sqrt{1 + \frac{r^2}{x^2}}} \right) = \ln(x + \sqrt{x^2 + r^2}) = \ln(x + r)$$

$$\int \log r \cdot f(x,y) dx dy$$

$$V = \frac{1}{2} \int \log(x+iy) \cdot f(x,y) dx dy$$

$$\frac{\partial V}{\partial x} = \frac{1}{2} \int \frac{x}{r^2} f(x,y) dx dy + \log r \cdot \frac{\partial f}{\partial x}$$

$$\frac{\partial V}{\partial y} = \frac{1}{2} \int \frac{y}{r^2} f(x,y) dx dy + \log r \cdot \frac{\partial f}{\partial y}$$



$$\frac{1}{r} \frac{\partial(rv)}{\partial r} = \frac{\partial v}{\partial r} + \frac{v}{r} = \frac{\rho g a^2}{r^2}$$

$$r v^k = \frac{c}{r^k}$$

$$r = c \rho^k$$

$$c k \rho^{k-1} \frac{\partial \rho}{\partial r} + \frac{c \rho^k}{r} = \frac{\rho g a^2}{r^2}$$

$$c k \rho^{k-2} \frac{d\rho}{dr} + \frac{c \rho^{k-1}}{r} = \frac{g a^2}{r^2}$$

$$c k \rho^{k-1} d\rho = \left( \frac{g a^2}{r^2} - \frac{c \rho^{k-1}}{r} \right) dr = \frac{dr}{r^2} (g a^2 - c r \rho^{k-1})$$

$$\rho^{k-1} = z$$

$$\frac{k}{k-1} \frac{dz}{dr} + \frac{z}{r} = \frac{g a^2}{c r^2}$$

$$\frac{z}{r} = \frac{A}{r}$$

$$z = \frac{A}{r} + \frac{D}{r^2} + \frac{C r^2}{2} \ln r$$

$$\frac{dz}{dr} = \frac{A}{r^2} + \frac{D}{r^3} + C r \ln r + \frac{C r^2}{2}$$

$$-\frac{k A}{k-1} + A = \frac{g a^2}{c}$$

$$A = \frac{g a^2}{c} \frac{1}{1 - \frac{k}{k-1}}$$

$$= \frac{g a^2}{c} (1 - k)$$

$$\rho^{k-1} = \frac{g a^2 (1-k)}{c} \frac{1}{r}$$

$$\rho = \left( \frac{g a^2 (1-k)}{c} \right)^{\frac{1}{k-1}} \frac{1}{r^{\frac{1}{k-1}}} = \frac{A}{r^{\frac{1}{k-1}}}$$

$$2 = u v \quad \frac{du}{dr} v + u \frac{dv}{dr}$$



$$\underbrace{\left( \frac{k}{k-1} \frac{dv}{dr} + \frac{v}{r} \right) u + \frac{k}{k-1} v \frac{du}{dr}}_{=0} = g \frac{a^2}{c r^2}$$

$$\frac{k}{k-1} \frac{dv}{v} + \frac{dr}{r} = 0$$

$$v^{\frac{k}{k-1}} r^{k-1} = b$$

$$v = b^{\frac{1}{k}} r^{-\frac{k-1}{k}}$$

$$du = \frac{k-1}{k} g \frac{a^2}{c} b^{-\frac{1}{k}} \frac{1}{r^{\frac{k+1}{k}}} dr$$

$$u = \frac{k-1}{k} g \frac{a^2}{c} b^{-\frac{1}{k}} \frac{1}{-\frac{1}{k}} r^{-\frac{1}{k}} + C$$

$$2 = \frac{(1-k)}{k} g \frac{a^2}{c} \frac{1}{r} + C r^{\frac{1-k}{k}} = p^{\frac{1-k}{k}}$$

$$\frac{k}{k-1} \left( -\frac{1}{r^2} g \frac{a^2}{c} + \frac{1}{r} \frac{1}{r^{\frac{k+1}{k}}} \right) + \frac{k-1}{k} g \frac{a^2}{c} \frac{1}{r} + C r^{\frac{1-k}{k}} = g \frac{a^2}{c r^2}$$

$$\frac{k}{k-1} \left( -\frac{1}{r^2} g \frac{a^2}{c} + \frac{1}{r} \frac{1}{r^{\frac{k+1}{k}}} \right) + \frac{k-1}{k} g \frac{a^2}{c} \frac{1}{r} + C r^{\frac{1-k}{k}} = g \frac{a^2}{c r^2}$$

$$p_0^{\frac{k-1}{k}} = (1-k) g \frac{a^2}{c} + C a^{\frac{k-1}{k}}$$

$$C = \left[ p_0^{\frac{k-1}{k}} + (k-1) g \frac{a^2}{c} \right] a^{\frac{k-1}{k}}$$

$$p^{\frac{k-1}{k}} = (1-k) g \frac{a^2}{c} \frac{1}{r} + \left[ p_0^{\frac{k-1}{k}} + (k-1) g \frac{a^2}{c} \right] \left( \frac{r}{a} \right)^{\frac{1-k}{k}}$$

$$= p_0^{\frac{k-1}{k}} \left( \frac{r}{a} \right)^{\frac{1-k}{k}} + (1-k) g \frac{a^2}{c} \left[ \frac{a}{r} - \left( \frac{r}{a} \right)^{\frac{1-k}{k}} \right]$$

$$= p_0^{\frac{k-1}{k}} \left( \frac{r}{a} \right)^{\frac{1-k}{k}} + (1-k) g \frac{a^2}{c r} \left[ 1 - \left( \frac{r}{a} \right)^{\frac{1}{k}} \right]$$

$$RT = p v = \frac{p}{\rho} = c p^{\frac{k-1}{k}} \rightarrow$$

$$n \sim \frac{\sqrt{T}}{p} \sim p^{\frac{k-1}{2k}}$$



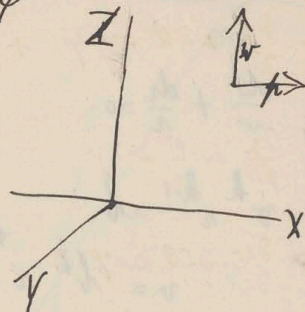
Transformation of general special equations (for rotational ~~body~~ symmetry) in polar coordinates  $r, \theta, \varphi$

$$z = \text{axis of symmetry} = r \cos \theta$$

$$x = r \sin \theta \cos \varphi$$

$$y = r \sin \theta \sin \varphi$$

Arts:  ~~$\frac{\partial u}{\partial r} = \frac{\partial u}{\partial \rho} = \frac{\partial u}{\partial z}$~~



Equation of Continuity:  $\frac{\partial u}{\partial r} + \frac{\partial v}{\partial \theta} + \frac{\partial w}{\partial \varphi} = 0$

$$\frac{\partial u}{\partial r} \sin \theta \cos \varphi + \frac{\partial u}{\partial \theta} \frac{\cos \theta \cos \varphi}{r} - \frac{\partial u}{\partial \varphi} \frac{\sin \varphi}{r \sin \theta} = \frac{\partial u}{\partial x}$$

$$u = 6 \sin \theta \cos \varphi$$

$$\frac{\partial u}{\partial r} \sin \theta \sin \varphi + \frac{\partial u}{\partial \theta} \frac{\cos \theta \sin \varphi}{r} + \frac{\partial u}{\partial \varphi} \frac{\cos \varphi}{r \sin \theta} = \frac{\partial u}{\partial y}$$

$$v = 6 \sin \theta \sin \varphi$$

$$\frac{\partial u}{\partial r} \cos \theta - \frac{\partial u}{\partial \theta} \frac{\sin \theta}{r} = \frac{\partial u}{\partial z}$$

$$w = 6 \cos \theta$$

New variable:  $\rho = \sqrt{u^2 + v^2}$   $\frac{\partial \rho}{\partial \varphi} = 0$

$$u = \rho \cos \varphi$$

$$\frac{\partial w}{\partial \varphi} = 0$$

$$v = \rho \sin \varphi$$

$$\frac{\partial u}{\partial x} = \frac{\partial \rho}{\partial r} \sin \theta \cos \varphi - \frac{\partial \rho}{\partial \theta} \frac{\cos \theta \cos \varphi}{r} + \frac{\partial \rho}{\partial \varphi} \frac{\sin \varphi}{r \sin \theta} + \rho \frac{\sin \varphi}{r \sin \theta}$$

$$\frac{\partial u}{\partial y} = \frac{\partial \rho}{\partial r} \sin \theta \sin \varphi + \frac{\partial \rho}{\partial \theta} \frac{\cos \theta \sin \varphi}{r} - \frac{\partial \rho}{\partial \varphi} \frac{\cos \varphi}{r \sin \theta} - \rho \frac{\cos \varphi}{r \sin \theta}$$

$$\frac{\partial u}{\partial z} = \frac{\partial \rho}{\partial r} \cos \theta - \frac{\partial \rho}{\partial \theta} \frac{\sin \theta}{r}$$



$$\frac{\partial v}{\partial x} = \frac{\partial}{\partial z} \sin^2 \theta \cos \varphi \sin \varphi + \frac{\partial}{\partial \theta} \frac{\cos \theta \sin \varphi \cos \varphi}{r} - \frac{\sin^2 \varphi \cos \varphi}{r \sin \theta}$$

$$\frac{\partial v}{\partial y} = \frac{\partial}{\partial z} \sin^2 \theta \sin \varphi + \frac{\partial}{\partial \theta} \frac{\cos \theta \sin \varphi}{r} + \varphi \frac{\cos \varphi}{r \sin \theta}$$

$$\frac{\partial v}{\partial z} = \frac{\partial}{\partial z} \cos \theta \sin \varphi - \frac{\partial}{\partial \theta} \frac{\sin \theta \sin \varphi}{r}$$

$$\frac{\partial w}{\partial x} = \frac{\partial w}{\partial z} \sin \theta \cos \varphi + \frac{\partial w}{\partial \theta} \frac{\cos \theta \cos \varphi}{r}$$

$$\frac{\partial w}{\partial y} = \frac{\partial w}{\partial z} \sin \theta \sin \varphi + \frac{\partial w}{\partial \theta} \frac{\cos \theta \sin \varphi}{r}$$

$$\frac{\partial w}{\partial z} = \frac{\partial w}{\partial z} \cos \theta - \frac{\partial w}{\partial \theta} \frac{\sin \theta}{r}$$

für Kugelkoordinaten

$$\frac{\partial u}{\partial x} = \frac{\partial \phi}{\partial z} \sin^2 \theta \cos \varphi + \frac{\phi}{r} \cos^2 \theta \cos \varphi + \frac{\phi}{r} \sin^2 \varphi$$

$$\frac{\partial w}{\partial y} = \frac{\partial \phi}{\partial z} \sin^2 \theta \sin \varphi + \frac{\phi}{r} \cos^2 \theta \sin \varphi + \frac{\phi}{r} \cos \varphi$$

$$\frac{\partial w}{\partial z} = \frac{\partial \phi}{\partial z} \cos^2 \theta + \frac{\phi}{r} \sin^2 \theta$$

$$\cos^2 \theta + \sin^2 \theta = 1$$

$$\frac{\partial u}{\partial y} = \frac{\partial \phi}{\partial z} \sin^2 \theta \sin \varphi + \frac{\phi}{r} (\cos^2 \theta \sin \varphi + \sin^2 \varphi \cos \varphi)$$

$$= \sin^2 \theta \sin \varphi \cos \varphi \left( \frac{\partial \phi}{\partial z} - \frac{\phi}{r} \right)$$

$$\frac{\partial v}{\partial x} = \frac{\partial \phi}{\partial z} \sin^2 \theta \cos \varphi + \frac{\phi}{r} (\cos^2 \theta \cos \varphi - \sin^2 \varphi \sin \varphi)$$

$$\frac{\partial u}{\partial z} = \frac{\partial \phi}{\partial z} \sin^2 \theta \cos \varphi - \frac{\phi}{r} \sin^2 \theta \cos \varphi$$

$$= \sin^2 \theta \cos \varphi \left[ \frac{\partial \phi}{\partial z} - \frac{\phi}{r} \right] = \frac{\partial w}{\partial x}$$

$$\frac{\partial v}{\partial z} = \frac{\partial w}{\partial y} = \left[ \frac{\partial \phi}{\partial z} - \frac{\phi}{r} \right] \sin^2 \theta \sin \varphi$$

$$\frac{\partial u}{\partial x} = \left[ \frac{\partial \phi}{\partial z} + \frac{\phi}{r} \right] \sin^2 \theta \cos \varphi + \frac{\phi}{r}$$

$$\frac{\partial v}{\partial y} = \left[ \frac{\partial \phi}{\partial z} - \frac{\phi}{r} \right] \sin^2 \theta \sin \varphi + \frac{\phi}{r}$$

$$\frac{\partial w}{\partial z} = \left[ \frac{\partial \phi}{\partial z} - \frac{\phi}{r} \right] \cos^2 \theta + \frac{\phi}{r}$$

$$\frac{\partial u}{\partial y} = \frac{\partial v}{\partial x} = \left[ \frac{\partial \phi}{\partial z} - \frac{\phi}{r} \right] \sin^2 \theta \sin \varphi \cos \varphi$$

$$\frac{\partial u}{\partial z} = \frac{\partial w}{\partial x} = \left[ \frac{\partial \phi}{\partial z} - \frac{\phi}{r} \right] \sin^2 \theta \cos^2 \varphi \cos \varphi$$

$$\frac{\partial v}{\partial z} = \frac{\partial w}{\partial y} = \left[ \frac{\partial \phi}{\partial z} - \frac{\phi}{r} \right] \sin^2 \theta \sin^2 \varphi \sin \varphi$$







$$\frac{\partial p}{\partial r} = -\rho \frac{g a^2}{r^2} \quad | \quad p v^k = c \quad p = c \rho^{\frac{1}{k}} \quad c = p_0 v_0^k \quad 74$$

$$= p_0 \rho_0^{-k}$$

$$k c \rho^{k-1} \frac{\partial p}{\partial r} = -\left(\frac{c}{r^2}\right) g a^2$$

$$k c \rho^{k-2} dp = -\frac{dr}{r^2} g a^2$$

$$k c \frac{\rho^{k-1}}{k-1} = \frac{g a^2}{r} + \text{const}$$

$$k c \frac{\rho_0^{k-1}}{k-1} = g a + \text{const}$$

$$\frac{k c}{k-1} (\rho^{k-1} - \rho_0^{k-1}) = g a \left(\frac{a}{r} - 1\right)$$

$$R \frac{dT}{dr} = -\frac{k-1}{k} \frac{g a^2}{r^2}$$

$$R(T - T_0) = \frac{k-1}{k} g a \left(\frac{a}{r} - 1\right)$$

$$\text{Grenzfall: } \frac{k-1}{k} \leq \frac{p_0}{\rho_0 g a}$$

$$\text{für } r \rightarrow \infty: \quad \rho^{k-1} = \rho_0^{k-1} - \frac{k-1}{k c} g a$$

$$= \rho_0^{k-1} \left[ 1 - \frac{k-1}{k p_0} \rho_0 g a \right]$$

nicht möglich!

$$\rho_0 = 0.0013$$

$$\mu_0 = 9.8 \times 13.6 \times 0.76$$

$$g = 9.8$$

$$a = 6366200$$

$$\frac{0.0013 \cdot 9.8 \cdot 6366200}{9.8 \cdot 13.6 \cdot 0.76}$$

$$r = \frac{a}{1 + \delta}$$

$$\text{Für } p = 0: \quad \frac{k c \rho_0^{k-1}}{k-1} = g a \left(1 - \frac{a}{r}\right)$$

$$\frac{1}{g a} \frac{k}{k-1} \frac{p_0}{\rho_0} = \frac{9.8 \cdot 13.6 \cdot 0.76}{0.0013 \cdot 9.8 \cdot 6366200}$$

$$\delta = \frac{76 \cdot 7}{126000} = \frac{1}{210}$$



Falls dagegen die Abnahme der Föhren wegen Centrifugalkraft  
derselbe wäre (mit wachsender Höhe) wie am Äquator

$$\frac{1}{\rho} \frac{\partial \rho}{\partial r} = - \frac{g a^2}{r^2} + \omega (r-a) = k c \rho^{k-2} \frac{\partial \rho}{\partial r}$$

$$\frac{k c}{k-1} (\rho^{k-1} - \rho_0^{k-1}) = \cancel{\frac{g a^2}{r^2}} + \frac{\omega}{2} (r-a)^2$$

$$= g a \left( \frac{a}{r} - 1 \right)$$

$$= (a-r) \left[ \frac{g a}{r} - \frac{\omega}{2} (a+r) \right]$$

$$\omega = \frac{\pi}{2} \frac{1}{365 \cdot 24 \cdot 60 \cdot 60}$$

$$\omega a = \frac{\pi}{2} \frac{6566 \cancel{000} \overset{2122}{10640}}{365 \cdot 24 \cdot 36 \cdot 6.73 \cdot 3} \overset{4064}{53}$$

$$= \frac{\cancel{38} \cdot \overset{27}{55}}{\underset{11}{22} \cdot \underset{8}{24}} = \frac{27}{88} = 0.40$$

Nacht sehr wenig aus.

Obiges nicht ganz genau; eigentlich:

$$\frac{1}{\rho} \frac{\partial \rho}{\partial r} = - \frac{g a^2}{r^2} + \omega r = k c \rho^{k-2} \frac{\partial \rho}{\partial r}$$

$$\frac{k c}{k-1} (\rho^{k-1} - \rho_0^{k-1}) = g a \left( \frac{a}{r} - 1 \right) + \frac{\omega}{2} (r^2 - a^2)$$



Damit  $p$  für  $r=0$   $p>0$  wird müsste sein:

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$$\frac{k-1}{k} \alpha g \frac{p_0}{p_0} = 1 \quad \frac{p_0}{p_0} = R T_0^{\text{bipr. temp}} = \frac{0.0013}{100} = 0.000013 = 1.3 \cdot 10^{-5}$$

$$\frac{k-1}{k} \alpha g = \frac{0.4}{1.4} \frac{6,366000}{4456} \cdot 987 = 17800,000$$

$$= 18 \cdot 10^6$$

$$\frac{1}{18} 10^{-6} = 5.5 \cdot 10^{-8}$$

Es müsste also die Temperatur  $\frac{1}{1200}$  der geübten h. g.

Dissipation of energy pro unit of time:

$$\Phi = -\frac{2}{3} \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + \mu \left\{ 2 \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 \right] + \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + \dots \right\}$$

$$\frac{\partial \rho u}{\partial x} + \dots = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = \frac{1}{\rho} \left[ \mu \frac{\partial \rho}{\partial x} + \mu \frac{\partial \rho}{\partial y} + \mu \frac{\partial \rho}{\partial z} \right]$$

$$\text{div}(\rho \mathbf{v}) = \frac{\partial(\rho \mathbf{v})}{\partial r} + 2 \frac{\rho \mathbf{v}}{r} = 0 = \rho \underbrace{\left[ \frac{d \mathbf{v}}{dr} + \frac{2 \mathbf{v}}{r} \right]}_{\text{div } \mathbf{v}} + \mathbf{v} \frac{d \rho}{dr} = 0$$

$$\frac{d \log \mathbf{v}}{dr} + \frac{2}{r} + \frac{d \log \rho}{dr} = 0$$

$$\text{div } \mathbf{v} = -\frac{\mathbf{v}}{\rho} \frac{d \rho}{dr}$$

$$\rho \mathbf{v} \cdot \mathbf{r} = \text{const}$$



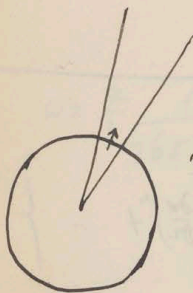
Falls man annimmt, dass der Unterschied zwischen aerostatischen und aerodynamischen Druck vernachlässigbar ist; dagegen der Temperatureinfluss der Bewegung zu berücksichtigen:

$$\left. \begin{aligned} \frac{1}{\rho} \frac{\partial p}{\partial r} &= \frac{g a^2}{r^2} \\ \frac{p}{\rho} &= R \theta \end{aligned} \right\}$$

Betreff  $\theta$  Annahme:

Es bewege sich von der Erdoberfläche aus ein Luftström mit der Schw.  $c$  aufwärts; welche Temp.verteilung entsteht?  
 $b$  = Radialgeschw.  $b_a = c$

Arbeit = Ausdehnungsarbeit + Reibungsarbeit + Schwerkraft



Falls keine Reibg wäre, so wäre die auch gleich

$$\rho \frac{g a^2}{r^2} dr = \rho \frac{\partial v}{\partial r} + c \frac{\partial \theta}{\partial r} + \mu \frac{\partial}{\partial r}$$

Reibarbeit:  $\rho dQ = \rho c_v d\theta + \rho A_p dr = 0$

pro Volum

$$\frac{d\theta}{dt} = - \frac{A_p dr}{c_v} = + \frac{\mu \dots}{c_v} dt$$

$$v = \frac{1}{\rho}$$

$$\frac{d\theta}{dp} = \frac{A_p}{c_v \rho^2} + \frac{A_p \dots}{c_v \rho} \frac{dt}{ds}$$

$$p = R \rho \theta$$

$$\frac{dp}{dt} = \frac{\partial p}{\partial r} b$$

$$\frac{R}{\rho} \left[ \frac{\partial \theta}{\partial r} \rho + \theta \frac{\partial \rho}{\partial r} \right] = \frac{g a^2}{r^2} \quad I).$$

$$\frac{\partial \theta}{\partial r} = \frac{A R \theta}{c \rho^2} \frac{\partial \rho}{\partial r} - \frac{4}{3} \frac{A}{c \rho} \left( \frac{b}{r^2} \right)^2 \left[ \frac{\partial \rho}{\partial r} + \frac{3 \rho}{r} \right]^2 \rho r^2$$

$$= \frac{A R \theta}{c \rho} \frac{\partial \rho}{\partial r} - \frac{4}{3} \frac{A \mu}{c} \frac{b}{r^2 \rho^4} \left[ \frac{\partial \rho}{\partial r} + \frac{3 \rho}{r} \right]^2 \quad II).$$



Work done by internal friction:

$$\Phi = -\frac{2}{3}\mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)^2 + \mu \left[ 2 \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 + \dots \right]$$

$$2 \left[ \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 \left[ \sin^4 \theta (\omega^4 \varphi + \sin^2 \varphi) + \omega^4 \theta \right] + 6 \frac{\phi^2}{r^2} + 4 \frac{\phi}{r} \left[ \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] \dots$$

$$+ 4 \left[ \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 \left[ \sin^4 \theta \cos^2 \theta + \sin^4 \theta \sin^2 \varphi \omega^2 \varphi \right] - \frac{2}{3} \left[ \frac{\partial \phi}{\partial r} + 2 \frac{\phi}{r} \right]^2$$

$$= 2 \left[ \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 \left[ \underbrace{\sin^4 \theta [\omega^4 \varphi + 2 \sin^2 \varphi \omega^2 \varphi + \sin^4 \varphi] + 2 \sin^4 \theta \cos^2 \theta + \omega^4 \theta}_{=1} \right] + \dots$$

$$= 2 \left[ \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2 + 6 \frac{\phi^2}{r^2} + 4 \frac{\phi}{r} \left[ \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right] - \frac{2}{3} \left[ \frac{\partial \phi}{\partial r} + 2 \frac{\phi}{r} \right]^2$$

$$= \left( \frac{\partial \phi}{\partial r} \right)^2 \left[ 2 - \frac{2}{3} \right] + \frac{\partial \phi}{\partial r} \cdot \frac{\phi}{r} \left[ -4 + 4 - \frac{8}{3} \right] + \frac{\phi^2}{r^2} \left[ 2 + 6 - 4 - \frac{8}{3} \right]$$

$$= \left( \frac{\partial \phi}{\partial r} \right)^2 \frac{4}{3} - \frac{\partial \phi}{\partial r} \cdot \frac{\phi}{r} \frac{8}{3} + \frac{\phi^2}{r^2} \frac{4}{3} = \frac{4}{3} \left[ \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right]^2$$

Equation of continuity:  $\rho \phi \cdot r^2 = \text{const} = \rho_0 \phi_0 a^2 = b$

$$\phi = \frac{b}{\rho r^2}$$

$$\frac{\partial \phi}{\partial r} = -\frac{b}{\rho^2 r^2} \frac{\partial \rho}{\partial r} - 2 \frac{b}{\rho r^3}$$

$$\Phi = -\frac{4}{3} \mu \left[ \frac{b}{\rho^2 r^2} \frac{\partial \rho}{\partial r} + \frac{2b}{\rho r^3} + \frac{b}{\rho r^3} \right]^2 = -\frac{4}{3} \left( \frac{b}{\rho^2 r^2} \right)^2 \mu \left[ \frac{\partial \rho}{\partial r} + 3 \frac{\rho}{r} \right]^2$$

$$\frac{\partial \rho}{\partial r} + \frac{3\rho}{r} = \frac{1}{r^3} \frac{\partial (\rho r^3)}{\partial r}$$



Transformation of Equations of Motion ~~for~~ for spherical symmetry:

Continuity:  $\rho b r^2 = \text{const.}$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = X - \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{\mu}{\rho} \nabla^2 \text{div } \delta + \frac{\mu}{\rho} \nabla^2 \tilde{u}$$

$$b \left( \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right) \sin^3 \theta \cos \varphi + \cancel{b \sin^3 \theta \cos \varphi \sin^2 \varphi} + r^{-2} \sin^2 \theta \cos \varphi$$

$$+ \frac{b^2}{r} \sin \theta \cos \varphi = b \left( \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right) \sin^3 \theta \cos \varphi + \frac{b^2}{r} \sin \theta \cos \varphi -$$

$$= b \frac{\partial \delta}{\partial r} \sin^3 \theta \cos \varphi$$

$$\text{div } \delta = -\frac{\delta}{\rho} \frac{\partial \rho}{\partial r}$$

$$\frac{\partial \text{div } \delta}{\partial x} = \frac{\partial \text{div } \delta}{\partial r} \sin^3 \theta \cos \varphi$$

$$= -\frac{\partial}{\partial r} \left( \frac{\delta}{\rho} \frac{\partial \rho}{\partial r} \right)$$

$$\frac{\partial^2 u}{\partial x^2} = \sin^3 \theta \cos \varphi \left[ \frac{\partial^2 \delta}{\partial r^2} - \frac{1}{r} \frac{\partial \delta}{\partial r} + \frac{\delta}{r^2} \right] \sin^3 \theta \cos \varphi + \frac{\partial \delta}{\partial r} \frac{1}{r} - \frac{\delta}{r^2}$$

$$\frac{\partial^2 u}{\partial y^2} = \sin^3 \theta \sin \varphi \left[ \frac{\partial^2 \delta}{\partial r^2} - \frac{1}{r} \frac{\partial \delta}{\partial r} + \frac{\delta}{r^2} \right] \sin^3 \theta \sin \varphi$$

$$\frac{\partial^2 u}{\partial z^2} = \cos \theta \left[ \frac{\partial^2 \delta}{\partial r^2} - \frac{1}{r} \frac{\partial \delta}{\partial r} + \frac{\delta}{r^2} \right] \sin^3 \theta \cos \theta \cos \varphi$$

$$\begin{aligned} \nabla^2 u &= \left[ \frac{\partial^2 \delta}{\partial r^2} - \frac{1}{r} \frac{\partial \delta}{\partial r} + \frac{\delta}{r^2} \right] \sin^3 \theta \cos \varphi + \frac{\sin^3 \theta \cos \varphi}{r} \left[ \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right] \\ &+ \frac{\sin^3 \theta \sin \varphi}{r} \left[ \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right] + \frac{\cos \theta}{r} \left[ \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right] \sin^3 \theta \cos \theta \cos \varphi \\ &= \frac{\partial^2 \delta}{\partial r^2} \sin^3 \theta \cos \varphi \end{aligned}$$

$$+ \left[ \frac{\sin^3 \theta \cos \varphi}{r} \left( \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right) + \frac{\sin^3 \theta \sin \varphi}{r} \left( \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right) - \sin^3 \theta \left( \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right) \cos \theta \cos \varphi \right] = \left[ \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right] \sin^3 \theta \cos \varphi$$



Equation of Motion:



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$$\delta \frac{\partial \delta}{\partial r} = R - \frac{1}{\rho} \frac{\partial \rho}{\partial r} - \frac{\mu}{3\rho} \frac{\partial}{\partial r} \left( \frac{\delta}{\rho} \frac{\partial \rho}{\partial r} \right) + \frac{\mu}{\rho} \left[ \frac{\partial^2 \delta}{\partial r^2} + \frac{2}{r} \frac{\partial \delta}{\partial r} \right]$$

$$+ \left[ \frac{\partial^2 \delta}{\partial r^2} + \frac{2}{r} \frac{\partial \delta}{\partial r} \right] \frac{\omega \theta \sin \varphi}{n} \quad \rho \delta r^2 = c$$

$$\delta = \frac{c}{\rho r^2}$$

$$\frac{\partial \delta}{\partial r} = -\frac{2c}{\rho r^3} - \frac{c}{\rho r^2} \frac{\partial \rho}{\partial r}$$

$$\frac{\partial^2 \delta}{\partial r^2} = + \frac{6c}{\rho r^4} \quad \frac{\partial}{\partial r} \left( \frac{\delta}{\rho} \frac{\partial \rho}{\partial r} \right) = \frac{\partial \delta}{\partial r} \frac{1}{\rho} \frac{\partial \rho}{\partial r} - \frac{\delta}{\rho^2} \left( \frac{\partial \rho}{\partial r} \right)^2 + \frac{\delta}{\rho} \frac{\partial^2 \rho}{\partial r^2} \dots$$

$$-\frac{2c^2}{\rho^2 r^5} = R - \frac{1}{\rho} \frac{\partial \rho}{\partial r} - \frac{\mu}{3\rho} \left( \frac{\partial}{\partial r} \left( \frac{\delta}{\rho} \frac{\partial \rho}{\partial r} \right) - \frac{c}{\rho^2 r^2} \left( \frac{\partial \rho}{\partial r} \right)^2 + \frac{c}{\rho^2 r^2} \frac{\partial^2 \rho}{\partial r^2} \right) + \frac{\mu}{\rho} \frac{\partial^2 \delta}{\partial r^2}$$

When  $\mu \rightarrow 0$ :  $\rho = \rho_0 r^k$   $\frac{\partial \rho}{\partial r} = k \rho_0 r^{k-1} \frac{\partial \rho}{\partial r}$

$$\frac{c^2}{\rho^2 r^5} \frac{\partial^2 \rho}{\partial r^2} = \frac{c^2}{\rho^2 r^5} \frac{d^2 \rho}{dr^2} = \frac{c^2}{\rho^2 r^5} \frac{d}{dr} \left( \frac{d\rho}{dr} \right) \quad \frac{1}{2} \frac{\partial^2 \delta}{\partial r^2} = - \frac{1}{2} k \rho^{k-2} \frac{\partial \rho}{\partial r} = - \frac{2k}{k-1} \frac{\partial}{\partial r} (\rho^{k-1})$$

$$\frac{1}{2} \frac{c^2}{\rho^2 r^5} = \frac{-2k}{k-1} \rho^{k-1} + \text{const} \quad \frac{c^2}{2} \left( \frac{1}{\rho^2 r^5} - \frac{1}{\rho^2 r^5} \right) = \frac{1}{k-1} (\rho^{k-1} - \rho^{k-1})$$

$$\frac{d^2 \rho}{dr^2} = \frac{d}{dr} \left( \frac{d\rho}{dr} \right) = \frac{d}{dr} (k \rho_0 r^{k-1}) = k(k-1) \rho_0 r^{k-2}$$

$$\sin^3 \theta \cos \varphi$$

$$\sin \theta \cos \varphi$$

$$\sin \theta \cos^2 \theta \cos \varphi$$

$$= \left[ \frac{\partial \delta}{\partial r} - \frac{\delta}{r} \right] \frac{1}{2} \left[ 2(\sin \theta \cos^2 \theta \cos^3 \varphi + \sin \theta \cos^2 \theta \sin^2 \varphi \cos \varphi) + \cos \varphi (\sin^3 \theta - \sin \theta \cos^2 \theta) + \frac{1}{\sin^2 \theta} (\sin^2 \theta \sin \varphi \cos \varphi + \sin^2 \theta (\cos^2 \varphi - \cos \varphi \sin \varphi)) \right] =$$



$$\nabla^2 u = \frac{\partial^2 u}{\partial r^2} + \frac{2}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 u}{\partial \varphi^2} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial u}{\partial \theta}$$

$$u = \frac{6 \cos \varphi \sin \theta}{r^2}$$

$$\nabla^2 u = \cos \varphi \sin \theta \left[ \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right] + \underbrace{\frac{\cos \varphi}{r^2 \sin^2 \theta} \frac{\partial^2}{\partial \varphi^2} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial}{\partial \theta}}_{\text{terms involving } \theta \text{ and } \varphi}$$

$$\frac{6}{r^2} \frac{\cos \varphi}{\sin \theta} [\cos^2 \theta - 1 - \sin^2 \theta] = -2 \frac{6}{r^2} \sin \theta \cos \varphi$$

$$\nabla^2 u = \cos \varphi \sin \theta \left[ \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} - \frac{2}{r^2} \right]$$

$$\frac{\partial^2}{\partial r^2} + 2 \frac{\partial}{\partial r} \left( \frac{6}{r} \right) = \frac{\partial}{\partial r} \left( \frac{\partial}{\partial r} + \frac{2}{r} \right) \frac{6}{r} = -\frac{6}{r^3} \frac{\partial}{\partial r}$$



Equation of Motion for spherical symmetry:

$$6 \frac{\partial \phi}{\partial r} = R - \frac{1}{\rho} \frac{\partial \rho}{\partial r} - \frac{\mu}{3\rho} \frac{\partial}{\partial r} \left( \frac{6}{\rho} \frac{\partial \rho}{\partial r} \right) + \frac{\mu}{\rho} \left[ \frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right]$$

$$\rho 6 r^2 = \text{const}$$

$$> - \frac{\partial}{\partial r} \left( \frac{6}{\rho} \frac{\partial \rho}{\partial r} \right)$$

$$6 \frac{\partial \phi}{\partial r} = R - \frac{1}{\rho} \frac{\partial \rho}{\partial r} - \frac{4\mu}{3\rho} \frac{\partial}{\partial r} \left( \frac{6}{\rho} \frac{\partial \rho}{\partial r} \right)$$

$$\frac{\partial \theta}{\partial r} + \frac{\theta}{\rho} \frac{\partial \rho}{\partial r} = \frac{g a^2}{R r^2}$$

$$\frac{\partial \theta}{\partial r} = \frac{A R}{c} \frac{\theta}{\rho} \frac{\partial \rho}{\partial r} - \frac{4}{3} \frac{A \mu}{c} \frac{b}{r^2 \rho^4} \left[ \frac{\partial \rho}{\partial r} + \frac{3\rho}{r} \right]^2$$

$$\frac{\theta}{\rho} \frac{\partial \rho}{\partial r} \left[ 1 + \frac{A R}{c} \right] = \frac{g a^2}{R r^2} + \frac{4}{3} \frac{A \mu}{c} \frac{b}{r^2 \rho^4} \left[ \frac{\partial \rho}{\partial r} + \frac{3\rho}{r} \right]^2$$

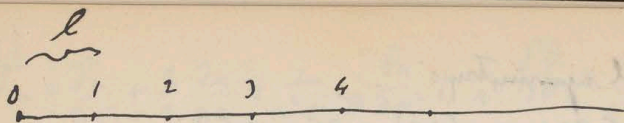
$$\theta = \frac{\rho}{c} \left[ \frac{\dots}{\frac{\partial \rho}{\partial r}} \right]$$

$$\frac{\partial \theta}{\partial r} = \frac{1}{c} \left[ \dots \right] + \frac{\rho}{c} \left[ \frac{\frac{\partial \rho}{\partial r}}{\left( \frac{\partial \rho}{\partial r} \right)} + \frac{\rho}{c} \frac{\partial}{\partial r} \right]$$

$$= \frac{g a^2}{R r^2} - \frac{1}{c} \left[ \dots \right]$$

$$\left[ \frac{g a^2}{R r^2} + \frac{4}{3} \frac{A \mu}{c} \frac{b}{r^2 \rho^4} \left[ \frac{\partial \rho}{\partial r} + \frac{3\rho}{r} \right]^2 \right] \left[ 2 + \rho \frac{\frac{\partial \rho}{\partial r}}{\left( \frac{\partial \rho}{\partial r} \right)} \right] + \frac{\rho}{\frac{\partial \rho}{\partial r}} \frac{\partial}{\partial r} \left[ \dots \right] - \frac{g a^2}{R r^2} = 0$$





A cord stretching out from 0 to  $\infty$ ; equal masses  $1, 2, \dots$  in equal distances; point 0 begins to move:  $\phi = a \sin t$ ; how will the motion of agitation ~~represents itself~~ spread out on the chord?

$\frac{d^2 \phi_0}{dt^2} = f(t)$  the law of force: ~~the~~ attracting forces between the ring points

$$\frac{d^2 \phi_1}{dt^2} = \cancel{f(t)} - f(x_1 - x_0) + f(x_2 - x_1)$$

$$= -k(\phi_0 - \phi_1) + k(\phi_1 - \phi_2) = k(2\phi_1 - \phi_0 - \phi_2)$$

$$\frac{d^2 \phi_2}{dt^2} = k(2\phi_2 - \phi_1 - \phi_3) = -k(\phi_1 - \phi_2) + k(\phi_2 - \phi_3)$$

$$\frac{d^2 \phi_3}{dt^2} = k(2\phi_3 - \phi_2 - \phi_4) = -k(\phi_2 - \phi_3) + k(\phi_3 - \phi_4)$$

$$\sum \frac{d^2 \phi_n}{dt^2} = k(\phi_1 - \phi_0)$$

$$\frac{d^2(\phi_0 - \phi_1)}{dt^2} = f + k(\phi_0 - \phi_1) - k(\phi_1 - \phi_2)$$

$$\frac{d^2}{dt^2}(\phi_1 - \phi_2) = k(-\phi_0 + 3\phi_1 - 3\phi_2 + \phi_3) = k[-(\phi_0 - \phi_1) + 2(\phi_1 - \phi_2) - (\phi_2 - \phi_3)]$$

$$\frac{d^4}{dt^4}(\phi_0 - \phi_1) = \frac{d^2 f}{dt^2} + k \frac{d^2}{dt^2}(\phi_0 - \phi_1) + k(\phi_0 - \phi_1) + 2 \frac{d^2}{dt^2}(\phi_1 - \phi_2) - 2k(\phi_0 - \phi_1) - k(\phi_2 - \phi_3)$$

$$2 \frac{d^2 \phi_2}{dt^2} - \frac{d^2 \phi_1}{dt^2} - \frac{d^2 \phi_3}{dt^2} = k(4\phi_2 - 2\phi_1 - 2\phi_3 - 2\phi_1 + \phi_0 + \phi_2 - 2\phi_3 + \phi_2 + \phi_4)$$

$$= k(\phi_0 - 4\phi_1 + 6\phi_2 - 4\phi_3 + \phi_4) = \frac{1}{k} \frac{d^4 \phi_2}{dt^4}$$



$$\frac{d}{dt} \left( \left( \frac{d\delta_n}{dt} \right)^2 \right) dt = ? = t \left( \frac{d\delta_n}{dt} \right)^2 - 2 \int t \frac{d\delta}{dt} \frac{d^2\delta}{dt^2} dt$$

$$= t \left( \frac{d\delta_n}{dt} \right)^2 - 2 t \delta \frac{d^2\delta}{dt^2} + 2 \int \delta \frac{\partial}{\partial t} \left( t \frac{d^2\delta}{dt^2} \right) dt$$

$$\delta_2 \frac{d^2\delta_2}{dt^2} = k (2\delta_2^2 - \delta_1\delta_2 - \delta_2\delta_3)$$

$$\leq \delta \frac{d^2\delta_n}{dt^2} = k (2\delta_2^2 - 2\delta_2\delta_{n-1})$$

$$\delta_3 \frac{d^2\delta_3}{dt^2} = k (2\delta_3^2 - \delta_2\delta_3 - \delta_3\delta_4)$$

$$\delta_3 \frac{d^2\delta_2}{dt^2} = k (2\delta_2\delta_3 - \delta_1\delta_3 - \delta_3^2)$$

$$\delta_2 \frac{d^2\delta_3}{dt^2} = k (2\delta_2\delta_3 - \delta_2^2 - \delta_2\delta_4)$$

$$\int \delta_3 \frac{d^2\delta_2}{dt^2} dt = \left. \delta_3 \frac{d\delta_2}{dt} \right| - \int \frac{d\delta_2}{dt} \frac{d\delta_3}{dt} dt = \left. \delta_3 \frac{d\delta_2}{dt} \right| - \left. \delta_2 \frac{d\delta_3}{dt} \right| + \int \delta_2 \frac{d^2\delta_3}{dt^2} dt$$

$$\leq \int \left( \frac{d\delta}{dt} \right)^2 dt$$

$$\frac{d^2\delta_n}{dt^2} = k (2\delta_n - \delta_{n-1} - \delta_{n+1})$$

$$\frac{d\delta_n}{dt} = k \int (2\delta_n - \delta_{n-1} - \delta_{n+1}) dt = k t (2\delta_n - \delta_{n-1} - \delta_{n+1}) - k \int t \left( 2 \frac{d\delta_n}{dt} - \dots \right)$$

$$= k t (2\delta_n - \delta_{n-1} - \delta_{n+1}) - k \frac{t^2}{2} \left( 2 \frac{d\delta_n}{dt} - \frac{d\delta_{n-1}}{dt} - \frac{d\delta_{n+1}}{dt} \right) +$$

$$+ \frac{k}{2} \int t^2 \left( 2 \frac{d^2\delta_n}{dt^2} - \dots \right) dt$$

$$k [ \delta_n - 4(\delta_{n-1} + \delta_{n+1}) + \delta_{n-2} + \delta_{n+2} ]$$

$$= k t (2\delta_n - \delta_{n-1} - \delta_{n+1}) \dots + k$$



$$\frac{d\delta_n}{dt} \frac{d^2\delta_n}{dt^2} = k \left[ 2\delta_n \frac{d\delta_n}{dt} - \delta_{n-1} \frac{d\delta_n}{dt} - \delta_{n+1} \frac{d\delta_n}{dt} \right]$$

$$\frac{1}{2} \frac{d}{dt} \left( \frac{d\delta_n}{dt} \right)^2 = k \left[ \frac{d}{dt} \left( \frac{\delta_n^2}{2} \right) - \frac{d\delta_n}{dt} (\delta_{n-1} + \delta_{n+1}) \right]$$

$$\frac{1}{2} \left( \frac{d\delta_n}{dt} \right)^2 = k \left[ \frac{\delta_n^2}{2} - \delta_n (\delta_{n-1} + \delta_{n+1}) + \int \delta_n \left( \frac{d\delta_{n-1}}{dt} + \frac{d\delta_{n+1}}{dt} \right) dt \right]$$

$$\leq \frac{1}{2} \left( \frac{d\delta_n}{dt} \right)^2 = k \leq \delta_n^2 - k \left[ \underbrace{\left\{ \begin{array}{l} \frac{d\delta_{n-1}}{dt} \delta_{n-2} + \frac{d\delta_{n+1}}{dt} \delta_n \\ \frac{d\delta_n}{dt} \delta_{n-1} + \frac{d\delta_n}{dt} \delta_{n+1} \\ \frac{d\delta_{n+1}}{dt} \delta_n + \frac{d\delta_{n+1}}{dt} \delta_{n+2} \\ \vdots \end{array} \right\}}_{= \sum \delta_n \delta_{n-1}} \right] dt$$

$$\leq \frac{1}{2} \left( \frac{d\delta_n}{dt} \right)^2 = k \left[ \leq \delta_n^2 - \leq \delta_n \delta_{n-1} \right] = L$$

$$\leq \delta_n \frac{d^2\delta_n}{dt^2} = 2k \left[ \leq \delta_n^2 - \leq \delta_n \delta_{n-1} \right]$$

$$\left\{ \begin{array}{l} \leq \left( \frac{d\delta_n}{dt} \right)^2 - \delta_n \frac{d^2\delta_n}{dt^2} = 0 \\ \frac{d\delta}{dt} \frac{d^2\delta}{dt^2} - \frac{d\delta}{dt} \frac{d^2\delta}{dt^2} \leq \delta \frac{d^3\delta}{dt^3} = 0 \end{array} \right. \quad \left\{ \begin{array}{l} \frac{\partial L}{\partial t} = \leq \frac{d\delta}{dt} \frac{d^2\delta}{dt^2} \\ = k \left[ \leq 2\delta_n \frac{d\delta_n}{dt} - \dots \right] \end{array} \right.$$

$$\begin{aligned} \frac{\partial L}{\partial x} &= 2k \left[ \leq \delta_{n+1}^2 - \leq \delta_{n+1} \delta_n - \leq \delta_n^2 + \delta_n \delta_{n-1} \right] \\ &= 2k (\delta_n^2 - \delta_n \delta_{n+1}) \end{aligned}$$



$$\frac{\delta L}{\delta t^2} = k \leq \underbrace{2\left(\frac{d\delta_n}{dt}\right)^2 + 2\delta_n\left(\frac{d\delta_n}{dt}\right)^2}_{-} - \frac{d\delta_{n-1}}{dt} \frac{d\delta_n}{dt} - \delta_{n-1} \frac{d\delta_n}{dt} \\ - \frac{d\delta_{n+1}}{dt} \frac{d\delta_n}{dt} - \delta_{n+1} \frac{d\delta_n}{dt}$$

$$= 8kL - \sum \frac{d\delta_n}{dt} \left( \frac{d\delta_{n-1}}{dt} + \frac{d\delta_{n+1}}{dt} \right) + \delta_{n-1}(2\delta_{n-2} - \delta_{n-3} - \delta_{n+1}) \\ + \delta_{n-2}(2\delta_{n-1} - \delta_{n-2} - \delta_n) + \delta_n(2\delta_{n-1} - \delta_{n+2} - \delta_n) \\ - \sum \delta_{n-1}(2\delta_n - \delta_{n-1} - \delta_{n+1}) + \delta_{n+1}(2\delta_n - \delta_{n-1} - \delta_{n+1}) \\ + \delta_n(2\delta_{n+1} - \delta_n - \delta_{n+2}) + \delta_{n+2}(2\delta_{n+1} - \delta_n - \delta_{n+2}) \\ + \delta_{n+1}(2\delta_{n+2} - \delta_{n+1} - \delta_{n+3}) + \delta_{n+3}(2\delta_{n+2} - \delta_{n+1} - \delta_{n+3}) \\ + \delta_{n+2}(2\delta_{n+3} - \delta_{n+2} - \delta_{n+4}) + \delta_{n+4}(\dots)$$

$$= \# 2 \leq \delta_n \delta_{n+1} - \delta_n^2 - \delta_n \delta_{n+2} + 2\delta_n \delta_{n+1} - \delta_n \delta_{n+2} - \delta_n^2$$



$$g_1 = f_1(t) = f_1(0) + t f_1'(0) + \frac{t^2}{2} f_1''(0) + \dots$$

$$= \cancel{g_1(0)} + t \cancel{\frac{dg_1(0)}{dt}} + \frac{t^2}{2} \frac{d^2 g_1(0)}{dt^2} + \frac{t^3}{3!} \frac{d^3 g_1(0)}{dt^3} + \frac{t^4}{4!} \frac{d^4 g_1(0)}{dt^4} + \dots$$

$$\frac{d^2 g_1(0)}{dt^2} = -k g_0(0)$$

$$\frac{d^3 g_1(0)}{dt^3} = -k \left( 2 \cancel{\frac{dg_1(0)}{dt}} - \cancel{\frac{dg_1(0)}{dt}} - \cancel{\frac{dg_1(0)}{dt}} \right) = -k \frac{dg_0(0)}{dt}$$

$$\frac{d^4 g_1(0)}{dt^4} = -k \left( 2 \frac{d^2 g_1(0)}{dt^2} - \frac{d^2 g_0(0)}{dt^2} - \frac{d^2 g_1(0)}{dt^2} \right) =$$

$$\begin{aligned} &= +2 k^2 g_0(0) + k \frac{d^2 g_0(0)}{dt^2} \\ d^5 &= 2 k \frac{d^2 g_0}{dt^2} + k \frac{d^4 g_0}{dt^4} \end{aligned}$$

$$d^6 = k \left[ 2 \frac{d^4 g_1}{dt^4} - \frac{d^4 g_0}{dt^4} - \frac{d^4 g_1}{dt^4} \right] = 4 k^3 g_0 + 2 k^2 \frac{d^2 g_0}{dt^2} - k \frac{d^4 g_0}{dt^4} - \cancel{k^3 g_0}$$

$$\frac{d^2 g_1(0)}{dt^2} = \cancel{0} = \frac{d^2 g_1(0)}{dt^2} \quad \text{etc.} \quad = 3 k^3 g_0 + 2 k^2 \frac{d^2 g_0}{dt^2} - k \frac{d^4 g_0}{dt^4}$$

$$d^7 = k \left[ 2 d^5 g_1 - d^5 g_0 - d^5 g_1 \right] = 4 k^3 \frac{dg_0}{dt} + 2 k^2 \frac{d^3 g_0}{dt^3} - k \frac{d^5 g_0}{dt^5} - k^3 \frac{dg_0}{dt}$$

$$= 3 k^3 \frac{dg_0}{dt} + 2 k^2 \frac{d^3 g_0}{dt^3} - k \frac{d^5 g_0}{dt^5}$$

$$d^8 = k \left[ 2 d^6 g_1 - d^6 g_0 - d^6 g_1 \right] = 6 k^4 g_0 + 4 k^3 \frac{d^2 g_0}{dt^2} - 2 k^2 \frac{d^4 g_0}{dt^4} + k^3 \frac{d^2 g_0}{dt^2} - k \frac{d^6 g_0}{dt^6}$$

$$= 6 k^4 g_0 + 5 k^3 \frac{d^2 g_0}{dt^2} - 2 k^2 \frac{d^4 g_0}{dt^4} - k \frac{d^6 g_0}{dt^6}$$



$$\frac{d^2 \delta_2}{dt^2}(0) = 0$$

$$\frac{d^3 \delta_2}{dt^3}(0) = k \left( 2 \frac{d\delta_1}{dt} - \frac{d\delta_1}{dt} - \frac{d\delta_1}{dt} \right) = 0$$

$$\frac{d^4 \delta_2}{dt^4}(0) = k \left( 2 \frac{d^2 \delta_1}{dt^2} - \frac{d^2 \delta_1}{dt^2} - \frac{d^2 \delta_1}{dt^2} \right) = +k^2 \delta_0(0)$$

$$\frac{d^5 \delta_2}{dt^5}(0) = k \left( 2 \frac{d^3 \delta_1}{dt^3} - \frac{d^3 \delta_1}{dt^3} - \frac{d^3 \delta_1}{dt^3} \right) = +k^2 \frac{d\delta_0}{dt}(0)$$

$$\frac{d^6 \delta_2}{dt^6}(0) = k \left( 2 \frac{d^4 \delta_1}{dt^4} - \frac{d^4 \delta_1}{dt^4} - \frac{d^4 \delta_1}{dt^4} \right) = 2k^3 \delta_0(0) - 2k^3 \delta_0(0) - k^2 \frac{d^2 \delta_0}{dt^2}(0)$$

$$d7 = k \left( 2 \frac{d^5 \delta_1}{dt^5} - \frac{d^5 \delta_1}{dt^5} - \frac{d^5 \delta_1}{dt^5} \right) = 2k^3 \frac{d\delta_0}{dt} - 2k^3 \frac{d\delta_0}{dt} - k^2 \frac{d^3 \delta_0}{dt^3}$$



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$$\frac{d^5 \delta_3}{dt^5} = 0$$

$$d^6 = \cancel{k} k d^4(2\delta_3 - \delta_2 - \delta_4) = -k^3 \delta_0$$

$$d^7 = k d^5(2\delta_3 - \delta_2 - \delta_4) = -k^4 \frac{d\delta_0}{dt}$$

$$d^8 = k d^6(2\delta_3 - \delta_2 - \delta_4) = -2k^4 \delta_0$$







Zwei Lösungen mit verschiedenen  $\mu$ :

$$(\mathbf{G}_1 \nabla) \mathbf{G}_1 = F - \frac{1}{\rho} \nabla p_1 + \frac{\mu_1}{\rho} \nabla \operatorname{div} \mathbf{G}_1 + \frac{\mu_1}{\rho} \nabla^2 \mathbf{G}_1 = \frac{1}{2} \nabla G_1^2 - \nabla G_1 \operatorname{div} \mathbf{G}_1$$

$$(\mathbf{G}_2 \nabla) \mathbf{G}_2 = F - \frac{1}{\rho} \nabla p_2 + \frac{\mu_2}{\rho} \nabla \operatorname{div} \mathbf{G}_2 + \frac{\mu_2}{\rho} \nabla^2 \mathbf{G}_2$$

$$\operatorname{curl} \nabla \mathbf{G}_1 \operatorname{curl} \mathbf{G}_1 = \frac{\mu_1}{\rho} \operatorname{curl} \nabla^2 \mathbf{G}_1$$

$$\operatorname{curl} \nabla \mathbf{G}_2 \operatorname{curl} \mathbf{G}_2 = \frac{\mu_2}{\rho} \operatorname{curl} \nabla^2 \mathbf{G}_2$$

$$\operatorname{curl} \nabla (\mathbf{G}_1 \operatorname{curl} \mathbf{G}_1 - \mathbf{G}_2 \operatorname{curl} \mathbf{G}_2) = \frac{1}{\rho} \operatorname{curl} \nabla^2 (\mu_1 \mathbf{G}_1 - \mu_2 \mathbf{G}_2)$$

$$\frac{1}{\rho} \frac{\partial p}{\partial x} = X$$

$$\frac{\partial p}{\partial x} = \frac{dp}{dr} \frac{\partial r}{\partial x} = \frac{dp}{dr} \cos \alpha$$

$$\frac{1}{\rho} \frac{\partial p}{\partial y} = Y$$

$$\frac{1}{\rho} \frac{dp}{dr} = X \cos \alpha + Y \sin \alpha + Z \sin \alpha = R$$

$$\frac{1}{\rho} \frac{\partial p}{\partial z} = Z$$



$$\frac{\partial}{\partial r}(r^2 p) = -g \frac{a^2}{r^2} p$$

$$p = c r^k$$

$$\frac{\partial}{\partial r}(r^2 p) + 2 p r = -g \frac{a^2}{r^2} p$$

$$k r^{k-1} \frac{\partial}{\partial r} + 2 p r = -g \frac{a^2}{c r^2} p$$

$$\frac{d}{dr}(r^2 p^k) = -g \frac{a^2}{c} p$$

$$r^{\frac{2}{k}} d(r^2 p^k) = -g \frac{a^2}{c} (p r^{\frac{2}{k}}) dr$$

$$\frac{d(p^k r^{\frac{2}{k}})}{p r^{\frac{2}{k}}} = -g \frac{a^2}{c} r^{-\frac{2}{k}} dr$$

$$k r^{\frac{k-1}{k}} \frac{dr}{r} = -g \frac{a^2}{c} r^{-\frac{2}{k}} dr$$

$$k \frac{1}{2} dr =$$

$$k \frac{r^{k-1}}{k-1} = -g \frac{a^2}{c} r^{-\frac{2}{k}+1}$$

$$p^{k-1} r^{\frac{2(k-1)}{k}} = -\frac{k-1}{k-2} g \frac{a^2}{c} r^{1-\frac{2}{k}} + \text{Const} = p^{k-1} r^{2-\frac{2}{k}}$$

$$p^{k-1} = A r^{\frac{2(1-k)}{k}} - \frac{k-1}{k-2} g \frac{a^2}{c} \frac{1}{r}$$

$$p^{k-1} = A a^{\frac{2(1-k)}{k}} - \frac{k-1}{k-2} g \frac{a^2}{c}$$

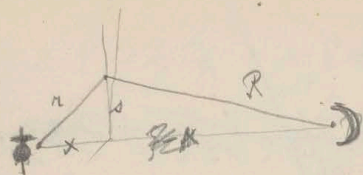
$$p^{k-1} a^{\frac{2(k-1)}{k}} = -\frac{k-1}{k-2} g \frac{a^2}{c} a^{3-\frac{2}{k}} + A$$

$$\frac{\partial}{\partial r}(r^2 p) + \frac{2}{r} = -g \frac{a^2}{r^2} p$$

$$p r^{\frac{2}{k}} = 2$$

$$p^k r^2 = 2^k$$





$$\frac{1}{\rho} \frac{\partial p}{\partial x} = X$$

$$\frac{1}{\rho} \frac{\partial p}{\partial y} = Y$$

$$\frac{1}{\rho} \frac{\partial p}{\partial z} = Z$$

$$\frac{\partial p}{\partial y} = \frac{\partial p}{\partial s} \sin \mu$$

$$\frac{\partial p}{\partial z} = -\frac{\partial p}{\partial s} \cos \mu$$

$$\left. \begin{aligned} \frac{1}{\rho} \frac{\partial p}{\partial x} &= X \\ \frac{1}{\rho} \frac{\partial p}{\partial s} &= S' \end{aligned} \right\} \text{ For rotational symmetry}$$

$$\left. \begin{aligned} \frac{1}{\rho} \frac{\partial p}{\partial x} &= -\frac{g a^2}{n^2} \frac{x}{R} + \frac{g A^2}{R^2} \frac{-x}{R} \\ \frac{1}{\rho} \frac{\partial p}{\partial s} &= -\frac{g a^2}{n^2} \frac{s}{R} - \frac{g A^2}{R^2} \frac{s}{R} \end{aligned} \right\} \begin{aligned} &= -\frac{\partial U}{\partial x} = +\frac{\partial P}{\partial x} \\ &= -\frac{\partial U}{\partial s} = +\frac{\partial P}{\partial s} \end{aligned}$$

$$P + U = \text{const}$$

$$P = \int \frac{1}{\rho} \nabla p = \frac{c k}{k-1} \rho^{k-2} dp = \frac{c k}{k-1} \rho^{k-1}$$

$$\left[ \frac{c k}{k-1} \rho^{k-1} = \frac{g a^2}{n^2} + \frac{g A^2}{R} \text{ const} \right]$$

$$\frac{c k}{k-1} (\rho_0^{k-1} - \rho^{k-1}) = g a - \frac{g a^2}{n^2} - \frac{g A^2}{R}$$

$$\text{Für (Oberfl.) } \frac{c k}{k-1} (\rho_0^{k-1} - \rho^{k-1}) = g a - g A$$

$$g : G = \frac{m}{a^2} : \frac{M}{A^2} \quad G = g \frac{M}{m} \frac{a^2}{A^2} \quad \parallel \quad = g a \left[ 1 - \frac{M a}{m A} \right]$$

$$\rho_0^{k-1} \frac{c k}{k-1} = g a - \frac{g A^2}{R}$$

$$\frac{c k}{k-1} \frac{\partial \alpha}{\partial \theta} (\theta_0 - \theta) = \frac{g a^2}{n^2} \text{ mit } 300 \frac{A}{R}$$

$$-\frac{d\theta}{dx} = \frac{g a^2}{n^2} \frac{k-1}{k} R \frac{a^2}{k^2} 300000 \frac{A}{R}$$





Sage bei ~~stetig~~ <sup>isothermen</sup> Gleichgewicht:

$$p = c \rho$$

$$\frac{1}{\rho} \frac{dp}{dr} = g \frac{a^2}{r^2}$$

$$c \log p = g \frac{a^2}{r} + \text{const}$$

$$c \log p_0 = g a + \text{const}$$

$$c \log \frac{p_0}{p} = g a - g \frac{a^2}{r}$$

Es ist  $r \rightarrow \infty$  für

$$r = \infty:$$

$$c \log \frac{p_0}{p_\infty} = g a$$

$$\frac{p_0}{p_\infty} = e^{\frac{g a}{c}}$$

$$p_\infty = p_0 e^{-\frac{g a}{c}}$$

$$c = \frac{p_0}{\rho_0}$$

$$\frac{g a}{c} = \frac{9.8 \cdot 636600 \cdot 0.0013}{9.8 \cdot 1250} = 0.00880$$

Lösung ganz vernünftig kleine Dichte

Die Lösung entspricht mit beliebigem  $p_0$  wenn  $\theta$  nicht gegeben ist.

Sage wie Densität:  $r = \infty$   
 $p = 0$ :  
unmöglich

bei zwei Körpern  $\theta$  und  $\phi$

$$c \log p = g \frac{a^2}{r} + \frac{g A^2}{R} + \text{const}$$

$$c \log p_0 = g a + \text{const}$$

$$c \log \frac{p_0}{p_\phi} = g a - g \frac{a^2}{r} - \frac{g A^2}{R}$$

$$c \log \frac{p_0}{p_\phi} = g a - g A$$

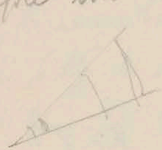
$$\frac{p_0}{p_\phi} = e^{\frac{g a - g A}{c}}$$

$$p_\phi = p_0 e^{-\frac{g a - g A}{c}}$$

Dichte auch sehr klein sein



No work is done by internal friction — when gas flows out from a source uniformly in all directions (spherical symmetry) — only if every volume element keeps its shape (but ~~change~~ changing size) therefore the only possible motion without loss of energy:



$$V = r^3 = R^3$$

$$\rho = \frac{\text{const}}{R^3}$$

$$\rho_0 = \frac{\text{const}}{a^3}$$

$$\rho = \rho_0 \frac{a^3}{r^3}$$

If gas is flowing

towards the center:  $\frac{1}{\rho} \frac{d\rho}{dr} = -\frac{g a^2}{r^2}$

$$\frac{d\rho}{dr} = -\frac{g a^2}{r^2} \rho_0 \frac{a^3}{r^3} = -g \frac{a^5 \rho_0}{r^5}$$

$$\rho = \frac{g a^5 \rho_0}{4 r^4} + \text{const}$$

$$\rho_0 = \frac{g a \rho_0}{4} + \text{const}$$

$$\rho - \rho_0 = \frac{g a \rho_0}{4} \left( \frac{a^4}{r^4} - 1 \right)$$

$$P = c\theta = \frac{g a^2}{4 r} + \frac{\rho_0 - \frac{g a \rho_0}{4}}{\rho_0 \frac{a^3}{r^3}} < 1$$

$$\rho_0 = 98. \quad \frac{g a \rho_0}{4} = \frac{606 \text{ mm. Hg.} \cdot 0.0013}{4}$$

Przyjmując że przed powstaniem wznosi się o powierzchni płaskiej z prędkością  $u_0$  do góry; jakie o nim będzie rozszerzenie prędkości, ciśnienia, gęstości i temperatury?

I. ~~Względnie~~ Względnie tylko prace wykonana przez rozszerzenie się gazu:

będzie "convector equilibrium"

$$p = c \rho^k \quad \frac{c k}{k-1} (\rho_0^{k-1} - \rho^{k-1}) = g a - \frac{g a^2}{r}$$

II. Względnie sprężenie tego gazu przez przewodzenie ciepła przez gaz:

$$\frac{1}{\rho} \frac{d\rho}{dr} = -\frac{g a^2}{r^2}$$

$$dV = \frac{c d\theta}{r} + A_2 \rho \frac{d(\frac{1}{\rho})}{dr} = \dots \propto \alpha$$

$$\text{III)} \quad \frac{\rho}{\rho_0} = \frac{\theta}{\theta_0}$$

$$\rho = \frac{\rho_0}{\rho_0 \theta_0} \rho \theta$$

$$2) \quad \rho \frac{d\theta}{dr} = -\frac{g a^2}{r^2} - \frac{1}{\rho} \frac{d\rho}{dr} \left[ -\frac{4\mu}{3\rho} \frac{d}{dr} \left( \frac{\rho}{\rho} \frac{d\rho}{dr} \right) \right]$$

$$3) \quad \rho \theta r^2 = \text{const} = \rho_0 \theta_0 a^2 = b$$

$$4) \quad \rho \theta r^2 \left[ c \frac{d\theta}{dr} + A_2 \rho \frac{d(\frac{1}{\rho})}{dr} \right] + \frac{d}{dr} \left( k r^2 \frac{d\theta}{dr} \right) = 0$$

$$k = \gamma \theta$$

$$\frac{d\rho}{dr} \theta r^2 + \frac{d\theta}{dr} \rho r^2 + 2 r \rho \theta = 0$$

$$\frac{\rho}{\rho} \frac{d\rho}{dr} + \frac{d\theta}{dr} + 2 \frac{\theta}{r} = 0$$

$$2) \quad \rho \theta a^2 \frac{d\theta}{dr} = -g a^2 \rho - r^2 \frac{d\rho}{dr} - \frac{4\mu}{3} r^2 \frac{d}{dr} \left( \frac{\rho}{\rho} \frac{d\rho}{dr} \right)$$

$$\theta = \frac{\rho_0 \theta_0 a^2}{\rho r^2} = \frac{b}{\rho r^2}$$

$$\frac{d\theta}{dr} = -\frac{b}{\rho r^3} \frac{d\rho}{dr} - \frac{2b}{\rho r^3}$$

$$\frac{\theta}{\rho} \frac{d\rho}{dr} = \frac{b}{\rho r^2} \frac{d\rho}{dr}$$

$$\frac{d\theta}{dr} =$$

$$2, 3) \quad \left[ -\frac{b^2}{\rho^2 r^2} \frac{d\rho}{dr} - \frac{2b^2}{\rho r^3} \right] = -g a^2 \rho - r^2 \frac{d\rho}{dr} \left[ \frac{4\mu}{3} r^2 \frac{d}{dr} \left[ \frac{b}{\rho r^2} \frac{d\rho}{dr} \right] \right]$$

$$\alpha = \frac{98.136.076}{0.0013.0280} = \frac{980}{3.6} = 270$$



$$bc \frac{d\theta}{dr} + bA \alpha \frac{\theta}{\rho^2} \frac{dp}{dr} + \frac{d}{dr} \left( \gamma \theta \frac{d\theta}{dr} r^2 \right) = 0$$

$$\left[ \frac{b^2}{\rho^2 r} \frac{dp}{dr} + \frac{2b^2}{\rho r^2} \right] = g a^2 \rho + r^2 \alpha \frac{d(\rho \theta)}{dr}$$

ještě nejto rovnice  
pomineme  $\left( \frac{dp}{dr} \right)$  budeme mít

$$g a^2 \rho + r^2 \alpha \rho \frac{d\theta}{dr} + r^2 \alpha \theta \frac{dp}{dr} = 0$$

$$\frac{1}{\rho} \frac{dp}{dr} = - \frac{1}{r^2 \alpha \theta} \left[ g a^2 + r^2 \alpha \frac{d\theta}{dr} \right]$$

$$g a^2 + r^2 \alpha \frac{d\theta}{dr} + r^2 \alpha \theta \frac{1}{\rho} \frac{dp}{dr} = 0 \quad | \cdot \theta$$

$$\frac{d\theta}{dr} g a^2 + \frac{d}{dr} \left( r^2 \alpha \frac{d\theta}{dr} \right) + \alpha \frac{d}{dr} \left( \frac{\theta^2 r^2}{\rho} \frac{dp}{dr} \right) = 0$$

$$r^2 \frac{d}{dr} \left( \frac{1}{r} \right) = - \frac{d}{dr} \left( \frac{1}{r} \right) \quad \frac{1}{r} = \xi$$

2

1

$$bc \frac{d\theta}{d\xi} - bA \alpha \frac{\theta}{\rho^2} \frac{dp}{d\xi} + \frac{d}{d\xi} \left( \frac{d(\theta^2)}{d\xi} \right) = 0$$

Cy převodník vytváří nové spřodávající znaménko rovnice?

$$c = \frac{\rho_0}{\rho_0 k}$$

Pro výpočet bytby:

$$\frac{ck}{k-1} (\rho_0^{k-1} - \rho^{k-1}) = g a^2 \left( 1 - \frac{a}{r} \right) = \dots$$

$$\Delta (\theta_0 - \theta) = \frac{k-1}{k} g a^2 \left( 1 - \frac{a}{r} \right)$$

$$\theta = \theta_0 - \frac{k-1}{k} g a^2 \left( 1 - \frac{a}{r} \right)$$

$$r^2 \frac{d\theta}{dr} = - \frac{k-1}{k} g a^2 \frac{1}{r} = B = \frac{98.04 \cdot [6366000]^{2/4}}{14.270}$$

$$\gamma = \frac{0.00006}{280}$$

$$bc B - \dots + \gamma B^2 = 0$$

$$\frac{\gamma B}{bc}$$

$$\frac{98.04 \cdot 0.00006 \cdot 2^{1/4}}{14.270 \cdot 0.0013 \cdot 6.280 \cdot 60}$$

Spíše ještě 60 vlnkové  $\frac{1}{5000} \text{ cm}!$

Prz. prowadzenie czołowe i zarysowywać kształt drzewa le. mierz długość toru

$$1). \rho b r^2 = \text{const} = \rho_0 b_0 r^2 = b$$

$$2). r = \int_{\theta_0}^{\theta} \rho d\theta$$

$$= \frac{b}{\rho^2 r^2} \frac{d\rho}{dr} \parallel \alpha = \frac{0.76 \cdot 98 \cdot 136}{0.0013 \cdot 280} = \frac{98}{0.36} = 270$$

$$3). 0 = -\frac{g a^2}{r^2} - \frac{1}{\rho} \frac{d\rho}{dr} - \frac{4\mu}{3\rho} \frac{d}{dr} \left( \frac{b}{\rho} \frac{d\rho}{dr} \right)$$

$$4). \rho b r^2 \left[ c \frac{d\theta}{dr} + A \rho \frac{d(\frac{1}{\rho})}{dr} \right] = \frac{4}{3} \left( \frac{b}{\rho^2 r^2} \right)^2 \mu \left[ \frac{d\rho}{dr} + \frac{3\rho}{r} \right]^2$$

$$3). \frac{g a^2}{r^2} + \alpha \frac{1}{\rho} \frac{d[\rho \theta]}{dr} - \frac{4\mu}{3\rho} \frac{d}{dr} \left[ \frac{b}{\rho^2 r^2} \frac{d\rho}{dr} \right] = 0$$

$$4). b c \frac{d\theta}{dr} = A b \alpha \frac{\theta}{\rho} \frac{d\rho}{dr} = \frac{4\mu}{3} \left( \frac{b}{\rho^2 r^2} \right)^2 \left( \frac{d\rho}{dr} + \frac{3\rho}{r} \right)^2$$

$$\frac{1}{\rho^2 r^2} \left( \frac{d\rho}{dr} + \frac{3\rho}{r} \right) = \frac{d(\rho r^3)}{\rho^2 r^5} = \left| \frac{1}{\rho^2 r^2} \frac{d}{dr} \log(\rho r^3) \right| = - \mu \frac{d}{dr} \left( \frac{1}{\rho r^3} \right)$$

$$\mu = \rho \theta$$

$$3). \frac{g a^2}{r^2} + \frac{\alpha}{\rho} \frac{d(\rho \theta)}{dr} - \frac{4\mu}{3\rho} \frac{d}{dr} \left[ \frac{b}{\rho^2 r^2} \frac{d\rho}{dr} \right] = 0$$

$$4). c \frac{d\theta}{dr} = A \alpha \frac{\theta}{\rho} \frac{d\rho}{dr} - \frac{4\mu}{3} \frac{b \theta}{\rho^4 r^4} \left[ \frac{d\rho}{dr} + \frac{3\rho}{r} \right]^2 = 0$$

$$4). : c \frac{d\theta}{dr} \frac{1}{\theta} = A \alpha \frac{d\rho}{dr} \frac{1}{\rho} + \frac{4\mu b}{3\rho^4 r^4} \left[ \frac{d\rho}{dr} + \frac{3\rho}{r} \right]^2$$

$$c \log \theta + \text{const} = \int \dots \dots \uparrow dr$$



$$c \log \theta + \omega r^2 = A \alpha \log \rho + \frac{4\mu b}{3} \int \left[ \frac{1}{\rho^2 n^2} \left( \frac{d\rho}{dr} + \frac{3\rho}{r} \right)^2 \right] dr$$

Zusatzbedingung (3):

$$\frac{\rho a^2}{r^2} + \frac{\alpha}{\rho} \frac{d}{dr}(\rho \theta) = 0 = \frac{\rho a^2}{r^2} + \alpha \frac{d\theta}{dr} + \alpha \frac{\theta}{\rho} \frac{d\rho}{dr}$$

$$\text{const } \theta^c = \rho^{\alpha A} \frac{4\mu b}{3} \int \dots \quad \parallel \quad \left( \frac{\theta}{\theta_0} \right)^c = \left( \frac{\rho}{\rho_0} \right)^{\alpha A}$$

$$\theta = \frac{r}{\alpha \rho}$$

$$\text{const } \rho^c \rho^{-c} = \rho^{\alpha A}$$

$$\text{const } \rho^c = \rho^{\alpha A + c}$$

$$\text{const } \rho = \rho$$

$$\begin{aligned} &= 1.5 \\ &\frac{\alpha A}{c} = 0.5 \\ &\frac{\alpha A}{c} - 1 = -\frac{1}{2} \end{aligned}$$

$$\text{const } \theta = \rho^{\frac{\alpha A}{c}} \frac{4\mu b}{3c} \int \dots$$

$$0 = \frac{\rho a^2}{r^2} + \left\{ \frac{A^2}{c} \frac{1}{\rho} \frac{d\rho}{dr} + \frac{4\mu b \alpha}{3\rho^2 n^2 c} \left[ \frac{d\rho}{dr} + \frac{3\rho}{r} \right]^2 + \frac{\alpha}{\rho} \frac{d\rho}{dr} \right\} \rho^{\frac{\alpha A}{c}} e^{\frac{4\mu b}{3c} \int \left( \frac{d\rho}{dr} + \frac{3\rho}{r} \right)^2 \frac{1}{\rho^2 n^2} dr}$$

$$= \frac{\rho a^2}{r^2} + \rho^{\frac{\alpha A}{c} - 1} \frac{d\rho}{dr} \left( \frac{A^2}{c} + 1 \right) \frac{4\mu b}{3c} \int \dots + \frac{4\mu b \alpha}{3c} \left( \frac{d\rho}{dr} + \frac{3\rho}{r} \right)^2 \frac{1}{\rho^2 n^2} e^{\frac{4\mu b}{3c} \int \dots}$$

$$\frac{\rho a^2}{r^2} e^{-\frac{4\mu b}{3c} \int \dots} + \left\{ \rho^{\frac{\alpha A}{c} - 1} \frac{d\rho}{dr} \left( \frac{A^2}{c} + 1 \right) + \frac{4\mu b \alpha}{3c} n^2 \left( \frac{d\rho}{dr} + \frac{3\rho}{r} \right)^2 \right\} = 0$$

$$-\frac{\rho a^2}{r^2} \frac{4\mu b}{3c} \left( \frac{d\rho}{dr} + \frac{3\rho}{r} \right)^2 \frac{1}{\rho^2 n^2} e^{-\frac{4\mu b}{3c} \int \dots} + \frac{d\rho}{dr} = 0$$

$$\frac{4\mu b}{3c} \left[ \frac{d\rho}{dr} + \frac{3\rho}{r} \right]^2 \frac{1}{\rho^2 n^2} e^{\frac{4\mu b}{3c} \int \dots} + \frac{d\rho}{dr} = 0$$

$$\int \left[ r \frac{d}{dr} \left( \frac{1}{r^3 \rho} \right) \right]^2 dr = f(r) \log r$$

$$\frac{1}{r^3 \rho} = \left[ f' \log r + \frac{f}{r} \right]^{\frac{1}{2}} = \frac{dp}{dr} + \frac{3\rho}{2} = \frac{dk}{\sqrt{r}} + \frac{r}{k} \frac{d}{dr}$$

$$\frac{1}{r^3 \rho} = \int \frac{1}{r} \left[ \right]^{\frac{1}{2}} dr$$

$$\frac{d}{dr} \left( \frac{1}{r^3 \rho} \right) = k \left( \frac{1}{r^2} \right) \frac{d}{dr}$$

$$\frac{1}{r^3 \rho} = k r^{\frac{5}{2}} + k'$$

$$\rho = \frac{1}{k r^{\frac{5}{2}} + k'}$$

$$\int = f(\log r)$$

$$\frac{1}{r^3 \rho} = \left[ \frac{f'(\log r)}{r} \right]^{\frac{1}{2}}$$

$$\int \dots dr = k^2 \log r$$

$$\frac{1}{r^3 \rho} = \left[ r f'(\log r) \right]^{\frac{1}{2}} dr$$

$$-k \log r = r^{-m}$$

$$M e^{-m \log r}$$

$$M r^{-m} + r^2 V r^{-\frac{9}{4}} r^{-\frac{11}{2}} + P r^2 r^{-1} = 0$$

$$\frac{d}{dr} \left( \frac{1}{r^3 \rho} \right) = f$$

$$\frac{d}{dr} \left( \frac{1}{r^3 \rho} \right) = f$$

$$\frac{d}{dr} \left( \frac{1}{r^3 \rho} \right) = \frac{f}{r}$$

$$\frac{1}{r^3 \rho} = \int f dr$$

$$\rho = \frac{1}{r^3 \int f dr}$$

$$M e^{-\int f r^2 dr}$$

$$\rho r^3 = z$$

$$\rho = r^3 z$$

$$\frac{dp}{dr} = 3 r^2 z + r^3 \frac{dz}{dr}$$

$$\frac{dp}{dr} = \frac{3}{r^4} \int f dr +$$



$$e^{-\int \left[ r \frac{d}{dr} \left( \frac{1}{\rho r^3} \right) \right]^2 dr} = F$$

$$\frac{d}{dr} \left( \frac{1}{\rho r^3} \right) = \frac{1}{r} \sqrt{\frac{F'}{F}}$$

$$-\int \left[ r \frac{d}{dr} \left( \frac{1}{\rho r^3} \right) \right]^2 dr = \ln F$$

$$\frac{1}{\rho r^3} = \int \frac{dr}{r} \sqrt{\frac{F'}{F}}$$

$$\left[ r \frac{d}{dr} \left( \frac{1}{\rho r^3} \right) \right]^2 = \frac{F'}{F}$$

Jak staže  $r$  bliskai  $a$   $\frac{-1}{e} = 1$

$$g a^2 + r^2 \rho \frac{dp}{dr} \left( \frac{A\alpha}{c} + 1 \right) \alpha + \frac{4\pi b \alpha}{3c} \frac{1}{a^2} \left( \frac{1}{\rho^2} \frac{d\rho}{dr} + \frac{3}{\rho a} \right)^2 = 0$$

$$\frac{1}{a^2} \left[ \frac{d}{dr} \left( \frac{1}{\rho} \right) \right]^2$$

$$\frac{4}{3} \frac{\pi b \alpha^2}{c} \frac{1}{a^2} \rho \left( \frac{d\rho}{dr} \right)^2$$

Zauważając wpływ termu  $r^4$  a modyfikujemy  $r^3$ :

$$\left( \frac{\theta}{\theta_0} \right)^{\frac{1}{\alpha}} = \left( \frac{\rho}{\rho_0} \right)^{\frac{\alpha A}{c}}$$

$$\theta = \theta_0 \left( \frac{\rho}{\rho_0} \right)^{\frac{\alpha A}{c}} = \beta \rho^{\frac{\alpha A}{c}}$$

$$3). \quad g a^2 + \frac{\alpha}{\rho} \beta \left( \frac{\alpha A}{c} + 1 \right) \rho^{\frac{\alpha A}{c} - 1} \frac{d\rho}{dr} - \frac{4\pi}{3} \beta \rho^{\frac{\alpha A}{c} - 1} \frac{d}{dr} \left[ \frac{b}{\rho^2 r} \frac{d\rho}{dr} \right] = 0$$

$$\frac{\alpha A}{c} = k^2$$

$$\frac{33 \cdot 0.78}{365} \cdot \frac{43}{24 \cdot 60 \cdot 60} \cdot \frac{42}{5} = 0.03$$

$$\frac{4}{120} = 0.03$$

2 g/mol per 1 min.

$$\begin{aligned} 1). & \quad \mu = \alpha \theta \rho \\ 2). & \quad 6 \frac{d\delta}{dx} = -\frac{g a^2}{x^2} - \frac{1}{\rho} \frac{d\mu}{dx} + \frac{4}{3} \frac{\mu}{\rho} \left( \frac{d\delta}{dx} + \frac{d\delta}{dy} + \frac{d\delta}{dz} \right) \\ 3). & \quad \left[ c \frac{d\theta}{dx} + A \mu \frac{d(\frac{1}{\rho})}{dx} \right] = \mu \left[ \left( \frac{du}{dx} \right)^2 + \left( \frac{du}{dy} \right)^2 + \left( \frac{du}{dz} \right)^2 \right] + \frac{1}{3} \mu \left( \frac{du}{dx} \right)^2 \\ 4). & \quad \rho \delta = \text{const} = b \end{aligned}$$

$$\delta = f(x)$$

$$\frac{1}{\rho} = \frac{\alpha \theta}{\mu}$$

$$1). \quad \mu = \alpha \theta \rho$$

$$2). \quad 0 = -\frac{g a^2}{x^2} - \frac{1}{\rho} \frac{d\mu}{dx} + \frac{4}{3} \frac{\mu}{\rho} \frac{d^2 \delta}{dx^2}$$

$$3). \quad \left[ c \frac{d\theta}{dx} + A \mu \frac{d(\frac{1}{\rho})}{dx} \right] = \frac{4}{3} \mu \left( \frac{d\delta}{dx} \right)^2$$

$$4). \quad \rho \delta = b$$

$$\frac{d}{dx} \left( -\frac{1}{\rho} \frac{d\mu}{dx} \right) =$$

$$\frac{2}{\rho^3} \left( \frac{d\mu}{dx} \right)^2 - \frac{1}{\rho^2} \frac{d^2 \mu}{dx^2}$$

$$3). \quad \left[ \frac{c}{A} \frac{d\theta}{dx} + \frac{\alpha \theta}{\rho} \frac{d\rho}{dx} \right] = \frac{4}{3} \mu \theta \frac{b^2}{\rho^4} \left( \frac{d\rho}{dx} \right)^2$$

$$2). \quad 0 = -\frac{g a^2}{x^2} - \frac{\alpha}{\rho} \left( \theta \frac{d\rho}{dx} + \rho \frac{d\theta}{dx} \right) + \frac{4}{3} \frac{\mu \theta}{\rho} \frac{d^2}{dx^2} \left( \frac{1}{\rho} \right)$$

$$-\frac{g a^2}{x^2} \frac{d\rho}{dx} = \frac{\alpha \theta}{\rho} \frac{d\rho}{dx}$$



$$0 = -g \frac{a^2}{x^2} - \frac{c}{A} \frac{d\theta}{dx} - \alpha \frac{d\theta}{dx} + \gamma \theta \left[ \frac{b}{p} \frac{4}{3} \frac{d^2}{dx^2} \left( \frac{1}{\theta} \right) + \frac{4}{3} \frac{b^4}{p^2} \left( \frac{d\theta}{dx} \right)^2 \right]$$

bei vollständiger Vernachlässigung von  $\gamma$

$$\text{const} = \frac{g a^2}{x} - \left( \frac{c}{A} + \alpha \right) \theta + \int dx \gamma \theta \left[ \right]$$

$$\frac{1}{p} = \frac{b}{\theta} \quad p = \frac{\alpha b \theta}{\delta}$$

$$2). 0 = -g \frac{a^2}{x^2} - \frac{\delta}{b} \frac{d}{dx} \left( \frac{\alpha \theta b}{\delta} \right) - \gamma \frac{\theta \delta}{b} \frac{d^2 \delta}{dx^2}$$

$$3). \frac{c}{A} \frac{d\theta}{dx} + \frac{\alpha \theta b}{\delta b} \frac{d\delta}{dx} = \frac{4}{3} \gamma \frac{\theta}{b} \left( \frac{d\delta}{dx} \right)^2 - \gamma \theta \frac{d\theta}{dx} \quad k = \gamma \theta$$

$$3). \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \alpha \frac{1}{\delta} \frac{d\delta}{dx} = \frac{4}{3} \gamma \frac{1}{b} \left( \frac{d\delta}{dx} \right)^2 - \frac{k}{b} \frac{d\theta}{dx}$$

$$2). 0 = -g \frac{a^2}{x^2} - \frac{\alpha}{\delta} \frac{d\theta}{dx} + \frac{\alpha}{\delta} \theta \frac{d\delta}{dx} + \frac{4}{3} \gamma \frac{\theta \delta}{b} \frac{d^2 \delta}{dx^2}$$

$$0 = -g \frac{a^2}{x^2} - \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \gamma \theta \left[ \frac{\delta}{b} \frac{d^2 \delta}{dx^2} + \frac{1}{b} \left( \frac{d\delta}{dx} \right)^2 \right]$$

$$\frac{c}{A} \log \theta + \alpha \log \delta = \frac{4}{3} \gamma \frac{\theta}{b} \int \left( \frac{d\delta}{dx} \right)^2 dx - \frac{k}{b} \frac{d\theta}{dx}$$

$$\text{const} \times \theta^{\frac{c}{A}} \cdot \delta^{\alpha} = e^{\frac{4}{3} \gamma \theta \dots}$$

$$\left( \frac{\theta}{\theta_0} \right)^{\frac{c}{A}} \left( \frac{\delta}{\delta_0} \right)^{\alpha} = \left( \frac{\theta}{\theta_0} \right)^{\frac{c}{A}} \left( \frac{p}{p_0} \right)^{\alpha}$$

$f(x) > 1$  wächst mit  $x$

$\theta = \text{const} \cdot p^{\frac{A}{c}}$   
 $\delta = \infty \quad p = \infty$   
 $\theta = 0 \quad p = 0$



$$\frac{g \varrho^2}{x^2} = \left(\alpha + \frac{c}{A}\right) \frac{d\theta}{dx} + f\theta \left[ - \right] \theta'$$

$$0 = \left(\alpha + \frac{c}{A}\right) \frac{d\theta'}{dx} + f\theta' \left[ - \right] \theta'$$

$$\frac{g \varrho^2}{x^2} \frac{\theta'}{\theta'} = \left(\alpha + \frac{c}{A}\right) \left( \frac{\theta'}{\theta'} \frac{d\theta}{dx} - \theta \frac{d\theta'}{dx} \right)$$

$$= \frac{d}{dx} \left( \frac{\theta}{\theta'} \right)$$

$$\frac{g \varrho^2}{x^2} = \left(\alpha + \frac{c}{A}\right) \frac{d\theta'}{dx}$$

$\theta'$  und  $\theta'$  berechnen

$$- \frac{g \varrho^2}{x} = \left(\alpha + \frac{c}{A}\right) \theta' + \text{const}$$

$$\theta' = M - \frac{N}{x} \quad \frac{d\theta'}{dx} = \frac{N}{x^2}$$

$$\frac{d\theta'}{dx} = \frac{N}{x^2} + \frac{\alpha}{6} \left(M - \frac{N}{x}\right) \frac{d\theta}{dx} = \frac{4}{3} f \left(M - \frac{N}{x}\right) \left(\frac{d\theta}{dx}\right)^{-1}$$

$$\frac{4}{3} f \left(\frac{d\theta}{dx}\right)^{-1} - \frac{\alpha}{6} \frac{d\theta}{dx} = \frac{cN}{A} \frac{1}{x^2 \left(M - \frac{N}{x}\right)}$$

$$\left(\alpha + \frac{c}{A}\right) \theta = \left(\alpha + \frac{c}{A}\right) \frac{1}{x} P = c \left(1 + \frac{c}{\alpha A}\right)$$

$$= \frac{c}{\alpha}$$



$$0 = \frac{g}{c^2} - (2 + \frac{c}{A}) \frac{d\theta}{dx} + \gamma \theta$$

$$6' \frac{d6'}{dx} = \frac{4}{3} \left( \frac{d6'}{dx} \right)^2$$

$$\frac{d^2 6'}{dx^2} = \frac{4}{3} \frac{1}{6'} \frac{d6'}{dx}$$

$$\ln \frac{d6'}{dx} = \frac{4}{3} \ln 6' + \text{const}$$

$$\frac{d6'}{dx} = A 6'^{\frac{4}{3}}$$

$$6'^{-\frac{4}{3}} d6' = A dx$$

$$-3 6'^{-\frac{1}{3}} = -B + Ax$$

$$\frac{1}{6} = \left( \frac{B - Ax}{3} \right)^3$$

$$6 = \frac{27}{(B - Ax)^3}$$

$$6 \frac{d^2 6}{dx^2} + \left( \frac{d6}{dx} \right)^2 = 0 = \frac{d}{dx} \left( 6 \frac{d6}{dx} \right)$$

$$6 \frac{d6}{dx} = \text{const}$$

$$6^2 = \text{const} \cdot x + \text{const}'$$

$$6 = \sqrt{a^2 x + m}$$

$$\frac{d6}{dx} = \frac{a}{2\sqrt{a^2 x + m}}$$

$$\frac{d6'}{dx} = A \frac{81}{(B - Ax)^{\frac{4}{3}}}$$

$$6 = c \theta^{\frac{-c}{\alpha A}}$$

$$\frac{d6}{dx} = -\frac{c}{\alpha A} \theta^{\frac{-c}{\alpha A} - 1}$$

in der abgeleiteten Gleichung ist

$$\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} = -\alpha \frac{1}{6} \frac{d6}{dx}$$

$$\theta = 0 \Rightarrow 6 = (\infty)^{\frac{1}{k-1}}$$

oder  $\frac{d6}{dx} = (\infty)^{\frac{k}{k-1}}$

$$3) +: \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} = \frac{d6}{dx} \left[ \frac{4}{3} \frac{d6}{dx} - \frac{d}{6} \right]$$

folange dies unendlich ist kann  $\frac{d6}{dx}$  nicht  $\infty$  werden

wenn  $\theta = 0$  ist  $\frac{d\theta}{dx}$  aber unendlich ist, so muss  $\frac{d6}{dx} < 0$  sein also

$\frac{a}{6} > -\frac{d6}{dx}$  und zwar  $6 = [0]^1$  und  $\frac{d6}{dx}$  endlich positiv

Was aber nicht möglich ist wenn 6 für kleinere x positiv infall.

Wenn gegen  $\theta = 0$   $\frac{d\theta}{dx}$  aber von höherer Ordg 0 so kann z.B.  $6 = \infty$  und  $\left(\frac{d6}{dx}\right)$  von höherer Ordg 0 werden

Von  $\frac{d\theta}{dx}$  von derselben Ordg 0, sodass  $\frac{1}{\theta} \frac{d\theta}{dx} = \text{endlich}$ :  $6 = 0$   $\frac{d6}{dx} = 0$  nicht möglich

und 6 mit  $\frac{d6}{dx}$  endlich so würde Gleichg. 2. verlangen dass  $\frac{d6}{dx}$  von 1ten Ordg unendlich wird (ander x z.B. 6) was aber zu Widerspruch führt



$$\theta = \theta_0 \left[ \left( \frac{b_0}{b} \right)^\alpha f(x) \right]^{\frac{A}{c}}$$

$$\frac{d\theta}{dx} = \theta_0 \frac{A}{c} \left[ \left( \frac{b_0}{b} \right)^\alpha f(x) \right]^{\frac{A}{c}-1} \left[ \left( \frac{b_0}{b} \right)^{-\alpha} \frac{db}{dx} - \alpha f \left( \frac{b_0}{b} \right)^{-\alpha-1} \frac{df}{dx} \right]$$

$$= \theta_0 \frac{A}{c} \left[ \left( \frac{b_0}{b} \right)^{-\alpha} f \right]^{\frac{A}{c}} \left[ \frac{1}{f} \frac{db}{dx} - \alpha \left( \frac{b_0}{b} \right)^{-1} \frac{df}{dx} \right]$$

$$g \frac{a^2}{x^2} + \left( \frac{c}{A} + \alpha \right) \frac{1}{f} \frac{df}{dx} = \frac{4}{3} \frac{r}{b} \left[ + b \frac{db}{dx^2} + \frac{1}{b} \left( \frac{db}{dx} \right)^2 \right] \theta_0 \left[ \left( \frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}}$$

$$f(x) = e^{\frac{4}{3} \frac{r}{b} \int_0^x \left( \frac{db}{dx} \right)^2 dx}$$

$$\frac{1}{f} \frac{df}{dx} = \frac{d}{dx} \ln f(x) = \frac{4}{3} \frac{r}{b} \frac{db}{dx}$$

$$g \frac{a^2}{x^2} = \frac{4}{3} \frac{r}{b} \left[ \left( \frac{db}{dx} \right)^2 + b \frac{db}{dx^2} \right] \theta_0 \left[ \left( \frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}} - \left( \frac{c}{A} + \alpha \right) \theta_0 \frac{A}{c} \left[ \left( \frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}} \left[ \frac{4}{3} \frac{r}{b} \left( \frac{db}{dx} \right)^2 - \alpha \frac{b_0}{b} \right]$$

$$= \left[ \left( \frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}} \theta_0 \left\{ \frac{4}{3} \frac{r}{b} \left( \frac{db}{dx} \right)^2 + \frac{4}{3} \frac{r}{b} b \frac{db}{dx^2} - \left( 1 + \frac{\alpha A}{c} \right) \left[ \frac{4}{3} \frac{r}{b} \left( \frac{db}{dx} \right)^2 - \alpha \frac{b_0}{b} \right] \right\}$$

$$= \left[ \left( \frac{b_0}{b} \right)^\alpha f \right]^{\frac{A}{c}} \theta_0 \left\{ - \frac{4}{3} \frac{r}{b} \frac{\alpha A}{c} \left( \frac{db}{dx} \right)^2 + \frac{4}{3} \frac{r}{b} b \frac{db}{dx^2} + \alpha \frac{b_0}{b} \left( 1 + \frac{\alpha A}{c} \right) \right\}$$

$$g \frac{a^2}{x^2} = \left( \frac{b_0}{b} \right)^{\frac{\alpha A}{c}} \theta_0 \left[ \frac{4}{3} \frac{r}{b} \left( \frac{db}{dx} \right)^2 + b \frac{db}{dx^2} + \alpha \frac{b_0}{b} \left( 1 + \frac{\alpha A}{c} \right) \right] e^{\frac{4}{3} \frac{r}{b} \frac{A}{c} \int_0^x \left( \frac{db}{dx} \right)^2 dx}$$

$$-g \frac{a^2}{x^2} = \frac{d\Phi}{dx} e^{\dots} + \Phi \frac{4}{3} \frac{r}{b} \frac{A}{c} \left( \frac{db}{dx} \right)^2 e^{\dots} \Phi$$



$$-\frac{2}{x} = \frac{d\Phi}{dx} + \frac{4}{3} \frac{A}{b} \left(\frac{db}{dx}\right)^2 \Phi$$

Versuche:

$$b = x^n$$

$$\frac{c}{A} \frac{1}{\theta} \frac{\partial \theta}{\partial x} + \frac{\alpha n}{x} = \frac{4}{3} \frac{A}{b} n^2 x^{2n-2}$$

$$\frac{c}{A} \log \theta + \alpha n \log x = \frac{4}{3} \frac{A}{b} n^2 \frac{x^{2n-1}}{2n-1}$$

$$\theta = \dots x^{-\frac{n \alpha A}{c}} \dots x^{2n-1}$$

$$\frac{d\theta}{dx} = e \left[ x^{-\frac{n \alpha A}{c}-1} + x^{-\frac{n \alpha A}{c}} \frac{2n-1}{x} \right]$$

$$\frac{1}{x^2} = e$$

$$b = e^x$$

$$\frac{1}{\theta} \frac{d\theta}{dx} = e^{2x}$$

$$\log \theta = \frac{e^{2x}}{e}$$

$$\theta = e$$

$$b = \log x$$

$$\frac{db}{dx} = \frac{1}{x}$$

$$\int \dots = \frac{1}{x}$$

$$b \frac{d^2 b}{dx^2} = x^{-1}$$

$$\left(\frac{db}{dx}\right)^2 = x^{-1}$$

$$\int \frac{db}{dx} dx = \log x$$

$$\left(\frac{db}{dx}\right)^2 = \frac{1}{x}$$

$$\frac{db}{dx} = x^{-\frac{1}{2}}$$

$$b = x^{\frac{1}{2}}$$

$$\frac{d^2 b}{dx^2} = x^{-\frac{3}{2}}$$

$$\theta = b^{-\frac{\alpha A}{c}} \int \dots$$

$$= \dots x^{-\frac{\alpha A}{2c}} \cdot x^{\frac{2}{3}}$$

$$0 = g \frac{a^2}{x} + m - \left(\alpha + \frac{c}{A}\right) \theta + \frac{\mu}{b} \theta \frac{d\theta}{dx}$$

$$\theta = 0$$

$$g \frac{a^2}{x} + m = 0$$

$$\theta = u + v$$

$$0 = g \frac{a^2}{x} + m - u v \left(\alpha + \frac{c}{A}\right) + \frac{\mu}{b} \left(u v \frac{dv}{dx} + u v^2 \frac{du}{dx}\right)$$

$$u \left[ -v \left(\alpha + \frac{c}{A}\right) + \frac{\mu}{b} \left(u v \frac{dv}{dx} + v^2 \frac{du}{dx}\right) \right]$$

$$\theta = u + v$$

$$g \frac{a^2}{x} + m - \left(\alpha + \frac{c}{A}\right) \theta_0 + \frac{\mu}{b} \theta_0 \left(\frac{d\theta}{dx}\right)_0 = -m$$

$$= g \frac{a^2}{x}$$

$$0 = g \frac{a^2}{x} + m - \left(\alpha + \frac{c}{A}\right) (u+v) + \frac{\mu}{b} (u+v) \left(\frac{du}{dx} + \frac{dv}{dx}\right)$$

$$0 = g \frac{a^2}{x} + m - \left(\alpha + \frac{c}{A}\right) u + \frac{\mu}{b} u \left(\frac{du}{dx} + \frac{dv}{dx}\right) + v \left[\left(\alpha + \frac{c}{A}\right) + \frac{\mu}{b} \left(\frac{du}{dx} + \frac{dv}{dx}\right)\right]$$

wobei:  
Wp. p. pseudonormiert  
empirische Zirkon

$$\frac{\mu}{b} \frac{d\theta}{dx} - \left(\alpha + \frac{c}{A}\right) + \frac{m}{\theta} + g \frac{a^2}{\theta x} = 0$$

$$\frac{\mu}{b} \frac{d\theta}{dx} - \left(\alpha + \frac{c}{A}\right) \theta + \frac{m}{\theta} + g \frac{a^2}{\theta x} = 0$$

$$\frac{\mu}{b} \left( \theta \frac{d\theta}{dx} - \theta_1 \frac{d\theta_1}{dx} \right) - \left(\alpha + \frac{c}{A}\right) \theta + \frac{m}{\theta} + g \frac{a^2}{\theta x} = 0$$

$$\theta \frac{d\theta}{dx} - \frac{d\theta}{dx} \left(\alpha + \frac{c}{A}\right) \theta + \theta_1 \frac{d\theta_1}{dx} = 0$$

$$\frac{\mu}{b} \frac{d(\theta - \theta_1)}{dx}$$



$$\frac{\mu}{2} \frac{d^2 \theta}{dx^2} + \frac{m}{2} \frac{d^2 \theta}{dx^2} - \frac{g a^2}{2} \frac{d\theta}{dx} - \frac{g a^2}{2} \frac{d\theta}{dx} = 0$$

$$u = (\log f(x))^2 \quad \frac{du}{dx} = 2 \log f \cdot \frac{f'}{f}$$

$$\frac{g a^2}{x} - \left(\alpha + \frac{c}{A}\right) \log f + \frac{\mu}{2b} \frac{f'}{f} \log f + m$$

$$\log f \left( \frac{\mu}{2b} \frac{f'}{f} - \alpha + \frac{c}{A} \right)$$

$$f = e^{\frac{1}{x}}$$

$$\frac{\mu}{2b} \frac{du}{dx} - \left(\alpha + \frac{c}{A}\right) u^{\frac{1}{2}} + \frac{g a^2}{x} + m = 0$$

$$\left(\alpha + \frac{c}{A}\right)^2 u = \left[ \frac{\mu}{2b} \frac{du}{dx} + \frac{g a^2}{x} + m \right]^2$$

$$\frac{du}{dx} = p$$

$$\left(\alpha + \frac{c}{A}\right)^2 p = 2 \left[ \frac{\mu}{2b} p + \frac{g a^2}{x} + m \right]$$

$$\left[ \frac{\mu}{2b} \frac{dp}{dx} - \frac{g a^2}{x^2} \right]$$

$$\frac{\frac{1}{2} \left(\alpha + \frac{c}{A}\right)^2 p}{\frac{\mu}{2b} p + \frac{g a^2}{x} + m} + \frac{g a^2}{x^2} = \frac{\mu}{2b} \frac{dp}{dx}$$

$$\frac{g a^2}{x^2} = \left(\alpha + \frac{c}{A}\right) u^{\frac{1}{2}} - m - \frac{\mu}{2b} \frac{du}{dx}$$

$$x = \frac{\frac{g a^2}{x^2} \frac{dx}{du}}{\left[\left(\alpha + \frac{c}{A}\right) u^{\frac{1}{2}} - m\right] \frac{dx}{du} - \frac{\mu}{2b}} \quad \parallel \quad 1 =$$

$$\left[ \left(\alpha + \frac{c}{A}\right) u^{\frac{1}{2}} - m - \frac{\mu}{2b} \frac{du}{dx} \right]^2 = \frac{g a^2}{x^2} \left[ \left(\alpha + \frac{c}{A}\right) \frac{1}{2} \frac{du}{dx} \frac{1}{u} - \frac{\mu}{2b} \frac{d^2 u}{dx^2} \right]$$

$$g \frac{dx}{\sqrt{u}} + m - \left(\alpha + \frac{c}{A}\right) \sqrt{u} + \frac{u}{2b} \frac{du}{dx} = 0$$

$$\frac{dx}{du} = p$$

$$g \frac{dx}{\sqrt{u}} + m - \left(\alpha + \frac{c}{A}\right) \sqrt{u} + \frac{u}{2b} \frac{1}{p} = 0$$

$$g \frac{1}{p} - \left(\alpha + \frac{c}{A}\right) \frac{1}{2} \frac{1}{\sqrt{u}} - \frac{u}{2b} \frac{1}{p^2} \frac{dp}{du} = 0$$

$$p \text{ linear } \sim \frac{1}{\sqrt{u}}$$

$$p = \frac{2}{\sqrt{u}} \quad \frac{dp}{du} = \frac{dz}{du} \frac{1}{\sqrt{u}} - \frac{2}{2u\sqrt{u}}$$

$$g \frac{2}{\sqrt{u}} - \left(\alpha + \frac{c}{A}\right) \frac{1}{2} \frac{1}{\sqrt{u}} - \frac{u}{2b} \frac{u}{2^2} \left( \frac{dz}{du} \frac{1}{\sqrt{u}} - \frac{2}{2u\sqrt{u}} \right)$$

$$g \frac{2}{\sqrt{u}} - \frac{1}{2} \left(\alpha + \frac{c}{A}\right) + \frac{u}{4b} \frac{1}{2} = \frac{u}{2b} \frac{u}{2^2} \frac{dz}{du}$$

$$\frac{du}{u} = \frac{u}{2b} \frac{dz}{\left[ g \frac{2}{\sqrt{u}} - \frac{1}{2} \left(\alpha + \frac{c}{A}\right) + \frac{u}{4b} \frac{1}{2} \right]}$$

$$\log u = f_c(z)$$

$$p = \frac{2}{\sqrt{u}}$$

$$\log u = f_c(p\sqrt{u})$$

$$= f_c \left( \frac{dx}{du} \sqrt{u} \right)$$

$$2 \log \theta = f_c \left[ \frac{dx}{d(\theta)} \theta \right]$$

$$\log u = \log \frac{u^2}{2^2 - \frac{1}{2g} + \frac{u}{4bg}} \left( \frac{2 - \sqrt{u}}{2 - -\sqrt{u}} \right)^{-\frac{1}{4g} \left(\alpha + \frac{c}{A}\right) \frac{1}{\sqrt{u}}}$$



$$\theta = \psi + n$$

$$0 = \frac{g a^2}{x} + m - \left(\alpha + \frac{c}{A}\right) \psi - \left(\alpha + \frac{c}{A}\right) n + \frac{\mu}{b} (\psi + n) \frac{d\psi}{dx}$$

$$m - \left(\alpha + \frac{c}{A}\right) n = 0$$

$$n = \frac{m}{\alpha + \frac{c}{A}}$$

$$0 = \frac{g a^2}{x} - \left(\alpha + \frac{c}{A}\right) \psi + \frac{\mu}{b} n \frac{d\psi}{dx} + \left(\frac{\mu}{b}\right) \psi \frac{d\psi}{dx}$$

$$\frac{d\psi}{\psi} = 2 \left[ \frac{dz}{z} + \frac{-g z + \frac{1}{2} \left(\alpha + \frac{c}{A}\right)}{g z^2 - \frac{1}{2} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg}} dz \right]$$

$$= 2 \left[ \frac{dz}{z} - \frac{\left[ z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) \right] dz}{z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg}} \right]$$

$$= 2 \frac{dz}{z} - \frac{2z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right)}{z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg}} + \frac{\frac{1}{2g} \left(\alpha + \frac{c}{A}\right)}{z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg}} dz$$

$$= 2 \log z - \log \left( z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg} \right) + \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) \int \frac{dz}{z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg}}$$

$$\int \frac{1}{\left[ z^2 - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) z + \frac{\mu}{4bg} \right]^2 - \left[ \frac{1}{4g} \left(\alpha + \frac{c}{A}\right) - \frac{\mu}{4bg} \right]^2} dz = \int \frac{d \frac{z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right)}{\sqrt{\left[ \frac{1}{4g} \left(\alpha + \frac{c}{A}\right) - \frac{\mu}{4bg} \right]^2 - 1}}}{\left[ \frac{z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right)}{\sqrt{\left[ \frac{1}{4g} \left(\alpha + \frac{c}{A}\right) - \frac{\mu}{4bg} \right]^2 - 1}} \right]^2 - 1} \cdot \frac{1}{\sqrt{\left[ \frac{1}{4g} \left(\alpha + \frac{c}{A}\right) - \frac{\mu}{4bg} \right]^2 - 1}}$$

$$= \frac{1}{2} \frac{1}{\sqrt{\left( \frac{\alpha + \frac{c}{A}}{4g} \right)^2 - \frac{\mu}{4bg}}} \log \left( \frac{z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) + \sqrt{\left[ \frac{1}{4g} \left(\alpha + \frac{c}{A}\right) - \frac{\mu}{4bg} \right]^2 - 1}}{z - \frac{1}{2g} \left(\alpha + \frac{c}{A}\right) - \sqrt{\left[ \frac{1}{4g} \left(\alpha + \frac{c}{A}\right) - \frac{\mu}{4bg} \right]^2 - 1}} \right)$$

$$gx + m - \left(x + \frac{c}{A}\right) \sqrt{u} + \sqrt{\frac{u}{2b}} \frac{du}{dx} = 0$$

$$g\sqrt{u} - \left(x + \frac{c}{A}\right) \frac{1}{2\sqrt{u}} \frac{du}{dx} + \sqrt{\frac{u}{2b}} \frac{d^2u}{dx^2} = 0 \quad \frac{du}{dx} = g \quad \frac{d^2u}{dx^2} = \frac{dg}{dx}$$

$$2 \left[ x + \frac{c}{A} - g \frac{x}{\theta} \right] = \frac{d}{dx} \left[ \frac{\left[ \frac{x}{2} + \frac{c}{A} - g \frac{x}{\theta} \right]^2 - \frac{x^2}{4}}{\frac{c}{A} - \frac{1}{\theta} \frac{d\theta}{dx}} \right]$$

$$\cancel{\theta = 2x} \quad x = 2\theta$$

$$\ln x = \ln 2 + \ln \theta$$

$$\frac{dx}{d\theta} = 2 + \theta \frac{d\theta}{d\theta}$$

$$\frac{1}{x} = \frac{1}{2} \frac{d\theta}{dx} + \frac{1}{\theta} \frac{d\theta}{dx}$$

$$x - x - \frac{c}{A} = \frac{m}{\theta} - \frac{gx}{\theta}$$

$$x + \frac{c}{A} - \frac{gx}{\theta} + \frac{m}{\theta} = 2$$

$$= \frac{m - gx}{\theta}$$

$$x = \frac{\theta}{g} \left[ x + \frac{c}{A} + \frac{m}{\theta} - 2 \right]$$

$$\theta = \frac{m - gx}{2 - x - \frac{c}{A}}$$

$$\ln \theta = \ln(m - gx) - \ln\left(2 - x - \frac{c}{A}\right)$$

$$gx = m + \theta \left(x + \frac{c}{A} - 2\right)$$

$$\frac{1}{\theta} \frac{d\theta}{dx} = \frac{g}{gx - m} - \frac{1}{2 - x - \frac{c}{A}} \frac{dx}{dx} = \frac{1}{x + \frac{c}{A} - 2} \left( \frac{g}{\theta} - \frac{dx}{dx} \right)$$

$$\frac{dx}{d\theta} = \frac{x + \frac{c}{A} - m}{2}$$

$$x = \frac{1}{g} \left( x + \frac{c}{A} \right) \theta + \frac{m}{g} - \frac{2\theta}{g}$$

$$\frac{dx}{d\theta} = \frac{1}{g} \left( x + \frac{c}{A} \right) - \frac{2}{g} - \theta \frac{d\theta}{d\theta}$$



$$\frac{2c}{A} z = \frac{d}{dx} \left[ \frac{\alpha + \frac{c}{A}}{g} \theta - \frac{z \theta}{g} - \frac{\theta^2 \frac{dz}{d\theta}}{g} \right] \left[ z(2-\alpha) \right]$$

$$\frac{2c}{A} z \frac{dx}{d\theta} = \frac{d}{d\theta} \left[ \frac{\alpha + \frac{c}{A}}{g} \theta - \frac{z \theta}{g} - \frac{\theta^2 \frac{dz}{d\theta}}{g} \right] = z(2-\alpha) \left[ \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{d\theta} - z - 3\theta \frac{dz}{d\theta} - \theta^2 \frac{d^2 z}{d\theta^2} \right]$$

$$+ \left[ 2z - \alpha \right] \frac{dz}{d\theta} \left[ \left( \alpha + \frac{c}{A} \right) \theta - z \theta - \theta^2 \frac{dz}{d\theta} \right]$$

$$\frac{dx}{dz} = \frac{1}{g} \left[ \left( \alpha + \frac{c}{A} - 2 \right) \frac{d\theta}{dz} - \theta \right]$$

$$\frac{2c}{A} z \frac{dx}{dz} = \frac{d}{dz} \left[ \frac{1}{g} \left( \alpha + \frac{c}{A} \right) \theta - \frac{z \theta}{g} - \frac{\theta^2 \frac{dz}{d\theta}}{g} \right]$$

$$= \frac{d}{dz} \left[ \theta \frac{dz}{d\theta} z(2-\alpha) \frac{1}{g} \left[ \left( \alpha + \frac{c}{A} - 2 \right) \frac{d\theta}{dz} - \theta \right] \right]$$

$$= \frac{d}{dz} \left[ \theta z(2-\alpha) \left[ \alpha + \frac{c}{A} - 2 - \frac{\theta}{\frac{d\theta}{dz}} \right] \right]$$

$$\frac{2c}{A} z \left[ \left( \alpha + \frac{c}{A} - 2 \right) \frac{d\theta}{dz} - \theta \right] = z(2-\alpha) \left[ \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dz} - 2 \frac{d\theta}{dz} - \theta \right] +$$

$$+ \theta (2-\alpha) \left[ \alpha + \frac{c}{A} - 2 - \frac{\theta}{\frac{d\theta}{dz}} \right] +$$

findet man  $2(2-x) = 2^2$  positiv:

$$\frac{2c}{A} = \frac{d}{dx} \left[ \frac{2 \cancel{\frac{c^2}{A^2}}}{\frac{1}{\theta} \frac{d\theta}{dx}} \right]$$

$$\frac{2c}{A} \cdot \frac{1}{2} = \cancel{\frac{2c}{A}} \frac{\frac{dx}{dx}}{\frac{1}{\theta} \frac{d\theta}{dx}} - 2 \frac{\frac{d}{dx} \left( \frac{1}{\theta} \frac{d\theta}{dx} \right)}{\left( \frac{1}{\theta} \frac{d\theta}{dx} \right)^2}$$

$$\frac{2c}{A} \frac{1}{\theta} \frac{d\theta}{dx} = 2 \frac{dx}{dx} - 2 \frac{d}{dx} \left( \ln \frac{1}{\theta} \frac{d\theta}{dx} \right)$$

$$\frac{2c}{A} \frac{1}{\theta} \frac{d\theta}{dx} = 2 - 2 \frac{d}{dx} \left( \ln \frac{1}{\theta} \frac{d\theta}{dx} \right)$$

$$\frac{d(\ln \theta)}{dx}$$

$$\left[ \frac{c^2}{A^2} + \frac{c\alpha}{A} + \frac{\alpha}{u} - \frac{1}{u^2} \right]$$

$$\left( u + \frac{du}{dx} \right)^2 \left[ \frac{2c\alpha}{A} + \frac{1c^2}{A^2} - \frac{2c}{A} - \frac{\alpha}{A} + \frac{\alpha}{u} + \frac{c}{A^2} + \frac{1c}{A\alpha} - \frac{1}{u^2} \right]$$



Integration:  $\frac{g x^2}{x^2} = g$

$$\frac{2c}{A} \left[ \alpha + \frac{c}{A} + \frac{m}{\theta} - \frac{g x}{\theta} \right] = \frac{d}{dx} \left[ \frac{\left[ \alpha + \frac{c}{A} + \frac{m}{\theta} - \frac{g x}{\theta} \right] \left[ \frac{c}{A} + \frac{m}{\theta} - \frac{g x}{\theta} \right]}{\frac{1}{\theta} \frac{d\theta}{dx}} \right]$$

$$g x - m = y$$

$$g dx = dy$$

$$\frac{2c}{A} \left[ \alpha + \frac{c}{A} - \frac{y}{\theta} \right] = \frac{d}{dy} \left[ \frac{\left[ \alpha + \frac{c}{A} - \frac{y}{\theta} \right] \left[ \frac{c}{A} - \frac{y}{\theta} \right]}{\frac{1}{\theta} \frac{d\theta}{dy}} \right]$$

$$= - \frac{\left[ \alpha + \frac{2c}{A} - \frac{2y}{\theta} \right] \frac{d}{dy} \left[ \frac{y}{\theta} \right]}{\frac{1}{\theta} \frac{d\theta}{dy}} - \frac{\left[ \alpha + \frac{c}{A} - \frac{y}{\theta} \right] \left[ \frac{c}{A} - \frac{y}{\theta} \right] \frac{d}{dy} \left( \frac{1}{\theta} \frac{d\theta}{dy} \right)}{\left( \frac{1}{\theta} \frac{d\theta}{dy} \right)^2}$$

$$\frac{2c}{A} \left[ \alpha + \frac{c}{A} - \frac{y}{\theta} \right] \left( \frac{1}{\theta} \frac{d\theta}{dy} \right)^2 = - \left[ \alpha + \frac{2c}{A} - \frac{2y}{\theta} \right] \frac{1}{\theta} \frac{d\theta}{dy} \left[ \frac{1}{\theta} - \frac{y}{\theta^2} \frac{d\theta}{dy} \right] -$$

$$- \frac{\left[ \alpha + \frac{c}{A} - \frac{y}{\theta} \right] \left[ \frac{c}{A} - \frac{y}{\theta} \right] \left[ \frac{1}{\theta} \frac{d^2\theta}{dy^2} - \frac{1}{\theta^2} \left( \frac{d\theta}{dy} \right)^2 \right]}{\left( \frac{1}{\theta} \frac{d\theta}{dy} \right)^2}$$

$$y = e^z \quad \theta = \frac{1}{u} e^z$$

$$y = e^z \quad \theta = u e^z$$

$$\frac{d\theta}{dy} = \left( u + \frac{du}{dz} \right)$$

$$\frac{d^2\theta}{dy^2} = \left( \frac{du}{dz} + \frac{d^2u}{dz^2} \right) e^{-2}$$

$$\frac{2c}{A} \left[ \alpha + \frac{c}{A} - \frac{1}{u} \right] \left( u + \frac{du}{dz} \right)^2 = - \left[ \alpha + \frac{2c}{A} - \frac{2}{u} \right] \left[ 1 - \frac{1}{u} \left( u + \frac{du}{dz} \right) \right] \left( u + \frac{du}{dz} \right) -$$

$$- \left[ \alpha + \frac{c}{A} - \frac{1}{u} \right] \left[ \frac{c}{A} - \frac{1}{u} \right] \left[ u \left( \frac{du}{dz} + \frac{d^2u}{dz^2} \right) - \left( u + \frac{du}{dz} \right)^2 \right]$$

$$\frac{2c}{A} \left[ \alpha + \frac{c}{A} - u \right] \left[ 1 - \frac{1}{u} \frac{du}{dz} \right] = - \left[ \alpha + \frac{2c}{A} - 2u \right] \left[ 1 - \frac{1}{u} \frac{du}{dz} \right] \frac{du}{dz} + \left[ \alpha + \frac{c}{A} - u \right] \left[ \frac{c}{A} - u \right] \left[ 1 - \frac{1}{u} \frac{du}{dz} - \frac{1}{u} \left( \frac{du}{dz} \right)^2 + \frac{1}{u} \frac{d^2u}{dz^2} \right]$$

$$\frac{2c}{A} \left[ \alpha + \frac{c}{A} - u \right] [1 - p] = - \left[ \alpha + \frac{2c}{A} - 2u \right] \frac{p}{1-p} + \left[ \alpha + \frac{c}{A} - u \right] \left[ \frac{c}{A} - u \right] \left[ \frac{1}{1-p} + \frac{\frac{dp}{du}}{(1-p)^2} \right]$$



$$\left[ \frac{c^2}{A^2} + \frac{c\alpha}{A} + \frac{\alpha}{u} - \frac{1}{u^2} \right] \left[ u + \frac{du}{dz} \right]^2 = \left[ \alpha + \frac{2c}{A} - \frac{2}{u} \right] \left[ u + \frac{du}{dz} \right] \frac{1}{u} \frac{du}{dz} -$$

$$- \left[ \alpha + \frac{c}{A} - \frac{1}{u} \right] \left[ \frac{c}{A} - \frac{1}{u} \right] \left[ \frac{du}{dz} + \frac{d^2u}{dz^2} \right] u = 0$$

$$\frac{d^2u}{dz^2} + \frac{2c}{A} \frac{du}{dz} + \frac{\alpha}{u} - \frac{1}{u^2}$$

$$\left[ \left( \frac{c^2}{A^2} + \frac{c\alpha}{A} \right) u^2 + \alpha u - 1 \right] + \frac{du}{dz} \left[ \frac{2c^2}{A^2} u + \frac{2c\alpha}{A} u + \frac{2c}{A} - \frac{2}{u} - \frac{2c}{A} + \frac{2}{u} + \right.$$

$$\left. + \frac{\alpha c}{A} u + \frac{c}{A^2} u - \frac{c}{A} - \frac{c}{A} + \frac{1}{u} \right]$$

$$+ \left( \frac{du}{dz} \right)^2 \left[ \frac{c^2}{A^2} + \frac{c\alpha}{A} + \frac{\alpha}{u} - \frac{1}{u^2} - \frac{\alpha}{u} - \frac{2c}{A} + \frac{2}{u^2} \right]$$

$$+ \frac{d^2u}{dz^2} \left[ \frac{\alpha c}{A} u + \frac{c^2}{A^2} u - \frac{c}{A} - \alpha - \frac{c}{A} + \frac{1}{u} \right] = 0$$

$$\left[ \left( \frac{c^2}{A^2} + \frac{c\alpha}{A} \right) u^2 + \alpha u - 1 \right] + \frac{du}{dz} \left[ 3 \left( \frac{c^2}{A^2} + \frac{c\alpha}{A} \right) u - \frac{4c}{A} + \frac{1}{u} \right] +$$

$$+ \left( \frac{du}{dz} \right)^2 \left[ \frac{c^2}{A^2} + \frac{c\alpha}{A} - \frac{2c}{A} \frac{1}{u} + \frac{1}{u^2} \right] + \frac{d^2u}{dz^2} \left[ \frac{c^2}{A^2} + \frac{c\alpha}{A} \right] u - \alpha - \frac{2c}{A} + \frac{1}{u} = 0$$

$$\frac{du}{dz} = p$$

$$\frac{d^2u}{dz^2} = p \frac{dp}{du}$$

$$U_0 + p U_1 + p^2 U_2 + p \frac{dp}{du} U_3 = 0$$



$$\alpha + \frac{c}{A} = \frac{\cancel{1} q}{\cancel{0} \cancel{A} \cancel{0}} = \alpha \left(1 + \frac{c}{\alpha A}\right) = \alpha \left(1 + \frac{1}{k-1}\right) = \frac{\alpha k}{k-1}$$

$$\frac{\alpha A}{c} = k-1 \quad \frac{c}{A} = \frac{\alpha}{k-1}$$

$$\frac{dq}{du} \underbrace{\left(\alpha + \frac{c}{A} - u\right)\left(\frac{c}{A} - u\right)}_{U_0} + q \underbrace{\left[\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - 2u\left(\alpha + \frac{2c}{A}\right) + 3u^2\right]}_{U_1} = \underbrace{\left[\frac{2c}{A}\left(\alpha + \frac{c}{A}\right) - u\left(\alpha + \frac{4c}{A}\right) + 2u^2\right]}_{U_2}$$

$$q = e^{-\int \frac{U_1}{U_0} du} \left[ C + \int \frac{U_2}{U_0} e^{\int \frac{U_1}{U_0} du} du \right]$$

$$\frac{U_1}{U_0} = \frac{\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - 2u\left(\alpha + \frac{2c}{A}\right) + 3u^2}{\left(\alpha + \frac{c}{A} - u\right)\left(\frac{c}{A} - u\right)} = 3 - \frac{2\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - u\left(\alpha + \frac{2c}{A}\right)}{\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - \left(\alpha + \frac{2c}{A}\right)u + u^2}$$

$$= 3 - \left[ \frac{\left(\alpha + \frac{c}{A}\right)}{\alpha + \frac{c}{A} - u} + \frac{\frac{c}{A}}{\frac{c}{A} - u} \right]$$

$$\int \frac{U_1}{U_0} du = 3u + \log \left[ \left(\alpha + \frac{c}{A} - u\right)^{+\left(\alpha + \frac{c}{A}\right)} \left(\frac{c}{A} - u\right)^{+\frac{c}{A}} \right]$$

$$\frac{U_2}{U_0} = \frac{\frac{2c}{A}\left(\alpha + \frac{c}{A}\right) - u\left(\alpha + \frac{4c}{A}\right) + 2u^2}{\frac{c}{A}\left(\alpha + \frac{c}{A}\right) - \left(\alpha + \frac{2c}{A}\right)u + u^2} = 2 -$$

$u_0$

$$\frac{dq}{du} (\alpha + \frac{c}{A} - u) (\frac{c}{A} - u) + q \left[ \frac{(\alpha + \frac{c}{A} - u) (\frac{c}{A} - u)}{u} - \frac{(\alpha + \frac{2c}{A} - 2u)}{u} \right] = 2x$$

$$q \left[ (\alpha + \frac{c}{A} - u) (\frac{c}{A} - u) - u (\alpha + \frac{2c}{A} - 2u) \right]$$

$$= \frac{2c}{A} (\alpha + \frac{c}{A} - u) - u (\alpha + \frac{2c}{A} - 2u)$$

$u_2$

$$u_1 = (\alpha + \frac{c}{A} - u) \left[ \frac{(\frac{c}{A} - u)}{u} - u \left( \alpha + \frac{c}{A} - u + \frac{c}{A} - u \right) \right]$$

$$\frac{u_1}{u_0} = 1 - u \left[ \frac{1}{\frac{c}{A} - u} + \frac{1}{\alpha + \frac{c}{A} - u} \right]$$

$$= 1 + \frac{u}{u - \frac{c}{A}} + \frac{u}{u - \alpha - \frac{c}{A}} = 3 - \frac{\frac{c}{A}}{\frac{c}{A} - u} - \frac{\alpha + \frac{c}{A}}{\alpha + \frac{c}{A} - u}$$

$$\frac{u_2}{u_0} = \frac{2c}{A} (\alpha + \frac{c}{A} - u) - u (\alpha + \frac{c}{A} - u + \frac{c}{A} - u)$$

$$\frac{u_2}{u_0} = \frac{\frac{2c}{A} - u}{\frac{c}{A} - u} - \frac{u}{\alpha + \frac{c}{A} - u} = 1 + \frac{\frac{c}{A}}{\frac{c}{A} - u} + 1 - \frac{\alpha + \frac{c}{A}}{\alpha + \frac{c}{A} - u}$$

$$= 2 + \frac{\frac{c}{A}}{\frac{c}{A} - u} - \frac{\alpha + \frac{c}{A}}{\alpha + \frac{c}{A} - u}$$

$$\int \frac{u_1}{u_0} du = 3u + \log \left( \alpha + \frac{c}{A} - u \right) \left( \frac{c}{A} - u \right)$$

$$\int \frac{u_2}{u_0} du = \frac{3u}{\alpha + \frac{c}{A} - u} \left( \frac{c}{A} - u \right)$$



$$\left. \begin{aligned} \int -\frac{\frac{c}{A}}{\frac{c}{A}-u} du &= \frac{c}{A} \log\left(\frac{c}{A}-u\right) = \log\left(\frac{c}{A}-u\right)^{\frac{c}{A}} \\ &= \int \frac{\frac{c}{A}}{u-\frac{c}{A}} du = \frac{c}{A} \log\left(u-\frac{c}{A}\right) = \log\left(u-\frac{c}{A}\right)^{\frac{c}{A}} \end{aligned} \right\} 2.$$

$$\begin{aligned} \int_{u_0}^{u_1} e^{\int_{u_0}^u \frac{3u}{\alpha + \frac{c}{A} - u}} du &= \int \left[ 2 \frac{\alpha + \frac{c}{A}}{\alpha + \frac{c}{A} - u} + \frac{\frac{c}{A}}{\alpha + \frac{c}{A} - u} \right] e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} du \\ &= 2 \int_0^{3u} e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} \left(\frac{c}{A} - u\right) du - \left(\alpha + \frac{c}{A}\right) \int_0^{3u} e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} du \\ &\quad + \frac{c}{A} \int_0^{3u} e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} du \end{aligned}$$

$$\left(\alpha + \frac{c}{A} - u\right) \left(\frac{c}{A} - u\right) = z$$

$$2 \left( \frac{dq}{du} + q \right) - (q-1) \frac{dz}{du} = \frac{2c}{A} \left(\alpha + \frac{c}{A} - u\right)$$

$$2 \frac{dq}{du} + q \frac{dz}{du} + 2q + \dots = f(u)$$

$$\frac{q}{2} = t$$

$$\frac{1}{2} \frac{dq}{du} - \frac{q}{2} \frac{dz}{du} + \frac{q}{2} = \frac{2c}{A} \left(\alpha + \frac{c}{A} - u\right) - \frac{dz}{du} = \frac{u_2}{2^2}$$

$$\begin{aligned} \int_0^{3u} e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} &= \int_0^{3u} e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} \left[ \frac{d}{du} \left( e^{\left(\alpha + \frac{c}{A} - u\right)^{\frac{c}{A}}} \right) \right] du \\ &= 3 \int_0 - \frac{c}{A} \int_2 \end{aligned}$$



$$(\alpha + \frac{c}{A}) J_1 + \frac{c}{A} J_2 - 3J_0 + e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} = 0$$

$$J_0 = \int e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} du = u e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} -$$

$$-3J_0 + (\alpha + \frac{c}{A}) J_1 + \frac{c}{A} J_2$$

$$4J_0 - (\alpha + \frac{c}{A}) J_1 - \frac{c}{A} J_2 = u e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}}$$

$$-3J_0 + (\alpha + \frac{c}{A}) J_1 + \frac{c}{A} J_2 = -e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}}$$

$$J_0 = e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} (u-1) ?$$

$$\frac{d}{du} = e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}-1} (\frac{c}{A} - u)^{\frac{c}{A}-1} [(u-1) [\cancel{3(\alpha + \frac{c}{A} - u)(\frac{c}{A} - u)} -$$

$$-(\alpha + \frac{c}{A})(\frac{c}{A} - u) - (\alpha + \frac{c}{A} - u) \frac{c}{A}] + (\alpha + \frac{c}{A} - u)(\frac{c}{A} - u)]$$

$$[3\alpha \frac{c}{A} + 3\frac{c^2}{A^2} - 6\frac{c}{A}u - 3u\alpha + 3u^2 - \alpha \frac{c}{A} + \alpha u + \frac{c}{A}u - \frac{c^2}{A^2} - \frac{\alpha c}{A} - \frac{c^2}{A^2} + \frac{uc}{A}]$$

$$= \frac{c}{A} + \frac{c^2}{A^2} - 4\frac{c}{A}u - 2\alpha u + 3u^2$$

$$= (\alpha + \frac{c}{A}) \frac{c}{A} - 2(\alpha + \frac{c}{A})u - 2\frac{c}{A}u + 3u^2 \parallel -\alpha \frac{c}{A} - \frac{c^2}{A^2} + \frac{2c}{A}u + \alpha u - u^2$$

$$= -\frac{2c}{A}u - \alpha u + 2u^2$$

$$3u^3 - 4\frac{c}{A}u^2 - 2\alpha u^2 + \frac{2c}{A}u + \frac{c}{A}u + \frac{2c}{A}u + \alpha u - 2u^2$$

$$-3 \int u e^{3u} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}} du + \int u e^{3u} (\alpha + \frac{c}{A}) (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}-1} (\frac{c}{A} - u)^{\frac{c}{A}} du$$

$$+ \int u e^{3u} \frac{c}{A} (\alpha + \frac{c}{A} - u)^{\frac{\alpha+c}{A}} (\frac{c}{A} - u)^{\frac{c}{A}-1} du$$



$$q = f(u) = \frac{1}{1-f} = \frac{1}{1-\frac{1}{u} \frac{du}{dz}}$$

$$u = \frac{y}{\theta} \quad z = \log y$$

$$\frac{du}{dz} = y \frac{du}{dy}$$

$$\frac{du}{dz} = u \left[ 1 - \frac{1}{fu} \right]$$

$$\int \frac{du}{u \left[ 1 - \frac{1}{fu} \right]} = \int dz = \int \frac{dy}{y} \quad \left. \vphantom{\int} \right\} u = f(y)$$

$$u = \frac{y}{\theta}$$

$$0 = g x - m - \left( \alpha + \frac{c}{A} \right) \theta + \frac{4}{3} \frac{K}{b} \theta \delta \frac{d\delta}{dx}$$

$$0 = y - \left( \alpha + \frac{c}{A} \right) \theta + \frac{4}{3} \frac{K}{b} \theta \delta \frac{d\delta}{dy}$$

$$0 = u - \left( \alpha + \frac{c}{A} \right) + \frac{2}{3} \frac{K}{b} \frac{d}{dy} (\delta^2)$$

~~$$0 = u - \left( \alpha + \frac{c}{A} \right) + \frac{2}{3} \frac{K}{b} \frac{d}{dy} (\delta^2) = \left( \alpha + \frac{c}{A} \right) y - \int u dy = \left( \alpha + \frac{c}{A} \right) y - \int f(y) dy$$~~

$$\frac{2}{3} \frac{K}{b} \delta^2 + \text{const} = \left( \alpha + \frac{c}{A} \right) y - \int u dy = \left( \alpha + \frac{c}{A} \right) y - \int f(y) dy$$

$$\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \frac{1}{2} \frac{\alpha}{\delta^2} \frac{d(\delta^2)}{dx} = \frac{2}{3} \frac{K}{b} \frac{1}{\delta^2} \left[ \frac{d(\delta^2)}{dx} \right]^2$$

Jok moga byt oznaczone 3 state prze  $b, \theta, ?$ .



System of equations to eliminate:

$$\left. \begin{aligned} \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \alpha \frac{1}{\theta} \frac{d\theta}{dx} &= \frac{4}{3} \frac{\gamma}{\rho} \left( \frac{d\theta}{dx} \right)^2 \\ g + \cancel{\alpha} \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} &= \frac{4}{3} \frac{\gamma}{\rho} \left[ \theta \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) + \theta \left( \frac{d\theta}{dx} \right)^2 \right] \\ g + \alpha \frac{d\theta}{dx} - \alpha \frac{\theta}{\theta} \frac{d\theta}{dx} &= \frac{4}{3} \frac{\gamma}{\rho} \theta \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) \\ &= \frac{4}{3} \frac{\gamma}{\rho} \theta \frac{d\theta}{dx} \frac{d\theta}{dx} + \frac{4}{3} \frac{\gamma}{\rho} \theta \frac{d^2\theta}{dx^2} \end{aligned} \right\}$$

$$\frac{d\theta}{dx} = v$$

$$\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} = \frac{4}{3} \frac{\gamma}{\rho} v^2 - \alpha \frac{v}{\theta}$$

$$g + \alpha \frac{d\theta}{dx} - \alpha \frac{\theta}{\theta} v = \frac{4}{3} \frac{\gamma}{\rho} \theta v \frac{d\theta}{dx} + \frac{4}{3} \frac{\gamma}{\rho} \theta \frac{dv}{dx}$$

I).  $\frac{d\theta}{dx} = v$

II).  $\frac{d\theta}{dx} = \frac{\theta}{\frac{c}{A}} \frac{4}{3} \frac{\gamma}{\rho} v^2 - \frac{\alpha}{\frac{c}{A}} \frac{\theta v}{\theta}$

$$\begin{aligned} \frac{4}{3} \frac{\gamma}{\rho} \theta \frac{dv}{dx} &= g - \alpha \frac{\theta v}{\theta} + \left[ \alpha - \frac{4}{3} \frac{\gamma}{\rho} \theta v \right] \left[ \frac{\frac{4}{3} \frac{\gamma}{\rho}}{\frac{c}{A}} \theta v^2 - \frac{\alpha}{\frac{c}{A}} \frac{\theta v}{\theta} \right] \\ &= g - \left( \alpha + \frac{\alpha^2}{\frac{c}{A}} \right) \frac{\theta v}{\theta} + \frac{\frac{4}{3} \frac{\gamma}{\rho}}{\frac{c}{A}} \alpha \theta v^2 - \left( \frac{\frac{4}{3} \frac{\gamma}{\rho}}{\frac{c}{A}} \right)^2 \theta v^3 \end{aligned}$$

III).  $\frac{dv}{dx} = \frac{g}{\frac{4}{3} \frac{\gamma}{\rho} \theta} \frac{1}{\theta} - \frac{\alpha (1 + \frac{\alpha}{\frac{c}{A}})}{\frac{4}{3} \frac{\gamma}{\rho}} \frac{v}{\theta^2} + \frac{2\alpha}{\frac{c}{A}} \frac{v^2}{\theta} - \frac{(\frac{4}{3} \frac{\gamma}{\rho})}{\frac{c}{A}} v^3$



$$g x + \left( \alpha - \frac{4}{3} \frac{\theta}{b} \frac{d\theta}{dx} \right) \frac{d\theta}{dx} = \alpha \frac{\theta}{b} \frac{d\theta}{dx} + \frac{4}{3} \frac{\theta}{b} \theta \frac{d\theta}{dx}$$

$$= - \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} \cdot \frac{\theta}{b} \frac{d\theta}{dx}$$

~~$$\frac{c}{A} \frac{1}{\theta} \frac{d^2\theta}{dx^2} - \frac{c}{A} \frac{1}{\theta^2} \left( \frac{d\theta}{dx} \right)^2 + \alpha \frac{\theta}{b} \frac{d^2\theta}{dx^2} - \frac{\alpha}{b} \left( \frac{d\theta}{dx} \right)^2 = \frac{4}{3} \frac{\theta}{b} \frac{d\theta}{dx} \frac{d\theta}{dx}$$~~

~~$$\frac{c}{A} \theta \frac{d\theta}{dx} + \alpha \frac{\theta^2}{b} \frac{d\theta}{dx} = \frac{4}{3} \frac{\theta^2}{b} \left( \frac{d\theta}{dx} \right)^2$$~~

~~$$\left( \theta \frac{d\theta}{dx} \right)^2 - \frac{\alpha}{\frac{4}{3} \frac{\theta}{b}} \theta \frac{d\theta}{dx} = \frac{c}{\frac{4}{3} \frac{\theta}{b}} \theta \frac{d\theta}{dx}$$~~

~~$$\theta \frac{d\theta}{dx} = \frac{\alpha}{\frac{4}{3} \frac{\theta}{b}} \frac{\theta}{b} \pm \sqrt{\left( \frac{\alpha}{\frac{4}{3} \frac{\theta}{b}} \right)^2 \left( \frac{\theta}{b} \right)^2 + \frac{c}{\frac{4}{3} \frac{\theta}{b}} \theta \frac{d\theta}{dx}}$$~~

~~$$g + \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} = \frac{d}{dx} \left[ \frac{\alpha}{2} \frac{\theta}{b} \pm \sqrt{\frac{\alpha^2}{4} \left( \frac{\theta}{b} \right)^2 + \frac{4}{3} \frac{\theta}{b} \frac{c}{A} \theta \frac{d\theta}{dx}} \right]$$

$$= \frac{\alpha}{2} \frac{1}{b} \frac{d\theta}{dx} - \frac{\alpha}{2} \frac{\theta}{b^2} \frac{d\theta}{dx} \pm \frac{1}{2} \sqrt{\frac{2\alpha^2}{4} \left( \frac{\theta}{b^2} \frac{d\theta}{dx} \right) \pm \frac{\theta^2}{b^3} \frac{d\theta}{dx}}$$

$$\pm \frac{1}{2} \sqrt{\frac{4}{3} \frac{\theta}{b} \frac{c}{A} \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right)}$$~~

~~$$\frac{c}{A} \frac{1}{\theta} \frac{d^2\theta}{dx^2} - \frac{c}{A} \frac{1}{\theta^2} \left( \frac{d\theta}{dx} \right)^2 + \frac{\alpha}{b} \frac{d\theta}{dx} - \frac{\alpha}{b} \left( \frac{d\theta}{dx} \right)^2 = \left[ \frac{4}{3} \frac{\theta}{b} \frac{d\theta}{dx} - \frac{\alpha}{b} \right] \frac{d}{dx} \left[ \frac{g + \alpha \frac{d\theta}{dx} - \alpha \frac{\theta}{b} \frac{d\theta}{dx}}{\frac{4}{3} \frac{\theta}{b} \theta \frac{d\theta}{dx} - \frac{\theta^2}{b} \frac{d\theta}{dx}} \right]$$~~



$$\left[ \frac{8}{3} \frac{\gamma}{b} \frac{db}{dx} - \frac{\alpha}{\sigma} \right] \frac{d\gamma}{dx} + \frac{\alpha}{\sigma^2} \left( \frac{d\gamma}{dx} \right)^2 = \frac{c}{A} \frac{d}{dx} \left( \frac{1}{\theta} \frac{d\theta}{dx} \right) \quad \left| \frac{4}{3} \frac{\gamma}{b} \theta b \right.$$

$$\left. \frac{4}{3} \frac{\gamma}{b} \theta b \frac{d\gamma}{dx} + 6 \frac{d\gamma}{dx} \frac{d\theta}{dx} \right] \frac{4}{3} \frac{\gamma}{b} + \frac{\alpha \theta}{\sigma} \frac{db}{dx} = g + \alpha \frac{d\theta}{dx} \quad \left| \frac{8}{3} \frac{\gamma}{b} \frac{db}{dx} - \frac{\alpha}{\sigma} \right.$$

$$- \frac{4}{3} \frac{\gamma}{b} \alpha \frac{\theta}{\sigma} \left( \frac{db}{dx} \right)^2 + 2 \left( \frac{4}{3} \frac{\gamma}{b} \right)^2 \frac{d\theta}{dx} \left( \frac{db}{dx} \right)^2 b - \frac{4}{3} \frac{\gamma}{b} \alpha \frac{db}{dx} \frac{d\theta}{dx} + \frac{8}{3} \frac{\gamma}{b} \alpha \frac{\theta}{\sigma} \left( \frac{db}{dx} \right)^2 -$$

$$- \alpha^2 \frac{\theta}{\sigma^2} \frac{db}{dx} = \frac{8}{3} \frac{\gamma}{b} g \frac{db}{dx} - \frac{\alpha g}{\sigma} + \frac{8}{3} \frac{\gamma}{b} \frac{db}{dx} \frac{d\theta}{dx} - \frac{\alpha^2}{\sigma} \frac{d\theta}{dx} - \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \theta b \frac{d}{dx} \left( \frac{1}{\theta} \frac{d\theta}{dx} \right)$$

$$\frac{4}{3} \frac{\gamma}{b} \frac{\alpha}{\sigma} \left( \frac{db}{dx} \right)^2 + 2 \left( \frac{4}{3} \frac{\gamma}{b} \right)^2 \frac{d\theta}{dx} \left( \frac{db}{dx} \right)^2 - 4 \frac{\gamma}{b} \alpha \frac{db}{dx} \frac{d\theta}{dx} - \alpha^2 \frac{\theta}{\sigma^2} \frac{db}{dx}$$

$$= \frac{8}{3} \frac{\gamma}{b} g \frac{db}{dx} - \frac{\alpha g}{\sigma} - \frac{\alpha^2}{\sigma} \frac{d\theta}{dx} - \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \theta b \frac{d}{dx} \left( \frac{1}{\theta} \frac{d\theta}{dx} \right)$$

$$\frac{4}{3} \frac{\gamma}{b} \left( \frac{db}{dx} \right)^2 = \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \alpha \frac{1}{\sigma} \frac{db}{dx}$$

$$\frac{\alpha c}{A} \frac{1}{\sigma} \frac{d\theta}{dx} + \frac{\alpha}{\sigma^2} \frac{db}{dx} + \frac{4}{3} \frac{\gamma}{b} \frac{d\theta}{dx} \left[ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \alpha \frac{1}{\sigma} \frac{db}{dx} \right] - 4 \frac{\gamma}{b} \alpha \frac{db}{dx} \frac{d\theta}{dx} - \frac{\alpha^2}{\sigma} \frac{d\theta}{dx}$$

$$= \frac{8}{3} \frac{\gamma}{b} g \frac{db}{dx} - \frac{\alpha g}{\sigma} - \frac{\alpha^2}{\sigma} \frac{d\theta}{dx} - \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \theta b \left[ \right]$$

$$\frac{4}{3} \frac{\gamma}{b} \frac{db}{dx} \left[ \alpha \frac{d\theta}{dx} - g \right] + \frac{\alpha g}{\sigma} + \left[ \alpha^2 + \frac{\alpha c}{A} \right] \frac{1}{\sigma} \frac{d\theta}{dx} +$$

$$+ \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \frac{1}{\theta} \left( \frac{d\theta}{dx} \right)^2 + \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \sigma \frac{d\theta}{dx} = 0$$

$$\frac{2}{3} \frac{\gamma}{b} \frac{d(\sigma^2)}{dx} \left[ \alpha \frac{d\theta}{dx} - g \right] + \alpha g + \alpha \left( \alpha + \frac{c}{A} \right) \frac{1}{\sigma} \frac{d\theta}{dx} + \frac{4}{3} \frac{\gamma}{b} \frac{c}{A} \frac{1}{\theta} \sigma^2 \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) = 0$$

$$\frac{1}{3} \frac{\gamma}{b} \left[ \frac{d(\sigma^2)}{dx} \right]^2 - \frac{\alpha}{2} \frac{d(\sigma^2)}{dx} = \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} \quad \left| \frac{4}{3} \frac{\gamma}{b} \right.$$



$$\left[ \alpha g + \alpha \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \frac{K}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) \right]^2 - \alpha \left[ \alpha \frac{d\theta}{dx} - g \right] \left[ \alpha g + \alpha \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \frac{K}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) \right] -$$

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$$= \frac{4}{3} \frac{K}{\theta} \frac{c}{A} \left[ \alpha \frac{d\theta}{dx} - g \right]^2 \frac{6^2}{\theta} \frac{d\theta}{dx}$$

$$\left[ \alpha g + \alpha \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \frac{K}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) \right]^2 - 2 \left[ \alpha \frac{d\theta}{dx} - g \right] \left[ \alpha g + \alpha \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \frac{K}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) \right] -$$

$$6^2 = \dots$$

$$\left[ \frac{6^2}{\theta} \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) \frac{4}{3} \frac{K}{\theta} \frac{c}{A} \right]^2 + \left[ \frac{6^2}{\theta} \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) \frac{4}{3} \frac{K}{\theta} \frac{c}{A} \right] \left[ 2 \alpha \left[ g + \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right] - \alpha^2 \frac{d\theta}{dx} + \alpha g \right] -$$

$$- \frac{4}{3} \frac{K}{\theta} \frac{c}{A} \frac{6^2}{\theta} \frac{d\theta}{dx} \left[ \alpha \frac{d\theta}{dx} - g \right]^2 = \alpha^2 \left[ \alpha \frac{d\theta}{dx} - g \right] \left[ g + \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right] -$$

$$- \alpha^2 \left[ g + \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right]^2$$

$$= \alpha^2 \left[ g + \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right] \left[ \alpha \frac{d\theta}{dx} - g - g - \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} \right]$$

Wstawiamy to  $6^2$  w równanie) otrzymamy z równania 3 składowe

(nie klawirajszu już  $\theta$ )

To równanie  $6^2 = \dots$  będzie służyć do oznaczenia stałych

=0



Overlying prismatic:

Isolated isothermally:

$$\rho = \frac{\mu}{\alpha \theta}$$

$$\begin{cases} \rho = \alpha \theta \\ 0 = -g - \frac{1}{\rho} \frac{\partial \rho}{\partial x} + \frac{4}{3} \frac{\mu}{\rho} \frac{d^2 \delta}{dx^2} \\ \rho \delta = b = \rho_0 \delta_0 = \frac{\mu_0 \delta_0}{\alpha \theta_0} \end{cases} \quad \rho = \frac{b}{\delta}$$

$$0 = -g - \alpha \theta \frac{1}{\rho} \frac{\partial \rho}{\partial x} + \frac{4}{3} \frac{\mu}{b} \delta \frac{d^2 \delta}{dx^2}$$

$$0 = -g + \alpha \theta \frac{1}{b} \frac{d\delta}{dx} + \frac{4}{3} \frac{\mu}{b} \delta \frac{d^2 \delta}{dx^2}$$

$$\frac{d\delta}{dx} = u \quad \frac{d^2 \delta}{dx^2} = \frac{du}{d\delta} = u \frac{du}{d\delta}$$

$$2\delta \frac{d\delta}{dx} = u$$

$$\frac{du}{dx} = 2 \left( \frac{d\delta}{dx} \right)^2 + 2\delta \frac{d^2 \delta}{dx^2}$$

$$2\delta \frac{d\delta}{dx} = \frac{du}{dx} \frac{1}{2} \left( \frac{u}{\delta} \right)^2$$

$$\frac{1}{\delta} \frac{d\delta}{dx} = \frac{u}{2\delta^2} \quad \left| \quad = \frac{du}{d(\delta^2)} u - \frac{1}{2} \frac{u^2}{\delta^2} \right.$$

$$0 = -g + \alpha \theta \frac{u}{\delta^2} + \frac{4}{3} \frac{\mu}{b} \frac{u}{\delta^2}$$

$$\frac{d\delta}{du} (g - \alpha \theta \frac{u}{\delta}) = \frac{4}{3} \frac{\mu}{b} u \delta$$

$$0 = -g + \alpha \theta \frac{u}{\delta^2} + \frac{4}{3} \frac{\mu}{b} \left[ \frac{du}{dx} - \left( \frac{u}{\delta} \right)^2 \right]$$

$$0 = -g + \alpha \theta \frac{u}{\delta^2} + \frac{4}{3} \frac{\mu}{b} \left[ \frac{1}{2} \frac{du}{d(\delta^2)} u - \frac{1}{4} \frac{u^2}{\delta^2} \right]$$

$$\frac{2}{3} \frac{\mu}{b} \frac{du}{d(\delta^2)} - \frac{1}{3} \frac{\mu}{b} \frac{u}{\delta^2} + \frac{\alpha \theta}{2} - \frac{g}{u} = 0$$

$$0 = -g + \alpha \theta \frac{u'v}{\delta^2} + \frac{4}{3} \frac{\mu}{b} \frac{u'v}{\delta^2} \left[ u' \frac{dv}{d\delta} + v \frac{du}{d\delta} \right]$$

$$u'v \left[ \frac{\alpha \theta}{\delta^2} + \frac{4}{3} \frac{\mu}{b} u' \frac{dv}{d\delta} \right]$$

$$\frac{d\delta}{dx} = - \frac{1}{\alpha \theta} \left( \frac{b}{\rho} \frac{d\rho}{dx} \right)$$

$$\rho \frac{\partial \delta}{\partial x} + \delta \frac{\partial \rho}{\partial x} = 0$$

$$\frac{\partial \delta}{\partial x} = - \frac{1}{\delta} \frac{\partial \rho}{\partial x} \quad \rho \delta = b$$

$$u\delta = x \quad \frac{u}{\delta} = y$$

$$u^2 = x^2 y \quad \frac{x}{y} = \delta^2$$

$$2u \frac{du}{dx} \frac{dy}{dx} = \frac{dx}{dx}$$

$$u \frac{du}{dx} + \delta \frac{du}{dx} = \frac{dx}{dx}$$

$$\frac{u}{\delta^2} \delta^2 + \frac{du}{\delta} = dy \quad - \delta^2$$

$$2u \delta^2 = dx - \delta^2 dy$$

$$2\delta^2 du = dx + \delta^2 dy$$

$$\frac{d\delta}{du} = \frac{1 - \frac{dy}{dx} \frac{x}{y}}{1 + \frac{dy}{dx} \frac{x}{y}} \quad \frac{1}{y}$$

2.



$$z = y$$

$$26 \frac{dz}{dx} = \frac{dy}{dx}$$

$$0 = -g + \frac{\alpha \theta}{2y} \frac{dy}{dx} + \frac{4}{3} \frac{\mu}{b} \left[ \frac{1}{2} \frac{dy}{dx} - \frac{1}{4y} \left( \frac{dy}{dx} \right)^2 \right]$$

$$2 \left( \frac{dz}{dx} \right)^2 + 26 \frac{dz}{dx} = \frac{dy}{dx} \quad \dots = -g + \frac{1}{y} \frac{dy}{dx} + \frac{2}{3} \frac{\mu}{b} \frac{d}{dx} \left[ \frac{1}{4} \left( \frac{dy}{dx} \right)^2 \right] = \frac{dy}{dx}$$

$$\frac{1}{2} \frac{dz}{dx} = \frac{1}{2} \frac{dy}{dx} = \frac{1}{2} \frac{1}{40} \left( \frac{dy}{dx} \right)^2$$

$$= \frac{1}{4} \frac{dy}{dx} - \frac{1}{4y} \left( \frac{dy}{dx} \right)^2$$

$$\frac{2}{3} \frac{dz}{dx} - \frac{1}{y} \left( \frac{dy}{dx} \right)^2$$

$$0 = -g + \frac{\alpha \theta}{2} \frac{1}{y} \frac{dy}{dx} + \frac{1}{3} \frac{\mu}{b} \frac{d}{dx} \left[ \frac{1}{4} \left( \frac{dy}{dx} \right)^2 \right]$$

$$\frac{1}{y} \frac{dy}{dx}$$

$$\frac{1}{y} \frac{dy}{dx} = 2$$

$$dy$$

$$0 = -g + \frac{\alpha \theta}{2} z + \frac{1}{3} \frac{\mu}{b} \frac{d}{dy} (z^2 y)$$

$$\theta = -\frac{g}{y} + \frac{\alpha \theta}{2} \frac{z}{y} + \frac{1}{3} \frac{\mu}{b} z^2 + \frac{2}{3} \frac{\mu}{b} y z \frac{dz}{dy}$$

$$\alpha \theta \frac{u}{\sigma^2} + \frac{4}{3} \frac{\mu}{b} u \frac{du}{d\sigma} = 0$$

$$u = u' + v$$

$$\frac{du}{d\sigma} \frac{4}{3} \frac{\mu}{b} = -\frac{\theta \alpha}{\sigma^2}$$

$$0 = -\frac{g}{\sigma^2} + \alpha \theta \left[ \frac{u'}{\sigma^2} + \frac{v}{\sigma^2} \right] + \frac{4}{3} \frac{\mu}{b} [u' + v] \left( \frac{du'}{d\sigma} + \frac{dv}{d\sigma} \right) = 0$$

$$0 = -\frac{g}{\sigma^2} + \alpha \theta \frac{v}{\sigma^2} + \frac{4}{3} \frac{\mu}{b} u' \frac{dv}{d\sigma} + \frac{4}{3} \frac{\mu}{b} v \frac{du'}{d\sigma} + \frac{4}{3} \frac{\mu}{b} v \frac{dv}{d\sigma} = 0$$

$$u z = t$$

$$u + z \frac{du}{dz} = \frac{dt}{dz}$$

$$\frac{dz}{dt} = \frac{1}{t^2} - \frac{1}{t^2} \frac{dt}{dz}$$

$$0 = -\frac{g}{\sigma^2} + \frac{4}{3} \frac{\mu}{b} \frac{dv}{d\sigma} (u' + v)$$

$$= \frac{4}{3} \frac{\mu}{b} v \frac{dv}{d\sigma} + \frac{4}{3} \frac{\mu}{b} \frac{d(u'v)}{d\sigma} + v \frac{\theta \alpha}{\sigma^2}$$

$$\frac{1}{\sigma} = 2 \quad \frac{dz}{d\sigma} = -\frac{1}{\sigma^2}$$

$$0 = -g \frac{1}{\sigma^2} + \alpha \theta u z^2 - \frac{4}{3} \frac{\mu}{b} u \frac{du}{dz} z^2$$

$$\frac{4}{3} \frac{\mu}{b} \frac{du}{dz} = \alpha \theta - \frac{g}{u z}$$

$$u \frac{d}{dz} \left( \frac{4}{3} \frac{\mu}{b} u - \alpha \theta z \right) + \frac{g}{z} dz = 0$$

$$u = \frac{\frac{q}{\theta^6}}{\frac{\alpha \theta}{\theta^2} + \frac{4}{3} \frac{1}{\theta} \uparrow}$$

$$\mu = \frac{-\frac{q}{\theta^2}}{\frac{\alpha \theta}{\theta^2} + \frac{4}{3} \frac{1}{\theta} \uparrow} - \frac{\frac{q}{\theta} \left[ \frac{2\alpha \theta}{\theta^3} + \frac{4}{3} \frac{1}{\theta} \frac{d\mu}{dx} \right]}{(\quad)^2}$$

$$h=0 \quad x=a \quad y = \left( \alpha + \frac{c}{A} \right) \theta - z \quad u = \left( 1 + \frac{c}{A\alpha} \right) - \delta$$

$$> 0 \quad = \frac{k}{k-1} - \delta < \frac{7}{2}$$



$$\frac{2c}{A\alpha} \left[ 1 + \frac{c}{A\alpha} + \frac{m-gx}{\alpha\theta} \right] = \frac{1}{dx} \left[ \frac{\left[ 1 + \frac{c}{A\alpha} + \frac{m-gx}{\alpha\theta} \right] \left[ \frac{c}{A\alpha} + \frac{m-gx}{\alpha\theta} \right]}{\left( \frac{1}{\alpha\theta} \right) \frac{d\theta}{dx}} \right]$$

m przybliżenie =  $g\alpha - \left(\alpha + \frac{c}{A}\right)\theta + z$

$$\frac{\alpha A}{c} = k-1$$

$$gx - m = y = e^z$$

$$\alpha\theta = u e^z$$

$$u = \frac{y}{\alpha\theta}$$

$$\frac{2c}{A\alpha} \left[ 1 + \frac{c}{A\alpha} - \frac{u}{u} \right] \left( u + \frac{du}{dz} \right)^2 = - \left[ \dots \right]$$

$$q = \int \left[ 2 - \frac{1 + \frac{c}{A\alpha}}{1 + \frac{c}{A\alpha} - u} + \frac{\frac{c}{A\alpha}}{\frac{c}{A\alpha} - u} \right] e^{3u} \left( 1 + \frac{c}{A\alpha} - u \right) \left( \frac{c}{A\alpha} - u \right) du$$

$$= \frac{1}{1-p} = f(u)$$

$$\int \frac{du}{u \left[ 1 - \frac{1}{f(u)} \right]} = \int dz = \int \frac{dy}{y}$$

$$q_{\text{max}} = \int 2 e^{3u} du = \frac{2}{3} e^{3u} - \frac{4}{3} \int e^{3u} u du$$

$\int 2 e^{3u} du = 2 e^{3u}$

$$= \frac{2}{3} e^{3u} \left[ \frac{2}{3} u - \frac{4}{9} u + \frac{4}{27} \right] = \frac{2}{3} e^{3u} \left[ \frac{2}{3} u - \frac{4}{9} u + \frac{4}{27} \right]$$

$$= \frac{2}{3} e^{3u}$$

$$\int \frac{du}{u \left[ 1 - \frac{2}{3} e^{-3u} \right]}$$

dla większych wartości  $u$

$$\int \frac{du}{u \left[ 1 - \frac{2}{3} e^{-3u} \right]}$$

dla małych  $u$

należy ~~nie~~ rozwinąć

Względna energia kinetyczna i nie stała:

$$1). p = \alpha \theta \rho$$

$$2). \rho \frac{d\theta}{dx} = -g - \frac{1}{\rho} \frac{\partial \rho}{\partial x} = -g - \alpha \frac{\partial \theta}{\partial x} + \frac{\alpha \theta}{\rho} \frac{\partial \rho}{\partial x}$$

$$\rho \theta = b$$

$$\rho = \alpha \frac{\theta b}{\theta}$$

$$3). \frac{c}{A \theta} \frac{\partial \theta}{\partial x} + \alpha \frac{1}{\theta} \frac{\partial \theta}{\partial x} = 0$$

$$\left(\frac{\theta}{\theta_0}\right)^{\frac{\alpha A}{c}} = 1$$

$$\frac{\alpha A}{c} = k-1$$

$$\frac{\theta}{\theta_0} = \left(\frac{\rho}{\rho_0}\right)^{-(k-1)}$$

$$\frac{\rho^2}{2} - g x$$

$$2 - \theta 3): \quad \rho \frac{d\theta}{dx} = -g - \left(\alpha + \frac{c}{A}\right) \frac{d\theta}{dx}$$

$$\frac{\rho^2}{2} + g x + \left(\alpha + \frac{c}{A}\right) \theta = \text{const}$$

$$\frac{\rho^2 - \rho_0^2}{2} + g(x-a) + \alpha \frac{k}{k-1} (\theta - \theta_0) = 0$$

$$\frac{\rho^2 - \rho_0^2}{2} + g(x-a) + \alpha \frac{k}{k-1} \theta_0 \left[ \left(\frac{\rho}{\rho_0}\right)^{-(k-1)} - 1 \right] = 0$$

$$\frac{\rho^2 - \rho_0^2}{2} + g(x-a) + \alpha \frac{k}{k-1} \frac{\theta_0}{\rho_0^{1-k}} \left[ \rho^{-(k-1)} - \rho_0^{-(k-1)} \right] = 0$$

$$20). k-1 = \frac{1}{2}$$

$$\frac{\rho^2 - \rho_0^2}{2} + \frac{2k}{k-1} \frac{\alpha \theta_0}{\rho_0^{1-k}} \left[ \frac{1}{\sqrt{\rho}} - \frac{1}{\sqrt{\rho_0}} \right] = -g(x-a)$$

$$\frac{\rho^2 - \rho_0^2}{2} \left( \frac{\rho^2 + \rho_0^2}{\rho^2 - \rho_0^2} \right)$$



$$g(x-a) = (\sqrt{b} - \sqrt{b_0}) \left[ \frac{2k}{k-1} \frac{\alpha \theta_0}{b_0^{1-k}} \frac{1}{\sqrt{b b_0}} - (b+b_0)(\sqrt{b} + \sqrt{b_0}) \right]$$

$$\frac{\alpha \theta_0 b}{b_0} = p_0$$

$$2g(x-a) = \frac{2k}{k-1} \frac{p_0}{b} \frac{b_0^{\frac{3}{2}}}{b_0^{1-k}} \left[ \frac{1}{\sqrt{b_0}} - \frac{1}{\sqrt{b}} \right] - (b^2 - b_0^2)$$

$$= \frac{6 p_0}{b} \left[ 1 - \sqrt{\frac{b_0}{b}} \right] - (b^2 - b_0^2)$$

nie ma niżej ~~tych~~ wartości  
wartości  $\frac{6 p_0 b_0}{b} = b \alpha \theta_0$

$$\frac{\partial g}{\partial x} = \theta_0 \frac{(1-k)}{b_0^{1-k}} b^{-k} \frac{\partial b}{\partial x}$$

$$\left[ b + \left( k + \frac{c}{A} \right) \frac{(1-k) \theta_0}{b_0} \left( \frac{b}{b_0} \right)^{-k} \right] \frac{\partial b}{\partial x} = 0$$

$= 0$  Max dla  $x$ :

$$b^{k+1} + \left( k + \frac{c}{A} \right) (1-k) \theta_0 b_0^{-k} b = 0$$

$$\left( \frac{b}{b_0} \right)^{k+1} = \left( k + \frac{c}{A} \right) \theta_0 = k \alpha \theta_0$$

$$\frac{b}{b_0} = [k \alpha \theta_0]^{\frac{2}{3}}$$

$$\frac{b_0}{b} = [k \alpha \theta_0]^{-\frac{2}{3}}$$

$$2g(x-a)_{\text{max}} = 6 p_0 \frac{b_0}{b} \left[ 1 - [k \alpha \theta_0]^{\frac{1}{3}} \right] - b_0^2 \left[ (k \alpha \theta_0)^{\frac{2}{3}} - 1 \right]$$

$$= 6 \alpha \theta_0 \left[ 1 - [k \alpha \theta_0]^{\frac{1}{3}} \right] - b_0^2 \left[ (k \alpha \theta_0)^{\frac{2}{3}} - 1 \right]$$

$$= 6 \alpha \theta_0 + b_0^2 - b$$

One type ~~of~~  $g(x-a)$  dla  $\theta_0 = 0$ :  $2g(x-a) = 2 \frac{\alpha k}{k-1} \theta_0 = b \alpha \theta_0$

↑  
w tej granicy ~~już~~   
mimo 0  
 $b \alpha \theta_0 [k \alpha \theta_0]^{-\frac{1}{3}} + b_0^2$   
 $= -b_0^2 + (k \alpha \theta_0)^{\frac{2}{3}} [6 \alpha \theta_0 + (k \alpha \theta_0)^{\frac{2}{3}}]$



Röhrchen komplette:

$$\begin{cases} \frac{G^2}{2} = \cancel{gx+m} - g x + m - \left(\alpha + \frac{c}{A}\right) \theta + \frac{4}{3} \frac{r}{b} \theta \cdot 6 \frac{db}{dx} \\ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \frac{\alpha}{\theta} \frac{db}{dx} = \frac{4}{3} \frac{r}{b} \left(\frac{db}{dx}\right)^2 \end{cases}$$

$$\frac{G_0^2}{2} = m - \left(\alpha + \frac{c}{A}\right) \theta_0 + \frac{4}{3} \frac{r}{b} \theta_0 \left(6 \frac{db}{dx}\right)_0$$

$$m = \cancel{\left(\alpha + \frac{c}{A}\right) \theta_0} + \frac{G_0^2}{2} - \frac{4}{3} \frac{r}{b} \theta_0 \left(6 \frac{db}{dx}\right)_0$$

$$gx - m = y$$

$$\begin{cases} \frac{G^2}{2} = -y - \left(\alpha + \frac{c}{A}\right) \theta + \frac{4}{3} \frac{r}{b} \theta \cdot 6 \frac{db}{dy} \\ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dy} + \frac{\alpha}{\theta} \frac{db}{dy} = \frac{4}{3} \frac{r}{b} \left(\frac{db}{dy}\right)^2 \end{cases}$$

Zurückführung  $G^2$ :

$$\frac{4}{3} \frac{r}{b} \theta \cdot 6 \frac{db}{dy} = y + \left(\alpha + \frac{c}{A}\right) \theta$$

$$\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dy} G^2 + \alpha \frac{6 db}{dy} = \frac{4}{3} \frac{r}{b} \left(6 \frac{db}{dy}\right)^2 \quad \left| \frac{4}{3} \frac{r}{b} \right.$$

$$\frac{4}{3} \frac{r}{b} G^2 = \frac{1}{\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dy}} \left[ -\alpha \left( \frac{y}{\theta} + \alpha + \frac{c}{A} \right) + \left( \frac{y}{\theta} + \alpha + \frac{c}{A} \right)^2 \right]$$

$$= \left( \alpha + \frac{c}{A} + \frac{y}{\theta} \right) \left( \frac{y}{\theta} + \frac{c}{A} \right)$$

$$2 \left[ \alpha + \frac{c}{A} + \frac{y}{\theta} \right] = \frac{d}{dy} \left[ \frac{\left( \alpha + \frac{c}{A} + \frac{y}{\theta} \right) \left( \frac{c}{A} + \frac{y}{\theta} \right)}{\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dy}} \right]$$



$$\frac{2c}{A\alpha} \left[ 1 + \frac{c}{A\alpha} + \frac{y}{\alpha\theta} \right] = \frac{d}{dy} \left[ \frac{\left( 1 + \frac{c}{A\alpha} + \frac{y}{\alpha\theta} \right) \left( \frac{c}{A\alpha} + \frac{y}{\alpha\theta} \right)}{\frac{1}{\theta} \frac{d\theta}{dy}} \right]$$

$$p_0 = 0.00018 \text{ (g/cm)}^2$$

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$$\frac{c}{A\alpha} = \frac{1}{k-1}$$

$$\frac{2}{k-1} \left[ \frac{k}{k-1} + \frac{y}{\alpha\theta} \right] = \frac{d}{dy} \left[ \frac{\left( \frac{k}{k-1} + \frac{y}{\alpha\theta} \right) \left( \frac{1}{k-1} + \frac{y}{\alpha\theta} \right)}{\frac{1}{\theta} \frac{d\theta}{dy}} \right]$$

$$(k-1)y = e^2 \quad \left| \frac{(k-1)y}{\alpha\theta} = u \right.$$

$$\alpha\theta = \frac{1}{u} e^2$$

$$\log \theta = \log x - \log u$$

$$\frac{1}{\theta} \frac{d\theta}{dz} = 1 - \frac{1}{u} \frac{du}{dz} = \frac{1}{\theta} \frac{d\theta}{dy} \frac{dy}{dz}$$

$$= e^2 \frac{1}{\theta} \frac{d\theta}{dy}$$

$$2(k+u) = \frac{d}{d(e^2)} \left[ \frac{(k+u)(1+u)}{\left( 1 - \frac{1}{u} \frac{du}{dz} \right) e^{-2}} \right]$$

$$= e^{-2} \frac{d}{dz} \left[ \frac{e^2 (k+u)(1+u)}{\left( 1 - \frac{1}{u} \frac{du}{dz} \right)} \right]$$

$$(k+u)(1+u) = k + (1+k)u + u^2$$

$$2(k+u) = \frac{d}{dz} \left[ \frac{(k+u)(1+u)}{1 - \frac{1}{u} \frac{du}{dz}} \right] + \frac{(k+u)(1+u)}{1 - \frac{1}{u} \frac{du}{dz}}$$

$$2(k+u) \left( 1 - \frac{1}{u} \frac{du}{dz} \right)^2 = (k+u)(1+u) \frac{d}{dz} \left( \frac{1}{u} \frac{du}{dz} \right) + \left( 1 - \frac{1}{u} \frac{du}{dz} \right) (1+k+2u) \frac{du}{dz}$$

$$+ \left( 1 - \frac{1}{u} \frac{du}{dz} \right) (k+u)(1+u)$$

$$\frac{1}{u} \frac{du}{dz} = p$$

$$2(k+u)(1-p)^2 = (k+u)(1+u) \frac{dp}{dz} + p(1-p)(u+uk+2u^2) + (1-p)(k+u)(1+u)$$

$$(k+u)(1+u) \frac{dp}{dz} - p^2(u+ku+2u^2)$$

$$\frac{dp}{dz} = \frac{dp}{du} \frac{du}{dz} = \frac{dp}{du} \frac{1}{p}$$



$$= u(1+u+ku)$$

$$2(k+u)p^2 = -(k+u)(1+u) \frac{dp}{dz} + p(1-p)(u+uk+2u^2) + p(k+u)(1+u)$$

$$p \frac{dp}{dz} + \frac{p^2}{u} \left( \frac{2}{1+u} + \frac{u}{1+u} + \frac{u}{k+u} \right) - \frac{p}{u} \left( 1 + \frac{u}{1+u} + \frac{u}{k+u} \right) = 0$$

$$= 2 - \frac{1}{1+u} - \frac{k}{k+u}$$

$$\frac{1}{p} \frac{dp}{dz} + \frac{1}{u} \left( 2 + \frac{1}{1+u} - \frac{k}{k+u} \right) - \frac{1}{p} \frac{1}{u} \left( 3 - \frac{1}{1+u} - \frac{k}{k+u} \right) = 0$$

$$\frac{1}{p} = q$$

$$q \frac{dq}{dz} + q \left( 3 - \frac{1}{1+u} - \frac{k}{k+u} \right) - \frac{1}{u} \left( 2 + \frac{1}{1+u} - \frac{k}{k+u} \right) = 0$$

$$2(k+u)(1+p)^2 = (k+u)(1+u)u p \frac{dp}{du} + p(1-p)(u+uk+2u^2) + (1-p)(k+u)(1+u)$$

$$\text{Jeśli } \frac{4}{3} \theta \frac{d\theta}{dx} = \frac{\alpha}{\theta} \text{ to mamy } \frac{d\theta}{dx} = 0$$

$$\text{a } \frac{4}{3} \theta \frac{d\theta}{dx} = \alpha \text{ więc: } \theta \neq \left( \frac{\alpha}{A} \right) \theta_0 - \frac{\alpha}{A} \theta$$

$$\text{więc różniczkując: } g = \frac{4}{3} \theta \frac{d}{dx} \left( \theta \frac{d\theta}{dx} \right) \Big|_{x=...}$$

$$\text{Gdy } \alpha \text{ większe niż } g_{x=0} = \left( \frac{\alpha}{A} \right) \theta_0 - \frac{\alpha}{A} \theta$$

$$\text{to } \frac{4}{3} \theta \frac{d\theta}{dx} > \frac{\alpha}{\theta} \text{ zatem } \underline{\underline{\frac{d\theta}{dx} > 0 !}}$$

$$(u^2 + 4u + 3k)$$

$$(k+u)(1+u)u p \frac{dp}{du} + p^2 [u+uk+2u^2 - 2k - 2u^2] + p [u+uk+2u^2 + 4k+4u - k - ku - k - u^2] + k+u+2u+u^2 - 2k-2u$$

$$- p^2 [4u^2 - u(k+1) - 2k]$$

$$u^2 + ku - u - k$$



Tan glin  $\frac{d\theta}{dx} = 0$ :

$$\frac{4}{3} \frac{1}{b} \frac{d\theta}{dx} = \frac{\alpha}{\theta} \quad \text{więc:}$$

$$\left(\frac{d\theta}{dx}\right) = -y - \left(\alpha + \frac{\epsilon}{A}\right)\theta + \alpha\theta = -y - \frac{\epsilon}{A}\theta$$

Zaniedbując modyfikację  $\frac{d\theta}{dx} = -gx + m - \frac{\epsilon}{A}\theta$

$$gx = \left(\alpha + \frac{\epsilon}{A}\right)\theta_0 - \frac{\epsilon}{A}\theta$$

$$0 = -gx + \left(\alpha + \frac{\epsilon}{A}\right)(\theta_0 - \theta) + \frac{4}{3} \frac{1}{b} \theta \frac{d\theta}{dx} \quad \text{I.}$$

$$\frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dx} + \frac{\alpha}{\theta} \frac{d\theta}{dx} = \frac{4}{3} \frac{1}{b} \left(\frac{d\theta}{dx}\right)^2 \quad \text{II.}$$

Najpierw  $\frac{d\theta}{dx} < 0$ , zatem z II:

$$\left(\frac{4}{3} \frac{1}{b} \frac{d\theta}{dx} < \frac{\alpha}{\theta}\right)$$

Gdy  $gx = \left(\alpha + \frac{\epsilon}{A}\right)(\theta_0 - \theta)$  ale z I):  $\theta$  weźmi większe anizeli gdyby  $\frac{d\theta}{dx} > 0$   
to z II):  $\frac{d\theta}{dx} > 0$  [stądby ono by nie stało = 0 przy  $gx = \left(\alpha + \frac{\epsilon}{A}\right)\theta_0$

Gdy  $gx = \left(\alpha + \frac{\epsilon}{A}\right)(\theta_0 - \theta)$  tutaj jednak przy  $gx = \left(\alpha + \frac{\epsilon}{A}\right)\theta_0$  mamy  
to z I):  $\frac{d\theta}{dx} = 0$  nie ma

I).  $\alpha + \frac{\epsilon}{A} = \frac{4}{3} \frac{1}{b} \theta \frac{d\theta}{dx}$  z czego wypunkt:

$$\left(\alpha + \frac{\epsilon}{A}\right) \frac{1}{\theta} \frac{d\theta}{dx} = \frac{4}{3} \frac{1}{b} \left(\frac{d\theta}{dx}\right)^2 = \frac{\alpha}{\theta} \frac{d\theta}{dx} + \frac{\epsilon}{A} \frac{1}{\theta} \frac{d\theta}{dx}$$

$$\text{więc} \quad \frac{1}{\theta} \frac{d\theta}{dx} = \frac{1}{\theta} \frac{d\theta}{dx} \quad \text{nie ma}$$

więc  $\theta = 0$  ?!

$$y \frac{dy}{dx} + y X_1 + X_2 = 0$$

$$\frac{1}{2} \frac{d^2}{dx^2} + X_1 \sqrt{2} + \bar{X}_2 = 0$$

$$\frac{y^2}{2} + \int y X_1 dx + \int X_2 dx = 0$$

$$y + \int X_1 dx + \int X_2 \frac{dx}{y} = 0$$

$$\begin{aligned} \frac{y^2}{2} + \int X_2 dx + y \int X_1 dx - \underbrace{\int dy \int X_1 dx}_{= - \int dx \int X_1 dx \left[ \bar{X}_1 + \frac{X_2}{y} \right]} \\ = + \int X_1 \int X_1 dx dx + \int \frac{X_2}{y} dx \int X_1 dx \end{aligned}$$

$$y = u + v$$

$$(u + v) \left( \frac{du}{dx} + \frac{dv}{dx} \right) + (u + v) X_1 + X_2 = 0$$

$$u \frac{du}{dx} + u \frac{dv}{dx} + v \frac{du}{dx} + v \frac{dv}{dx} + u X_1 + v X_1 + X_2 = 0$$

$$y = u + a$$

$$(y + a) \frac{dy}{dx} + (y + a) X_1 + X_2 = 0$$

$$y \frac{dy}{dx} + y X_1 + X_2 + a \left( \frac{dy}{dx} + X_1 \right) = 0$$



$$y_1 \frac{dy_1}{dx} + y_1 X_1 = 0$$

$$\frac{1}{2} \frac{d(y^2 - y_1^2)}{dx} + (y - y_1) X_1 + X_2 = 0$$

$$\frac{1}{2} \frac{d[(y - y_1)(y + y_1)]}{dx} + \uparrow$$

$$(y - y_1) \left[ \frac{1}{2} \frac{d(y + y_1)}{dx} + X_1 \right] + \frac{1}{2} (y + y_1) \frac{d(y - y_1)}{dx} + X_2 = 0$$

$$(y - y_1) \frac{dy}{dx} + (y + y_1) \frac{d(y - y_1)}{dx} + 2X_2 = 0$$

$$y \frac{dy}{dx} - y \frac{dy_1}{dx} + y_1 \frac{dy}{dx} - y_1 \frac{dy_1}{dx} + 2X_2$$

$$2y \frac{dy}{dx} - y \frac{dy_1}{dx} + y_1 X_1 + 2X_2 = 0$$

$$y_1 y \frac{dy}{dx} - y y_1 \frac{dy_1}{dx} + X_2 = 0$$

$$y y_1 \frac{d(y - y_1)}{dx} + X_2 = 0$$

$$(y - y_1 + y_1) y_1 \frac{d(y - y_1)}{dx} + X_2 = 0$$

$$(y - y_1) \frac{d(y - y_1)}{dx} + y_1^2 \frac{d(y - y_1)}{dx} + X_2 = 0$$

$$u \frac{du}{dx} + y_1^2 \frac{du}{dx} + X_2 = 0$$

$$\frac{dy}{dx} + X_1' + \frac{1}{y} X_2' = 0$$

$$\frac{d^2 y}{dx^2} + X_1' + \frac{X_2'}{y} - \frac{X_2}{y^2} \frac{dy}{dx} = 0$$

$$\frac{d^2 y}{dx^2} + X_1' + \frac{X_2'}{y} + \frac{X_1 X_2}{y^2} + \frac{X_2^2}{y^3} = 0$$

$$y = \frac{-X_2}{\frac{dy}{dx} + X_1}$$

$$\frac{dy}{dx} = \frac{-X_2'}{\frac{dy}{dx} + X_1} + X_2 \frac{\frac{d^2 y}{dx^2} + X_1'}{(\frac{dy}{dx} + X_1)^2}$$

$$\frac{dy}{dx} (\frac{dy}{dx} + X_1)^2 = -X_2' (\frac{dy}{dx} + X_1) + X_2 (\frac{d^2 y}{dx^2} + X_1')$$

$$p (p + X_1)^2 = -X_2' (p + X_1) + X_2 (\frac{dp}{dx} + X_1')$$

$$\frac{dp}{dx} + f_1(x) p^3 + f_2(x) p^2 + f_3(x) p + f_4(x) = 0$$



Spherical symmetry:

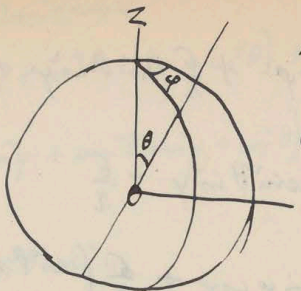
$$u = \frac{\partial \phi}{\partial x} = \frac{\partial \phi}{\partial r} \frac{\partial r}{\partial x}$$

~~the~~

$$u = \frac{\partial \phi}{\partial r} \sin \theta \cos \varphi$$

$$v = \frac{\partial \phi}{\partial r} \sin \theta \sin \varphi$$

$$w = \frac{\partial \phi}{\partial r} \cos \theta$$



$$x = r \sin \theta \cos \varphi$$

$$y = r \sin \theta \sin \varphi$$

$$z = r \cos \theta$$

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$$\begin{aligned} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) &= \frac{\partial}{\partial r} \left[ \sin^2 \theta \cos \varphi + \sin^2 \theta \sin \varphi + \cos^2 \theta \right] \\ &+ \frac{\partial}{\partial \theta} \left[ \cos^2 \theta \cos \varphi + \cos^2 \theta \sin \varphi + \sin^2 \theta \right] \\ &+ \frac{\partial}{\partial \varphi} \left[ \frac{\sin^2 \theta \cos \varphi}{\sin \theta} + \frac{\sin^2 \theta \sin \varphi}{\sin \theta} \right] \end{aligned}$$

$$= \frac{\partial \phi}{\partial r} + \frac{2\phi}{r}$$

$$\nabla^2 u = \frac{\partial^2 \phi}{\partial r^2} \sin \theta \cos \varphi + \frac{2}{r} \frac{\partial \phi}{\partial r} \sin \theta \cos \varphi + \frac{\partial^2 \phi}{\partial \theta^2} \cos \varphi + \frac{\partial^2 \phi}{\partial \varphi^2} \frac{\cos \varphi}{\sin \theta} + \frac{2 \cos \theta \sin \varphi}{r^2 \sin \theta}$$

$$= \left[ \frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right] \sin \theta \cos \varphi$$

$$\nabla^2 w = \left[ \frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right] \cos \theta$$

$$\left(\frac{\partial u}{\partial x}\right) = \frac{\partial \phi}{\partial r} \sin^2 \theta \cos \varphi + \frac{\phi}{r} (\cos^2 \theta \cos \varphi + \sin^2 \varphi)$$

$$= \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \varphi + \frac{\phi}{r}$$

$$\frac{\partial u}{\partial y} = \frac{\partial \phi}{\partial r} \sin^2 \theta \sin \varphi \cos \varphi + \frac{\phi}{r} (\cos^2 \theta \sin \varphi \cos \varphi + \frac{\sin^2 \varphi \sin \varphi}{\sin^2 \theta})$$

$$= \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \sin \varphi \cos \varphi$$

$$\frac{\partial u}{\partial z} = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \theta \cos \varphi$$

$$\frac{\partial v}{\partial x} = \frac{\partial \phi}{\partial r} \sin^2 \theta \sin \varphi \cos \varphi + \frac{\phi}{r} \cos^2 \theta \sin \varphi \cos \varphi - \frac{\phi \sin \varphi \cos \varphi}{r \sin^2 \theta}$$

$$= \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \sin \varphi \cos \varphi$$

$$\frac{\partial v}{\partial y} = \frac{\partial \phi}{\partial r} \sin^2 \theta \sin^2 \varphi + \frac{\phi}{r} (\cos^2 \theta \sin^2 \varphi + \cos^2 \varphi)$$

$$= \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \sin^2 \varphi + \frac{\phi}{r}$$

$$\frac{\partial v}{\partial z} = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \theta \sin \varphi$$

$$\frac{\partial w}{\partial x} = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \theta \sin \varphi$$

$$\frac{\partial w}{\partial y} = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \sin^2 \theta \cos \theta \sin \varphi$$

$$\frac{\partial w}{\partial z} = \frac{\partial \phi}{\partial r} \cos^2 \theta + \frac{\phi}{r} \sin^2 \theta = \left(\frac{\partial \phi}{\partial r} - \frac{\phi}{r}\right) \cos^2 \theta + \frac{\phi}{r}$$



$$2 \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 \right] = 2 \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right)^2 \left[ \sin^4 \theta \cos^4 \varphi + \sin^4 \theta \sin^4 \varphi + \cos^4 \theta \right] +$$

$$4 \frac{c}{r} \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right) \left[ \sin^2 \theta \cos^2 \varphi + \sin^2 \theta \sin^2 \varphi + \cos^2 \theta \right] + 6 \left( \frac{c}{r} \right)^2$$

$$\left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial z} \right)^2 = 4 \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right)^2 \sin^2 \theta \cos^2 \theta \sin^2 \varphi$$

$$\left( \frac{\partial u}{\partial z} + \frac{\partial v}{\partial x} \right)^2 = 4 \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right)^2 \sin^2 \theta \cos^2 \theta \cos^2 \varphi$$

$$\left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 = 4 \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right)^2 \sin^4 \theta \sin^2 \varphi \cos^2 \varphi$$

$$= 2 \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right)^2 \left[ \sin^4 \theta \cos^4 \varphi + \sin^4 \theta \sin^4 \varphi + \cos^4 \theta + \sin^2 \theta \cos^2 \theta + \right.$$

$$\left. + \sin^4 \theta \sin^2 \varphi \cos^2 \varphi \right]$$

$$+ 4 \frac{c}{r} \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right) \left[ \sin^2 \theta \cos^2 \theta + \sin^2 \theta \sin^2 \theta + \cos^2 \theta \right] + 6 \left( \frac{c}{r} \right)^2$$

$$4 = 2 \sin^2 \theta + \sin^4 \theta - \cos^2 \theta \sin^2 \varphi$$

$$\sin^2 \theta (\cos^2 \varphi - \cos^2 \theta \sin^2 \varphi + \sin^2 \theta \sin^2 \varphi - \sin^2 \theta \sin^2 \varphi \cos^2 \theta) + \cos^2 \theta$$

$$1 - \cos^2 \theta$$

$$= \sin^4 \theta [1 - \sin^2 \varphi \cos^2 \theta] = \sin^4 \theta [1 - \sin^2 \varphi + \sin^4 \varphi]$$

$$= 2 \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right)^2 \left[ \sin^4 \theta \cos^4 \varphi + \sin^4 \theta \sin^4 \varphi + \cos^4 \theta + 2 \sin^2 \theta \cos^2 \theta + 2 \sin^4 \theta \sin^2 \varphi \cos^2 \varphi \right]$$

$$+ 4 \frac{c}{r} \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right) \left[ \sin^2 \theta \cos^2 \theta + \sin^2 \theta \sin^2 \theta + \cos^2 \theta \right] + 6 \left( \frac{c}{r} \right)^2$$

$$\Phi = 2 \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right)^2 + 4 \frac{c}{r} \left( \frac{\partial \phi}{\partial r} - \frac{c}{r} \right) + 6 \left( \frac{c}{r} \right)^2 - \frac{2}{3} \left( \frac{\partial \phi}{\partial r} + \frac{2c}{r} \right)^2 = \frac{4}{3} \left[ \frac{d\phi}{dr} - \frac{c}{r} \right]^2$$



$$+v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}$$

$$u \frac{\partial u}{\partial x} = - \frac{g \rho^2 x}{\rho^2} - \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{\mu}{\rho} \frac{\partial}{\partial x} (\text{div}) + \frac{\mu}{\rho} \nabla^2 u$$

$$u \frac{\partial u}{\partial x} = - \frac{g \rho^2 x}{\rho^2} - \frac{1}{\rho} \frac{\partial p}{\partial x} + \frac{\mu}{\rho} \nabla^2 u$$

$$6 \frac{\partial \phi}{\partial r} \sin \theta \sin \varphi = - \frac{g \rho^2}{r^2} \sin \theta \sin \varphi - \frac{1}{\rho} \frac{\partial p}{\partial r} + \frac{\mu}{\rho} \frac{\partial}{\partial r} \left[ \frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right] + \frac{\mu}{\rho} \left[ \frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right]$$

$$6 \frac{\partial \phi}{\partial r} \sin \theta \sin \varphi = - \frac{g \rho^2}{r^2} \sin \theta \sin \varphi - \frac{1}{\rho} \frac{\partial p}{\partial r} + \frac{\mu}{\rho} \frac{\partial}{\partial r} \left[ \frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right] + \frac{\mu}{\rho} \left[ \frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right]$$

$$6 \frac{\partial \phi}{\partial r} \sin \theta \sin \varphi + u \frac{\partial u}{\partial x}$$

$$6 \left( \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) (\sin^2 \theta \cos^2 \varphi + \sin^2 \theta \sin^2 \varphi \cos^2 \varphi + \sin^2 \theta \sin^2 \varphi) + \frac{\phi}{r} \sin^2 \theta \cos^2 \varphi =$$

$$= \left[ 6 \left( \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) + \frac{\phi}{r} \right] \sin^2 \theta \cos^2 \varphi$$

$$\left[ 6 \left( \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) + \frac{\phi}{r} \right] \sin^2 \theta \cos^2 \varphi =$$

$$6 \left( \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) \sin^2 \theta \cos^2 \varphi + \sin^2 \theta \cos^2 \varphi \sin^2 \varphi + \cos^2 \theta$$

$$\left[ 6 \left( \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) + \frac{\phi}{r} \right] \cos^2 \theta =$$

$$\left[ 6 \left( \frac{\partial \phi}{\partial r} - \frac{\phi}{r} \right) + \frac{\phi}{r} \right] = - \frac{g \rho^2}{r^2} - \frac{1}{\rho} \frac{\partial p}{\partial r} + \frac{\mu}{\rho} \frac{\partial}{\partial r} \left[ \frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right] + \frac{\mu}{\rho} \left[ \frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} \right]$$

$$= 6 \frac{\partial \phi}{\partial r}$$

$$\frac{\partial \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r} - \frac{2\phi}{r^2} + 3 \frac{\partial \phi}{\partial r^2} + \frac{6}{r} \frac{\partial \phi}{\partial r} - \frac{6\phi}{r^2}$$

$$4 \frac{\partial \phi}{\partial r^2} + \frac{8}{r} \frac{\partial \phi}{\partial r} - \frac{8\phi}{r^2}$$

$$= \frac{4}{r} \frac{\partial}{\partial r} \left[ \frac{\partial \phi}{\partial r} + \frac{2\phi}{r} \right]$$



$$\sigma \frac{\partial \sigma}{\partial r} = -\frac{\partial a^2}{\partial r} - \frac{1}{\rho} \frac{\partial \tau}{\partial r} + \frac{4\mu}{3\rho} \frac{\partial}{\partial r} \left[ \frac{\partial \sigma}{\partial r} + \frac{2\sigma}{r} \right]$$

$$\frac{1}{A} \rho \sigma \frac{\partial \theta}{\partial r} + \left( \frac{\partial \sigma}{\partial r} + \frac{2\sigma}{r} \right) \tau = \frac{4\mu}{3} \left[ \frac{\partial \sigma}{\partial r} - \frac{\sigma}{r} \right]^2 \bigg| r^2$$

$$\tau = \alpha \rho \theta$$

$$\rho \sigma r^2 = \rho \cdot \sigma \cdot a^2 = b$$

$$\mu = \rho \theta$$

$$\rho = \frac{b}{\sigma r^2} \quad \tau = \alpha b \frac{\theta}{\sigma r^2}$$

$$\left. \begin{aligned} \sigma \frac{d\sigma}{dr} &= -\frac{\partial a^2}{\partial r} - \alpha b r^2 \frac{d}{dr} \left( \frac{\theta}{\sigma r^2} \right) + \frac{4\mu \theta}{3b} \sigma r^2 \frac{d}{dr} \left[ \frac{\partial \sigma}{\partial r} + \frac{2\sigma}{r} \right] \\ \frac{1}{A} \frac{\partial \theta}{\partial r} + \alpha \frac{\theta}{\sigma r^2} \left( \frac{d\sigma}{dr} + \frac{2\sigma}{r} \right) &= \frac{4\mu \theta}{3b} \left[ \frac{d\sigma}{dr} - \frac{\sigma}{r} \right]^2 \end{aligned} \right\}$$

$$\frac{\partial}{\partial r} \left[ \sigma r^2 \left( \frac{d\sigma}{dr} + \frac{2\sigma}{r} \right) \right] = \left[ \frac{d\sigma}{dr} + \frac{2\sigma}{r} \right]^2 + \sigma r^2 \left[ \frac{d^2 \sigma}{dr^2} + \frac{2}{r} \frac{d\sigma}{dr} - \frac{2\sigma}{r^2} \right]$$

$$\partial_{\mu \kappa \alpha} + \dots = -\frac{2}{3} \frac{\partial}{\partial x} (\mu \operatorname{div}) + \frac{\partial}{\partial y} \left[ \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] + \frac{\partial}{\partial z} \left[ \mu \left( \frac{\partial v}{\partial y} + \frac{\partial u}{\partial z} \right) \right]$$

$$+ 2 \frac{\partial}{\partial x} \left( \mu \frac{\partial u}{\partial x} \right)$$

$$= -\frac{2}{3} \frac{\partial \mu}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - \frac{2}{3} \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right) + \frac{\partial \mu}{\partial y} \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) +$$

$$+ \mu \left( \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 u}{\partial y^2} \right) + \frac{\partial \mu}{\partial z} \left( \frac{\partial w}{\partial x} + \frac{\partial v}{\partial z} \right) + \mu \left( \frac{\partial^2 w}{\partial y \partial z} + \frac{\partial^2 v}{\partial z^2} \right) + 2 \frac{\partial \mu}{\partial x} \frac{\partial u}{\partial x} + 2 \mu \frac{\partial^2 u}{\partial x^2}$$

$$= \mu \left[ -\frac{2}{3} \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right) + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 u}{\partial z^2} + \frac{\partial^2 w}{\partial x \partial z} + 2 \frac{\partial^2 u}{\partial x^2} \right]$$

$$+ \frac{\partial \mu}{\partial x} \left[ -\frac{2}{3} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + 2 \frac{\partial u}{\partial x} \right] + \frac{\partial \mu}{\partial y} \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) + \frac{\partial \mu}{\partial z} \left( \frac{\partial w}{\partial x} + \frac{\partial v}{\partial z} \right)$$



$$= -\frac{2}{3} \frac{d}{dx} \left[ \mu \left( \frac{dv}{dx} + \frac{dv}{dy} + \frac{dv}{dz} \right) \right] + \frac{d}{dx} \left( \mu \frac{dv}{dx} \right) + \frac{d}{dy} \left( \mu \frac{dv}{dy} \right) + \frac{d}{dz} \left( \mu \frac{dv}{dz} \right) + \frac{d}{dx} \left( \mu \frac{dv}{dx} \right) + \frac{d}{dy} \left( \mu \frac{dv}{dy} \right) + \frac{d}{dz} \left( \mu \frac{dv}{dz} \right)$$

$$-\frac{2}{3} \frac{\partial}{\partial x} \left[ \mu \left( \frac{dv}{dz} + \frac{2v}{r} \right) \right] + 2 \frac{\partial}{\partial x} \left[ \mu \left( \frac{dv}{dz} - \frac{v}{r} \right) \sin^2 \theta \cos \varphi + \frac{6\mu}{r} \right] + 2 \frac{\partial}{\partial y} \left[ \mu \left( \dots \right) \right] + 2 \frac{\partial}{\partial z} \left[ \mu \left( \dots \right) \right]$$

$$= -\frac{2}{3} \frac{d}{dr} \left[ \mu \left( \frac{dv}{dr} + \frac{2v}{r} \right) \right] \sin \theta \cos \varphi +$$

$$2 \frac{d}{dr} \left[ \mu \left( \frac{dv}{dr} - \frac{v}{r} \right) \right] \left[ \sin^3 \theta \cos^3 \varphi + \sin^3 \theta \sin^2 \varphi \cos \varphi + \sin \theta \cos^2 \theta \cos \varphi \right] \sin \theta \cos \varphi$$

$$+ 2 \frac{d}{dr} \left( \mu \frac{v}{r} \right) \sin^2 \theta \cos \varphi$$

$$= \frac{d}{dr} \left[ \mu \left( \frac{2}{3} \left( \frac{dv}{dr} + \frac{2v}{r} \right) + 2 \left( \frac{dv}{dr} - \frac{v}{r} \right) + 2 \frac{v}{r} \right) \right] \sin^2 \theta \cos \varphi$$

$$= \frac{d}{dr} \left[ \mu \left( -\frac{2}{3} \frac{dv}{dr} - \frac{4}{3} \frac{v}{r} + 2 \frac{dv}{dr} - \frac{2v}{r} + \frac{4v}{r} \right) \right]$$

$$= \frac{d}{dr} \left[ \mu \left( \frac{4}{3} \left( \frac{dv}{dr} - \frac{v}{r} \right) \right) \right] = \frac{4}{3} \frac{d}{dr} \left[ \mu \left( \frac{dv}{dr} - \frac{v}{r} \right) \right]$$

$$+ \frac{d}{dr} \frac{dv}{dr} + \frac{dv}{dr} + \frac{dv}{dr} \frac{dv}{dr}$$

$$+ \frac{d}{dr} \left[ -\frac{2}{3} \mu \frac{dv}{dr} + \frac{2}{3} \mu \frac{v}{r} \right]$$

$$+ \frac{d}{dr} \left[ \mu \left( \frac{dv}{dr} - \frac{v}{r} \right) \right] + \frac{d}{dr} \left[ \mu \left( \frac{dv}{dr} - \frac{v}{r} \right) \right]$$

$$= \frac{d}{dr} \left[ \frac{4}{3} \mu \left( \frac{dv}{dr} - \frac{v}{r} \right) \right] + \frac{4\mu}{r} \left[ \frac{dv}{dr} - \frac{v}{r} \right] = \frac{4\mu}{3} \left[ \frac{dv}{dr} - \frac{1}{r} \frac{dv}{dr} + \frac{v}{r} + \frac{3}{r} \frac{dv}{dr} - \frac{3v}{r} \right] + \frac{4\mu}{3} \left[ \frac{dv}{dr} - \frac{v}{r} \right]$$



$$\nabla^4 + \frac{d}{dr}(\text{div}) = \frac{d}{dr} \left( \frac{d\phi}{dr} \right) - \dots$$

$$2\theta \sin \varphi \left[ \frac{d^2 \phi}{dr^2} + \frac{2}{r} \frac{d\phi}{dr} - \frac{2\phi}{r^2} + \frac{d}{dr} \left( \frac{d\phi}{dr} + \frac{2\phi}{r} \right) \right]$$

$$\frac{d^2 \phi}{dr^2} + \frac{2}{r} \frac{d\phi}{dr} - \frac{2\phi}{r^2}$$

$$\nabla^2 u = \frac{\partial}{\partial x} \frac{\partial u}{\partial x} + \frac{\partial}{\partial y} \frac{\partial u}{\partial y} + \frac{\partial}{\partial z} \frac{\partial u}{\partial z}$$

$$= \frac{d}{dr} \left( \frac{d\phi}{dr} + \frac{\phi}{r} \right) \sin^3 \theta \sin^2 \varphi + \frac{d}{dr} \left( \frac{\phi}{r} \right) 2\theta \sin \varphi$$

$$+ \dots \sin^3 \theta \sin^2 \varphi \sin \theta \sin^2 \varphi$$

$$= 2\theta \sin \varphi \left[ \frac{d}{dr} \left( \frac{d\phi}{dr} + \frac{\phi}{r} \right) + \frac{d}{dr} \left( \frac{\phi}{r} \right) \right]$$

$$= 2\theta \sin \varphi \frac{d^2 \phi}{dr^2}$$

~~dr = r dr~~

$$= \frac{d}{dx} \left[ -\frac{2}{3} \mu \left( \frac{d\phi}{dr} + \frac{2\phi}{r} \right) \right] + 2 \left[ \frac{d}{dx} \left( \mu \frac{d\phi}{dr} \right) + \frac{d}{dy} \left( \mu \frac{d\phi}{dr} \right) + \dots \frac{d}{dz} \left( \mu \frac{d\phi}{dr} \right) \right]$$

$$+ 2\mu \frac{\phi}{r}$$

$$\frac{d}{dr} \left[ \mu \left( \frac{d\phi}{dr} + \frac{\phi}{r} \right) \right] \sin^3 \theta \sin^2 \varphi + \mu \left( \frac{d\phi}{dr} + \frac{\phi}{r} \right) \frac{2 \sin^2 \theta \sin^2 \varphi + 2 \sin \theta \sin \varphi \sin^2 \varphi}{r}$$

$$\frac{\sin^3 \theta \sin^2 \varphi}{\sin^3 \theta \sin^2 \varphi} \quad 2 \sin^2 \theta \sin^2 \varphi \sin \varphi + \sin^3 \theta \sin \varphi - \sin^2 \theta \sin^2 \varphi$$

$$\frac{\sin^3 \theta \sin^2 \varphi}{\sin^3 \theta \sin^2 \varphi} \quad - \sin^2 \theta \sin \varphi (\sin^2 \theta - \sin^2 \varphi)$$

$$= \sin \theta [2 \sin^2 \theta \sin \varphi + \sin \varphi \sin^2 \theta \sin \varphi + \sin^2 \theta \sin \varphi]$$

$$= 2 \sin \theta \sin \varphi \sin^2 \theta$$



$$6 \frac{d\delta}{dr} = -\frac{g a^2}{r^2} - \alpha 6 r^2 \frac{d}{dr} \left( \frac{\theta}{6 r^2} \right) + \frac{4 \mu \theta}{3 b} 6 r^2 \left[ \frac{d}{dr} \left( \frac{d\delta}{dr} + \frac{2\delta}{r} \right) + \right. \\ \left. + \frac{4 \mu}{3 b} 6 r^2 \left[ \frac{d\delta}{dr} - \frac{\delta}{r} \right] \frac{d\theta}{dr} \right]$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{6} \left[ \frac{d\delta}{dr} + \frac{2\delta}{r} \right] = \frac{4 \mu \theta}{3 b} r^2 \left[ \frac{d\delta}{dr} - \frac{\delta}{r} \right]^2$$

$$\frac{d\delta}{dr} \theta = -\frac{g a^2}{r^2} - \alpha \frac{d\theta}{dr} + \frac{\alpha \theta}{6} \left[ \frac{d\delta}{dr} + \frac{2\delta}{r} \right] + \frac{4 \mu \theta}{3 b} \dots = \frac{d}{dr} \left( \theta \left( \frac{d\delta}{dr} - \frac{\delta}{r} \right) \right) + \frac{3}{r} \left( \frac{d\delta}{dr} - \frac{\delta}{r} \right)$$

$$6 \frac{d\delta}{dr} = -\frac{g a^2}{r^2} - \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dr} + \frac{4 \mu}{3 b} \left\{ \theta 6 r^2 \frac{d}{dr} \left[ \frac{d\delta}{dr} + \frac{2\delta}{r} \right] + 6 \frac{d\theta}{dr} r^2 \left[ \frac{d\delta}{dr} - \frac{\delta}{r} \right] + r^2 \theta \left[ \frac{d\delta}{dr} - \frac{\delta}{r} \right]^2 \right\}$$

$$\theta \left[ r^2 6 \frac{d\delta}{dr} + 2 r \delta \frac{d\theta}{dr} - 2 \delta^2 + r^2 \left( \frac{d\delta}{dr} \right)^2 + 6^2 - 2 6 r \frac{d\delta}{dr} \right]$$

$$= \theta \left[ r^2 6 \frac{d\delta}{dr} + r^2 \left( \frac{d\delta}{dr} \right)^2 - 6^2 \right]$$

$$= \frac{d}{dr} \left[ 6 r^2 \left( \frac{d\delta}{dr} - \frac{\delta}{r} \right) \right] = \left( \frac{d\delta}{dr} \right)^2 r^2 - 6 r \frac{d\delta}{dr} + 2 r \delta \frac{d\theta}{dr} - 2 \delta^2 + 6 r^2 \frac{d\delta}{dr} - 6 r \frac{d\delta}{dr} + 6^2$$

$$\left\{ \begin{array}{l} 6 \frac{d\delta}{dr} = -\frac{g a^2}{r^2} - \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dr} + \frac{4 \mu}{3 b} \frac{d}{dr} \left[ \theta 6 r^2 \left( \frac{d\delta}{dr} - \frac{\delta}{r} \right) \right] \\ \frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{6} \left[ \frac{d\delta}{dr} + \frac{2\delta}{r} \right] = \frac{4 \mu}{3 b} \theta r^2 \left[ \frac{d\delta}{dr} - \frac{\delta}{r} \right]^2 \end{array} \right. \quad \begin{array}{l} \text{I}_a \\ \text{II}_a \end{array}$$

$$\frac{d\delta}{dr} - \frac{\delta}{r} = r \frac{d}{dr} \left( \frac{\delta}{r} \right) = r \frac{d}{dr} \left( \frac{\delta r^2}{r^3} \right)$$

$$\frac{d\delta}{dr} + \frac{2\delta}{r} = \frac{1}{r^2} \frac{d}{dr} (6 r^2)$$



$\phi r^2 = z$ 

$$\frac{\phi^2}{2} = \frac{g a^2}{r} + m - \left(\alpha + \frac{c}{A}\right) \theta + \frac{4\mu}{3b} \theta \phi r^2 \left(\frac{d\phi}{dr} - \frac{\phi}{r}\right) \quad I_b$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{\phi} \left[ \frac{d\phi}{dr} + \frac{2\phi}{r} \right] = \frac{4\mu}{3b} \theta r^2 \left( \frac{d\phi}{dr} - \frac{\phi}{r} \right)^2 \quad II_b$$

$$\phi r^2 = z = \frac{b}{\rho}$$

$$\frac{1}{2} \frac{z^2}{r^4} = \frac{g a^2}{r} + m - \left(\alpha + \frac{c}{A}\right) \theta + \frac{4\mu}{3b} \theta z r \frac{d}{dr} \left( \frac{z}{r^3} \right) \quad I_c$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{z} \frac{dz}{dr} = \frac{4\mu}{3b} \theta r^4 \left[ \frac{d}{dr} \left( \frac{z}{r^3} \right) \right]^2 \quad II_c$$

$$\frac{\phi}{r} = u$$

$$\frac{u^2 r^2}{2} = \frac{g a^2}{r} + m - \left(\alpha + \frac{c}{A}\right) \theta + \frac{4\mu}{3b} \theta r^4 u \frac{du}{dr} \quad I_d$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{u r^3} \frac{d}{dr} (u r^3) = \frac{4\mu}{3b} \theta r^4 \left( \frac{du}{dr} \right)^2 \quad II_d$$

zby  $\frac{d\theta}{dr} > 0$  must by:

$$\frac{3\alpha\theta}{u r} + \frac{\alpha\theta}{u} \frac{du}{dr} \geq \frac{4\mu}{3b} \theta r^4 \left( \frac{du}{dr} \right)^2$$

$$\frac{4\mu\alpha}{3b} \frac{u^2}{r} + \frac{4\mu\alpha}{3b} u \frac{du}{dr} \geq \left( \frac{4\mu}{3b} \right)^2 r^4 u^2 \left( \frac{du}{dr} \right)^2$$

$$\left( \frac{4\mu}{3b} \right)^2 r^4 u \frac{du}{dr} \geq \frac{\alpha}{2} \pm \sqrt{\frac{\alpha^2}{4} + \frac{4\mu\alpha}{b} u^2 r^3}$$

$$\left. \begin{aligned} \frac{g a^2}{r^2} + \frac{m}{r} - \left(\alpha + \frac{c}{A}\right) \frac{\theta}{r} + \frac{4\mu}{3b} \theta r^2 \left( \frac{d\phi}{dr} - \frac{\phi}{r} \right) \frac{\phi}{r} &= 0 \\ \left[ \frac{g a^2}{r^2} + \frac{m}{r} - \left(\alpha + \frac{c}{A}\right) \frac{\theta}{r} \right] \frac{d\phi}{dr} + \frac{4\mu}{3b} \theta r^2 \left( \frac{d\phi}{dr} - \frac{\phi}{r} \right) \frac{d\phi}{dr} &= 0 \end{aligned} \right\}$$

$$\frac{4}{3} \frac{\mu}{b} \theta r^2 \left( \frac{d\theta}{dr} - \frac{\theta}{r} \right) = \frac{d\theta}{dr} \left[ \frac{g a^2}{r \theta} + \frac{m}{\theta} - \left( \alpha + \frac{c}{A} \right) \frac{\theta}{\theta} \right] - \frac{g a^2}{r^2} - \frac{m}{r} + \left( \alpha + \frac{c}{A} \right) \frac{\theta}{r}$$

$$= \frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha \theta}{\theta} \left( \frac{d\theta}{dr} + \frac{2\theta}{r} \right)$$

$$\frac{d\theta}{dr} \left[ \frac{g a^2}{r \theta} + \frac{m}{\theta} \right] - \left[ \frac{g a^2}{r^2} + \frac{m}{r} \right] + \left( \frac{c}{A} - \alpha \right) \frac{\theta}{r} - \left( \frac{c}{A} + 2\alpha \right) \frac{\theta}{\theta} \frac{d\theta}{dr} = \frac{c}{A} \frac{d\theta}{dr}$$

$$\frac{1}{\theta} \left( \frac{g a^2}{r} + m \right) \left( \frac{d\theta}{dr} - \frac{\theta}{r} \right) - \frac{\theta}{\theta} \left( \frac{c}{A} + 2\alpha \right) \left( \frac{d\theta}{dr} - \frac{\theta}{r} \right) - \frac{3\alpha \theta}{r}$$

$$\frac{1}{\theta} \left( \frac{d\theta}{dr} - \frac{\theta}{r} \right) \left[ \frac{g a^2}{r} + m - \left( \frac{c}{A} + 2\alpha \right) \theta \right] = \frac{3\alpha \theta}{r} + \frac{c}{A} \frac{d\theta}{dr}$$

$$\left[ \frac{g a^2}{r} - g a + \left( \alpha + \frac{c}{A} \right) \theta - \left( \alpha + \frac{c}{A} \right) \theta - \alpha \theta \right] = \left[ g a \left( \frac{a}{r} - 1 \right) + \left( \alpha + \frac{c}{A} \right) (\theta - \theta) - \alpha \theta \right]$$

$$I.b): \quad \frac{\theta^2}{2} = g a + m \theta - \left( \alpha + \frac{c}{A} \right) \theta + \frac{4}{3} \frac{\mu}{b} \theta \cdot \theta \cdot a^2 \left( \frac{d\theta}{dr} - \frac{\theta}{r} \right)$$

$$\frac{\theta^2 - \theta_0^2}{2} = g a \underbrace{\left( \frac{a}{r} - 1 \right)}_{< 0} - \underbrace{\left( \alpha + \frac{c}{A} \right) (\theta - \theta_0)}_{> 0} + \underbrace{\frac{4}{3} \frac{\mu}{b} \theta \cdot \theta \cdot a^2 \left( \frac{d\theta}{dr} - \frac{\theta}{r} \right)}_{\varepsilon}$$

$$\frac{4}{3} \frac{\mu}{b} \left\{ \frac{c}{A} \frac{d\theta}{dr} \frac{1}{\theta} + \frac{\alpha}{\theta} \left[ \frac{d\theta}{dr} + \frac{2\theta}{r} \right] \right\} = \left[ \frac{4}{3} \frac{\mu}{b} r \left( \frac{d\theta}{dr} - \frac{\theta}{r} \right) \right]^2$$

$$= \frac{1}{(\theta \theta r)^2} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right]^2$$

$$\frac{4}{3} \frac{\mu}{b} \left\{ \frac{c}{A} \frac{d\theta}{dr} \frac{1}{\theta} + \frac{\alpha}{\theta} \frac{d\theta}{dr} + \frac{2\alpha}{r} \right\} = \uparrow$$

$$\frac{4}{3} \frac{\mu}{b} \frac{d\theta}{dr} = \frac{4}{3} \frac{\mu}{b} \frac{\theta}{r} - \frac{1}{\theta \theta r^2} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right]$$

$$\frac{4}{3} \frac{\mu}{b} \left\{ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{\alpha}{r} + \frac{2\alpha}{r} \right\} = \frac{\alpha}{\theta \theta r^2} \left[ \quad \right] + \frac{1}{(\theta \theta r)^2} \left[ \quad \right]^2$$



Jaka będzie wartość  $\left(\frac{db}{dr} - \frac{c}{r}\right)_{r=a}$ ?

W przybliżeniu:

$$\frac{c}{A} \log \theta + \alpha (\log b + \log r) = \text{const}$$

$$\theta^{\frac{c}{A}} (br)^{\alpha} = \text{const} = \theta_0^{\frac{c}{A}} \left(\frac{b_0}{r_0}\right)^{\alpha}$$

$$\frac{g r^2}{r} + m = \left(\alpha + \frac{c}{A}\right) \theta$$

$$\underline{g a + m = \left(\alpha + \frac{c}{A}\right) \theta_0}$$

$$\left(\frac{db}{dr}\right)_0 = - \frac{g}{\left(\alpha + \frac{c}{A}\right) a}$$

$$\underline{g a \left(\frac{a}{r} - 1\right) = \left(\alpha + \frac{c}{A}\right) (\theta - \theta_0)}$$

$$\frac{2\alpha\theta}{r} + \frac{\alpha\theta}{b} \frac{db}{dr} - \frac{\frac{c}{A} g}{\alpha + \frac{c}{A}} = 0$$

$$\frac{\alpha\theta_0}{b} \frac{db}{dr} = \frac{g}{1 + \frac{\alpha A}{c}} - \frac{2\alpha\theta_0}{a}$$

$$\begin{aligned} \left(\frac{db}{dr} - \frac{b}{r}\right)_0 &= \frac{b}{\alpha\theta_0} \left[ \frac{g}{1 + \frac{\alpha A}{c}} - \frac{2\alpha\theta_0}{a} - \frac{\alpha\theta_0}{a} \right] \\ &= \frac{b}{\alpha\theta_0 \underbrace{\left(1 + \frac{\alpha A}{c}\right)}_{=k}} - \frac{3}{a} \end{aligned}$$

$$\frac{9.8}{1.4 \cdot 270 \cdot 290} - \frac{3}{6,366.200} \gg 0$$

$$\left(\frac{db}{dr}\right)_0 > \left(\frac{b}{r}\right)_0$$

$$\left(\frac{1}{b} \frac{db}{dr}\right)_0 > \left(\frac{1}{r}\right)_0$$

$$\left(\frac{d \log b}{dr}\right)_0 > \left(\frac{1}{r}\right)_0$$

Exprese energii v závislosti na rovině

Již  $\frac{d\phi}{dr}$  stane se  $= \frac{6}{r}$  to:

$$\frac{ga^2}{r} + m - (\alpha + \frac{c}{A})\theta = 0$$

$$ga(\frac{a}{r} - 1) - (\alpha + \frac{c}{A})(\theta - \theta_0) = 0$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{3\alpha}{r} = 0$$

$$ga(1 - \frac{a}{r}) = (\alpha + \frac{c}{A})(\theta - \theta_0)$$

Vždycky nějak  $\theta$  muselo by' mezi minimem a maximem ~~ležet~~ ležet.   
 Jednak zatím  $(\frac{d\phi}{dr} - \frac{6}{r})$  stane se  $= 0$  to musí být nějaký bod:

$$\frac{\alpha}{8} \left( \frac{d\phi}{dr} + \frac{2\phi}{r} \right) = \frac{4\mu}{3b} r^2 \left( \frac{d\phi}{dr} - \frac{6}{r} \right)^2$$

Tam kde  $\frac{d\phi}{dr} = 0$  !

Co ten bod by měl být?

$$\frac{d\phi}{dr} > \frac{6}{r}$$

$$\frac{\alpha}{8} \frac{d\phi}{dr} + \frac{2\alpha}{r} \geq \frac{4\mu}{3b} r^2 \left( \frac{d\phi}{dr} - \frac{6}{r} \right)^2$$

$$\phi = 0$$

$$\frac{\alpha}{2} \frac{d\phi^2}{dr} + \frac{2\alpha\phi^2}{r} \geq \frac{4\mu}{3b} r^2 \left[ \left( \frac{d\phi}{dr} - \frac{6}{r} \right)^2 \right]$$

$$\frac{\alpha}{2} s \frac{ds}{dr} + \frac{2\alpha s^2}{r} \geq \frac{4\mu}{3b} \left[ \frac{1}{4} r^2 \left( \frac{ds}{dr} \right)^2 - r s \frac{ds}{dr} + s^2 \right]$$

$$0 \geq \frac{4\mu}{3b} \left[ \frac{r^2}{4} \left( \frac{ds}{dr} \right)^2 \right] - s \frac{ds}{dr} \left[ \frac{4\mu r}{3b} + \frac{\alpha}{2} \right] + s^2 \left[ \frac{4\mu}{3b} - \frac{2\alpha}{r} \right]$$

$$0 \geq \frac{4\mu}{3b} \frac{1}{4} \left( r \frac{ds}{dr} \right)^2 - r \frac{ds}{dr} s \left[ \frac{4\mu}{3b} + \frac{\alpha}{2r} \right] + s^2 \left[ \frac{4\mu}{3b} - \frac{2\alpha}{r} \right]$$

$$0 \geq \left( \frac{r}{2} \frac{ds}{dr} \right)^2 - 2 \left( \frac{r}{2} \frac{ds}{dr} \right) s \left( 1 + \frac{3b}{4\mu} \frac{\alpha}{2r} \right) + s^2 \left( 1 - \frac{3b}{4\mu} \frac{2\alpha}{r} \right)$$



$$\left[ \frac{r}{2} \frac{ds}{dr} - s \left( 1 + \frac{3b}{4r} \frac{\alpha}{2r} \right) \right]^2 \leq s^2 \left[ \frac{3b}{4r} \frac{\alpha}{2r} + \left( \frac{3b}{4r} \frac{\alpha}{2r} \right)^2 + \frac{3b}{4r} \frac{2\alpha}{2} \right]$$

$$s^2 \frac{3b}{4r} \frac{\alpha}{2} \left( 3 + \frac{3b}{4r} \frac{\alpha}{4r} \right)$$

$$\frac{2\alpha}{r} \left[ \left[ s + \frac{1}{8} \frac{ds}{dr} \right]^2 - \frac{1}{64} \left( \frac{ds}{dr} \right)^2 \right] \geq \frac{4r}{3b} \left[ \frac{r}{2} \frac{ds}{dr} - s \right]^2$$

Jeżeli  $\frac{ds}{dr}$  wzr. w. zmniejsz. wtedy w trójkącie musi być kąt ostry

W przeciwnym przypadku (?)  $\frac{d\theta}{dr}$  wzr. by dłużej  $< 0$

$$\frac{ds}{dr} > \frac{6}{r}$$

~~zatem mógłby być punkt gdzie  $\theta = 0$~~

$$(\theta_0 - \theta) \left( \alpha + \frac{c}{r} \right) = + g^2 \left( 1 - \frac{a}{r} \right) - \frac{4r}{3b} \theta b r^2 \left( \frac{1}{2r} \right)$$

Wzr. mógłby być punkt gdzie  $\theta = 0$  jeżeli 1).  $b$  i  $\frac{ds}{dr}$  stałymi a  $\frac{d\theta}{dr} = 0$   
2).

1). wymagałoby wstąpienia do takiej:  $b \frac{ds}{dr} = -g \frac{a^2}{r^2}$  ! co nie możliwe bo

wówczas rozwiązani byłoby ze  $\frac{ds}{dr} > \frac{6}{r}$



$$\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} + \frac{\alpha}{\theta} \left[ \frac{d\theta}{dr} - \frac{\theta}{r} \right] = \frac{4\mu}{3b} r^2 \left[ \frac{d\theta}{dr} - \frac{\theta}{r} \right]^2$$

$$\frac{4\mu}{3b} r^2 \left[ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right] = \frac{1}{\theta^2} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right] + \left\{ \frac{1}{\theta^2} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right] \right\}^2$$

$$\frac{4\mu}{3b} \theta^2 = \frac{\frac{1}{\theta} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right] + \frac{1}{\theta^2} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right]^2}{\frac{4\mu}{3b} r^2 \left[ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]}$$

$$\left[ \begin{aligned} 0 &= \underbrace{\frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta}_v + r^2 \theta \left[ \frac{1}{2} \frac{d}{dr} \left\{ \frac{\frac{1}{\theta} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right]^2}{r^2 \left[ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]} \right\} - \frac{1}{r} \frac{\frac{1}{\theta} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right]^2}{r^2 \left[ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]} \right] \\ 0 &= v + \frac{r^2 \theta}{2} \frac{d}{dr} \left\{ \frac{\frac{1}{\theta} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right]^2}{r^2 \left[ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]} \right\} - \frac{1}{r} \frac{\frac{1}{\theta} \left[ \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta \right]^2}{r^2 \left[ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]} \end{aligned} \right]$$

$$Id: \quad 0 = \frac{g a^2}{r} + m - \left( \alpha + \frac{c}{A} \right) \theta + \frac{4\mu}{3b} \theta r^4 u \frac{du}{dr} \quad \left| \frac{du}{dr} \right.$$

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{3\alpha\theta}{r} + \frac{\alpha\theta}{u} \frac{du}{dr} = \frac{4\mu}{3b} \theta r^4 \left( \frac{du}{dr} \right)^2 \quad \left| u \right.$$

$$\begin{aligned} \frac{c}{A} \frac{d\theta}{dr} + \frac{3\alpha\theta}{r} &= \frac{c}{A r} \left[ r \frac{d\theta}{dr} + \frac{3\alpha}{\theta} \theta \right] \\ &= \frac{c}{A} \frac{d}{dr} \left( \theta r^{\frac{3\alpha}{A}} \right) \cdot \frac{1}{r^{\frac{3\alpha}{A}}} \end{aligned}$$

$$\begin{aligned} \frac{c}{A} u \frac{d\theta}{dr} + \frac{3\alpha\theta u}{r} &= + \frac{c}{A} \theta \frac{du}{dr} - m \frac{du}{dr} - \frac{g a^2}{r} \frac{du}{dr} \\ \frac{c}{A} \frac{d}{dr} \left( \frac{\theta}{u} \right) + \frac{3\alpha}{r} \frac{\theta}{u} &= - \frac{1}{u} \frac{d}{dr} \left( m + \frac{g a^2}{r} \right) \frac{du}{dr} = 0 \end{aligned}$$



$$0 = v + \frac{4\gamma}{3b} \theta \frac{r^4}{2} \frac{dv}{dr}$$

$$\frac{4\gamma}{3b} \frac{r^2}{2} \frac{dv}{dr} = - \frac{v}{\theta r^2}$$

$$v^2 \left[ \frac{c}{A} \frac{d\theta}{dr} + \frac{3\alpha\theta}{r} \right] + \frac{\alpha\theta}{2} \frac{d(v^2)}{dr} = \frac{4\gamma}{3b} \frac{\theta r^4}{4} \left[ \frac{dv}{dr} \right]^2$$

$$\frac{4\gamma}{3b} v^2 = \frac{1}{\frac{c}{A} \frac{d\theta}{dr} + \frac{3\alpha\theta}{r}} \left( + \frac{v^2}{\theta r^4} + \frac{\alpha}{r^4} \frac{v}{r^4} \right)$$

$$0 = v + \frac{\theta r^4}{2} \frac{d}{dr} \left\{ \frac{\frac{v^2}{\theta} + \alpha v}{r^4 \left[ \frac{c}{A} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]} \right\} \quad \text{to same factor}$$

$$\underbrace{\frac{g\alpha^2}{r\theta} + \frac{m}{\theta} - (\alpha + \frac{c}{A})}_{w} + \frac{r^4}{2} \frac{d}{dr} \left\{ \frac{\left[ \frac{g\alpha^2}{r\theta} + \frac{m}{\theta} - (\alpha + \frac{c}{A}) \right]^2 + \alpha \left[ \right]}{r^4 \left[ \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r} \right]} \right\}$$

$$\frac{1}{r^3} = z$$

$$-\frac{3}{r^4} dr = dz$$

$$\frac{d\theta}{dr} = -\frac{3}{r^4} \frac{d\theta}{dz}$$

$$2w = \frac{3}{r} \frac{d}{dr} \left\{ \frac{w^2 + w\alpha}{-3\frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dr} + \frac{3\alpha}{r}} \right\} = \frac{d}{dz} \left\{ \frac{w^2 + w\alpha}{\frac{\alpha}{r} - \frac{c}{A} \frac{1}{\theta} \frac{d\theta}{dz}} \right\}$$

$$= \frac{d}{dz} \log \left( z^{\alpha} \theta^{\frac{c}{A}} \right)$$

$$\frac{1}{r} = t \quad \frac{g\alpha^2 t + m}{\alpha} = y \quad \frac{dr}{r^2} = -dt$$

$$\frac{y}{\theta} - \frac{k}{k-1} t - \frac{1}{2t^2} \frac{d}{dt} \left\{ \frac{\left( \frac{y}{\theta} - \frac{k}{k-1} \right)^2 + \left( \frac{y}{\theta} - \frac{k}{k-1} \right)}{\frac{3}{t^3} - \frac{1}{k-1} \frac{1}{\theta t^2} \frac{d\theta}{dt}} \right\}$$

$$\frac{1}{\theta} \left( \frac{g\alpha^2}{r} + m \right) = w + \alpha + \frac{c}{A} \quad \frac{1}{\theta} \frac{d\theta}{dr} = \frac{-\frac{g\alpha^2}{r^2} \frac{dr}{dr}}{\frac{g\alpha^2}{r} + m} - \frac{\frac{dr}{dr}}{w + \alpha + \frac{c}{A}}$$

$$\log \left( \frac{g\alpha^2}{r} + m \right) - \log \theta = \log \left( w + \alpha + \frac{c}{A} \right)$$



Uzegljuvage tami tyllbo r I:

$$\frac{c}{A} \frac{d\theta}{dr} + \frac{\alpha}{\delta} \frac{d\delta}{dr} + \frac{2\alpha}{r} = 0$$

$$\log(\theta^{\frac{c}{A}} \delta^{\alpha} r^{2\alpha}) = \text{const}$$

$$\left[\frac{\theta}{\theta_0}\right]^{\frac{c}{A\alpha}} \left(\frac{\delta}{\delta_0}\right) \left(\frac{r}{r_0}\right)^2 = 1$$

$$0 = -\frac{g\alpha^2}{r^2} - \underbrace{\alpha \frac{d\theta}{dr} + \frac{2\alpha\theta}{r} + \frac{\alpha\theta}{\delta} \frac{d\delta}{dr}}_{-(\alpha + \frac{c}{A}) \frac{d\theta}{dr}} + \frac{4\mu}{3b} 6r^2 \left[ \theta \frac{d}{dr} \left( \frac{1\delta}{dr} + \frac{2\delta}{r} \right) + \frac{d\theta}{dr} \left( \frac{1\delta}{dr} - \frac{\delta}{r} \right) \right]$$

$$\frac{c}{A\alpha} = \frac{1}{k-1}$$

$$\frac{\theta}{\theta_0} \left( \frac{6r^2}{\delta_0 a^2} \right)^{\frac{1}{k-1}} = 1$$

$$\frac{\theta}{\theta_0} = \left( \frac{6r^2}{\delta_0 a^2} \right)^{k-1}$$

$$\frac{d\theta}{dr} = \frac{2(1-k)\theta_0}{(\delta_0 a^2)^{k-1}} (6r^2)^{k-1} \frac{d(6r^2)}{dr}$$

$$= 2(1-k) \frac{\theta_0}{\delta_0 a^2} \frac{d(6r^2)}{dr}$$

$$1 + 30\alpha = \frac{0.00367}{1.110.14} \cdot \frac{184}{184}$$

$$\begin{array}{r} 288081 \\ 844 \\ \hline 20368 \end{array}$$

$$10885$$

$$\begin{array}{r} 1.414 \\ 14 \\ \hline 1554 : 184 = 0.844 \\ \hline 828 \end{array}$$

$$\begin{array}{r} 760 \\ 690 \\ \hline 1.111 \\ \hline 1.99455 \\ \hline 0.844 \\ \hline 2.8385 \end{array}$$



~~Problemin skizze:~~

I  ~~$0 = g \frac{a}{n} \sin \theta - (\alpha + \frac{c}{A}) \theta$~~

$$g = -\frac{\alpha k}{k-1} \frac{d\theta}{dx} \quad \parallel \theta = \theta_0 - g x \frac{k-1}{\alpha k}$$

~~$$g a \left( \frac{a}{n} - 1 \right) = \alpha \frac{k}{k-1} \theta$$~~

$$\frac{\theta}{\theta_0} = \left( \frac{\sigma}{\sigma_0} \right)^{1-k} = \left( \frac{\rho}{\rho_0} \right)^{1-k} = \left( \frac{p}{p_0} \right)^{k-1}$$

$$\frac{p}{p_0} = \frac{\theta}{\theta_0} \frac{\rho}{\rho_0} = \left( \frac{\theta}{\theta_0} \right)^{1 + \frac{1}{k-1}} = \left( \frac{\theta}{\theta_0} \right)^{\frac{k}{k-1}}$$

$$g x + m = -(\alpha + \frac{c}{A}) \theta$$

$$\sigma = \sigma_0 \left( \frac{\theta}{\theta_0} \right)^{\frac{1}{1-k}}$$

$$m = -(\alpha + \frac{c}{A}) \theta_0$$

$$\frac{d\sigma}{d\theta} = \frac{\sigma_0}{1-k} \frac{\theta^{\frac{k}{1-k}}}{\theta_0^{\frac{k}{1-k}}} \frac{d\theta}{d\sigma}$$

$$g x = (\alpha + \frac{c}{A}) (\theta_0 - \theta)$$

$$g x = \alpha \frac{k}{k-1} (\theta_0 - \theta) = \alpha \frac{k}{k-1} \theta_0 \left( 1 - \frac{\theta}{\theta_0} \right)$$

$$= \frac{\sigma_0}{\theta_0} \frac{1}{1-k} g \frac{k}{\alpha k} \left( \theta_0 - g x \frac{k-1}{\alpha k} \right)^{\frac{k}{1-k}}$$

$$= \frac{\sigma_0}{\alpha k \theta_0} \frac{1}{1-k} \left( \theta_0 - g x \frac{k-1}{\alpha k} \right)^{\frac{k}{1-k}}$$

$$\frac{d\sigma}{d\theta} = \frac{\sigma_0}{\alpha k \theta_0} \left( 1 - g x \frac{k-1}{\theta_0 \alpha k} \right)^{\frac{k}{1-k}}$$

$$\frac{\theta}{\theta_0} = \frac{1}{5}$$

$$\left( \frac{p}{p_0} \right) = \left( \frac{1}{5} \right)^{\frac{1.4}{0.4}} = \left( \frac{1}{5} \right)^{\frac{7}{2}}$$

$$\theta = 56^\circ \text{ ab.}$$

$$= 217^\circ$$

$$\lg \left( \frac{p}{p_0} \right) = -\frac{7}{2} \lg 5$$

$$0.69897$$

$$489279$$

$$-244680$$

$$= 0.55360 - 3$$

$$\frac{p}{p_0} = 0.003578260$$

$$\mu = \text{ca } 2.5 \text{ mm}$$

Nun aber nach Anmann, Hypsometrie.

$$\text{in ca } 14000 \text{ m : } -650 = 208^\circ$$

$$\Delta = 80^\circ$$

$$\Delta = 140^\circ$$

Wahrscheinlichste Formel mit sollte 140°

$$\frac{7}{2} : x = \frac{7}{14} : 8$$

$$x = \frac{14}{7} = 2 = \frac{k}{k-1}$$

$$\frac{56}{208} = \frac{7}{26}$$

$$\left( \frac{p}{p_0} \right) = \left( \frac{208}{280} \right)^2 \left( \frac{7}{26} \right)^{\frac{7}{2}}$$

$$\begin{array}{r} 41497 \\ 54407 \\ \hline 95904 \\ 004096 \\ \hline 004096 \end{array}$$

$$\begin{array}{r} 84510 \\ 41497 \\ \hline 43013 \\ 54407 \\ \hline 056987 \\ 004096 \\ \hline 004096 \end{array}$$

$$\begin{array}{r} 1.99955 \\ 0.08192 \\ \hline 2.08147 \end{array}$$

7 mm



Krytyczny punkt linii nie wykończy 27 km więc tam g o mierzni 1%,  
 $\approx 1/2 g$ .  
 zmniejszone a b o tyle zwiększone

weźmy równanie wystarczające są porównania przybliżone.

$$I.) \quad \delta \frac{d\delta}{dx} = -g - (\alpha + \frac{c}{A}) \frac{d\theta}{dx} + \frac{4}{3} \theta \left[ \delta \frac{d\delta}{dx} + \theta \left( \frac{d\delta}{dx} \right)^2 \right]$$

$$II.) \quad \frac{\delta^2}{2} = -gx + m - (\alpha + \frac{c}{A}) \theta + \frac{4}{3} \theta \delta \frac{d\delta}{dx} \quad \parallel \quad \left[ \delta \frac{d\delta}{dx} + \left( \frac{d\delta}{dx} \right)^2 \right] \theta + \delta \frac{d\delta}{dx} \frac{d\theta}{dx}$$

$$III.) \quad \frac{c}{A} \frac{d\theta}{dx} \frac{1}{\theta} + \frac{\alpha}{\delta} \frac{d\delta}{dx} = \frac{4}{3} \theta \left( \frac{d\delta}{dx} \right)^2$$

$$\delta \frac{d\delta}{dx} + g - \frac{4}{3} \theta \left[ \delta \frac{d\delta}{dx} + \left( \frac{d\delta}{dx} \right)^2 \right] \theta = \left[ -(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \delta \frac{d\delta}{dx} \right] \frac{d\theta}{dx}$$

$$\frac{1}{\theta} \left[ \delta \frac{d\delta}{dx} + g \right] - \frac{4}{3} \theta \left[ \delta \frac{d\delta}{dx} + \left( \frac{d\delta}{dx} \right)^2 \right] = \left[ -(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \delta \frac{d\delta}{dx} \right] \frac{1}{\theta} \frac{d\theta}{dx}$$

$$= \frac{-(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \delta \frac{d\delta}{dx}}{\frac{\delta^2}{2} + gx - m}$$

$$= \frac{A}{c} \left[ \frac{4}{3} \theta \left( \frac{d\delta}{dx} \right)^2 - \frac{\alpha}{\delta} \frac{d\delta}{dx} \right]$$

$$\left[ -(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \delta \frac{d\delta}{dx} \right] \left[ \delta \frac{d\delta}{dx} + g \right] - \left[ \frac{\delta^2}{2} + gx - m \right] \left[ \delta \frac{d\delta}{dx} + \left( \frac{d\delta}{dx} \right)^2 \right] \frac{4}{3} \theta =$$

$$= \left[ \frac{\delta^2}{2} + gx - m \right] \left[ \frac{4}{3} \theta \left( \frac{d\delta}{dx} \right)^2 - \frac{\alpha}{\delta} \frac{d\delta}{dx} \right] \left[ -(\alpha + \frac{c}{A}) + \frac{4}{3} \theta \delta \frac{d\delta}{dx} \right] \frac{A}{c}$$

$$(p^2 + \frac{a}{2} p q + b p = 0)$$

$$\frac{c}{A} \frac{d\theta}{dx} + \frac{\alpha}{\delta} \frac{d\delta}{dx} = \frac{4}{3} \theta \left( \frac{d\delta}{dx} \right)^2$$

$$\frac{c}{A} \left( \frac{dx}{d\delta} \right)^2 + \frac{\alpha}{\delta} \frac{dx}{d\delta} \frac{d\theta}{d\delta} = \frac{4}{3} \theta \frac{dx}{d\delta} \quad \parallel \quad \frac{c}{A} p^2 + \frac{\alpha}{\delta} p q = \frac{4}{3} \theta q$$



Answer:

$$\frac{c}{A} \delta \frac{d\theta}{dx} + \alpha \theta \frac{d\delta}{dx} = \frac{4}{3} \frac{r_0}{\theta} \delta \left( \frac{d\delta}{dx} \right)^2$$

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$$\frac{c}{A} \frac{d^2\theta}{dx^2} + \frac{d\theta}{dx} \frac{d}{d\theta} \left( \frac{c}{A} \frac{d\theta}{dx} + \alpha \theta \frac{d\delta}{dx} \right) +$$

$$\frac{c}{A} \delta \frac{d^2\theta}{dx^2} + \frac{c}{A} \frac{d\delta}{dx} \frac{d\theta}{dx} + \alpha \frac{d\theta}{dx} \frac{d\delta}{dx} + \alpha \theta \frac{d^2\delta}{dx^2} = \frac{4}{3} \frac{r_0}{\theta} \left[ \frac{d\theta}{dx} \delta \left( \frac{d\delta}{dx} \right)^2 + \theta \left( \frac{d\delta}{dx} \right)^3 + 2\theta \delta \frac{d\delta}{dx} \frac{d\theta}{dx} \right]$$

$$I + III: \delta \frac{d\delta}{dx} = -g - \frac{c}{A} \frac{d\theta}{dx} + \frac{\alpha}{\theta} \frac{d\delta}{dx} + \frac{4}{3} \frac{r_0}{\theta} \left[ \delta \theta \frac{d^2\delta}{dx^2} + \delta \frac{d\delta}{dx} \frac{d\theta}{dx} \right]$$

$$\frac{1}{\theta} \frac{\delta^2}{2} \frac{d\theta}{dx} = \frac{(m-gx)}{\theta} \frac{d\theta}{dx} - \left( \alpha + \frac{c}{A} \right) \frac{d\theta}{dx} + \frac{4}{3} \frac{r_0}{\theta} \delta \frac{d\delta}{dx} \frac{d\theta}{dx}$$

$$\delta \frac{d\delta}{dx} - \frac{\delta^2}{2} \frac{1}{\theta} \frac{d\theta}{dx} = - \frac{(m-gx)}{\theta} \frac{d\theta}{dx} + \frac{c}{A} \frac{d\theta}{dx} - g + \frac{\alpha}{\theta} \frac{d\delta}{dx} + \frac{4}{3} \frac{r_0}{\theta} \delta \theta \frac{d^2\delta}{dx^2}$$

$$- \frac{c}{A} \frac{1}{\theta^2} \left( \frac{d\theta}{dx} \right)^2 + \frac{c}{A} \frac{1}{\theta} \frac{d^2\theta}{dx^2} - \frac{\alpha}{\theta^2} \left( \frac{d\delta}{dx} \right)^2 + \frac{\alpha}{\theta} \frac{d^2\delta}{dx^2} = 2 \frac{4}{3} \frac{r_0}{\theta} \delta \frac{d\delta}{dx} \frac{d\theta}{dx}$$

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$$y \frac{dy}{dx} + X_1 y^2 + X_2 y + X_3 = 0$$

$$\frac{dy}{dx} + X_1 y + X_2 = 0$$

$$y = e^{-\int X_1 dx} \left[ C - \int X_2 e^{\int X_1 dx} dx \right]$$

$$e^{-\int X_1 dx} \left[ C - \int X_2 e^{\int X_1 dx} dx \right] \left[ -X_1 e^{-\int X_1 dx} \left( C - \int X_2 e^{\int X_1 dx} dx \right) - X_2 e^{-\int X_1 dx} + \frac{dC}{dx} e^{-\int X_1 dx} \right] +$$

$$X_1 e^{-\int X_1 dx} \left( C - \int X_2 e^{\int X_1 dx} dx \right) + X_2$$

$$+ X_3 = 0$$

$$\left[ C - \int X_2 e^{\int X_1 dx} dx \right] \frac{dC}{dx} e^{-\int X_1 dx} + X_3 e^{2\int X_1 dx} = 0$$



$$c \frac{dc}{dx} + f_1(x) \frac{dc}{dx} + f_2(x) = 0$$

$$(c + f_1(x)) = y$$

$$\frac{dc}{dx} + f_1'(x) = \frac{dy}{dx}$$

$$c = -\frac{f_2}{\frac{dc}{dx} + f_1'(x)} = -\frac{f_2}{\frac{dc}{dx}} = -f_1 - \frac{f_2}{\frac{dc}{dx}}$$

$$\frac{dc}{dx} = -\frac{df_1}{dx} - \frac{df_2}{dx} + \frac{f_2}{\left(\frac{dc}{dx}\right)} \frac{d^2c}{dx^2}$$

$$\frac{dc}{dx} = p$$

$$f_2 \frac{dp}{dx} = p^3 + \frac{df_1}{dx} p^2 + \frac{df_2}{dx} p$$

$$\frac{d\theta}{dx} = +\frac{6_0}{\theta_0} \frac{1}{1-x} \frac{g}{ak} \left[ \theta_0 - \frac{g x (k-1)}{ak} \right]^{\frac{k}{1-k}}$$

$$= \frac{6_0 g}{ak \theta_0} \left[ 1 - \frac{g x (k-1)}{ak \theta_0} \right]^{\frac{k}{1-k}}$$

(area under plot sec. 1 sec) =

$$y \frac{dy}{dx} + y^2 X_1 + y X_2 + X_3 = 0$$

$$y + u = v$$

$$(y+u) \left( \frac{dy}{dx} + u' \right) + (y+u)^2 X_1 + X = 0$$

$$v \frac{dv}{dx} + v^2 X_1 + X = 0$$

for

$$y \frac{dy}{dx} + u \frac{dy}{dx} + y^2 X_1 + y \underbrace{(u' + 2u X_1)}_{= X_2} + u u' + u^2 X_1 + X = 0$$



znaleźć jako pierwsze przybliżenie:

$$g^x = \alpha \frac{L}{k-1} (\theta_0 - \theta) \quad \frac{d\theta}{dx} = - \frac{g^x}{\alpha k} \frac{1}{\theta_0 - \theta}$$

$$\theta = \theta_0 \left( \frac{x}{L} \right)^{\frac{1}{1-k}}$$

$$\frac{d\theta}{dx} = \frac{g \theta_0}{\alpha k \theta_0} \left( 1 - \frac{g^x}{\theta_0 \alpha k} \right)^{\frac{k}{1-k}}$$

$$= \frac{g L}{k \theta_0} \left[ 1 - \frac{g^x (k-1)}{\theta_0 \alpha k} \right]^{\frac{k}{1-k}}$$

$$= \frac{4}{3} \mu \left( \frac{d\theta}{dx} \right)^L = \left( \frac{g L}{k \theta_0} \right)^2 \left[ 1 - \frac{g^x (k-1)}{\theta_0 \alpha k} \right]^{\frac{2k}{1-k}} \frac{4}{3} \mu$$

$$\int_0^x \left[ 1 - \frac{g^x (k-1)}{\theta_0 \alpha k} \right]^{\frac{2k}{1-k}} dx = \frac{\theta}{\theta_0}$$

$$= - \int_{\theta_0}^{\theta} \left( \frac{\theta}{\theta_0} \right)^{\frac{2k}{1-k}} \frac{\alpha k}{g^{k-1}} d\theta = - \frac{\alpha k}{g^{k-1} \theta_0^{\frac{2k}{1-k}}} \frac{1}{\frac{2k}{1-k} + 1} \theta^{\frac{2k}{1-k} + 1}$$

$$= + \frac{\alpha k}{g^{k-1} (1+k)} \left[ \left( \frac{\theta}{\theta_0} \right)^{\frac{2k}{1-k} + 1} - 1 \right] = \frac{4}{3} \mu \frac{g}{k (1+k)} \frac{1}{\theta_0 \theta_0} \left[ \left( \frac{\theta}{\theta_0} \right)^{\frac{1+k}{1-k}} - 1 \right]$$

$$= \frac{4}{3} \mu \frac{\alpha}{1+k} \frac{g L}{k \theta_0^2} \theta_0 \left[ \left( \frac{\theta}{\theta_0} \right)^{\frac{1+k}{1-k}} - 1 \right] = \frac{4}{3} \mu \frac{g}{k (1+k)} \frac{1}{\theta_0 \theta_0} \left[ \left( \frac{\theta}{\theta_0} \right)^{\frac{1+k}{1-k}} - 1 \right]$$

$$g \theta_0 = 0.00018 \text{ (gram)}$$

$$g = 980$$

$$\rho_0 = 0.0013$$

$$\rho_0 = 980.76 \cdot 13.6$$

$$\frac{L}{g} = \frac{0.00018}{980} \cdot \frac{1}{0.0013} \cdot \frac{1}{1.4 \cdot 2.4} = 4.4$$

$$\frac{24}{336} = \frac{1008}{427}$$

$$\text{w. } L = 10 \text{ cm}$$

$$\frac{0.0006}{200}$$

$$\text{w. } \frac{\theta}{\theta_0} = \frac{1}{5} \quad \left( \frac{1}{5} \right)^6 = \frac{(125)^2}{250} = \frac{15000}{15000}$$

$$\frac{0.0003}{150} = 0.0045$$

$$\log 2^{0.0045} = \frac{0.42426 \cdot 0.0045}{21713.9}$$

$$0.0195397$$

$$2^{0.0045} = 1.046$$



$$\frac{6^2}{2} = -g + m - \left(\alpha + \frac{c}{A}\right)\theta + \frac{4}{3}\theta \left(6 \frac{d\theta}{dx}\right) \quad \left| 2\theta \frac{d\theta}{dx} = \frac{4}{3}\theta \left(\alpha + \frac{c}{A}\right) \frac{d\theta}{dx} + \frac{4}{3}\theta \frac{d}{dx} \left(\theta \frac{d\theta}{dx}\right) \right.$$

$$\frac{c}{A} 6^2 \frac{d\theta}{dx} + \alpha \theta 6 \frac{d\theta}{dx} = \frac{4}{3}\theta \left(6 \frac{d\theta}{dx}\right)^2$$

$$\left(\alpha + \frac{c}{A}\right) = \alpha \left(1 + \frac{1}{k-1}\right) = \frac{\alpha k}{k-1}$$

$$m = \left(\alpha + \frac{c}{A}\right)\theta_0 + \frac{6_0^2}{2} - \frac{4}{3}\theta_0 \left(6 \frac{d\theta}{dx}\right)_0$$

$$6^2 = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$$

$$\frac{\theta}{\theta_0} = b_0 + b_1 x + b_2 x^2 + b_3 x^3 + \dots$$

$$2\theta \frac{d\theta}{dx} = a_1 + 2a_2 x + 3a_3 x^2 + 4a_4 x^3 + 5a_5 x^4 + \dots$$

$$\frac{2\theta}{\theta_0} \frac{d\theta}{dx} =$$

$$a_1 b_0$$

$$+ (a_1 b_1 + 2a_2 b_0)x$$

$$+ (a_1 b_2 + 2a_2 b_1 + 3a_3 b_0)x^2$$

$$+ (a_1 b_3 + 2a_2 b_2 + 3a_3 b_1 + 4a_4 b_0)x^3$$

$$+ (a_1 b_4 + 2a_2 b_3 + 3a_3 b_2 + 4a_4 b_1 + 5a_5 b_0)x^4$$

$$+$$



$$\frac{26df}{dx} + 2g + \frac{2\alpha k}{k-1} \frac{d\theta}{dx} + \frac{4}{3} \frac{d}{dx} \left( \theta \frac{26df}{dx} \right)$$

$$\left. \begin{aligned} & a_1 + 2g + \frac{2\alpha k}{k-1} \theta_0 b_1 + \left( \frac{4}{3} \frac{d}{dx} \right) (a_1 b_1 + 2a_2 b_0) \theta_0 = 0 \\ x & \quad 4a_2 + \frac{2\alpha k}{k-1} \theta_0 b_2 + \frac{4}{3} \frac{d}{dx} (a_1 b_2 + 2a_2 b_1 + 3a_3 b_0) \theta_0 = 0 \\ x^2 & \quad 4a_3 + \frac{2\alpha k}{k-1} \theta_0 b_3 + \frac{4}{3} \frac{d}{dx} (a_1 b_3 + 2a_2 b_2 + 3a_3 b_1 + 4a_4 b_0) \theta_0 = 0 \\ x^3 & \quad 4a_4 + \frac{2\alpha k}{k-1} \theta_0 b_4 + \frac{4}{3} \frac{d}{dx} (a_1 b_4 + 2a_2 b_3 + 3a_3 b_2 + 4a_4 b_1 + 5a_5 b_0) \theta_0 = 0 \end{aligned} \right\}$$

$$\frac{\alpha}{k-1} a_0 b_1 + \frac{\alpha}{2} a_1 b_0 = \frac{4}{3} \frac{d}{dx} \frac{b_0 a_1^2}{4}$$

$$\frac{\alpha}{k-1} (2a_0 b_2 + a_1 b_1) + \frac{\alpha}{2} (2a_2 b_0 + a_1 b_1) = \frac{4}{3} \frac{d}{dx} \frac{1}{4} (b_0 (4a_1 a_2) + b_1 a_1^2)$$

$$\frac{\alpha}{k-1} (3a_0 b_3 + 2a_1 b_2 + a_2 b_1) + \frac{\alpha}{2} (3a_3 b_0 + 2a_2 b_1 + a_1 b_2) = \frac{4}{3} \frac{d}{dx} \frac{1}{4} [b_0 (6a_1 a_3 + 4a_2^2) + b_1 (4a_1 a_2 + b_2 a_1^2)]$$

$$\begin{aligned} & \frac{\alpha}{k-1} (4a_0 b_4 + 3a_1 b_3 + 2a_2 b_2 + a_3 b_1) + \frac{\alpha}{2} (4a_4 b_0 + 3a_3 b_1 + 2a_2 b_2 + a_1 b_3) = \\ & = \frac{4}{3} \frac{d}{dx} \frac{1}{4} [b_0 (8a_1 a_4 + 12a_2 a_3) + b_1 (6a_1 a_3 + 4a_2^2) + b_2 (4a_1 a_2 + b_3 a_1^2)] \end{aligned}$$

Jokin jost  $\frac{d^2\theta}{dx^2}$  v kytämyksen punkti?

$\frac{dI}{dx}$ :

$$\frac{d}{dx}\left(6\frac{d\delta}{dx}\right) = \left(\frac{d\delta}{dx}\right)' + 6\frac{d^2\delta}{dx^2} = -\left(\alpha + \frac{c}{A}\right)\frac{d^2\theta}{dx^2} + \frac{4}{3}k_b\left\{\left[6\frac{d^2\delta}{dx^2} + \left(\frac{d\delta}{dx}\right)'\right]\frac{d\theta}{dx} + \theta\frac{d}{dx}\left[6\frac{d^2\delta}{dx^2} + \left(\frac{d\delta}{dx}\right)'\right]\right\}$$

$$0 =$$

$$\frac{4}{3}k_b 6\frac{d\delta}{dx} = \alpha$$

$$\frac{c}{A}\frac{d^2\theta}{dx^2} = \frac{4}{3}k_b\theta\frac{d}{dx}\left[6\frac{d^2\delta}{dx^2} + \left(\frac{d\delta}{dx}\right)'\right]$$

$$g = \frac{4}{3}k_b\theta\left[\left(\frac{d\delta}{dx}\right)' + 6\frac{d^2\delta}{dx^2}\right]$$

$$\frac{4}{3}k_b g^2 = \frac{\alpha^2}{\theta} + \left(\frac{4}{3}k_b\right)\theta^3\frac{d\delta}{dx^2} \quad \text{II} \quad 2(I)$$

$$\times \left(\frac{4}{3}k_b\right)^2 \theta^3$$

$$\frac{c}{A}6\frac{d^2\theta}{dx^2} + \frac{c}{A}\frac{d\delta}{dx}\frac{d\theta}{dx} + \alpha\frac{d\delta}{dx}\frac{d\theta}{dx} + \alpha\theta\frac{d^2\delta}{dx^2} = \frac{4}{3}k_b\left[\frac{d\theta}{dx}6\left(\frac{d\delta}{dx}\right)' + \theta\left(\frac{d\delta}{dx}\right)'\right] + 2\theta6\frac{d\delta}{dx}\frac{d^2\delta}{dx^2}$$

$$\frac{c}{A}6\frac{d^2\theta}{dx^2} \frac{4}{3}k_b\theta^3 + \left[\frac{4}{3}k_b\theta g^2 - \alpha^2\theta\right] = \theta\frac{\alpha^3}{\theta} + \theta\alpha\left(\frac{4}{3}k_b g^2 - \alpha^2\theta\right)$$

$$\frac{c}{A}6\frac{d^2\theta}{dx^2} \frac{4}{3}k_b\theta^3 = \frac{4}{3}k_b g^2 \alpha$$

$$\left[\frac{d^2\theta}{dx^2} = \frac{g\alpha}{\frac{c}{A}\theta^3}\right]$$

> 0



Imy spódt wzimzde k szere:

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$$p = \frac{1}{s} = \frac{1}{u} \frac{du}{dz}$$

$$dz = \frac{1}{u} du$$

$$y = \frac{e^2}{k-1}$$

$$\beta = \frac{e^2}{\alpha u} = \frac{k-1}{\alpha} \frac{y}{u}$$

$$\frac{dp}{du} = -\frac{1}{s^2} \frac{ds}{du}$$

$$-(k+u)(1+u)u \frac{1}{s^3} \frac{ds}{du} - \frac{1}{s^2} [4u^2 - u(1+k) - 2k] + \frac{1}{s} [u^2 + 4u + 3k] + u^2 + ku - u - k = 0$$

$$(k+u)(1+u)u \frac{ds}{du} + [4u^2 - u(1+k) - 2k]s - [u^2 + 4u + 3k]s^2 - [u^2 + ku - u - k]s^3 = 0$$

$$s = a_0 + a_1 u + a_2 u^2 + a_3 u^3 + a_4 u^4 + \dots$$

$$-2ka_0 - 3ka_0^2 + ka_0^3 = 0$$

$$ka_0 [2 + 3a_0 - a_0^2] = 0$$





Zadanie catkine oznaczone jzisto dane

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$\theta_0$   $p_0$   $p_1$

$$p_0 = \alpha \theta_0 p_0 = \alpha \theta_0 \frac{b}{\theta_0}$$

$$p_1 = \alpha \frac{\theta_1}{\theta_0} b$$

ale 4 niewiadome stat.  $\theta_0$   $\theta_1$   $b$   $m$ ?

$\theta$	$\theta$	$\theta$	$\theta$	$\theta$	$\theta$
$\theta$	$\theta$	$\theta$	$\theta$	$\theta$	$\theta$
$\theta$	$\theta$	$\theta$	$\theta$	$\theta$	$\theta$
$\theta$	$\theta$	$\theta$	$\theta$	$\theta$	$\theta$

$$p = \alpha \theta b = \frac{\alpha \theta b}{\theta} \quad \left\| \quad \frac{dp}{dx} = \alpha b \left[ \frac{1}{\theta} \frac{d\theta}{dx} - \frac{\theta}{\theta^2} \frac{d\theta}{dx} \right]$$

$$= \alpha b \frac{1}{\sqrt{v}} \left[ \frac{d\theta}{dx} - \frac{\theta}{2} \frac{dv}{dx} \right]$$

$$\log p = \log \alpha b + \log \theta - \log \theta$$

$$\frac{1}{p} \frac{dp}{dx} = \frac{1}{\theta} \frac{d\theta}{dx} - \frac{1}{2v} \frac{dv}{dx}$$

$$v = a_0 + a_1 x + a_2 x^2 + a_3 x^3 + \dots$$

$$\frac{1}{\sqrt{v}} = v^{-\frac{1}{2}} =$$

$$\log p = A \log \frac{\theta}{\theta}$$

$$p - p_0 = \int_0^\theta \alpha b \left[ \frac{1}{\sqrt{v}} \frac{d\theta}{dx} - \frac{\theta}{2} \frac{dv}{dx} \right] = f_1(\theta_0 v_0 b m)$$

$$p_0 + \int_0^\theta = \frac{\alpha \theta b}{\theta}$$

$$\frac{p_0}{\alpha b} + \underbrace{\int_0^\theta \left[ \frac{1}{\sqrt{v}} \frac{d\theta}{dx} - \frac{\theta}{2} \frac{dv}{dx} \right]}_{\frac{\theta}{\theta} - \frac{\theta_0}{\theta_0}} = \frac{\theta}{\theta}$$

$$\frac{p_0}{\alpha b} = \frac{\theta_0}{\theta_0}$$



Terminierung nichtad:

$$\rho = \frac{b}{\theta}$$

$$0 = -g + \alpha \theta \frac{1}{\theta} \frac{db}{dx} + \frac{4}{3} \frac{1}{b} \theta \frac{dx}{dx}$$

$$\frac{1}{\theta} \frac{d\theta}{dx} + \frac{1}{b} \frac{db}{dx} = 0$$

by nie wystawiaj polanie  $\rightarrow$  warunki  
druch mój siod 2

treboby podać  $b, b_2, p_1$

$$p = \alpha \theta p$$

$$p_1 u_1 \frac{du_1}{dx} + \frac{dp_1}{dx} + p_1 g + \alpha p_1 p_2 (u_1 - u_2) = 0$$

$$p_2 u_2 \frac{du_2}{dx} + \frac{dp_2}{dx} + p_2 g + \alpha p_1 p_2 (u_2 - u_1) = 0$$

$$\alpha_1 \theta \frac{1}{p_1} \frac{dp_1}{dx} + g + \alpha p_2 (u_1 - u_2) = 0$$

$$\alpha_2 \theta \frac{1}{p_2} \frac{dp_2}{dx} + g + \alpha p_1 (u_2 - u_1) = 0$$

$$p_1 = \alpha_1 p_1 \theta \quad \frac{dp_1}{dx} = \alpha_1 \theta \frac{dp_1}{dx} \text{ (jakiś błąd)}$$

$$p_2 = \alpha_2 p_2 \theta$$

$$\frac{d}{dx} (p_1 + p_2) + (p_1 + p_2) g = 0$$

$$\left[ \alpha_1 \theta \frac{dp_1}{dx} + p_1 g \right] = - \left[ \alpha_2 \theta \frac{dp_2}{dx} + p_2 g \right]$$

$$\left( \frac{u_{10}}{p_{10}} + \frac{u_{20}}{p_{20}} \right) \frac{dp_0}{dx} = p_1 u_1 + p_2 u_2$$

$$\alpha_2 p_2 u_2 + \alpha_1 p_1 u_1$$

$$\text{Für } x=0: u_1 = u_2 = u_0$$

$$\frac{d}{dx} (p_1 u_1) = 0$$

$$\frac{d}{dx} (p_2 u_2) = 0$$

$$u_1 = u + v$$

$$p_2 u_2 = c_2$$

$$p_1 u_1 = c_1$$

$$p_1 u + p_2 u = c_1 = p_{10} u_0$$

$$p_2 u + p_2 v = c_2 = p_{20} u_0$$

$$\frac{p_{10}}{p_{20}} = \frac{c_1}{c_2}$$

$$\frac{p_1}{p_2} = \frac{c_1}{c_2} \frac{u_2}{u_1}$$

$$\alpha_1 \theta \frac{dp_1}{dx} + p_1 g + \alpha (c_1 p_2 - c_2 p_1) = 0$$

$$\alpha_2 \theta \frac{dp_2}{dx} + p_2 g + \alpha (c_2 p_1 - c_1 p_2) = 0$$

$$p_1 p_2 (u_1 - u_2) = c_1 p_2 - c_2 p_1 = p_2 c_1 \left[ 1 - \frac{c_2}{c_1} \frac{p_1}{p_2} \right]$$

$$c_1 = p_{10} u$$

$$c_2 = p_{20} u$$

$$= p_{20} c_1 \left[ 1 - \frac{p_{20}}{p_{10}} \frac{p_1}{p_2} \right]$$

$$= p_{10} c_1 \left[ \frac{p_2}{p_1} - \frac{p_{20}}{p_{10}} \right]$$



$$\alpha_1 \theta \frac{d\rho_1}{dr} + (g + ac_1) \frac{d\rho_1}{dr} + \alpha_1 \frac{d\rho_1}{dr} = 0 \quad \alpha_1 \rho_2 = -\alpha_1 \theta \frac{d\rho_1}{dr} - \rho_1 (g + ac_1)$$

$$\alpha_2 \theta \frac{d\rho_2}{dr} = -(g + ac_1) \rho_2 - ac_2 \rho_1$$

$$= \left( \frac{g + ac_1}{ac_1} \right) \left[ \rho_1 (g + ac_1) - \alpha_1 \theta \frac{d\rho_1}{dr} \right] - ac_2 \rho_1$$

$$\alpha_1 \alpha_2 \theta^2 \frac{d^2 \rho_1}{dr^2} + \alpha_2 \theta (g + ac_1) \frac{d\rho_1}{dr} + \left( \frac{g + ac_1}{ac_1} \right) \left[ \rho_1 (g + ac_1) - \alpha_1 \theta \frac{d\rho_1}{dr} \right] - ac_2 \rho_1 = 0$$

$$\alpha_1 \alpha_2 \theta^2 \frac{d^2 \rho_1}{dr^2} + [\alpha_2 (g + ac_1) + \alpha_1 (g + ac_1)] \theta \frac{d\rho_1}{dr} + [(g + ac_1)(g + ac_1) - ac_2 \rho_1] \rho_1 = 0$$

$$\rho_1 = \frac{A_1 e^{-\beta r}}{1 + B e^{\gamma r}}$$

$$\alpha_1 \alpha_2 \theta^2 \beta^2 - [\alpha_2 (g + ac_1) + \alpha_1 (g + ac_1)] \theta \beta + (g + ac_1)(g + ac_1) - ac_2 \rho_1 = 0$$

$$[\alpha_1 \theta \beta - (g + ac_1)] [\alpha_2 \theta \beta - (g + ac_1)] = ac_2 \rho_1 = \frac{ac_2 \rho_1 - (g + ac_1)(g + ac_1)}{\alpha_1 \alpha_2}$$

$$(\theta \beta)^2 - \left[ \frac{g + ac_1}{\alpha_1} + \frac{g + ac_1}{\alpha_2} \right] \theta \beta + \frac{(g + ac_1)(g + ac_1)}{\alpha_1 \alpha_2} = \frac{ac_2 \rho_1}{\alpha_1 \alpha_2}$$

$$\theta \beta = + \frac{g + ac_1}{2\alpha_1} + \frac{g + ac_1}{2\alpha_2} \pm \sqrt{\frac{(g + ac_1)(g + ac_1)}{2\alpha_1 \alpha_2} + \frac{ac_2 \rho_1}{\alpha_1 \alpha_2}}$$

$$\alpha_1 \alpha_2 \theta^2 \beta^2 - g(\alpha_1 + \alpha_2) \theta \beta + g^2 = 0$$

$$\theta \beta = \frac{g}{\alpha_1}$$

$$(\alpha_1 \theta \beta - g)(\alpha_2 \theta \beta - g) = 0$$

$$\theta \beta = \frac{g}{\alpha_2}$$

$$- \frac{1}{2} \alpha_1 \alpha_2 (g + ac_1)(g + ac_1) + \frac{1}{2} ac_2 \rho_1 \alpha_1 \alpha_2 + \alpha_1^2 (g + ac_1)^2 + \alpha_2^2 (g + ac_1)^2$$

$$- 2\alpha_1 \alpha_2 g^2 + 2\alpha_1 \alpha_2 g(ac_1 + ac_2) + 2\alpha_1 \alpha_2 ac_2 \rho_1 + \alpha_1^2 g^2 + 2\alpha_1^2 g ac_1 + \alpha_1^2 ac_2^2$$

$$= \frac{g^2(\alpha_1 - \alpha_2)^2}{2\alpha_1} + 2ga(\alpha_1^2 c_1 + \alpha_2^2 c_2 - 2\alpha_1 \alpha_2 c_1 - 2\alpha_1 \alpha_2 c_2) + a^2(\alpha_1^2 c_1^2 + \alpha_2^2 c_2^2)$$



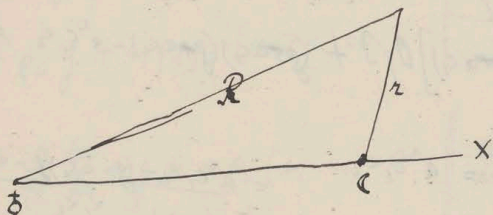
Isotermiczny rozkład dwóch gazów <sup>u.p.</sup> między sobą i pojem. ~~pojem.~~

$$u = u_1 = 0$$

$$\left. \begin{aligned} \frac{\partial p_1}{\partial x} &= p_1 X_1 & \frac{\partial p_2}{\partial x} &= p_2 X_2 \\ \frac{\partial p_1}{\partial y} &= p_1 Y_1 & \frac{\partial p_2}{\partial y} &= p_2 Y_2 \\ \frac{\partial p_1}{\partial z} &= p_1 Z_1 & \frac{\partial p_2}{\partial z} &= p_2 Z_2 \end{aligned} \right\} \frac{\partial p_1}{\partial x} = p_1 \frac{F_1}{F_2} \rightarrow \frac{\partial p_2}{\partial x} = p_2 \frac{F_2}{F_2}$$

$$X_1 = X_2 = \frac{k M}{R} \frac{\partial u}{\partial x}$$

etc.



$$\int \frac{1}{p_1} dp_1 = u = \int \frac{1}{p_2} dp_2$$

$$u = \frac{k M}{R} + \frac{k m}{z}$$

$$p_1 = \alpha_1 p_1 \theta$$

$$p_2 = \alpha_2 p_2 \theta$$

$$\log p_1 = \log \alpha_1 \theta + \log p_1$$

$$u = \alpha_1 \theta \log p_1 + \text{const} = \alpha_2 \theta \log p_2 + \text{const} = \frac{k M}{R} + \frac{k m}{z}$$

$$\alpha_1 \theta \log p_1 + \text{const} = \alpha_2 \theta \log p_2 + \text{const} =$$

$$\alpha_1 \theta \log p_{10} + \text{const} = \frac{k M}{A}$$

$$\alpha_1 \theta \log \frac{p_1}{p_{10}} = \left[ \frac{k M}{R} + \frac{k m}{z} - \frac{k M}{A} \right] \quad \left| \quad \alpha_2 \theta \log \frac{p_2}{p_{20}} = \left[ \dots \right] \right.$$



$$\alpha_1 \lg \frac{p_1}{p_{10}} = \alpha_2 \lg \frac{p_2}{p_{20}}$$

$$\left( \frac{p_1}{p_{10}} \right)^{\alpha_1} = \left( \frac{p_2}{p_{20}} \right)^{\alpha_2}$$

$$\frac{p_1}{p_{10}} = \left( \frac{p_2}{p_{20}} \right)^{\frac{\alpha_2}{\alpha_1}}$$

$$\frac{p_1}{p_2} = \frac{p_{10}}{p_{20}^{\frac{\alpha_2}{\alpha_1}}} p_2^{\left( \frac{\alpha_2}{\alpha_1} - 1 \right)}$$

Wzr. ihy stromkova je ston

davch je to byle nixmoma,  $\frac{\alpha_2}{\alpha_1} - 1$  nixstobylol  $= 0$ , wzr.  $\alpha_1 = \alpha_2$

Inacz je je ston na wzkrse d n.p.  $\alpha_2 > \alpha_1$

ly nie moe stromkova ~~wzkrse~~ <sup>nixkrse</sup> co' nixmi parajelne tam je nie p just

wzkrse n.p. wodre <sup>nixkrse</sup> ~~wzkrse~~ u blizkoni

$$6 \frac{ds}{dr} = -\left(2s \frac{c}{A}\right) \frac{dt}{dr} + \frac{4}{3} \frac{dt}{dr} \left[ 6r^2 \left( \frac{ds}{dr} - \frac{s}{r} \right) \right]$$

$$\frac{c}{A} \frac{dt}{dr} + \frac{2s}{6} \left[ \frac{ds}{dr} + \frac{2s}{r} \right] = \frac{4}{3} \frac{dt}{dr} 6r^2 \left[ \frac{ds}{dr} - \frac{s}{r} \right]^2$$

Let's motivate  $\frac{dt}{dr} = 0$  ?

$$6 \frac{ds}{dr} = \frac{4}{3} \frac{dt}{dr} \left\{ \left[ \frac{d}{dr}(6r^2) \right] \left( \frac{ds}{dr} - \frac{s}{r} \right) \right\} + 6r^2 \left[ \frac{ds}{dr} - \frac{s}{r} \right]^2$$

$$\frac{dt}{dr} \left[ \frac{ds}{dr} + \frac{2s}{r} \right] = \frac{4}{3} \frac{dt}{dr} 6r^2 \left[ \frac{ds}{dr} - \frac{s}{r} \right]^2$$

$$= \frac{1}{r^2} \frac{d}{dr}(6r^2)$$

$$\frac{d}{dr}(6r^2) = \frac{4}{3} \frac{dt}{dr} 6r^2 \left[ \frac{ds}{dr} - \frac{s}{r} \right]^2$$

Just to remember  $6 \frac{ds}{dr}$ :

$$\frac{d}{dr}(6r^2) + \frac{\frac{d}{dr} \left( \frac{ds}{dr} - \frac{s}{r} \right)}{\frac{ds}{dr} - \frac{s}{r}} = 0$$

$$\frac{d}{dr}(6r^2) = \frac{4}{3} \frac{dt}{dr} r^2 \left[ \frac{ds}{dr} - \frac{s}{r} \right]^2$$

$$\frac{4}{3} \frac{dt}{dr} r^2 + \frac{\frac{d}{dr} \left( \frac{ds}{dr} - \frac{s}{r} \right)}{\left( \frac{ds}{dr} - \frac{s}{r} \right)^3} = 0$$

$$= -\frac{1}{2} \frac{d}{dr} \frac{1}{\left( \frac{ds}{dr} - \frac{s}{r} \right)^2}$$

$$\frac{4}{3} \frac{dt}{dr} r^3 = \frac{1}{\left( \frac{ds}{dr} - \frac{s}{r} \right)^2}$$

$$\frac{ds}{dr} - \frac{s}{r} = \sqrt{\frac{3 \alpha k}{4 \mu}} r^{-\frac{3}{2}}$$

$$\frac{d}{dr} \left( \frac{s}{r} \right) = A r^{-\frac{5}{2}}$$

$$\frac{s}{r} = -\frac{3}{2} A r^{-\frac{3}{2}} + \text{const}$$

$$s = -\frac{3}{2} A r^{-\frac{1}{2}} + r \alpha$$



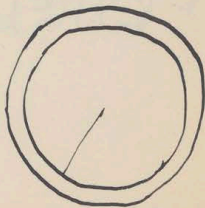
Bestimmung eines guten Kristalls: nicht möglich

$\theta = \text{unver}$

$$r = \alpha \rho \theta$$

$$\rho = f(r, \alpha)$$

$$R = -\frac{1}{r} \int_0^r \rho^2 dr = -\frac{1}{r} \int_0^r f(r, \alpha) dr$$



$$R = \frac{1}{\rho} \frac{d\rho}{dr}$$

$$-\frac{1}{r} \int_0^r \rho^2 dr = \frac{1}{\rho} \alpha \theta \frac{d\rho}{dr}$$

$$-k \rho^2 = \alpha \theta \frac{d}{dr} \left( r^2 \frac{\rho}{dr} \right)$$

$$-\frac{k}{2} r^2 \rho = \frac{1}{2} \frac{d}{dr} \left( r^2 \frac{\rho}{dr} \right) - \frac{1}{2} \frac{d}{dr} \left( r^2 \frac{\rho}{dr} \right) + \frac{1}{2} \frac{d}{dr} \left( r^2 \frac{\rho}{dr} \right)$$

$$E_{gr} = \int_0^r \rho^2 dr$$

$$= \int_0^r k r^2 \int_0^r \frac{1}{r^2} \frac{d\rho}{dr} \int_0^r \rho^2 dr$$

$$= k r^2 \int_0^r \rho^2 dr = k r^2 \int_0^r \rho^2 dr$$

$$F_r = \int_0^r \rho^2 dr = \int_0^r \rho^2 dr = \int_0^r \rho^2 dr$$

$$E_1 + E_{gr} = \theta \left[ -\alpha \rho^2 \frac{1}{r} + (3\alpha - c) \int_0^r \rho^2 dr \right] = \theta \left[ \alpha r \rho^2 \frac{1}{r} + (3\alpha - c) M \right]$$

$$I = \int \left[ u \frac{\partial u}{\partial t} + v \frac{\partial v}{\partial t} + w \frac{\partial w}{\partial t} - (uX + vY + wZ) + c \frac{\partial \phi}{\partial t} \right] du +$$

$$dS = \int \left( \rho_{xx} \cos \alpha + \rho_{xy} \cos \beta + \rho_{xz} \cos \gamma \right) dS$$

$$= \int \left( \rho_{xx} \cos \alpha + \rho_{xy} \cos \beta + \rho_{xz} \cos \gamma \right) dS$$

$$= \int \left( \rho_{xx} \cos \alpha + \rho_{xy} \cos \beta + \rho_{xz} \cos \gamma \right) dS$$

$$= \int \left( \rho_{xx} \cos \alpha + \rho_{xy} \cos \beta + \rho_{xz} \cos \gamma \right) dS$$

$$= \int \left( \rho_{xx} \cos \alpha + \rho_{xy} \cos \beta + \rho_{xz} \cos \gamma \right) dS$$

$$= \int \left( \rho_{xx} \cos \alpha + \rho_{xy} \cos \beta + \rho_{xz} \cos \gamma \right) dS$$

$$= \int \left( \rho_{xx} \cos \alpha + \rho_{xy} \cos \beta + \rho_{xz} \cos \gamma \right) dS$$

$$= \int \left( \rho_{xx} \cos \alpha + \rho_{xy} \cos \beta + \rho_{xz} \cos \gamma \right) dS$$

$$= \int \left( \rho_{xx} \cos \alpha + \rho_{xy} \cos \beta + \rho_{xz} \cos \gamma \right) dS$$



$$e^{\frac{x}{\theta}} \frac{\partial}{\partial \theta} + \frac{x}{\theta} \frac{\partial}{\partial x} = \frac{x}{\theta} \frac{\partial}{\partial x} + \frac{x}{\theta} \frac{\partial}{\partial \theta}$$

$$e^{\frac{x}{\theta}} \frac{\partial}{\partial \theta} + \frac{x}{\theta} \frac{\partial}{\partial x} = \frac{x}{\theta} \frac{\partial}{\partial x} + \frac{x}{\theta} \frac{\partial}{\partial \theta}$$

$$-\frac{3}{2} \sqrt{x} \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right)$$

$$\frac{\partial}{\partial \theta} = \frac{x}{\theta} \frac{\partial}{\partial x}$$

$$\theta p = k$$

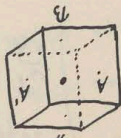
$$= 2 \sqrt{x} \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) + \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) + \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) + \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right)$$

$$+ \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

$$+ \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial x} + \frac{\partial}{\partial y} + \frac{\partial}{\partial x} + \frac{\partial}{\partial y}$$

$$A_{\text{ext}} = \int -4.6 \, ds - \frac{3}{2} \sqrt{x} \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) - \frac{3}{2} \sqrt{x} \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) + \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right) + \left( \frac{\partial}{\partial x} + \frac{\partial}{\partial y} \right)$$





depth of the cut =  $n \Delta t$ ,  $v \Delta t$ ,  $v \Delta t$

both of point A:  $u(x - \frac{\delta}{2})_{y,z}$   $\Delta t$ ,  $v(x - \frac{\delta}{2})_{y,z}$   $\Delta t$ ,  $w(x - \frac{\delta}{2})_{y,z}$   $\Delta t$

$$A' : u(x + \frac{z}{2}, y, z) \Delta z, v(x + \frac{z}{2}, y, z) \Delta z$$

but the forces are not  $\vec{r}_{xx}$  ~~to~~  $\vec{r}_{xx}(x+\Delta x, y, z)$  but averaged from  $\vec{r}_{xx}(x-\frac{\Delta x}{2}, y, z)$  to  $\vec{r}_{xx}(x+\frac{\Delta x}{2}, y, z)$   $\left[ \frac{\partial^2}{\partial x^2} \right] \Delta x$  during the whole time.

$$\left[ x \frac{\partial}{\partial x} + y \frac{\partial}{\partial y} \right] (x^{\frac{1}{2}} y^{\frac{1}{2}} x^{\frac{1}{2}} y^{\frac{1}{2}}) = 0$$

$$- \dots - u \cdot \int_{t_1}^{t_2} x(t, y(t)) \Delta t \cdot \sqrt{x(t, y(t))} \cdot \Delta t$$

[illegible]

$$A_{ek} = \int - \left( \mu + \frac{2}{3} \mu \operatorname{div} \right) 6 dS + \frac{\partial \mu}{\partial x} \left[ \mu \frac{\partial^2}{\partial x^2} dy dz + \mu \frac{\partial^2}{\partial y^2} dx dz + \mu \frac{\partial^2}{\partial z^2} dx dy \right] + \sqrt{\mu} \left\{ \mu \frac{\partial^2 \mu}{\partial x^2} + \left( \mu \frac{\partial^2 \mu}{\partial y^2} + \nu \frac{\partial^2 \mu}{\partial x^2} + \nu \frac{\partial^2 \mu}{\partial y^2} \right) \left[ dy dz + \left( \nu \frac{\partial^2}{\partial y^2} + \mu \frac{\partial^2}{\partial x^2} \right) dy dz \right] \right\} + \sqrt{\mu} \left[ \nu \frac{\partial^2 \mu}{\partial x^2} + \left( \mu \frac{\partial^2 \mu}{\partial y^2} + \nu \frac{\partial^2 \mu}{\partial x^2} + \nu \frac{\partial^2 \mu}{\partial y^2} \right) \left[ dx dz + \left( \mu \frac{\partial^2}{\partial x^2} + \nu \frac{\partial^2}{\partial y^2} \right) dx dz \right] \right]$$

$$\int \frac{1}{\sqrt{x}} \left[ \frac{\partial u}{\partial x} + \left( \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dx + \frac{\partial u}{\partial y} dy + \frac{\partial u}{\partial z} dz + \frac{\partial v}{\partial x} dx + \frac{\partial v}{\partial y} dy + \frac{\partial v}{\partial z} dz + \frac{\partial w}{\partial x} dx + \frac{\partial w}{\partial y} dy + \frac{\partial w}{\partial z} dz \right]$$

$$+ \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} + \frac{\partial^2}{\partial t^2}$$







$$X = -\frac{\partial \psi}{\partial x}$$

$$\rho \frac{\partial u}{\partial t} = \rho X - \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial y} + \frac{\partial \psi}{\partial z} + \frac{\partial \psi}{\partial t}$$

$$\rho \frac{\partial v}{\partial t} = \rho Y - \frac{\partial \psi}{\partial y} + \frac{\partial \psi}{\partial x} + \frac{\partial \psi}{\partial z} + \frac{\partial \psi}{\partial t}$$

$$\frac{\partial}{\partial t} \int \rho (u^2 + v^2 + w^2) d\tau + \rho \frac{\partial \psi}{\partial t} = 0$$

$$p dt = dm$$

$$\frac{\partial}{\partial t} \left[ \int \frac{u^2 + v^2 + w^2}{2} + U + c\theta \right] dm = 0$$

$$\left[ u \frac{\partial u}{\partial t} + v \frac{\partial v}{\partial t} + w \frac{\partial w}{\partial t} + U \frac{\partial U}{\partial t} + c \frac{\partial \theta}{\partial t} \right] dm = 0$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = - (uX + vY + wZ)$$

$$\left[ \left( u \frac{\partial u}{\partial t} + v \frac{\partial v}{\partial t} + w \frac{\partial w}{\partial t} + U \frac{\partial U}{\partial t} + c \frac{\partial \theta}{\partial t} \right) + \frac{\partial}{\partial t} \left( u \frac{\partial \psi}{\partial x} + v \frac{\partial \psi}{\partial y} + w \frac{\partial \psi}{\partial z} \right) \right] dm = 0$$

$$- \left[ u \frac{\partial \psi}{\partial x} + v \frac{\partial \psi}{\partial y} + w \frac{\partial \psi}{\partial z} \right] + \frac{\partial}{\partial t} \left( u \frac{\partial \psi}{\partial x} + v \frac{\partial \psi}{\partial y} + w \frac{\partial \psi}{\partial z} \right) + \frac{\partial}{\partial t} \left( \frac{1}{2} (u^2 + v^2 + w^2) + U + c\theta \right) = 0$$

$$\left( u \frac{\partial \psi}{\partial x} + v \frac{\partial \psi}{\partial y} + w \frac{\partial \psi}{\partial z} \right) + \frac{\partial}{\partial t} \left( u \frac{\partial \psi}{\partial x} + v \frac{\partial \psi}{\partial y} + w \frac{\partial \psi}{\partial z} \right) + \frac{\partial}{\partial t} \left( \frac{1}{2} (u^2 + v^2 + w^2) + U + c\theta \right) = 0$$



$$\frac{3}{2} p \frac{d(\frac{A}{\rho})}{dt} = \frac{A}{\rho} \frac{dp}{dt} + \frac{15}{4} \left[ \frac{\partial}{\partial x} \left( R \frac{\partial (\frac{A}{\rho})}{\partial x} \right) + \dots \right]$$

$$+ R \left[ 2 \left( \frac{\partial u}{\partial x} \right)^2 + \dots \right] - \frac{3}{2} \left( \frac{\partial u}{\partial x} + \dots \right)^2 +$$

$$+ \left( \frac{\partial v}{\partial x} + \frac{\partial w}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} + \frac{\partial v}{\partial x} \right)^2 + \left( \dots \right)^2$$

$$L = \frac{15}{4} \frac{R R}{\mu}$$

$$j_r = \frac{3R}{2\mu}$$

$$= 2 \left[ \frac{\partial^2 u}{\partial x^2} - \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] + 2 \left( \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + \frac{\partial u}{\partial y} \frac{\partial u}{\partial z} + \frac{\partial u}{\partial z} \frac{\partial u}{\partial x} \right) + 2 \left( \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial v}{\partial x} \frac{\partial u}{\partial y} + \dots \right)$$

$$- \left[ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] -$$

$$- \left[ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] -$$

$$- \left[ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] -$$

$$- \left[ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] -$$

$$- \left[ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right] -$$

$$\sqrt{\frac{1}{10000}} = \frac{1}{100}$$

$$\phi = \frac{1}{2} \frac{u}{r}$$

$$m = \left( \frac{1}{20} \right)^2 = \frac{1}{400}$$



For the purpose of this experiment, the following apparatus is required:







$$\frac{d}{dt} \begin{vmatrix} a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix} = \frac{\partial}{\partial x} \begin{vmatrix} a_2 & a_3 \\ b_2 & b_3 \end{vmatrix} + \frac{\partial}{\partial y} \begin{vmatrix} a_1 & a_3 \\ b_1 & b_3 \end{vmatrix} + \frac{\partial}{\partial z} \begin{vmatrix} a_1 & a_2 \\ b_1 & b_2 \end{vmatrix}$$

$$S \text{ char } a = b_1 \left( \frac{\partial a_3}{\partial y} - \frac{\partial a_2}{\partial z} \right) + b_2 \left( \frac{\partial a_1}{\partial y} - \frac{\partial a_3}{\partial z} \right) - a_2$$

+ b\_3

$$- a_3 \left( \frac{\partial b_2}{\partial x} - \frac{\partial b_1}{\partial y} \right)$$



$$-\frac{dw}{dt} = \frac{8\pi\mu a^3 \omega_0}{\frac{4}{3} a^3 \pi \cdot \frac{2a^2}{5}} = \frac{15\pi \omega_0}{a^2} = \frac{15\pi \cdot 2\pi}{a^2 \cdot t}$$

$$K \frac{dw}{dt} = P$$

$$t \frac{dw}{dt} = \frac{30\pi\mu}{a^2} = \text{zusammenfassend vorzeichenlos}$$

$$\frac{365 \cdot 30 \cdot 2\pi\mu}{a^2} = \text{" " " 1 sekunde}$$

$$\frac{35 \cdot 10^3 \cdot 0.00017}{36 \cdot 10^{16}} = 1.7 \cdot 10^{-17} \cdot \frac{t}{2\pi} = 1.7$$

$$\frac{265 \cdot 10^3 \cdot 0.00017}{26 \cdot 10^{16}} \cdot 86400 = 2 \cdot 10^{-13}$$

$$\Delta t = \frac{2}{\pi} \cdot \frac{2000000 \cdot 0.00017}{6 \cdot 10^8} = \frac{4}{800}$$

$$1 \sim 980 \cdot 76.136 = 10^6 = 10^{-12} = 10^9 \text{ mm}$$

$$T = \frac{a^2}{\pi} \Delta t \cdot 86400 \cdot 365 = \text{Berechnung} \cdot 10^4$$

$$= \frac{10^{-9} \cdot 1 \cdot 10^7}{15 \cdot 7^8 \cdot 1 \cdot 10^8} = \frac{10^{-10}}{15}$$

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~23~



interesam

rony i  
naciski

Jeszcze za... jak długo jeszcze

by motyw... Ale błędem byłoby

hwałę z 28 n

s tego sztanda-

iazków,

ie.

ii.

że... sprawiałym, gdyby naród  
nasz nie ciążył na decyzjach w każdej  
fazie, jaką przynoszą zawikłania orężne  
i dyplomatyczne. Dlatego oczekiwac

ładziemy w tej chwili głosu G.

su nie tylko urzędowego, ale po

go, który powinien odezwać się z

łą przekonania, że przyszłość nar

wymaga złączenia Galicyi z powstającą

niepodległą Polską. Mamy nadzieję

się odezwie, i że w rokowania brze

padnie z takim naciskiem, jakiego

magają obecne stosunki i dobro Oj-

czyzny.

zależnej

urząd-

go... alia się

względ... żądań un

innych grup narod

„Zwłaszcza o

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narodowym.

5. stycznia.

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i Nr. 12



9408

II

*Handwritten text, possibly a signature or date, written diagonally across the lower right portion of the cover.*



Z HANDLU  
STANISŁAWA KÖHLERA  
we Lwowie.

130

ae



Thermal effect of effusion:

Watson Weir Am 37 p. 341 (1889)

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Przykład udeśloni noizymia

$$\int \int \int \frac{\partial \theta}{\partial n} \frac{dF}{dt} = \int \int \int \frac{\partial^2 \theta}{\partial t^2} dv = \int \left[ \frac{c}{A} \frac{\partial \rho}{\partial t^2} + \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + f \operatorname{div} - \Phi \right] dv dt$$



$$0 = \frac{\partial f_{x1}}{\partial x} + \frac{\partial f_{xy}}{\partial y} + \frac{\partial f_{xz}}{\partial z} = -\frac{\partial f}{\partial x} + \frac{\mu}{3} \frac{\partial \text{div}}{\partial x} + \mu \nabla_u^c$$

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$$\bar{f} = \frac{\partial f}{\partial x}$$

$$\frac{\partial f}{\partial x} = \mu \left( \frac{1}{3} \frac{\partial \text{div}}{\partial x} + \nabla_u^c \right)$$

$$r = R \rho \theta$$

$$\frac{\partial f}{\partial y} = \mu \left( \frac{1}{3} \frac{\partial \text{div}}{\partial y} + \nabla_v^c \right)$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$\frac{\partial f}{\partial z} = \mu \left( \frac{1}{3} \frac{\partial \text{div}}{\partial z} + \nabla_w^c \right)$$

$$\frac{c}{A} \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + \rho \text{div} = \Phi$$

Prämissen

$$\bar{W}_I = - \iint \rho (u l + v m + w n) d\sigma = - \iiint \left[ \frac{\partial}{\partial x} (\rho u) + \frac{\partial}{\partial y} (\rho v) + \frac{\partial}{\partial z} (\rho w) \right] dv$$

$$\bar{W}_I = \iiint \Phi dv$$

$$\bar{W}_I = -R \iiint \theta \left[ \frac{\partial}{\partial x} (\rho u) + \dots \right] + \rho \left[ \frac{\partial}{\partial x} (\theta u) + \dots \right]$$

$$= - \iiint R \rho \left[ u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + \dots \right] + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)$$

$$-\bar{W}_I = \iiint \Phi + \left( R - \frac{c}{A} \right) \iiint \rho \left( u \frac{\partial \theta}{\partial x} + \dots \right)$$

$$\underbrace{\iiint \rho (u l + v m + w n) d\sigma}_{= \left( 1 - \frac{c}{AR} \right) \iiint \rho (u l + v m + w n) d\sigma}$$

$$-\bar{W}_I = (k-1) \bar{W}_I$$

$$-W_I = \iiint \left( u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) + f \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dV$$

noter:

$$\iiint \operatorname{Re} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) dV = \iiint \left( u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) dV$$

$$\underbrace{\iiint \operatorname{Re} \theta (u l + v m + w n) dV}_{f} - \iiint \operatorname{Re} \theta \frac{\partial \theta}{\partial \bar{\theta}} dV = -W_I$$

noter 2 :  $\iiint f \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dV = 0$

$$-W_I = \iiint \left( u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) dV =$$

$$= \mu \iiint \left( u \nabla^2 u + v \nabla^2 v + w \nabla^2 w \right) dV + \frac{1}{3} \left( u \frac{\partial \operatorname{div}}{\partial x} + v \frac{\partial \operatorname{div}}{\partial y} + w \frac{\partial \operatorname{div}}{\partial z} \right) dV$$

$$= \mu \iiint u \left( \frac{\partial u}{\partial x} l + \frac{\partial u}{\partial y} m + \frac{\partial u}{\partial z} n \right) + v \left( \frac{\partial v}{\partial x} l + \dots \right) + w \left( \frac{\partial w}{\partial x} l + \dots \right) dV +$$

$$+ \frac{1}{3} \iiint \operatorname{div} (u l + v m + w n) dV$$

$$- \iiint \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 + \left( \frac{\partial v}{\partial x} \right)^2 + \dots \right] dV$$

$$+ \frac{1}{3} (\operatorname{div})^2 dV$$

$$= \mu \iiint \frac{\partial}{\partial n} \left( \frac{u^2 + v^2 + w^2}{2} \right) dS + \frac{\mu}{3} \iiint \operatorname{div} dV - \mu \iiint \uparrow$$



2 drugi strony  $\bar{W}_{II} = \iiint \Phi dv =$

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$$\mu \iiint \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 + \dots + \frac{1}{3} (\text{div})^2 + 2 \left[ \frac{\partial u}{\partial y} \frac{\partial v}{\partial z} + \frac{\partial u}{\partial z} \frac{\partial v}{\partial x} + \frac{\partial v}{\partial x} \frac{\partial u}{\partial y} - \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} - \frac{\partial v}{\partial y} \frac{\partial u}{\partial z} - \frac{\partial u}{\partial z} \frac{\partial v}{\partial x} \right] dv$$

$$\iiint \left[ \frac{\partial u}{\partial y} \frac{\partial v}{\partial z} - \frac{\partial v}{\partial y} \frac{\partial u}{\partial z} \right] dv = \iiint w \left( m \frac{\partial v}{\partial z} - n \frac{\partial v}{\partial y} \right) dV - \iiint w \frac{\partial v}{\partial y \partial z} - w \frac{\partial v}{\partial y \partial z} dv$$

$$\iiint \dots = \iiint v \left( n \frac{\partial v}{\partial y} - m \frac{\partial v}{\partial z} \right) dV$$

$$\bar{W}_{II} = \mu \iiint \left( \frac{\partial u}{\partial x} \right)^2 + \dots + \frac{1}{3} (\text{div})^2 + \mu \iiint \left\{ u \left( n \frac{\partial w}{\partial x} - l \frac{\partial w}{\partial z} \right) + w \left( l \frac{\partial u}{\partial z} - n \frac{\partial u}{\partial x} \right) + \right.$$

$$\left. + v \left( l \frac{\partial u}{\partial y} - m \frac{\partial u}{\partial x} \right) + u \left( m \frac{\partial v}{\partial x} - l \frac{\partial v}{\partial y} \right) + w \left( m \frac{\partial v}{\partial z} - n \frac{\partial v}{\partial y} \right) + v \left( n \frac{\partial w}{\partial y} - m \frac{\partial w}{\partial z} \right) \right\} dV$$

zatem jeżeli można znaleźć w tej postaci rozwiązanie to będzie

$\bar{W}_{II} = \bar{W}_I$  co z tamtym rezultatem z tego study się zgodzić można  
 jeżeli  $\bar{W}_{II} = \bar{W}_I = 0$

Albo też: rotacja  $\iiint f dv = 0$

$\iiint \Phi dv = \frac{c}{A} \iiint \rho \left( u \frac{\partial \theta}{\partial x} + \dots \right) = -\frac{c}{AR} \bar{W}_I$  to samo co przedtem

$\bar{W}_{II} = \mu \iiint \left( \frac{\partial u}{\partial x} \right)^2 + \dots + \frac{1}{3} \text{div}^2 + \mu \iiint \left[ u \left( \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) (v_n) - \frac{\partial u}{\partial x} \text{div} \right] dV$

=

$+ 2 \mu \iiint \left[ l \left( v \frac{\partial u}{\partial y} - u \frac{\partial v}{\partial z} \right) + m \left( u \frac{\partial v}{\partial x} - v \frac{\partial u}{\partial z} \right) + n \left( u \frac{\partial w}{\partial y} - v \frac{\partial w}{\partial x} \right) \right] dV$

patrz Lamb p. 519



leg motive nashprens formy  $\theta = f(p)$

$$\rho = \varphi(p) = \frac{1}{R f(p)}$$

$$\frac{\partial \rho}{\partial x} = \rho \left( V_h^x + \frac{\partial \text{div}}{\partial x} \right)$$

$$\frac{\partial \rho}{\partial y} =$$

$$\frac{\partial \rho}{\partial z} =$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$\text{II). } \frac{c}{A} \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + \rho \left( \frac{\partial h}{\partial x} + \dots \right) = \Phi$$

$$\left[ \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = - \left[ u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right] + R \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) \right]$$

$$\frac{c}{A} \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = \Phi + \left[ u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right]$$

$$\frac{\partial \theta}{\partial x} = f' \frac{\partial f}{\partial x}$$

$$\frac{c}{AR} \frac{\rho f'}{f} \left( u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} \right) = \Phi + [ \dots ]$$

$$\frac{c}{AR} = \frac{k}{k-1}$$

jieli sis izda ismoneis adibot yums:  $\rho = c \rho^k$

$$\rho = c' \rho^{\frac{1}{k}} = \frac{1}{k k'}$$

$$f = \rho^{\frac{1}{1-k}}$$

$$f \sim \rho^{\frac{k-1}{k}}$$

$$\frac{f f'}{f} = \frac{k-1}{k}$$

$$f' \sim \frac{k-1}{k} \rho^{-\frac{1}{k}}$$

$$\text{zetaeta redukcija uz } \frac{c}{AR} \frac{f f'}{f} = 1$$

Wise tykko motive jiel.  $\Phi = 0$



~~Stwierdzenie~~

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Wzrost  $v = u = 0$ :

$$\frac{\partial p}{\partial x} = \mu \left[ \frac{1}{3} \frac{\partial^2 u}{\partial x^2} + \nabla u \right]$$

$$\frac{\partial p}{\partial y} = \mu \frac{1}{3} \frac{\partial^2 u}{\partial x \partial y}$$

$$\frac{\partial p}{\partial z} = \mu \frac{1}{3} \frac{\partial^2 u}{\partial x \partial z}$$

$$\frac{\partial(pu)}{\partial x} = 0$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \mu \frac{\partial u}{\partial x} = \Phi_u$$

Jedrowymiarowe zadanie:

$$x=0: p_0, \rho_0$$

$$x=l: p_1$$

$$\frac{\partial p}{\partial x} = \frac{4}{3} \mu \frac{\partial^2 u}{\partial x^2} \quad |u \quad \rho u = \rho_0 u_0$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \mu \frac{\partial u}{\partial x} = \frac{4}{3} \mu \left( \frac{\partial u}{\partial x} \right)^2$$

$$\frac{c}{A} \frac{\partial \theta}{\partial x} = \frac{1}{k-1} \mu$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \frac{\partial(pu)}{\partial x} = \frac{4}{3} \mu \left[ u \frac{\partial^2 u}{\partial x^2} + \left( \frac{\partial u}{\partial x} \right)^2 \right] = \frac{4}{3} \mu \frac{\partial}{\partial x} \left( u \frac{\partial u}{\partial x} \right)$$

$$\mu = 2 \rho \theta$$

$$\frac{c}{A} \rho u \theta + \mu u = \frac{4}{3} \mu \frac{\partial u}{\partial x}$$

$$\mu = \frac{4}{3} \mu \frac{\partial u}{\partial x} + \rho_0 \quad \uparrow \quad \left\| \frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \frac{4}{3} \mu \left( \frac{\partial u}{\partial x} \right)^2 + \rho_0 \frac{\partial u}{\partial x} = \frac{4}{3} \mu \left( \frac{\partial u}{\partial x} \right)^2 \right.$$

$$\frac{c}{A} \rho u \theta + \rho_0 u = \text{const} = a$$

$$\frac{c}{A R} \mu u + \rho_0 u = \left( \frac{c}{A R} + 1 \right) \rho_0 u + \frac{4}{3} \mu \frac{c}{A R} u \frac{\partial u}{\partial x} = a$$

$$\frac{4}{3} \mu u \frac{\partial u}{\partial x} + k \rho_0 u = (k-1) a$$

$$\frac{4}{3}\mu u \frac{du}{dx} + k p_0 u = (k-1)q \quad \parallel \quad \frac{\frac{4}{3}\mu u du}{(k-1)q - k p_0 u} = dx$$

Substitution:  $u = \alpha + z$

$$\frac{4}{3}\mu \alpha \frac{dz}{dx} + \frac{4}{3}\mu z \frac{dz}{dx} + k p_0 \alpha + k p_0 z = (k-1)q$$

$$\alpha = \frac{(k-1)q}{k p_0}$$

$$\frac{4}{3}\mu z \frac{dz}{dx} + \frac{4}{3}\mu \alpha \frac{dz}{dx} + k p_0 z = 0$$

$$\frac{4}{3}\mu \frac{dz}{dx} + \frac{4}{3}\mu \alpha \frac{d \log z}{dx} + k p_0 = 0$$

$$\frac{4}{3}\mu z + \frac{4}{3}\mu \alpha \log z + k p_0 x = b$$

$$\frac{4}{3}\mu (u - \alpha) + \frac{4}{3}\mu \alpha \log(u - \alpha) + k p_0 x = b \quad \text{convert a logij uigra } \alpha$$

$$\frac{4}{3}\mu \log[e^{u-\alpha} \cdot (u-\alpha)^\alpha] = b - k p_0 x$$

$$\frac{\mu u}{k-1} + p_0 u$$

$$= \frac{k p_0}{k-1} \alpha$$

$$p = p_0 + \frac{4}{3}\mu \frac{du}{dx}$$

$$e^{u-\alpha} (u-\alpha)^\alpha = e^{\frac{b - k p_0 x}{\frac{4}{3}\mu}}$$

$$e^u (u-\alpha)^\alpha = B e^{-\frac{3}{4} \frac{k p_0}{\mu} x}$$

$$\frac{u + \frac{3}{4} \frac{k p_0}{\mu} x}{e} (u-\alpha)^\alpha = B$$

$$e^{u + \frac{3}{4} \frac{k p_0}{\mu} x} (u-\alpha)^\alpha = B$$

$$p = \frac{k p_0 \alpha - p_0 (k-1) u}{u}$$

$$p = \frac{k p_0 \alpha}{u} - p_0 (k-1)$$

$$\theta =$$



Baronaz eliminacyi:

$$\theta = \frac{p}{R\rho}$$

$$p \frac{du}{dx} + u \frac{dp}{dx} = 0 \quad 135$$

$$\frac{c}{AR} \rho u \left[ \frac{1}{\rho} \frac{dp}{dx} - \frac{p}{\rho^2} \frac{d\rho}{dx} \right] + p \frac{du}{dx} = \frac{4}{3} \mu \left( \frac{du}{dx} \right)^2$$

$$-\frac{1}{\rho} \frac{dp}{dx} = + \frac{1}{u} \frac{du}{dx}$$

$$\left. \begin{aligned} \frac{c}{AR} \left[ u \frac{dp}{dx} + p \frac{du}{dx} \right] + p \frac{du}{dx} &= \frac{4}{3} \mu \left( \frac{du}{dx} \right)^2 \\ \frac{dp}{dx} &= \frac{4}{3} \mu \frac{d^2 u}{dx^2} \end{aligned} \right\}$$

Zatem ~~z~~ 3 stale do  
oznaczenia  $p, u$   
a jedyne jemu do  $\theta$  lub  $\rho$

Stale miedzy Potowiz, w tej gracie energii:

$$u = u_1 : x = 0$$

$$u = u_2 : x = l$$

$$b = \frac{4}{3} \mu \log e^{u_1 - \alpha} (u_1 - \alpha)^\alpha$$

$$\frac{4}{3} \mu \log \left[ e^{u - u_1} \left( \frac{u - \alpha}{u_1 - \alpha} \right)^\alpha \right] = -k p_0 x$$

$$k p_0 x = \frac{4}{3} \mu \log \left[ e^{u_1 - u} \left( \frac{u_1 - \alpha}{u - \alpha} \right)^\alpha \right]$$

$$k p_0 l = \frac{4}{3} \mu \log \left[ e^{u_1 - u_2} \left( \frac{u_1 - \alpha}{u_2 - \alpha} \right)^\alpha \right]$$

$$\frac{x}{l} = \frac{\log}{\log} = \frac{(u_1 - u) + \alpha \log(u_1 - \alpha) - \alpha \log(u - \alpha)}{(u_1 - u_2) + \alpha \log(u_1 - \alpha) - \alpha \log(u_2 - \alpha)}$$

$$\left[ e^{(u_1 - u_2) \frac{\alpha}{l}} \left( \frac{u_1 - \alpha}{u_2 - \alpha} \right)^\alpha \right] = e^{(u_1 - u) \frac{\alpha}{l}} \left( \frac{u_1 - \alpha}{u - \alpha} \right)^\alpha$$

$$\left\| \begin{aligned} \alpha &= \text{prędkość dla } x = \infty \\ p_0 \alpha + (k-1) p_0 \alpha &= k p_0 \alpha \\ p_\infty &= p_0 \end{aligned} \right.$$

$$\left( \frac{du}{dx} \right)_\infty = 0$$

$$p = p_{\infty} \frac{k\alpha - (k+1)u}{u} = p_{\infty} \left( k \frac{\alpha}{u} - k+1 \right) = p_{\infty} \left[ 1 + k \left( \frac{\alpha}{u} - 1 \right) \right]$$

$$u \leq \alpha$$

$$\frac{4}{3}\mu \log \left[ e^{u_1 - u} \left( \frac{\alpha - u_1}{\alpha - u} \right)^{\frac{1}{k}} \right]$$

$$x=0 : u = u_1$$

$$x=\infty : u = \alpha$$

$$x=\infty : p = p_{\infty}$$

$$p u = \text{const}$$

$$\frac{p}{\theta} u = \text{const} = \frac{p_{\infty} \alpha}{\theta_{\infty}}$$

$$\theta = \frac{p u}{p_{\infty} \alpha} \theta_{\infty} = \theta_{\infty} \cdot \frac{u + k(\alpha - u)}{\alpha} = \theta_{\infty} \left[ k - (k-1) \frac{u}{\alpha} \right]$$

$$\frac{4}{3}\mu \frac{du}{dx} = p - p_0$$

Więc istotnie:  $u_1 < u < \alpha$

$$\text{to: } 0 < x < \infty$$

$$p_{\infty} \left[ 1 + k \left( \frac{\alpha}{u} - 1 \right) \right] > p > p_0$$

$$> \frac{du}{dx} > 0$$

$$\theta_{\infty} \left[ k - (k-1) \frac{u}{\alpha} \right] > \theta > \theta_0$$

$$\frac{2}{3} \frac{p_0}{\mu}$$

$$\log(1-x) = -x - \frac{x^2}{2} - \frac{x^3}{3}$$

$$\frac{p}{p_0} = \frac{u_0}{u}$$

$$x = \frac{\frac{3}{2} (u^2 - u_0^2)}{p_0 u}$$

Więc dane muszą być 4 warunkami!

Wyróżając zwrócić  $p$   $\theta$ :

$$\frac{1}{k} \frac{p - p_{\infty}}{p_{\infty}} = \left( \frac{\alpha}{u} - 1 \right)$$

$$\frac{u}{\alpha} = \frac{1}{1 + \frac{1}{k} \left( \frac{p}{p_{\infty}} - 1 \right)}$$

$$\frac{p u}{\theta} = \text{const} = \frac{p_0 u_0}{\theta_0} \parallel \theta = \text{const}$$

$$x = \frac{3}{2} \frac{u_0}{p_0} \left[ 1 - \left( \frac{u_0}{u} \right)^2 \right]$$

$$= \frac{3}{2} \frac{u_0}{p_0} \left[ 1 - \left( \frac{u_0}{u} \right)^2 \right] = \frac{3}{2} \frac{u_0}{p_0} \left[ 1 - \left( \frac{p}{p_0} \right)^2 \right]$$

$$= \frac{3}{2} \frac{u_0}{p_0} \left[ \frac{p_0}{p} - \frac{p}{p_0} \right]$$



$$\theta = \theta_{\infty} \left[ k - \frac{k-1}{1 + \frac{1}{k} \left( \frac{p}{p_{\infty}} - 1 \right)} \right] = \theta_{\infty} \frac{k + \frac{1}{p_{\infty}} - 1 - k + 1}{1 - \frac{1}{k} + \frac{1}{k} \frac{p}{p_{\infty}}}$$

$$= \theta_{\infty} \frac{p}{p_{\infty}} \frac{k}{k-1 + \frac{p}{p_{\infty}}}$$

Zatun:  $p_{\infty} = p \frac{k}{k-1 + \frac{p}{p_{\infty}}}$

$$\rho = \rho_{\infty} \left[ \frac{k-1}{k} + \frac{p}{k p_{\infty}} \right]$$

$$u_0 = 30000 \quad p_0 = 1 \text{ atm} = 10^6$$

$$\frac{p}{p_0} = \frac{1}{2}$$

$$x = \frac{9}{4} \frac{3}{100} = \frac{27}{400} = 0.0675 \text{ cm}$$

$$\frac{p}{p_0} = \frac{1}{10}$$

$$x = \frac{9}{4} \frac{100}{100} = \frac{9}{4} = 0.225 \text{ cm}$$

Lambert type minus table:  $\frac{p_{01}}{p_{\infty}} = \left[ 1 + k \left( \frac{\alpha}{u_0} - 1 \right) \right]$

$$\frac{p_{01}}{p_{\infty}}$$

$$\frac{u_0}{u_1}$$

$$\frac{\theta_0}{\theta_1}$$

Initial  $p_{\infty} = 0$ :  $u_0 = \text{sonic}$   
 $\frac{p_0}{p} = \lim_{\alpha \rightarrow \infty} \frac{1 + k \left( \frac{\alpha}{u_0} - 1 \right)}{1 + k \left( \frac{\alpha}{u} - 1 \right)} = \frac{u}{u_0}$

$$\parallel \lim_{\alpha \rightarrow \infty} \log \left( \frac{\alpha - u_1}{\alpha - u} \right)^{\alpha} = \log \left( \frac{1 - \frac{u_1}{\alpha}}{1 - \frac{u}{\alpha}} \right)^{\alpha} = \log \left( 1 + \frac{u - u_1}{\alpha} \right)^{\alpha} = (u - u_1)$$

$$k p_{\infty} x = \frac{4}{3} p_{\infty} \left[ 1 + k \left( \frac{\alpha}{u} - 1 \right) \right] + u - u_1$$

$$p_{\infty} = \frac{p_0}{1 + k \left( \frac{\alpha}{u} - 1 \right)} \parallel k p_{\infty} x = \frac{4}{3} p_{\infty} \left[ 1 + k \left( \frac{\alpha}{u} - 1 \right) \right] \left\{ u_1 - u + \alpha \left[ \log(\alpha - u_1) - \log(\alpha - u) \right] \right\}$$

$$\log \frac{k p_{\infty} x}{\frac{4}{3} p_{\infty}} = \frac{u_1 - u + \alpha \left[ \log \frac{\alpha - u_1}{\alpha - u} \right]}{\frac{1}{1 + k \left( \frac{\alpha}{u} - 1 \right)}} = \log \frac{\alpha - u_1}{\alpha - u} + \frac{\alpha}{\alpha - u} \left( \frac{1}{\alpha - u_1} - \frac{1}{\alpha - u} \right) - \frac{\frac{k}{u}}{\left[ 1 + k \left( \frac{\alpha}{u} - 1 \right) \right]^2}$$

$$= -\frac{u_1}{\alpha} + \frac{1}{2} \left( \frac{u_1}{\alpha} \right)^2 + \frac{4}{\alpha} - \frac{1}{2} \left( \frac{u}{\alpha} \right)^2 + x + \frac{4}{\alpha} + \left( \frac{u_1}{\alpha} \right)^2 - x - \frac{4}{\alpha} - \left( \frac{u}{\alpha} \right)^2 \left( \frac{k}{u} \right)^2 \alpha^2$$

$$= -\frac{k}{u} \frac{2}{2} (u_1^2 - u^2)$$

Przebieg

Ruchy cząstek nieskończonych, zamkniętych:  $p, p, p, p$ .

$$\begin{array}{l} \rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x} + \frac{\mu}{3} \frac{\partial \operatorname{div} v}{\partial x} + \mu \nabla^2 u \\ \rho \frac{\partial v}{\partial t} = \\ \rho \frac{\partial w}{\partial t} = \end{array} \quad \left| \begin{array}{l} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{array} \right| \quad \left| \begin{array}{l} \frac{\partial}{\partial y} \\ -\frac{\partial}{\partial x} \\ \end{array} \right|$$

$$\frac{\mu}{3} \nabla^2 \operatorname{div} v + \mu \nabla^2 \operatorname{div} v = 0$$

$$\nabla^2 \operatorname{div} v = 0$$

$$\nabla^2 \xi = \nabla^2 \eta = \nabla^2 \zeta = 0$$

$$\nabla^2 \operatorname{curl} v = 0$$

$$\nabla^2 \operatorname{curl} v = 0$$

$$v = \nabla u + \operatorname{curl} v$$

$$\nabla^2 v = 0$$

Jżeli przestrzeń wielka, to  $\operatorname{div} v = 0$  i  $\operatorname{curl} v = 0$  w nieskończoności, wtedy: ruch taki jak ciepły nieskończonych z potencjałem prędkości:

$$u = \frac{\partial \varphi}{\partial x} \quad v = \frac{\partial \varphi}{\partial y} \quad w = \frac{\partial \varphi}{\partial z}$$

$$\operatorname{div} v = \frac{\partial u}{\partial x} + \dots = \nabla^2 \varphi = 0$$

$$\nabla^2 u = \frac{\partial}{\partial x} \nabla^2 \varphi = 0$$

[nie ma zjawisk skrzyżnych!  
ruch wzdłuż osi symetrii]

N. p. kula w przestrzeni

$$\varphi = \frac{a}{r}$$

$$u = -\frac{a}{r^3} a$$

$$v = -\frac{a}{r^3} a$$

$$w = -\frac{a}{r^3} a$$

$$\frac{\partial u}{\partial x} = \left(-\frac{1}{r^3} + \frac{3x^2}{r^5}\right) a = \frac{a}{r^3} \left(-1 + \frac{3x^2}{r^2}\right)$$

To byłoby nieumowne bo nieporównanie byłoby słodowe ruchu  
słowne, ale to nie umowne prędkości: bo  $\operatorname{curl} v$  nie będzie = 0 nieporównanie  
 $\operatorname{div} v$  i potencjał

not



Równanie wypływu tutaj nie ma sensu, bo robimy linie  $\rho=0$  tutaj jest  $\infty$  a więc umiemy sobie wyobrazić wyrażenie przez siebie.

Równanie ~~to~~ natomiast się wskazuje prowadząc wyrażenie które tutaj dajemy wchodzi znowu w rachuby, toż jest bzdura:

$$\kappa \nabla^2 \theta = \Phi$$

linia wskazująca  
kierunek curl na powierzchni!

Np. kula o promieniu

$$\varphi = \frac{Ca^2 x}{r^3} \quad \frac{\partial \varphi}{\partial x} = \frac{Ca^2}{r^3} \left[ 1 - \frac{3x^2}{r^2} \right] = u$$

$$\frac{\partial \varphi}{\partial y} = \frac{3Ca^2 xy}{r^5} = v$$

$$\text{div } v = - \frac{\partial v}{\partial y}$$

$$- \text{div } \nabla \varphi$$

$$\frac{\partial \varphi}{\partial z} = \frac{3Ca^2 xz}{r^5} = w$$

$$v = \nabla \varphi + \nabla \int \frac{\text{div } v}{n} dv + \text{curl} \int \frac{\text{curl } v}{n} dv$$

$$\nabla^2 \text{div } v = \text{div } \nabla^2 v \quad ? \quad \nabla \text{curl } v = \text{curl } \nabla^2 v$$

$$\left( \frac{\partial}{\partial x^2} + \frac{\partial}{\partial y^2} + \frac{\partial}{\partial z^2} \right) \left( \frac{\partial u}{\partial x^2} + \frac{\partial v}{\partial y^2} + \frac{\partial w}{\partial z^2} \right) \Big| \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x^2} + \frac{\partial v}{\partial y^2} + \frac{\partial w}{\partial z^2} \right) + \dots$$

$$\text{zatem Resultat: } \text{div } \nabla^2 v = 0$$

$$\text{curl } \nabla^2 v = 0$$

$$\therefore \nabla^2 v = \nabla U$$

Wyprowadzenie:

$$\nabla^2 v = -\frac{1}{3} \nabla \text{div } v$$

$$\nabla \text{div } v = \text{curl}^2 v$$

$$\text{curl}^2 v = \frac{4}{3} \nabla \text{div } v$$

$$U = -\frac{1}{3} \text{div } v$$

Nr. 1. d. 1. planowania

$$v = u = 0$$

$$\text{div} = 0$$

$$\frac{1}{3} \frac{\partial^2 u}{\partial x^2} + \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = 0$$

$$\frac{1}{3} \frac{\partial u}{\partial x^2} = 0$$

$$\frac{1}{3} \frac{\partial u}{\partial x^2}$$

$$= 0$$

$$\neq 0$$

$$\frac{\partial u}{\partial x} = f(x)$$

zisk planowania  $x = c$

$$\frac{\partial u}{\partial x} = 0$$

$$u = \frac{y}{\delta} c$$

$$\frac{\partial u}{\partial y} = \frac{c}{\delta}$$

$$\Phi = \mu \left( \frac{\partial u}{\partial y} \right)^2 = \mu \frac{c^2}{\delta^2}$$

$$-K \frac{\partial^2 \theta}{\partial y^2} = \mu \frac{c^2}{\delta^2}$$

$$\frac{d\theta}{dy} = -\frac{\mu}{K} \frac{c^2}{\delta^2} y + a$$

$$\theta = -\frac{\mu}{K} \frac{c^2}{\delta^2} \frac{y^2}{2} + ay + \theta_0$$

$$\theta_0 = -\frac{\mu}{K} \frac{c^2}{\delta^2} \frac{\delta^2}{2} + a\delta + \theta_0$$

$$\theta - \theta_0 = -\frac{\mu}{K} \frac{c^2}{\delta^2} \frac{y^2}{2}$$

$$a = -\frac{\mu}{K} \frac{c^2}{\delta^2} \frac{\delta}{2}$$

$$\theta = \frac{\mu}{K} \frac{c^2}{\delta^2} \frac{y(\delta - y)}{2} + \theta_0$$

$$\text{Maksimum: } y = \frac{\delta}{2} \quad \theta = \frac{\mu}{K} \frac{c^2}{8} + \theta_0$$

Nierówności w granicach wartości Nr. 1.  $\mu = 0.00017$

$$K = 42 \cdot 10^6 \cdot 0.000057$$

$$\frac{\mu}{8K} = \frac{1.7 \cdot 10^{-4}}{8 \cdot 42 \cdot 0.57 \cdot 10^2} = 10^{-8}$$

Wzrost dopięcia przy  $\theta = 10^4 \frac{\text{cm}}{\text{m}} \frac{\text{cm}}{\text{m}} \frac{\text{cm}}{\text{m}}$



Wzrostle ~~z~~ przy terminowaniu bzdur bardzo nieumiejętnie przy wykładzie 138  
 przykrociach

$$\frac{1}{3} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0$$

$$\frac{1}{3} \frac{\partial}{\partial y} ( \quad ) + \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} = 0$$

$$\frac{1}{3} \frac{\partial}{\partial z} ( \quad ) + \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} = 0$$

$$\int \rho \, dV \cos \alpha x$$



4πr

$$\frac{4\pi r^2}{3} + \frac{4}{3} \frac{\partial^2 r^2}{\partial x^2}$$

$$r \left( \frac{8\pi}{3} - 4 \right)$$

$$- \frac{4}{3} \pi x$$

Skierując dookoła  $\text{div } v = U = f(x, y, z)$  otrzymamy

$$w = -\frac{1}{3} \int \frac{\partial U}{\partial z} \, dv + A_3$$

$$v = -\frac{1}{3} \int \frac{\partial U}{\partial y} \, dv + A_2$$

$$u = -\frac{1}{3} \int \frac{\partial U}{\partial x} \, dv + A_1$$

$$\frac{\partial}{\partial x} \int \rho \frac{dv}{r} = \int \frac{\partial \rho}{\partial x} \frac{dv}{r} + \int \rho \frac{\partial dv}{\partial x} \frac{1}{r}$$

$$v = -\frac{1}{3} \int \frac{\nabla U}{r} \, dv + A$$

$$\nabla^2 U = 0$$

$$\text{div } U = 0$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = -\frac{1}{3} \int \frac{\nabla^2 U}{r} \, dv + \frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z}$$

$$\nabla^2 u = -\frac{1}{3} \int \frac{\partial^2 U}{\partial x^2} \frac{dv}{r}$$

$$\frac{\partial A_1}{\partial x} + \frac{\partial A_2}{\partial y} + \frac{\partial A_3}{\partial z} = C = 0$$

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At. —

wyznaczymy wartość termu:

dalej notujemy:  $W_I = \iiint u \frac{\partial r}{\partial x} + \dots$

$$\begin{aligned} & \iiint \rho u \left[ u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right] + \\ & + v \left[ u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right] + \\ & + w \left[ u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right] dv = \iiint \frac{\rho}{\rho_0} \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \cdot \frac{u^2 + v^2 + w^2}{2} dv \end{aligned}$$

$$= - \iiint \frac{u^2 + v^2 + w^2}{2} \frac{\rho}{\rho_0} (u l + v m + w n) dV + \iiint \frac{u^2 + v^2 + w^2}{2} \frac{\rho}{\rho_0} \left[ \frac{\partial}{\partial x} (\rho u) + \frac{\partial}{\partial y} (\rho v) + \frac{\partial}{\partial z} (\rho w) \right]$$

Widać że jest to samo

Całkowicie podobnie

$$\begin{aligned} & \iiint u \left( n \frac{\partial w}{\partial x} - l \frac{\partial w}{\partial z} + m \frac{\partial v}{\partial x} - l \frac{\partial v}{\partial y} \right) + \dots \\ & \pm l \frac{\partial u}{\partial x} \end{aligned}$$

$$\begin{aligned} & = \iiint u \frac{\partial}{\partial x} (l u + m v + n w) - l u \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \\ & + v \frac{\partial}{\partial y} \quad - m v ( \quad ) \\ & + w \frac{\partial}{\partial z} \quad - n w ( \quad ) \end{aligned}$$

$$= \iiint \left[ \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n - v_n \cdot \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \right] dV$$



rotor e colomni:

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$$W_{II} = W_I + \mu \iint \left[ \frac{\partial}{\partial n} \left( \frac{u^2 + v^2 + w^2}{2} \right) + \frac{1}{3} v_n \operatorname{div} + \left( u \frac{\partial}{\partial x} + \dots \right) v_n - v_n \operatorname{div} \right] dS$$

$$W_{II} = W_I + \mu \iint \left[ \frac{\partial}{\partial n} \left( \frac{v^2}{2} \right) + (\nabla \cdot \nabla) (v \cdot n) - \frac{2}{3} \operatorname{div} v \cdot \nabla (v \cdot n) \right] dS$$

$$(k-1) W_{II} = -W_I$$

$$0 = W_I \left( 1 + \frac{1}{k-1} \right) + \mu \iint$$

$$W_I = -\frac{k-1}{k} \mu \iint$$

$$W_{II} = \frac{1}{k} \mu \iint \left[ u \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial x} + w \frac{\partial w}{\partial x} + u \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial w}{\partial z} - \frac{2}{3} u \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] \right]$$

$$= \frac{\mu}{k} \iint \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial x} \right)^2 + \left( \frac{\partial w}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial y} \right)^2 + \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \frac{\partial v}{\partial x} \frac{\partial u}{\partial y} - \frac{2}{3} \frac{\partial u}{\partial x} \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] \right. \\ \left. + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial y} \right)^2 + \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \frac{\partial v}{\partial y} \frac{\partial u}{\partial x} - \frac{2}{3} \frac{\partial v}{\partial y} \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] \right. \\ \left. + \left( \frac{\partial u}{\partial z} \right)^2 + \left( \frac{\partial v}{\partial z} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 + \frac{\partial u}{\partial z} \frac{\partial w}{\partial x} + \frac{\partial w}{\partial z} \frac{\partial u}{\partial x} - \frac{2}{3} \frac{\partial w}{\partial z} \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] \right]$$

$$+ u \frac{\partial^2 u}{\partial x^2} + v \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 u}{\partial x \partial y} \right) + w \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 u}{\partial x \partial z} \right) - \frac{2}{3} u \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial x \partial y} + \frac{\partial^2 w}{\partial x \partial z} \right) \\ + v \frac{\partial^2 v}{\partial y^2} + w \left( \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 v}{\partial y \partial z} \right) + u \left( \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 v}{\partial y \partial x} \right) - \frac{2}{3} v \left( \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 w}{\partial y \partial z} + \frac{\partial^2 u}{\partial y \partial x} \right) \\ + w \frac{\partial^2 w}{\partial z^2} + u \left( \frac{\partial^2 u}{\partial z^2} + \frac{\partial^2 w}{\partial x \partial z} \right) + v \left( \frac{\partial^2 v}{\partial z^2} + \frac{\partial^2 w}{\partial y \partial z} \right) - \frac{2}{3} w \left( \frac{\partial^2 w}{\partial z^2} + \frac{\partial^2 u}{\partial x \partial z} + \frac{\partial^2 v}{\partial y \partial z} \right) \Bigg]$$

$$u \left[ \left( \frac{\delta u}{\delta x} + \frac{\delta u}{\delta y} + \frac{\delta u}{\delta z} \right) + \frac{1}{3} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) \right] - \frac{2}{3} u \frac{\partial}{\partial x} \left( \text{scribbled out} \right)$$

$$u \frac{\partial u}{\partial x}$$

$$\frac{1}{k} \left[ \Phi + u \frac{\partial \Phi}{\partial x} + v \frac{\partial \Phi}{\partial y} + w \frac{\partial \Phi}{\partial z} \right] = \Phi$$

$$u \frac{\partial \Phi}{\partial x} + v \frac{\partial \Phi}{\partial y} + w \frac{\partial \Phi}{\partial z} = (k-1) \Phi$$

by the ordinary method?



Two dimensional problem :

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$$\begin{aligned} u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} &= - \frac{\partial \chi}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) & \frac{\partial}{\partial y} \\ u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} &= - \frac{\partial \chi}{\partial y} + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) & \frac{\partial}{\partial x} \end{aligned}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$$\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = \xi$$

$$u \frac{\partial \xi}{\partial x} + v \frac{\partial \xi}{\partial y} = \mu \left( \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial^2 \xi}{\partial y^2} \right)$$

$$\frac{\partial u}{\partial x} \frac{\partial \xi}{\partial x} + \frac{\partial v}{\partial x} \frac{\partial \xi}{\partial y} + u \frac{\partial \xi}{\partial x^2} + v \frac{\partial \xi}{\partial x \partial y} = \mu \frac{\partial^2 \xi}{\partial x^2}$$

$$\frac{\partial u}{\partial y} \frac{\partial \xi}{\partial x} + \frac{\partial v}{\partial y} \frac{\partial \xi}{\partial y} + u \frac{\partial \xi}{\partial x \partial y} + v \frac{\partial \xi}{\partial y^2} = \mu \frac{\partial^2 \xi}{\partial y^2}$$

$$\frac{\partial v}{\partial x} \frac{\partial \xi}{\partial y} - \frac{\partial u}{\partial y} \frac{\partial \xi}{\partial x} + u \frac{\partial \xi}{\partial x^2} + v \frac{\partial \xi}{\partial x \partial y} = \mu \frac{\partial^2 \xi}{\partial x^2}$$

$$\frac{\partial u}{\partial x} \frac{\partial \xi}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial \xi}{\partial y} + \xi \frac{\partial \xi}{\partial y} + u \frac{\partial \xi}{\partial x^2} + v \frac{\partial \xi}{\partial x \partial y} =$$

$$\frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - u \xi = - \frac{\partial \chi}{\partial x} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} - u \xi = - \frac{\partial \chi}{\partial y} + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right)$$

By continuity:

$$u = \frac{\partial \psi}{\partial y} + \frac{\partial \chi}{\partial y}$$

$$v = \frac{\partial \psi}{\partial x} - \frac{\partial \chi}{\partial x}$$

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} = 0$$

$$\xi = - \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right)$$

$$\frac{\partial \chi}{\partial y} \frac{\partial}{\partial x} \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right) - \frac{\partial \chi}{\partial x} \frac{\partial}{\partial y} \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right) = \mu \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right) \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right)$$

$$v = \nabla \cdot \dots + \text{curl} \dots$$

$$\begin{vmatrix} i & j & k \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F & G & H \end{vmatrix}$$

$$u = \frac{\partial H}{\partial x} + \frac{\partial G}{\partial y}$$

$$v = \frac{\partial G}{\partial y} - \frac{\partial F}{\partial x}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0 \Rightarrow \nabla^2 \psi + \frac{\partial}{\partial y} (H - G) = 0$$

$$\xi = - \left( \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} \right)$$

Określę bieżącą wartość funkcji hydrostatycznej  $\psi = 0$

zatem  $\frac{\delta \psi}{\delta x} + \frac{\delta \psi}{\delta y} = f(\psi)$

zatem prawa strona:

$$\left( \frac{\delta}{\delta x} + \frac{\delta}{\delta y} \right) f(\psi) = 0 \quad \text{Myślenie! dowieść!}$$

Atmosfera jest w równowadze:

$$\psi = \psi_0 + \mu \left( \frac{\partial \psi}{\partial \mu} \right)_0 \quad \psi = f(x, y, \mu)$$

$$\psi(x, y, \mu) = \psi(x, y, \mu=0) + \mu \left[ \frac{\partial \psi(x, y, \mu)}{\partial \mu} \right]_{\mu=0}$$



$$v = 4.70$$

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$$\frac{\partial f}{\partial x} = \mu \left[ \frac{1}{3} \frac{\partial^2 u}{\partial x^2} + \nabla u \right]$$

$$\frac{\partial f}{\partial y} = \mu \frac{1}{3} \frac{\partial^2 u}{\partial x \partial y}$$

$$\frac{\partial f}{\partial z} = \mu \frac{1}{3} \frac{\partial^2 u}{\partial x \partial z}$$

$$\frac{\partial}{\partial x}(\rho u) = 0$$

$$\rho u = k(y, z)$$

$$u \frac{\partial \rho}{\partial x} + \rho \frac{\partial u}{\partial x} = 0$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + k \frac{\partial u}{\partial x} = \Phi$$

$$\frac{\partial f}{\partial x \partial y} \parallel$$

$$\frac{\partial}{\partial y} (\nabla^2 u) = 0$$

$$\frac{\partial}{\partial z} (\nabla^2 u) = 0$$

$$\nabla^2 u = f(x)$$

$$\rho = R \rho \theta$$

$$\theta = \frac{k}{R \rho}$$

$$\nabla^2 u$$

$$\nabla^2 f = \frac{4}{3} \mu \frac{\partial}{\partial x} (\nabla^2 u)$$

$$\nabla^2 f = \frac{4}{3} \mu \frac{\partial^2 u}{\partial x^2}$$

$$\frac{c}{AR} \rho u \left[ \frac{1}{\rho} \frac{\partial f}{\partial x} - \frac{k}{\rho^2} \frac{\partial \rho}{\partial x} \right] + k \frac{\partial u}{\partial x} = \Phi$$

$$\frac{c}{AR} \left[ u \frac{\partial f}{\partial x} - \frac{k u}{\rho} \frac{\partial \rho}{\partial x} \right] + k \frac{\partial u}{\partial x} = \Phi$$

$$\frac{c}{AR} u \frac{\partial f}{\partial x} + \left[ \frac{c}{AR} + 1 \right] k \frac{\partial u}{\partial x} = \Phi$$

$$u \frac{\partial f}{\partial x} + k k \frac{\partial u}{\partial x} = (k-1) \Phi$$

$$\rho = \frac{\mu}{3} \frac{\partial u}{\partial x} + \varphi(x)$$

$$\frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \frac{\partial \varphi}{\partial x} = \frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \mu \nabla^2 u$$

$$\nabla^2 f = \frac{\mu}{3} \frac{\partial}{\partial x} (\nabla^2 u) + \nabla^2 \varphi = \frac{4}{3} \mu \frac{\partial}{\partial x} (\nabla^2 u)$$

$$\nabla^2 \varphi = \frac{\partial^2 \varphi}{\partial x^2} = \mu \frac{\partial}{\partial x} (\nabla^2 u)$$

$$\frac{\partial \varphi}{\partial x} = \mu \nabla^2 u + \text{const}$$

$$\varphi(x) = \mu \int \nabla^2 u dx$$

Spindelmengenerierung:  
 $\rho = \frac{4}{3} \mu \frac{\partial u}{\partial x} + c$

$$\frac{4}{3}\mu u \frac{\partial u}{\partial x^2} + k \frac{4}{3}\mu \left(\frac{\partial u}{\partial x}\right)^2 + k c \frac{\partial u}{\partial x} = (k-1) \left[ \frac{4}{3} \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial u}{\partial z}\right)^2 \right] \quad \left. \vphantom{\frac{4}{3}\mu u \frac{\partial u}{\partial x^2}} \right\}$$

$$\frac{4}{3}\mu \left( \frac{\partial u}{\partial x^2} + \frac{\partial u}{\partial y^2} + \frac{\partial u}{\partial z^2} \right) = f(x)$$

$$u = a_0 + a_1 x + a_2 x^2 + b_1 y + \cancel{b_2 y^2} + \cancel{b_3 y^3} + \cancel{b_4 y^4} + \cancel{b_5 y^5} + \cancel{b_6 y^6} + \cancel{b_7 y^7} + \cancel{b_8 y^8} + \cancel{b_9 y^9} + \cancel{b_{10} y^{10}} + \cancel{b_{11} y^{11}} + \cancel{b_{12} y^{12}} + \cancel{b_{13} y^{13}} + \cancel{b_{14} y^{14}} + \cancel{b_{15} y^{15}} + \cancel{b_{16} y^{16}} + \cancel{b_{17} y^{17}} + \cancel{b_{18} y^{18}} + \cancel{b_{19} y^{19}} + \cancel{b_{20} y^{20}} + \cancel{b_{21} y^{21}} + \cancel{b_{22} y^{22}} + \cancel{b_{23} y^{23}} + \cancel{b_{24} y^{24}} + \cancel{b_{25} y^{25}} + \cancel{b_{26} y^{26}} + \cancel{b_{27} y^{27}} + \cancel{b_{28} y^{28}} + \cancel{b_{29} y^{29}} + \cancel{b_{30} y^{30}} + \cancel{b_{31} y^{31}} + \cancel{b_{32} y^{32}} + \cancel{b_{33} y^{33}} + \cancel{b_{34} y^{34}} + \cancel{b_{35} y^{35}} + \cancel{b_{36} y^{36}} + \cancel{b_{37} y^{37}} + \cancel{b_{38} y^{38}} + \cancel{b_{39} y^{39}} + \cancel{b_{40} y^{40}} + \cancel{b_{41} y^{41}} + \cancel{b_{42} y^{42}} + \cancel{b_{43} y^{43}} + \cancel{b_{44} y^{44}} + \cancel{b_{45} y^{45}} + \cancel{b_{46} y^{46}} + \cancel{b_{47} y^{47}} + \cancel{b_{48} y^{48}} + \cancel{b_{49} y^{49}} + \cancel{b_{50} y^{50}} + \cancel{b_{51} y^{51}} + \cancel{b_{52} y^{52}} + \cancel{b_{53} y^{53}} + \cancel{b_{54} y^{54}} + \cancel{b_{55} y^{55}} + \cancel{b_{56} y^{56}} + \cancel{b_{57} y^{57}} + \cancel{b_{58} y^{58}} + \cancel{b_{59} y^{59}} + \cancel{b_{60} y^{60}} + \cancel{b_{61} y^{61}} + \cancel{b_{62} y^{62}} + \cancel{b_{63} y^{63}} + \cancel{b_{64} y^{64}} + \cancel{b_{65} y^{65}} + \cancel{b_{66} y^{66}} + \cancel{b_{67} y^{67}} + \cancel{b_{68} y^{68}} + \cancel{b_{69} y^{69}} + \cancel{b_{70} y^{70}} + \cancel{b_{71} y^{71}} + \cancel{b_{72} y^{72}} + \cancel{b_{73} y^{73}} + \cancel{b_{74} y^{74}} + \cancel{b_{75} y^{75}} + \cancel{b_{76} y^{76}} + \cancel{b_{77} y^{77}} + \cancel{b_{78} y^{78}} + \cancel{b_{79} y^{79}} + \cancel{b_{80} y^{80}} + \cancel{b_{81} y^{81}} + \cancel{b_{82} y^{82}} + \cancel{b_{83} y^{83}} + \cancel{b_{84} y^{84}} + \cancel{b_{85} y^{85}} + \cancel{b_{86} y^{86}} + \cancel{b_{87} y^{87}} + \cancel{b_{88} y^{88}} + \cancel{b_{89} y^{89}} + \cancel{b_{90} y^{90}} + \cancel{b_{91} y^{91}} + \cancel{b_{92} y^{92}} + \cancel{b_{93} y^{93}} + \cancel{b_{94} y^{94}} + \cancel{b_{95} y^{95}} + \cancel{b_{96} y^{96}} + \cancel{b_{97} y^{97}} + \cancel{b_{98} y^{98}} + \cancel{b_{99} y^{99}} + \cancel{b_{100} y^{100}} + \dots$$



$$v = w = 0 \quad \text{hydrodynamic}$$

$$\rho u \frac{\partial u}{\partial x} = - \frac{\partial p}{\partial x} + \frac{\partial}{\partial x} \left( \frac{\mu}{A} \frac{\partial u}{\partial x} \right)$$

$$\rho u = \text{const}$$

$$\frac{c}{A} \rho u \frac{\partial \theta}{\partial x} + \mu \frac{\partial u}{\partial x} = 0$$

$$p = R \rho \theta$$

$$\frac{c}{A} \rho_0 u_0 \frac{d\theta}{dx} + (\rho_0 - u \rho_0 u_0) \frac{du}{dx} = 0$$

$$\frac{c}{A} \rho_0 u_0 \theta + \rho_0 u - \rho_0 u_0 \frac{u^2}{2} = a$$

$$\frac{c}{AR} u \mu$$

$$= \frac{c}{AR} u (\rho_0 - \rho_0 u_0 u)$$

$$u^2 \left[ \frac{c}{AR} + \frac{1}{2} \right] \rho_0 u_0 - u \left[ \frac{c}{AR} + 1 \right] \rho_0 = a$$

$$\frac{1}{k-1}$$

$$u^2 (k+1) \rho_0 u_0 - 2u k \rho_0 = A$$

$$\mu \frac{\partial u}{\partial x} = \frac{c}{A} \frac{\partial p}{\partial x}$$

$$\rho_0 u_0 \frac{\partial u}{\partial x} = - \frac{\partial p}{\partial x}$$

$$\rho_0 u_0 u + p = p_0$$

$$\frac{c}{A} \rho_0 u_0 \theta + R \rho_0 \theta = 0$$

$$\frac{c}{AR} \frac{d\theta}{dx} + \frac{d}{dx} \left( \frac{p}{u} \right) = 0$$

$$\frac{p}{\rho_0} = \left( \frac{p}{\rho_0} \right)^k$$

$$p = \rho_0 \left( \frac{u_0}{u} \right)^k$$

$$\rho_0 u_0 \cdot u + \rho_0 \left( \frac{u_0}{u} \right)^k = p_0$$

$$?$$

$$u = \text{const.}!$$

$$\frac{dp}{dx} = \frac{4}{3} \mu \frac{d^2 u}{dx^2}$$

$$\frac{d}{dx}(\rho u) = 0$$

$$\frac{c}{A} \rho u \frac{d\theta}{dx} + \rho \frac{du}{dx} = \frac{4}{3} \mu \left( \frac{du}{dx} \right)^2$$

$$\mu = \mu \theta$$



# Wytyczne kłisty

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$$u = \frac{x}{r} \quad \varphi = \frac{y}{r} \quad v = \frac{z}{r}$$

$$= x \varphi \quad = y \varphi \quad = z \varphi$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 3\varphi + \varphi' r$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 4\varphi' \frac{x}{r} + \varphi'' x$$

$$\frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \dots \right) = 4\varphi' \frac{x}{r} + \varphi'' x$$

$$\frac{d\mu}{dx} = \frac{d\mu}{dr} \frac{x}{r} = \frac{4}{3}\mu \left[ 4\varphi' \frac{x}{r} + \varphi'' x \right]$$

$$= \frac{4}{3}\mu \frac{d}{dr} [3\varphi + r\varphi'] \cdot \frac{x}{r}$$

$$I). \quad p = \frac{4}{3}\mu [3\varphi + r\varphi'] + p_0$$

$$II). \quad 4\pi r^2 \varphi r \rho = \omega r^3$$

$$\varphi \rho r^3 = \omega r^3$$

$$\rho d(\varphi r^3) + \varphi r^3 d\rho = 0$$

$$\rho(\varphi' r^3 + 3r^2 \varphi) + \varphi r^3 \frac{d\rho}{dr} = 0$$

$$(3\varphi + \varphi' r) + \varphi r \frac{1}{\rho} \frac{d\rho}{dr} = 0$$

$$III). \quad \frac{c}{A} \rho \left[ x\varphi \frac{x}{r} \frac{d\theta}{dr} + y\varphi \frac{y}{r} \frac{d\theta}{dr} + \dots \right] + \mu [3\varphi + \varphi' r] = \Phi$$

$$\Phi =$$

$\frac{\partial u}{\partial x} = \varphi + \varphi' \frac{x^2}{r^2}$	$\frac{\partial v}{\partial x} = \varphi' \frac{xy}{r^2}$	$\frac{\partial u}{\partial x} = \varphi' \frac{x^2}{r^2}$
$\frac{\partial u}{\partial y} = \varphi' \frac{xy}{r^2}$	$\frac{\partial v}{\partial y} = \varphi + \varphi' \frac{y^2}{r^2}$	$\frac{\partial u}{\partial y} = \varphi' \frac{y^2}{r^2}$
$\frac{\partial u}{\partial z} = \varphi' \frac{x^2}{r^2}$	$\frac{\partial v}{\partial z} = \varphi' \frac{yz}{r^2}$	$\frac{\partial u}{\partial z} = \varphi + \varphi' \frac{z^2}{r^2}$

$$\frac{\Phi}{r} = -\frac{2}{3} [3\varphi + r\varphi']^2 + 2 \left[ \left( \varphi + \frac{x^2}{r^2} \varphi' \right)^2 + \left( \varphi + \frac{y^2}{r^2} \varphi' \right)^2 + \left( \varphi + \frac{z^2}{r^2} \varphi' \right)^2 \right] +$$

$$+ 4 \varphi'^2 \left[ \frac{y^2 z^2}{r^2} + \frac{z^2 x^2}{r^2} + \frac{x^2 y^2}{r^2} \right]$$

$$= -\frac{2}{3} [3\varphi + r\varphi']^2 + 2 \left[ 3\varphi^2 + 2\varphi\varphi' r + \varphi'^2 \frac{x^4 + y^4 + z^4 + 2x^2 y^2 + \dots}{r^2} \right]$$

$$= -\frac{2}{3} [3\varphi + r\varphi']^2 + 2 [3\varphi^2 + 2r\varphi\varphi' + r^2 \varphi'^2]$$

$$= -\frac{2}{3} r^2 \varphi'^2 + 2 r^2 \varphi'^2 = \frac{4}{3} r^2 \varphi'^2$$

$$\text{III). } \frac{c}{A} \rho \varphi r \frac{d\theta}{dr} + \mu [3\varphi + r\varphi'] = \frac{4}{3} \mu r^2 \varphi'^2$$

$$\theta = \frac{\mu}{R\rho}$$

$$\frac{c}{AR} \left( \varphi r \frac{d\mu}{dr} - \frac{\varphi r \mu}{\rho} \frac{d\rho}{dr} \right) = \frac{c}{AR} \left[ \varphi r \frac{4}{3} \mu (\varphi' + r\varphi'') + \left[ \frac{4}{3} \mu (3\varphi + r\varphi') + \mu_0 \right] [3\varphi + r\varphi'] \right] +$$

$$+ \left[ \frac{4}{3} \mu (3\varphi + r\varphi') + \mu_0 \right] [\varphi + \varphi' r] = \Phi$$



$$\frac{c}{AR} (4\varphi' + r\varphi'') \varphi r + \left(1 + \frac{c}{AR}\right) (3\varphi + r\varphi') (3\varphi + r\varphi' + P_0) = r^2 \varphi'^2 \quad 144$$

$$P_0 = \frac{\mu_0}{\frac{4}{3}\pi}$$

$$(4\varphi' + r\varphi'') \varphi r - (k-1) r^2 \varphi'^2 + k (3\varphi + r\varphi') (3\varphi + r\varphi' + P_0) = 0$$

$$r^2 \varphi \varphi'' + \varphi'^2 [r^2(1-k) + k r^2] + \varphi' [4 r \varphi + 6 k r \varphi + P_0 k r] + 9 k \varphi^2 + 3 k \varphi P_0 = 0$$

$$r^2 (\varphi \varphi'' + \varphi'^2) + \varphi' [2 r \varphi (2+3k) + k r P_0] + 3 k \varphi [3\varphi + P_0] = 0$$

$$\underbrace{\frac{d}{dr}(\varphi \varphi')}$$

$$\underbrace{r^4 \frac{d}{dr}(\varphi \varphi') + \varphi \varphi' \cdot 4 r^3}_{\frac{d}{dr}(\varphi \varphi' r^4)} + k (6 \varphi \varphi' r^3 + 9 \varphi^2 r^2) + 3 k [2 r^3 \varphi \varphi' + 3 r^2 \varphi^2] + k P_0 (\varphi' r^3 + 3 \varphi^2 r) = 0$$

$$\underbrace{\frac{d}{dr}(r^3 \varphi^2)} \quad \underbrace{\frac{d}{dr}(\varphi r^3)}$$

$$\varphi \varphi' r^4 + 3 k \varphi^2 r^3 + k P_0 \varphi r^3 = a$$

$$\varphi \varphi' + 3 k \frac{\varphi^2}{r} + k P_0 \frac{\varphi}{r} = \frac{a}{r^4}$$

$$\frac{d\varphi}{dr} + 6 k \frac{\varphi}{r} + k P_0 \frac{1}{r} = \frac{a}{r^5}$$

$$\varphi^2 = 2r$$

$$\varphi \varphi' = \frac{dr}{dr}$$

$$r\varphi = y$$

$$r\varphi' + \varphi = \frac{dy}{dr}$$

$$r^2 \varphi' = r \frac{dy}{dr} - y$$

$$r y (r \frac{dy}{dr} - y) + 3 k r y^2 + k P_0 r^2 y = a$$

$$r^2 y \frac{dy}{dr} + (3k-1) r y^2 + k P_0 r^2 y = a$$

$$y \frac{dy}{dr} + (3k-1) \frac{y^2}{r} + k P_0 y = \frac{a}{r^2}$$

$$\frac{dy}{dr} + (3k-1) \frac{y}{r} + k P_0 y = 0$$

$$y = uv$$

$$\frac{dy}{dr} = u \frac{dv}{dr} + v \frac{du}{dr}$$

$$u^2 v \frac{dv}{dr} + u v^2 \frac{du}{dr} + (3k-1) \frac{u^2 v^2}{r} + k P_0 u v = \frac{a}{r^2}$$

$$u^2 \left[ v \frac{dv}{dr} + (3k-1) \frac{v^2}{r} \right] + u \frac{du}{dr} \cdot v^2 + k P_0 u v = \frac{a}{r^2}$$

$$\underbrace{\hspace{10em}}_{=0}$$

$$\log v = -(3k-1) \log r$$

$$v = r^{1-3k}$$

$$u \frac{du}{dr} + u R_1 = R_2$$

$$\parallel \quad \begin{array}{l} u = x + y \\ x \frac{dx}{dr} + x \frac{dy}{dr} + y \frac{dx}{dr} + y \frac{dy}{dr} + x R_1 + y R_1 = R_2 \end{array}$$

$$\cancel{u = xy} \quad \cancel{y x^2 \frac{dy}{dr} + x y^2 \frac{dx}{dr} + x y R_1 = R_2}$$

Final  $a=0$ :

$$u = -k P_0 \int \frac{dr}{r} = -\frac{k P_0}{b} \int \frac{dr}{r^{1-3k}} = -\frac{k P_0}{b} \int (r^{3k-1}) dr$$

$$u = -\frac{k P_0}{b} \frac{r^{3k}}{3k} + c$$

$$y = c r^{1-3k} - \frac{P_0}{3} r = r \varphi = s$$



$$\varphi = c r^{-3k} - \frac{P_0}{3}$$

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$$\varphi' = -3kc r^{-3k-1}$$

$$I). \quad \rho = \frac{4}{3}\mu \left[ 3c r^{-3k} - P_0 - 3kc r^{-3k} + P_0 \right] = 4\mu c(1-k) r^{-3k}$$

$$II). \quad \rho \left[ c r^{3(1-k)} - \frac{P_0}{3} r^3 \right] = \text{const} \quad \text{not the numerator!}$$

$$\varphi r^3 = \frac{c}{\rho}$$

$$\varphi = \frac{c}{\rho r^3}$$

$$\varphi' = -\frac{3c}{\rho r^4} - \frac{c}{\rho^2 r^3} \frac{d\rho}{dr}$$

$$\left[ -\frac{3c^2}{\rho^2 r^7} - \frac{c^2}{\rho^3 r^6} \frac{d\rho}{dr} \right] r^4 + 3k \frac{c^2}{\rho^2 r^6} r^3 + k P_0 \frac{c}{\rho} = a$$

$$\frac{c^2}{r^2} \frac{1}{\rho^3} \frac{d\rho}{dr} + \frac{3c^2}{\rho^2 r^3} + \frac{3k c^2}{\rho^2 r^3} + k P_0 \frac{c}{\rho} = a$$

$$\frac{d\rho}{dr} + \rho \cdot \frac{3(k+1)}{r} + \frac{k P_0}{c} \frac{\rho^2}{r^2} = \frac{a}{c^2} \rho^3 r^2$$

$$\rho = u v^3$$

$$u \left[ \frac{dv}{dr} + v \frac{3k+1}{r} + \frac{k P_0}{c} \frac{u v^2}{r^2} \right] + v \frac{du}{dr} = \frac{a}{c^2} u^3 v^3 r^2$$

$$\frac{du}{dr} + (3k+1) \frac{u}{r} + k P_0 \frac{u}{r^2} = \frac{a}{r^3}$$

hidrodinamische normierung, folgende:

$$I. \left\{ \begin{aligned} \frac{\partial f}{\partial x} &= \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \\ \frac{\partial f}{\partial y} &= \frac{\mu}{3} \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \end{aligned} \right\} \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} \right) \left( \frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} \right) = 0$$

$$II. \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} = 0$$

$$III. \frac{c}{A} \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} \right) + \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = \Phi$$

$$\theta = \frac{f}{\rho \mu}$$

$$\frac{c}{A \rho} \rho \left[ \frac{1}{\rho} \frac{\partial f}{\partial t} - \frac{f}{\rho} \frac{\partial \rho}{\partial t} \right]$$

$$IV. \frac{c}{A \rho} \rho \left[ u \frac{1}{\rho} \frac{\partial f}{\partial x} + v \frac{1}{\rho} \frac{\partial f}{\partial y} \right] - u \frac{f}{\rho} \frac{\partial \rho}{\partial x} - v \frac{f}{\rho} \frac{\partial \rho}{\partial y} + \dots$$

$$\frac{1}{k-1} \left[ u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} - \frac{f}{\rho} \left( u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} \right) \right] + \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = \Phi$$

$$\frac{\partial f}{\partial t} \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} = 0$$

$$V. u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + (k-1) \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = (k-1) \Phi$$

$$VI. u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + k \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = (k-1) \Phi$$

hier: vorteilhafteste Form für die Berechnung!

$$u = \frac{\partial p}{\partial x}$$

$$v = \frac{\partial p}{\partial y}$$

$$f = \frac{\mu}{3} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \int u dx + v dy + \dots$$

$$\nabla^2 \varphi = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial x^2}$$



Eliminating  $\rho$  |  $\rho = R \rho \theta$

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$$\cancel{R \left( \theta \frac{\partial \rho}{\partial x} + \rho \frac{\partial \theta}{\partial x} \right) = \frac{\mu}{3} \frac{\partial}{\partial x}}$$

$$\text{Wtedy: } \frac{\partial \rho}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} \right) + \mu \frac{\partial}{\partial x} \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) = \frac{4\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) \rho$$

$$\frac{\partial \rho}{\partial y} = \frac{4\mu}{3} \frac{\partial}{\partial y} \left( \right) \rho$$

$$\text{I). } \rho = \rho_0 + \frac{4\mu}{3} \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)$$

$$\text{II). } \frac{\partial \varphi}{\partial x} \frac{\partial \rho}{\partial x} + \frac{\partial \varphi}{\partial y} \frac{\partial \rho}{\partial y} + k \rho \nabla^2 \varphi = (k-1) \Phi$$

$$\Phi = -\frac{2}{3} \mu (\nabla^2 \varphi)^2 + 2 \left[ \left( \frac{\partial^2 \varphi}{\partial x^2} \right)^2 + \left( \frac{\partial^2 \varphi}{\partial y^2} \right)^2 \right] + 4 \left( \frac{\partial^2 \varphi}{\partial x \partial y} \right)^2$$

$$\left[ \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) \right]^2$$

$$\cancel{k \rho \nabla^2 \varphi} = \frac{4\mu}{3} \left[ \left( \frac{\partial^2 \varphi}{\partial x^2} \right)^2 + \left( \frac{\partial^2 \varphi}{\partial y^2} \right)^2 - \frac{\partial^2 \varphi}{\partial x^2} \frac{\partial^2 \varphi}{\partial y^2} + 3 \left( \frac{\partial^2 \varphi}{\partial x \partial y} \right)^2 \right]$$

$$\text{I). } \nabla^2 \rho = \frac{\mu}{3} \nabla^2 \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) + \mu \nabla^2 \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) = \frac{4\mu}{3} \nabla^2 \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)$$

$$\rho = \frac{4\mu}{3} \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) + A \quad \parallel \nabla^2 A = 0 \quad \left. \begin{array}{l} \text{Jedyną wartość} \\ \text{dla całego obszaru} \end{array} \right\}$$

Łatwiejsze jest  $A = \rho_0 = \text{const}$ :

$$\frac{4}{3} \mu \left( \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} \right) + \frac{4\mu}{3} \left( \frac{\partial^2 \varphi}{\partial x \partial y} + \frac{\partial^2 \varphi}{\partial y \partial x} \right) + \cancel{\dots} =$$

$$(k-1) \left[ -\frac{2}{3} \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)^2 + 2 \left( \frac{\partial^2 \varphi}{\partial x^2} \right)^2 + 2 \left( \frac{\partial^2 \varphi}{\partial y^2} \right)^2 + \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)^2 \right] - \frac{4}{3} \mu \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)^2 - A \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right)$$



$$u \left[ \frac{4}{3} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right] + v \left[ \frac{4}{3} \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right] =$$

$$k \left[ -2 \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + 2 \left( \frac{\partial u}{\partial x} \right)^2 + 2 \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right] +$$

$$+ \left[ \frac{2}{3} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 - 2 \left( \frac{\partial u}{\partial x} \right)^2 - 2 \left( \frac{\partial v}{\partial y} \right)^2 - \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right]$$

$$= k \left[ -4 \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right] + \left[ \frac{2}{3} ( \quad ) - \right]$$

zrobić sprządkowy rodzaj rachunku potencjału:  $\frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0$

$$\frac{\partial u}{\partial x} = \frac{\partial \varphi}{\partial x^2} \quad \frac{\partial u}{\partial y} = \frac{\partial \varphi}{\partial x \partial y} = \frac{\partial v}{\partial x}$$

~~$$\frac{\partial \varphi}{\partial x} \left[ \frac{4}{3} \frac{\partial}{\partial x} \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) + \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} \right] + \frac{\partial \varphi}{\partial y} \left[ \frac{4}{3} \frac{\partial}{\partial y} \left( \frac{\partial \varphi}{\partial x} + \frac{\partial \varphi}{\partial y} \right) + \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} \right] =$$~~

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

~~$$\frac{\partial \varphi}{\partial x} \left[ \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial x \partial y} \right]$$~~

$$0 = (k) \left[ 2 \left( \frac{\partial^2 \varphi}{\partial x^2} \right)^2 + 2 \left( \frac{\partial^2 \varphi}{\partial y^2} \right)^2 + 4 \left( \frac{\partial^2 \varphi}{\partial x \partial y} \right)^2 \right]$$

$$0 = \left( \frac{\partial^2 \varphi}{\partial x^2} \right)^2 + 2 \left( \frac{\partial^2 \varphi}{\partial x \partial y} \right)^2 + \left( \frac{\partial^2 \varphi}{\partial y^2} \right)^2$$

$$\left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2$$

Mozliwa trybka jwiz 2 rocha

$$\frac{\partial u}{\partial x} = \frac{\partial u}{\partial y} = \frac{\partial v}{\partial x} = \frac{\partial v}{\partial y} = 0$$



$$v = \varphi \cdot u$$

Na powierzchni musi być równo ciśnie  $u = 0$   
 $v = 0$

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t.zn. tem musi

Postać:

$$\frac{\partial v}{\partial x} = u \frac{\partial \varphi}{\partial x} + \varphi \frac{\partial u}{\partial x}$$

$$v = u(a - u) = a u - u^2$$

$\vec{v}$

$$d \left[ \left( 1 - \frac{u}{a} \right) \left( \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} \right) \right] = \frac{\partial \varphi}{\partial x} dx + \frac{\partial \varphi}{\partial y} dy + \frac{\partial \varphi}{\partial z} dz$$

$$= \mu (V_x^2 dx + V_y^2 dy + V_z^2 dz)$$

$$= \mu \int (V^2 \cdot d\vec{b})$$

niezależnie od drogi

Nad krywą zamkniętą:

$$\int_0 \left[ 1 - \frac{u}{a} \right] = 0$$

$$\int_0 \int (V^2 \cdot d\vec{b}) = 0$$

$$\text{Teorema Stokesa: } \iint_S (\nabla \cdot \text{curl } \vec{v}) dS = \int_0 \int (\vec{v} \cdot d\vec{b})$$

$$\iint_S (\nabla \cdot \text{curl } \vec{v}) dS = 0$$

$$\text{curl } \vec{v} = \nabla \times \vec{v}$$

$$\text{curl } \vec{v} = \nabla \text{div} - \nabla^2 \vec{v}$$

$$\text{curl } \vec{v} = -\text{curl}^2 \vec{v} - \text{curl } \nabla \text{div} \vec{v}$$

$$= \nabla \times \text{curl} \vec{v} - \nabla \text{div} \text{curl} \vec{v}$$

$$\text{Wzyc } \nabla^2 \vec{v} = \nabla \nabla \cdot \vec{v} - \text{curl}^2 \vec{v}$$

traga

$$\int (\vec{v} \cdot d\vec{b}) = \int \nabla \cdot \vec{v} dx + \nabla \cdot \vec{v} dy + \nabla \cdot \vec{v} dz = \int \nabla \cdot \vec{v} dx + \nabla \cdot \vec{v} dy + \nabla \cdot \vec{v} dz$$

?

Spiegamy rodzaj:  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y}, \frac{\partial v}{\partial x} = 0$

$$\left\{ \begin{array}{l} \frac{\partial f}{\partial x} = \mu \nabla^2 u \\ \text{---} \end{array} \right.$$

$$f = A \quad \parallel \nabla^2 A = 0$$

$$u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} = (k-1) \left[ 2 \left( \frac{\partial u}{\partial x} \right)^2 + 2 \left( \frac{\partial v}{\partial y} \right)^2 + 2 \left( \frac{\partial v}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} + \frac{\partial u}{\partial x} \right)^2 - \right]$$

$u$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$$

$u$

$$u \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + v \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) = (k-1) \left[ 2 \left( \frac{\partial u}{\partial x} \right)^2 + 2 \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right]$$

$$\left( \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right)^2 - 2 \frac{\partial u}{\partial x} \frac{\partial v}{\partial y}$$

$$u \frac{\partial^2 u}{\partial x^2} + \left( \frac{\partial u}{\partial x} \right)^2 + \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + u \frac{\partial^2 v}{\partial y^2} = 0$$

$$u \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial y} + u \frac{\partial^2 v}{\partial y^2} = 0$$

$$v \frac{\partial^2 v}{\partial x^2} + \left( \frac{\partial v}{\partial x} \right)^2 + \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + v \frac{\partial^2 u}{\partial y^2} = 0$$

~~Rozdział 3~~

Stwierdzić, że dla każdej postaci  $u, v = 0$   
 otrzymujemy z III: Składowe  $u$  i  $v$  w kierunku  $y$   
 normalnym

$$\frac{\partial u}{\partial x} = 0$$

[co dozwolone ponieważ tylko pierwsze potęgę]

$$k \mu \frac{\partial v}{\partial y} = (k-1) \mu \left[ -\frac{2}{3} \left( \frac{\partial v}{\partial y} \right)^2 + 2 \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 \right] + (k-1) \mu \nabla^2 v$$

$$\underbrace{\left[ -\frac{2}{3} \left( \frac{\partial v}{\partial y} \right)^2 + 2 \left( \frac{\partial v}{\partial y} \right)^2 \right]}_{\frac{4}{3} \left( \frac{\partial v}{\partial y} \right)^2}$$



z II wytycznej mamy:  $\frac{\partial u}{\partial y} = 0$

z reguły wytycznej  $\frac{\partial u}{\partial y} = 0$  <sup>1418</sup>

To prawda: ciepła zostaniemy wyrażać długości  $\frac{\partial u}{\partial y} \geq 0$ , podnoszący nam to  
my paraboliczne, zatem musimy być w stanie - być że  $\frac{\partial u}{\partial y} = 0$

lub tu: uwzględnienie przewodzenia ciepła!

ważnym n.p. dla prędkości prądu

uwzględnienie przewodzenia ciepła

ważnym toku  
dla prędkości prądu

Zatem adreśatywa tego będzie minimalizacja n.p. dla prądu ~~adreśatywa~~

Ponieważ się wyjdzie okoliczności prędkości prądu wyjdzie natężenie prądu

na przed form! To prawda, że możemy mieć tylko n.p. dla  
prądu waty i dośw. Kubiś

zły przewodnik będzie prąd nieznacznie niż dobry

Obliczmy zatem więcej prędkości prądu: adreśatywa!

$$\left. \begin{aligned} u &= u_0 + a\rho + b\rho^2 \\ \frac{\partial u}{\partial \rho} &= a + 2b\rho = 0 \\ \text{lub } u_0 + a\rho + b\rho^2 &= 0 \end{aligned} \right\}$$

$$u_0 + \delta(a + 2b\delta) - b\delta^2 = 0$$

$$b = \frac{u_0}{\delta^2}$$

$$a = -\frac{2u_0}{\delta}$$

$$\rho \left( \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) + u \left( \frac{\partial \rho}{\partial x} + \frac{\partial \rho}{\partial y} \right) = 0$$

$$\left( \frac{\partial u}{\partial y} \right)^2 = -\frac{\kappa}{\mu} \left( \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} + \frac{\partial^2 \theta}{\partial z^2} \right)$$

Robimy założenie że  $\frac{\partial \theta}{\partial x} = \frac{\partial \theta}{\partial z} = 0$

$$\left( \frac{\partial u}{\partial y} \right)^2 = -\frac{\kappa}{\mu} \frac{\partial^2 \theta}{\partial y^2}$$

## Punkti storkovate

Uprovođenju izvika priključimo z izvikaćim rovanima tuniranj:

$$\frac{\partial f}{\partial y} = \frac{\partial f}{\partial z} = 0$$

$$\frac{df}{dx} = \mu \left( \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$\frac{\partial(\rho u)}{\partial x} = 0$$

$$II). \quad u \frac{df}{dx} + k f \frac{\partial u}{\partial x} = (k-1) \left[ \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 \right] \mu + \kappa \Delta^2 \theta$$

$$u = f(x, r)$$

$$\frac{\partial u}{\partial y} = f' \frac{y}{r}$$

$$\left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 = (f')^2$$

$$\frac{\partial^2 u}{\partial y^2} = f'' \frac{y^2}{r^2} + f' \left( \frac{1}{r} - \frac{y^2}{r^3} \right) \quad \left\{ \begin{array}{l} \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = f'' + f' \frac{1}{r} = \frac{1}{r} d(r f') \end{array} \right.$$

$$\frac{\partial^2 u}{\partial z^2} = f'' \frac{z^2}{r^2} + f' \left( \frac{1}{r} - \frac{z^2}{r^3} \right)$$

$$\frac{df}{dx} = \mu \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) = \mu \left[ \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} \right]$$

$$\rho u = f(r)$$

$$u \frac{df}{dx} + k f \frac{\partial u}{\partial x} = (k-1) \mu \left( \frac{\partial u}{\partial r} \right)^2 + \underbrace{\frac{\kappa}{R} \frac{1}{r} \frac{\partial}{\partial r} \left[ r \frac{\partial}{\partial r} \left( \frac{f}{\rho} \right) \right]}_{= -\frac{\kappa}{R} \frac{1}{r} \frac{\partial}{\partial r} \left[ \frac{r}{\rho^2} \frac{\partial \rho}{\partial r} \right]}$$

~~III. Hantogje K=0:~~

$$\frac{\partial}{\partial r} \left( \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} \right) = 0$$

$$\mu \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) = \mu \varphi(x) = \frac{df}{dx}$$

$$\frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) = r \varphi(x)$$

$$r \frac{\partial u}{\partial r} = \frac{r^2}{2} \rho(x) + \psi(x)$$

$$u = \frac{r^2}{4} \varphi(x) + \psi(x) \ln(r) + \chi(x)$$

$$\frac{\partial u}{\partial r} = \frac{r}{2} \varphi(x) + \frac{1}{r} \psi(x)$$

$$\mu = \int \rho(x) dx$$



Stawiamy  $x=0$ :

$$\frac{n^2}{4} [\varphi(x)]^2 + 2 \log \varphi(x) \varphi(x) + \chi(x) \varphi(x) + k \left[ \frac{n^2}{4} \varphi'(x) \int \varphi(x) dx + 2 \log \varphi(x) \int \varphi(x) dx + \chi'(x) \int \varphi(x) dx \right] =$$

$$= (k-1) \left[ \frac{n^2}{4} [\varphi(x)]^2 + \varphi(x) \varphi'(x) + \frac{1}{n^2} [\varphi(x)]^2 \right]$$

Nasi bzi równanie dla dowolnego  $x$ ,  $\forall x$

$$[\varphi(x)]^2 + k \varphi'(x) \int \varphi(x) dx = (k-1) [\varphi(x)]^2$$

$$\varphi(x) \varphi'(x) + k \varphi'(x) \int \varphi(x) dx = 0$$

$$\chi(x) \varphi(x) + k \chi'(x) \int \varphi(x) dx = (k-1) \varphi(x) \varphi'(x)$$

$$0 = \frac{k-1}{n^2} [\varphi(x)]^2 \quad \varphi(x) = 0$$

$$\cancel{\chi} \varphi \pm k \chi' \int \varphi \quad \text{Wsk}$$

$$\frac{\chi}{\chi'} \varphi = -k \int \varphi$$

$$\varphi - \frac{\chi \chi''}{\chi'^2} \varphi + \frac{\chi}{\chi'} \varphi' = -k \varphi$$

$$\varphi \left[ 1 + k \frac{\chi}{\chi'} - \frac{\chi \chi''}{\chi'^2} \right] = -\frac{\chi}{\chi'} \varphi'$$

$$(1+k) \frac{\chi'}{\chi} - \frac{\chi''}{\chi'} = a \frac{4-k}{2-k}$$

$$(1+k) \log \chi - \log \chi' = a \frac{4-k}{2-k} x + a \frac{k-4}{k-2} x$$

$$\frac{\chi'}{\chi^{1+k}} = c e$$

$$\chi^{-k} = \frac{-ck}{k} \int e^{a \frac{k-4}{k-2} x} dx$$

$$\text{Wsk } \cancel{\chi} \int \varphi = \frac{(k-2)}{k} \frac{\varphi^2}{\varphi'}$$

$$k \varphi = \frac{k-2}{k} \left[ 2\varphi - \frac{\varphi^2 \varphi'}{\varphi'^2} \right]$$

$$k-4 = (k-2) \frac{\varphi \varphi''}{\varphi'^2}$$

$$\frac{k-4}{k-2} \frac{\varphi'}{\varphi} = \frac{\varphi''}{\varphi'}$$

$$a \frac{k-4}{k-2} \varphi = \varphi'$$

$$\frac{\varphi'}{\varphi} = a \frac{k-4}{k-2}$$

$$\varphi = b e^{a \frac{k-4}{k-2} x}$$

Należy pamiętać, że na pewnym przedziale musimy być:  
 $u = \text{konstanta dla } r=0$

$$\frac{\delta^2}{4} \varphi(x) + \chi(x) = 0$$

$$\chi(x) = -\frac{\delta^2}{4} \varphi(x)$$

$$\varphi = 0$$

Jeśli wyznaczamy:

$$\varphi^2 + k \varphi' \int \varphi = 0$$

Co musi zadecydować się z równaniem dla  $\varphi$  z tego wynika (niezmienny) do spełnienia jądła  $\kappa=0$  i jądła rachowyjany tamte problemy

Spróbujemy przy  $\kappa \geq 0$ :

$$u = \frac{r^2 - \delta^2}{4} \varphi(x)$$

$$\rho u = f(r):$$

$$\frac{\partial u}{\partial r} = \frac{\kappa}{2} \varphi(x)$$

$$\frac{r^2 - \delta^2}{4} \rho \varphi(x) - \frac{\delta^2}{4} \rho \varphi(x) = \rho u = f(r)$$

$$\frac{\partial}{\partial r} = 0:$$

$$\frac{r^2 - \delta^2}{4} \frac{\partial}{\partial x} (\rho \varphi) = 0$$

$$\frac{\partial \varphi}{\partial x} \varphi + \rho \frac{\partial \varphi}{\partial u} = 0$$

$$\rho \varphi(x) = f(r)$$

$$\frac{1}{\rho} = \frac{\varphi(x)}{f(r)}$$

$$\left\| \frac{1}{r} \frac{\partial}{\partial r} \left[ r \frac{\partial}{\partial r} \frac{1}{f(r)} \right] = F(r) \right\|$$

$$\frac{d\varphi}{dx} = \mu \varphi$$

$$\mu = \mu \int \varphi dx$$

$$\frac{r^2 - \delta^2}{4} \mu \varphi^2 + k \mu \frac{r^2 - \delta^2}{4} \varphi' \int \varphi = \mu(k-1) \frac{r^2}{4} \varphi^2 + \frac{\kappa \varphi(x)}{2} F(r)$$

Musi być pełnym rozwiązaniem dla każdego  $r$  i  $x$



$$(r^2 - \delta^2) [\varphi^2(x) + k \varphi'(x) \int \varphi dx] = (k-1) r^2 \varphi^2(x) + \frac{4k}{R\mu} \varphi(x) F(r)$$

$$r^2 [(2-k) \varphi^2(x) + k \varphi'(x) \int \varphi dx] - \delta^2 [\varphi^2(x) + k \varphi'(x) \int \varphi dx] = \frac{4k}{R\mu} \varphi(x) F(r)$$

$$2r \left[ \right] = \frac{4k}{R\mu} \varphi(x) F'(r)$$

$$2 \left[ \right] = \frac{4k}{R\mu} \varphi(x) F''(r)$$

$$\frac{F''}{F'} = \frac{1}{r}$$

$$\log F' = \log r + \dots$$

$$F' = \text{const} = \frac{dF}{dr}$$

$$F = a r^2 + b$$

$$(2-k) \varphi^2 + k \varphi' \int \varphi = \frac{2ak}{R\mu} \varphi \quad \parallel \quad -\delta^2 [\varphi^2 + k \varphi' \int \varphi] = \frac{4bk}{R\mu} \varphi$$

$$2(2-k) \varphi \varphi' + k \varphi'^2 + k \varphi \varphi' = \frac{2ak}{R\mu} \varphi'$$

$$[2-k] [\varphi^2 \varphi'' - 2\varphi \varphi'^2] = k \varphi'^3 - \frac{2ak}{R\mu} [\varphi \varphi'' - \varphi'^2]$$

$$[2-k] \left[ \frac{\varphi''}{\varphi'} - 2 \frac{\varphi'}{\varphi} \right] - k \frac{\varphi'}{\varphi} = \frac{2ak}{R\mu} \left[ \frac{\varphi''}{\varphi \varphi'} - \frac{\varphi'}{\varphi^2} \right]$$

$$(4-k) \varphi'' = \varphi \left[ \frac{2ak}{R\mu} + \frac{4bk}{\delta^2 R\mu} \right]$$

$\varphi = \text{const}$

$$\text{Wedge product: } \theta = \frac{\mu}{R\rho} = \frac{\mu u}{R\rho u} = \frac{\mu(x) \frac{r^2}{4} \varphi(x)}{R}$$

$$\frac{1}{2} \frac{\partial}{\partial r} \left( r \frac{\partial \theta}{\partial r} \right) = \frac{\mu \varphi}{2} F(r) = \frac{\mu \varphi}{2} \left( \frac{a r^2}{2} + b \right)$$

$$\frac{\partial}{\partial r} \left( r \frac{\partial \theta}{\partial r} \right) = \frac{\mu \varphi}{R} \left[ \frac{a r^3}{2} + b r \right]$$

$$r \frac{\partial \theta}{\partial r} = \frac{\mu \varphi}{R} \left[ \frac{a r^4}{8} + \frac{b r^2}{2} \right] + \text{const}$$

$$\theta = \frac{\mu \varphi}{R} \left[ \frac{a r^4}{32} + \frac{b r^2}{4} \right] + \text{const} \cdot \ln r + \text{const}$$

$$\lambda = \lambda_1 + (\lambda_2 - \lambda_1) \frac{x}{l} \quad \parallel \quad \frac{d\lambda}{dx} = \frac{\lambda_2 - \lambda_1}{l} = \mu \varphi$$

$$\varphi = \frac{\lambda_2 - \lambda_1}{l \mu} = \frac{2 a \kappa}{(2-k) R \mu} = \frac{-4 b \kappa}{\delta^2 R \mu}$$

$$a = - \frac{2 b}{(2-k) \delta^2}$$

$$a = \frac{2-k}{2} \frac{(\lambda_2 - \lambda_1) R}{\delta l \kappa}$$

$$b = - \frac{(2-k) \delta^2}{2} a$$

$$\theta = \frac{\lambda_2 - \lambda_1}{R l \mu} \left[ \lambda_1 + (\lambda_2 - \lambda_1) \frac{x}{l} \right] \left[ \frac{r^4}{32} - \frac{(2-k) \delta^2 r^2}{8} \right] \frac{2-k}{2} \frac{\lambda_2 - \lambda_1}{l \kappa} R \frac{1}{\delta^2} \left[ -\frac{\delta^4}{32} + \frac{(2-k) \delta^4}{8} \right]$$

$$\theta - \theta_0 = \left( \frac{\lambda_2 - \lambda_1}{l} \right)^2 \frac{2-k}{46} \frac{1}{\kappa \mu} \left[ \lambda_1 + (\lambda_2 - \lambda_1) \frac{x}{l} \right] \left[ \frac{r^4 - \delta^4}{4} - (2-k) \delta^2 \left( \frac{r^2 - \delta^2}{2} \right) \right]$$

$$= \frac{1}{4} (r^2 - \delta^2) \left[ \frac{r^2 + \delta^2}{4} - (2-k) \delta^2 \right]$$

$$= \frac{1}{4} (r^2 - \delta^2) \left[ r^2 + (4k-7) \delta^2 \right]$$



$$\rho = \frac{\mu}{R\theta}$$

$$\rho u = \mu \frac{r^2 - \delta^2}{4} \varphi$$

$$R \left[ \theta_0 + \frac{\mu \rho}{R} \cdot \frac{2-k}{64} \frac{\mu^2 - \mu}{2\mu} R (r^2 - \delta^2 - 4(2-k)\delta^2 r^2 + 4(2-k)\delta^4) \right]$$

$$M = 2\pi \int_0^R r \rho u dr = \frac{2\pi \mu \varphi}{2R} \int_0^R \frac{(r^3 - r\delta^2)}{\theta_0 + \dots} dr$$

↓  
Mit maximaler Spannung  
 $\rho u = \mu(r)$

Is same downyminowr:

$$\frac{\partial \rho}{\partial t} = \frac{\partial \mu}{\partial t} = 0 \quad v = \text{max}$$

$$\left\{ \begin{array}{l} \frac{\partial \rho}{\partial x} = \mu \frac{\partial^2 u}{\partial y^2} \\ \frac{\partial \rho u}{\partial x} = 0 \\ u \frac{\partial \rho}{\partial x} + \rho u \frac{\partial u}{\partial x} = (k-1) \mu \left( \frac{\partial u}{\partial y} \right)^2 + \mu \frac{\partial^2 \theta}{\partial y^2} \left( 1 + \frac{\partial^2 \theta}{\partial x^2} \right) \end{array} \right. \rightarrow$$

$$\frac{\partial^3 u}{\partial y^3} = 0$$

$$u = \frac{y^2}{2} \varphi(x) + y \psi(x) + \chi(x)$$

$$\rho u = f(y)$$

$$\frac{\partial \rho}{\partial x} = \mu \varphi(x)$$

$$\rho = \mu \int \varphi(x) dx + \rho_0$$

$$u = \frac{y^2}{2} \frac{1}{\mu} \frac{d\rho}{dx} + y \psi(x) + \chi(x)$$

$$\frac{\partial u}{\partial y} = \frac{y}{\mu} \frac{d\rho}{dx} + \psi(x)$$

$$\theta = \frac{\mu}{R\rho}$$

$$\frac{\partial^2 \theta}{\partial y^2} = \frac{\mu}{R} \frac{\partial^2}{\partial y^2} \left( \frac{1}{\rho} \right)$$

$$\left. \begin{array}{l} u|_{y=0} \\ u|_{y=\delta} \end{array} \right\} u=0$$

$$\chi=0$$

$$y = -\frac{\delta}{2} \quad \varphi(x)$$

$$u = \frac{y(y-\delta)}{2} \frac{1}{\mu} \frac{d\rho}{dx}$$

$$\frac{\partial u}{\partial y} = \frac{2y-\delta}{2\mu} \frac{d\rho}{dx}$$

$$\rho u = \frac{y(y-\delta)}{2\mu} \frac{d\rho}{dx} \rho = f(y)$$

$$\rho = \frac{f(y)}{\frac{d\rho}{dx}} \quad \left\| \frac{1}{\rho} = \frac{d\rho}{f(y)} \right.$$

$$\frac{\partial^2 \theta}{\partial y^2} = \frac{1}{R} \frac{d\rho}{dx} \frac{\partial^2}{\partial y^2} \left[ \frac{1}{f(y)} \right]$$

$$\frac{y^2 - y\delta}{2} \left( \frac{dy}{dx} \right)^2 + k p \frac{d^2 y}{dx^2} \frac{y^2 - y\delta}{2} = (k-1) \left( \frac{2y - \delta}{2} \right)^2 \left( \frac{dy}{dx} \right)^2 + p \frac{dy}{dx} \frac{k}{2} F(y)$$

$$\cancel{\left( \frac{y^2 - y\delta}{2} \right) \left( \frac{dy}{dx} \right)^2}$$

$$\left( \frac{dy}{dx} \right)^2 \left[ \frac{y^2 - y\delta}{2} - (k-1) \left( \frac{2y - \delta}{2} \right)^2 \right] + k p \frac{d^2 y}{dx^2} \frac{y^2 - y\delta}{2} = p \frac{dy}{dx} \frac{k}{2} F(y)$$

$$\left( \frac{dy}{dx} \right)^2 \left[ y - \frac{\delta}{2} - (k-1) \left( \frac{2y - \delta}{2} \right) \right] + k p \frac{d^2 y}{dx^2} \left( y - \frac{\delta}{2} \right) = p \frac{dy}{dx} \frac{k}{2} F(y)$$

$$y^2 \left[ \left( \frac{3}{2} - k \right) \left( \frac{dy}{dx} \right)^2 + \frac{k}{2} p \frac{d^2 y}{dx^2} \right] + y\delta \left[ \left( \frac{k-3}{2} \right) \left( \frac{dy}{dx} \right)^2 - \frac{k}{2} p \frac{d^2 y}{dx^2} \right]$$

$$\left( -\frac{(k-1)\delta^2}{4} \left( \frac{dy}{dx} \right)^2 \right) = p \frac{dy}{dx} \frac{k}{2} F(y)$$

$$(y^2 - y\delta) \left[ \left( \frac{3}{2} - k \right) \left( \frac{dy}{dx} \right)^2 + \frac{k}{2} p \frac{d^2 y}{dx^2} \right]$$

$$(2y - \delta) \left[ \quad \right] = p \frac{dy}{dx} \frac{k}{2} F'(y)$$

$$2 \left[ \quad \right] = \quad F''(y)$$

$$y - \frac{\delta}{2} = \frac{F'}{F''}$$

$$\frac{F''}{F'} = \frac{1}{y - \frac{\delta}{2}}$$

$$\log F' = \log \left( y - \frac{\delta}{2} \right) + \dots$$

$$F' = a \left( y - \frac{\delta}{2} \right)$$

$$F = a \left( \frac{y^2}{2} - y \frac{\delta}{2} \right) + b = \frac{a}{2} y (y - \delta) + b$$



$$(y^2 - y\delta) \left[ \right] - \frac{(k-1)\delta^2}{4} \left( \frac{dy}{dx} \right)^2 = \mu \frac{dy}{dx} \frac{k}{R} \left[ \frac{a}{2} (y^2 - y\delta) + b \right]$$

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$$\left. \begin{aligned} \left( \frac{3}{2} - k \right) \left( \frac{dy}{dx} \right)^2 + \frac{k}{2} \mu \frac{d^2 y}{dx^2} &= \frac{a}{2} \frac{k}{R} \mu \frac{dy}{dx} \\ \frac{(k-1)\delta^2}{4} \left( \frac{dy}{dx} \right)^2 &= -b \frac{k}{R} \mu \frac{dy}{dx} \end{aligned} \right\}$$

$$\frac{1}{\mu} \frac{dy}{dx} = - \frac{4bk}{(k-1)\delta^2 R}$$

$$\mu = A e^{\frac{-4bkx}{(k-1)\delta^2 R}}$$

$$\left( \frac{3}{2} - k \right) \left[ \frac{4bk}{(k-1)\delta^2 R \mu} \right]^{\frac{3-k}{2}} \left[ \frac{3}{2} - k + \frac{k}{2} \right] = - \frac{a}{2} \frac{k}{R \mu}$$

$$\left\{ \begin{aligned} a &= - \frac{4(3-k)b}{(k-1)\delta^2} \end{aligned} \right.$$

$$\frac{\partial^2 \theta}{\partial y^2} = \mu \frac{dy}{dx} \frac{F}{R} = \mu \frac{dy}{dx} \frac{1}{R} \left[ \frac{a}{2} (y^2 - y\delta) + b \right]$$

$$\frac{\partial \theta}{\partial y} = \mu \frac{dy}{dx} \left[ \frac{a}{2} \left( \frac{y^3}{3} - y^2 \frac{\delta}{2} \right) + by \right] + v(x)$$

$$\theta = \mu \frac{dy}{dx} \left[ \frac{a}{2} \left( \frac{y^4}{12} - \frac{y^3 \delta}{6} \right) + b \frac{y^2}{2} \right] + y v(x) + z(x)$$

$$y=0 : \theta_0 = \eta(x)$$

$$y=\delta : \theta_1 = \mu \frac{dy}{dx} \left[ -\frac{a}{2} \frac{\delta^3 y}{12} + b \frac{\delta^2 y}{2} \right] + y v(x) + z$$

$$\theta = \theta_0 + \mu \frac{dy}{dx} \left[ \frac{a}{2} \left( \frac{y^4 + \delta^3 y}{12} - \frac{y^3 \delta}{6} \right) + b \frac{y^2 - y\delta}{2} \right] = \frac{\mu u}{R \rho u}$$

$$R\theta = \frac{f}{\rho}$$

$$R\theta = \frac{f(x)}{f(y)} \cdot \frac{y(y-\delta)}{2\mu} \frac{dy}{dx} = F(y) \mu \frac{dy}{dx} = \frac{c}{2} F(y)$$

Numerators do not increase <sup>da y > 0</sup> or are just

$$f \frac{dy}{dx} = \text{const}$$

$$f^2 = cx + a \quad \left\| \quad f \frac{dy}{dx} = \frac{c}{2}\right.$$

$$u\rho = f = \frac{y(y-\delta)}{2\mu} \cdot \frac{1}{F(y)}$$

~~$$f \frac{dy}{dx} = \frac{c}{2}$$~~

$$f \frac{dy}{dx} = \frac{c}{2} \quad \left\| \quad f \frac{d^2y}{dx^2} + \left(\frac{dy}{dx}\right)^2 = 0\right.$$

$$u = \frac{y(y-\delta)}{2} \cdot \frac{1}{\mu} \frac{dy}{dx}$$

$$\frac{\partial^2 \theta}{\partial y^2} = \frac{c}{2R} F''$$

$$\frac{y^2 - y\delta}{2\mu} \left(\frac{dy}{dx}\right)^2 + k \frac{y^2 - y\delta}{2\mu} \mu \frac{d^2y}{dx^2} = (k-1) \mu \left(\frac{2y-\delta}{2\mu}\right)^2 \left(\frac{dy}{dx}\right)^2 + \frac{kc}{2R} F''(y)$$

$$p = \sqrt{cx+a}$$

$$f \frac{d^2y}{dx^2} = -\frac{c^2}{4(cx+a)}$$

$$\frac{dy}{dx} = \frac{c}{2\sqrt{cx+a}}$$

$$\left(\frac{dy}{dx}\right)^2 = \frac{c^2}{4(cx+a)}$$

$$\frac{d^2y}{dx^2} = \frac{-c^2}{4\sqrt{(cx+a)^3}}$$

$$\left[ (1-k)(y^2 - y\delta) - (k-1) \frac{(2y-\delta)^2}{2} \right] \frac{c^2}{4(cx+a)}$$

$$(1-k) y^2 - y\delta - 2y^2 + 2y\delta$$

Wzic nie spelnia warunku II

(p = p(x) etc)  
Zobaczmy naszymi oczami, czy spelnia warunki I:



Adiabaty

$$\frac{dp}{dx} = \mu \frac{1}{r} \frac{\partial u}{\partial r} \left( r \frac{\partial u}{\partial r} \right)$$

$$\frac{p}{p_0} = \left( \frac{\rho}{\rho_0} \right)^k$$

$$\rho = \rho(x)$$

$$\frac{\partial(\rho u)}{\partial x} = 0$$

$$r^{\frac{1}{k}} \sim \rho$$

$$\rho u = f(x)$$

$$p \text{ minimalne od } r \text{ zato } : \frac{\partial}{\partial r} \left[ \frac{r^2}{2} \frac{\partial u}{\partial r} + \frac{r^2}{2} \frac{\partial u}{\partial r} \right] = 0$$

$$\frac{dp}{dx} = \mu \varphi(x)$$

$$u = \frac{r^2}{4} \alpha x + \gamma x \ln x + \mu(x)$$

$$u = \frac{r^2 - \delta^2}{4} \varphi(x)$$

$$u = \frac{r^2 - \delta^2}{4\mu} \frac{dp}{dx}$$

$$\frac{1}{p_0} \frac{dp}{dx} = \frac{k}{p_0^k} \rho^{k-1} \frac{d\rho}{dx}$$

$$\frac{\partial}{\partial x} \left[ \frac{r^2 - \delta^2}{4\mu} \frac{k p_0}{\rho_0^k} \rho^{\frac{k}{k-1}} \frac{d\rho}{dx} \right] = 0$$

$$\frac{r^2 - \delta^2}{4\mu} \frac{k p_0}{\rho_0^k} \rho^{\frac{k}{k-1}} = \alpha f(x) + \gamma(x) = (r^2 - \delta^2) (Ax + B)$$

$$\rho^{\frac{k+1}{k}} = ax + b$$

$$p^{\frac{k+1}{k}} = ax + b$$

$$\frac{p_2^{\frac{k+1}{k}} - p_1^{\frac{k+1}{k}}}{l} = a$$

$$p^{\frac{k+1}{k}} - p_1^{\frac{k+1}{k}} = \frac{x}{l} (p_2^{\frac{k+1}{k}} - p_1^{\frac{k+1}{k}})$$

etc.

Podobno je pri  
izotermičnem ustlovanju

je  $\frac{1+k}{k}$  namesto 2

Terminacje 2 uogólnieniem  $\frac{\partial u}{\partial x}$

$$\frac{dp}{dx} = \mu \frac{\partial u}{\partial y^2} + \frac{4}{3} \mu \frac{\partial u}{\partial x}$$

$$\frac{\partial(pu)}{\partial x} = 0 = \frac{\partial(pu)}{\partial x}$$

$$\mu u = \varphi(y)$$

$$u = \frac{\varphi(y)}{f(x)}$$

$$\mu = f(x)$$

$$\frac{\varphi^{(4)}}{\varphi^{(3)}} = \frac{\varphi''}{\varphi'}$$

$$f'(x) = \mu \frac{\varphi''(y)}{f(x)} + \frac{4}{3} \mu \varphi(y) \frac{d}{dx} \left[ \frac{1}{f(x)} \right]$$

$$f'(x) f(x) = \mu \varphi''(y) + \frac{4}{3} \mu \varphi(y) f(x) \frac{d}{dx} \left[ \frac{1}{f(x)} \right]$$

$\frac{\partial}{\partial y}$ :

$$0 = \mu \varphi''(y) + \frac{4}{3} \mu \varphi'(y)$$

$$0 = \mu \varphi'''(y) + \frac{4}{3} \mu \varphi''(y)$$

Możliwość tylko jeżeli: ~~to jest~~  
I).

$$f(x) f'(x) = a$$

$$\frac{1}{2} \frac{d}{dx} f^2$$

$$f^2 = 2ax + b$$

$$f^2 = \sqrt{2ax + b}$$

$$f' = \frac{a}{\sqrt{\quad}}$$

$$f'' = -\frac{a^2}{(\sqrt{\quad})^3}$$

$$f(x) \frac{d}{dx} \left[ \frac{1}{f(x)} \right] = c$$

$$\frac{1}{d} - \frac{f'}{f^2}$$

$$-\frac{f''}{f^3} + 2 \frac{f'^2}{f^2} =$$

$$+ \frac{a^2}{(2ax+b)^2} + \frac{2a^2}{(\quad)^2} = c$$

Niemalże oprócz jeżeli  $a=0$

A. z.  $\mu = \text{const}$

Inne możliwości:  $\varphi''(y) = a$   $\varphi(y) = b$  niemalże bo chyba  $a=$

Zatem to wzięło nie ma być przystosowane do warunków początkowych

Jedyną możliwą:  $f = \text{const}$  lub  $\mu u = \text{const}$



Rotations- & ungedrehte Koordinaten  $\rho, \varphi$ ,  $u, v$

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$$\frac{\partial f}{\partial x} = \mu \frac{\partial u}{\partial y^2} + \frac{\mu}{3} \frac{\partial u}{\partial x^2}$$

$$\frac{\partial f}{\partial y} =$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} = 0$$

$$\rho u = \frac{\partial \varphi}{\partial y} \quad \rho v = -\frac{\partial \varphi}{\partial x}$$

$$\frac{\lambda}{\rho} = R\theta$$

$$\frac{v}{u} = -\frac{\frac{\partial \varphi}{\partial x}}{\frac{\partial \varphi}{\partial y}}$$

$$u = \frac{1}{\rho} \frac{\partial \varphi}{\partial y} = \frac{R\theta}{r} \frac{\partial \varphi}{\partial y}$$

$$v = -\frac{1}{\rho} \frac{\partial \varphi}{\partial x} = -\frac{R\theta}{r} \frac{\partial \varphi}{\partial x}$$

$$\frac{\partial u}{\partial x} = \frac{1}{\rho} \frac{\partial^2 \varphi}{\partial x \partial y} - \frac{1}{\rho^2} \frac{\partial \rho}{\partial x} \frac{\partial \varphi}{\partial y}$$

$$\frac{\partial v}{\partial y} = \frac{1}{\rho} \frac{\partial^2 \varphi}{\partial y^2} + \frac{1}{\rho^2} \frac{\partial \rho}{\partial y} \frac{\partial \varphi}{\partial x}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = -\frac{1}{\rho} \left( \mu \frac{\partial \rho}{\partial x} + \nu \frac{\partial \rho}{\partial y} \right)$$

$$= -\frac{1}{\rho^2} \left( \frac{\partial \varphi}{\partial y} \frac{\partial \rho}{\partial x} - \frac{\partial \varphi}{\partial x} \frac{\partial \rho}{\partial y} \right)$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} = -\frac{1}{\rho^2} \left( \frac{\partial \rho}{\partial y} \frac{\partial \varphi}{\partial y} - \frac{\partial \rho}{\partial x} \frac{\partial \varphi}{\partial x} \right) + \frac{1}{\rho} \left( \frac{\partial^2 \varphi}{\partial y^2} - \frac{\partial^2 \varphi}{\partial x^2} \right)$$

$$\frac{\partial v}{\partial x} - \frac{\partial u}{\partial y} = +\frac{1}{\rho^2} \left( \frac{\partial \rho}{\partial y} \frac{\partial \varphi}{\partial y} + \frac{\partial \rho}{\partial x} \frac{\partial \varphi}{\partial x} \right)$$

$$+ \frac{1}{\rho} \left( \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} \right)$$

$$\Phi = \frac{\mu}{3} \left[ \left( \frac{\partial u}{\partial x} \right)^2 - \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \left( \frac{\partial v}{\partial y} \right)^2 \right] + \mu \left[ \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right]^2$$

$$= \frac{1}{\rho^4} \left[ \left( \frac{\partial \varphi}{\partial y} \frac{\partial \rho}{\partial x} \right)^2 + \left( \frac{\partial \varphi}{\partial x} \frac{\partial \rho}{\partial y} \right)^2 \right] + \frac{1}{\rho^2} \left( \frac{\partial^2 \varphi}{\partial x \partial y} \right)^2 - \frac{1}{\rho^3} \frac{\partial^2 \varphi}{\partial x \partial y} \left[ \frac{\partial \rho}{\partial x} \frac{\partial \varphi}{\partial y} + \frac{\partial \rho}{\partial y} \frac{\partial \varphi}{\partial x} \right]$$

$$- \frac{1}{\rho^4} \frac{\partial \rho}{\partial x} \frac{\partial \rho}{\partial y} \frac{\partial \varphi}{\partial x} \frac{\partial \varphi}{\partial y}$$

$$\left[ -\frac{1}{\rho^2} \left( \frac{\partial^2 \varphi}{\partial x \partial y} \right)^2 + \frac{1}{\rho^3} \frac{\partial^2 \varphi}{\partial x \partial y} \left[ \frac{\partial \rho}{\partial x} \frac{\partial \varphi}{\partial y} + \frac{\partial \rho}{\partial y} \frac{\partial \varphi}{\partial x} \right] \right]$$



II).

$$k \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = \frac{4\mu}{3} \left[ \left( \frac{\partial u}{\partial x} \right)^2 - \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + \left( \frac{\partial v}{\partial y} \right)^2 \right] + \mu \left[ \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right]^2$$

$$- \frac{\mu}{3} \left[ u \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + v \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right] - \mu \left[ u \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + v \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \right]$$

$$= \frac{4}{3} \mu \left[ \left( \frac{\partial u}{\partial x} \right)^2 - u \frac{\partial^2 u}{\partial x^2} + \left( \frac{\partial v}{\partial y} \right)^2 - v \left( \frac{\partial^2 v}{\partial y^2} \right) \right] - \frac{4}{3} \mu \left[ \frac{\partial u}{\partial x} \frac{\partial v}{\partial y} + u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 u}{\partial x \partial y} \right]$$

$$u^2 \left[ \frac{1}{u^2} \frac{\partial u}{\partial x} - \frac{1}{u} \frac{\partial^2 u}{\partial x^2} \right] + v^2 \left[ \dots \right]$$

$$= - u^2 \frac{\partial}{\partial x} \left( \frac{1}{u} \frac{\partial u}{\partial x} \right) + \mu \left[ \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 - u \frac{\partial^2 u}{\partial y^2} - v \frac{\partial^2 v}{\partial x^2} \right]$$

$$= - \left[ u^2 \frac{\partial}{\partial x} (\log u) + v^2 \frac{\partial}{\partial y} (\log v) \right] \frac{4}{3} - \left[ u^2 \frac{\partial^2}{\partial y^2} (\log u) + v^2 \frac{\partial^2}{\partial x^2} (\log v) \right]$$

~~Wzrost~~

$$[a_1 x^3 + a_2 x y^2 + a_3] [8a_1 + 2a_2] x + \frac{2\mu}{3} b_2 y + \left[ -\frac{b_2}{3} x^3 + b_2 y^2 x + b_3 \right] \left[ \frac{8}{3} b_2 + 6b_1 \right] x + \frac{2\mu}{3} a_2 y$$

$$+ k \left[ \frac{\mu}{3} + \mu (4a_1 + a_2) x^2 + \frac{2}{3} b_2 x y + \frac{2}{3} b_2 x y \right] [3a_1 x^2 + a_2 y^2 + 2b_2 x y] =$$

		stopień		równanie $\frac{\partial^2 u}{\partial x \partial y}$		równanie	
Jedn.	$\begin{matrix} u \\ v \\ f \end{matrix}$	1	3 + 3	$\frac{\partial^3 v}{\partial x^3} + \frac{\partial^3 v}{\partial x \partial y^2} = \frac{\partial^3 u}{\partial x^2 \partial y} + \frac{\partial^3 u}{\partial y^3}$	:	$x^{n-3} y^3$	0
		2	6 + 6				0
		3	10 + 10				1
		4	15 + 15				3
		5	21 + 21				6
		6	28				

Wzrost do równania dla  $\Phi$ :

Stopień:  $2(n-1)$

0	0
2	6
4	15
6	28
8	45

równanie dla  $\Phi$

prostej rotacji dowolnych:

1	6
2	6
3	5
4	2
5	-3



$$u = e^{a+x}$$

$$v = e^{b+y}$$

$$p = e^{c+x}$$

$$\frac{\partial u}{\partial x} = \frac{\partial}{\partial x} e^x = e^x$$

$$\frac{\partial v}{\partial y} = \frac{\partial}{\partial y} e^y = e^y$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{\partial}{\partial x} e^x = e^x$$

$$\frac{\partial^2 v}{\partial y^2} = \frac{\partial}{\partial y} e^y = e^y$$

$$e^x \frac{\partial}{\partial x} = \left\{ \frac{4}{3} \left[ \frac{\partial^2}{\partial x^2} + \left( \frac{\partial}{\partial x} \right)^2 \right] + \mu \left[ \frac{\partial^2}{\partial y^2} + \left( \frac{\partial}{\partial y} \right)^2 \right] \right\} e^x + \frac{1}{3} \left[ \frac{\partial^2}{\partial x \partial y} + \frac{\partial}{\partial x} \frac{\partial}{\partial y} \right] e^x$$

$$u = x(2ax - y^2) \varphi$$

$$v = x(2ax - y^2) \psi$$

$$\frac{\partial u}{\partial x} =$$

$$u = x(a_1 x^2 + a_2 y^2) + a_3$$

$$v = x(b_1 x^2 + b_2 y^2) + b_3$$

$$\frac{\partial u}{\partial x} = 3a_1 x^2 + 2a_2 xy$$

$$\frac{\partial v}{\partial y} = 2b_2 xy$$

$$\frac{\partial v}{\partial x} = 3b_1 x^2 + b_2 y^2$$

$$\frac{\partial^2 u}{\partial x^2} = 6a_1 x$$

$$\frac{\partial^2 u}{\partial y^2} = 2a_2 x$$

$$\frac{\partial^2 v}{\partial y^2} = 2b_2 x$$

$$\frac{\partial^2 v}{\partial x^2} = 6b_1 x$$

$$\frac{\partial^2 u}{\partial x \partial y} = 2a_2 y$$

$$\frac{\partial^2 v}{\partial x \partial y} = 2b_2 y$$

$$\frac{\partial p}{\partial x} = \frac{4}{3} 6a_1 x + \frac{1}{3} 2b_2 y + \mu 2a_2 x = \mu(8a_1 + 2a_2)x + \frac{2}{3} b_2 y$$

$$\frac{\partial p}{\partial y} = \frac{4}{3} 2b_2 x + \frac{1}{3} 2a_2 y + \mu 6b_1 x = \mu\left(\frac{8}{3} b_2 + 6b_1\right)x + \frac{2}{3} a_2 y$$

$$p = p_0 + \mu(4a_1 + a_2)x^2 + \frac{1}{3} a_2 y^2 + \frac{2}{3} b_2 xy$$

$$\frac{\partial^2}{\partial x \partial y} \log u = \frac{2}{y} \left( \frac{1}{u} \frac{\partial u}{\partial x} \right) = -\frac{1}{u^2} \frac{\partial u}{\partial x} \frac{\partial u}{\partial y} + \frac{1}{u} \frac{\partial^2 u}{\partial x \partial y}$$

$$\frac{2}{3} b_2 = \frac{8}{3} b_2 + 6b_1$$

$$b_2 = -3b_1$$

$$u = a_0 + a_1 x + a_2 y + a_3 x^2 + a_4 xy + a_5 y^2 \quad \left| \quad \frac{\partial u}{\partial x} = a_1 + 2a_3 x + a_4 y \right.$$

$$v = b_0 + b_1 x + b_2 y + b_3 x^2 + b_4 xy + b_5 y^2 \quad \left| \quad \frac{\partial u}{\partial x^2} = 2a_3 \quad \frac{\partial u}{\partial x \partial y} = a_4 \quad \frac{\partial u}{\partial y^2} = 2a_5 \right.$$

$$\frac{\partial^2 v}{\partial x^2} = 2b_3$$

$$\frac{\partial^2 v}{\partial x \partial y} = b_4 \quad \frac{\partial^2 v}{\partial y^2} = 2b_5$$

$$\frac{\partial f}{\partial x} = \frac{4}{3} \mu (2a_3 + b_4) + \mu (2a_3 + 2a_5)$$

$$\frac{\partial v}{\partial y} = b_2 + b_4 x + 2b_5 y$$

$$\frac{\partial f}{\partial x} = \mu \left( \frac{8}{3} a_3 + \frac{b_4}{3} + 2a_5 \right)$$

$$\frac{\partial v}{\partial x} = b_1 + 2b_3 x + b_4 y$$

$$\frac{\partial u}{\partial y} = a_2 + a_4 x + 2a_5 y$$

$$\frac{\partial f}{\partial y} = \mu \left( \frac{8}{3} b_3 + \frac{a_4}{3} + 2b_5 \right)$$

$$f = f_0 + \mu \left( \frac{8}{3} a_3 + \frac{1}{3} b_4 + 2a_5 \right) x + \mu \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 + 2b_5 \right) y$$

$$\mu \left( \frac{8}{3} a_3 + \frac{1}{3} b_4 + 2a_5 \right) (a_0 + a_1 x + a_2 y + a_3 x^2 + a_4 xy + a_5 y^2) +$$

$$\left( \frac{8}{3} b_3 + \frac{1}{3} a_4 + 2b_5 \right) (b_0 + b_1 x + b_2 y + b_3 x^2 + b_4 xy + b_5 y^2) +$$

$$k \left[ f_0 + \mu \left( \frac{8}{3} a_3 + \frac{1}{3} b_4 + 2a_5 \right) x + \mu \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 + 2b_5 \right) y \right] \left[ a_1 + b_1 + (2a_3 + b_4)x + (2b_5 + a_4)y \right]$$

$$= (k-1) \left\{ \frac{4}{3} \mu \left\{ (a_1 + 2a_3 x + a_4 y)^2 + (b_1 + b_4 x + 2b_5 y)^2 - (a_1 + 2a_3 x + a_4 y)(b_1 + b_4 x + 2b_5 y) \right\} \right.$$

$$\left. + \mu \left[ a_2 + b_1 + (a_4 + 2b_3)x + (2a_5 + b_4)y \right]^2 \right\}$$

$$\left( \frac{8}{3} a_3 + \frac{1}{3} b_4 + 2a_5 \right) a_0 + \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 + 2b_5 \right) b_0 + k(a_1 + b_1) \frac{\mu}{\mu} =$$

$$= (k-1) \left[ \frac{4}{3} (a_1^2 + b_1^2 - a_1 b_1) + (a_2 + b_1)^2 \right]$$



$$A a_5 + B b_5 + k B (2b_5 + a_4) = (k-1) \left[ \frac{4}{3} (a_4^2 + 4b_5^2 - 2a_4 b_5) + (2a_5 + b_4)^2 \right] \quad 156$$

$$\text{Přičtením } a_0 = b_0 = a_1 = b_1 = a_5 = b_5 = 0$$

$$\text{tímže } u = v = 0 \text{ máme}$$

$$\begin{aligned} & \left( \frac{8}{3} a_3 + \frac{1}{3} b_4 \right) (a_1 x + a_3 x^2 + a_4 x y) + \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 \right) (b_1 x + b_3 x^2 + b_4 x y) + \\ & + k \left[ \frac{4}{3} + \left( \frac{8}{3} a_3 + \frac{1}{3} b_4 \right) x + \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 \right) y \right] [a_1 + b_1 + (2a_3 + b_4)x + (2b_3 + a_4)y] \\ & - (k-1) \left[ \frac{4}{3} \left\{ (a_1 + 2a_3 x + a_4 y)^2 + (b_1 x)^2 - (a_1 + 2a_3 x + a_4 y) b_1 x \right\} + \right. \\ & \left. [b_1 + (a_4 + 2b_3)x + b_4 y]^2 \right] \end{aligned}$$

6. Přičtením na splnění  $y^2 - x^2 - xy + x + y = 0$

$$u = x(a_1 + a_3 x + a_4 y)$$

$$v = x(b_1 + b_3 x + b_4 y)$$

jinými rovnostmi mezi  $a_i$  a  $b_i$  je  $= 0$

na druhé straně to bychom měli že

$$a_1 : b_1 = a_3 : b_3 = a_4 : b_4$$

$$\begin{aligned} & \left( \frac{8}{3} a_3 + \frac{1}{3} b_4 \right) a_4 x + \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 \right) b_4 x + k \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 \right) [a_1 + b_1 + (2a_3 + b_4)x + (2b_3 + a_4)y] + \\ & + a_4 \left[ \frac{4}{3} + \left( \frac{8}{3} a_3 + \frac{1}{3} b_4 \right) x + \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 \right) y \right] = \end{aligned}$$

$$= (k-1) \left[ \frac{8}{3} a_4 (a_1 + 2a_3 x + a_4 y) - a_4 b_1 x + 2 [b_1 + (a_4 + 2b_3)x + b_4 y]^2 \right]$$

$$k \left\{ \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 \right) a_4 + a_4 \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 \right) \right\} = (k-1) \left( \frac{8}{3} a_4^2 + 2 b_4^2 \right)$$

$$k a_4 \left( \frac{8}{3} b_3 + \frac{1}{3} a_4 \right) =$$

Czy możliwe są rozwiązania formy

$$u = a + e^{\alpha_1 x + \alpha_2 y}$$

$$v = b + e^{\beta_1 x + \beta_2 y}$$

$$\frac{\partial u}{\partial x} = \alpha_1 e^{\alpha_1 x + \alpha_2 y}$$

$$\frac{\partial v}{\partial x} = \beta_1 e^{\beta_1 x + \beta_2 y}$$

$$\frac{\partial u}{\partial y} = \alpha_2 e^{\alpha_1 x + \alpha_2 y}$$

$$\frac{\partial v}{\partial y} = \beta_2 e^{\beta_1 x + \beta_2 y}$$

Znaleźć takie  $u$  i  $v$  które spełniają  $u=0$  i  $v=0$  dla  $x=0$  i  $y=0$

$$r = R \rho \theta$$

$$\rho \frac{\partial \theta}{\partial x} + \theta \frac{\partial \rho}{\partial x} = \left( \frac{u}{3R} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \frac{v}{2} \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \right)$$

$$\rho \left[ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} \right] = - \frac{\partial p}{\partial x} + \frac{4u}{3} \frac{\partial u}{\partial x^2}$$

$$\frac{\partial p}{\partial t} + \frac{\partial (\rho u)}{\partial x} = 0$$

| u

$$\frac{\partial^2 p}{\partial t^2} = - \frac{\partial^2 (\rho u)}{\partial x^2}$$

$$\frac{\partial (\rho u)}{\partial t} + \frac{\partial (\rho u^2)}{\partial x} = - \frac{\partial p}{\partial x} + \frac{4u}{3} \frac{\partial u}{\partial x^2}$$

$$\frac{\partial^2 p}{\partial t^2} = \frac{\partial^2 (\rho u^2)}{\partial x^2} + \frac{\partial^2 p}{\partial x^2} - \frac{4u}{3} \frac{\partial^3 u}{\partial x^3}$$

$$\frac{\partial^2 p}{\partial t^2} = \frac{\partial^2}{\partial x^2} \left[ p + \rho u^2 - \frac{4u}{3} \frac{\partial u}{\partial x} \right]$$

$$= \frac{\partial^2}{\partial x^2} \left[ p(R\theta + u^2) - \frac{4u}{3} \frac{\partial u}{\partial x} \right]$$

Zamieńmy teraz i  $u^2$

$$\frac{c}{A} \rho \left( \frac{\partial \theta}{\partial t} + u \frac{\partial \theta}{\partial x} \right) + \gamma \frac{\partial u}{\partial x} = \Phi + \kappa \nabla^2 \theta$$

$$\frac{\partial p}{\partial t} + u \frac{\partial p}{\partial x} + \kappa p \frac{\partial u}{\partial x} = (k-1) \Phi + (k-1) \kappa \frac{\partial^2 \theta}{\partial x^2}$$



$$\frac{\partial^2 \theta}{\partial t^2} = R \frac{\partial^2}{\partial x^2} (p \theta) = R \left[ p \frac{\partial^2 \theta}{\partial x^2} + 2 \frac{\partial p}{\partial x} \frac{\partial \theta}{\partial x} + \theta \frac{\partial^2 p}{\partial x^2} \right]$$

zamiast tego:  $\theta = a \sin(\alpha x - \beta t)$

$$\frac{\partial^2 p}{\partial t^2} = \frac{\partial^2}{\partial x^2} [R p \theta]$$

$$\frac{\partial p}{\partial t} + p_0 \frac{\partial u}{\partial x} + u \frac{\partial p}{\partial x} = 0$$

$$\frac{R}{k-1} p \frac{\partial \theta}{\partial t} + u \frac{\partial \theta}{\partial x} + \frac{\partial u}{\partial x} = k \frac{\partial^2 \theta}{\partial x^2}$$

$$\frac{R}{k-1} p_0 \frac{\partial \theta}{\partial t} - R \theta_0 \frac{\partial p}{\partial t} = k \frac{\partial^2 \theta}{\partial x^2}$$

Przyjmijmy rozwiązanie:

$$\text{supozycja: } u = a \sin(\alpha x - \beta t)$$

$$p = -p_0 \frac{\alpha}{\beta} \sin(\alpha x - \beta t)$$

W jednowymiarowym zadaniu:  $\rho = \rho_0$

$$\left\{ \begin{array}{l} \frac{dp}{dx} = \frac{4}{3} \mu \frac{d^2 u}{dx^2} \\ u \frac{dp}{dx} + k p \frac{du}{dx} = (k-1) \frac{4}{3} \mu \left( \frac{du}{dx} \right)^2 + (k-1) k \frac{d^2 \theta}{dx^2} \end{array} \right. \quad \theta = \frac{k u}{R p_0 u_0}$$

$$\frac{d\theta}{dx} = \frac{1}{R p_0 u_0} \left[ p_0 \frac{du}{dx} + \frac{4}{3} \mu \left( \frac{du}{dx} \right)^2 + \frac{4}{3} \mu u \frac{d^2 u}{dx^2} \right]$$

$$p = p_0 + \frac{4}{3} \mu \frac{du}{dx}$$

$$\frac{4}{3} \mu u \frac{d^2 u}{dx^2} + k p_0 \frac{du}{dx} + \frac{4}{3} \mu k \left( \frac{du}{dx} \right)^2 = \frac{4}{3} \mu k \left( \frac{du}{dx} \right)^2 - \frac{4}{3} \mu \left( \frac{du}{dx} \right)^2 + (k-1) k \frac{d^2 \theta}{dx^2}$$

$$\frac{4}{3} \mu \left[ u \frac{d^2 u}{dx^2} + \left( \frac{du}{dx} \right)^2 \right] + k p_0 \frac{du}{dx} = (k-1) k \frac{d^2 \theta}{dx^2}$$

$$\frac{4}{3} \mu u \frac{du}{dx} + k p_0 u = (k-1) k \frac{d\theta}{dx} + (k-1) a$$

$$= (k-1) a + \frac{(k-1) k}{R p_0 u_0} \left[ p_0 \frac{du}{dx} + \frac{4}{3} \mu \frac{d}{dx} \left( u \frac{du}{dx} \right) \right]$$

$$\frac{(k-1)\kappa}{R\rho_0 u_0} \left[ \frac{4}{3}\mu \frac{d}{dx} \left( u \frac{du}{dx} \right) + p_0 \frac{du}{dx} \right] - \frac{4}{3}\mu u \frac{du}{dx} = k p_0 u - a(k-1)$$

Z przybliżeniem podanego jako pierwsze przybliżenie:

$$R \frac{dp}{dx} = - \frac{(k-1) p_0}{\rho_0 u_0} \frac{du}{dx}$$

$$\frac{\frac{4}{3}\mu u - \frac{(k-1)\kappa}{R\rho_0 u_0} p_0}{k p_0 u - a(k-1)} du = dx$$

$$\int \frac{\frac{4}{3}\mu u - \frac{(k-1)\kappa}{u_0 \theta_0}}{u - \alpha} du = k p_0 x - b$$

$$= \frac{4}{3}\mu + \frac{4}{3}\mu \alpha - \frac{\frac{(k-1)\kappa}{u_0 \theta_0}}{u - \alpha}$$

$$\frac{4}{3}\mu(u - \alpha) + \left[ \frac{4}{3}\mu \alpha - \frac{(k-1)\kappa}{u_0 \theta_0} \right] \log(u - \alpha) = k p_0 x - b$$



$$\frac{\partial^2 \rho}{\partial t^2} = R \left[ \rho_0 \frac{\partial^2 \theta}{\partial x^2} + 2 \frac{\partial \rho}{\partial x} \frac{\partial \theta}{\partial x} + \theta_0 \frac{\partial^2 \rho}{\partial x^2} \right]$$

$$\rho_0 \frac{\partial \theta}{\partial t} - (k-1) \theta_0 \frac{\partial \rho}{\partial t} = \frac{(k-1) \kappa}{R} \frac{\partial^2 \theta}{\partial x^2} \quad 158$$

$$\frac{\partial^3 \rho}{\partial t^3} = R \theta_0 \frac{\partial^3 \rho}{\partial t \partial x^2} + \kappa (k-1) \frac{\partial^3 \theta}{\partial x^3}$$

↓  
przylżeni

$$\rho_0 \frac{\partial^3 \theta}{\partial t \partial x^2} = (k-1) \theta_0 \frac{\partial^3 \rho}{\partial t \partial x^2} + (k-1) \frac{\kappa}{R} \frac{\partial^3 \theta}{\partial x^3}$$

$$\rho \sim \rho^k \sim \rho^\theta$$

$$\theta \sim \rho^{k-1}$$

$$\gamma_\theta \theta = c + (k-1) \gamma_\rho \rho$$

$$\frac{1}{\rho_0} \frac{\partial^3 \theta}{\partial x^3} = (k-1) \frac{\partial^3 \rho}{\partial x^3} \frac{1}{\rho_0}$$

$$\frac{\partial^3 \rho}{\partial t^3} = R \theta_0 \kappa \frac{\partial^3 \rho}{\partial t \partial x^2} + \kappa \frac{(k-1)^2 \theta_0}{\rho_0} \frac{\partial^3 \rho}{\partial x^3}$$

$$\rho = a \sin(\alpha x - \beta t)$$

$$\alpha^3 = R \theta_0 \kappa \alpha^2 \beta - \frac{\kappa (k-1)^2 \theta_0}{\rho_0} \alpha^3$$

$$\alpha^3 = R \theta_0 \kappa \alpha - \frac{\kappa (k-1)^2 \theta_0}{\rho_0}$$

$$\frac{\beta}{\alpha} = a$$

$$a = \sqrt{k R \theta_0} \text{ jako } I \text{ przylżeni}$$

$$\left[ a^2 - R \theta_0 \right] = - \frac{\kappa (k-1)^2 \theta_0}{\rho_0 \sqrt{k R \theta_0}}$$

$$a = \sqrt{k R \theta_0 - \frac{\kappa (k-1)^2 \theta_0}{\rho_0 a_0}}$$

$$a = \sqrt{a_0^2 - \frac{\kappa (k-1)^2 \theta_0}{\rho_0 a_0^3}}$$

$$= a_0 \left[ 1 - \frac{1}{2} \frac{\kappa (k-1)^2 \theta_0}{\rho_0 a_0^3} \right]$$

$$\frac{1}{2} \frac{(0.4)^2 \cdot 300 \cdot 0.000 \dots}{0.0013 \cdot (33000)^3} /$$

$$\begin{aligned}
& -\frac{2}{3} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + 2 \left( \frac{\partial u}{\partial x} \right)^2 + 2 \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \\
& - u \frac{\partial}{\partial x} \left[ -\frac{2}{3} \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + 2 \mu \frac{\partial u}{\partial x} \right] - v \frac{\partial}{\partial y} \left[ -\frac{2}{3} \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + 2 \mu \frac{\partial v}{\partial y} \right] \\
& - u \frac{\partial}{\partial y} \left[ \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right] - v \frac{\partial}{\partial x} \left[ \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right]
\end{aligned}$$

$$\begin{aligned}
k \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) &= \frac{2}{3} \left[ u \frac{\partial}{\partial x} \mu \text{div} + v \frac{\partial}{\partial y} \mu \text{div} - \mu [\text{div}]^2 \right] \\
& - 2 \left[ u \frac{\partial}{\partial x} \left( \mu \frac{\partial u}{\partial x} \right) + v \frac{\partial}{\partial y} \left( \mu \frac{\partial v}{\partial y} \right) \right] - \mu \left( \frac{\partial u}{\partial x} \right)^2 - \mu \left( \frac{\partial v}{\partial y} \right)^2 \\
& - \left[ u \frac{\partial}{\partial y} \left( \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) + v \frac{\partial}{\partial x} \left( \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) - \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 \right]
\end{aligned}$$

$$= \frac{2}{3} \left\{ u^2 \left[ \frac{1}{u} \frac{\partial}{\partial x} \left( \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right) \right] - \frac{1}{u^2} \frac{\partial u}{\partial x} \cdot \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right\} + v^2 \left\{ \frac{1}{v} \frac{\partial}{\partial y} \left( \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) - \frac{1}{v^2} \frac{\partial v}{\partial y} \left( \mu \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right) \right) \right\}$$

~~1~~ + -

$$\begin{aligned}
& = \frac{2}{3} \left[ u^2 \frac{\partial}{\partial x} \left( \mu \frac{\left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)}{u} \right) + v^2 \frac{\partial}{\partial y} \left( \mu \frac{\left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)}{v} \right) \right] \\
& - 2 \left[ u^2 \frac{\partial}{\partial x} \left( \mu \frac{\frac{\partial u}{\partial x}}{u} \right) + v^2 \frac{\partial}{\partial y} \left( \mu \frac{\frac{\partial v}{\partial y}}{v} \right) \right] - \left[ u^2 \frac{\partial}{\partial y} \left( \mu \frac{\left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)}{u} \right) + v^2 \frac{\partial}{\partial x} \left( \mu \frac{\left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)}{v} \right) \right]
\end{aligned}$$

$$2(k-1) \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)$$



~~W~~ Równanie mechaniczne poddane:  $p = \sqrt{cx+a} + \varphi$

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$$u = \frac{y(y-\delta)}{2\mu} \frac{dp}{dx} + \varphi$$

$$\left\{ \begin{array}{l} \frac{\partial p}{\partial x} = \mu \frac{\partial^2 u}{\partial y^2} \\ \frac{\partial p}{\partial y} = \frac{\mu}{3} \frac{\partial^2 u}{\partial x \partial y} \end{array} \right.$$

$$\frac{\partial(pu)}{\partial x} = 0$$

$$u \frac{\partial p}{\partial x} + k p \frac{\partial u}{\partial x} = (k-1)\mu \left(\frac{\partial u}{\partial y}\right)^2 + \kappa(k-1) \frac{\partial^2 \theta}{\partial y^2}$$

$$u = \frac{y(y-\delta)}{4\mu} \cdot \frac{-c}{\sqrt{cx+a}} + \varphi \quad \parallel \quad \frac{\partial u}{\partial y} = \frac{2y-\delta}{4\mu} \cdot \frac{c}{\sqrt{cx+a}} + \frac{\partial \varphi}{\partial y} \quad \left\| \quad \frac{\partial^2 u}{\partial y^2} = \frac{c}{2\mu \sqrt{cx+a}} + \frac{\partial^2 \varphi}{\partial y^2} \right.$$

$$\frac{\partial u}{\partial x} = \frac{y(y-\delta)}{8\mu \sqrt{cx+a}^3} \cdot c^2 + \frac{\partial \varphi}{\partial x} \quad \frac{\partial^2 u}{\partial x \partial y} = \frac{-(2y-\delta)c^2}{8\mu \sqrt{cx+a}^3} + \frac{\partial^2 \varphi}{\partial x \partial y}$$

$$\frac{c}{2\sqrt{cx+a}} + \frac{\partial \varphi}{\partial x} = \mu \frac{c}{2\mu \sqrt{cx+a}} + \mu \frac{\partial^2 \varphi}{\partial y^2} \quad \left. \begin{array}{l} \\ \frac{\partial \varphi}{\partial y} = \frac{\mu}{3} \left[ \frac{-(2y-\delta)c^2}{8\mu \sqrt{cx+a}^3} + \frac{\partial^2 \varphi}{\partial x \partial y} \right] \end{array} \right\} \text{Hamilton!}$$

$$\kappa(k-1) \frac{\partial^2 \theta}{\partial y^2} = \frac{y(y-\delta)}{4\mu} \frac{-c}{\sqrt{cx+a}} \cdot \frac{-c}{2\sqrt{cx+a}} = k \sqrt{cx+a} \frac{y(y-\delta)c^2}{8\mu \sqrt{cx+a}^3}$$

$$-(k-1)\mu \frac{(2y-\delta)^2}{16\mu^2} \frac{c^2}{(cx+a)}$$

$$\begin{aligned} \kappa \frac{\partial^2 \theta}{\partial y^2} &= \frac{-2y(y-\delta) - (2y-\delta)^2}{16\mu^2} \frac{c^2}{(a-cx)} = \frac{-\delta^2 + 4y\delta - 4y^2 + 2y\delta - 2y^2}{16\mu^2} \frac{c^2}{a-cx} \\ &= - \frac{(\delta^2 - 6y\delta + 6y^2)}{16\mu^2} \frac{c^2}{a-cx} \end{aligned}$$

$$N.p. \quad y = \frac{\delta}{2}$$

$$\delta^2 - 3\delta^2 + \frac{6}{4} = -\frac{\delta^2}{2}$$

$$y^2 - y\delta + \frac{\delta^2}{4} = 0$$

$$y = \frac{\delta}{2} \pm \sqrt{\frac{\delta^2}{4} - \frac{\delta^2}{4}} = \frac{\delta}{2} \pm \frac{\delta}{\sqrt{12}}$$

$$k \frac{d\theta}{dy} = - \frac{(\delta^2 y - 3\delta y^2 + 2y^3)}{16\mu} \frac{c^2}{a-cx} \quad y = \frac{\delta}{2}$$

$$y = \frac{\delta}{2}$$

$$\frac{d\theta}{dy} = 0$$

$$\frac{1}{2} - \frac{2}{4} + \frac{1}{4}$$

$$k \theta = - \frac{(\delta^2 y^2 - 2\delta y^3 + \frac{y^4}{4})}{32\mu} \frac{c^2}{a-cx} + b$$

$$\theta = \theta_0 - \frac{\delta^2 (y - \frac{\delta}{2})^2}{32\mu k} \frac{c^2}{a-cx}$$

$$\text{Maximum } y = \frac{\delta}{2}$$

$$\theta = \theta_0 - \frac{\delta^4}{128\mu k} \frac{c^2}{a-cx}$$

$$= \theta_0 - \frac{\delta^4}{128\mu k} \frac{c^2}{r^2}$$

$$\frac{15 \cdot 8}{16 \cdot 7}$$

$$\frac{1}{3}$$

Podobnie przy symetrycznej walce:

$$u = \frac{r^2 - \delta^2}{8\mu} \frac{-c}{\sqrt{a-cx}} \quad \parallel \quad \lambda = \sqrt{a-cx}$$

$$\frac{d\lambda}{dx} = \mu \frac{1}{2} \frac{\partial}{\partial x} \left( r \frac{\partial u}{\partial r} \right)$$

$$u \frac{d\lambda}{dx} + k \lambda \frac{du}{dx} = (k-1) \mu \left( \frac{\partial u}{\partial r} \right)^2 + (k-1) k \cdot \frac{1}{2} \frac{\partial}{\partial x} \left( r \frac{\partial u}{\partial r} \right)$$

$$\frac{d\lambda}{dx} = \frac{-c}{2\sqrt{a-cx}}$$

$$\frac{\partial u}{\partial x} = \frac{r^2 - \delta^2}{8\mu} \frac{-c^2}{\sqrt{a-cx}^3}$$

$$\frac{\partial u}{\partial r} = \frac{r}{4\mu} \frac{-c}{\sqrt{a-cx}}$$

$$\frac{c^2}{2} \frac{r^2 - \delta^2}{8\mu} \frac{1}{\sqrt{a-cx}} - k \frac{r^2 - \delta^2}{8\mu} \frac{c^2}{\sqrt{a-cx}} - (k-1) \mu \frac{r^2}{16\mu^2} \frac{c^2}{\sqrt{a-cx}} = (k-1) k \frac{1}{2} \frac{\partial}{\partial x} \left( r \frac{\partial u}{\partial r} \right)$$

$$\frac{r^2}{2} \frac{\partial}{\partial x} \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) \right) = \frac{r^2}{2} \frac{\partial}{\partial x} \left( \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) \right)$$



$$\frac{1}{x} \frac{\partial}{\partial x} \left( x \frac{\partial \theta}{\partial x} \right) = \frac{1}{k\mu} \frac{-(\delta^2 - r^2)c^2 - \kappa^2 c^2}{16(a - cx)} = \frac{c^2}{16k\mu} \frac{\delta^2 - 2r^2}{a - cx}$$

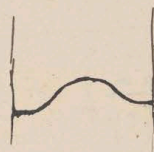
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$$\frac{\partial \theta}{\partial x} = \frac{c^2}{16k\mu} \frac{\delta^2 - 2r^2}{a - cx}$$

$$x \frac{\partial \theta}{\partial x} = \frac{c^2}{16k\mu} \frac{\frac{\delta^2 x^2}{2} - \frac{r^4}{2}}{a - cx} + b$$

$$\frac{\partial \theta}{\partial x} = \frac{c^2}{32k\mu} \frac{2\delta^2 - r^3}{a - cx} + \frac{b}{x}$$

$$\begin{cases} \theta = \frac{c^2}{32k\mu} \frac{\frac{r^2 \delta^2}{2} - \frac{r^4}{4}}{a - cx} + \frac{b}{2} \ln x + m \\ \theta_0 = \frac{\frac{\delta^2}{4}}{a - cx} + n \end{cases}$$



$$\theta = \theta_0 - \frac{c^2}{128k\mu} \frac{(\delta^2 - r^2)^2}{a - cx} = \theta_0 - \frac{(\delta^2 - r^2)^2}{128k\mu} \left[ \frac{r_1^2 - r_2^2}{l_f} \right]^2$$

$$\left. \begin{aligned} r_1^2 &= \delta^2 \\ r_2^2 &= a - cl \end{aligned} \right\} \frac{r_1^2 - r_2^2}{l} = c \quad r = \frac{\delta}{2}$$

$$\text{Minimum: } \theta = \theta_0 - \frac{\delta^4}{k\mu} \frac{9}{16 \cdot 128} \left[ \frac{r_1^2 - r_2^2}{l_f} \right]^2$$

$$\begin{aligned} & \frac{100}{240} \cdot \frac{10^6}{2} \cdot \frac{10^6}{10} \cdot \frac{10^6}{10} \cdot \frac{10^6}{10} \\ & \frac{100}{240} \cdot \frac{10^6}{2} \cdot \frac{10^6}{10} \cdot \frac{10^6}{10} \cdot \frac{10^6}{10} \end{aligned}$$

$$\begin{aligned} N.p. \quad \delta &= 0.01 \\ r_1 &= 10^6 \parallel r_2 = \frac{3}{4} \cdot 10^6 \\ l &= 10 \\ \kappa &= 0.00006 \\ \mu &= 0.00017 \end{aligned}$$

$$\begin{aligned} & \frac{1}{240} \left[ \frac{1}{2} \frac{10^6}{10} \right]^2 \cdot \frac{10^{-8}}{1.7 \cdot 6 \cdot 10^9 \cdot 42 \cdot 10^6} \\ & = \frac{10^5}{240 \cdot 4 \cdot 10 \cdot 42} = \frac{10^3}{96 \cdot 42} \end{aligned}$$

$$= \frac{10}{40} = \frac{1}{4} ^\circ \text{C}$$

$$\left. \begin{aligned} \text{Izračun robne n.p.} \quad \delta &= 0.02 \\ l &= 5 \text{ cm} \\ r_2 &= \frac{1}{2} r_1 \end{aligned} \right\} \text{bedeniny miki}$$

$$\Delta \theta = \frac{1}{4} \cdot 16 \cdot 4 \cdot 3 = 48^\circ !!$$

Wzajemny przypadek gdy stosunek  $\theta$  stały i determinuje tylko  $\theta_0$ .

$$\theta = \theta_0 + \varphi$$

$$r = R \rho(\theta_0 + \varphi)$$

$$\rho = \frac{r}{R(\theta_0 + \varphi)}$$

$$\frac{\partial}{\partial x} \left( \frac{ru}{\theta_0 + \varphi} \right) + \frac{\partial}{\partial y} \left( \frac{rv}{\theta_0 + \varphi} \right) = 0$$

$$ru \cdot \left( 1 - \frac{\varphi}{\theta_0} \right)$$

$$\frac{\partial}{\partial x} (ru) + \frac{\partial}{\partial y} (rv) + \frac{1}{\theta_0} \left[ \frac{\partial(\varphi u)}{\partial x} + \frac{\partial(\varphi v)}{\partial y} \right] = 0$$

$$\frac{\partial}{\partial x} \left[ ru \cdot \left( 1 - \frac{\varphi}{\theta_0} \right) \right]$$

$$II. \quad \frac{\partial}{\partial x} (ru) + \frac{\partial}{\partial y} (rv) - \frac{r \left[ u \left( \frac{\partial \varphi}{\partial x} + v \frac{\partial \varphi}{\partial y} \right) \right]}{\theta_0 - \varphi} = 0$$

$$III. \quad u \frac{\partial k}{\partial x} + v \frac{\partial k}{\partial y} + k r \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = (k-1) \Phi + (k-1) k \Delta^2 \varphi$$

$$\theta = \theta_0 + \varphi$$

$$r = R \rho(\theta_0 + \varphi) = r + \varphi$$

Wtedy w og  
wzajemnie jest  
zatem tylko  
 $ru \frac{\partial k}{\partial x}$

Przy tym ~~istotnie~~  $\frac{\partial \theta}{\partial z} = 0$  dla powierzchni zate (niektóre nie uderzyły)  
ciepła [wzrost to jest faktycznie przybliżone wzajemnie z odniesienia -- =  $\Phi + k \Delta^2 \theta$   
do nich =  $\Phi$  (to stały mierzalność  $\frac{\partial u}{\partial z} = 0$  tylko na powierzchni!)]

Należy zatem tu ~~zgodnie~~ zgodzić się iż nie tylko powierzchnie nie wstępują  
zmienną, po upływie, mimo iż istnieją nie są oddzielone.

byłoby wzajemnie istnieć gdyby  $k = \infty$ .



II pythion:

$$\frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) - \underbrace{R \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} \right)}_{= R \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} \right)} = 0$$

Integrace: by unaliv  $\theta = \text{const}$  // žile  $k=0$

$$\begin{aligned} \frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) &= 0 = u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \\ \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) &= -\frac{\mu}{3} \left[ u \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + v \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right] \\ &\quad - \mu \left[ u \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + v \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) \right] \end{aligned} \quad \left. \vphantom{\frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v)} \right\} \text{I+II}$$

2 druzij stromy

$$\rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = \Phi \quad \text{zato dyba magsraty byl:}$$

$$\begin{aligned} & \frac{\mu}{3} \left[ u \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + v \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) \right] + u \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + v \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) + \\ & - \frac{2}{3} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + 2 \left( \frac{\partial u}{\partial x} \right)^2 + 2 \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 \end{aligned}$$

Najpustej davor i gubie nennatim pythody zidnagynisave!

Podobitost dynamice

$$\frac{\partial \rho}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$\frac{\partial}{\partial x}(\rho u) + \frac{\partial}{\partial y}(\rho v) = 0$$

$$u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + k \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = (k - \mu) \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \dots \right] + k \left[ \frac{\partial^2 \theta}{\partial x^2} + \dots \right]$$





$$\frac{1}{2\theta} \left[ \mu \frac{\partial u}{\partial x} + \nu \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right] + \frac{\partial \lambda}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) + \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)$$

I = X 162  
II  
III

$$\frac{\partial}{\partial x} \varphi(x) + \frac{\partial}{\partial y} \varphi(y) = 0$$

$$\mu \frac{\partial u}{\partial x} + \nu \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} + k \mu \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = (k-1) \mu \Phi + k \nabla^2 \varphi$$

$$I). \quad \frac{b}{r} \frac{m^2}{n} \equiv \frac{b}{n} \equiv \alpha \frac{m}{n^2} = \frac{b}{n}$$

$$II). \quad m \frac{b}{n} \equiv \alpha \frac{m^2}{n^2} \equiv \beta \frac{r}{n^2}$$

$$I). \quad b \left( \frac{m^2}{n} + 1 \right) \equiv \alpha \frac{m}{n}$$

$$II). \quad b m \equiv \alpha \frac{m^2}{n} + \beta \frac{r}{n}$$

$$I). \quad \text{Kürzungsatz} \quad \alpha = 1 \quad \beta = 1$$

$$b \left( \frac{m^2}{n} + 1 \right) \equiv \frac{m}{n}$$

$$b m \equiv \frac{m^2}{n} + \frac{r}{n}$$

$$1). \quad \text{Kürzungsatz} \quad r = 1: \quad \left. \begin{aligned} b \left( \frac{m^2}{n} + 1 \right) &\equiv \frac{m}{n} \\ b m &\equiv \frac{m^2}{n} + \frac{1}{n m} \end{aligned} \right\} \quad b \frac{m^2}{n} \equiv \frac{1}{n m}$$

$$\frac{m^2}{n} + \frac{r}{n m} \equiv \frac{m}{n}$$

$$(m^2 + 1) \left( m + \frac{1}{m} \right) \equiv m$$

$$(m^2 + 1)^2 \equiv m$$

Kürzungsatz

$$\frac{m}{n} + \frac{r}{n m} \left( \frac{m^2}{n} + 1 \right) \equiv \frac{r}{n}$$

$$\text{Rohre rot} \quad r = -m^2$$

$$m^2 + (m^2 + r) \equiv m^2$$

Kürzungsatz!

Zaniedbyte gródku męgi kinst:

~~II.  $b = \alpha \frac{m}{n}$~~

~~III.  $b \frac{m}{n} = \alpha \frac{m^2}{n^2} + \rho \frac{r}{n^2}$~~

~~$\alpha \frac{m^2}{n^2} = \alpha \frac{m^2}{n^2} + \rho \frac{r}{n^2}$~~

~~Nimmolte!~~

II.  $\frac{b}{n} m^2 = b = \alpha \frac{m}{n}$

III.  $mb = \alpha \frac{m^2}{n} = \rho \frac{r}{n}$

~~$\alpha = \rho$~~   
3 równania męgi 6 wielkości  
3 dozwolone

IV.  ~~$m^2 = r$~~

$m^2 = r$

$\alpha \frac{m^2}{n} = \rho \frac{r}{n}$

$\alpha = \rho$

$\alpha m^2 = \rho r$

$\alpha r = \rho r$

zatem powyższe  
2 dozwolone

$b = \alpha \frac{m}{n} = b \frac{m^2}{r}$

$mb = \alpha \frac{r}{n}$  }  $m^2 = r$   
 }  $b = \alpha \frac{m}{n}$   
 }  $\alpha = \rho$

powyższe 2 równania:

$b = \alpha \frac{m}{n} = b \frac{m^2}{r}$  }  $\left\{ \begin{array}{l} b = \alpha \frac{m}{n} \\ r = m^2 \end{array} \right\}$



$$b = 2 \frac{m}{n}$$

$$r = m^2$$

5 wielkości z których 3 dowolne 163

Przykład:

określenie kątów tworzących obrot

$$1). \text{ Niezmienność } \begin{cases} k \mu : \alpha = 1 \\ \theta : r = 1 \end{cases}$$

$$\mu = 1$$

$$b = \frac{1}{n}$$

Tj. Rozmiary w rozprzeczności, obrotu  $\frac{1}{n}$  zmniejszają wartość nianiania  
Względnie pewnie o białe; masę przesyła. nianian.

$$2). \text{ Niezmienność } k \mu : \alpha = 1$$

$$\text{zmniejszenie: } n = 1$$

$$b = m \quad r = m^2$$

to same takie dla  
rodzaju 2 oraz 3  
zmniejszają

Obrotowe przemieszczenia w rozprzeczności: nie należy obrotu w rozprzeczności, tylko w rozprzeczności

Różnica między pewnymi obrotami: jeżeli 2 przemieszczenia w rozprzeczności, to pewnie  
w rozprzeczności, to pewnie w rozprzeczności [tylko, nie  $m^2$ ] w rozprzeczności, a tym samym w rozprzeczności.

Względnie zmniejszenie kątów od tęg i kłódgi j. prop.  $\theta$ :

$$I). \left. \begin{aligned} \frac{b}{n} m^2 = b = r \frac{m}{n} \\ r = m^2 \quad b = \frac{m^3}{n} \end{aligned} \right\}$$

$$II). \left. \begin{aligned} m b = \frac{r^2}{n} \\ \frac{m^4}{n} = \frac{m^4}{n} \end{aligned} \right\} \text{ same pewnie w rozprzeczności}$$

Przestępniki:  $r = m^2 \quad b = \frac{m^3}{n}$

1). Przestępniki takie same

$$2). \underline{n=1} \quad \text{~~Przestępniki~~ } r = m^2 \quad b = m^3$$

III)  
a

$$a=1$$

~~III)~~

$$m = \frac{1}{n}$$

$$b = \frac{1}{n^2}$$

$$r = \frac{1}{n^2}$$

Wz: ~~Wz~~ porównanie wartości w rozg; zmniejszenie prędkości  $\frac{1}{n}$   
 odleg. od źródła i temp. zmniejsz.  $\frac{1}{n^2}$  (porówn. Helmholtza)

IV)

$$a=1$$

$$m=n$$

$$b=1$$

$$r=n^2$$

[Ogólny sposób wyznaczenia wartości przy tej analizie nie jest konieczny]

$$\cancel{r^2 \varphi'' \varphi + 2r \varphi \varphi' - r^2 \varphi'^2 + b(2\varphi + r\varphi')(r_0 + 2\varphi + r\varphi')} = 0$$

$$r^2 \varphi'' \varphi + 2r \varphi \varphi' + \varphi^2 + r \varphi \varphi' + r^2 \varphi'^2 + k[r\varphi + r\varphi'](r_0 + 2\varphi + r\varphi') - \varphi^2 - r \varphi \varphi' - r^2 \varphi'^2 = 0$$

$$r^2(\varphi'' \varphi + \varphi'^2) + \varphi^2 + 4r \varphi \varphi'$$

$$\left. \begin{aligned} r^2 d(\varphi \varphi') + 2r \varphi \varphi' + d(r \varphi^2) \\ d(r^2 \varphi \varphi') \end{aligned} \right\} = \frac{d[r \varphi (\varphi + r \varphi')]}{= \frac{1}{2} d[r \varphi^2 + r^2 \varphi \varphi']} = \frac{1}{2} d^2(r^2 \varphi^2)$$

$$r^3 \varphi'' \varphi + 4r^2 \varphi \varphi' + r \varphi^2 + r^3 \varphi'^2$$

$$r^3 d(\varphi \varphi') + 3r^2 \varphi \varphi' + \frac{1}{2} d(r^2 \varphi^2)$$

$$d(r^3 \varphi \varphi') + \frac{1}{2} d(r^2 \varphi^2) + k[r_0 d(r^2 \varphi) + 3\varphi^2 r + 3\varphi \varphi' r^2] = 0$$

$$r^3 \varphi \varphi' + \frac{r^2 \varphi^2}{2} + k r_0 r^2 \varphi + \frac{3}{2} k r^2 \varphi^2 = a$$

$$\cancel{r^3 \varphi \varphi'} + r^3 \varphi \varphi' + \frac{r^2 \varphi^2}{2} (1+3k) + k r_0 r^2 \varphi = a$$



Wzrosty kotowy dwuramiowy:

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$$u = x \frac{x}{r} \quad \parallel \quad v = 2 \frac{y}{r}$$

$$= \varphi x \quad = \varphi y$$

$$\frac{\partial u}{\partial x} = \varphi + \varphi' \frac{x^2}{r}$$

$$\frac{\partial^2 u}{\partial x^2} = \varphi' \frac{3x}{r} - \varphi' \frac{x^3}{r^3} + \varphi'' \frac{x^3}{r^2}$$

$$\frac{\partial u}{\partial x} + \frac{\partial^2 u}{\partial y^2} = \varphi' \frac{3x}{r} + \varphi'' x$$

$$\left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = 2\varphi + \varphi' r$$

$$\frac{\partial}{\partial x} = 3\varphi' \frac{x}{r} + \varphi'' x =$$

$$\frac{d\varphi}{dr} \cdot \frac{x}{r} = \frac{4\mu}{3} (\varphi'' x + 3\varphi' \frac{x}{r})$$

$$I). \frac{d\varphi}{dr} = \frac{4\mu}{3} (\varphi'' r + 3\varphi')$$

$$II). \varphi x \cdot \frac{x}{r} + \varphi r \frac{4\mu}{3} (\varphi'' r + 3\varphi') + k p (2\varphi + r\varphi') =$$

$$= \frac{(k-1)^2}{3} \varphi^2 + \frac{4}{3} r \varphi \varphi' + \frac{4}{3} r^2 \varphi'^2 = \frac{(k-1)}{3} [\varphi^2 + r \varphi \varphi' + r^2 \varphi'^2]$$

$$I). \frac{d\varphi}{dr} = \frac{4\mu}{3} \frac{d}{dr} [\varphi' r + 2\varphi]$$

$$p = \frac{4\mu}{3} [\varphi' r + 2\varphi] + p_0 \frac{4\mu}{3}$$

$$\Phi = -\frac{1}{3} (2\varphi + r\varphi')^2 + 4\varphi^2 + 2\varphi'^2 \frac{x^4 + y^4}{r^2}$$

$$+ 4\varphi \varphi' r + 4\varphi'^2 \frac{x^2 y^2}{r^2}$$

$$= -\frac{2}{3} (2\varphi + r\varphi')^2 + 4\varphi^2 + 4\varphi \varphi' r + 2r^2 \varphi'^2$$



$$r^3 \varphi' + \frac{r^2 \varphi^2}{2} (1+3k) + k p_0 r^2 \varphi = a$$

$$r \varphi = z$$

$$r d\varphi + \varphi dr = dz$$

$$r \varphi' = \frac{dz}{dr} - \frac{z}{r}$$

$$z \left( r \frac{dz}{dr} - z \right) + \frac{z^2}{2} (1+3k) + k p_0 r z = a$$

$$\frac{z}{r} \frac{dz}{dr} + \frac{z^2}{2} \left( \frac{3k-1}{2} \right)$$

$$z \frac{dz}{dr} + \frac{z^2}{2} \frac{3k-1}{2} + k p_0 z = \frac{a}{r}$$

$$r^2 \varphi = z$$

$$\varphi = \frac{z}{r^2}$$

$$\varphi' = \frac{1}{r^2} \frac{dz}{dr} - \frac{2z}{r^3}$$

$$r z \left( \frac{1}{r^2} \frac{dz}{dr} - \frac{2z}{r^3} \right) + \frac{z^2}{r^2} \frac{1+3k}{2} + k p_0 z = a$$

$$z \frac{dz}{dr} - \frac{2z^2}{r^2} + \frac{z^2}{r^2} \left( \frac{1+3k}{2} \right) + k p_0 z = a$$

$$z \frac{dz}{dr} + \frac{z^2}{r^2} \frac{3(k-1)}{2} + k p_0 z = a$$

$$r \varphi^2 = z$$

$$r \varphi \varphi' = \frac{1}{2r} \frac{dz}{dr} - \frac{z}{r^2}$$

$$\frac{1}{2} \left( r^2 \frac{dz}{dr} - rz \right) + rz \left( \frac{1+3k}{2} \right) + k p_0 r^2 \varphi = a$$

$$r^2 \varphi = y^2$$

$$z + r \frac{dz}{dr} = 2y \frac{dy}{dr}$$

$$\frac{1}{2} y \frac{dy}{dr} - \frac{y^2}{2} + \frac{y^2}{2} \left( \frac{1+3k}{2} \right) + k p_0 r^2 \varphi = a$$

$$y \frac{dy}{dr} + \frac{y^2}{2} \frac{3k-1}{2} + k p_0 y = \frac{a}{r}$$

$$z \frac{dz}{dr} + \frac{z^2}{2} \frac{3k+1}{2} + k p_0 \frac{z}{r} = \frac{a}{r^3}$$



$$z \frac{dz}{dr} \frac{dr}{dr} + z^k \varphi \frac{3k-1}{2} + k p_0 z = \frac{a \varphi}{z}$$

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~~$$\varphi = \frac{z}{r}$$~~

$$z + \varphi \frac{dz}{dr} = \frac{dz}{dr}$$

$$\frac{dr}{dz} = \frac{\varphi^2}{\varphi \frac{dz}{dr} - z}$$

$$\varphi^2 \frac{dr}{dz} = \varphi \frac{dz}{dr} - z$$

$$z \varphi^2 \frac{dz}{dr} + \left( z \varphi \frac{3k-1}{2} + k p_0 z - \frac{a \varphi}{z} \right) \left( \varphi \frac{dz}{dr} - z \right) = 0$$

$$z^2 \varphi = z$$

$$\frac{dr}{dz} = \frac{\varphi \frac{dz}{dr} - z}{2 \varphi \sqrt{p_0 z}}$$

$$\varphi r^2 + 2z \frac{dz}{dr} \varphi^2 = \frac{dz}{dr} \varphi$$

$$z \frac{dz}{dr} 2 \varphi \sqrt{p_0 z} + \left( \varphi \frac{dz}{dr} - z \right) \left[ z^k \varphi \frac{3(k-1)}{2} + k p_0 z - a \right] = 0$$

$$\rightarrow z = u \cdot v$$

$$u v \left( u \frac{dv}{dr} + v \frac{du}{dr} \right) + \frac{u^2 v^2}{r^2} \frac{3(k-1)}{2} + k p_0 u v = \frac{a}{2}$$

$$u^2 \left[ v \frac{dv}{dr} + \frac{v^2}{r^2} \frac{3(k-1)}{2} \right] + u \left[ v^2 \frac{du}{dr} + k p_0 v \right] = \frac{a}{2}$$

$$\frac{du}{dr} = - \frac{k p_0}{v}$$

$$+ u^2 k p_0 \left[ - \frac{1}{\left( \frac{du}{dr} \right)^2} \frac{d^2 u}{dr^2} \right] + \frac{u^2 3k-1}{2 r^2} \frac{k^2 p_0^2}{\left( \frac{du}{dr} \right)^2} = \frac{a}{2}$$

$$v = - \frac{k p_0}{\frac{du}{dr}}$$

$$\frac{1}{v} \frac{dv}{dr} + \frac{3k-1}{2} \frac{1}{r} = 0$$

$$\gamma v = - \frac{3k-1}{2} \gamma r$$

$$v = A r^{-\frac{3k-1}{2}}$$

~~$$u \left( \frac{du}{dr} + k p_0 \frac{1}{v} \right) = \frac{a}{2 v}$$~~

$$u \frac{du}{dr} + k p_0 u A r^{\frac{3k-1}{2}} = \frac{a}{A^2} r^{-\frac{1-3k-1}{2}} = \frac{a}{A^2} r^{-3k}$$

~~$$\frac{du}{dr} = \frac{a}{A^2 r^{-3k}}$$~~



$$\varphi = 2r \quad \varphi' = 2 + r \frac{dz}{dr}$$

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20  
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$$2r^4(2+r \frac{dz}{dr}) + \frac{2^2 r^4}{2} \frac{3k+1}{2} + k p r r^3 = 0$$

3 km

$$2r^5 \frac{dz}{dr} + 2^2 r^4 \frac{3k+1}{2} + 2r^3 k p = 0$$

III).

$$\frac{\partial \theta}{\partial x} + \frac{\partial \theta}{\partial y} = \frac{1}{r} \left( \frac{\partial \theta}{\partial x} + \frac{\partial \theta}{\partial y} \right) + \frac{1}{r} \left( \frac{\partial \theta}{\partial x} + \frac{\partial \theta}{\partial y} \right)$$

$$\iint \Phi dv = \mu \iint \left( \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} \right) + \frac{1}{3} (\text{div})^2 +$$

$$\mu \iint \left\{ u \left[ m \frac{\partial v}{\partial x} + n \frac{\partial v}{\partial y} + l \frac{\partial u}{\partial x} - l \frac{\partial v}{\partial y} - l \frac{\partial u}{\partial z} \right] + v \left[ \right] \right\} dv$$

$$\iint u \frac{\partial}{\partial x} v_n + v \frac{\partial}{\partial y} v_n + w \frac{\partial}{\partial z} v_n -$$

$$- v_n \text{div} \quad \left( \Phi = \iint \left( \frac{\partial u}{\partial x} \right)^2 + \frac{1}{3} \text{div}^2 + \iint \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n - \iint v_n \text{div} dv \right)$$

$$\iint \rho \left( u \frac{\partial}{\partial x} + \dots \right) dv = \iint \rho (u l + v m + w n) dv$$

$$\iint \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dv = \iint \rho (u l + v m + w n) - \iint \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n$$

Mo M1

$$= \iint \frac{\partial}{\partial n} \left( \frac{u^2 + v^2 + w^2}{2} \right) d\sigma + \frac{\mu}{3} \iint v_n \text{div} dv - \mu \iint \left( \frac{\partial u}{\partial x} \right)^2 \frac{d\sigma}{3}$$

$$c_0 \quad c_1 = \frac{c_0}{\sqrt{M_1}}$$



$$\left(\frac{c}{A} + R\right) \iint \rho \theta (u l + v m + w n) dS =$$

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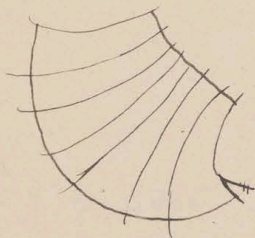
$$= \mu \iint \left[ \frac{\partial}{\partial n} \left( \frac{u^2 + v^2 + w^2}{2} \right) + \frac{1}{3} v_n \operatorname{div} + \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n - v_n \operatorname{div} \right] dS +$$

$$= \mu \iint \left[ \frac{\partial}{\partial n} \left( \frac{u^2 + v^2 + w^2}{2} \right) + \left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) v_n - \frac{2}{3} v_n \operatorname{div} \right] dS +$$

$$* - \iint \frac{u^2 + v^2 + w^2}{2} \rho \left( \frac{v_n}{\rho} \right) dS$$

$$R \left( 1 + \frac{1}{k-1} \right) \iint \dots = \frac{R k}{k-1} \iint \rho \theta v_n dS = \uparrow = \frac{k}{k-1} \iint \rho v_n dS$$

Jedli viz to kontury do ruzki prachu



$$g_1 p_1 v_1 = g_2 p_2 v_2$$

$$\frac{kR}{k-1} \left( p_2 \theta_2 v_2 g_2 - p_1 \theta_1 v_1 g_1 \right) = - p_2 \frac{v_2^3}{2} g_2 - p_1 \frac{v_1^3}{2} g_1 + \mu \left\{ \left[ \frac{\partial}{\partial s} \left( \frac{v_2^2}{2} \right) g_2 - \left( \frac{\partial}{\partial s} \left( \frac{v_1^2}{2} \right) g_1 \right] \right. \right.$$

$$\left. + \left[ v_2 \frac{\partial v_2}{\partial s} g_2 - v_1 \frac{\partial v_1}{\partial s} g_1 \right] - \frac{2}{3} \left[ v_2 \frac{\partial v_2}{\partial s} g_2 - v_1 \frac{\partial v_1}{\partial s} g_1 \right] \right\}$$

$$\left\{ \right\} = \frac{4}{3} \left[ v_2 \frac{\partial v_1}{\partial s} g_2 - v_1 \frac{\partial v_1}{\partial s} g_1 \right] + \iint \frac{\partial}{\partial n} \left( \frac{u^2 + v^2 + w^2}{2} \right) dS + \iint \nabla^2 \frac{u^2 + v^2 + w^2}{2} \frac{dS}{\rho}$$

$$\frac{kR}{k-1} g_1 p_1 v_1 (\theta_2 - \theta_1) = p_1 p_1 v_1 \frac{v_2^2 - v_1^2}{2} + \frac{4\mu}{3} \left[ \frac{1}{p_2} \frac{\partial v_2}{\partial s} - \frac{1}{p_1} \frac{\partial v_1}{\partial s} \right] p_1 g_1 v_1$$

$$\frac{kR}{k-1} (\theta_2 - \theta_1) = - \frac{v_2^2 - v_1^2}{2} + \frac{4\mu}{3} \left[ \frac{1}{p_2} \frac{\partial v_2}{\partial s} - \frac{1}{p_1} \frac{\partial v_1}{\partial s} \right] + \int \nabla^2 \left( \frac{u^2 + v^2 + w^2}{2} \right) \frac{ds}{\rho w}$$

$$\int \frac{\partial}{\partial n} \left( \frac{u^2 + v^2 + w^2}{2} \right) dS = \iint_{\partial V} S \left( \nabla \left( \frac{u^2 + v^2 + w^2}{2} \right) \cdot \mathbf{n} \right) dS =$$

$$\iint \operatorname{div} \nabla \frac{u^2 + v^2 + w^2}{2} dv = \iiint \nabla^2 \frac{u^2 + v^2 + w^2}{2} dv = \iiint (\nabla^2)^2 \rho ds$$

$$u^2 + v^2 + w^2 = r^2$$

$$dv = \rho d\vec{r}$$

$$= \iint \left[ u \frac{\partial u}{\partial n} + v \frac{\partial v}{\partial n} + w \frac{\partial w}{\partial n} \right] dS = \iint S v$$

Skorzystajmy z twierdzenia Gaussa, aby wyrazić powyższą całkę w postaci całki objętościowej.

$$\delta \cdot \frac{\partial u}{\partial n}$$

$$\delta \cdot \frac{\partial v}{\partial n}$$

$$\delta \cdot \frac{\partial w}{\partial n}$$

$$\frac{\partial u}{\partial n} = \frac{\partial}{\partial n} \left( \frac{r^2}{2} \right) \dots$$

$$= \frac{\partial u}{\partial n} + \delta \frac{\partial^2 u}{\partial n^2}$$

zatem:

$$\int u \frac{\partial u}{\partial n} dS \dots \delta \left[ \left( \frac{\partial u}{\partial n} \right)^2 + \left( \frac{\partial v}{\partial n} \right)^2 + \left( \frac{\partial w}{\partial n} \right)^2 \right] ds \cdot dt$$

$$= \iint \left[ \left( \frac{\partial u}{\partial n} \right)^2 + \dots \right] ds \cdot \rho$$

$$\rho, v, \rho_1 = \rho_2, v_2, \rho_2$$

$$\delta dt \delta \left( \frac{\partial u}{\partial n} \right) \dots = \dots$$

$$= \frac{\int \left( \frac{\partial u}{\partial n} \right)^2 ds}{\rho \rho}$$

zatem dla nich znowu  $\int$  nie zeruje

zatem dla nich znowu  $\int$  nie zeruje

$$\frac{kR}{k-1} (r_2 - r_1) = - \frac{v_2 - v_1}{2}$$



Prędkość ruchu cieczy: odwracalny

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zmiennego znak  $\frac{p_1 - p_2}{\rho}$  i znak  $\frac{u}{w}$  otrzymujemy znak taki same

Szybki ruch nie odwracalny! Tworzenie się prądów wirów!

U gazów: także prędkość ruchu nie odwracalny [asymetryczny wpływ na

Idealne gazy  $\gamma = 1.4$  i  $\gamma = 1.2$  i  $\gamma = 1.0$  i  $\gamma = 0.7$  i  $\gamma = 0.5$

$$-\int \frac{dp}{\rho} = \frac{u^2 + v^2 + w^2}{2}$$

$$\int \frac{dp}{\rho_0 \left(\frac{p}{p_0}\right)^{\frac{1}{k}}} = \frac{p_0}{\rho_0} \int \frac{dp}{p^{\frac{1}{k}}} = \frac{1}{\frac{1}{k} + 1} \frac{p_0}{\rho_0} p^{\frac{1}{k} + 1}$$

$$= -\left(\frac{p_0}{p}\right)^{\frac{1}{k}} \frac{p}{p_0} \cdot \frac{k}{k-1} \Big| = -\frac{p_0}{\rho_0} \frac{p}{p_0} \frac{k}{k-1} \Big| = -\frac{k p_0}{\rho_0 (k-1)} \Big|$$

Krytyczna prędkość:  $k \frac{p_2}{p_1} = -2 \frac{k}{k-1} \frac{p_0}{\rho_0} \left(\frac{p_0}{p_1}\right)^{\frac{1}{k}} = +k \frac{p_2}{\rho_0} \left(\frac{p_0}{p_1}\right)^{\frac{1}{k}}$

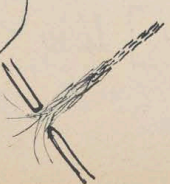
$$= -2 \frac{k}{k-1} \left[ \frac{p_2}{\rho_0} \left(\frac{p_0}{p_1}\right)^{\frac{1}{k}} - \frac{p_0}{\rho_0} \right]$$

$$\frac{p_2}{\rho_0} \left(\frac{p_0}{p_1}\right)^{\frac{1}{k}} \left(\frac{2}{k-1} + 1\right) = \frac{2}{k-1} \frac{p_0}{\rho_0}$$

$$\frac{p_2}{\rho_0} \left(\frac{p_0}{p_1}\right)^{\frac{1}{k}} = \frac{2}{k+1}$$

$$\left(\frac{p_0}{p_1}\right)^{\frac{1-k}{k}} = \frac{2}{1+k}$$

$$\frac{p_2}{p_0} = \left(\frac{2}{1+k}\right)^{\frac{k}{1+k}}$$



$$\sqrt{k} \sqrt{\frac{p_2}{\rho_2}} \cdot \rho_2 = \sqrt{k} \sqrt{\frac{p_2}{\rho_2}} \cdot \rho_2$$

$$= \sqrt{k} \sqrt{\frac{p_2}{\rho_2}} \left(\frac{p_2}{\rho_2}\right)^{\frac{1}{k}}$$

$$= \sqrt{k} \sqrt{\frac{p_0}{\rho_0}} \sqrt{\frac{p_2}{\rho_2}}^{\frac{k+1}{2k}}$$

$$= \sqrt{k} \sqrt{\frac{p_0}{\rho_0}} \rho_0^{\frac{k+1}{2k}} \left(\frac{2}{1+k}\right)^{\frac{k}{2(1+k)}}$$

$$= \sqrt{k} \sqrt{p_0 \rho_0} \left(\frac{2}{1+k}\right)^{\frac{k+1}{2(1+k)}}$$



zinde satrime:  $\nabla(u^2 + v^2) = 0$

N.p. domygnicrow:  $\frac{\partial}{\partial x} (u \frac{\partial v}{\partial x})$

$$u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 v}{\partial x^2} + u \frac{\partial^2 u}{\partial y^2} + v \frac{\partial^2 v}{\partial y^2} + \left(\frac{\partial u}{\partial x}\right)^2 + \left(\frac{\partial u}{\partial y}\right)^2 + \left(\frac{\partial v}{\partial x}\right)^2 + \left(\frac{\partial v}{\partial y}\right)^2 = 0$$

$$\frac{4}{3} \left( u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 v}{\partial y^2} \right) + u \frac{\partial^2 u}{\partial y^2} + v \frac{\partial^2 v}{\partial x^2} + \frac{1}{3} \left( u \frac{\partial^2 v}{\partial x \partial y} + v \frac{\partial^2 u}{\partial x \partial y} \right) +$$

$$k \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + k \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) p_0 = (k-1) \left[ \frac{4}{3} \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 \right] + \left( \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \right)^2 - \frac{4}{3} \frac{\partial u}{\partial x} \frac{\partial v}{\partial y}$$

$$\frac{kR}{k-1} (\theta_2 - \theta_1) = \frac{\mu}{3} \frac{1}{\rho} \frac{\partial \theta}{\partial s}$$

$$\frac{\partial \theta}{\partial x} \frac{dx}{ds} + \frac{\partial \theta}{\partial y} \frac{dy}{ds} + \dots$$

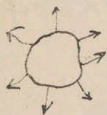
$$= \frac{\mu}{3} \frac{1}{\rho} \frac{u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 v}{\partial y^2} + v \frac{\partial^2 u}{\partial x \partial y} (u^2 + v^2)}{\sqrt{u^2 + v^2}}$$

$$\frac{kR}{k-1} (\theta - \theta_0) = \frac{\mu}{3} \frac{1}{\rho} \frac{(u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y}) \sqrt{u^2 + v^2}}{\sqrt{u^2 + v^2}}$$

Wystarczy zinde całka nad pow. mry = 0

Kiedy to w koidy punkcie: ~~tylko~~ zinde dla koidy elementu powierzchni

1 w całce nad obszar  $\text{div} \frac{\partial}{\partial n} (u^2 + v^2) = 0$



$$\int_{ds} \nabla(u^2 + v^2) \cdot \mathbf{V}_0 \mathbf{V}_0 = \int_{ds} \nabla \cdot \mathbf{V}_0 \cdot \mathbf{V}_0 (u^2 + v^2) = 0$$

$$= \int_{ds} (\text{div} \cdot \mathbf{V}_0 \cdot \mathbf{V}_0 (u^2 + v^2))$$

$$\int_{ds} (\text{div} \cdot \mathbf{V}_0) = \int_{ds} (\text{curl} \cdot \mathbf{n}) / df \parallel \int_{ds} [\mathbf{V}_0 \cdot \text{curl} \mathbf{V}_0 (u^2 + v^2)] df = 0$$



$$\nabla p = \frac{\mu}{3} \nabla \operatorname{div} v + \mu \nabla^2 v - \underbrace{\rho(v \nabla) v}_{= -\rho \left( \nabla \frac{v^2}{2} + v \operatorname{curl} v \right)}$$

Firstly we have:  $\operatorname{curl} v \perp v$   
 $\int v \operatorname{curl} v = 0$   
 $\nabla \cdot (v \otimes v) = 0$

$$\nabla^2 v = \nabla \operatorname{div} v - \operatorname{curl}^2 v$$

$$\nabla p = \frac{4}{3} \mu \nabla \operatorname{div} v - \operatorname{curl}^2 v$$

$$\operatorname{curl}^2 v = \nabla \left( p - \frac{4}{3} \mu \operatorname{div} v \right)$$

$$\operatorname{curl}^3 v = 0$$

$$\nabla^2 \left( p - \frac{4}{3} \mu \operatorname{div} v \right) = 0$$

$$v = \operatorname{curl} \int \frac{\operatorname{curl} v}{2} dv + \nabla \int \frac{\operatorname{div} v}{2} dv$$

$$= \operatorname{curl} \int \frac{\nabla p - \frac{4}{3} \mu \operatorname{div} v}{2} dv + \nabla \int \frac{\operatorname{div} v}{2} dv$$

$$\text{Lagrange multiplier } p \text{ satisfying } \operatorname{div} v = \frac{1}{\rho}$$

$$\operatorname{div}(\rho v) = 0$$

to ensure, i.e.  $\operatorname{curl} v \cdot \nabla u = 0 \perp v$

$$\begin{vmatrix} \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial z} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial z} \end{vmatrix}$$

$$\frac{\partial u}{\partial t}$$

$$\int \int S \cdot \nabla u \, d\mathbf{f} = \int \left( q, v, \frac{dv}{dt} \right) d\mathbf{f}$$

$$\int \nabla u \, d\mathbf{f}$$

$$\int \nabla u \cdot \mathbf{q} \, d\mathbf{s}$$

$$\frac{d}{dt} \left( q \cdot \frac{dv}{dt} \right) = q \cdot \frac{dv}{dt}$$



Urey-adiabatischen Koeffizienten erzeuge

$$\begin{aligned}
 \frac{u^2 + v^2 + w^2}{2} &= \frac{k}{k-1} \left[ \frac{\rho_0}{\rho} - \frac{\rho_0}{\rho} \left( \frac{\rho_0}{\rho} \right)^{\frac{1}{k}} \right] \\
 &= \frac{k}{k-1} \left[ \frac{\rho_0}{\rho} - \frac{\rho_0}{\rho} \underbrace{\left( \frac{\rho_0}{\rho} \right)^{\frac{1}{k}}}_{\left[ \frac{\rho_0}{\rho} \right]^{\frac{k-1}{k}}} \right] \quad \frac{\rho}{\rho_0} = \left( \frac{p}{p_0} \right)^k \\
 &= \frac{k}{k-1} \left[ \frac{\rho_0}{\rho} - \frac{\rho_0}{\rho} \left( \frac{p}{p_0} \right)^{k-1} \right] = \frac{k}{k-1} \frac{\rho_0}{\rho} \left[ 1 - \left( \frac{p}{p_0} \right)^{k-1} \right]
 \end{aligned}$$

geois. typ:  $\xi = \eta = \xi = 0$

$$u = \frac{\partial p}{\partial x} \quad \frac{\partial(\rho u)}{\partial x} + \dots = 0$$

$$u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = 0$$

$$\begin{cases} \frac{\partial p}{\partial x} \frac{\partial(\rho u)}{\partial x} + \frac{\partial p}{\partial y} \frac{\partial(\rho v)}{\partial y} + \left( \frac{\partial p}{\partial x} \right)^2 + \left( \frac{\partial p}{\partial y} \right)^2 = 0 \\ \left( \frac{\partial p}{\partial x} \right)^2 + \left( \frac{\partial p}{\partial y} \right)^2 = f(p) = \frac{k}{k-1} \frac{\rho_0}{\rho} \left[ 1 - \left( \frac{p}{p_0} \right)^{k-1} \right] \end{cases}$$

$$\rho \left\{ 1 - \left[ \left( \frac{\partial p}{\partial x} \right)^2 + \left( \frac{\partial p}{\partial y} \right)^2 \right] \frac{k-1}{k} \frac{\rho_0}{\rho} \right\} = (k-1) [\rho_y p - \rho_x p_0]$$

$$\begin{aligned}
 (k-1) \frac{\partial \rho_y p}{\partial x} &= \frac{\partial}{\partial x} \rho \left\{ 1 - a \left[ \left( \frac{\partial p}{\partial x} \right)^2 + \left( \frac{\partial p}{\partial y} \right)^2 \right] \right\} \\
 &= \frac{-2a \left( \frac{\partial p}{\partial x} \frac{\partial p}{\partial x} + \frac{\partial p}{\partial y} \frac{\partial p}{\partial y} \right)}{1 - a \left[ \left( \frac{\partial p}{\partial x} \right)^2 + \left( \frac{\partial p}{\partial y} \right)^2 \right]}
 \end{aligned}$$

$$2a \left[ \left( \frac{\partial p}{\partial x} \right)^2 \frac{\partial p}{\partial x} + 2 \frac{\partial p}{\partial y} \frac{\partial p}{\partial x} \frac{\partial p}{\partial y} + \left( \frac{\partial p}{\partial y} \right)^2 \frac{\partial p}{\partial y} \right] = (k-1) \left( \frac{\partial p}{\partial x} + \frac{\partial p}{\partial y} \right) \left[ 1 - a \left[ \left( \frac{\partial p}{\partial x} \right)^2 + \left( \frac{\partial p}{\partial y} \right)^2 \right] \right]$$



Próba dla sprężyny izotermicznej:

$$\frac{p_0}{\rho_0} = a$$

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$$\frac{u^2 + v^2}{2} = -\frac{p_0}{\rho_0} \ln \frac{p}{p_0}$$

$$\frac{\partial \ln p}{\partial x} = \frac{a}{z} \frac{\partial}{\partial x} \left[ \left( \frac{\partial p}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial x} \right)^2 \right]$$

$$a \left[ \left( \frac{\partial p}{\partial x} \right)^2 \frac{\partial p}{\partial x} + 2 \frac{\partial p}{\partial x} \frac{\partial v}{\partial x} \frac{\partial v}{\partial x} + \left( \frac{\partial v}{\partial x} \right)^2 \frac{\partial v}{\partial x} \right] + \frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 v}{\partial x^2} = 0 \quad \text{Adekwat?}$$

$$\frac{p}{p_0} = \left( \frac{\rho}{\rho_0} \right)^k \quad \frac{\theta}{\theta_0} = \left( \frac{p}{p_0} \right)^{\frac{k-1}{k}} = \left( \frac{\rho}{\rho_0} \right)^{\frac{k-1}{k}}$$

$$\frac{u^2 + v^2}{2} = \frac{k}{k-1} \left[ \frac{p}{p_0} - \frac{p_0}{\rho_0} \frac{\theta}{\theta_0} \right] = \frac{k}{k-1} R \theta_0 \left[ 1 - \frac{\theta}{\theta_0} \right] = \frac{k}{k-1} R (\theta_0 - \theta)$$

u i v będzie miało maksimum na osi symetrii  
zatem  $\frac{\partial}{\partial n} (u^2 + v^2) = 0$  wzdłuż osi jak  $\theta$  (jak  
dla prądu  $\theta$  będzie  $\theta^2$  tylko samą wartością  $\theta$ )

→ jeżeli zadani jest symetryczny:

izotermiczny:

$$a \left( \frac{\partial p}{\partial x} \right)^2 + \frac{\partial v}{\partial x} \quad p u = \text{const}$$

$$u e^{-\frac{p_0}{\rho_0} \frac{u^2}{2}} = \text{const}$$

adibatykalny:

Równanie to ~~nie~~ musi być spełnione równo wzdłuż

przy prądzie niesymetrycznym, chyba: ~~nie~~

$$\begin{cases} \frac{\partial p}{\partial t} + \frac{\partial (p u)}{\partial x} = 0 \\ \frac{\partial p}{\partial t} + \frac{1}{2} \left( \frac{\partial p}{\partial x} \right)^2 = \frac{k}{k-1} \frac{p_0}{\rho_0} \left[ 1 - \left( \frac{p}{p_0} \right)^{k-1} \right] \end{cases}$$

$$\begin{cases} \frac{\partial p}{\partial t} + \frac{\partial (p u)}{\partial x} = 0 \\ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} = -k \frac{p_0}{\rho_0} \left( \frac{p}{p_0} \right)^{k-2} \frac{\partial p}{\partial x} \end{cases} \quad \left| \begin{array}{l} u \\ p \end{array} \right. \quad \begin{cases} \frac{\partial p u}{\partial t} + \frac{\partial (p u^2)}{\partial x} = -k \frac{p_0}{\rho_0} \left( \frac{p}{p_0} \right)^{k-2} p \frac{\partial p}{\partial x} \end{cases}$$



$$\Delta^2 \theta = \alpha \left[ u \frac{\partial^2 \theta}{\partial x^2} + v \frac{\partial^2 \theta}{\partial y^2} + k \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) - (k-1) \Phi \right]$$

$$\alpha = \frac{1}{R}$$

$$\theta = \theta_0 + \alpha \theta' + \frac{\alpha^2}{2} \theta'' + \dots$$

$$\theta = \theta_0 + \alpha \theta' + \frac{\alpha^2}{2} \theta'' + \dots$$

$$\Delta^2 \theta = \alpha \Delta^2 \theta_0 + \frac{\alpha^2}{2} \Delta^2 \theta'' + \dots$$

$$u = u_0 + \alpha u' + \frac{\alpha^2}{2} u'' + \dots$$

~~Dla danych umiemy wyznaczyć  $\theta$  i  $\rho$  z dokładnością do  $\alpha^2$ .~~

$$\rho = \rho_0 + \alpha \rho' + \frac{\alpha^2}{2} \rho'' + \dots$$

Wtedy w pierwszym przybliżeniu:

$$\Delta^2 \theta = u \frac{\partial^2 \theta}{\partial x^2} + v \frac{\partial^2 \theta}{\partial y^2} +$$

Inny ten zapis:

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} = 0$$

$$\frac{\partial \rho_0}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial u_0}{\partial x} + \dots \right) +$$

$$\frac{\partial(\rho_0 u_0)}{\partial x} + \frac{\partial(\rho_0 v_0)}{\partial y} = 0$$

$$\frac{\rho_0}{\rho_0} = R \theta_0$$

$$\Delta^2 \theta' = \left[ u_0 \frac{\partial^2 \theta_0}{\partial x^2} + \dots - (k-1) \Phi_0 \right]$$

2o porównajmy drugie przybliżenie:

$$\frac{\rho_0 + \alpha \rho'}{\rho_0 + \alpha \rho'} = R(\theta_0 + \alpha \theta')$$

$$\frac{\rho'}{\rho_0} = \frac{\theta'}{\theta_0} + \frac{\rho'}{\rho_0}$$

$$\rho_0 + \alpha \rho' = R(\theta_0 + \alpha \theta')(\rho_0 + \alpha \rho')$$

$$\rho_0 \left( \frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} \right) + u_0 \frac{\partial \rho'}{\partial x} + v_0 \frac{\partial \rho'}{\partial y} = 0$$

$$\rho' = R \left[ \rho_0 \theta' + \rho' \theta_0 \right]$$

$$= \rho_0 \left[ \frac{\theta'}{\theta_0} + \frac{\rho'}{\rho_0} \right]$$

$$\frac{\partial \rho'}{\partial x} = \frac{\mu}{3} \frac{\partial^2 u'}{\partial x^2} +$$

$$\rho' = \rho_0 \frac{\theta'}{\theta_0} + R \theta_0 \rho'$$

$$R \theta_0 \frac{\partial \rho'}{\partial x} = \frac{\partial \rho'}{\partial x} - \frac{\partial \rho_0}{\partial x} \frac{\theta'}{\theta_0} - \frac{\rho_0}{\theta_0} \frac{\partial \theta'}{\partial x}$$

$$\frac{\partial \rho'}{\partial x} = \frac{\frac{\partial \rho_0}{\partial x} \cdot \theta' + \rho_0 \frac{\partial^2 \theta'}{\partial x^2}}{\theta_0} + R \theta_0 \frac{\partial \rho'}{\partial x}$$

$$R \theta_0 \rho_0 \left( \frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} \right) +$$

$$+ u_0 \frac{\partial \rho'}{\partial x} + v_0 \frac{\partial \rho'}{\partial y} - \frac{\theta'}{\theta_0} (u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y}) -$$

$$- \frac{\rho_0}{\theta_0} (u_0 \frac{\partial \theta'}{\partial x} + v_0 \frac{\partial \theta'}{\partial y}) = 0$$



$$\nabla_i: \quad \frac{\partial f'}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} \right) + \dots$$

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$$\frac{\partial f'}{\partial y} = \dots$$

$$\rho_0 \left( \frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} \right) + \mu_0 \frac{\partial f'}{\partial x} + \nu_0 \frac{\partial f'}{\partial y} = \frac{\mu_0}{\rho_0} \frac{1}{\theta_0} \left( u_0 \frac{\partial}{\partial x} + v_0 \frac{\partial}{\partial y} \right) (\rho_0 \theta')$$

just dummy integrals  $\frac{\partial f'}{\partial y} = 0$  [hydro-mechanics by the jinks  $\frac{\partial u'}{\partial x \partial y}$  b. not a primary do  $\frac{\partial u'}{\partial y^2}$ ]

$$\therefore v_0 = 0$$

$$\left\{ \begin{array}{l} \frac{\partial f'}{\partial x} = \mu \frac{\partial^2 u'}{\partial y^2} \\ \rho_0 \frac{\partial u'}{\partial x} + \mu_0 \frac{\partial f'}{\partial x} = \frac{1}{\theta_0} \mu_0 \frac{\partial (\rho_0 \theta')}{\partial x} \end{array} \right\} \parallel \frac{\partial}{\partial y^2}$$

$$\rho_0 \frac{\partial u'}{\partial x \partial y^2} + \frac{\partial \mu_0}{\partial y^2} \frac{\partial f'}{\partial x} = \frac{1}{\theta_0} \frac{\partial^2}{\partial y^2} \left( \mu_0 \frac{\partial}{\partial x} \right)$$

$$\rho_0 \frac{\partial^2 f'}{\partial x^2} + \mu \frac{\partial \mu_0}{\partial y^2} \frac{\partial f'}{\partial x} = \frac{\mu}{\theta_0} \frac{\partial^2}{\partial y^2} \left( \mu_0 \frac{\partial}{\partial x} (\rho_0 \theta') \right)$$

$$\left\{ \frac{1}{R\theta} \mu \frac{\partial u}{\partial x} + \frac{\partial \mu}{\partial x} = \mu \frac{\partial^2 u}{\partial x^2} \right.$$

$$\left. \mu \frac{\partial \mu}{\partial x} + k \mu \frac{\partial u}{\partial x} = (k-1) \mu \Phi + \frac{(k-1)}{k} \nabla^2 \theta \right\}$$

Podobnie dla innych gazów:

gęstość relatywna  $R = \frac{1}{\rho_0}$

zatem  $R$  ma  $\rho R$  stałą

$$\left. \begin{aligned} \frac{b}{\rho R} &\equiv \frac{b}{n} \equiv \alpha \frac{m}{n^2} \\ \frac{m b}{n} &\equiv \alpha \frac{m^2}{n^2} \equiv \beta \frac{r}{n^2} \end{aligned} \right\}$$

$$\frac{m^2}{\rho R} = 1$$

$$\frac{b}{\rho R} = \alpha \frac{m}{n} = \beta \frac{r}{m n} \left\{ \begin{array}{l} 3 \text{ równości} \\ \text{no 7 wielkości} \\ 4 \text{ dowolnych} \end{array} \right.$$

~~At. p. obrotu dookoła p. i. p.~~

$$\frac{m^2}{r} \equiv \rho \equiv \frac{m^2}{r} \equiv \frac{r}{\alpha}$$

$$\underline{\rho \equiv \frac{r}{\alpha}}$$

$$b \equiv \alpha \frac{m}{n}$$

Podobne może być tylko między takimi gazami

przy których  $\frac{K}{\mu R}$  tak samo więc przy których

$\frac{\rho_0 K}{\mu}$  tak samo

$\frac{\rho_0 K}{\mu}$	$H_2$	$O_2$	$N_2$	$CO_2$	$CH_4$	$C_2H_4$	$NO$
$\frac{7}{0.5} = 14$	$\frac{16.1}{1}$	$\frac{14.1}{1}$	$\frac{22.071}{0.82} = 19$	$\frac{8.160}{0.63} = 21$	$\frac{14.089}{0.56} = 22$	$\frac{22.073}{0.82} = 20$	

więc współwielkości i inne warunki nie są konieczne i wpływają tylko na



Wtedy redukują się to do:

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$$\frac{m^2}{n} = \rho$$

stwierdza dowolnie 4 wielkości

$$b = \alpha \frac{m}{n}$$

Np.  $\rho, \alpha, n=1,$

$$m^2 = \rho$$

$$b n = \alpha m = \alpha \sqrt{\rho}$$

$$\left. \begin{array}{l} m = \sqrt{\rho} \\ b n = \alpha \sqrt{\rho} \end{array} \right\}$$

I. robimy wymiary nieskrajnie  $n=1$  powyżej

$$\left\{ \begin{array}{l} m = \sqrt{\rho} = \sqrt{\frac{1}{\rho_0}} \\ b = \alpha \sqrt{\rho} = \frac{\alpha}{\sqrt{\rho_0}} \end{array} \right.$$

Wzr. prędkości  $v \sim \frac{1}{\sqrt{\rho}}$   
jakiś wymiar  $\sim \frac{\alpha}{\sqrt{\rho}}$

$$\text{ilosc przepływu} \sim \rho^{\frac{1}{2}} \rho^{\frac{1}{2}} = \frac{b m}{\rho r} \equiv \frac{\beta m}{\rho} = \frac{\alpha}{\rho}$$

zatem jakiś

ograniczenie nie ma  $\rho$  w  $\rho^{\frac{1}{2}}$

$$\frac{m^2}{\rho n} = 1 \quad m = \sqrt{\rho n}$$

rest:  $m = \sqrt{\rho}$   
prędkość  $v \sim \frac{1}{\sqrt{\rho}}$   
masa dla prędkości  $v \sim \frac{1}{\sqrt{\rho}}$

II. dla skrajnie nieskrajnie  $b=1$

$$m^2 = \rho$$

$$n = \alpha m = \alpha \sqrt{\rho}$$

$$m = \frac{1}{\sqrt{\rho_0}}$$

$$n = \frac{\alpha}{\sqrt{\rho_0}}$$

$$\rho = \frac{m^2}{n}$$

$$b = \alpha \frac{m}{n}$$

$$m = \frac{1}{\sqrt{\rho}}$$

$$N.p. n=1$$

$$m = \sqrt{\rho}$$

$$b = \alpha \sqrt{\rho}$$

$$m = \frac{1}{\sqrt{\rho}}$$

$$n = \frac{1}{\alpha \sqrt{\rho}}$$

$$\frac{b=1}{n=1} \quad m = \sqrt{\rho}$$

$$b = \beta \sqrt{\rho}$$

$$\frac{\partial u}{\partial t} = 0$$

$$\frac{b=1}{b=1} \quad \alpha = m$$

$$n = \beta \sqrt{\rho}$$

masa dla prędkości  $v \sim \frac{1}{\sqrt{\rho}}$

Des tarcz, a d. laty uni:

$$\frac{b m^2}{\rho n} \equiv \frac{b}{n}$$

$$\frac{m b}{n} \equiv k \frac{b}{n} \quad || \quad k=1$$

Tylko takie będą podobne, które mają równo k

Testujemy z tarczami:

$$\frac{b m^2}{\rho n} \equiv \frac{b}{n} \equiv \alpha \frac{m}{n^2}$$

$$m^2 = \rho$$

$$b n = \alpha m = \alpha \sqrt{\rho}$$

To jest tak samo jak z innymi dźwiękami —  $\Phi$  i  $\alpha$  są  
jako k = 1000

$$m = \sqrt{\rho} = \frac{1}{\sqrt{\rho_0}}$$

$$b n = \frac{\alpha}{\sqrt{\rho_0}}$$

to jest równo wymiarowe:  
ciężar powierzchniowy  $\propto \alpha$

$$\text{ciężar powierzchniowy} \propto \frac{\alpha}{\sqrt{\rho_0}} \sqrt{\rho_0} = \sqrt{\rho_0}$$

$$\text{gęstość} \frac{1}{\rho_0} = \frac{\alpha}{\sqrt{\rho_0}} \rho_0 = \alpha \sqrt{\rho_0} \quad \text{objętość} \propto \frac{\sqrt{\rho_0}}{\alpha \sqrt{\rho_0}} = \frac{1}{\alpha}$$

↓  
To będzie się stosować do dowolnie naciętych tarcz jako k = k  
i jako powiązany z tarczami przy odpowiednim wymiarach.



U myklych metodach transpozicij:  
 Objektivni jezi miorona pod istimim  $\frac{1}{2}(\rho, \theta)$   $\sim \frac{1}{u}$   
 ista ista

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Stavioje  $u = u_0 + \mu u'$  etc.

$$\left. \begin{aligned} u_0 \frac{\partial u_0}{\partial x} + \dots &= -\frac{\partial \rho_0}{\partial x} \\ \frac{\partial \rho_0 u_0}{\partial x} + \dots &= 0 \\ u_0 \frac{\partial \rho_0}{\partial x} + \dots + k \rho_0 \left( \frac{\partial u_0}{\partial x} + \dots \right) &= \kappa \Delta^2 \theta_0 \end{aligned} \right\} \rho_0 = R \theta_0$$

$$\left\{ \begin{aligned} u_0 \frac{\partial u'}{\partial x} + \dots + u' \frac{\partial u_0}{\partial x} + \dots &= -\frac{\partial \rho'}{\partial x} + \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial u_0}{\partial x} + \frac{\partial u_0}{\partial y} \right) + \dots \\ \rho_0 \frac{\partial u'}{\partial x} + u_0 \frac{\partial \rho'}{\partial x} + \dots &= 0 \\ u_0 \frac{\partial \rho'}{\partial x} + \dots + u' \frac{\partial \rho_0}{\partial x} + \dots + k \rho_0 \left( \frac{\partial u'}{\partial x} + \dots \right) + k \rho' \left( \frac{\partial u_0}{\partial x} + \dots \right) &= (k-1) \rho_0 + \kappa(k-1) \Delta^2 \theta' \end{aligned} \right.$$

~~$\rho = R \theta$~~   $\rho' = R[\theta_0 \rho' + \theta' \rho_0]$

Ova tona i puvu...

~~$\frac{\partial \rho}{\partial x}$~~

$$u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} + k \rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0$$

$$u \frac{\partial \rho_0}{\partial x} + v \frac{\partial \rho_0}{\partial y} + w \frac{\partial \rho_0}{\partial z} + k \rho_0 \left( \frac{\partial u_0}{\partial x} + \frac{\partial v_0}{\partial y} + \frac{\partial w_0}{\partial z} \right) = 0$$

$$u \frac{\partial \rho_0}{\partial x} + v \frac{\partial \rho_0}{\partial y} + \dots + \left( \frac{\partial u_0}{\partial x} + \frac{\partial v_0}{\partial y} + \frac{\partial w_0}{\partial z} \right) = 0$$

$$-\rho \left[ u \left( \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) + v \left( \frac{\partial u}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) + w \left( \frac{\partial u}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) \right] + k \rho \left( \frac{\partial u}{\partial x} + \dots \right) = 0$$

$$\left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \frac{u^2 + v^2 + w^2}{2} = \frac{k \rho}{\rho} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right)$$

$$u \frac{\partial f}{\partial x} + v \frac{\partial f}{\partial y} + w \frac{\partial f}{\partial z} + k f \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = 0 \quad \text{III.}$$

$$\text{Jako że przyjmujemy} \quad \frac{f}{f_0} = \left( \frac{\rho}{\rho_0} \right)^k : \quad \text{IV.}$$

$$\therefore k u \frac{\partial \rho}{\partial x} \cdot \rho^{k-1} + \dots + k \rho^k \frac{\partial u}{\partial x} = 0$$

$$\text{II.} \quad \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \dots = 0$$

Stąd się widzi, że jeżeli założymy III można także wyjąć IV

III otrzymujemy wtórnie IV do II

Stądże z tego nam wynika że z III i II również wyplywa IV?

$$\left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \log f + k \left( \frac{\partial u}{\partial x} + \dots \right) = 0$$

$$\left( u \frac{\partial}{\partial x} + \dots \right) \log \rho + \left( \frac{\partial u}{\partial x} + \dots \right) = 0 \quad -k$$

$$\left( u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} \right) \log \left( \frac{f}{\rho^k} \right) = 0$$

To znaczy że każda ustępka form nie zmienia podnoszonego bieru  $\log \left( \frac{f}{\rho^k} \right)$  zatem prowadzimy.

Wynika stąd dla nich niezmienności z równania  $\int \frac{df}{f} = \frac{k}{k-1} \dots = \frac{u^2 + v^2 + w^2}{2}$   
to samo co dla nich ogólności wzięty  $\int \dots$  :

$$\frac{k R (\theta_2 - \theta_1)}{k-1} + \left( \frac{u^2 + v^2 + w^2}{2} \right)_2 - \left( \frac{u^2 + v^2 + w^2}{2} \right)_1 = 0$$

~~Stąd przyjmujemy dla porównania~~

$$\text{Zatem} \quad \frac{k}{k-1} R \theta + \frac{u^2 + v^2 + w^2}{2} = \text{const} = \frac{k}{k-1} R \theta_0 \quad \text{[jako że w powyższym uogólnieniu]}$$

maksymalna wartość dla prędkości gdy  $\theta = 0$

$$\frac{u^2 + v^2 + w^2}{2} = \frac{k}{k-1} R \theta_0 = \frac{k}{k-1} \frac{p_0}{\rho_0}$$



$$\sqrt{k^2 v^2} = \sqrt{\frac{2}{k-1}} \sqrt{k \frac{p_0}{\rho_0}}$$

but the magnitude  $a^2 = k \frac{p}{\rho} = k R \theta$  173

$\sqrt{\frac{2}{k-1}}$  is independent, motive pressure =  $\sqrt{\frac{2}{k-1}}$  <sup>empirical</sup> ratio pressure flow

$$\sqrt{\frac{2}{0.4}} = \sqrt{5} = 2.24$$

which immediately gives nozzle exit pressure (0° ab.)

Synthesizing with Riemann & Wamant properties:

$$\sqrt{u} = a$$

$$\frac{k}{k-1} \theta + \frac{k \theta}{2} = \frac{k}{k-1} \theta_0$$

$$(2+k-1)\theta = 2\theta_0$$

$$\theta = \frac{2\theta_0}{k+1}$$

$$\theta_0 - \theta = \theta_0 \frac{k-1}{k+1}$$

$$h_f. \theta_0 = 300$$

$$\theta_0 - \theta = \frac{0.4}{2.4} \cdot 300 = 50^\circ$$

$$\begin{array}{r} + 27^\circ \\ - 23^\circ \end{array}$$





Entropie form  $S = k \ln \theta + R \ln v + \text{const}$

$R \ln \frac{1}{\rho} - 2k \ln \theta = c_v (\ln \theta + (k-1) \ln v)$

$= c_v \ln \frac{\theta}{\rho^{k-1}} + \text{const} = c_v \ln \frac{p}{\rho^k} + \text{const.}$

$\frac{\partial f}{\partial x} = \mu \frac{\partial u}{\partial x} -$

$p = p_1 + p_2$

$u = u_1 + u_2$

$\frac{\partial p u}{\partial x} + = 0$

$(p_1 + p_2) \left( \frac{\partial u_1}{\partial x} + \frac{\partial u_2}{\partial x} \right) + (u_1 + u_2) \left( \frac{\partial p_1}{\partial x} + \frac{\partial p_2}{\partial x} \right) + \dots = 0$

Podstawienie rozprawy ułamkowej uformuła opiera dla bardzo małych  $\frac{\partial p}{\partial x} \neq 0$

$p_1 \frac{\partial u_2}{\partial x} + p_2 \frac{\partial u_1}{\partial x} + u_1 \frac{\partial p_2}{\partial x} + u_2 \frac{\partial p_1}{\partial x} + = 0$

$\frac{\partial p}{\partial x} = \mu \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \right) + \mu \frac{\partial u}{\partial x} +$

$p = p_1 + p_2$

$u = u_1 + u_2$

$\frac{\partial p_2}{\partial x} = \mu \frac{\partial}{\partial x} \left( \frac{\partial u_2}{\partial x} + \right) + \mu \frac{\partial u_2}{\partial x} +$

$\mu \frac{\partial u}{\partial x} + u \frac{\partial p}{\partial x} = 0$

$\mu \frac{\partial u_1}{\partial x} + = 0$

$\mu \left( \frac{\partial u_2}{\partial x} + \right) + u \frac{\partial p}{\partial x} = 0$

$(u_1 + u_2) \left( \frac{\partial p_1 + p_2}{\partial x} \right) = 0$



Rozwiązanie obliczenia dla kół i prędkości

Równanie: istotniejsze: o dystrybucji

$$\left\{ \begin{array}{l} \frac{\partial \rho}{\partial x} = \frac{\mu}{3} \frac{\partial \rho}{\partial x} + \mu \Delta^2 u \\ k \rho \operatorname{div} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = 0 \end{array} \right.$$

Suponujemy  $\rho$  jako bierze dwie, podnoszą  $\frac{\partial \rho}{\partial x}$  maleje, stąd  $\rho \operatorname{div} = 0$   
 więc mamy wtedy jak u cięży  $\rho \approx P + \rho$   $P = \text{const}$

$$\operatorname{div} = - \frac{1}{P + \rho} \left( u \frac{\partial \rho}{\partial x} + \dots \right)$$

$$= - \frac{1}{P} \left( u \frac{\partial \rho}{\partial x} + \dots \right) + \frac{\rho}{P^2} \left( u \frac{\partial \rho}{\partial x} + \dots \right)$$

$$\rho = \rho_0 + \frac{1}{P} \rho' + \frac{1}{2P^2} \rho'' + \dots$$

$$\left\{ \begin{array}{l} \frac{\partial \rho_0}{\partial x} + \frac{1}{P} \frac{\partial \rho'}{\partial x} + \dots = \frac{\mu}{3} \frac{\partial \rho}{\partial x} + \frac{1}{P} \operatorname{div}' + \dots + \mu \left[ \Delta^2 u_0 + \frac{1}{P} \Delta^2 u' + \dots \right] \\ \left( P \rho_0 + \frac{1}{P} \rho' + \dots \right) \left( \frac{\partial \rho_0}{\partial x} + \frac{1}{P} \frac{\partial \rho'}{\partial x} + \dots \right) + \mu \left( u_0 + \frac{1}{P} u' \right) \left( \frac{\partial \rho_0}{\partial x} + \frac{1}{P} \frac{\partial \rho'}{\partial x} + \dots \right) = 0 \end{array} \right.$$

Formuły rozkładu  $\frac{1}{P}$ :

$$\frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial \rho_0}{\partial x} + \dots = 0 \quad \rho = \rho_0 + \frac{1}{P} \rho'$$

$$\frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial \rho_0}{\partial x} + \dots = 0 \quad \frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0$$

$$\frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial \rho_0}{\partial x} + \dots = 0 \quad \frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0$$

$$\frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial \rho_0}{\partial x} + \dots = 0 \quad \frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0$$

$$\frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial \rho_0}{\partial x} + \dots = 0 \quad \frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0$$

$$\frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0 \quad \frac{\partial \rho_0}{\partial x} + \dots = 0 \quad \frac{\partial \rho_0}{\partial x} = \mu \Delta^2 u_0$$



$$\frac{1}{\rho} (\text{div}' + \dots) \left( 1 + \frac{\rho_0}{\rho} + \frac{1}{\rho} \rho' + \dots \right) + \left( \rho_0 + \frac{1}{\rho} u' \right) \left( \frac{\partial \rho_0}{\partial x} + \frac{1}{\rho} \frac{\partial \rho'}{\partial x} \right) + \dots = 0$$

$$k \text{div}' + u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z} = 0$$

$$\left. \begin{aligned} \frac{\partial \rho'}{\partial x} &= \frac{\mu}{3} \frac{\partial \text{div}'}{\partial x} + \mu \Delta^2 u' \\ \frac{\partial \rho'}{\partial y} &= \frac{\mu}{3} \frac{\partial \text{div}'}{\partial y} + \mu \Delta^2 v' \\ \frac{\partial \rho'}{\partial z} &= \frac{\mu}{3} \frac{\partial \text{div}'}{\partial z} + \mu \Delta^2 w' \end{aligned} \right\} \begin{aligned} \Delta^2 \rho' &= \frac{4\mu}{3} \Delta^2 \text{div}' \\ \rho' &= \frac{4\mu}{3} \text{div}' + \varphi \end{aligned} \quad \Delta^2 \varphi = 0$$

$$\mu \frac{\partial \text{div}'}{\partial x} + \frac{\partial \varphi}{\partial x} = \mu \Delta^2 u' = \frac{\partial}{\partial x} (\mu \text{div}' + \varphi)$$

$$\mu \Delta^2 v' = \frac{\partial}{\partial y} ( \quad )$$

$$\mu \Delta^2 w' = \frac{\partial}{\partial z} ( \quad )$$

$$\frac{1}{\rho} \text{div}' u_0 \frac{\partial \rho_0}{\partial x} + \dots = k \text{div}'$$

$$\rho = \rho_0 - \frac{3}{2} \mu c a \frac{x}{r^3}$$

$$\frac{\partial \rho}{\partial x} = -\frac{3}{2} \mu c a \left( \frac{1}{r^3} - \frac{3x^2}{r^5} \right) \quad \left| \quad u = -\frac{3}{4} \frac{c a}{r^4} \left( 1 - \frac{a^2}{r^2} \right) \frac{x^2}{r^3} + c \left( 1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right)$$

$$\frac{\partial \rho}{\partial y} = \frac{3}{2} \mu c a \frac{3xy}{r^5} \quad \left| \quad v = -\frac{3}{4} c a \left( 1 - \frac{a^2}{r^2} \right) \frac{xy}{r^3}$$

$$\frac{\partial \rho}{\partial z} = \frac{3}{2} \mu c a \frac{3xz}{r^5} \quad \left| \quad w = -\frac{3}{4} c a \left( 1 - \frac{a^2}{r^2} \right) \frac{xz}{r^3} \right.$$

$$\frac{\partial}{\partial x} \left( \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} \right) = -\frac{27}{8} \mu c^2 a^2 \frac{x^2}{r^6} + \frac{9}{8} \mu c^2 a^2 \left( 1 - \frac{a^2}{r^2} \right) \frac{x^2}{r^6} - \frac{3}{2} \mu c^2 a \frac{1}{r^3} \left( 1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right)$$

$$+ \frac{9}{2} \mu c^2 a \frac{x^2}{r^5} \left( 1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right)$$



$$\begin{aligned}
 -k \operatorname{div}' &= -\frac{3}{2} \mu a c^2 \frac{1}{r^3} \left( 1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right) + \frac{9}{2} \mu c^2 a \frac{x^2}{r^5} \left( 1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right) \\
 &\quad - \frac{18}{8} \mu c^2 a \frac{x^2}{r^5} \left( \frac{a}{r} - \frac{a^3}{r^3} \right) \\
 &\quad + \frac{9}{2} \mu c^2 a \frac{x^2}{r^5} \left( 1 - \frac{5}{4} \frac{a}{r} + \frac{1}{4} \frac{a^3}{r^3} \right)
 \end{aligned}$$

symmetry axis  $dx \pm x$

$$\text{dla } r=a, r=\infty$$

$$\operatorname{div}' = 0$$

$$\text{dla } x=0: r>a \quad \operatorname{div}' < 0$$

$$\text{dla } x=r: (\sigma' \chi) \quad \operatorname{div}' = \mu c^2 a \frac{1}{r^3} \left[ 3 - \frac{9}{2} \frac{a}{r} + \frac{3}{2} \frac{a^3}{r^3} \right] = 3 \mu c^2 a \frac{1}{r^3} \left[ 1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3} \right]$$

$$\begin{aligned}
 \frac{a}{r} &= 1 - \delta & 1 - \frac{3}{2}(1-\delta) + \frac{1}{2}(1-\delta)^3 &= \frac{3}{2}\delta - \frac{3}{2}\delta^2 + \frac{3}{2}\delta^3 - \frac{\delta^3}{2} \\
 & & &> 0
 \end{aligned}$$

$$\operatorname{div}' > 0$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^2 u}{\partial x \partial z} = \frac{\partial \operatorname{div}'}{\partial x} = \Delta^2 u + \underbrace{\frac{\partial \xi}{\partial y} - \frac{\partial \eta}{\partial z}}_{= -\frac{\partial \varphi}{\partial x}}$$

$$\frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} - \frac{\partial u}{\partial y} \right) + \frac{\partial u}{\partial y} \left( \frac{\partial}{\partial z} \left( \frac{\partial u}{\partial x} - \frac{\partial u}{\partial z} \right) \right) + \frac{\partial^2 u}{\partial z^2}$$

$$\frac{\partial \operatorname{div}'}{\partial y} = \Delta^2 u + \underbrace{\frac{\partial \xi}{\partial z} - \frac{\partial \xi}{\partial x}}_{= -\frac{\partial \varphi}{\partial y}}$$

$$\frac{\partial \operatorname{div}'}{\partial z} = \Delta^2 u + \underbrace{\frac{\partial \eta}{\partial x} - \frac{\partial \eta}{\partial y}}_{= -\frac{\partial \varphi}{\partial z}}$$

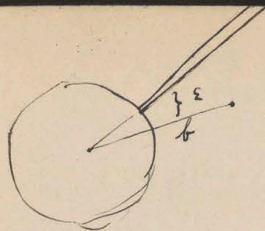
$$\xi=0 \quad \frac{\partial u}{\partial y} - \frac{\partial u}{\partial z} = 0$$

$$\frac{\partial \xi}{\partial x} = \frac{\partial \varphi}{\partial y} \quad \frac{\partial \eta}{\partial x} = -\frac{\partial \varphi}{\partial z}$$

$$\frac{\partial^2 \xi}{\partial x \partial z} + \frac{\partial^2 \eta}{\partial x \partial y} = 0$$

$$\frac{\partial \xi}{\partial x} + \frac{\partial \eta}{\partial y} = f(y, z)$$





$$\int_a^\infty \frac{1}{r^3} \left( 1 - \frac{5}{4} \frac{a}{r} + \frac{1}{4} \frac{a^3}{r^3} \right) \cdot \cos^2 \theta \cdot \frac{dr}{\sqrt{b^2 + r^2 - 2br \cos \theta}}$$

$$\frac{\partial}{\partial x} \left( \frac{x^m}{r^n} \right) = m \frac{x^{m-1}}{r^n} - n \frac{x^{m+1}}{r^{n+2}}$$

$$\frac{\partial^2}{\partial x^2} ( ) = m(m-1) \frac{x^{m-2}}{r^n} - \cancel{m(m-1)} n(2m+1) \frac{x^m}{r^{n+2}} + n(n+2) \frac{x^{m+2}}{r^{n+4}}$$

$$\frac{\partial}{\partial y} \left( \frac{x^m}{r^n} \right) = -n \frac{x^m y}{r^{n+2}}$$

$$\frac{\partial^2}{\partial y^2} ( ) = -n \frac{x^m}{r^{n+2}} + n(n+2) \frac{x^m y^2}{r^{n+4}}$$

$$\Delta^2 \left( \frac{x^m}{r^n} \right) = m(m-1) \frac{x^{m-2}}{r^n} - \frac{x^m}{r^{n+2}} [n(2m+1) + 2n] + \frac{x^m}{r^{n+2}} n(n+2)$$

$$= m(m-1) \frac{x^{m-2}}{r^n} + \frac{x^m}{r^{n+2}} \underbrace{[n^2 + 2n - 2mn - 3n]}_{n^2 - 2mn - n}$$

$$m=4 \quad n=10$$

$$m=2$$

$$\Delta^2 \left( \frac{x^2}{r^n} \right) = \frac{2}{r^n} + (n^2 - 5n) \frac{x^2}{r^{n+2}}$$

$$n=3 : \Delta^2 \left( \frac{x^2}{r^3} \right) = \frac{2}{r^3} - 6 \frac{x^2}{r^5} = 2 \left( \frac{1}{r^3} - \frac{3x^2}{r^5} \right)$$

$$n=4 : \Delta^2 \left( \frac{x^2}{r^4} \right) = \frac{2}{r^4} - 4 \frac{x^2}{r^6} = 2 \left( \frac{1}{r^4} - \frac{2x^2}{r^6} \right)$$

$$n=5 : \Delta^2 \left( \frac{x^2}{r^5} \right) = \frac{2}{r^5}$$

$$n=6 : \Delta^2 \left( \frac{x^2}{r^6} \right) = \frac{2}{r^6} + 6 \frac{x^2}{r^8} = 2 \left( \frac{1}{r^6} + 3 \frac{x^2}{r^8} \right)$$

8

$$\frac{x^2}{r^5} = \frac{1}{3} \frac{1}{r^3} - \frac{1}{6} \Delta^2 \left( \frac{x^2}{r^3} \right) = \frac{2}{r^8} + \frac{66}{24} \frac{x^2}{r^{10}}$$

$$n=10 : \parallel = \frac{2}{r^{10}} + 50 \frac{x^2}{r^{12}}$$

$$\begin{array}{r} 100 \\ - 80 \\ \hline 20 \\ - 10 \\ \hline 10 \end{array}$$

$$\begin{array}{r} 64 \\ - 8 \\ \hline 56 \end{array}$$

$$\left\{ \begin{array}{l} 16 \\ 16 \\ 16 \end{array} \right\}$$

$$\left\{ \begin{array}{l} 36 \\ 36 \\ 36 \end{array} \right\}$$



$$\left. \begin{aligned} \frac{x^2}{2^5} &= \frac{1}{3} \frac{1}{2^3} - \frac{1}{6} \Delta^2 \left( \frac{x^2}{2^3} \right) \\ \frac{x^2}{2^6} &= \frac{1}{2} \frac{1}{2^4} - \frac{1}{4} \Delta^2 \left( \frac{x^2}{2^4} \right) \\ \frac{x^2}{2^8} &= -\frac{1}{3} \frac{1}{2^6} + \frac{1}{6} \Delta^2 \left( \frac{x^2}{2^6} \right) \end{aligned} \right\} \begin{aligned} & \\ & -\frac{5}{4} a \\ & \frac{1}{4} a^3 \end{aligned}$$

$$\frac{x^2}{2^5} - \frac{5}{4} a \frac{x^2}{2^6} + \frac{1}{4} a^3 \frac{x^2}{2^8} = \frac{1}{3} \frac{1}{2^3} - \frac{5}{8} \frac{a}{2^4} - \frac{1}{12} \frac{a^3}{2^6}$$

$$- \Delta^2 \left\{ \frac{1}{6} \frac{x^2}{2^3} - \frac{5}{16} \frac{a x^2}{2^4} - \frac{1}{24} \frac{a^3 x^2}{2^6} \right\}$$

$$\frac{q}{2} \mu c^2 a \left\{ \left( \frac{x^2}{2^5} - \frac{1}{4} a^3 \frac{x^2}{2^8} \right) - \frac{1}{3} \left( \frac{1}{2^3} - \frac{3}{4} \frac{a}{2^4} - \frac{1}{4} \frac{a^3}{2^6} \right) \right\} = \frac{q}{2} \mu c^2 a$$

$$\left( -\frac{5}{8} + \frac{1}{4} \right) \frac{a}{2^4} - \Delta^2 \left\{ \frac{1}{6} \frac{x^2}{2^3} - \right\}$$

$$= -\frac{q}{2} \mu c^2 a \left[ \frac{3}{8} \frac{a}{2^4} + \frac{1}{6} \Delta^2 \left( \frac{x^2}{2^3} - \frac{15}{8} \frac{a x^2}{2^4} - \frac{1}{4} \frac{a^3 x^2}{2^6} \right) \right]$$

$$\Delta^2 \left( \frac{x^2}{2^3} \right) = -\frac{\partial^2}{\partial x^2} \left( \frac{x^2}{2^3} \right) + \dots = 2 \left( -\frac{1}{2^4} + \frac{4}{2^6} \right) = \frac{2}{2^4}$$

$$= -\frac{q}{2} \mu c^2 a \left[ \frac{3}{8} \frac{a}{2^4} + \frac{1}{6} \Delta^2 \left( \frac{x^2}{2^3} - \frac{15}{8} \frac{a x^2}{2^4} - \frac{1}{4} \frac{a^3 x^2}{2^6} \right) \right]$$

$$\text{Zatem } \Delta^2 \psi = \Delta^2 \psi$$

$$\Delta^2 u' = \Delta^2 \frac{\partial \psi}{\partial x} + \frac{1}{\mu} \frac{\partial^2 \psi}{\partial x^2}$$

$$\Delta^2 v' = \Delta^2 \frac{\partial \psi}{\partial y} + \frac{1}{\mu} \frac{\partial^2 \psi}{\partial y^2}$$

$$\Delta^2 w' = \Delta^2 \frac{\partial \psi}{\partial z} + \frac{1}{\mu} \frac{\partial^2 \psi}{\partial z^2}$$

$$\frac{\partial u'}{\partial x} + \frac{\partial v'}{\partial y} + \frac{\partial w'}{\partial z} = \Delta^2 \psi$$

$$\text{Pozostymi typy: } u' = \frac{\partial \psi}{\partial x} + u$$

$$v' = \frac{\partial \psi}{\partial y} + v$$

$$w' = \frac{\partial \psi}{\partial z} + w$$

$$\Delta^2 u = \frac{1}{\mu} \frac{\partial^2 p}{\partial x^2}$$

$$\Delta^2 v =$$

$$\Delta^2 w =$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$\Delta^2 p = 0$  } Zupelni  
to samo  
jak dla  
u, v, w



$$-k \frac{\partial \psi}{\partial x} = -\mu c^2 a^2 \left[ -\frac{27}{8} \frac{x}{a^3} \frac{x}{2} + 3 \left( \frac{x}{2^3} - \frac{15ax}{8a^4} - \frac{a^3 x}{4a^6} \right) - \frac{3}{2} \left( \frac{3x^3}{2^5} - \frac{15}{2} \frac{ax^3}{2^6} - \frac{3}{2} \frac{a^3 x^3}{2^8} \right) \right] \quad 177$$

$$= -\mu c^2 a^2 \left[ \frac{3x}{2^3} \left[ 1 - \cancel{3} \frac{a}{2} - \frac{1}{4} \frac{a^3}{x^3} \right] - \frac{9}{4} \frac{x^3}{2^5} \left[ 1 - \frac{5}{2} \frac{a}{2} - \frac{1}{2} \frac{a^3}{2^3} \right] \right]$$

$$-k \frac{\partial \psi}{\partial y} = -\mu c^2 a \left[ -\frac{27}{8} \frac{ay}{a^4} - \frac{9}{4} \frac{x^2 y}{2^5} \left[ 1 - \frac{5}{2} \frac{a}{2} - \frac{1}{2} \frac{a^3}{2^3} \right] \right]$$

$$-k \frac{\partial \psi}{\partial z} = -\mu c^2 a \left[ - - - - - \right]$$

Sta  $x=a$ :

$$-k \frac{\partial \psi}{\partial x} \Big|_{x=a} = -\mu c^2 a \left[ \frac{3}{a^3} \cancel{a} \left( -\frac{9}{4} \right) - \frac{9}{2} \frac{x^3}{a^5} (-2) \right] = \frac{\mu c^2 a}{2a} \left[ \frac{27}{4} \frac{x}{a} - 9 \frac{x^3}{a^3} \right]$$

$$= \frac{9\mu c^2}{2a} \left[ \frac{3}{4} \frac{x}{a} - \frac{x^3}{a^3} \right]$$

$$-k \frac{\partial \psi}{\partial y} \Big|_{x=a} = +\mu c^2 a \left[ \frac{27}{8} \frac{ay}{a^4} + \frac{9}{2} \frac{x^2 y}{a^5} (-2) \right] = \frac{9\mu c^2}{2a} \left[ \frac{3}{8} \frac{y}{a} - \frac{x^2 y}{a^3} \right]$$

$$-k \frac{\partial \psi}{\partial z} \Big|_{x=a} = \cancel{\mu c^2 a} \left[ - - - - - \right] = \frac{9\mu c^2}{2a} \left[ \frac{3}{8} \frac{z}{a} - \frac{x^2 z}{a^3} \right]$$

Wzrostowi  $\Delta^2 \psi$ :

$$3 \frac{1}{2^3} \left[ 1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right] - 9 \frac{x^2}{2^5} \left[ 1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right] + 3 \frac{x^2}{2^3} \left[ \frac{3a}{2^3} + \frac{3}{4} \frac{a^3}{2^5} \right] -$$

$$- \frac{27}{2} \frac{x^2}{2^5} \left[ 1 - \frac{5}{2} \frac{a}{2} - \frac{1}{2} \frac{a^3}{2^3} \right] + \frac{45}{2} \frac{x^4}{2^7} \left[ 1 - \frac{5}{2} \frac{a}{2} - \frac{1}{2} \frac{a^3}{2^3} \right] - \frac{9}{2} \frac{x^4}{2^5} \left[ \frac{5}{2} \frac{a}{2^3} + \frac{3}{2} \frac{a^3}{2^5} \right]$$

$$- \frac{27}{8} \frac{a}{2^4} - \frac{9}{2} \frac{x^2}{2^5} \left[ 1 - \frac{5}{2} \frac{a}{2} - \frac{1}{2} \frac{a^3}{2^3} \right] + \frac{27}{2} \frac{ay^2}{2^6} + \frac{45}{2} \frac{x^2 y^2}{2^7} \left[ 1 - \frac{5}{2} \frac{a}{2} - \frac{1}{2} \frac{a^3}{2^3} \right] -$$

$$- \frac{9}{2} \frac{x^2 y^2}{2^5} \left[ \frac{5}{2} \frac{a}{2^3} + \frac{3}{2} \frac{a^3}{2^5} \right]$$

$$- \frac{27}{8} \frac{a}{2^4} - \frac{9}{2} \frac{x^2}{2^5} \left[ 1 - \frac{5}{2} \frac{a}{2} - \frac{1}{2} \frac{a^3}{2^3} \right] + \frac{27}{2} \frac{a^2 z^2}{2^6} + \frac{45}{2} \frac{x^2 z^2}{2^7} \left[ 1 - \frac{5}{2} \frac{a}{2} - \frac{1}{2} \frac{a^3}{2^3} \right] -$$

$$- \frac{9}{2} \frac{x^2 z^2}{2^5} \left[ \frac{5}{2} \frac{a}{2^3} + \frac{3}{2} \frac{a^3}{2^5} \right]$$



$$\begin{aligned}
&= 3 \frac{1}{r^3} \left[ 1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{r^3} \right] - \frac{27}{4} \frac{a}{r^4} + \frac{27}{2} a \frac{(r^2 + 2^2)}{r^6} - \frac{9x^2}{r^5} \left[ 1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{r^3} \right] \\
&\quad + \frac{3x^2}{r^3} \left[ \frac{3a}{r^3} + \frac{3}{4} \frac{a^3}{r^5} \right] - \frac{9}{2} \frac{x^2}{r^3} \left[ \frac{5}{2} \frac{a}{r^3} + \frac{3}{2} \frac{a^3}{r^5} \right] \\
&= \frac{3}{r^3} \left[ 1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{r^3} \right] - \frac{27}{4} \frac{a}{r^4} + \frac{27}{2} \frac{a}{r^4} \left[ 1 - \frac{x^2}{r^2} \right] - \frac{9x^2}{r^5} \left[ 1 - \frac{3a}{2} - \frac{1}{4} \frac{a^3}{r^3} \right] \\
&\quad + \frac{3x^2}{r^5} \left[ 3 \frac{a}{r^3} + \frac{3}{4} \frac{a^3}{r^5} \right] - \frac{9}{2} \frac{x^2}{r^5} \left[ \frac{5}{2} \frac{a}{r^3} + \frac{3}{2} \frac{a^3}{r^5} \right] \\
&= \frac{3}{r^3} \left[ 1 - \frac{3a}{4r} - \frac{1}{4} \frac{a^3}{r^3} \right] + \frac{x^2}{r^5} \left[ \frac{1}{2} \left( -\frac{27}{2} + 27 + 9 - \frac{45}{4} \right) + \frac{a^3}{r^3} \left[ \frac{9}{4} + \frac{9}{4} - \frac{27}{4} \right] \right] \\
&= \frac{3}{r^3} \left[ 1 - \frac{3a}{4r} - \frac{1}{4} \frac{a^3}{r^3} \right] + \frac{9}{r^5} \left[ 1 + \frac{5}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right] \quad \text{Jedna cis}
\end{aligned}$$

Tvor nález jine U V W tak anayí zby na porinění ov  
vartóni byt nález:

$$U = - \frac{27 \mu c^2}{8a} \frac{x}{a} \left[ 1 - \frac{4}{3} \frac{x^2}{a^2} \right]$$

$$V = - \frac{27 \mu c^2}{8a} \frac{y}{a} \left[ \frac{1}{2} - \frac{4}{3} \frac{x^2}{a^2} \right]$$

$$W = - \frac{27 \mu c^2}{8a} \frac{z}{a} \left[ \frac{1}{2} - \frac{4}{3} \frac{x^2}{a^2} \right]$$

Jedn usigreni:

$$U = \frac{1}{\mu} \sum \left\{ \frac{r^2}{2(2n+1)} \frac{d p_n}{dx} + \frac{n r^{2n+3}}{(n+1)(2n+1)(2n+3)} \frac{d}{dx} \left( \frac{p_n}{r^{2n+1}} \right) \right\} + \sum \frac{d p_n}{dx}$$

$$V = \frac{d}{dy} \quad \frac{d}{dy} \quad \frac{d p_n}{dy}$$

$$W =$$



$$\begin{aligned} \mu_0 &= \omega \mu_1 \\ \mu_1 &= x \\ \mu_2 &= \mu = 2^m \sin \\ \mu_{-1} &= \\ \mu_{-2} &= \frac{1}{2^{m+1}} \sin \end{aligned}$$

$$\frac{4x^2}{2^3}$$

$$\frac{2x}{2^4} - \frac{3x^3}{2^5}$$

$$\mu_n =$$

$$xu + yv + zw = 0$$

$$\int_0 = 1$$

$$\int_1 = \omega$$

$$\int_2 = \frac{1}{2}(3\omega^2 - 1)$$

$$\int_3 = \frac{1}{2}(5\omega^3 - 3\omega)$$

$$x \quad \frac{x}{2^3}$$

$$\frac{1}{2} \mu_0 = 1 \quad \mu_{-1} = \frac{1}{2}$$

$$\mu_1 = x \quad \mu_{-2} = \frac{x}{2^3}$$

$$\mu_2 = \frac{1}{2}(3x^2 - x^2) \quad \mu_{-3} = \frac{1}{2x^3}(3\frac{x^2}{x^2} - 1)$$

$$\frac{xu + yv + zw}{n} = \frac{1}{n} \sum_{n=1}^{\infty} \mu_n + \frac{1}{n} \sum_{n=1}^{\infty} \mu_{-n} = 0$$

$n < -1$        $n < 0$

$$\begin{aligned} \frac{\partial \mu_{-3}}{\partial x} &= \frac{\partial}{\partial x} \left[ \frac{1}{2x^3} (3\frac{x^2}{x^2} - 1) \right] + \frac{3x}{2x^5} - \frac{3x^3}{2x^7} = \frac{3x}{2x^5} \left[ \frac{3}{2} - \frac{5}{2} \frac{x^2}{x^2} \right] \\ &= \frac{4x}{2x^5} \left[ 1 - \frac{5}{3} \frac{x^2}{x^2} \right] \end{aligned}$$

$$\frac{\partial \mu_{-3}}{\partial y} = \frac{\partial}{\partial y} \left[ \frac{1}{2x^3} (3\frac{x^2}{x^2} - 1) \right] - \frac{3yx^2}{2x^7} = \frac{3y}{2x^5} \left[ 1 - \frac{5}{2} \frac{x^2}{x^2} \right] = \frac{4}{2} \frac{y}{x^5} \left[ \frac{1}{3} - \frac{5}{3} \frac{x^2}{x^2} \right]$$

$$\frac{\partial}{\partial x} \left( \frac{\mu_{-3}}{x^5} \right) = \frac{\partial}{\partial x} \left[ \frac{1}{2} \left( \frac{3x^2}{x^2} - 1 \right) \right] = \frac{1}{2} \frac{\partial}{\partial x} \left[ \frac{3x^2}{x^2} - x^2 \right] = 3x - x = 2x$$

$$\frac{\partial}{\partial y} \left( \frac{\mu_{-3}}{x^5} \right) = \frac{1}{2} \frac{\partial}{\partial y} [3x^2 - x^2] = -y$$



$$n = -3$$

$$U = \frac{-x^2}{2.5} \cdot \frac{3x}{x^5} \left[ \frac{3}{2} - \frac{5}{2} \frac{x^2}{x^2} \right] + \frac{1}{2.5} \cdot \frac{1}{x^3} \cdot 2x = \frac{1}{10} \frac{x}{x^3} \left[ -\frac{5}{2} + \frac{15}{2} \frac{x^2}{x^2} \right]$$

$$= -\frac{1}{4} \frac{x}{x^3} \left[ 1 - 3 \frac{x^2}{x^2} \right]$$

$$V = \frac{-x^2}{2.5} \cdot \frac{3x}{x^5} \left[ \frac{1}{2} - \frac{5}{2} \frac{x^2}{x^2} \right] - \frac{1}{10} \cdot \frac{1}{x^3} \cdot x = \frac{1}{10} \frac{x}{x^3} \left[ -\frac{5}{2} + \frac{15}{2} \frac{x^2}{x^2} \right]$$

$$= -\frac{1}{4} \frac{x}{x^3} \left[ 1 - 3 \frac{x^2}{x^2} \right]$$

$$U = A \frac{x}{x^3} \left[ 1 - 3 \frac{x^2}{x^2} \right] + B \frac{x}{x^3} + C \frac{x}{x^5} \left[ \frac{3}{2} - \frac{5}{2} \frac{x^2}{x^2} \right]$$

$$V = A \frac{x}{x^3} \left[ 1 - 3 \frac{x^2}{x^2} \right] + B \frac{x}{x^3} + C \frac{x}{x^5} \left[ \frac{1}{2} - \frac{5}{2} \frac{x^2}{x^2} \right]$$

$$A \left[ \frac{1}{a^3} + B \frac{1}{a^3} + \frac{3}{2} C \frac{1}{a^5} \right] = \frac{1}{a}$$

$$\left[ -3A \frac{1}{a^5} - \frac{5}{2} C \frac{1}{a^7} \right] \cdot x^3 = -\frac{4}{3} \frac{x^3}{a^3}$$

$$A \frac{1}{a^3} + B \frac{1}{a^3} + \frac{1}{2} C \frac{1}{a^5} = \frac{1}{2} \frac{1}{a}$$

$$-3A \frac{1}{a^5} - \frac{5}{2} C \frac{1}{a^7} = -\frac{4}{3} \frac{1}{a^3}$$

$$\frac{3A}{a^5} + \frac{5}{4} \frac{1}{a^3} = \frac{4}{3} \frac{1}{a^3}$$

$$\frac{3A}{a^5} = \left( \frac{4}{3} - \frac{5}{4} \right) \frac{1}{a^3} = \frac{1}{12} \frac{1}{a^3}$$

$$A = \frac{a^2}{36}$$



$$A + B + \frac{1}{2} C \frac{1}{a^2} = \frac{1}{2} a^2$$

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$$B = \frac{1}{2} a^2 - \frac{a^2}{36} - \frac{1}{2} \frac{a^2}{2} = \frac{2}{9} a^2$$

$$U = -\frac{27 \mu c^2}{8a} \left[ \frac{a^2}{36} \left\{ \frac{x}{a^3} \left[ 1 - 3 \frac{x^2}{a^2} \right] + 8 \frac{x}{a^3} \right\} + \frac{a^4}{2} \frac{x}{a^5} \left[ \frac{3}{2} - 5 \frac{x^2}{a^2} \right] \right]$$

$$U = -\frac{27 \mu c^2}{8a} \left[ -\frac{a^2}{12} \frac{x^3}{a^5} + \frac{a^4}{4} \frac{x}{a^5} \left[ 3 - 5 \frac{x^2}{a^2} \right] \right]$$

$$V = -\frac{27 \mu c^2}{8a} \left[ -\frac{a^2}{12} \frac{y^2}{a^5} + \frac{a^4}{4} \frac{y}{a^5} \left[ 1 - 5 \frac{x^2}{a^2} \right] \right]$$

$$U = +\frac{27 \mu c^2 a^4}{32} \left[ \frac{1}{3} \frac{x}{a^5} - \frac{a^2 x}{a^5} \left( 3 - 5 \frac{x^2}{a^2} \right) \right]$$

$$V = \frac{27 \mu c^2 a^4}{32} \left[ \frac{1}{3} \frac{y}{a^5} - \frac{a^2 y}{a^5} \left( 1 - 5 \frac{x^2}{a^2} \right) \right]$$

Proba:  $\frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} + \frac{\partial W}{\partial z} \sim = \frac{x^2}{a^5} - \frac{5}{3} \frac{x^4}{a^7} - \left( \frac{3a^2}{a^5} + \frac{15a^2 x^2}{a^7} + \frac{15a^2 x^2}{a^7} - \frac{35x^4}{a^9} \right)$

$+ \frac{1}{a^3} - \frac{3x^2}{a^5} = 0$

$+ \frac{1}{2}$

$= -\frac{5a^2}{a^7} (x^2 + y^2) + \frac{5a^2 x^2}{a^7}$

$= \frac{1}{a^7} \left\{ 2 - \frac{5}{3} (x^4 + y^4 + 2x^2 y^2) \right\} = 0$

$$\Delta^2 U \sim \frac{1}{3} \left( 6 \frac{x}{a^5} - 10 \frac{x^3}{a^7} \right) - 3a^2 \left( 10 \frac{x}{a^7} \right) + 5a^2 \left( 6 \frac{x}{a^7} \right) = \frac{2x}{a^5} - \frac{10}{3} \frac{x^3}{a^7}$$

$$\Delta^2 V \sim \frac{2}{3} \frac{y}{a^5} - \frac{10}{3} \frac{y^3}{a^7}$$

$$\Delta^2 W \sim \frac{2}{3} \frac{x}{a^5} - \frac{10}{3} \frac{x^3}{a^7}$$

$$\frac{\partial}{\partial x} \left( \frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} + \frac{\partial W}{\partial z} \right) \sim 0$$

zgodno z



Curvature radius

transverse

longitudinal

$\Delta \theta$

$\frac{\partial \theta}{\partial x}$

$$\theta = \frac{1}{4\pi} \int \frac{\Delta \theta}{r} dx$$

$\Delta \theta \frac{\partial \theta}{\partial x}$

$\Delta^2 u$

grad  $\lambda \frac{\partial u}{\partial x}$

$$N_{\frac{1}{2}} \int \frac{\Delta^2 u}{r} dx$$

$\Delta u \cdot \frac{\partial u}{\partial x}$

max by the method:

def. from given  
 $\Delta u$   
 only in part  
 given by





$$\frac{\mu_1 - \mu_2}{l} \frac{a^4 n}{8\mu} = F$$

$$\mu_1 - \mu_2 = \frac{8\mu}{a^4 n} F l$$

$$\frac{40000. \text{ g. } 0.0015. 1000}{3.16} = 0.06 \text{ atm}$$

$$-\frac{52}{27}$$

$$-\frac{5}{27} + \frac{352^2}{29}$$

$$-\frac{72}{29}$$

$$-\frac{7}{29} + 63 \frac{2^2}{21}$$



$\frac{\partial}{\partial x}$

$$\frac{1}{3} \frac{yx^2}{n^5} - \frac{2y}{n^5} + \frac{5a^2xy}{n^7}$$

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$$\frac{1}{3} \left( \frac{2xy}{n^5} - \frac{5x^3}{n^7} \right) + \frac{5a^2xy}{n^7} + \frac{15a^2xy}{n^7} - \frac{35a^2x^3}{n^9}$$

$$\frac{2}{3} \frac{y}{n^5} - \frac{10xy}{3n^7} - \frac{25x^2}{3n^7} + \frac{35x^4}{3n^9} + \frac{15a^2y}{n^7} - \frac{23.5.7}{n^9} \frac{a^2x^2}{n^9} - \frac{35.7}{n^9} \frac{a^2x^2}{n^9} + 9.35 \frac{a^2xy}{n^{11}}$$

$$\frac{1}{3} \frac{x^2}{n^5} - \frac{15x^4}{3n^7} - \frac{5x^2}{n^5} + \frac{5a^2y^2}{n^7} + \frac{5a^2x^2}{n^7} - \frac{35a^2xy^2}{n^9}$$

$$-\frac{5}{3} \frac{x^4}{n^7} - \frac{10x^4}{3n^7} + \frac{15.7}{3} \frac{x^4y^3}{n^9} + \frac{15a^2y}{n^7} + \frac{35a^2y^3}{n^9} - \frac{105a^2xy}{n^9} + 35.9 \frac{a^2xy^3}{n^{11}}$$

$$\frac{1}{3} \frac{yx^2}{n^5} - \frac{2y}{n^5} + \frac{5a^2xy}{n^7}$$

$$-\frac{5}{3} \frac{yx^2}{n^7} + \frac{35}{3} \frac{yx^2}{n^9} + \frac{5a^2y}{n^7} - \frac{35a^2y^2}{n^9} - \frac{35a^2xy}{n^9} + \frac{9.35}{n^{11}} \frac{a^2xy^2}{n^9}$$

$$+\frac{35x^2y}{n^7} - \frac{35a^2y^2}{n^9}$$

$$+9.35 \frac{a^2xy}{n^9}$$

$$\frac{2}{3} \frac{y}{n^5} - \frac{10}{3} \frac{xy^2}{n^7}$$

=0

$$- \frac{35a^2y}{n^7}$$

$$-105$$

$$-210$$

$$-35$$

$$350$$

$$+ 315$$

$$= -35 \frac{a^2xy}{n^9}$$

$$\frac{2}{n^5} - \frac{10x^2}{n^7} - \frac{10x^2}{n^7} + \frac{70x^4}{3n^9}$$

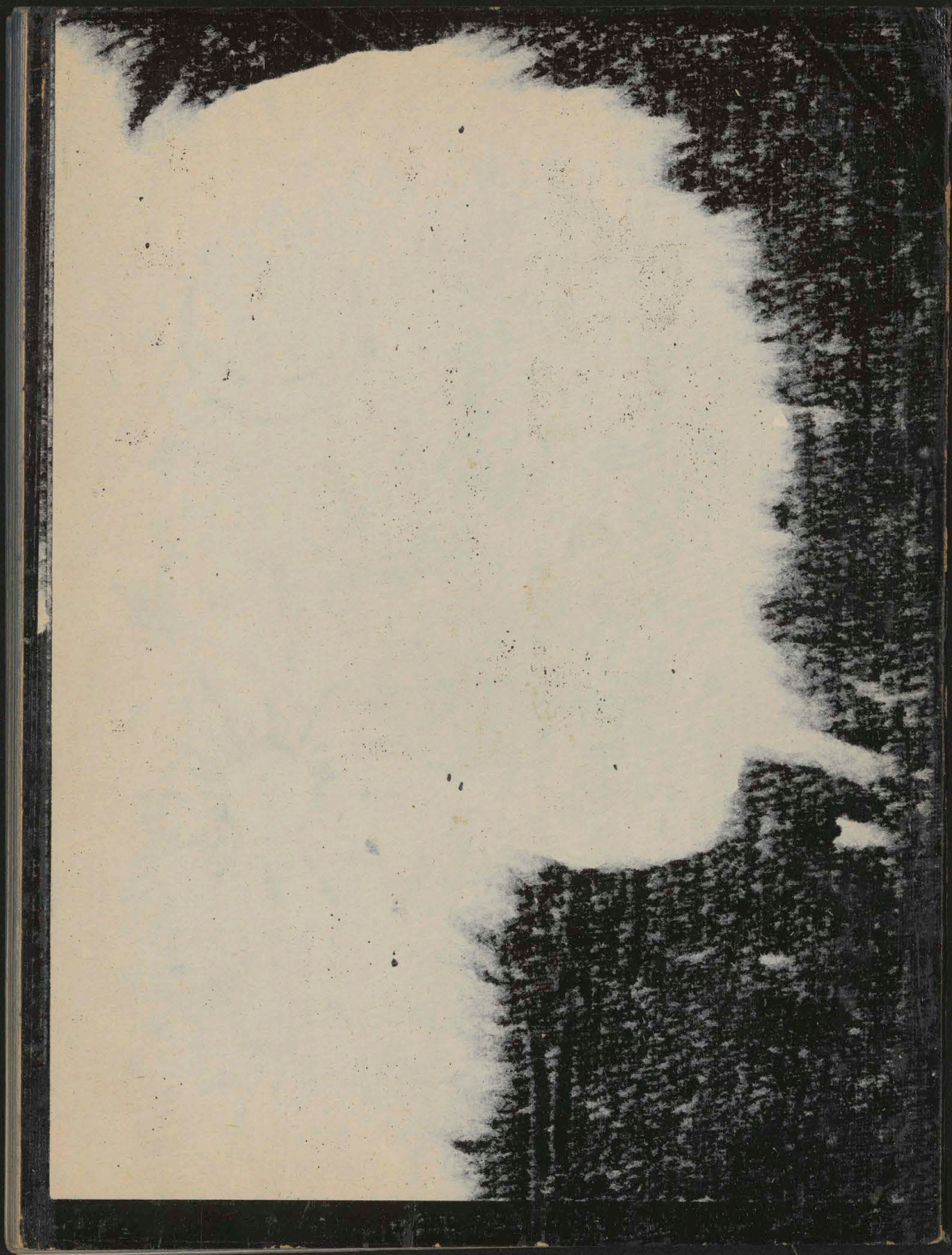
$$\frac{10}{3} \frac{1}{n^5} - \frac{10}{3}$$

$$\frac{2}{3n^5} - \frac{10}{3} \frac{y^2}{n^7} - \frac{10x^2}{3n^7} + \frac{70x^4}{3n^9}$$

$$\frac{2}{3n^5} - \frac{10}{3} \frac{y^2}{n^7} - \frac{10x^2}{3n^7} + \frac{70x^4}{3n^9}$$

$$\frac{70x^2}{3n^7}$$







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II



70 5/11  
30

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Rindski O. *butcher* *fil. nigritus* *in* *photodark* *chromatid*  
Page 33 (13) p. 277 (1898)

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Phil. Mag. 50 (1905) p. 210 Rayleigh  
On a theorem analogous to the Kelvin theorem

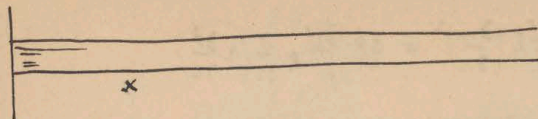
$$2 \sum m \frac{dx}{dt} \frac{dy}{dt} = \sum (x Y + y X)$$

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Thomson J. J. Elements de math. H. de Cl. & M.  
DN. 80329 CLXVIII J. 26

C.R. BN 5006 XXXVIII A1-D1





$$\frac{\partial}{\partial x} \left[ x \frac{\partial u}{\partial x} \right] = 1 - x \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial^2}{\partial r^2} \left( r \frac{\partial u}{\partial r} \right) = -\frac{\partial^2 u}{\partial x^2} + r \frac{\partial^2 u}{\partial x \partial r}$$

$$r \frac{\partial u}{\partial r} = \cancel{f(x)} + c$$

$$r \frac{\partial^2}{\partial r^2} \left( r \frac{\partial u}{\partial r} \right) = + \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right)$$

$$\log \left( r \frac{\partial u}{\partial r} \right) = + \log(r) + \cancel{f(x)}$$

$$\frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) = \cancel{r} \frac{f(x)}{r}$$

$$u = - \frac{1}{\partial r} f(x) + \cancel{f(x)}$$

$$r \frac{\partial u}{\partial r} = \frac{r^2}{2} \varphi(x) + \chi(x)$$

$$\frac{\partial u}{\partial r} = r \varphi(x) + \frac{1}{r} \chi(x)$$

$$u = \frac{r^2}{2} \varphi(x) + \chi(x) \log r + \chi(x)$$

$$u = \frac{r^2 - R^2}{2} \varphi(x)$$

$$\frac{\partial}{\partial x} (p u) = \cancel{0}$$

$$p u = \cancel{A} \times \cancel{F(x)} + \Phi(x) = p \frac{r^2 - R^2}{2} \varphi(x)$$

$$\cancel{f(x)} \quad p \varphi(x) = \cancel{A} \times \cancel{f(x)} \quad \frac{\partial}{\partial r} = 0 \quad \cancel{f(x)} = 0 \quad \cancel{f(x)} = 0$$

$$u = \frac{r^2 - R^2}{2} \frac{\varphi(x)}{p}$$

$$\frac{\partial u}{\partial r} = r \varphi(x)$$

$$\frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) = 2 r \varphi(x)$$

$$2 \varphi(x) = - \frac{d}{dx}$$

$$p \varphi(x) = c$$

$$2c = - \frac{d}{dx}$$

$$r^2 = Ax + B$$

$$\cancel{\frac{f(x)}{r^2}} = - r \frac{\partial^2 u}{\partial x^2}$$

$$r=R \quad u=0$$

$$r=0 \quad u = \text{const}$$

$$\varphi(x) = 0$$

$$0 = \frac{R^2}{2} \varphi(x) + \chi(x)$$

$$\varphi(x) = - \frac{2}{R^2} \chi$$

$$\chi(x) = - \frac{R^2}{2} \varphi(x)$$

$$u = (a^2 - r^2) \frac{k}{r}$$

$$\frac{\partial u}{\partial r} = -2r \frac{k}{r^2}$$

$$-r \frac{\partial u}{\partial x} + \mu \left[ 2 \left( \frac{\partial u}{\partial r} \right)^2 \right] = 4 \mu \frac{\partial}{\partial r} \left( r \frac{\partial \theta}{\partial r} \right)$$

$$-8 \mu \left( \frac{k}{r} \right)^2 r^2 = \frac{\partial}{\partial r} ( )$$

$$\frac{8}{3} \mu \left( \frac{k}{r} \right)^2 r^2 = \frac{\partial \theta}{\partial r} \left( \theta = \frac{8}{9} \mu \left( \frac{k}{r} \right)^2 r^3 + c \right)$$

$$\theta_0 = \frac{8}{9} \mu \frac{r^3}{r^3} = \frac{8}{9} \mu$$

$$\theta - \theta_0 = \frac{8}{9} \mu \left( \frac{k}{r} \right)^2 (r^3 - a^3)$$

$$J_1 = \frac{A}{\lambda^5} e^{-\frac{\theta}{\lambda^2}}$$

$$\frac{\partial J}{\partial \lambda} = -\frac{5}{\lambda} J + \frac{\partial}{\partial \lambda} = 0$$

$$\lambda_m \theta = \frac{\partial}{\partial \lambda}$$

$$\theta = 5 \lambda_m \theta$$

$$\begin{array}{r} 8.863.208.5 \\ 35452144 \\ \hline 3545 \end{array}$$

$$\theta = 1276.3$$

$$\frac{\partial}{\partial \lambda} = 4.4315$$

$${}^{10} \log J_\lambda = {}^{10} \log A - 5 {}^{10} \log \lambda - \frac{\theta}{\lambda^2} {}^{10} \log e$$

$$\theta = \frac{1440}{273} = 1167$$

$$\frac{\theta}{\theta} = \frac{8863.04343}{3434}$$

$$\lambda = 1: \log J = -3.8486$$

$$0.3514$$

$$2.246$$

$$58531$$

$$23920$$

$$0.346015$$

$$35452$$

$$2659$$

$$3545$$

$$205$$

$$3.8486$$

$$\lambda = \frac{1}{2}$$

$$+ 0.90103.5$$

$$1.50515$$

$$-2.6972$$

$$38080$$

$$0080$$

$$-1.50515$$

$$-1.9243$$

$$-3.4245$$

$$\lambda = 2:$$

$$0.102$$

$$0.3920$$

$$2.466$$

$$\lambda_{\text{max}} = 1.735$$

$$0.7705$$

$$5895$$

$$0.23930$$

$$-1.1965$$

$$-2.2182$$

$$-3.4147$$

$$1.735.12$$

$$347$$

$$2082$$

$$4164$$

$$6098$$

$$0.7852$$



$$\lambda = 3$$

$$\begin{array}{r} -1.2829 \\ \hline -2.3856 \\ \hline -3.6685 \end{array}$$

$$477.2$$

$$0.5315$$

$$3.400$$

$$\lambda = 4$$

$$\begin{array}{r} 0.96215 \\ 3.0103 \\ \hline -3.97245 \\ \hline 0.2275 \end{array}$$

$$1.688$$

$$\begin{array}{r} 0.157 \\ \hline 3.14 \\ \hline 3.7 \end{array}$$

$$\theta = \begin{array}{r} 11440 \\ 720 \\ \hline 2160 \\ 273 \\ \hline 1887 \end{array}$$

$$\frac{\beta}{\theta} = \begin{array}{r} 1.28287 \\ 2.5657 \end{array}$$

$$\lambda = 1$$

$$\gamma J = -2.5657$$

$$\lambda = 2$$

$$\gamma J = -1.28285$$

$$\lambda = 0.5$$

$$\begin{array}{r} -5.1314 \\ +1.5052 \end{array}$$

$$\begin{array}{r} 1.50515 \\ -2.7880 \end{array}$$

$$\begin{array}{r} -3.6262 \\ 0.5738 \end{array}$$

$$2.582$$

$$\lambda = 3$$

$$\begin{array}{r} 0.8552 \\ 2.3856 \\ \hline 3.2408 \\ 0.9592 \\ \hline 0.7103 \end{array}$$

$$\lambda = 4$$

$$\begin{array}{r} 0.6414 \\ 3.0103 \\ \hline 3.6517 \\ 0.5483 \end{array}$$

$$3.748$$

$$3.534$$

$$3^4 = 81$$

$$\theta = \begin{array}{r} 720 \\ 273 \end{array}$$

$$\frac{\beta}{\theta} = 7.7572$$

$$\lambda_{max} = 3.47$$

$$\lambda = 3: \begin{array}{r} -2.7856 \\ -2.5857 \\ \hline -4.9713 \end{array}$$

$$0.0287-1$$

$$0.1068$$

$$185$$

$$\lambda_{max} = 1.157 \begin{array}{r} 0.40929 \\ 0.06337 \\ \hline 0.34588 \end{array}$$

$$\begin{array}{r} 0.06333.5 \\ +0.31665 \end{array}$$

$$\begin{array}{r} -2.2176 \\ -0.2166 \\ \hline -2.4342 \end{array}$$

$$1.6658$$

$$4.632$$

$$\theta = 1440 \cdot \frac{5}{4}$$

$$\frac{7200}{1800}$$

$$277$$

$$1527$$

~~25657~~

$$38486 \cdot \frac{4}{5}$$

~~32~~

$$153944$$

$$\lambda = 1 \quad \begin{array}{l} 3'07888 \\ 0'1211 \end{array}$$

$$13'22$$

$$\lambda = 2$$

$$1'53944$$

$$1'50515$$

$$-3'0446$$

$$0'1554$$

$$1430$$

$$\lambda = \frac{1}{2}$$

$$-6'15776$$

$$+1'50515$$

$$-4'65261$$

$$0'5474$$

$$0'353$$

$$\lambda = \frac{1}{2}$$

$$1'735 \cdot \frac{4}{5}$$

$$0'347$$

$$1'388$$

~~48820~~

$$0'14239$$

$$0'34601$$

$$\lambda = 3$$

$$-1'02629$$

$$2'3856$$

$$-3'4119$$

$$0'7881$$

$$6'139$$

$$388 \cdot 24$$

$$776$$

$$1552$$

$$931$$

$$221825$$

$$0'71195$$

$$2'9902$$

$$0'2698$$

$$1861$$



$$\rho \left( \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) = \gamma \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) u + \frac{1}{3} \gamma \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) - \frac{\partial p}{\partial x}$$

$$u = f(r, \varphi) = f(r, \varphi)$$

$$v = f(r, \varphi) \sin \varphi = f(r, \varphi) \sin \varphi$$

$$w = f(r, \varphi) \cos \varphi = f(r, \varphi) \cos \varphi$$

$$x = r \cos \varphi$$

$$u = f(r, \varphi)$$

$$f, v = f(r, \varphi)$$

$$y = r \sin \varphi$$

$$v = f(r, \varphi) \sin \varphi$$

$$z$$

$$w = f(r, \varphi) \cos \varphi$$

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \varphi}{\partial x} \frac{\partial}{\partial \varphi} = \cos \varphi \frac{\partial}{\partial r} - \frac{\sin \varphi}{r} \frac{\partial}{\partial \varphi}$$

$$\frac{\partial}{\partial x} = \frac{\partial r}{\partial x} \frac{\partial}{\partial r} + \frac{\partial \varphi}{\partial x} \frac{\partial}{\partial \varphi} = \cos \varphi \frac{\partial}{\partial r} - \frac{\sin \varphi}{r} \frac{\partial}{\partial \varphi}$$

$$\frac{\partial}{\partial y} = \frac{\partial r}{\partial y} \frac{\partial}{\partial r} + \frac{\partial \varphi}{\partial y} \frac{\partial}{\partial \varphi} = \frac{\sin \varphi}{r} \frac{\partial}{\partial r} + \cos \varphi \frac{\partial}{\partial \varphi}$$

$$\begin{cases} \frac{\partial u}{\partial x} = \frac{\partial f}{\partial r} \cos \varphi - \frac{f}{r} \sin \varphi \\ \frac{\partial u}{\partial y} = \frac{\partial f}{\partial r} \sin \varphi + \frac{f}{r} \cos \varphi \\ \frac{\partial u}{\partial z} = \frac{\partial f}{\partial z} \end{cases} \quad \begin{cases} \frac{\partial v}{\partial x} = \left( \frac{\partial f}{\partial r} - \frac{f}{r} \right) \sin \varphi \cos \varphi \\ \frac{\partial v}{\partial y} = \frac{\partial f}{\partial r} \sin^2 \varphi + \frac{f}{r} \cos^2 \varphi \\ \frac{\partial v}{\partial z} = \frac{\partial f}{\partial z} \sin \varphi \end{cases}$$

$$\begin{cases} \frac{\partial w}{\partial x} = \frac{\partial f}{\partial r} \cos \varphi \\ \frac{\partial w}{\partial y} = \frac{\partial f}{\partial r} \sin \varphi \\ \frac{\partial w}{\partial z} = \frac{\partial f}{\partial z} \end{cases} \quad \begin{cases} \frac{\partial f}{\partial x} = \frac{\partial f}{\partial r} \cos \varphi \\ \frac{\partial f}{\partial y} = \frac{\partial f}{\partial r} \sin \varphi \\ \frac{\partial f}{\partial z} = \frac{\partial f}{\partial z} \end{cases}$$

$$\frac{\partial}{\partial x} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} + \frac{\partial w}{\partial x} = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial x} + \frac{\partial w}{\partial x}$$

$$\left[ \frac{\partial^2}{\partial r^2} + \frac{\partial^2}{\partial \varphi^2} + \frac{1}{r} \frac{\partial}{\partial r} - \frac{f}{r^2} \right] \cos \varphi = \nabla^2 u$$

$$\nabla^2 u = \frac{\partial^2 u}{\partial r^2} + \frac{\partial^2 u}{\partial \varphi^2} + \frac{1}{r} \frac{\partial u}{\partial r}$$

$$\frac{\partial}{\partial z} = \frac{\partial f}{\partial z} + \frac{1}{r} \frac{\partial f}{\partial r} + \frac{\partial^2 f}{\partial z^2}$$



$$\rho \left[ \frac{\partial \psi}{\partial t} \cos \psi + g \sin \psi \left( \frac{\partial \phi}{\partial r} \cos \psi + \frac{g}{r} \sin \psi \right) + g \sin \psi \left( \frac{\partial \phi}{\partial r} - \frac{g}{r} \right) \sin \psi + w \frac{\partial \psi}{\partial z} \right]$$

$$= \eta \left[ \frac{\partial \psi}{\partial t} + \frac{4}{3} \left( \frac{\partial \phi}{\partial r} + \frac{1}{2} \frac{\partial \phi}{\partial r} - \frac{g}{r} \right) + \frac{1}{3} \frac{\partial \psi}{\partial r \partial z} \right] - \frac{\partial \psi}{\partial r}$$

$$\left[ \frac{\partial \psi}{\partial t} + g \frac{\partial \psi}{\partial r} + w \frac{\partial \psi}{\partial z} \right] = \frac{\eta}{\rho} \left[ \frac{4}{3} \frac{\partial \phi}{\partial r} + \frac{\partial \psi}{\partial r} + \frac{1}{2} \frac{\partial \psi}{\partial r} + \frac{1}{3} \left( \frac{\partial \phi}{\partial r \partial z} + \frac{1}{2} \frac{\partial \phi}{\partial r} \right) \right] - \frac{1}{\rho} \frac{\partial \psi}{\partial r}$$

$$\left[ \frac{\partial \psi}{\partial t} + g \frac{\partial \psi}{\partial r} + w \frac{\partial \psi}{\partial z} \right] = \frac{\eta}{\rho} \left[ \frac{\partial \phi}{\partial r} + \frac{4}{3} \left( \frac{\partial \phi}{\partial r} + \frac{1}{2} \frac{\partial \phi}{\partial r} - \frac{g}{r} \right) + \frac{1}{3} \frac{\partial \psi}{\partial r \partial z} \right] - \frac{1}{\rho} \frac{\partial \psi}{\partial r}$$

Equation of motion with ~~cylindrical~~ <sup>radial</sup> symmetry (independent of  $\phi$ )

$$c \rho \frac{\partial \psi}{\partial t} = -\frac{2}{3} \mu \nabla^2 + \mu \left[ 2 \left( \frac{\partial u}{\partial r} \right)^2 + \left( \frac{\partial v}{\partial r} \right)^2 + \left( \frac{\partial w}{\partial r} + \frac{\partial v}{\partial z} \right)^2 + \left( \frac{\partial u}{\partial z} + \frac{\partial v}{\partial r} \right)^2 + \left( \frac{\partial u}{\partial r} + \frac{\partial v}{\partial z} \right)^2 \right]$$

$$- \mu \nabla^2 \psi$$

$$c \rho \left[ \frac{\partial \psi}{\partial t} + u \frac{\partial \psi}{\partial r} + v \frac{\partial \psi}{\partial r} + w \frac{\partial \psi}{\partial z} \right]$$

$$c \rho \left[ \frac{\partial \psi}{\partial t} + g \frac{\partial \psi}{\partial r} + w \frac{\partial \psi}{\partial z} \right] = -\mu \left[ \frac{\partial \psi}{\partial r} + \frac{g}{r} + \frac{\partial \psi}{\partial z} \right] - \frac{2}{3} \mu \left[ \frac{\partial \psi}{\partial r} + \frac{g}{r} + \frac{\partial \psi}{\partial z} \right]^2$$

$$+ \mu \left[ 2 \left( \frac{\partial \phi}{\partial r} \right)^2 \cos^2 \psi + 2 \frac{g}{r} \frac{\partial \phi}{\partial r} \cos \psi \sin \psi + \left( \frac{g}{r} \right)^2 \sin^2 \psi \right. \\ \left. + \left( \frac{\partial \psi}{\partial r} \right)^2 \right] \\ \sin^2 \psi + 2 \cos^2 \psi + \sin^2 \psi = 1 - 2 \sin^2 \psi \cos^2 \psi \\ = \left( \frac{\partial \phi}{\partial r} \right)^2 + \left( \frac{g}{r} \right)^2 - 2 \sin^2 \psi \cos^2 \psi \left[ \left( \frac{\partial \phi}{\partial r} \right)^2 + \left( \frac{g}{r} \right)^2 + 2 \frac{\partial \phi}{\partial r} \frac{g}{r} \right] \\ = \left( \frac{\partial \phi}{\partial r} + \frac{g}{r} \right)^2$$

$$+ \left( \frac{\partial \psi}{\partial r} + \frac{\partial \phi}{\partial r} \right)^2 \sin^2 \psi + \left( \frac{\partial \phi}{\partial r} + \frac{\partial \psi}{\partial r} \right)^2 \cos^2 \psi + \left( \frac{\partial \phi}{\partial r} - \frac{g}{r} \right)^2 \sin^2 \psi \cos^2 \psi$$

$$2 \left( \frac{\partial \psi}{\partial r} \right)^2 + 2 \left( \frac{g}{r} \right)^2 + 2 \left( \frac{\partial \phi}{\partial r} \right)^2 - 4 \sin^2 \psi \cos^2 \psi \left( \frac{\partial \phi}{\partial r} + \frac{g}{r} \right)^2 + \left( \frac{\partial \psi}{\partial r} \right)^2 + \left( \frac{\partial \phi}{\partial r} \right)^2 + 2 \frac{\partial \phi}{\partial r} \frac{\partial \psi}{\partial r} \\ + 4 \sin^2 \psi \cos^2 \psi \left( \frac{\partial \phi}{\partial r} - \frac{g}{r} \right)^2$$



$$\left[ \frac{c_p}{A} \left( \frac{\partial \theta}{\partial t} + v \frac{\partial \theta}{\partial z} + w \frac{\partial \theta}{\partial r} \right) \right] = -\rho \left[ \frac{\partial \theta}{\partial t} + \frac{v}{r} + \frac{\partial w}{\partial z} \right] + \mu \left[ -\frac{2}{3} \left( \frac{\partial v}{\partial r} + \frac{v}{r} + \frac{\partial w}{\partial z} \right)^2 + 2 \left[ \left( \frac{\partial v}{\partial z} \right)^2 + \left( \frac{\partial w}{\partial r} \right)^2 \right] + \left( \frac{\partial v}{\partial r} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 + 2 \frac{\partial v}{\partial z} \frac{\partial w}{\partial r} \right]$$

$$= \left( \frac{\partial v}{\partial z} + \frac{\partial w}{\partial r} \right)^2$$

Thermal equation in respect to motion with radial symmetry

Ex. Stationary flow in tube:

$$q=0 \quad w = \frac{p_1^2 - p_2^2}{8\mu p l} (R^2 - r^2) \quad p^2 = p_1^2 - \left( \frac{p_1^2 - p_2^2}{l} \right) z = \alpha$$

$$w = \frac{\alpha (R^2 - r^2)}{8\mu p}$$

With neglect of  $\mu \frac{\partial w}{\partial z}$

$$\frac{c_p}{A} w \frac{\partial \theta}{\partial z} = -\rho \frac{\partial w}{\partial z} + \mu \left( \frac{\partial w}{\partial r} \right)^2$$

$$\frac{\partial w}{\partial z} = -\frac{\alpha}{4\mu p}$$

$$\frac{c_p}{A} \frac{\partial \theta}{\partial z} \frac{\alpha (R^2 - r^2)}{8\mu p} = + \rho \frac{\alpha (R^2 - r^2)}{8\mu p^2} \frac{dp}{dz} + \mu \frac{\alpha^2 r^2}{16\mu^2 p^2}$$

$$= \frac{1}{8\mu p^2} \left[ -\frac{\alpha^2 (R^2 - r^2)}{2} + \mu \frac{\alpha^2 r^2}{2\mu} \right]$$

$$= \frac{1}{8\mu p^2} \cdot \frac{\alpha^2 (2r^2 - R^2)}{2}$$

$$\frac{c_p}{A} \frac{\partial \theta}{\partial z} = \frac{\alpha (2r^2 - R^2)}{2\mu p (R^2 - r^2)} = \frac{\alpha (2r^2 - R^2)}{2(R^2 - r^2)}$$

$$= \frac{\alpha}{2} \frac{1}{\sqrt{p_1^2 - \alpha z}} \left[ \frac{R^2}{R^2 - r^2} - 2 \right]$$

$$\frac{p}{\rho} = \alpha \theta$$

$$p = \frac{p_1}{\alpha \theta}$$

$$p^2 = \frac{p_1^2}{\alpha^2 \theta^2}$$

$$\frac{c_p}{A} \frac{\partial \theta}{\partial z} = \frac{\alpha (2r^2 - R^2)}{2\mu p (R^2 - r^2)} = \frac{\alpha}{2} \frac{1}{p_1^2 - \alpha z} \left[ \frac{R^2}{R^2 - r^2} - 2 \right]$$



$$\frac{c}{R^2} \int 2p r w \theta dr = \frac{2}{R^2} \int w p \theta r dr = \frac{2}{R^2} \int_0^R \frac{p_1^2 - p_1^2}{\rho_{\text{fuel}}} (R^2 - r^2) r dr = \frac{R^2 (p_1^2 - p_1^2)}{16 \rho_{\text{fuel}}} = \frac{\rho \theta r^2 p_1^2}{16 \rho_{\text{fuel}} r}$$

$$\frac{c \log \theta}{A \theta} = \frac{-1}{2} \log(p_1^2 - a r^2) \left[ \frac{R^2}{R^2 - r^2} - 2 \right] + \text{const}$$

$$\frac{c \log \theta}{A \theta} = -\frac{1}{2} \log p_1^2 \quad [ \quad ] + \text{---}$$

making for a!  
degrees were for m = 1/2  
was unimportant; b) or c

just p w = p p / c \theta  
constant

$$\frac{c \alpha}{A} [\theta^2 - \theta_0^2] = \log \frac{p_1^2}{p_1^2 - a r^2} \left[ \frac{R^2}{R^2 - r^2} - 2 \right]$$

$$\frac{c}{\alpha A} \log \frac{\theta}{\theta_0} = \frac{1}{2} \log \frac{p_1^2}{p_1^2 - a r^2} \left[ \frac{R^2}{R^2 - r^2} - 2 \right]$$

z = l:

$$\theta = \theta_0 \left[ \frac{p_1}{p_2} \right]$$

$$\frac{2r^2 - R^2}{R^2 - r^2} \cdot \frac{\alpha A}{c}$$

$$\theta = \theta_0 \left[ \frac{p_1^2}{p_1^2 - a r^2} \right]^{\frac{1}{2} \frac{\alpha A}{c} \frac{2r^2 - R^2}{R^2 - r^2}} = \theta_0 \left[ 1 - \frac{a r^2}{p_1^2} \right]^{\frac{1}{2} \frac{\alpha A}{c} \frac{2r^2 - R^2}{R^2 - r^2}}$$

r = 0:

$$\theta = \theta_0 \left( \frac{p_1}{p_2} \right)^{-\frac{\alpha A}{c}}$$

$$\int \left( \frac{R^2}{R^2 - r^2} - 2 \right) r dr = R^2 \log(R^2 - r^2)$$

r = R:

$$\theta = \theta_0 \infty$$

With taking into account the condition of heat:

$$\frac{c p}{A} \frac{\partial \theta}{\partial z} \frac{a(R^2 - r^2)}{\rho_{\text{fuel}} r} = \frac{1}{\rho_{\text{fuel}} r^2} \frac{a^2 (2r^2 - R^2)}{2} + \kappa \left[ \frac{\partial \theta}{\partial r^2} + \frac{1}{r} \frac{\partial \theta}{\partial r} \right]$$

$$\frac{c}{\alpha A} \frac{1}{\theta} \frac{\partial \theta}{\partial z} \frac{a(R^2 - r^2)}{\rho_{\text{fuel}}} = \frac{1}{\rho_{\text{fuel}} (p_1^2 - a r^2)} \frac{a^2 (2r^2 - R^2)}{2} + \kappa \nearrow$$



$$\theta = b_0 + b_1 z + (\cancel{b_2} + b_3 z) r^2$$

$$\frac{\partial \theta}{\partial z} = b_1 + b_3 r^2$$

$$r \frac{\partial \theta}{\partial r} = 2 r^2 (b_2 + b_3 z)$$

$$\frac{1}{2} \frac{\partial}{\partial r} ( ) = 4 \kappa (b_2 + b_3 z)$$

$$\frac{c}{\alpha A} \alpha (R^2 - r^2) (b_1 + b_3 r^2) (p_1^2 - \alpha z) = a^2 \left( r^2 - \frac{R^2}{2} \right) (b_0 + b_1 z + b_2 r^2 + b_3 z r^2) + 4 \kappa (b_2 + b_3 z) (b_0 + b_1 z + b_2 r^2 + b_3 z r^2) (p_1^2 - \alpha z)$$

$$\frac{c}{\alpha A} a R^2 b_1 p_1^2 = -a^2 \frac{R^2}{2} b_0 + 4 \kappa p_1^2 b_0 b_2$$

$$\frac{c}{\alpha A} a (R^2 b_3 - b_1) p_1^2 = a^2 \left( b_0 - \frac{R^2}{2} b_2 \right) + 4 \kappa b_2^2 p_1^2$$

$$-\frac{c}{\alpha A} a^2 R^2 b_1 = a^2 \left( \cancel{b_0} - \frac{R^2}{2} \right) b_1 + 4 \kappa \left[ (b_0 b_3 + b_1 b_2) p_1^2 - a b_0 b_2 \right]$$

$$+\frac{c}{\alpha A} a^2 (b_1 - R^2 b_3) = a^2 \left( b_1 - \frac{R^2}{2} b_3 \right) + 4 \kappa \left[ 2 b_2 b_3 p_1^2 - a b_2^2 \right]$$

$$0 = a^2 \left[ \cancel{b_0} - \frac{R^2}{2} (p_1^2 + a b_0) \right] + 4 \kappa p_1^2 (b_0 b_3 + b_1 b_2)$$

$$0 = a^2 \left[ b_1 p_1^2 + b_0 - \frac{R^2}{2} (b_3 p_1^2 + b_2) \right] + 8 \kappa b_2 b_3 p_1^4$$

$$1 + \frac{\alpha A a}{2 c p_1^2} \frac{2 r^2 - R^2}{R^2 - r^2} z -$$

$$= \frac{R^2}{R^2 - r^2} - 2 = \frac{1}{1 - \frac{r^2}{R^2}} - 2 = 1 + \frac{r^2}{R^2} + \frac{r^4}{R^4} \dots - 2 = -1 + \frac{r^2}{R^2} + \frac{r^4}{R^4}$$

$$= 1 - \frac{1}{2} \frac{a^2}{p_1^2} z + \frac{1}{2} \frac{a^2}{p_1^2 R^2} z r^2 + \frac{\partial \theta}{\partial z} = \frac{\partial \theta}{\partial z} + \frac{\partial}{\partial z} \left[ \frac{\alpha A a}{2 c p_1^2} \frac{2 r^2 - R^2}{R^2 - r^2} \left[ 1 - \frac{a z}{p_1^2} \right] \right] - \frac{2 \alpha a \kappa a r}{c R^2 r^2}$$

$$\frac{\partial \theta}{\partial z} = -\frac{a}{p_1^2} \frac{1}{1 - \frac{a z}{p_1^2}} = \frac{-a}{p_1^2 - a z}$$

$$-\frac{a}{p_1^2 - a z} \frac{c}{\alpha A} \frac{\alpha (R^2 - r^2)}{p_1^2} = x$$



$$\gamma \left( \frac{\partial^2 w}{\partial r^2} + \frac{1}{2} \frac{\partial w}{\partial r} \right) = \frac{\partial \mu}{\partial r}$$

$$\frac{\partial}{\partial r}(\rho w) = 0$$

$$+ b_{11} r^2$$

$$\theta = b_0 + b_1 r + b_2 r^2 + b_3 r^3 + b_4 r^4 + b_5 r^5 + \dots$$

$$\frac{2c}{\alpha A} a(R^2 - r^2)(r_1^2 - a^2) \frac{\partial \theta}{\partial r} = a^2(2r^2 - R^2) \theta + ~~16\mu k~~ 16\mu k (r_1^2 - a^2) \frac{\theta}{2} \frac{\partial}{\partial r} \left( r \frac{\partial \theta}{\partial r} \right)$$

$$2 \frac{\partial \theta}{\partial r} = 2b_1 + 2b_2 r + 4b_3 r^2 + 4b_4 r^3 + 4b_5 r^4$$

$$\frac{\partial}{\partial r}(\ ) = 4b_2 + 4b_3 r + 16b_4 r^2 + 16b_5 r^3$$

$$\begin{aligned} & \frac{2c}{\alpha A} a(R^2 - r^2)(r_1^2 - a^2) (b_1 + b_2 r + 2b_3 r^2 + b_4 r^3 + 2b_5 r^4) = \\ & = a^2(2r^2 - R^2) (b_0 + b_1 r + b_2 r^2 + b_3 r^3 + b_4 r^4 + b_5 r^5) + \\ & + ~~16\mu k~~ 16\mu k (r_1^2 - a^2) (b_0 + b_1 r + b_2 r^2 + b_3 r^3 + b_4 r^4 + b_5 r^5) (b_2 + b_3 r + 4b_4 r^2 + 4b_5 r^3) \end{aligned}$$

$$1) \beta R^2 r_1^2 b_1 = -a^2 R^2 b_0$$

$$- \beta R^2 a b_1 = -a^2 R^2 b_1 + 16\mu k r_1^2 b_0 b_2$$

$$2) -\beta r_1^2 b_1 + \beta R^2 r_1^2 b_2 = 2a^2 b_0$$

$$2r^2)$$

$$2\beta R^2 r_1^2 b_3 - \beta R^2 a b_2 + \beta ~~a~~ a b_1 = -a^2 R^2 b_2 + 2a^2 b_1$$



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$$\text{I II: } \beta R^2 \rho_1^2 b_2 = a^2 b_0 = -\rho_1^2 \rho b_1$$

$$b_1 = -\frac{a^2 b_0}{\rho \rho_1^2}$$

$$\text{II. } \frac{2}{3} \rho_1^2 b_{11} = \rho a b_1 - a^2 b_1 + 6 \gamma \mu \kappa \rho_1^2 \frac{b_0 b_2}{R^2}$$

$$b_2 = \frac{a^2 b_0}{\rho \rho_1^2 R^2}$$

$$\begin{aligned} b_{11} &= b_1 \left[ \frac{a}{2 \rho_1^2} - \frac{a^2}{2 \rho \rho_1^2} \right] \\ &= \frac{-a^3 b_0}{2 \rho_1^2 \rho \rho_1^2} \left( 1 - \frac{a}{\rho} \right) \end{aligned}$$

$$\left[1 - 2\alpha + \frac{17}{16}\alpha^2\right]^{-1} = 1 + 2\alpha - \frac{17}{16}\alpha^2 + 4\alpha^2 \dots$$

$$\frac{1}{1-x} = 1 + x + x^2 + \dots$$

Dieterich-Kopp 15:

$$\frac{v}{v_x} = e^{\frac{h^2}{2m_x^2}} = e^{\frac{m_x^2}{3}} = e^{\frac{m_x^2}{RT}}$$

$$\frac{m \sigma^2}{2} \left[ n \log n \right]$$

$$= LK \text{ of } \text{of } \int^2$$

$$\psi_f = \frac{2m a}{v_f}$$

$$\frac{RT}{2a} \ln \frac{v_o}{v_i} = \frac{1}{2} \frac{m v_f^2}{v_f}$$

$$B = RT \ln \frac{v_e}{v_i}$$

$$L = \frac{RT}{2}$$

$$\gamma \frac{v_o(t-b)}{v_o - b} = \gamma \frac{v_o}{v_i} \cdot \frac{1 - \frac{b}{v_o}}{1 - \frac{b}{v_i}}$$

$$= \gamma_j \frac{v_a}{v_i} + \gamma_j (1 - \frac{b}{v_a}) - \gamma_j (1 - \frac{b}{v_i})$$

$$= \gamma \frac{v_o}{v_i} - \frac{b}{v_a} + \frac{b}{v_i} - \frac{b^2}{v_a^2} + \frac{b^2}{v_i^2}$$

$$= \gamma \frac{v_o}{v_i} - b \left( \frac{1}{v_o} - \frac{1}{v_i} \right) - b^2 \left( \frac{1}{v_o^2} - \frac{1}{v_i^2} \right)$$

$$\begin{aligned} \text{(ii)} \quad a \left( \frac{1}{v_f} - \frac{1}{v_g} \right) &= nT \left[ \gamma \frac{v_g - b}{v_f - b} - \left( \frac{v_g}{v_g - b} - \frac{v_f}{v_f - b} \right) \right] \\ &= nT \left[ \gamma \frac{v_0}{v_i} - b \left( \frac{1}{v_g} - \frac{1}{v_f} \right) - b \left( \frac{1}{v_g} - \frac{1}{v_f} \right) + b \left( \frac{1}{v_g} - \frac{1}{v_f} \right) - b \left( \frac{1}{v_g} - \frac{1}{v_f} \right) \right] \\ &= \gamma (v_f - v_g) \end{aligned}$$



Oldtimers (78)

$$\frac{v_f}{v_f - b} = 1 + \frac{b}{v_f - b}$$

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$$p(v_g - v_f) = nT \left[ \gamma \frac{v_f - b}{v_f - b} + a \left( \frac{1}{v_g} - \frac{1}{v_f} \right) \right]$$

$$p = \frac{nT}{v - b} - \frac{a}{v^2} = \frac{b}{v_f - b} - \frac{b}{v_f - b}$$

$$nT \left[ \frac{-v_f}{v_g - b} + \frac{v_f}{v_f - b} + \gamma \frac{v_f - b}{v_f - b} \right] = 2a \left( \frac{1}{v_g} - \frac{1}{v_f} \right)$$

not identical with  
Helmholtz equation

$$= \gamma \frac{v_f}{v_f} - 2b \left( \frac{1}{v_g} - \frac{1}{v_f} \right) - 2b^2 \left( \frac{1}{v_g} - \frac{1}{v_f} \right)$$

$$W = \frac{1}{2} \sum p_{ij} u_{ij}$$

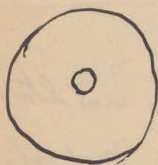
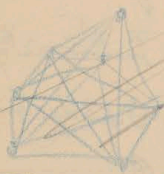
$$\delta W = p u$$

$$4\pi \left[ R^2 M a a - \sqrt[3]{R^3 - r^3} \right]^2$$

$$= 4\pi R^2 \left[ 1 - \left( 1 - \left( \frac{r}{R} \right)^3 \right)^{\frac{2}{3}} \right]$$

$$= 4\pi R^2 \left( 1 - 1 + \frac{2}{3} \left( \frac{r}{R} \right)^3 \right)$$

$$= \frac{8\pi}{3} \frac{r^3}{R} = \frac{2r}{R}$$



$$\begin{aligned} & \gamma \frac{v_g}{v_f} \frac{1 - \frac{b}{v_g}}{1 - \frac{b}{v_f}} \\ & \gamma \frac{v_g}{v_f} \left( -\frac{b}{v_g} - \frac{b^2}{v_g^2} + \frac{b}{v_f} + \frac{b^2}{v_f^2} \right) \\ & + \gamma \frac{b}{v_f} + \frac{b^2}{v_f^2} \\ & - \gamma \frac{b}{v_g} - \frac{b^2}{v_g^2} \end{aligned}$$

$$= \gamma \frac{v_g}{v_f} + 2b \left( \frac{1}{v_f} - \frac{1}{v_g} \right) - 2b^2 \left( \frac{1}{v_g} - \frac{1}{v_f} \right)$$

$m_1$   
 $m_2$   
 $m_3$   
 $m_4$   
 $m_5$

$$\begin{aligned}
 W = & m_1 m_2 x_{12} + m_1 m_3 x_{13} + m_1 m_4 x_{14} + m_1 m_5 x_{15} \\
 & + m_2 m_3 x_{23} + m_2 m_4 x_{24} + \\
 & + m_3 m_4 x_{34} + \\
 & + m_4 m_5 x_{45} + \\
 & + m_5 m_6 x_{56} + \dots
 \end{aligned}$$

$$= \frac{1}{2} \sum m_i m_k x_{ik}$$

$$= \frac{1}{2} \sum m_i \sum m_k x_{ik}$$

$$= \frac{1}{2} \int_0^{\infty} \frac{1}{M} \int_0^{\infty} \rho(r) \rho(r') x(r, r') dr dr' = 2 \pi M \rho \int_0^{\infty} r^2 \chi(r) dr$$

$\Sigma$ , könnte also je e. Fall,  $\Sigma$ ,  $m = \frac{nB}{2}$  da  $B = \sqrt{2} \cdot 1$   $\rho_{max}$   
 $\rho_{max}$ ,  $\rho < \rho_{max}$  für  $B / \sqrt{2} \rho_{max}$ ,  $\rho < \rho_{max}$ ; da  $B$  ist  $1/\sqrt{2} \rho_{max}$   
 $1/\rho < \rho < \rho_{max}$   $\sim \frac{1}{\rho_{max}}$   $\rho_{max}$ .  $\rho = \frac{1}{2} \sum m_k$  1. in Summand fort  
 2.  $\rho$  wird bei der Integration

Teilchen klein und diese beiden Werten unabhängig  $= B$

also in Summe Arbeit  $\Sigma W = B$

Wenn man aber den entstehenden Balken wieder verschwindet so wird letzter  
 Arbeit  $= \frac{1}{2} B$  wieder gewonnen; also wirklich immer  $\frac{1}{2} B$  für 1 Teilchen  $= \frac{B}{2}$ !



$$dN = A e^{-h(U+L)} du dv dw \dots dx dy dz$$

$$= A e^{-h(U+L_a+L_i)} dw_a dw_i dv$$

$$N_u = A e^{-\frac{hU}{v}} \int e^{L_a+L_i} dw_a dw_i = B e^{-\frac{hU}{v}}$$

$$= N_{gr} e^{-\frac{hU}{v}}$$

$$\frac{\rho_f}{\rho_g} = e^{-\frac{hU}{v}} = e^{-h \int \left( \frac{mc^2}{3\pi(d-2r)^3} \right)}$$

~~$$b = \frac{4}{3} \pi r^3$$~~

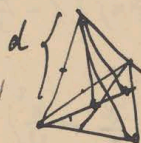
$$\frac{4}{3} \pi r^3 = b$$

$$2r = \sqrt[3]{\frac{3b}{2\pi}}$$

$$\rho = \frac{mc^2}{3\pi(\sqrt[3]{v} - \sqrt[3]{\frac{3b}{2\pi}})^3}$$

~~$$d^3 = v$$~~

~~$$d = \sqrt[3]{v}$$~~



$$h = \sqrt{d^2 - \left(\frac{1}{3} \frac{d}{\sqrt{3}}\right)^2}$$

$$= d \sqrt{1 - \frac{1}{3}} = d \sqrt{\frac{2}{3}}$$

$d \perp \sqrt{3}$

$$\rho = \frac{mc^2}{3\pi v \left(1 - \sqrt[3]{\frac{3b}{2\pi v}}\right)^3}$$

~~$$d \neq \sqrt[3]{v}$$~~

$$\frac{4}{3} \pi r^3 = b_1$$

$$r = \sqrt[3]{\frac{3b_1}{4\pi}}$$

$$\rho = \frac{mc^2}{3\pi(\sqrt[3]{v} - \sqrt[3]{\frac{6b_1}{\pi}})^3}$$

~~$$\frac{d}{2} \cdot \frac{d}{2} \sqrt{3} \cdot d \sqrt{\frac{2}{3}} = \frac{d^3}{\sqrt{2}} = v$$~~

$$d = \sqrt[3]{v \sqrt{2}}$$

$$\sqrt{2} = \frac{3b}{2\pi v}$$

$$\frac{b}{v} = \frac{\pi \sqrt{8}}{3}$$

$$\rho = \frac{mc^2}{3\pi(\sqrt[3]{v \sqrt{2}} - \sqrt[3]{\frac{6b_1}{\pi}})^3} = \frac{mc^2}{\left(\sqrt[3]{3\sqrt{2}\pi v} - \sqrt[3]{18b_1}\right)^3} = \frac{mc^2}{3\pi \sqrt{2} \cdot v \left[1 - \sqrt[3]{\frac{b_1}{\pi \sqrt{2} v}}\right]^3}$$

$$\frac{6 b_1}{2 \sqrt{2}} = \beta$$

$$p = \frac{n m v}{3 n \sqrt{2} \cdot v \left(1 - \sqrt[3]{\frac{\phi}{v}}\right)^3}$$

$$\left[\frac{\phi}{v}\right]^{\frac{1}{3}} = \left[1 - \frac{v-\phi}{v}\right]^{\frac{1}{3}} = 1 - \frac{v-\phi}{3v}$$

$$p = \frac{n m c^2}{3 n \sqrt{2} \cdot v \left(\frac{v-\phi}{3v}\right)^3} = \frac{n m c^2}{3 n \sqrt{2}} \frac{9 v^4}{(v-\phi)^3} = n m c^2 \frac{3}{2} \frac{\beta}{b_1} \frac{v^2}{(v-\phi)^3}$$

$$p v = n m c^2 \cdot \frac{9}{2 \sqrt{2}} \frac{1}{\left(1 - \frac{\phi}{v}\right)^3} = \frac{9}{2 \sqrt{2}} \frac{n m c^2}{\sqrt{2}} \left[1 + 3 \frac{\phi}{v}\right]$$

$$\frac{1 + \frac{2}{3}x}{1 - \frac{x}{3}} = \left(1 + \frac{2}{3}x\right) \left(1 - \frac{x}{3}\right)^{-1} =$$

$$= \left(1 + \frac{2x}{3}\right) \left(1 + \frac{x}{3} + \frac{x^2}{9} + \frac{x^3}{27}\right)$$

$$= 1 + x + \frac{x^2}{3} + \frac{x^3}{9}$$



$$W_i = \sum \sum \frac{r_{12}}{r_{12}^2} \frac{f_{12}}{r_{12}} = \frac{1}{t} \int_0^t \sum \sum r_{12} f_{12} dt$$

$$= m \phi \sum \gamma$$

$$= m \phi N \cdot \bar{\gamma}$$

$$N = \frac{e}{\lambda} n$$

$$= m \phi \bar{e} \bar{\gamma} n$$

$$= \frac{6}{\lambda} \frac{m \bar{e}^2}{2} \frac{2\sqrt{2}}{3}$$

$$2L = 3\mu V - \frac{2\sqrt{2}}{3} \frac{6}{\lambda} L - W_i''$$

$$L \left[ 1 + \frac{\sqrt{2}}{3} \frac{6}{\lambda} \right] = \frac{3}{2} \mu V - \frac{1}{2} W_i''$$

$$L \left[ 1 + \left( 1 + \frac{56}{3\sqrt{2}} \right) \frac{2n\phi^3 n}{3V} \right]$$

$$\frac{m \bar{e}^2}{2}$$

$$\bar{e}^2 = 3nT$$

$$nT \left[ 1 + \frac{\sqrt{2}}{3} \frac{6}{\lambda} \right] = \mu v + \underbrace{\frac{1}{3} \frac{W_i''}{nm}}_{\frac{a}{v}}$$

$$\mu + \frac{a}{v} = \frac{nT}{v} \left[ 1 + \frac{\sqrt{2}}{3} \frac{6}{\lambda} \right]$$

$$\frac{V}{nm} = v \parallel \frac{2n\phi^3}{3\mu m} = b$$

$$\frac{b}{v} = \frac{2n\phi^3 n}{3V}$$

$$W_i'' = 3\rho^2 V$$

Nach Jern für Plücker und nach Lutharand für gute Körper

$$\lambda = d - b$$

Somit

$$\mu + \frac{a}{v} = \frac{rT}{v} \left[ 1 + \frac{\sqrt{2}}{3} \frac{b}{d-b} \right]$$

$$\frac{d}{b} = \sqrt[3]{\frac{v}{v_0}}$$

$$= \frac{rT}{v} \left[ 1 + \frac{\sqrt{2}}{3} \frac{1}{\sqrt[3]{\frac{v}{v_0}} - 1} \right]$$

$$\sqrt[3]{\frac{v}{v_0}} = \left[ 1 + \frac{v-v_0}{v_0} \right]^{\frac{1}{3}} = 1 + \frac{1}{3} \frac{v-v_0}{v_0}$$

$$= \frac{rT}{v} \left[ 1 + \frac{\sqrt{2}}{3} \frac{1}{\frac{1}{3} \frac{v-v_0}{v_0}} \right] = \frac{rT}{v} \left[ \frac{v-v_0 + v_0 \sqrt{2}}{v-v_0} \right]$$

$$= \frac{rT}{v} \frac{v_0 \sqrt{2}}{v-v_0} = \frac{rT \sqrt{2}}{v-v_0}$$

$$\mu + \frac{a}{v} = \frac{rT}{v} + \frac{a}{v} - \frac{a}{v} = \frac{rT}{v}$$

$$\frac{a}{v} - \frac{a}{v_0} = rT \sqrt{2}$$

$$\frac{dv}{dt} \left[ \frac{a}{v^2} + \frac{2a}{v^3} \right] = -rT \sqrt{2}$$

mit:  $\frac{a}{v_0} (v-v_0) = rT \sqrt{2}$

$$\frac{a}{v_0} \frac{dv}{dt} = rT \sqrt{2}$$

$$\alpha = \frac{1}{3} \frac{1}{v} \frac{dv}{dt} = \frac{v_0 (rT \sqrt{2} T)}{3 a T}$$

$$= \frac{v-v_0}{3 v_0 T} = \frac{rT \sqrt{2}}{3} \frac{v_0}{a} = \frac{rT \sqrt{2}}{3 a}$$

$$v-v_0 \neq rT \sqrt{2} \frac{v_0}{a}$$



$$dp + \frac{2a}{v^3} dv = -\frac{RT\sqrt{2}}{(v-v_0)^2} dv$$

$$k = \frac{1}{v} \frac{dv}{dp} \quad k = v \frac{dp}{dv}$$

$$v \frac{dp}{dv} = \frac{2a}{v^2} - \frac{RT\sqrt{2}}{(v-v_0)^2} v = \frac{2a}{v^2} - \frac{av}{v_0^2(v-v_0)} = a \frac{2vv_0^2 - 2v_0^3 - v^3}{v_0^2 v^2 (v-v_0)}$$

$$= -\frac{a}{v_0(v-v_0)} = \frac{a^2}{RT v_0^3 T}$$

$$k = \frac{v_0(v-v_0)}{a} = RT\sqrt{2} \frac{v_0^3}{a^2}$$

$$\frac{k}{a} = \frac{v-v_0}{v} \frac{3}{\sqrt{2}} \neq \frac{2(v-v_0)}{v} = \frac{3}{\sqrt{2}} T\sqrt{2} \frac{v_0^3}{a} = \frac{3}{\sqrt{2}} \frac{T\sqrt{2}}{\rho_0^2} \frac{1}{a}$$

$$a = \frac{RT}{\rho} \frac{\sqrt{2}}{3} \frac{1}{a}$$

$$k = \frac{RT\sqrt{2}}{\rho^3} \frac{\rho^2}{v} \frac{1}{2} \alpha^2 = \frac{1}{2} \frac{RT\sqrt{2}}{\rho^2 \alpha} \alpha^2$$

$$k = \frac{2}{9} \frac{\rho RT}{\sqrt{2} T \alpha^2} = \frac{\sqrt{2}}{9} \frac{RT}{T} \cdot \frac{\rho}{\alpha^2}$$

$$= \frac{\sqrt{2}}{9} \frac{R}{T} \frac{\rho}{\mu \alpha^2}$$

$$v = \frac{R}{\mu}$$

$$= \frac{1}{\mu} \frac{RT}{T} = \frac{1}{\mu} \frac{R}{\rho T} = \frac{1}{\mu}$$

$$\frac{1000}{96.136 \cdot 980} = \frac{1}{0.00129 \cdot 273}$$

$$\mu = \frac{\text{atm} \cdot \text{cm}^3}{14.5}$$

$$\frac{\sqrt{2} R}{\rho T} = \frac{\sqrt{2}}{9} \frac{980.000}{(273)^2 \cdot 0.00129}$$

$$\begin{array}{r} 24362 \\ 48724 \\ 01106 - 3 \\ 09542 \\ \hline 29372 \end{array}$$

$$\begin{array}{r} 0.20103 \\ 0.1505 \\ 5.9912 \\ \hline 6.1417 \\ 2.9372 \\ \hline 3.2045 \end{array}$$

$$\gamma_c = \frac{6.42 \cdot 10^6}{\mu} \cdot 252$$

$$\frac{R}{\mu} = \frac{10^6 \cdot 14.5}{(273)^2 \cdot 0.0013} \cdot \frac{14.5}{273 \cdot 0.0013} =$$

$$G_n = \frac{p}{\mu a^2} \quad \frac{8.8 \cdot 145}{65.3 \cdot [168 \cdot 10^9]^2} = \frac{145}{\alpha \cdot \frac{\alpha A}{2}} = \frac{145 \cdot 10^{15}}{168 \cdot 10^9 \cdot 121 \cdot 10^9}$$

$$\begin{array}{r} 3.2045 \\ 1.1614 \\ \hline 4.3659 \end{array}$$

$$\begin{array}{r} 19.3659 \\ - 4.3081 \\ \hline 15.0578 \end{array}$$

$$\begin{array}{r} 2.2253 \\ 1.0828 \\ \hline 3.3081 \end{array}$$

$$1150 \cdot 10^{12}$$

Die Dyeen Flokyphten haben nur sehr unbedeutende Werte, während die Werte für die Flokyphten sehr groß sind. Was?

$$m \frac{d^2 x}{dt^2} = -kx$$

$$x = a \sin \sqrt{\frac{k}{m}} t$$

$$m \frac{a^2 k}{m} = C \quad a = \sqrt{\frac{2C}{k}}$$

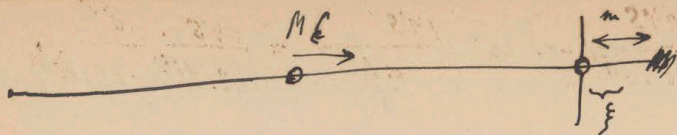
a ist Wert für das Schwingungs Volumen

Derby L k dasselbe

also dass auch Schwing. Vol. dasselbe wenn Kropf, der welche auf d. Rohrer wirkt, dasselbe ist

$$m \frac{a^2 k}{m} = C \quad a = \sqrt{\frac{2C}{k}}$$





$$\xi = A \sin \omega t$$

$$\xi|_0 = a \alpha = v$$

$$\overline{M c^2} = \overline{m c^2}$$

$$\frac{\overline{M c^2} + \overline{m c^2}}{2} + \overline{V} = \frac{M c^2}{2}$$

$$\overline{V} = \frac{\overline{m c^2}}{2}$$

$$\frac{c^2}{h} = \frac{1}{3} c^2$$

$$M = 2m$$

$$\left. \begin{aligned} M v^2 + m v^2 &= M V_0^2 + m v_0^2 \\ M V + m v &= M V_0 + m v_0 \end{aligned} \right\} \begin{aligned} M (V^2 - V_0^2) &= m (v_0^2 - v^2) \\ M (V - V_0) &= m (v_0 - v) \end{aligned}$$

$$V - v = -V_0 + v_0 \quad | \cdot m - M \quad V + V_0 = v + v_0$$

$$V = \frac{M - m}{M + m} V_0 + \frac{2m}{M + m} v_0 = \frac{V_0 + 2v_0}{3}$$

$$v = \frac{2m}{M + m} V_0 + \frac{M - m}{M + m} v_0 = \frac{-v_0 + 4V_0}{3}$$

$$p + \frac{a}{v(v-b)} = \frac{RT}{v-b}$$

$$p = \frac{RT}{v-b} \left[ 1 - \frac{a}{v(v-b)} \right]$$

$$\frac{\partial p}{\partial v} = -\frac{RT}{(v-b)^2} + \frac{a(2v-b)}{v^2(v-b)^2} = 0$$

$$\frac{\partial p}{\partial v} = \left[ -RT + \frac{a(2v-b)}{v^2} \right] = 0$$

$$2v^2 - 2v(2v-b) = 0$$

$$2vb = 2v^2$$

$$v = b$$

$$p = \frac{RT}{v-b} e^{-\frac{C}{Rv}} = \frac{RT}{v-b} \left[ 1 - \frac{C}{Rv} + \frac{1}{2} \frac{C^2}{R^2 v^2} - \dots \right]$$

$$p = \frac{RT}{v-b} - \frac{C}{v(v-b)} + \dots$$

$$p = \frac{RT}{v} + \frac{RT}{v} \frac{v + \frac{2}{3}b}{v - \frac{1}{3}b} = \frac{RT}{v} \frac{1 + \frac{2}{3}\frac{b}{v}}{1 - \frac{1}{3}\frac{b}{v}} = \frac{RT}{v} \left( 1 + \frac{2b}{3v} \right) \left( 1 + \frac{1}{3}\frac{b}{v} \right)$$

$$\frac{\partial p}{\partial v} = -\frac{2a}{v^3} + \frac{RT}{v^2} \frac{(v - \frac{1}{3}b) - (v + \frac{2}{3}b)}{(v - \frac{1}{3}b)^2} = -\frac{2a}{v^3} + \frac{RTb}{v^2(v - \frac{1}{3}b)^2} = 0$$

$$-\frac{2a}{v^3} + \frac{RTb}{v^2(v - \frac{1}{3}b)^2} = 0 \quad \left| \frac{2a}{v} = \frac{RTb}{(v - \frac{1}{3}b)^2} \right.$$

$$\frac{\partial p}{\partial v} = \frac{2a}{v^3} - \frac{2RTb}{(v - \frac{1}{3}b)^3} = 0$$

$$\frac{a}{v^2} = \frac{RTb}{(v - \frac{1}{3}b)^2} = \frac{RTb}{2v(v - \frac{1}{3}b)^2}$$

$$2v = v - \frac{1}{3}b$$

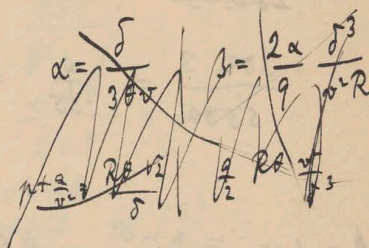


$$\left(1 - \frac{b}{v}\right)^{-1} = \left[1 + \frac{1}{3} \frac{b}{v} + \frac{1}{9} \left(\frac{b}{v}\right)^2 + \dots\right] \left[1 + \frac{2}{3} \frac{b}{v}\right]$$

$$\left. \begin{aligned} 1 + \frac{1}{3} \frac{b}{v} + \frac{1}{9} \left(\frac{b}{v}\right)^2 + \dots \\ + \frac{2}{3} \frac{b}{v} + \frac{2}{9} \left(\frac{b}{v}\right)^2 + \dots \end{aligned} \right\} = 1 + \frac{b}{v} + \frac{1}{3} \left(\frac{b}{v}\right)^2 + \dots$$

Nach Integration:

$$\left(1 + \frac{a}{v}\right)^{\frac{1}{3}} = \frac{9 b^2 R \theta}{2(v-b)^3}$$



$$1 + \frac{2a}{v^3} \frac{dv}{d\theta} = -\frac{9 b R \theta}{2} \frac{3}{(v-b)^4} \frac{dv}{d\theta}$$

$$1 = \frac{dv}{d\theta} \left[ \frac{2a}{v^3} - \frac{9 \cdot 3 b R \theta}{2 (v-b)^4} \right]$$

$$\left(1 + \frac{a}{v}\right) \frac{3}{v-b} = \frac{dv}{d\theta} \frac{2}{v^2} \left[ \frac{2}{v} - \frac{3}{v-b} \right]$$

$$\frac{v^2}{a} = \frac{2(v-b)^2}{9 b R \theta}$$

$$= \frac{dv}{d\theta} \frac{a [2v - 2b - 3v]}{v^3 (v-b)}$$

$$\frac{a}{v^2} (v-b)^3 = \frac{9}{2} b R \theta$$

$$\frac{d\theta}{dv} = -\frac{a(v+2b)}{v^3(v-b)}$$

$$\left[ -\frac{2a}{v^3} (v-b)^3 + \frac{3a}{v^2} (v-b)^2 \right] \frac{dv}{d\theta} = \frac{9}{2} R b^2 = \frac{dv}{d\theta} \frac{a(v-b)^2}{v^2} \left[ -\frac{2(v-b)}{v} + 3 \right]$$

$$\left[ -2a(v-b)^3 + 3av(v-b)^2 \right] \frac{dv}{d\theta} \frac{1}{v^3}$$

$$\left[ -2av^3 + 6av^2b - 6avb^2 + 2ab^3 + 3av^3 - 6av^2b + 3avb^2 \right] \frac{1}{v^3} \frac{dv}{d\theta}$$

$$= \frac{a}{v^2} (v-b)^3$$

$$\frac{1}{v} \frac{dv}{d\theta} = \frac{v-b}{v+2b} \frac{1}{\theta} = \alpha$$

$$\frac{1}{v} \frac{dv}{d\theta} = \beta = \frac{v^2(v-b)}{a(v+2b)} = \frac{\theta a v^2}{a} = \frac{2a}{9} \frac{(v-b)^3}{b^2 R}$$

$$\alpha_{H_f} = \frac{1}{5500}$$

$$v - b = (v + 2b) \theta \alpha$$

$$1 - \frac{b}{v} = (1 + \frac{2b}{v}) \theta \alpha \neq 3 \theta \alpha$$

~~280.3~~

$$\frac{300.3}{5500} = \frac{9}{55} = \frac{1}{6}$$

$$b = \frac{5}{6} v$$

$$\left[ \begin{array}{l} \text{when } \alpha \text{ is } 0 \\ b \approx 0 \end{array} \right]$$

$$R_A = \frac{1}{\theta} \frac{v}{\theta} = \frac{nm\sigma}{\theta^2} = \frac{\rho c^2}{3\theta}$$

$$\frac{(1855)^2}{3.27} = \frac{(485)^2 \cdot 0.00129 \cdot 10^3}{3.27}$$

$$\begin{array}{r} 2.6857 \\ 5.3714 \\ 0.1106-3 \\ \hline 5.4820-3 \end{array}$$

$$2.4362$$

$$0.4771$$

$$2.9133$$

$$\begin{array}{r} 5.4820-3 \\ -2.9133 \\ \hline 2.5687 \end{array}$$

$$= 370 \cdot 10^4$$

$$\rho = \frac{2}{9} \alpha \left(\frac{1}{6}\right)^3 \frac{1}{370 \cdot 10^4} = \frac{2}{9} \frac{1}{216} \frac{1}{5500} \frac{1}{370 \cdot 10^4}$$

$$0.9542$$

$$2.7745$$

$$3.7404$$

$$6.5682$$

$$13.5973$$

$$2010$$

$$13.2963$$

$$= 2 \cdot 10^{-13} !$$

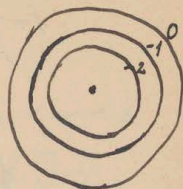
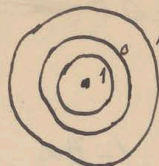
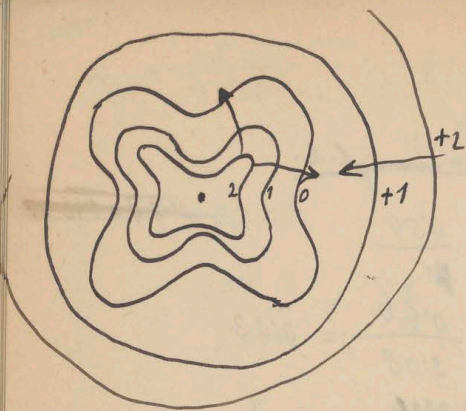
$$\rho_{H_f} = 0.000004 \cdot \frac{1}{136.76 \cdot 980}$$

$$= 4 \cdot 10^{-12}$$

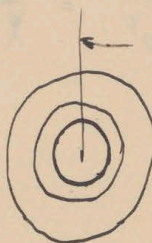
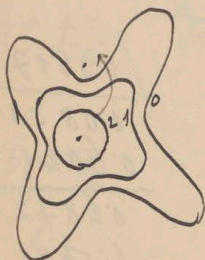
$$\text{also } 2037'$$







~~Ho / Cos~~



$$\varphi = \cancel{F_1} + F_2 + F_3 + \dots$$

$$= \cancel{(x, y, z)} + (x, y, z) + \dots$$

$$\lambda = -\frac{\partial \varphi}{\partial x} = -\left[ \cancel{\frac{\partial F_1}{\partial x}} + \frac{\partial F_2}{\partial x} + \dots \right]$$

$$= -\left[ (A_2 x + D_4 + \dots) - (A_3 x^2 + \dots) - \frac{\partial F_3 + F_5 + \dots}{\partial x} \right]$$

$$F_1 = 0$$

of the ~~the~~  $\lambda_{x,y,z}$   
 $\hookrightarrow$  stabil

$$-\frac{1}{2}(\lambda x + y_1 + 2z) = F_2 + \frac{3}{2}F_3 + 2F_4 + \dots = L$$

$$\varphi \text{ null } < 0 \text{ in } F_2 + F_3 + F_4 + \dots < 0$$

$$F_2 + \frac{1}{2}F_3 + 2F_4 + \dots > 0 > -\varphi$$

$$3F_3 + 5F_5 + \dots < 2F_2 + 4F_4 + \dots$$

~~from~~  $F_L$  ~~the~~





$$\frac{2L}{3d^2(d-b)} - \rho - \frac{2}{d^3} \underbrace{A_m n p \lambda \frac{R}{a}}_{\rho} = 0$$

$$\rho + \frac{a}{v^2} = \frac{R\theta}{d^2(d-b)}$$

$$\cancel{\rho + \frac{a}{v^2}} = \frac{R\theta}{v^2} \underbrace{\frac{n}{1 - \frac{b}{d}}}_{\frac{1}{v} \frac{v-v_0}{v_0}}$$

$$= \frac{R\theta \cdot 3}{v-v_0}$$





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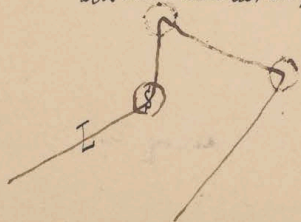






2. W przeciwieństwie do poprzednich <sup>one</sup> teorii, <sup>zjawisk</sup> zjawiska imę drogi <sup>zjawisk</sup> między-  
 jądrowych ~~zjawisk~~ i że <sup>zjawisk</sup> doprawdy <sup>zjawisk</sup> teoretycznych wyników, zatem  
 wyznaczeni są nie podlega kwestji. <sup>zjawisk</sup> ~~Teoria~~ więc nie wymagałby  
 krytykować, co nie ~~jest~~ wydaje mi się niezgodnie z zasadami,  
 bo sądzę że to się wzięło przede mi wyliczanie wszystkich formuł  
 które na podstawie podobnych rozumowań w ostatnich latach zostały  
 wydane, chociaż że może Panowi odnieść wrażenie iż tytuł  
 mojego referatu mógłby raczej brzmieć: "Drogi postępowe na polu  
 teorii kinematyki".

Dawniejsza teoria kin. t.j. teoria skonstruowana przez Clausiusa  
 i, w znaczeniu <sup>dotychczas</sup> ~~poprzedniej~~ formu, przez Maxwella była oparta na  
 (A.2) węg. drogi zwołującej t.j. drogi, ~~patrz~~ na której występuje  
 porównanie z jednostką prędkości, w tym samym kierunku, co  
 następuje (dwustronny) <sup>albo bardziej dokładnie</sup> spotkanie z inną cząstką.



~~Przebieg~~ Średnia energia cząstek  
 na tych krótkich drogach <sup>wzrost</sup> ~~zwiększa~~  
<sup>wzrost</sup> średnia energia kinet. ujęte; ~~to~~



200 3

3). drop' pschytz' podres stjo rosa

~~W~~ porównaniu 2 dtyjnie I  
drugie w dtyjnie

strawberry  
rose de roy; ~~the~~ jek with the long pur white. etc.

a jednolite wyrażenie, przewodzące

Wzrost więc prawo jest niezbędnym do hipotezy co  
do istoty nie drastycznej, przy założeniu, podał gdy istotnicze obliczenie  
temitych zjawisk wymagałoby wiedzenia istoty hipotezy.

do istoty nie drążę się, przy matematycznym podaniu jakiejś istotności obliczenia  
tamtych zjawisk wymagaloby wiedzenia takiego hipotetycznego.

~~mieni rasi adunare ei de portretului~~ <sup>maius</sup> ~~si~~ <sup>stingher</sup> ~~si~~ <sup>poziere</sup> ~~si~~ <sup>a pozitione</sup>

co u bratru nasi konytni swadny • wytworosci tych teori.

w stanie ~~jezu~~ ~~z~~ ~~bliskosci~~ ~~pozi~~ ~~st.~~ ~~u~~ ~~cepu~~ ~~u~~ ~~sta~~ ~~sta~~, która się

przy przewodzeniu ciepła (także elektryczności?)



[illegible]

Cl.-M.	M.	exclusion <del>exclusion</del>
$\gamma$	$\sqrt{\theta}$	$\theta$
$\kappa$	$\sqrt{\theta}$	$\theta$
$D$	$\theta^{\frac{3}{2}}$	$\theta^2$



~~We find ways th'do steps pass just miserably~~

~~Do woy this type resultation jchoi woych~~

Do jakiegociego Homo suntu wyz sz |ch tych zjawisk wystepuie przegznie  
ofolnuych rosad troyi kinetyzmu, bez sprecyzowuy hipotezy co do ~~ich~~ istoty  
iil dwoiejnych mnych ogotowkani.

sit dröjelijgh myder vrgto schammi.

Wladomosi tydzień już niebydno do stoliczno obkładał okien,

(tylko prawo Doyle-Charles - Anglos typ nie wynosi).

(tylko prawo Boyle - Mariotte)  
Odnosi się to nie tylko do bezwzględnej wartości współczynnika, także  
wzrostu tego? przewodnictwa ciepła, dyfuzji (<sup>d.</sup> ~~fizyki~~) <sup>chemii</sup> są dotąd  
tylko pod założeniem że siły są proporcjonalne do 5<sup>ej</sup> potęgi odległości.  
Boltzmann

[illegible]

wszystkiego, przewidzianego przez prawo, w tym celu, aby  
tylko pod zacięciem i siły są <sup>obrotami</sup> proporcjonalne do 5%, jeżeli odległość  
Rottenburg

2 dotkano wyprzedzając (Roxwell)  
(dotykanie)

2 dotans wyrechoval (dotans) <sup>dotans</sup> <sup>tych milkoici</sup> ~~parta~~ (Clamouse, Rayne str.)  
~~prodejsky~~ <sup>Wazy</sup> <sup>then</sup> <sup>Yohi</sup> <sup>vamni</sup> <sup>(tohin</sup> <sup>gasky</sup> <sup>by</sup> <sup>lyty</sup> <sup>pelami</sup>

parte na hipotezie że wstęski wyginają się <sup>do sfery tynkowej</sup> w kierunku <sup>do sfery tynkowej</sup> kulami  
wytynkami są foliowe, a staniw. drogo <sup>do sfery tynkowej</sup> <sup>przekazana przez</sup> <sup>Altman</sup>

parte na hipotezie iż węglowodór wywołuje m.  
stężenie są fałszywe, a właściwo droga <sup>do sfery tyfoidalnej</sup> wskazana przez Balthamano  
jest niestychanie możliwe.

W.C. = zależność od temperatury

just niestety anie mor obna.

~~Co do zawiesin tych opółsymunków i ich związku od temperatury~~

Co do zamierzenia tych opłat wycenianych w 1890 r. Pomieszczenia 10  
~~Setna jednak wykorzystać w inny sposób~~  
 do zamierzenia wycenianych w 1890 r. Pomieszczenia 10

Siódmy punkt  $\theta$ , jak  $\theta$  może być rozumiany w kierunku, musi być być  
proporcjonalne do  $\theta$  wady pierwszego zlecenia, a do  $\sqrt{\theta}$  wady drugiego.

produkty one ~~z największą~~ wartości endulsiwne między innymi

produkty one ~~z największą~~ wartości endulsiwne między innymi







W prawie Sutherlanda w każdym razie jest zawarte słowo zarodek że  
sity w różnych okolicznościach mogą być przysięgią w mniejszych ilościach  
opracowane, ale <sup>już</sup> samo pojęcie kul nętych jest niejako nieograniczone, abstrakcyjne,  
które ogranicza tylko do ustalenia rachunków; natomiast nieograniczone,  
a żeby prawo Sutherlanda było to <sup>pojęcie z danymi</sup> pojęciem jest przysięgią  
miałoby odpowiadać rzeczywistości, jest to <sup>hipoteza</sup> bardzo niedokładne doświadczenie  
przebiega, który w dalszym ciągu jeszcze więcej objętych czyni bytami.

jaht u ogledu pravišho iton V. dub.

[illegible]







Porównanie ~~trójwymiarowej~~ trójwymiarowej jest konieczne co do większej  
trójwymiarowej rozciągłości: dyskusja ~~z~~ trójwymiarowej N. i D.

~~Teoretyczna~~ Zachowując nomenklaturę zaprowadzoną przez Bregana w swoim  
cennym Art. Am. Rev. 1894 rozważamy ~~z~~

problem Maxwella co do rozkładu energii kin. następujące prawo:

Jeżeli w systemie dynamicznym konserwatywnym obieramy ~~prędkości~~ <sup>spójne</sup>  $p_1, p_2, p_3$

tak, że energia będzie <sup>wyrażona</sup> ~~wyrażać się~~ ~~przez~~ jako suma kwadratów ich  
(momentów)  $q_i = \frac{dp_i}{dt}$  to w stanie statycznym

$$T = \frac{1}{2} \left[ \left( \frac{dp_1}{dt} \right)^2 + \left( \frac{dp_2}{dt} \right)^2 + \dots \right]$$

Średnia wartość każdego z tych kwadratów (t.j. energii przypadającej  
na ruch  $p_n$ ) będzie równa:  $\overline{\left( \frac{dp_1}{dt} \right)^2} = \overline{\left( \frac{dp_2}{dt} \right)^2} = \dots$

Tych energii będzie tyle ile system ma stopni swobody ruchu.

~~Maxwella~~ Maxwell-Boltzmannowskie twierdzenie roz' opiera:

Prawdopodobieństwo że w jakimś systemie mechanicznym spójne  
mają wartości w okolicy  $p_1 + dp_1, p_2 + dp_2, \dots$  a prędkości  $\dot{q}_1 + d\dot{q}_1, \dots$   
jest proporcjonalne do  $e^{-hU} dp_1 dp_2 \dots d\dot{q}_1 d\dot{q}_2 \dots$

gdzie  $U = \text{energia}$  potencjalna w owym układzie współrzędnych  $p_1, \dots, p_n$







Próbujemy przedstawić tymi wyrazami prawo zasada między prawem Boltzmana  
do udowodnienia trójki wstępującej.

~~Próbujemy~~ Boltzmann przyjmujemy że przed spotkaniem dwóch cząstek  
prawdopodobieństwo ich <sup>liczba wstępnych</sup> jest  $f(u, v, w)$  jest  
prawdopodobieństwo że cząstka ma prędkości  $u, v, w$ , również  $f(u, v, w)$   
jeżeli jakaś cząstka ma prędkości  $u, v, w$ ; to prawdopodobieństwo równoczesnego  
istnienia tych zdarzeń jest oznaczane przez  $f(u, v, w) f(u, v, w) du, dv, dw, du, dv, dw$   
ale stąd tylko wtedy jeżeli one są od siebie niezależne.

[Dobrze rozumowanie bardzo proste; ilość spotkań jest proporcjonalna do tego wyrażenia  
przy spotkaniach zmienia się:

$$\frac{m}{2}(u_1^2 + v_1^2 + w_1^2) + U_1 + \frac{m}{2}(u_2^2 + \dots) + U_2 = \frac{m}{2}(u_1'^2 + v_1'^2 + w_1'^2) + U_1' + \dots$$

czyli jeżeli  $f$  ma wykładnik eksponencyjny, to  $f_1 f_2$  po zamianach =  $f_1' f_2'$

z drugiej strony według naszego twierdzenia Liouville  $\int du, dv, \dots d\epsilon = \text{const}$   
 $f_1' f_2' du_1' dv_1' \dots$   
to oznacza jednak równościem ilości spotkań przeciwnych  $f_1 f_2$  takich  
które ~~zamiast~~ zamieniają prędkości cząstek z  $u_1' v_1' \dots$  na  $u_1 v_1 \dots$   
więc, ponieważ jeden proces będzie równoważony przez drugi to wyżej mi  
nastąpi zmiana w wykładniku.]

Próbujemy jednak powiedzieć że jeżeli jakaś cząstka ma prędkości  $u, v, w$ , to <sup>(mnożenie stałych)</sup>  
ona przez to ma wpływ na prawdopodobieństwo prędkości  $u$  i innych cząstek,  
że tych zdarzeń nie ma więcej jako od siebie niezależnych.







13

jeżeli powołamy ~~na~~ wszystkie systemy same sobie, także modyfik. i w nich nie ma



tylko systemy dystryb.  $p_1$   $p_1 + dp_1$  ~~zamiast tego~~  
 $K F$   $p_n$   $q_n + dq_n$  ~~przebieg innej konfiguracji~~;  $p_1'$   $p_1' + dp_1'$   
 $K F$   $p_n$   $q_n + dq_n$   $K F$   $p_n'$   $q_n' + dq_n'$

~~Następnie pytanie wiele może być tłumaczonych systemami jest takich  
jakie np.  $q_1$  ma pewną wartość  $q_1 - q_1 + dq_1$  a inne systemy mogą być~~

määrä wertonin H. j. Jokin heinä mandapodložitse —  
C. & it " t. u. m. g. d. y. i. s.

Calcunite ileri sisteminde jüdeleği ni:

$$\int dq_1 \dots dq_n$$

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$$T + V = E = V + \frac{1}{2}(\dot{q}_1^2 + \dot{q}_2^2)$$

$$p_1 dg_1 = dE \quad dg_1 = \frac{dE}{p_1} = \frac{dT}{p_1}$$

$$\frac{dE}{dp_1 \dots dp_n} = \frac{dE/dq_1 \dots dq_n}{\sqrt{E - V - q_1^2 \dots q_n^2}}$$



przy czym ~~można~~ widać należy że  $q_1^2 + \dots + q_n^2 < T$

Oznaczmy więc 
$$N = \frac{[\Gamma(\frac{1}{2})]^n}{[\Gamma(\frac{n}{2})]} [2E - 2V]^{\frac{n}{2}-1}$$

a jeżeli stamtąd staniemy się pytaniem jakimi  $p_1, \dots, p_n$  odp. do całkowitej linii:

$$n p_i = \frac{\Gamma(\frac{n}{2})}{\Gamma(\frac{1}{2}) \Gamma(\frac{n}{2}-\frac{1}{2})} \left[1 - \frac{p_i^2}{2T}\right]^{\frac{n}{2}-\frac{3}{2}} \frac{dp_i}{\sqrt{2T}}$$

$$\left[ \text{Natomiast} \int_{-\sqrt{2T}}^{+\sqrt{2T}} n p_i = 1 \right]$$

zauważamy w tym wzorze zerujemy się  $n \rightarrow \infty$  to

$$n p_i = \frac{e^{-\frac{q_i^2}{4T}}}{\sqrt{2\pi}} \frac{dq_i}{\sqrt{\frac{2T}{n}}}$$

a jeżeli staniemy  $\frac{T}{n} =$  średniemu kw. lin.

zichujsi spłaszczenia =

$$F(\frac{n}{2}) = e^{-\frac{n}{2}} \left(\frac{n}{2}\right)^{\frac{n}{2}} \sqrt{n\pi} \quad 2\Gamma(\frac{1}{2}) = \sqrt{\pi}$$

$$\left(\frac{n}{2e\pi}\right)^{\frac{n}{2}} \sqrt{n\pi}$$

$$\frac{\int_0^{\sqrt{2T}} \Gamma(\frac{n}{2}-\frac{1}{2})}{\Gamma(\frac{n}{2})}$$

$$\int \frac{[\Gamma(\frac{1}{2})]^{n-1}}{\Gamma(\frac{n}{2}-\frac{1}{2})} \underbrace{\left(1 - \frac{p_i^2}{2T}\right)^{\frac{n}{2}-\frac{3}{2}}}_{(2T - q_i^2)^{\frac{n-3}{2}}} (2T)^{\frac{n}{2}-\frac{3}{2}} dp_1 dp_2 \dots dp_n$$













208 9  
~~Trzeci~~ Dojmy & na to iż istnieją tuż wielka ilość takich punktów czyli kul  
 które jednak na sobie nie działają (przechodzą przez siebie jak dymy).  
 Czy ta masa może być trój. D.M.? Oszczęściu nie, bo każda kula nie może  
 być nową, gdyż ośi przestawij się system nie przynosi nowych for. możliwości.  
 Dopiero jeżeli przynajmniej z one się zdarzają jak kule sprężyste albo w  
 jakiś inny sposób na ośi działają, wtedy następuje wymiana przedkości  
 i wtedy ~~można~~ <sup>być</sup> stworzyć nowe twierdzenie.

Inny przykład: ~~W~~ Kule w kierunku prostym, odlegają się z A i D  
~~przodkiem~~ <sup>przodem</sup> przestawiają się. ~~Jeżeli~~ <sup>jeżeli</sup> mamy równie, to zawsze ~~jeżeli~~ <sup>jeżeli</sup> kule będą miały  
 przodki e, jeżeli inne e, etc. - . Dopiero gdy jakaś przynajmniej ma co  
 względności a.p. może różnica w masie, albo uderzenie ekscentryczne etc.  
 nastąpi wskazać M.D.

Przebieganie otwieranych naciąg być ze zastawianiem M.D. do systemów  
 dróg jak.

Nasze przedziwne ~~warunki~~ <sup>warunki</sup> jest niestabilność (Unstabilität) ruchów składowych,  
 t.j. jeżeli warunki przestawiają się, to ruch ~~może~~ <sup>może</sup> być się wahać wokoło  
~~od pierwotnego~~ <sup>od pierwotnego</sup> typu tylko będąc się coraz więcej od niego oddalając.  
 [Gdybyśmy mieli pewną ilość takich punktów w otoczeniu naszego ciała] ~~możemy~~ <sup>możemy</sup>  
 Zależy się, że w gwałtowności, cięności etc. w krótkim czasie te warunki są spełnione  
 z bardzo wielkim przybliżeniem







W przeciwnym kierunku i takie prawo entropii trzeba by odwrócić.  
Niemniej cenna demonstracja myślowa to wskazywanie, iż jednak nie musimy  
brać ośmi jednego z dwóch : predkoci dokładniejsi i ujemnie są równie prawdopodobni  
względnie i równie prawdopodobni jest iżby się entropia zwiększała jak zmniejszała.

Otóż tu powstaje z tego że nie określamy bliżej co rozumujemy pod prawem  
o danych rozróż - jeżeli są to właściwe przypadki których ilość jest nieskończona  
we wyrażeniu dla prawdopodobieństwa

Życie my obieramy n.p. uśrednieni możemy predkoci i (dejmujemy sobie  
kierunki - nie wiemy - <sup>wielkości</sup> predkoci. Tak więc powiada - to pewnie będzie więcej  
równanie prawdopodobne iż  $\frac{dH}{dt}$  dodatni jak ujemne, bo  $\frac{d^2H}{dt^2}$  będzie ujemne = 0  
Tę najprawdopodobniej jest wtedy stan zupełnej „niepewności”, stan stęży

gdzie panuje nieład D.M.

Oczywiście n.p. rozróż nadany regim nieprawdopodobny, jeżeliśmy przypuszczają  
do którejś ujemnej rozróżności wzięli same uśrednieni <sup>obdarzeni</sup> w kierunku +X  
a do dodatniej ujemnej -X. Życie się to jednak stało, to będzie rozróż  
nadany regim prawdopodobny iż  $\frac{dH}{dt}$  będzie ujemnym



„prawdopodobieństwo“ pewnego układu p<sub>ij</sub>

musimy wziąć utwór pewnych warunków parających jako dowód, co do których  
nie możemy mieć żadnych prawdopodobieństw, bo nie wiemy ~~skąd~~ ~~gdzie~~  
jakiś ~~system~~ ~~jest~~ rozkład spowodował, innemu stanowi nie wiemy ostateczności  
dotyczy przeszłości systemu, więc study ruchów musi tylko ująć

Kardorod. ie w pewnym momencie czerpnąć z tego systemu oraz modyfikować go. Nie ma tu żadnego problemu. Wierzę, że one będą służyć do celów <sup>innych</sup> i analizowania precyzyjnego.

Poczci wyrażenia się jemu lepiej ~~statystyk~~ dyktantów przez wyłączenie  
 trójdzielnego opławy mechanizmu Poincaré'a i ~~wyższej~~ <sup>istoty</sup> ~~istoty~~  
 ręk systemu ~~dobrego~~ konserwatywnego znowu po upływie <sup>istoty</sup> ~~istoty~~ <sup>współczesny</sup>  
 się powtórzy więc i będzie skusony. Zmowa trójdzielną i ~~to~~ <sup>współczesny</sup>  
 trójdzielną o entropii nie modeluje restoracji do takich systemów, więc  
 i ~~entropii~~ <sup>entropii</sup> ono nie da się wyłomować mechanizmu. Alternatywnie  
 odpowiedział jednak i nie zachodzi iedna sprzeczność jeśli się owe  
 prawo entropii uważy jako ~~prawo~~ <sup>nie jako</sup> trójdzielną ~~nie~~ <sup>nie</sup> ~~nie~~ <sup>nie</sup>  
 istoty tylko <sup>jako trójdzielną</sup> ~~prawdopodobieństwo~~ <sup>prawdopodobieństwo</sup> nadzwyczaj wielkiego, tak jak ~~współczesny~~  
 nowa prawa fizyki empirycznie poznane.

(skrivning)

Werkstoffe

~~K. ...~~



[illegible]



[illegible]



Pracę Maxwella co do wartości energii kinetycznej wzięliśmy za podstawę do interpretacji stanu ciała stałego  $\frac{C}{\epsilon} = k$  <sup>gorzej</sup> ~~przez grzech~~.

Jeżeli cząsteczka może mieć  $n$  stopni wolności ( $n$  ruchów niezależnych) to ~~to~~ <sup>energii  $E =$</sup>  przypadnie na nią  $n\alpha$ , ~~ponieważ~~ ponieważ każdej stopniowi odpowiada równa ilość energii kin.; z tego  $3\alpha$  na ruch postępowy, co się równa temperaturze  $\theta$ , zatem  $\alpha = \frac{\theta}{3}$ ,  $E = \frac{n}{3}\theta$ .

Opierając się na tym możemy naliczyć (energję potencyalną) przy podwyższeniu temp. m.p. wskutek zmiany objętości stanów stałych  $u = v\alpha = \frac{v\theta}{3}$  gdzie  $v$  oznacza <sup>liczbę stanów</sup> stałą wielkość, i pracę wykonaną przez ciśnienie ciśnieniu ewentualnemu  $\int p dv = \frac{m\bar{c}^2}{3} = \frac{2}{3}$

Zatem  $\frac{C}{\epsilon} = \frac{n + v + 2}{n + v} = 1 + \frac{2}{n + v}$

Jak wiadomo Boltzmann stosując rozumując tego wron wartości  $k = 1.66, 1.4, 1.33$  które odpowiadają ~~to~~ a porów jedno, dwa - (Satony

1. Przeglądając jako Boltzmann cząsteczek ~~Wskale~~ całkowitą gładkość ~~Wskale~~ <sup>przebiegi</sup> mamy ~~dotychczasowe~~ 3 stopnie swobody ruchu postępowego i 3 ruchy obrotowe — ale tych ostatnich nie należy uwzględnić ponieważ, jeżeli każde są gładkość ruchy obrotowe w ogóle nie będą żadnego miały wpływu, zatem  $n = 3, v = 0$ ;  $k = 1 + \frac{2}{3}$



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albo ogólnie ciele

2). elipsoidalny <sup>obrotowe</sup>  $n=5, v=0; k=1.4$ 

3). elipsoidalny trójosiowy albo ogólnie ciele netyczne dowolnego kształtu

$$n=6, v=0; k=1.33$$

Mniejsze wartości stosunku  $k$  do tego wyrażenia przysługują większym ruchom wewnętrznym, trudności tylko następująca te wielkie wartości  $k$ . Trudności polegają na tym:

1). Stosunek osi elipsoidalny trójosiowy nie zmienia stosunku  $k$ , ale on ma wpływ na czas relaksacji  $\tau$ , i nie przewidywać potrzebny do osiągnięcia stanu stopu, cenn mniejsze różnice między osiami, ten dłuższy czas będzie potrzebna iż wszystkie ruchy się wyrównają.

Aby więc n.p. gas mieć  $k=1.4$ , rozstrząsłby być motetykami idealnymi ciałami obrotowymi <sup>gładkimi</sup>, najmniejszą brak symetrii zrobi  $k=1.33$ . <sup>Taka symetria kłóci się</sup> <sup>przejmują</sup> ~~jest~~ jednak rzecz ~~nie~~ bardzo prawdopodobna dla niektórych gazów n.p.  $H_2$ , które ~~jest~~ <sup>jest</sup> trój - albo może wartościowe.

Więc Boltzmann ~~to~~ sądzi, że owe wartości  $k$  mogą być ewentualnie za wielkie, że gazy mogą w rzeczywistości mniejsze  $k$ , tylko że <sup>to</sup> z powodu wielkiego czasu relaksacji zostało dotychczasowym badaniom.

Trudno sądzić o prawdopodobieństwie tego przypuszczenia dla tamtych gazów, w każdym razie stawa się tu nowe pole <sup>do doświadczeń</sup> dla badań doświadczalnych: <sup>badania</sup> <sup>zmienności</sup> ciepła właściwego <sup>zróżnic</sup> ~~zróżnic~~ <sup>zróżnic</sup> (zob. Nachmisch d. z. W.), które



2. powołanie odprawy on-line w celu uformowania wiekotowych i może przy tym się  
do wystomoczenia <sup>branych</sup> opinii dot. historycznych rezultatów różnych bodaw.

2). Gdyby rzeczywiste były orbitami sprężystymi, toby ~~jeżeli~~ z rosnącą energią mechaniczną postępująco zmniejszały się amplitudy i drgania sprężyste tych ciał stałych, ponieważ każda sprężysta ma  $n = \infty$  (niekt. r. drgań fundamentalnych). Wprawdzie zależy mi na iż zachodzi pewna wytykliwość czy zjawiska Rowalla tutaj jest ściśle spełnione ale trzeba przemyśleć i istnienie energii ruchu wymuszonych <sup>wielkość</sup> ~~zjawisk~~ <sup>zjawisk</sup> wykonywanych w rzeczywistości.

Ogródniki jednak owe pojęcie kłó między innych było tylko wprowadzone do  
umysłowania sfer działania i t. n. nie miało myślenia o tym aby je  
przełożyć na obiektywną rzeczywistość. Wracając więc do racjonalniejszego pojęcia sfery  
omawianych tendencji. Me z drugiej strony możemy przejąć ze  
inne rodzaje, które powodują

pragnąc objętych egzystencji. <sup>Wobec</sup> z drugiej strony musimy przystać na  
omijany to trudności. <sup>Wobec</sup> jakiegoś drugiego innego rodzaju, które powoduje  
muszą się objęci <sup>istotnie</sup> różniących w przedmiocie <sup>istotnie</sup> różniących w przedmiocie  
promieniowania, ~~zatem musi posiadać być większy stopień swobody ruchu~~

promieniowanie, ~~zatem~~ <sup>co</sup> na który owe ruchy się  
In jednak w grę wchodzi ośrodek, eter, ~~na~~ na który owe ruchy się  
przebiega. Jego wpływ nie można subsumować w siły konserwatywne  
sugerowane przez uogodnienie prawa M., zatem do tych ruchów nie możemy  
stosować prawa wdrożenia równego energii. Wkracza to o pole niestacjonarne  
względem promieniowania z tego krystaliku.



z pewnym dwojakim ciekawym na interesujący  
 Pod tym względem Stoney podgi myśl o fosforescencji moie  
 była polegać na takich ruchach wewnętrznych które mają stonnowo  
 długi czas relaksacji.  
 (są tylko w małym stopniu  
 związane z innymi ruchami)

3). Jeśli sobie wyobrażamy stony jako punkty materialne otoczone  
 siłą, cząsteczka jednoatomowa będzie miała  $n=3$ , tak samo jak kula;  
 cząsteczka dwuatomowa  $n=5$ , ale tylko jeśli odstęp dwóch atomów jest  
 niezerowy; ~~z pewnym rozróżnieniem~~ <sup>przez pewien rozróżnieniem</sup> ~~przez pewien rozróżnieniem~~  $n=6$ ; trójatomowa w górnym rzędzie  $n=9$ ,  
~~przez pewien rozróżnieniem~~

Wzr. jeśli połączenie między dwoma atomami jest idealnie styczne,  
 matematycznie niezerowe, to będzie  $n=5$ ,  $K=14$ . Nie mogłoby być  
 n.p. wskazywaniem przez połączenie fizycznie styczne, rozumiejąc że  
 sprężystość, bo wtedy byłoby  $n=6$  a pewnie tego jeszcze  $v=1$  (zob. później)

Co to znaczy jednak: jest matematycznie styczne, a nie fizycznie styczne tylko przez siły, a nie przez materię  
 Warto ~~jednak~~ <sup>dla tego</sup> wrócić na to, że możemy otrzymać  $K=14$ ,  
 jeżeli ~~zaryzykujemy~~ <sup>zaryzykujemy</sup> z wprowadzeniem potencjału i idealnie styczności, a nie zerowania energii jak  
 robimy  $n=6$ ,  $v=-1$ . Wskazanie  $v$  może mieć także wartość

ujemną, bo nie koniecznością musi się posługiwać wewnętrzna energia  
 potencjalna przy podwyższeniu temperatury. ~~Dwa punkty~~ w dziedzinie

dotrnia jeżeli siły są tego samego rodzaju jak sprężystość, będzie

podobnie jak np. przygotowanie według prawa  $\frac{1}{n}$

bo wtedy <sup>musi się</sup> ~~zmniejszyć~~ <sup>zwiększyć</sup> odstęp ~~między~~ (wzr. wielkości cząstek! zob. porządek,  
 Sutherland) przy podwyższeniu temperatury. jeżeli układ ~~byłby~~ <sup>byłby</sup> na pewien stopień







Albionem pierwoty wóz sprawdził oddaje ~~bacha~~ w świątyni spóś  
jakosciowo spawiska zachodzący przy zgrupowaniu i skupieniu gorów  
ale ~~dalekim~~ jest od ilościowej dokładności.

Pokazuje się to n.p. mianowicie w objętości krytycznej, ~~która jest~~  
[t.j. objętości punktu]  $\frac{\partial p}{\partial v} = 0, \frac{\partial T}{\partial v} = 0$

Z równania otrzymano się  $v_k =$  t.j.  $\frac{1}{2.8}$  części objętości,  
która by odpowiadała wykluczeniu prawca Boyle Charlesa,  
podczas gdy liście doświadczania mian. S. Younga podają jego  
wartość tego stosunku  $\frac{1}{3.7} - -$

Dieterici pokazuje że także z formy ( ) otrzymano się  $\frac{1}{3}$ , ~~co~~  
~~XXXXXX~~ a uwzględniwszy <sup>dobrze</sup> dodatkowe wyrażenie szeregu ( ) jemu  
wskazuje wartości. Z tego on wnioskuję że w ogóle równanie formy  
nie może odpowiadać rzeczywistości.

Ten wniosek zdaje mi się <sup>istotny</sup> przesądzać, że nie mamy przyczyny  
do przypuszczenia, że dobrze potęgi muszą być dodatnie; przesunięcie  
~~przez~~ wyrażenie /byłoby może znak - <sup>a istnieć dołem wyrażenie - przy p. h. mogą być między sobą</sup>, więc możliwe iżbyśmy z  
zupelnego równania uwzględnionego otrzymali wartość przybliżoną do tego  $\frac{1}{3.7}$ .



Historia podzieli dwa inne wzory:

$$p v + \frac{a}{v^2} = \frac{R \theta}{v - b} \quad i \quad p v =$$

z których pierwszy dałby stosunek  $\frac{v_1}{v_2} =$  a drugi

Pierwszy jednak nie jest wcale zbyt uśrednionym, a drugi jest oparty na formułach z teorii cieplej historycznej, którą dolił hydrodynamiczny krytykowi. Ani jeden ani drugi nie czyni żadnej warunków  $p \rightarrow \infty \quad v = \frac{b}{3}$

Wzór ~~ten~~ nie może ich ująć ze stanowiska teoretycznego a pod względem doświadczalnym różni tylko i zgoła się w tym jednym punkcie z doświadczeniem, ~~dalej inne porównanie~~ <sup>pod inną perspektywą</sup> niż zostały one <sup>bliz</sup> jemu sprawdzone.

<sup>z każdego czasu</sup> ~~W~~ Równanie musi mieć postać  $p + \frac{a}{v^2} = T \varphi(v)$ , jeżeli możemy uznać, że cięła masy ma jakiegobądź postać; wynika z tego że można

wszystkie prędkości zmniejszyć w pierwszym stosunku, przez co nie zmienia się <sup>formy</sup> postać ruchu, tylko ciśnienie. (Rayleigh). <sup>z</sup> ~~Stąd otrzymujemy se~~ <sup>przebieg one</sup>

wyrażenie  $\frac{a}{v^2}$ , niezależnie od prawa działania, jeżeli sphere jest ciałem w porównaniu do ~~ciężkości~~ <sup>odległości</sup> cząstek. Gdyby była mała, to ~~by~~ <sup>trzeba</sup> byłoby zastąpić <sup>jakiejś</sup> funkcję  $v$  i  $T$ .

Jeżeli jednak cząsteczki nie są idealnie stygną, ~~tylko cząsteczkami~~ <sup>to</sup> jeżeli sity odpychają się nie stopniowo  $\infty$  -- to proporcjonalność ciśnienia



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 całkowitego do temperatury ustęży. Tak n.p. pod założeniem Maxwella  
 jest  $\frac{A}{25}$  otrzymano z równania (Daltona).

$$pv + \frac{a}{v} = 2\theta \left[ 1 + \frac{b}{v} \right]$$

gdzie jednak błąd jest proporcjonalny ~~do~~ (do potęgi i) do potęgi  $\theta^{-\frac{3}{2}}$ .

Tego rodzaju jest także równanie Van der Waalsa  $\left( p + \frac{a}{v^2} \right) (v - b) = \frac{RT}{v}$

~~ponieważ tutaj i v są zmienne~~ które Rengmann uważa jako  
 rezultat empiryczny <sup>Younga i do do punktu</sup> ~~liczący~~ <sup>mostrzenia</sup> gdzie a i b są wielkościami

zmiennymi:

$$a = A \frac{e}{\beta + 3 R \theta}$$

$$b = \beta \frac{e}{\beta + 3 R \theta}$$

Równanie to ~~jest~~ mimo swej skomplikowanej formy zawiera tylko  
 trzy <sup>niezależne</sup> stałe, i ogni ~~zadaje~~ <sup>specjalnie</sup> trzecie ~~do~~ 0

~~stałe~~ <sup>stałe</sup> ~~concy~~

; ~~jest~~ stosuje się ono z wielką

dokładnością do doświadczeń, ale ~~teoretycznie~~ nie ma żadnych teoretycznych

podstaw, ~~i nie~~ <sup>może</sup> być uważane tylko jako empiryczna formuła.

\* Rozumowanie teoretyczne p. Renganna są błędne, mianowicie ~~stałe~~ <sup>stałe</sup> ~~ma~~  
 temperatury jest średnia energia kinet. uśredniona wzdłuż całej drogi, a nie tylko  
 w częściach drogi gdzie  $nta = 0$ .



Już mi udało się

Z tej moim przekonaniu że zostanie ~~zostanie~~ pojęte V. d. W. do czego nie  
moim nam ~~stwierdzić~~ się spodziewać pomysłowych rezultatów, dopóki  
nie znamy ~~istoty~~ <sup>do bliższej</sup> ~~istoty~~ <sup>sposobu do bliższej wartości</sup> ( ) i jej kąt dokładniejszy, ponieważ tam  
 $\frac{1}{v}$  już znacząco musi mieć wartość (zwykle  $> 1$ ). ~~Wystarczy to do osiągnięcia~~

~~stwierdzić~~ <sup>kinetyczna</sup> Voğta, z tej przyczyny tej ~~stwierdzić~~ <sup>kinetyczna</sup> teoria cieczy w  
tej formie jak została ~~zaproponowana~~ <sup>nie posiadać sensu V. d. W.</sup> przez Voğta, Dieterici'ego i Helmholtza,  
jest bez praktycznej wartości. Voğta pierwotna teoria była zupełnie  
"idealnym" <sup>albo raczej ujemnym</sup> ~~cieczy~~ ponieważ nie uwzględniała wcale wielkości sfery i  
odpychających tej, uważała regule jak punkty nie jako kule.

W drugiej rozprawie ~~zaproponował~~ <sup>V. d. W.</sup> Voğt ~~zaproponował~~ <sup>nie jest</sup> ~~zaproponował~~ <sup>co do sensu (7-10-1)</sup>  
o przeprowadzeniu teorii — pominięciu nawet o wziętych warunkach —  
jest nieścisłe, oparte na przybliżeniach, <sup>wrodziny bliższej teorii Clausiusa i Regnola</sup> których wpływ trudno  
ocenić. To samo stosuje się do teorii Dieterici'ego i Helmholtza.

Jako stwarzają <sup>zadaje</sup> ~~podstawę~~ <sup>zadaje</sup> że także w cieczy średnia energia kinetyczna  
jest miarą temperatury, ale Voğt i Diet. nie przyjmują <sup>ty</sup> ~~ty~~ <sup>ty</sup> ~~ty~~







Niegodnosc z nieprzyjemnosc<sup>205</sup> / mi moie nas walc dzwicz pomiesci<sup>mi moie 27</sup> <sup>nipli</sup> <sup>o nich</sup>  
 równanie same zastawia do stanów jedni  $\frac{b}{v}$  na wartosci 217

Wychoდე z formy      która jest już o jeden stopień doświadczone,  
stwierdza się według Doltzmann:

de zapune i to nie hiedzi dwata dni spetnom.

Jędrzej, zdołać się, jak <sup>zyskaniem</sup> Siśmienie nadzwyczaj wielkie wystrach w  
 cię, i skutek którego  $\frac{1}{5}$  stojać się tak wielki wstąpię, niezgodnie,  
 o ile wiem, jednemu przez Jędrzej; o równaniu jego wspomniany przez inną  
 osobę.

W skutek owych rozr<sup>o</sup>  
danie jest roz  
(romanie rosadnizet).

*obscure* L. *Aster solanum* or *cypripedium* / *estivation*

Całkiem nowego obliczenia jednych wymagalnych zjawiska tarcia występowania, <sup>i jego przyczyn</sup> pękania iętki i dyfuzji dla cieczy. Lotro jednak rozumiemy że trudności tu porzucić nie możemy, jeżeli nie pokonamy, gdyż nawet dla jawań doskonałych nie zdolano <sup>już</sup> tych rachunków wykonać ~~z~~ przynajmniej tyle, ile dostyganych (a nawet metody Maxwella nie można zastosować jeżeli ~~z~~ zyszczeniu ~~z~~ można). Nie możemy się spodziewać ~~z~~ osiągnięcia jakichś rezultatów przynajmniej co do umiarkowania tych wielkości z temperaturą - która <sup>dla jawań, doch.</sup> ~~z~~ próby można obliczyć.



7 Tutaj jidzi przez zachowanie stałego objętości, wszystkie ruchy porostają  
 geometrycznie podobne jidzi <sup>przekrój  $\alpha$</sup>  ~~je~~ w pewnym stosunku powiększonym t. zn.  
 ruchy cząstekowe i <sup>prędkość</sup> ~~ruchy~~ <sup>prędkość</sup> ~~liczby~~ <sup>prędkość</sup> ~~samej~~. Przez to jednak wszystkie  
~~siły~~ natężenia w elementach cieczy są proporcjonalne w stosunku  $\alpha^2$   
 a temperatura w stosunku  $\alpha^3$ .  
 Wzrost również natężenia styganie także wewnętrzne,

N.p.  $A_{xy} = \alpha \cdot (A_{xy})_0 = \cancel{7.4}$  2 tego wyniku. Tak samo jak przy poprzednim obliczeniu:

$$(f \times g)_0 = \eta_0 \left( \frac{\partial u_0}{\partial y} - \frac{\partial v_0}{\partial x} \right)$$

$$f(x, y) = \eta \left( \frac{\partial \eta_0}{\partial y} - \frac{\partial \eta_0}{\partial x} \right) = \alpha^2 \eta_0 \left( \frac{\partial \eta_0}{\partial y} - \dots \right) \quad \text{wird } \eta = \alpha \eta_0$$

$$= \eta_0 \left( \frac{\theta}{\theta_0} \right)^2 \frac{1}{2}$$

[illegible]

$$\frac{dy}{d\theta} = \left( \frac{\partial y}{\partial \theta} \right)_{\theta} + \left( \frac{\partial y}{\partial v} \right)_{\theta} \left( \frac{\partial v}{\partial \theta} \right)_{\theta}$$

 $\frac{\partial v}{\partial \theta}$  jest zdefiniowany, z rozważeniem technicznym

a  $\frac{\partial y}{\partial v}$  można obliczyć dla kilku różnych wartości zmiennej stanu  
wynoszących od  $\frac{\partial y}{\partial p}$  i składowych wtedy  $\frac{\partial v}{\partial p} = \frac{\partial y}{\partial v} = \frac{\partial y}{\partial x} \cdot \frac{\partial x}{\partial v}$

Znamy te wartości ~~W~~ n.p. dla  $\theta = 0$  i  $\theta = 2\pi$  dla których  
stwierdzamy n.p. dla  $\theta = 2\pi$ :  $\frac{dy}{dx} =$  resp.  
podnoszący w rezytacji:



Wzrost pokazuje się kompletnie prawie naszej formułki, zatem i zasady  
K. d. Waals - Clauwisa, t. zn. że nie można sądzić, że jako był  
spółczesny, ~~co się stało~~ Wierzy to już z odpowiednim wzorem dla gęstości  
dokonywał, ale tutaj sprasnowie zabiera i niezgodności występują  
Bile jemu jaskrawiej.

Wolałbym ciebie zobaczyć żywcem do ~~nie~~ omówienia wniosków z tej  
pracy niż nasupięz cych.

[illegible]



W kinetycznej teorii rzeczy wice nie postępićmy jeszcze doleko,  
 kinetyczne teorie wstępnym jednak jeszcze mniej jest wykonane,  
~~choćby nam jeszcze o zdany~~ nie spodziewa się nawet jemu co do  
 głównych rozpraw które tej teorii trzeba nadac.

<sup>dot</sup> <sup>względ</sup> ~~z~~ jednym ~~przekaz~~ jednak tutaj "konkretniejszy" jest ten wytwór  
 niż u obu innych t.j. że mamy ~~tu~~ prawo tak zadowolając  
 ogólności i prostoty - choć nie do końca spełnionem - jak prawo Dulonga  
 i Rottsa co do ciepła właściwego.

A te regulaminy <sup>zgodnie z przypuszczeniem że ciepło właściwe zależy od temperatury</sup> ~~zgodnie z przypuszczeniem że ciepło właściwe zależy od temperatury~~ <sup>zgodnie z przypuszczeniem że ciepło właściwe zależy od temperatury</sup> ~~zgodnie z przypuszczeniem że ciepło właściwe zależy od temperatury~~  
 wychodzą z ogólnych ~~zgodnie z przypuszczeniem że ciepło właściwe zależy od temperatury~~ <sup>zgodnie z przypuszczeniem że ciepło właściwe zależy od temperatury</sup> ~~zgodnie z przypuszczeniem że ciepło właściwe zależy od temperatury~~  
 znowu teorii kinetycznej ~



219 41

~~Richardson & ty - ale niegdy trójdzielnie w do silnika, z którego wypływa, stąd~~  
 (Richardson)

ponieważ p. v. jako m. o.:

$$\bar{L} = -\frac{1}{2} \sum (x^2 + y^2 + z^2)$$

albo też wprost powłoki się na prawo Maxwella  $\bar{L}$

~~Przejmując - tworząc~~

wdług którego:

$$= +\frac{1}{2} \sum (x \frac{\partial U}{\partial x} + y \frac{\partial U}{\partial y} + z \frac{\partial U}{\partial z})$$

$$\bar{U} = \frac{\int U e^{-hU} dx dy dz \dots}{\int e^{-hU} dx dy dz \dots}$$

gdzie  $h = \frac{1}{kT}$

Jedni uważają, ponieważ w tej pierwszej i drugiej przynajmniej równowaga to się  
 w pierwszym dotknięciu mamy obrotów będąc mianem przysięgi jako prop. do wychylenia,  
 więc U jako funkcja drugiego stopnia potęg drugich,  $\bar{U} = \bar{L}$  w odległości  
 i drugiego wzoru daje  $\bar{U} = \bar{L}$  (gdzie też zmienia energię pot. będąc równo  
 zmianie energii kinet., zatem całkowita zmiana energii będzie dwa razy tak wielka  
 jak gdyby  $U=0$ ; t.j.) (dwa razy tak wielka jak  $\bar{U}$  jeżeli  $\bar{U}$  jest  $\bar{L}$  atomowy tej j.  
 uwzględniając wra funkcjonalnej  $\bar{U}$  i  $\bar{L}$  atomowy i  $\bar{U}$  i  $\bar{L}$  atomowy  
 stopniak się:

$$c = 6.$$

Am większe wychylenie występuje poza obrot sfer, gdzie się można uważać że  
 porównywalne do odstępów, ten mniej dokładniej będzie się ~~zgodzić~~ ~~zgodzić~~ ~~zgodzić~~  
 sprowadza to prawo, więc również nieprzekazywać można określić w tych pierwszych

1). które mają najmniejszy wiek ~~pot~~ atomowy, bo te przy równym temp. atome  
 muszą mieć odpowiednio większą prędkość, więc i wychylenie ~~mały~~ ~~mały~~ ~~mały~~

2). które mają małą wartość obrotu atomowy, więc może obrotu  
 atomowe, ponieważ ten się o mały obrotu mogą być ~~zwiększone~~















drugą inną wartość, ale raczej jemu przybliżeń podobnej wielkości.

Dlatego  $\frac{d}{\phi} = \sqrt{\frac{v}{v_0}} = 1 + \frac{1}{3} \frac{v-v_0}{v_0}$  otrzymujemy wreszcie  $v-v_0$  jak młot:

$$\mu + \frac{a}{v} = \frac{2\theta\sqrt{2}}{v-v_0} \quad (1.544)$$

Sutherland <sup>równanie gęstości</sup> ~~wprowadza się powyższe explante swoje równania, dla symboli~~

~~jego~~ równowazim ~~do~~

$\mu + \frac{a}{v} = \frac{32\theta}{v-v_0}$ , co polega na przekształceniu symbolu  $\frac{\sqrt{2}}{3}$

Z tego równania otrzymujemy się związek między współczynnikiem rozrzedności  $\alpha$  i siłowości  $\frac{1}{k}$ :

$$k = \frac{\phi}{\sqrt{2}} \frac{2\theta\sqrt{2}}{R\rho\alpha^2}$$

który jednak zupełnie mi sprzeczne z uśrednioności, obliczone wartości

~~siłowości~~ są kilka tysięcy razy za małe!

Sutherland ~~myśli~~ myśli wy poprawić założenie o bryle promień cząsteczek <sup>bardzo</sup> zależny od temperatury, ale ~~obliczenia~~ <sup>te</sup> i hipotezy jego są już problematyczne wartości.

Nadaje się mi się wydać fakt, że jego ~~cel~~ <sup>cel</sup> równania dla cieczy otrzymuje wychodząc z zupełnie tych samych założeń; ~~zobacz~~ <sup>z</sup> uśrednioności jego ~~postępowanie~~ <sup>postępowanie</sup> powinien być otrzymać zupełnie to same równanie i wyniki jego równania ~~po naszym~~ <sup>po naszym</sup> polega tylko na innym, z czego mi się mniej ścisły, ~~po prostu~~ <sup>po prostu</sup> ~~zobacz~~ <sup>zobacz</sup> ~~proste~~ <sup>proste</sup> ~~wprowadzenie warunków przybliżenia~~ <sup>wprowadzenie</sup> ~~do~~ <sup>do</sup> jego pracy. Jeśli jednak to równanie jest ważne dla cieczy, jak wtedy Sutherland ułomaczy sprężystości postaciową?



[illegible]

mieli tyko interes. <sup>dosłowny</sup>  
Mając sygnal i ~~stagnację~~ tak przynajmniej do roszczenia  
zasadniczego rzeczy, ale obliczenia ~~osobliwych i zaskakujących~~  
zwiazku między ~~osobliwych i~~ ~~zaskakujących~~ terminów  
wielu (tak samo takie według) ) daje nam rezultaty  
zgodnie niegdyż i racjonalistycznym

6th

<sup>jak dawać</sup>  
Zatem wynika tu sam: poruczenie ~~pracy~~ <sup>pracy</sup> istnienia co do  
ogółu jak ~~każdy~~ <sup>każdy</sup> V. d. Wolski.





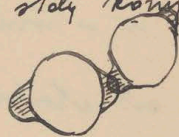






z drugimi stronami nalezia i <sup>pozingerowy kryptokary</sup> ~~inne~~ <sup>223 49</sup> inne zjawisk  
nos i tak jacy skoteni do przyjscia nie kierunkowych, przedwojennych  
zjawisko chemiczne. Chemicy, mowia o nowej wartosci pierwiastkow,  
ktore to same widzi szkodliwosci - najwiecej reprezentowane przez  
kwasowy, sygnalizacja i niezgodnosc takich sily kierunkowe.

223 45

[illegible]











Według ~~W~~ tropnego prądu Tammona należy to robi wystarcz  
 jako cieple pod chłodzone (unter kühler Fl. b. h. h. t.). Nie więc się  
 rozchodzi o cieple, nie może się drugi struktur ani kierunkowości, do  
 której wogóle stało się <sup>nie było mowa o tej mowie</sup> tak wielkim ~~nie~~ nie może więc nie  
 być niekiedy orientacji regularnej. <sup>(ogólnie)</sup> Takie ciała istotnie nie  
 mają oznaczonego punktu topnienia. One niższą stopniowo przez  
 ogrzewanie i nie mają żadnej temperatury gdzie by nastąpiło nagłe  
 przekształcenie wycieku utępnienia.

Kryl - Jannu kresow







<sup>se vyplní sklenice do</sup>  
7 prouků tehle mletých křemíku / tlučeného, ~~voda~~ abychom mohli stlačit  
dříve přes samé kompresy bez výhledu omezení.

Možno by sa postarali stavať pľachy v doslovny smieri:

Παρτὸν ῥεῖ.

Jeżeli ~~to~~ na koniec musimy rozjrzeć skąd na rezultaty  
pozyskane z tej omawianej <sup>nowej</sup> teorii kinetycznej materji — powinniśmy  
zwrócić uwagę, dośkonale — to będzie się nam wydawało, maie iż pła-  
nie być ~~to~~ zbyt optytm. Ale myślimy, że i negatywne rezultaty mają  
swoje wartości i również te <sup>ciężkie</sup> trudne pytania, które ~~są~~  
przy omówieniu różnych <sup>teorii</sup> ~~teori~~ musieliśmy wnieść, i które nam  
wskazują, jakie kwestje należy uważać za najważniejsze, ~~najważniejsze~~;  
i który kierunek należy głównie pracować.

Pod tym względem chciał mianowicie zobaczyć na (tęgi problem kontrowersyjny aspekt



stężeń, ponieważ są one z reguły tuż po mierzach od tego musi  
rozpoznać, i ~~nie~~ mógłby z tym (przemian) dążeniem do wzajemnych rezultatów  
aniżeli w swojej pracy. ~~W~~ ~~Nadzwyczaj~~ Nadzwyczaj w swoim byłoby co do  
tego przewidzieć, że ogromne ilości dolnych mierzonych doświadczeń  
mianowicie co do ~~stężeń~~ sprężystości krystalów i ich właściwości  
barwotwórczych (nie krystalizacyjnych, ale są barwotwórci) przy bardzo  
niskich <sup>i wyskich</sup> temperaturach, doświadczenia. W tym celu, badał Tennant, że  
choć ~~nie~~ teraz najnowszym nam jest enancj: przykaż się stężeń.

guy 20/11/5

c 9

ciężar 7 1/2

stężeń 9 1/2 + 20



$$\frac{\partial v}{\partial \rho} = 0.000110$$

$$0.000650$$

$$\frac{424}{315}$$

$$110 : 37 = 3$$

Ans.

15%

0.015

$$\alpha = 0.00118$$

$$\frac{\partial \eta}{\partial \rho} = 0.00093$$

$$- \frac{0.00093}{0.00065} \cdot 0.00009$$

$$\begin{array}{r} 837.5 \\ - 0.00167 \\ + 0.00180 \\ \hline + 0.00015 \end{array}$$

$$\frac{18.3}{18.9}$$

0.4

$$14.5$$

$$11.7$$

2.8

Ans.

$$0.00148$$

$$0.00073$$

$$28 : 20$$

$$14 : 131 = 11$$


$$- \frac{0.00073}{17} \cdot 0.00148$$

$$\begin{array}{r} 148.75 \\ 1036 \\ 444 \\ \hline 1080 : 17 = 63 \\ 60 \end{array}$$

$$\begin{array}{r} - 0.0063 \\ + 0.0018 \\ \hline - 0.0045 \end{array}$$

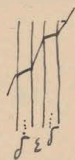
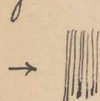


Przewodnictwo cieplne próbek musi zależeć od ~~stosunku~~ grubości gazu

→  otaczającego i od Temp. spręż. kufki, zatem d. ciennika.

Można sobie to wyobrazić w przybliżeniu pod obrazem układu bloków o

funkcji podobnej jak warstwa próbek:



$\chi$  przew. ciał. stałych

$\kappa$  " gazu

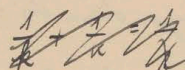
$\chi$  " próbek

$$\chi \frac{dT_1}{dx} = \kappa \frac{dT_2}{dx} = \chi \frac{dT_3}{dx}$$

$$\delta \frac{dT_1}{dx} + \varepsilon \frac{dT_2}{dx} = \chi \frac{dT_3}{dx} (\delta + \varepsilon)$$

$$\delta + \varepsilon \frac{\chi}{\kappa} = \frac{\chi}{\chi} (\delta + \varepsilon)$$

$$\frac{\delta}{\kappa} + \frac{\varepsilon}{\kappa} = \frac{\delta + \varepsilon}{\chi}$$

albo narysujmy  $\mu$  procentową zawartość  
 (względem objętości) ciała stałego, zatem  $\frac{\varepsilon}{\delta + \varepsilon} = 1 - \mu$ :

$$\frac{\mu}{\kappa} + \frac{1 - \mu}{\kappa} = \frac{1}{\chi}$$

Wskazując stroną temp. zmienia się to na:

$$\delta \frac{dT_1}{dx} + (\varepsilon + 2\mu) \frac{dT_2}{dx} = (\delta + \varepsilon) \frac{dT_3}{dx}$$

$$\frac{\delta}{\kappa} + \frac{\varepsilon + 2\mu}{\kappa} = \frac{\delta + \varepsilon}{\chi}$$

$$\frac{\mu}{\kappa} + \frac{1 - \mu}{\kappa} + \frac{2\mu}{\kappa} = \frac{1}{\chi}$$



Np. dla parietale przy  $\lambda = 10^5 \text{ cm}$   
 $\gamma = 1.7 \cdot 10^{-5} \text{ cm}$

Jużli kule to przybliżenie:  $\mu = \frac{3}{4}$

$$\frac{1}{\lambda} \neq \frac{1}{K} \left[ \frac{1}{4} - \frac{3.4 \cdot 10^{-5} \text{ cm}}{\delta + z} \right]$$

Np.  $\delta + z = 0.1 \text{ mm}$

$$\frac{1}{\lambda} = \frac{1}{K} \left[ \frac{1}{4} - 3.4 \cdot 10^{-3} \right] = \frac{1}{4K} \left[ 1 - 13 \cdot 10^{-2} \right] \quad 1.3\%$$

$\delta + z = 0.01 \text{ mm}$

$$\frac{1}{\lambda} = \frac{1}{4K} \left[ 1 - 1.3 \cdot 10^{-1} \right] \quad 13\%$$

~~$\delta + z = 0.001 \text{ mm}$~~

$\delta + z = 0.001 \text{ mm}$  tutaj  $\lambda$  byłoby 10 razy większe, zatem już nie możemy  
 zestrośować takich obliczeń, ale <sup>tu jest</sup> ~~nie możemy~~ granice ~~złoty~~ porzucić  
 której przewidziano bydzie nie zmniejszając proporcji odległości do ~~wzrostu~~  
 gęstości, a nie bydzie zohinem od grubości 2000 (już ~~to~~  $z < 0.001$ )  
 i średnicie proszku



Jaka jest średnia prędkość ~~dot~~ średnia ciężkości dwóch ciał?

$$f(u, v, w) = A e^{-k(u^2 + v^2 + w^2)} du dv dw$$

$$\iiint A^2 e^{-k[(u_1^2 + v_1^2 + w_1^2) + (u_2^2 + v_2^2 + w_2^2)]} du_1 dv_1 dw_1 du_2 dv_2 dw_2 \sqrt{\frac{(u_1 + u_2)^2 + (v_1 + v_2)^2 + (w_1 + w_2)^2}{2}}$$

$$e^{-k(V_1^2 + V_2^2)} V_1^2 V_2^2 \sin \theta_1 \sin \theta_2 d\theta_1 d\theta_2 d\varphi_1 d\varphi_2 d\varphi_3 \sqrt{V_1^2 + V_2^2 + 2V_1 V_2 \cos \theta}$$

Jedną prędkość : średnia prędkość c

$$\iiint \sin \theta_1 \sin \theta_2 d\theta_1 d\theta_2 d\varphi_1 d\varphi_2 \frac{1}{2} \sqrt{1 - \cos \theta_1 \theta_2}$$

$\cos \theta = \cos \theta_1 \cos \theta_2 + \sin \theta_1 \sin \theta_2 \cos(\varphi_1 - \varphi_2)$

$$= \iint 2\pi \sin \theta d\theta \frac{\sqrt{1 + 1 + 2 \cos \theta}}{4\pi} = \frac{\sqrt{2}}{2} \int_0^\pi \sqrt{1 + \cos \theta} \sin \theta d\theta = \frac{1}{2} \int_0^\pi (1 + \cos \theta) \sin \theta d\theta$$

$$= \frac{1}{2} \int_0^\pi \sin \theta d\theta + \frac{1}{2} \int_0^\pi \cos \theta \sin \theta d\theta = \frac{1}{2} [-\cos \theta]_0^\pi + \frac{1}{4} [\sin^2 \theta]_0^\pi = \frac{1}{2} (1 + 1) = 1$$



$$c_{\text{eff}} = \frac{\sqrt{2} c}{2} = \frac{1}{\sqrt{2}} c$$

Średnia prędkość 4 ciałek : również wyobraz sobie Liang z

$$2 \text{ grup } \hat{=} 2 \text{ ciałek} = \left(\frac{1}{\sqrt{2}}\right)^2 c$$

$$\text{Prędkość} = \left(\frac{1}{\sqrt{2}}\right)^3 c$$

$$\frac{16}{2} \cdot \left(\frac{1}{\sqrt{2}}\right)^4 c = \frac{1}{2} c = \frac{c}{\sqrt{2}}$$

n.p. ~~średnia~~ prędkość średnia masowa  
1000 ciałek  $c_{\text{eff}} \left(\frac{1}{2}\right)^5 c = \frac{c}{32}$







$$\begin{aligned}
 \tau c \sqrt{2} & \quad 2\tau \\
 \tau c (\sqrt{2})^2 & \quad 4\tau \\
 \tau c (\sqrt{2})^3 & \quad 8\tau \\
 \tau c \sqrt{m} & \quad m\tau \\
 \text{"} & \quad \sqrt{t} \\
 = \sqrt{m\tau} \cdot \frac{\sqrt{t}}{\sqrt{t}} & \quad \sqrt{t} \\
 & \quad \sqrt{t} \cdot \sqrt{c} \cdot \sqrt{c}
 \end{aligned}$$

$$l = \sqrt{t} \lambda c$$

$$\lambda = 10^{-8} \text{ cm}$$

$$t = 1$$

$$c = 0.04 \text{ cm}$$

$$l = \sqrt{4 \cdot 10^{-10}} = 2 \cdot 10^{-5} \text{ cm} = 0.0002 \text{ mm}$$

$$= 0.2 \mu$$

$$\text{wzr "scheinbares" } c = c' = 0.0002 \frac{\text{mm}}{\text{sec}}$$

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$$n.p. \text{ jizeli } \lambda = 10^{-8} \text{ cm}$$

$$t = 1$$

$$c = 400.100$$

$$l = \sqrt{4 \cdot 10^{-4}} = 2 \cdot 10^{-2}$$

$$= 0.02 \text{ cm} = 0.2 \text{ mm}$$

$$= 200 \mu$$

Emulsijs možna uvozić jako rastvor, kugelke drobne u njih zaradi jako molekuly. Difuzija.

A zatim kugelke same jako gas.

$$\frac{1}{p} dp = -g dz$$

$$p = p_0 e^{-\frac{g p_0 z}{p_0}}$$

$$p = \frac{p_0}{p_0}$$

$$\frac{1}{p} = R \theta$$

to same

R u stranu a, izvor molek.

$$\frac{980 \cdot 0.0012}{980 \cdot 76 \cdot 13.6} = 10^{-6} \text{ cm} = 10^{-4} \text{ cm}$$

jizeli n.p.  $\delta = 0.1 \mu$  to hdeci u njih kugelke

cca  $10^9$  molekula

zatim stala jarova

$$-10^{-3} \text{ cm}$$

$$p = p_0 e$$

Wje jizeli u 1mm visokosti p pravi zero

jizeli jizdnak  $\delta = 0.01 \mu$  to hdeci  $p = p_0 e^{-2 \text{ cm}}$  zatim razstuski taj velikonas

rogole nie ~~na~~ sadrzi sig, jizce u odlytosti kelku cm  $p > 0$

"Faller" puz dodavanu sil et. polija na tu se sig zminuie. Istovratno i se omaz elaviz u vjeku kugelke.







Nie snęję już z dawać  
 Nie w porę drąże już dawać dawać dawać co do wielkości  
 owych 5 punktów, ~~Podoba~~ nie można ~~szczęśliwie~~ badeć doli  
 przeprowadzić 5 ścieżki punkt; ~~Podoba~~ ~~bliska~~ ~~głównie~~ ~~szczęśliwie~~  
 zależeć co do owych wielkości na podstawie badeć praw do podolnych  
 dyktando owego ~~rozwiązania~~ ~~głównie~~ ~~szczęśliwie~~ ~~głównie~~ ~~szczęśliwie~~  
~~na podstawie~~ ~~głównie~~ ~~szczęśliwie~~ ~~głównie~~ ~~szczęśliwie~~

[illegible]







231  
Gouy: Note préliminaire: Journal de Physique 31/12 1888

Attention: quelques substances se dissolvent à la paroi, sont frottées par  
d'autant plus vite que moindre viscosité  
phénomène général

Le mouvement brownien est donc un phénomène général d'autant plus sensible que  
la viscosité du liquide est plus petite. Le point le plus important est la dépendance  
du phénomène; de milliers de part. ont été examinées et dans aucun

cas on n'a vu une part. en suspension qui n'offrit pas le mouvement  
brownien, avec une intensité ordinaire, en regard à la grosseur de la particule.

Lumière n'a pas d'influence  
des particules de même grosseur, mais de nature diverse solides, liquides,  
gazeuses, sont animées de mouvements peu différents.

Tous rapides à la limite du visible, beaucoup plus que pour  $\lambda = 1 \mu$   
vitesses ces quelques  $\frac{1}{1000}$ , ce qui répond peut être à l'objection  
qu'on pourrait tirer de la loi des grands nombres, en considérant  
l'extrême petitesse des molécules.

Paris Doll d. 18 mch. 1888. Wied. Ann. 36 p. 334-346 1889

Galathea 18 mch. 1888. Zpt. Ch. 4 p. 417 (1889)

Wied. Ann. 55 p. 200 (1888)

Schweinf. 8. 1888. Recherches sur le mouvement des liquides. J. de Phys. 8 p. 411 (1889)



Nerves Substance of fine white particles in liquid

July 27 1922

March 12 7 363 (1888)

Ridhan 4, 957

Feb. 1889 2513

21 Enlarged & better

↓ West Ann ~~to~~ 52 p. 132 (1899)

$$\mu_{H_2O} = 0.39 - 36^\circ$$

0.91 -26°

2-08 - 10°

 $4.60 + 0.00$ 

§. 16  $10^{\circ}$

$$\mu = 4.525 \cdot 10^6 \frac{7.4475 \text{ t}}{234.69 \text{ t}} = a \cdot 10^{\frac{1 \text{ t}}{c+t}}$$

n.p.  $t = -20$

$$\begin{array}{r} 148.95 \\ \hline 214.69 \end{array}$$

1731

- 33 18

0.8413 - 1

$$10^{10} \cdot 0.6938 = 6941$$
$$2\gamma_1 = 0.6556 \pm 0.6928$$

~~22/2/2018~~ = 0.9618-10

$$= 0.916$$



$$\frac{dp}{dt} = a \cdot 10^{\frac{bx}{c+x}} \cdot \log 10 \cdot \frac{b}{(c+x)^2} [(c+x) - x]$$

$$= p \cdot e^{\log 10} \cdot \frac{bc}{(c+x)^2}$$

$$s = \frac{1}{p} \quad \log s = -\log p$$

$$\frac{d \log s}{ds} = -\frac{d \log p}{dp} = -\frac{1}{p} \frac{dp}{ds} = -e^{\log 10} \cdot \frac{bc}{(c+x)^2}$$

$$J\lambda = \frac{T}{p} \frac{dp}{dt}$$

$$V = \frac{v_0}{273} \cdot T$$

$$\frac{dv}{dt} = - \frac{J\lambda - \lambda J V \frac{d \log s}{ds}}{p + \lambda J} = - \frac{J\lambda + T \left( \frac{dp}{dt} \right) \frac{V}{p}}{p + T \frac{dp}{dt}}$$

$$\frac{dx}{dt} = p \frac{dv}{dt} - \frac{p v}{T}$$

$$= -p \left\{ \frac{J\lambda + T \left( \frac{dp}{dt} \right) \frac{V}{p}}{p + T \frac{dp}{dt}} + \frac{V}{T} \right\}$$

$$= -p \left\{ \frac{J\lambda + \left( T \frac{dp}{dt} \right)^2 \frac{1}{p} \frac{v_0}{273}}{p + T \frac{dp}{dt}} + \frac{v_0}{273} \right\}$$

$$J\lambda = 9897$$

$$C = 0.2377$$

$$J = \frac{42200 \cdot 10^3}{980 \cdot 76.136} = 4164$$

$$\begin{array}{r} 88081 \\ 99149 \\ 17354 \\ \hline 00584 \end{array}$$

$$\begin{array}{r} 62531 \\ 00584 \\ \hline 61947 \\ 37603 \\ \hline 99550 \end{array}$$

$$\left( \frac{dp}{dx} \right)_0 = p \cdot e^{\log 10} \cdot \frac{b}{c} = 4.525 \cdot 2.3026 \cdot \frac{7.4475}{23469}$$

$$\begin{array}{r} 65562 \\ 87201 \\ \hline 27046 \\ 36222 \\ \hline 20034 \\ \hline 88985 \\ \hline 51936 \end{array}$$

$$\begin{array}{r} 51936 \\ 43616 \\ \hline 95552 \\ T_{d_1} = 90265 \\ 4525 \\ \hline 94790 \end{array}$$

$$\begin{array}{r} 91104 \\ 45089 \\ \hline 36193 \\ -65562 \\ \hline 70631 \\ 50853 \\ 99 \\ \hline 50952 \end{array}$$



$$X_x = a \frac{\partial \xi}{\partial x} + b \theta$$

$$Y_y = a \frac{\partial \eta}{\partial y} + b \theta$$

$$Z_z = a \frac{\partial \xi}{\partial z} + b \theta$$

$$X_y = Y_x = \frac{a}{2} \left( \frac{\partial \xi}{\partial y} + \frac{\partial \eta}{\partial x} \right)$$

$$Y_z = Z_y = \frac{a}{2} \left( \frac{\partial \eta}{\partial z} + \frac{\partial \xi}{\partial y} \right)$$

$$Z_x = X_z = \frac{a}{2} \left( \frac{\partial \xi}{\partial x} + \frac{\partial \xi}{\partial z} \right)$$

$$\begin{aligned} \rho \frac{\partial^2 \xi}{\partial t^2} &= \frac{\partial X_x}{\partial x} + \frac{\partial X_y}{\partial y} + \frac{\partial X_z}{\partial z} = a \frac{\partial^2 \xi}{\partial x^2} + \frac{a}{2} \left( \frac{\partial^2 \xi}{\partial y^2} + \frac{\partial^2 \eta}{\partial x \partial y} + \frac{\partial^2 \xi}{\partial x \partial z} + \frac{\partial^2 \xi}{\partial z^2} \right) + b \frac{\partial \theta}{\partial x} \\ &= \frac{a}{2} \nabla^2 \xi + \frac{a}{2} \frac{\partial \theta}{\partial x} + b \frac{\partial \theta}{\partial x} = \frac{a}{2} \nabla^2 \xi + \left( b + \frac{a}{2} \right) \frac{\partial \theta}{\partial x} \end{aligned}$$

$$\left. \begin{aligned} \rho \frac{\partial^2 \xi}{\partial t^2} &= \frac{a}{2} \nabla^2 \xi + \left( \frac{a}{2} + b \right) \frac{\partial \theta}{\partial x} \\ \rho \frac{\partial^2 \eta}{\partial t^2} &= \frac{a}{2} \nabla^2 \eta + \left( \frac{a}{2} + b \right) \frac{\partial \theta}{\partial y} \\ \rho \frac{\partial^2 \xi}{\partial t^2} &= \frac{a}{2} \nabla^2 \xi + \left( \frac{a}{2} + b \right) \frac{\partial \theta}{\partial z} \end{aligned} \right\} \begin{aligned} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \\ \frac{\partial}{\partial z} \end{aligned} \quad \left\{ \begin{aligned} \rho \frac{\partial^2 \theta}{\partial t^2} &= (a+b) \nabla^2 \theta \\ \text{Xyzowa składowa} \\ \text{wektora } \sqrt{\frac{a+b}{\rho}} \end{aligned} \right.$$

$$\rho \frac{\partial^2}{\partial t^2} \left( \frac{\partial \xi}{\partial y} - \frac{\partial \eta}{\partial x} \right) = \frac{a}{2} \nabla^2 \left( \frac{\partial \xi}{\partial y} - \frac{\partial \eta}{\partial x} \right) \quad \left\{ \begin{aligned} \text{Toroidalne wektory } \sqrt{\frac{a}{2\rho}} = \sqrt{\frac{\pi}{\rho}} \end{aligned} \right.$$

$$\frac{a}{2} = T$$

$$\begin{aligned} & x_{n-m} \frac{d^2 x_{n-m}}{dt^2} + x_{n-m+1} \frac{d^2 x_{n-m+1}}{dt^2} + \dots + x_{n+m} \frac{d^2 x_{n+m}}{dt^2} = \\ & = E \left[ x_{n-m} (x_{n-m-1} - 2x_{n-m} + x_{n-m+1}) + x_{n-m+1} (x_{n-m} - 2x_{n-m+1} + x_{n-m+2}) + \dots \right] \\ & = E \left[ (x_{n-m} - x_{n-m+1})^2 + (x_{n-m+1} - x_{n-m+2})^2 + \dots \right] + \\ & + E \left[ x_{n-m}^2 + x_{n-m+1}^2 + \dots + x_{n+m}^2 - x_{n+m}^2 \right] \\ & = \frac{d}{dt} \left[ x_{n-m} \frac{dx_{n-m}}{dt} + \dots \right] - \left[ \left( \frac{dx_{n-m}}{dt} \right)^2 + \dots + \left( \frac{dx_{n+m}}{dt} \right)^2 \right] \end{aligned}$$



$$\frac{d^2 x_n}{dt^2} = E \left[ (x_{n+1} - x_n - l) + (l - (x_n - x_{n-1})) \right]$$

$$= E [x_{n+1} - 2x_n + x_{n-1}]$$

$$\frac{d^2 x_1}{dt^2} = E (x_2 - x_1 - l)$$

$$\frac{d^2 x_2}{dt^2} = E (x_3 - 2x_2 + x_1)$$

$$\frac{d^2 x_3}{dt^2} = E (x_4 - 2x_3 + x_2)$$

$$\frac{d^2 x_4}{dt^2} = E (x_5 - 2x_4 + x_3)$$

$$\frac{d^2 x_n}{dt^2} = E (x_{n+1} - 2x_n + x_{n-1})$$

$$\frac{d^2 x_{n+1}}{dt^2} = E (x_{n+2} - 2x_{n+1} + x_n)$$

$$\frac{d^2 x_n}{dt^2} \frac{dx_n}{dt} = E \left\{ \underbrace{x_n \frac{dx_{n+1}}{dt} + x_{n-1} \frac{dx_n}{dt}}_{\frac{d}{dt}(x_n x_{n+1})} - 2x_n \frac{dx_n}{dt} + x_{n+1} \frac{dx_{n+1}}{dt} + x_{n-2} \frac{dx_{n-1}}{dt} - 2x_{n-1} \frac{dx_{n-1}}{dt} + x_n \frac{dx_n}{dt} \right\}$$

$$\frac{1}{2} \frac{d}{dt} \left[ \left( \frac{dx_{n-m}}{dt} \right)^2 + \left( \frac{dx_{n-m+1}}{dt} \right)^2 + \left( \frac{dx_{n-1}}{dt} \right)^2 + \dots + \left( \frac{dx_{n+m}}{dt} \right)^2 \right] = E \left[ \frac{d}{dt} (x_{n-m} \cdot x_{n-m+1} + x_{n-m+1} \cdot x_{n-m+2} + \dots) \right]$$

$$= E \left[ \frac{d}{dt} \left[ x_{n-m}^2 + x_{n-m+1}^2 + \dots \right] + x_{n-m-1} \frac{dx_{n-m}}{dt} + x_{n+m} \frac{dx_{n+m}}{dt} \right]$$

$$= E \left[ \frac{d}{dt} \left[ \frac{1}{2} (x_{n-m+1} - x_{n+m})^2 + (x_{n+m+2} - x_{n-m+1})^2 + \dots \right] + x_{n-m-1} \frac{dx_{n-m}}{dt} + x_{n+m} \frac{dx_{n+m}}{dt} \right]$$



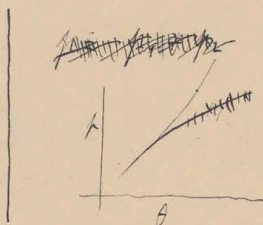
$$dQ = A p dv + dU \quad \text{pro 1 gr.}$$

$$0 = A p dv + c d\theta + r dx$$

$$dx = \frac{\partial x}{\partial p} dp + \frac{\partial x}{\partial \theta} d\theta$$

$$\frac{1}{\rho} \frac{dp}{d\theta} = f$$

$$\frac{p}{\rho} = R\theta$$



$$x = 20 \text{ g} = 1 \text{ kg vj}$$

Wenn 1 kg.  $x$  kg vj  $\sim \tan \theta$   $\left( \frac{\partial x}{\partial p} \right)$ , wie viel wird sich ändern wenn  $p + dp$   $\theta + d\theta$   $= dx$

$$r \theta \sim \theta \sim \theta P$$

$$0.6 \text{ vj. } \sim \frac{x}{p} = R\theta \quad x = p d.$$

$$0.6 \text{ vj. } \frac{1}{p} \frac{dp}{d\theta} \sim c_{pR} P \text{ vj. } \sim p \theta \quad x = \frac{p d\theta}{p d\theta} = \frac{1}{\rho p}$$

$$\frac{p}{\rho} = \frac{RT}{P} \quad s = s_0 \cdot \frac{T}{T_0} \cdot \frac{P_0}{P}$$

$$\frac{p}{\rho} = R\theta \quad R = \frac{760.}{0.001293 \cdot 273}$$

$$s = \frac{1}{0.627} \frac{R_{Lp} T}{P}$$

$$x = \frac{p}{\rho R_{Lp} \theta} \quad n = T \frac{dp}{dT} \sim \frac{\theta \sim R_{Lp}}{p} \frac{dT}{dT}$$



$$v dp = g dz$$

$$\rho v = \rho_0$$

$$\rho dz = R d\theta - g dz$$

$$x = \frac{P}{R + \theta} v$$

$$dx =$$

$$\rho = \frac{R\theta}{v}$$

$$v dp = \frac{R\theta}{v} dv$$

$$A \rho dv + c d\theta = + A d\left(\frac{Pv}{R\theta}\right) \cdot \frac{\theta^2 R}{P} \frac{dP}{d\theta}$$

$$\rho v = R\theta$$

$$\frac{v}{R\theta} = \frac{1}{\rho}$$

$$v dp = g dz$$

$$\rho v = R\theta$$

$$\frac{AR\theta}{v} dv + c d\theta = A \frac{\theta^2 R}{P} \frac{dP}{d\theta} d\left(\frac{Pv}{R\theta}\right) = \frac{-\theta^2 R}{P} \frac{dP}{d\theta} \left[ P d\left(\frac{v}{R\theta}\right) + \frac{v}{R\theta} dP \right]$$

$$v d\left(\frac{R\theta}{v}\right) = -g dz$$

$$A R d\theta + c d\theta + A g dz = -A \frac{\theta^2 R}{P} \frac{dP}{d\theta} \left[ d\left(\frac{1}{\rho}\right) + \frac{1}{\rho} \frac{dP}{P} d\theta \right]$$

$$\frac{R\theta}{\rho} d\rho = g dz$$

$$d\theta \left[ AR + c + A \frac{\theta^2 R}{\rho P} \left(\frac{dP}{d\theta}\right)^2 \right] = -A g dz \frac{\theta^2 R}{P} \frac{dP}{d\theta} \frac{1}{\rho} g dz$$

$$\frac{ARk}{k-1}$$

$$= \left( A + \frac{\theta}{\rho} \frac{dP}{d\theta} \right) g dz$$

$$\frac{d\theta}{dz} = \frac{g}{R} \frac{1 + \frac{\theta}{\rho} \frac{dP}{d\theta}}{1 + \frac{k}{k-1} + \frac{\theta^2}{\rho P} \left(\frac{dP}{d\theta}\right)^2}$$

$$= \frac{k-1}{k} \frac{g}{R}$$

$$\frac{1 + \frac{\theta}{\rho} \frac{dP}{d\theta}}{1 + \frac{k-1}{k} + \frac{\theta^2}{\rho P} \left(\frac{dP}{d\theta}\right)^2}$$

$$= 1 \frac{1 + \left(\frac{1}{A} \frac{\theta}{\rho} \frac{dP}{d\theta}\right)}{1 + \left(\frac{1}{A} \frac{\theta}{\rho} \frac{dP}{d\theta}\right) \cdot \left(\frac{k-1}{k} \frac{\theta}{P} \frac{dP}{d\theta}\right)}$$



	-25°	-15°	-5°	0°	+5°	+10°	+15°
$\frac{dP}{d\theta}$			<del>0.309</del>	0.340	0.451	0.6095	
$\frac{dP}{d\theta}$	$\theta$	$P$	$r$				
-30°							
-25°							
-20°	0.074	253	0.91	519	35		
-15°	0.1185	258	1.44	554			
-10°	0.1695	263	2.15	591			
-5°	0.238	268	3.16	629			
0	0.340	273	4.52	671			
5	0.451	278	6.51	715			
10	0.6095	283	9.14	760			

$$\begin{array}{r}
 9.767 \\
 8.548 \\
 \hline
 1.219 : 2 \\
 \\
 6.971 \\
 0.69 \\
 \hline
 0.902 : 2 \\
 \\
 4.909 \\
 5.69 \\
 \hline
 840 \\
 \\
 4.569 \quad 3406 \\
 2.939 \quad 2930 \\
 \hline
 0.6619 \quad 0.476 \\
 \\
 1.562 \\
 225 \\
 \hline
 237 \\
 \\
 2.327 \\
 1.988 \\
 \hline
 0.339
 \end{array}$$

$$\theta = 273 \parallel 1 + 273 \frac{0.34}{760}$$

$$1 + 273 \cdot \frac{0.34}{760} = \frac{0.4}{1.4} \cdot \frac{39}{273} \cdot \frac{2.26}{4.52}$$

$$\frac{7}{2} \cdot \frac{5}{283} = \frac{3500}{104} : 526 = 0.0618$$

$$\frac{7}{2} \cdot \frac{30}{283} = 105 : 283 =$$

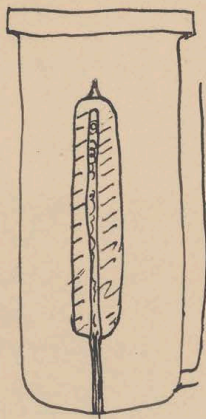
$$\begin{aligned}
 \frac{r}{r_0} &= \left[ 1 - \frac{k-1}{k} \frac{\theta x}{2\theta_0} \right]^{\frac{k}{k-1}} \left( \frac{\theta}{\theta_0} \right)^{\frac{k}{k-1}} \\
 r &= 760 \cdot \frac{283}{273} \left( \frac{\theta_0 - \Delta}{\theta_0} \right)^{\frac{k}{k-1}} \\
 &= 760 \left[ 1 - \frac{k}{k-1} \frac{\Delta}{\theta_0} + \frac{\alpha(\alpha-1)}{1.2} \left( \frac{\Delta}{\theta_0} \right)^2 - \frac{\alpha(\alpha-1)(\alpha-2)}{1.2 \cdot 3} \left( \frac{\Delta}{\theta_0} \right)^3 \dots \right]
 \end{aligned}$$

$$\begin{array}{r}
 20103 \\
 84510 \\
 \hline
 45593
 \end{array}$$









$$100 \text{ cm}^2 \cdot \frac{50^\circ}{1 \text{ cm}} \cdot 0.0001 =$$

$$= 0.5 \frac{\text{cal.}}{\text{sec.}} = 2 \text{ Volt Amp}$$

50 Ohm 10 Volt

$$\frac{e}{w} = \frac{1}{w}$$

$$\frac{7}{3} (1.4)^2 (9.8) \cdot \frac{12.93}{(76.13.6)^2} \cdot \frac{(2.73)^2}{8} \cdot 1.67 \cdot 10^{-6} \cdot 10^{-6}$$

$$\theta = 3$$

$$46 = 10$$

$$V_p c \frac{\partial \theta}{\partial t} = -0.01 \theta$$

$$\theta = \theta_0 e^{-\alpha t}$$

$$\alpha = 0.001$$

$$e^{-\alpha t} = 1\%$$

$$\left( \frac{1.4}{76.13.6} \right)^2 \cdot \frac{4.1293.167}{3} \cdot (9.8)^6$$

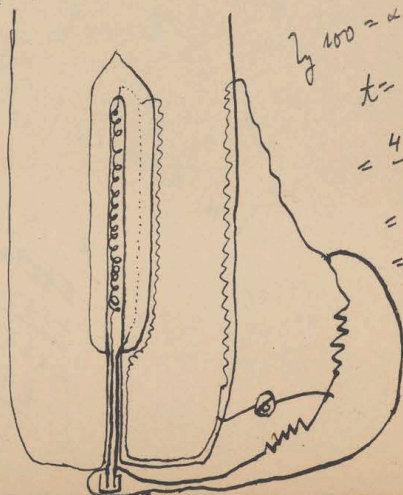
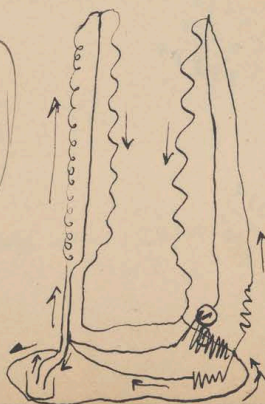
$$\left( \frac{1}{74} \right)^2$$

$$\left( \frac{9.1^3}{740} \right)^2 \cdot 4.167 \cdot 0.431$$

$$\left( \frac{754}{740} \right)^2 = 104 \cdot \frac{1.67 \cdot 1.72}{(1.7)^2}$$

$$\begin{array}{r} 819 \\ 8281 \\ 7529 \\ 8281 \\ \hline 75357 \end{array}$$

$$\begin{array}{r} 0.034 \cdot 13.6 \\ 408 \\ \hline 544 \\ 0.46 \end{array}$$



$$100 = e^{\alpha t}$$

$$\ln 100 = \alpha t$$

$$t = \frac{\ln 100}{\alpha}$$

$$= \frac{4.6}{10^{-3}}$$

$$= 4.6 \cdot 10^3$$

$$= 0.7 \cdot 10^2$$

$$= 70 \text{ min}$$

$$= 1 \text{ hour}$$



$$\theta = a \int_0^{\frac{\sqrt{x}}{\sqrt{k}}} e^{-\frac{c\rho}{4k} y^2} dy + b$$

$$\begin{aligned} x=0 & : \theta = \theta_2 \\ t=0 & : \theta = \theta_1 \end{aligned}$$

$$\theta_1 = a \underbrace{\int_0^{\infty} e^{-\frac{c\rho}{4k} y^2} dy}_b + b$$

$$\left. \begin{aligned} \theta_1 &= a \frac{\sqrt{k}}{c\rho} \frac{\sqrt{\pi}}{2} + b \\ \theta_2 &= b \end{aligned} \right\} a = (\theta_1 - \theta_2) \frac{\sqrt{c\rho}}{k\sqrt{\pi}}$$

$$\theta = (\theta_1 - \theta_2) \frac{\sqrt{c\rho}}{k\sqrt{\pi}} \int_0^{\frac{\sqrt{x}}{\sqrt{k}}} e^{-\frac{c\rho}{4k} y^2} dy + \theta_2$$

$$= (\theta_1 - \theta_2) \frac{2}{\sqrt{\pi}} \int_0^{\frac{\sqrt{x}}{\sqrt{k}} \frac{\sqrt{k}}{c\rho}} e^{-y^2} dy + \theta_2 = \frac{2}{\sqrt{\pi}} (\theta_1 - \theta_2) \int_0^{\frac{2x}{\sqrt{x}} \frac{\sqrt{k}}{c\rho}} e^{-y^2} dy + \theta_2$$

može zohľadniť hydru a

$$\left. \frac{\partial \theta}{\partial x} \right|_{x=0} = \frac{2}{\sqrt{\pi}} (\theta_1 - \theta_2) e^{-\frac{4x^2}{t} \frac{k}{c\rho}} \cdot \frac{2}{\sqrt{x}} \frac{\sqrt{k}}{c\rho} \bigg|_{x=0} = \frac{2(\theta_1 - \theta_2)}{\sqrt{x}} \frac{\sqrt{k}}{c\rho}$$

$$k \frac{\partial \theta}{\partial x} = \frac{4}{\sqrt{x}} (\theta_1 - \theta_2) \frac{k}{\sqrt{\pi}} \frac{\sqrt{k}}{c\rho} = \text{na povrchu absorbované teplo}$$

0.3  
10 min  
0 min  
10 min



Ściana zewnątrz w kontakcie z parą wodną, która np. parę przegrzewa do cylindra.

$$\frac{\partial \theta}{\partial t} = \frac{k}{c\rho} \frac{\partial^2 \theta}{\partial x^2}$$

Warunki początkowe  $t=0 \quad \theta=0 \quad \begin{cases} x=0 \\ x=l \end{cases}$

$t \rightarrow \infty \quad \theta = \theta_1 \quad | \quad x=0$

$$\theta = f\left(\frac{z}{\sqrt{t}}\right)$$

$$\frac{\partial \theta}{\partial t} = f'(z) \frac{1}{2\sqrt{t}} \cdot \frac{z}{\sqrt{t}} = f'(z) \cdot \frac{z}{2t} = f'(z) \frac{1}{2z} \frac{z^2}{t}$$

$$\sqrt{t} = z^2$$

$$\frac{\partial \theta}{\partial x} = f'(z) \frac{1}{x^2} \cdot \frac{\partial \theta}{\partial x} = -f'(z) \frac{\sqrt{t}}{x^2}$$

$$\theta = \frac{\partial^2 \theta}{\partial x^2} = +f''(z) \frac{t}{x^4} + 2f'(z) \frac{\sqrt{t}}{x^3} = \frac{f''(z) z^2 + 2f'(z) z}{x^2}$$

$$\frac{f'(z)}{2z^4} = \frac{k}{c\rho} \frac{f''(z) z^2 + 2f'(z) z}{x^2}$$

$$f(z) = e^{\varphi(z)}$$

$$f'(z) = \varphi' e^{\varphi(z)}$$

$$\frac{f'}{f} = \frac{\varphi'}{\varphi}$$

$$\varphi' \cdot z^2 + 2z - \frac{c\rho}{2kz} = 0$$

$$\varphi' + \frac{2}{z} - \frac{c\rho}{2kz^3} = 0$$

$$\varphi = \frac{c\rho}{4kz^2} - 2 \log z \quad \parallel \quad f(z) = e^{\frac{c\rho}{4kz^2} - 2 \log z}$$

$$\theta = A \int \frac{e^{-\frac{c\rho}{4kz^2}}}{z^2} dz$$

$$\frac{1}{z} = y$$

$$= A \int e^{-\frac{c\rho}{4k} y^2} dy = A \int e^{-\frac{c\rho}{4k} y^2} dy + \text{const}$$

$$\frac{\partial \theta}{\partial t} = -e^{-\frac{c\rho}{4k} \frac{x^2}{t}} \frac{x^2}{2\sqrt{t}^3}$$

$$\frac{\partial \theta}{\partial x} = -\frac{c\rho}{4k} \frac{x}{\sqrt{t}} \frac{1}{\sqrt{t}}$$

$$\frac{\partial^2 \theta}{\partial x^2} = \frac{c\rho}{4k} \left[ \frac{1}{\sqrt{t}} + \frac{x^2}{t^2} \right]$$

$$\frac{\partial^2 \theta}{\partial x^2} = \frac{c\rho}{4k} \frac{2x}{\sqrt{t}^3} e^{-\frac{c\rho}{4k} \frac{x^2}{t}}$$



Ilon' cipele puev de ougo

237

mauzos

$$\frac{0.000066 \cdot 100}{0.8} \cdot 35 = \frac{0.231}{0.8} = 0.3 \frac{\text{g Cal}}{\text{sec}} = \text{~~18~~ } 18 \frac{\text{g Cal}}{\text{min}}$$

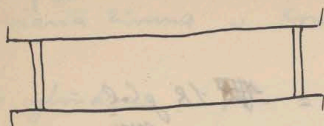
puev nkh.

$$\frac{0.001 \cdot 100}{0.8} \cdot 2 = 0.25 \frac{\text{g Cal}}{\text{sec}}$$

puev nkh' zihonq  $q = 10 \text{ mm}^2$

$$\frac{0.15 \cdot 100}{0.8} \cdot 0.1 = 2 \frac{\text{g Cal}}{\text{sec}}$$





$$\rho_0 (1 + \varepsilon \theta) \frac{d\theta}{dz} = \text{const} = a$$

$$\rho_0 \theta + \rho_0 \varepsilon \frac{\theta^2}{2} = az + \text{const}$$

$$\rho_0 \theta_0 + \rho_0 \varepsilon \theta^2 \quad z=0 : \quad \theta=0 \quad \text{const} = 0$$

~~$$\rho_0 \theta + \rho_0 \varepsilon \frac{\theta^2}{2} = az$$~~

$$\rho_0 \theta \left[ 1 + \varepsilon \frac{\theta}{2} \right] = az$$

$$\rho_0 \theta_1 \left[ 1 + \varepsilon \frac{\theta_1}{2} \right] = ah$$

$$\theta \left( 1 + \varepsilon \frac{\theta}{2} \right) = \frac{z}{h} \theta_1 \left( 1 + \varepsilon \frac{\theta_1}{2} \right)$$

$$\text{N.p. } z = \frac{h}{2} \quad \theta \left( 1 + \varepsilon \frac{\theta}{2} \right) = \frac{1}{2} \theta_1 \left( 1 + \varepsilon \frac{\theta_1}{2} \right)$$

~~$$\left( \frac{\theta}{2} - \frac{\theta_1}{2} \right) + \frac{\varepsilon}{2} \left( \frac{\theta^2}{2} - \frac{\theta_1^2}{2} \right) = 0$$~~

$$\underbrace{\theta - \frac{\theta_1}{2}}_0 + \frac{\varepsilon}{2} \left( \frac{\theta^2}{2} - \frac{\theta_1^2}{2} \right) = 0$$

$$\int \theta dz = \int_0^{\theta_1} \frac{\theta \rho_0 (1 + \varepsilon \theta)}{a} d\theta = \frac{\rho_0}{a} \left( \frac{\theta^2}{2} + \varepsilon \frac{\theta^3}{3} \right) = \frac{\rho_0}{a} \frac{\theta^2}{2} \left[ 1 + \frac{2\varepsilon}{3} \theta \right] \Big|_0^{\theta_1}$$

$$= h \frac{\frac{\theta_1^2}{2} \left[ 1 + \frac{2\varepsilon}{3} \theta_1 \right]}{\theta_1 \left[ 1 + \varepsilon \frac{\theta_1}{2} \right]} = \frac{h}{2} \theta_1 \left[ 1 + \frac{1}{6} \varepsilon \theta_1 \right] \quad \text{wzgl. równica } \left( \frac{1}{6} \varepsilon \theta \right) \text{ od średniej temp.}$$

$$\text{N.p. } \varepsilon = \frac{1}{273} = 0.0036$$

$$\theta_1 = 100$$

$$\frac{\varepsilon \theta_1}{6} = 0.06 = 6\%$$

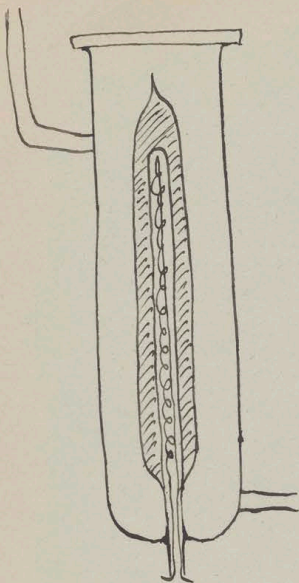
wzgl. temperatura  $53^\circ\text{C}$   
wynika od średniej  $50^\circ$

Temperatura różnica w ciśnieniu lub objętości  $\frac{2}{273} = \frac{1}{90}$

t.j. 8 mm Hg = ~~80~~ 87 mm słupowy



8700 cm



$$K \cdot \frac{30 \text{ cm}^2}{1 \text{ cm}} \theta = 50$$

$$K_{\text{H}_2\text{O}} = 0.0015$$

glas

$$0.045 \cdot 50 = 2.5$$

$$K_{\text{Luft}} = 0.00006$$

$$0.0018 \cdot 50 = 0.09$$

$$1 \text{ Volt Ampere} = 0.24 \frac{\text{g cal}}{\text{sec}}$$

$$10 \text{ --- } 0.3 \text{ Volt}$$

$$i^2 R = \frac{e^2}{R}$$

$$R = 2 \text{ Ohm}$$

$$i^2 = 5 \text{ --- } 0.15$$

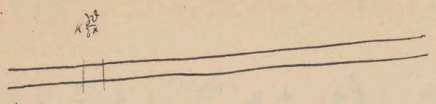
$$i = 4 \text{ --- } 0.4 \text{ Amp}$$







2. a) ...  
2. b) ...



$i = 0.2 \text{ pro cm}^2$

$$\begin{aligned} \varphi = i^2 x &= \frac{i^2}{\lambda_0} = -\frac{\partial}{\partial x} \left( k \frac{\partial \theta}{\partial x} \right) \\ &= -\frac{dk}{dx} \frac{d\theta}{dx} - k \frac{d^2 \theta}{dx^2} \\ &= -\frac{dk}{d\theta} \left( \frac{d\theta}{dx} \right)^2 - k \frac{d^2 \theta}{dx^2} \end{aligned}$$

$$\begin{aligned} k &= k_0 (1 + \alpha \theta) \\ \lambda &= \lambda_0 (1 + \beta \theta) \end{aligned}$$

1. a) ...  $k = k_0$

$$\frac{i^2}{\lambda} = -\lambda_0 (1 + \beta \theta) k_0 \frac{d^2 \theta}{dx^2}$$

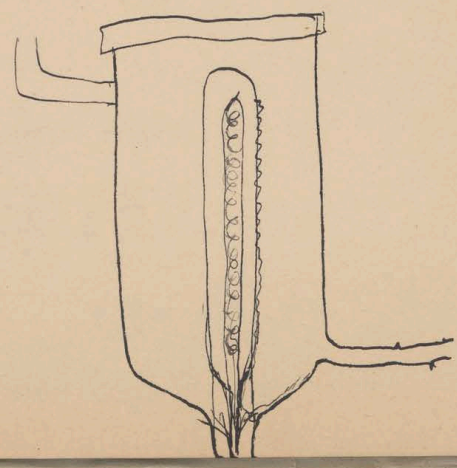
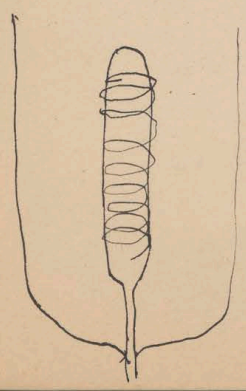
1. b) ...  $i^2 = -\lambda_0 k_0 \frac{d^2 \theta}{dx^2}$

$$\theta = \theta_0 - \frac{i^2}{\lambda_0 k_0} x^2 + \frac{i^2}{\lambda_0 k_0} x l$$

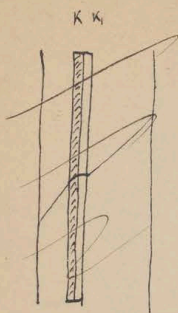
1. c) ...  $\theta_0 = 0$

$$W = \int \frac{dx}{\lambda_0} = \int \frac{dx}{\lambda_0 (1 + \beta \theta_0 + \beta \frac{i^2}{\lambda_0 k_0} l x - \beta \frac{i^2}{\lambda_0 k_0} x^2)} = \frac{1}{\lambda_0} \int \frac{dx}{1 + \frac{\beta i^2 l}{\lambda_0 k_0} x - \frac{\beta i^2}{\lambda_0 k_0} x^2}$$

$$= \frac{1}{\lambda_0} \frac{1}{1 - \sqrt{\frac{\beta}{\lambda_0 k_0}} i x}$$







$$\frac{c}{A} f(r) \frac{\partial \theta}{\partial x} = R f(r) \frac{\partial \theta}{\partial x} - W \frac{\partial \mu}{\partial x} + \mu \left( \frac{\partial u}{\partial r} \right)^2 + K \frac{1}{2} \frac{\partial}{\partial r} \left( R \frac{\partial \theta}{\partial r} \right)$$

$$\left( \frac{c}{A} - R \right) f(r) \frac{\partial \theta}{\partial x} = - \frac{W}{\rho} \frac{\partial \mu}{\partial r} f(r) + \mu \left( \frac{\partial u}{\partial r} \right)^2 + K \frac{1}{2} \frac{\partial}{\partial r} \left( R \frac{\partial \theta}{\partial r} \right)$$

$$- \frac{1}{2} (x+y+z)^2 + 3[x^2+y^2+z^2]$$

$$- 2(x+y+z) + 6x$$

$$4x - 2y - 2z$$

$$2x^2 + 2xy + 2y^2 + 2z^2 - 2xz - 2xy$$

$$-(1+\alpha+\beta)^2 + 3[1+\alpha^2+\beta^2]$$

$$= 2[1 + \alpha^2 + \beta^2 - \alpha - \beta - \alpha\beta]$$

$$= [(\alpha-\beta)^2 + (1-\alpha)^2 + (1-\beta)^2]$$

$$\left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right)^2 + \dots = \left( \frac{\partial u}{\partial x} \right)^2 +$$



$$\frac{\partial w}{\partial t} + w \frac{\partial w}{\partial z} = \frac{\mu}{\rho} \left[ \frac{4}{3} \frac{\partial^2 w}{\partial z^2} + \frac{\partial w}{\partial z^2} + \frac{1}{2} \frac{\partial w}{\partial z} \right] - \frac{1}{\rho} \frac{\partial p}{\partial z}$$

$$\frac{\rho}{A} w \frac{\partial \theta}{\partial z} = -\mu \frac{\partial w}{\partial z} + \mu \left[ -\frac{2}{3} \left( \frac{\partial w}{\partial z} \right)^2 + 2 \left( \frac{\partial w}{\partial z} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 \right] + \kappa \underbrace{\frac{1}{2} \frac{\partial}{\partial z} \left( r \frac{\partial \theta}{\partial z} \right)}_{\frac{r}{2} \frac{\partial^2 \theta}{\partial z^2} + \frac{1}{2} r \frac{\partial \theta}{\partial z}}$$

$$\theta, \rho, w = f_c(r, z)$$

$$\frac{\mu}{\rho} = R\theta$$

$$(\rho w) = f_c(r)$$

$$\frac{\partial p}{\partial x} = \mu \left( \frac{\partial^2 w}{\partial z^2} + \frac{1}{2} \frac{\partial w}{\partial z} \right)$$

$$\rho w = f_c(r)$$

$$\frac{\partial}{\partial x} (\rho w) = 0$$

$$\frac{\mu}{\rho} = R\theta$$

$$\frac{\rho}{A} w \frac{\partial \theta}{\partial x} = -\mu \frac{\partial w}{\partial x} + \mu \left( \frac{\partial w}{\partial z} \right)^2 + \kappa \underbrace{\left( \frac{\partial^2 \theta}{\partial z^2} + \frac{1}{2} \frac{\partial \theta}{\partial z} \right)}_{\frac{1}{2} \frac{\partial \theta}{\partial z}}$$

$$p = f_c(x)$$

$$\frac{\partial}{\partial z} \left( \frac{\partial u}{\partial z} + \frac{1}{2} \frac{\partial u}{\partial z} \right) = 0$$

$$R \frac{\partial \theta}{\partial x} = \frac{w}{f_c(x)} \frac{\partial p}{\partial x} - \mu \frac{\partial}{\partial x} \left( \frac{w}{f_c(x)} \right)$$

$$= \frac{w}{f_c(x)} \frac{\partial p}{\partial x} - \frac{\mu}{f_c(x)} \frac{\partial w}{\partial x}$$

$$\frac{\partial u}{\partial z} + \frac{1}{2} \frac{\partial u}{\partial z} = \varphi(x)$$

$$\frac{\partial}{\partial z} \left( \frac{3}{2} \frac{\partial u}{\partial z} \right) = 2 \varphi(x)$$

$$R f_c(x) \frac{\partial \theta}{\partial x} = w \frac{\partial p}{\partial x} - \mu \frac{\partial w}{\partial x}$$

$$r \frac{\partial u}{\partial z} = \frac{r^2}{2} \varphi(x) + \psi(x)$$

$$u = \frac{r^2}{2} \varphi(x) + \psi(x) \log(r) + \chi(x)$$

$$u = \frac{r^2 - R^2}{2} \varphi(x) = \frac{r^2 - R^2}{2} \frac{1}{\mu} \frac{\partial p}{\partial x}$$

$$\rho \frac{r^2 - R^2}{2\mu} \frac{\partial p}{\partial x} = f_c(r)$$

$$\rho \frac{\partial p}{\partial x} = \frac{2\mu}{r^2 - R^2} f_c(r)$$



C, c mit Styr, Glycer, Nit, niki, reu! stemp!

Das geschlossene System ist ein stemp.

negativ.

elektrisch, oder einmengen?

und also keine für ~~passive~~ messen in der!

Unter kühler durch Drogen: Depote CR II Poff Am. XI

Leitungsmenge von Iden: Natrie Wied. 40 p. 18 (1890)

KCl der Andrews Endb. Pro. 1884/5 13 p. 275  
(in p. 1. 2. 3.) # KCl 2% 850°

Selbstkühlung in versch. Richt. M!, dann bei Druck bis zur Zerkleinerung

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Kann die Capillartatschente Eis-Wasser theilhaft bestehen?

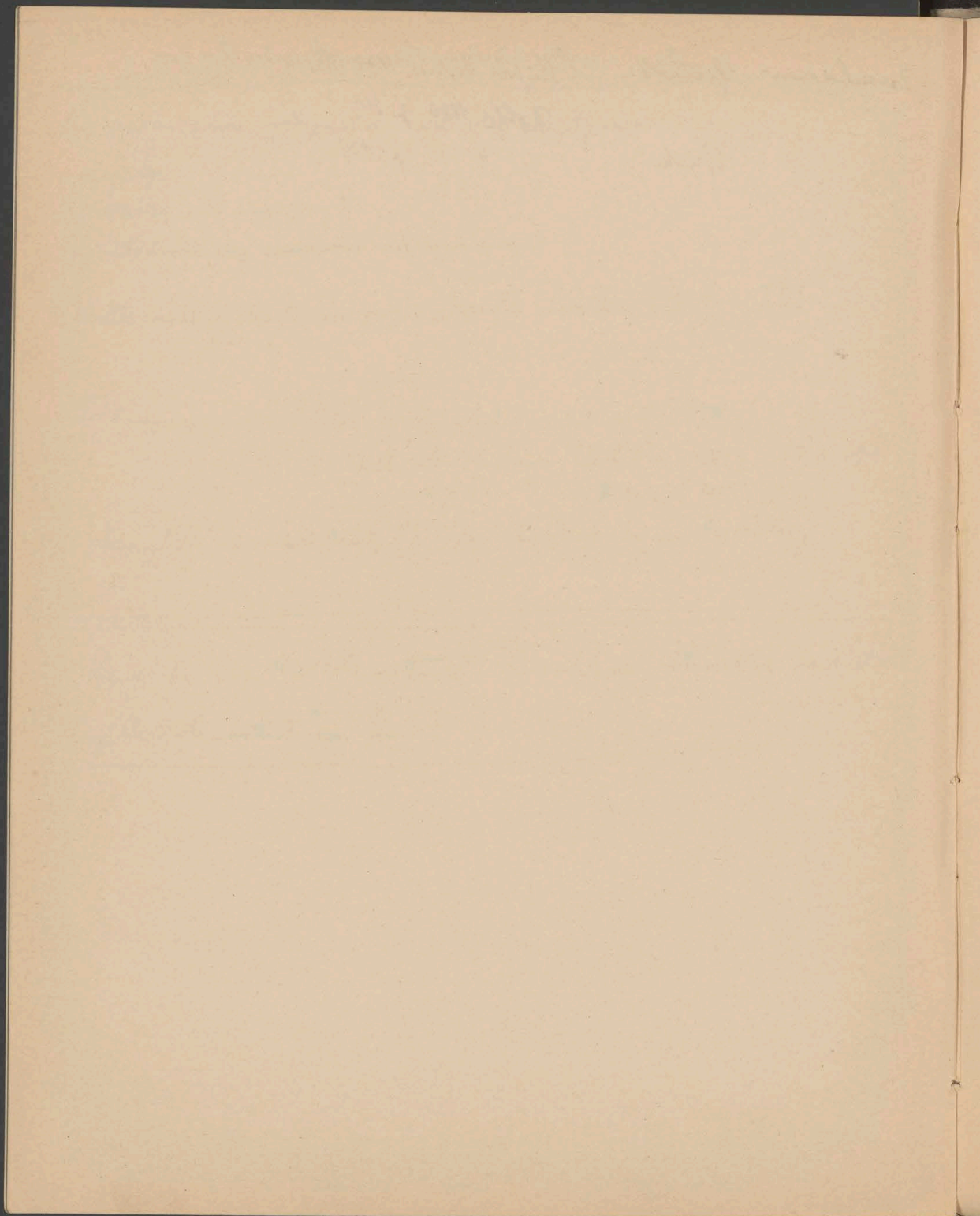
Capillartatschente von Eis?

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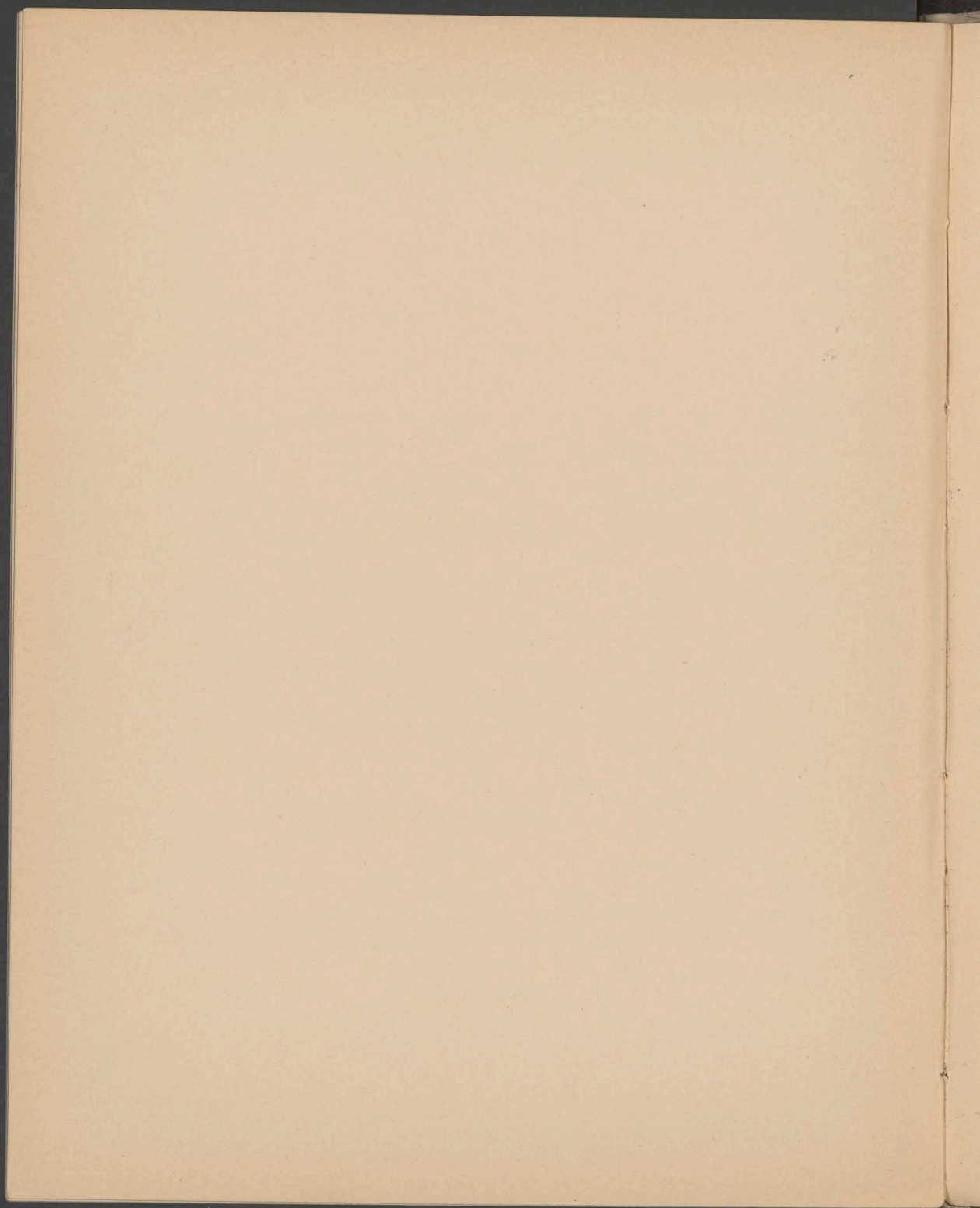
Emulsion: Grönke      Offici's Archiv 1879 Bd. 19  
Aobl. 1880 p. 140  
Dicks      " " p. 109





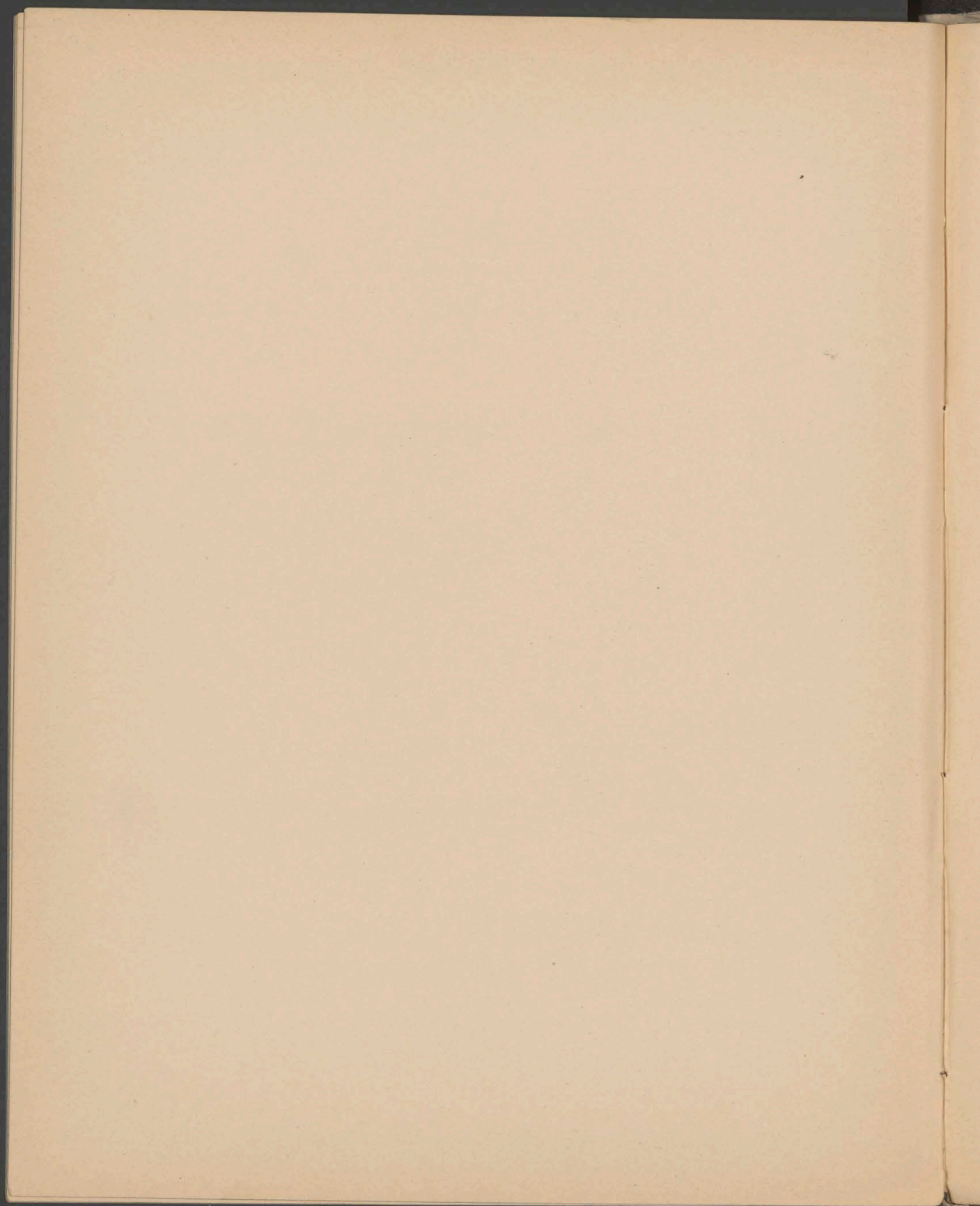






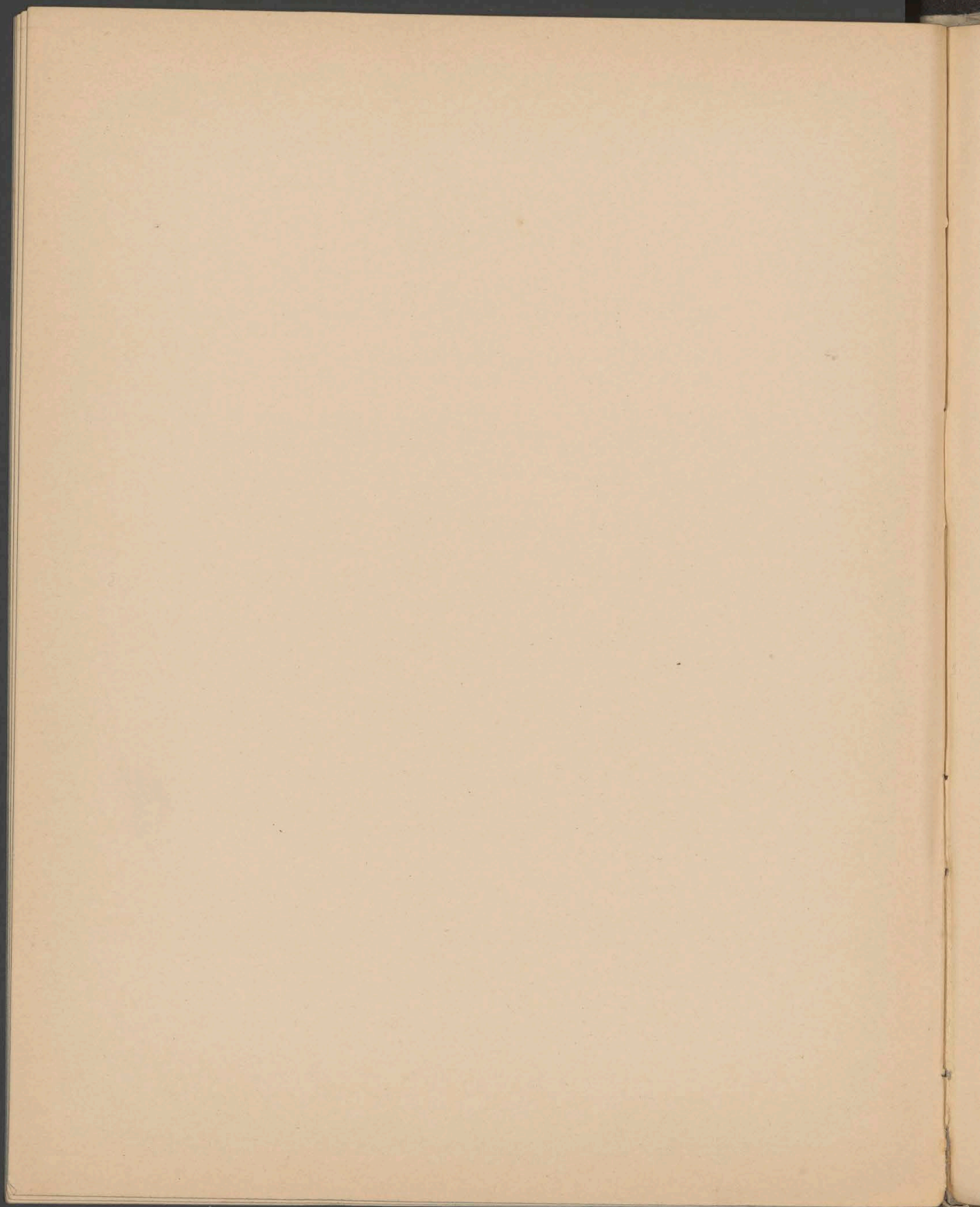






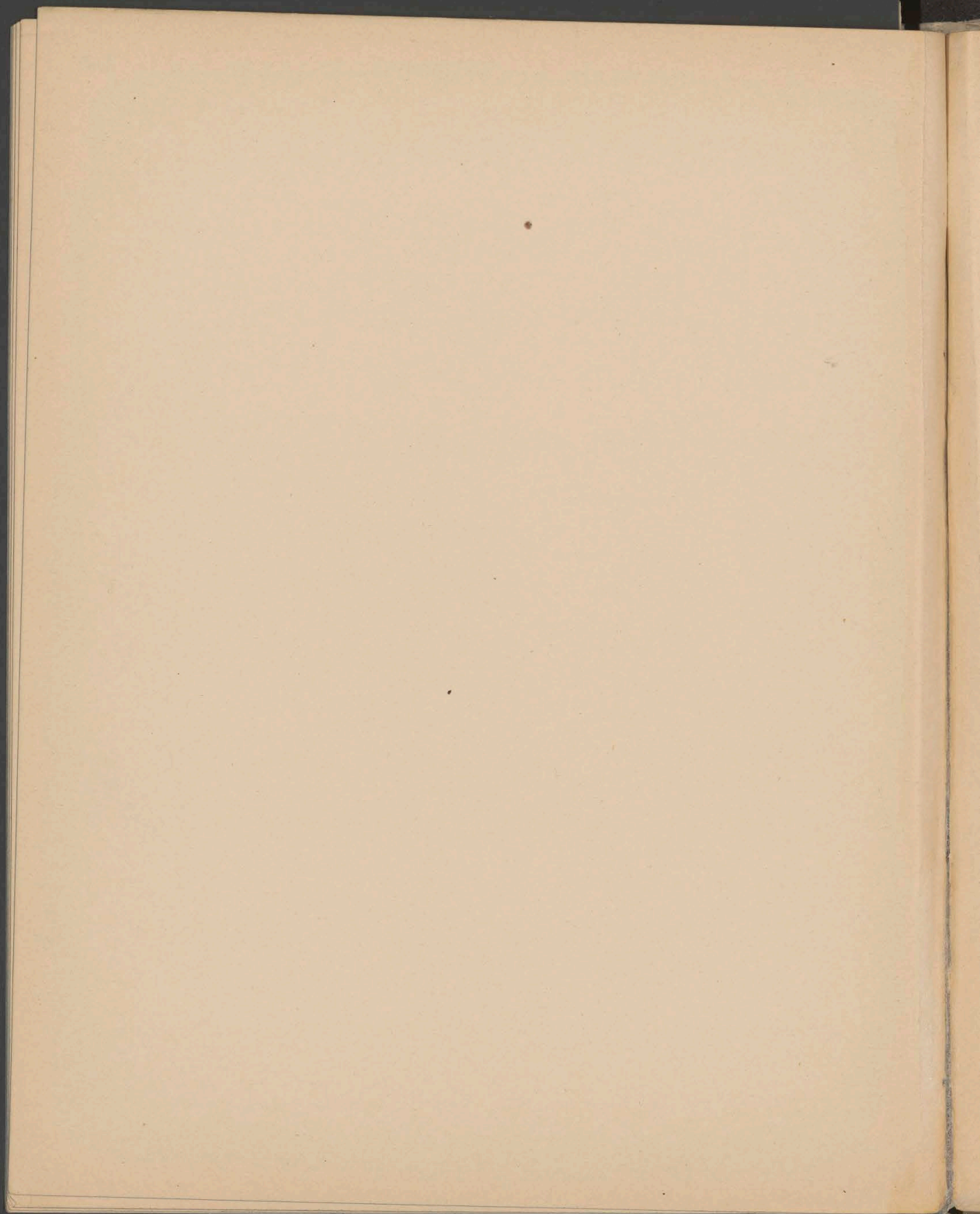






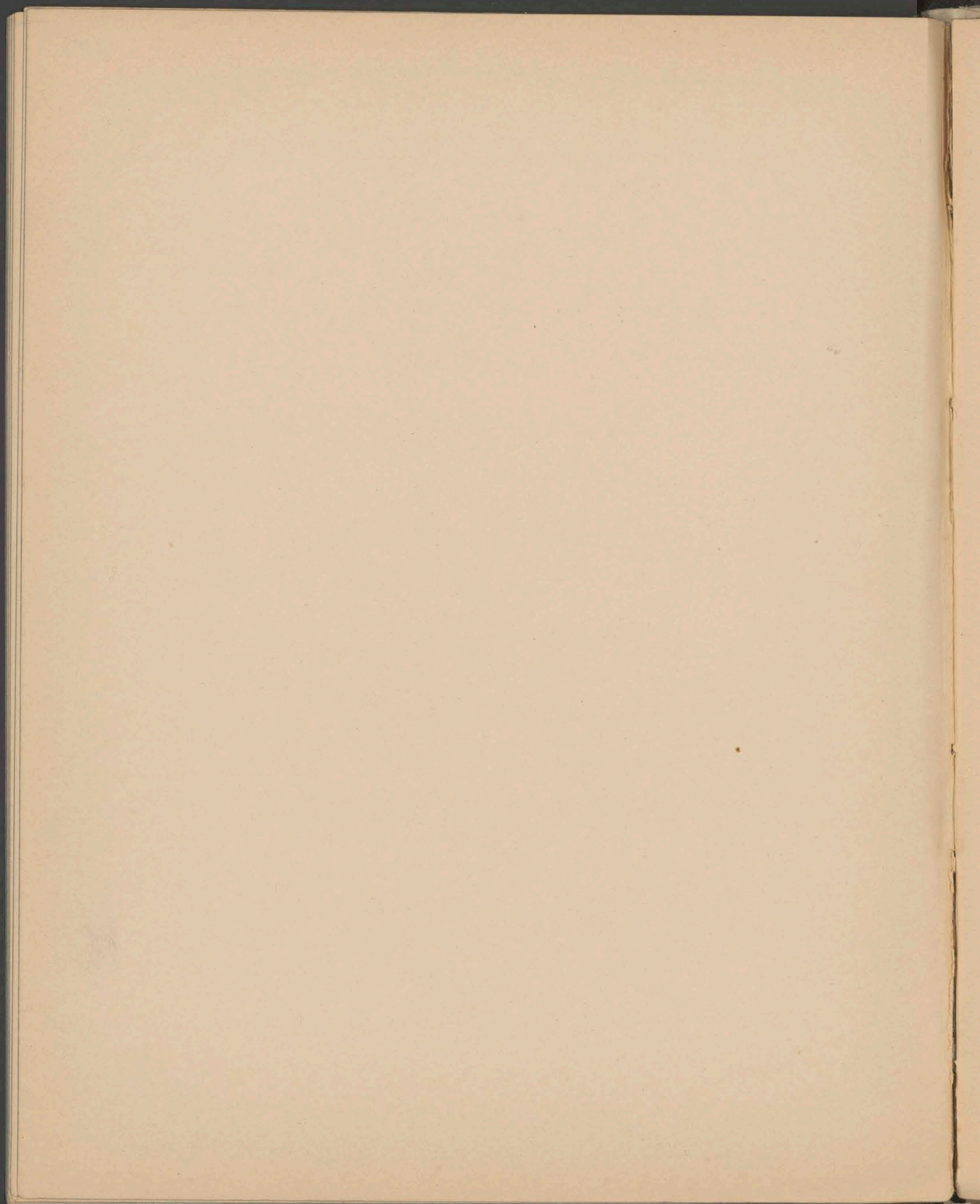


245



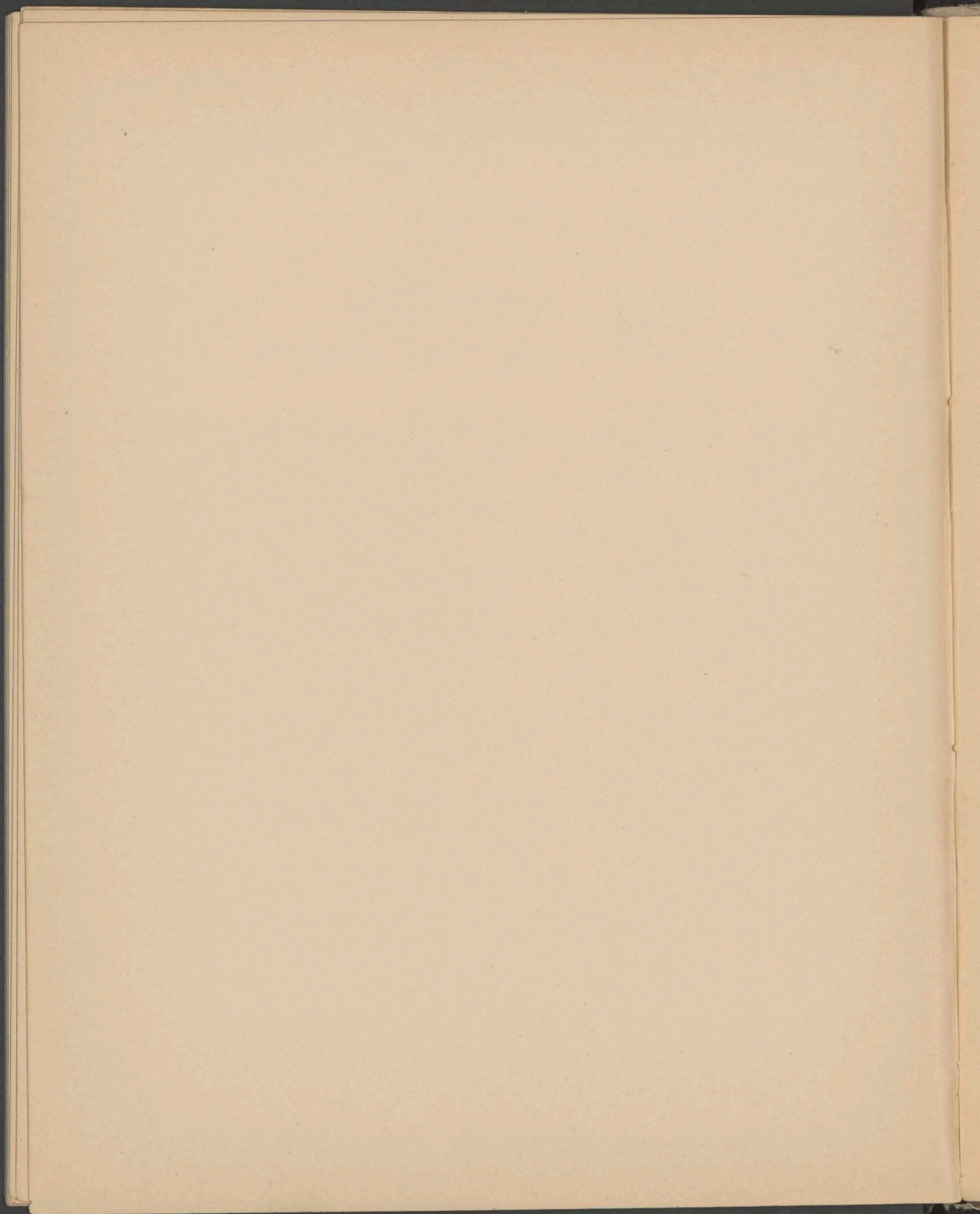






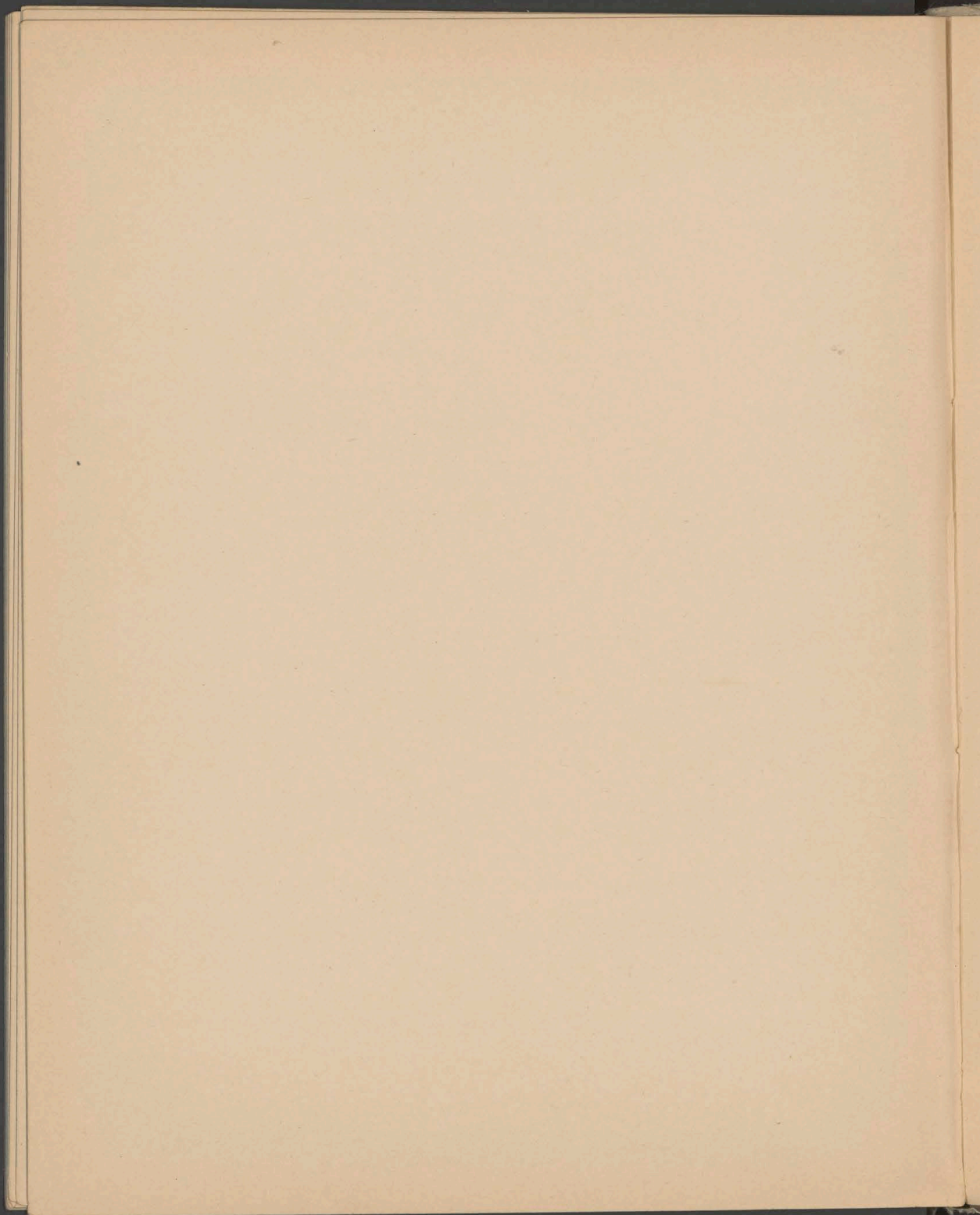






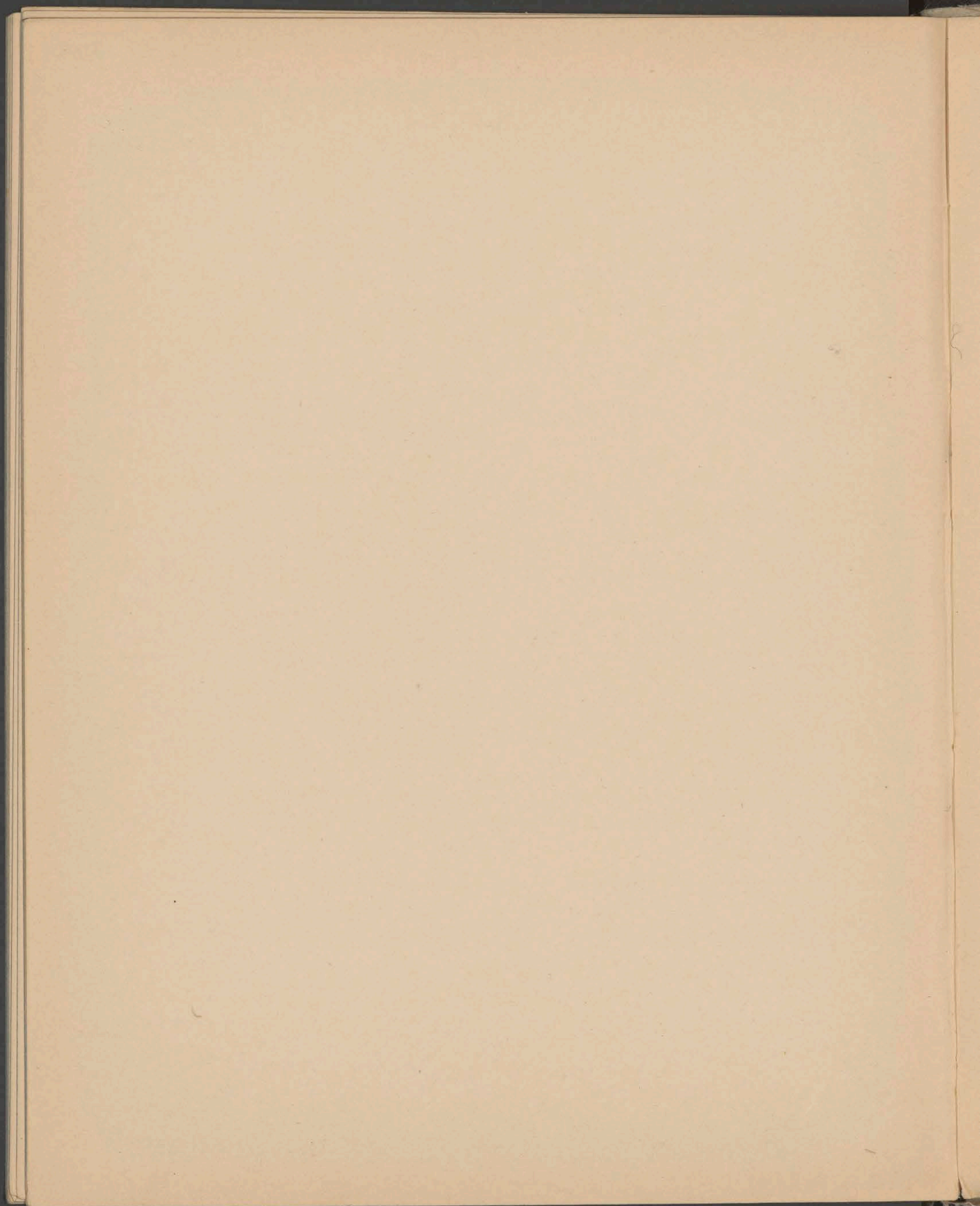
















Ths Am 67 p. 202 (1899) Adon long forest m. 10 58 1x 856.

1.  $\lambda = 20 \text{ cm}$   $\lambda = 20 \text{ cm}$

$\lambda = 20 \text{ cm}$

2.  $\lambda = 20 \text{ cm}$   $\lambda = 20 \text{ cm}$

$$\lambda = 20 \text{ cm}$$

$$\lambda = 20 \text{ cm}$$

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$$\lambda = 20 \text{ cm}$$

$\lambda = 20 \text{ cm}$

$\lambda = 20 \text{ cm}$

$\lambda = 20 \text{ cm}$



251

$\frac{7}{2} \cdot \frac{7}{2}$

1325

~~151584~~  
1116

$$\begin{array}{r} \cancel{8830} \\ 4468 \\ 0156 \\ \hline 4624 \end{array}$$

$$\frac{293}{273} = \frac{4518}{4262} \\ 0156$$

4000.0	28
200.0	28
800.0	28
820.0	0.00
482.0	0.00
85.4	0.0

Wm. Am. 67 1. 65 to 1859

[f m a / y e p d a x c h a  
[2] 27. 2. 1902]

$$x^2 + y^2 + z^2 = r^2$$

$$7 \text{ lb} = \frac{1}{7} \text{ lb}$$

$$2x = \frac{2xg}{2xg}$$

$$f(x) = \frac{x^2 + 2x + 1}{x^2}$$

$12 \times 10 = 120$

$$Ed. 5 (e + g + v) = 17 \text{ n'}$$

Ans:  $C_1 = 0$  and  $C_2 = 1$   
 $y = \ln x$

$$\left[ c_v = 0.98835 \frac{J}{g} \right] = \frac{1}{5.93} \frac{J}{g} = \alpha = 0.16861$$

$$\mu_{\text{eff}} = \frac{1}{\frac{1}{\mu_1} + \frac{1}{\mu_2} + \frac{1}{\mu_3}} = 1 \quad \text{und} \quad \frac{1}{\mu_{\text{eff}}} = 1$$

1.670 ① *Atropa* var. *longa*, 2/12 Aug, 1967

St. Paulin  
July 22 to 24

[illegible]

gung manna g = 8 kxc 2 f

Gray v (9-28) C 24

27. 9 3 = 10 17. 27

$\sum m_2 \ell^2 \omega^2 = 36$

3C

4. 22.3.22

9-4C

17. 2. 18. 19. 20. 21. 22. 23. 24. 25. 26. 27. 28. 29. 30. 31. 32. 33. 34. 35. 36. 37. 38. 39. 40. 41. 42. 43. 44. 45. 46. 47. 48. 49. 50. 51. 52. 53. 54. 55. 56. 57. 58. 59. 60. 61. 62. 63. 64. 65. 66. 67. 68. 69. 70. 71. 72. 73. 74. 75. 76. 77. 78. 79. 80. 81. 82. 83. 84. 85. 86. 87. 88. 89. 90. 91. 92. 93. 94. 95. 96. 97. 98. 99. 100. 101. 102. 103. 104. 105. 106. 107. 108. 109. 110. 111. 112. 113. 114. 115. 116. 117. 118. 119. 120. 121. 122. 123. 124. 125. 126. 127. 128. 129. 130. 131. 132. 133. 134. 135. 136. 137. 138. 139. 140. 141. 142. 143. 144. 145. 146. 147. 148. 149. 150. 151. 152. 153. 154. 155. 156. 157. 158. 159. 160. 161. 162. 163. 164. 165. 166. 167. 168. 169. 170. 171. 172. 173. 174. 175. 176. 177. 178. 179. 180. 181. 182. 183. 184. 185. 186. 187. 188. 189. 190. 191. 192. 193. 194. 195. 196. 197. 198. 199. 200. 201. 202. 203. 204. 205. 206. 207. 208. 209. 210. 211. 212. 213. 214. 215. 216. 217. 218. 219. 220. 221. 222. 223. 224. 225. 226. 227. 228. 229. 230. 231. 232. 233. 234. 235. 236. 237. 238. 239. 240. 241. 242. 243. 244. 245. 246. 247. 248. 249. 250. 251. 252. 253. 254. 255. 256. 257. 258. 259. 260. 261. 262. 263. 264. 265. 266. 267. 268. 269. 270. 271. 272. 273. 274. 275. 276. 277. 278. 279. 280. 281. 282. 283. 284. 285. 286. 287. 288. 289. 290. 291. 292. 293. 294. 295. 296. 297. 298. 299. 300. 301. 302. 303. 304. 305. 306. 307. 308. 309. 310. 311. 312. 313. 314. 315. 316. 317. 318. 319. 320. 321. 322. 323. 324. 325. 326. 327. 328. 329. 330. 331. 332. 333. 334. 335. 336. 337. 338. 339. 340. 341. 342. 343. 344. 345. 346. 347. 348. 349. 350. 351. 352. 353. 354. 355. 356. 357. 358. 359. 360. 361. 362. 363. 364. 365. 366. 367. 368. 369. 370. 371. 372. 373. 374. 375. 376. 377. 378. 379. 380. 381. 382. 383. 384. 385. 386. 387. 388. 389. 390. 391. 392. 393. 394. 395. 396. 397. 398. 399. 400. 401. 402. 403. 404. 405. 406. 407. 408. 409. 410. 411. 412. 413. 414. 415. 416. 417. 418. 419. 420. 421. 422. 423. 424. 425. 426. 427. 428. 429. 430. 431. 432. 433. 434. 435. 436. 437. 438. 439. 440. 441. 442. 443. 444. 445. 446. 447. 448. 449. 450. 451. 452. 453. 454. 455. 456. 457. 458. 459. 460. 461. 462. 463. 464. 465. 466. 467. 468. 469. 470. 471. 472. 473. 474. 475. 476. 477. 478. 479. 480. 481. 482. 483. 484. 485. 486. 487. 488. 489. 490. 491. 492. 493. 494. 495. 496. 497. 498. 499. 500. 501. 502. 503. 504. 505. 506. 507. 508. 509. 510. 511. 512. 513. 514. 515. 516. 517. 518. 519. 520. 521. 522. 523. 524. 525. 526. 527. 528. 529. 530. 531. 532. 533. 534. 535. 536. 537. 538. 539. 540. 541. 542. 543. 544. 545. 546. 547. 548. 549. 550. 551. 552. 553. 554. 555. 556. 557. 558. 559. 560. 561. 562. 563. 564. 565. 566. 567. 568. 569. 570. 571. 572. 573. 574. 575. 576. 577. 578. 579. 580. 581. 582. 583. 584. 585. 586. 587. 588. 589. 590. 591. 592. 593. 594. 595. 596. 597. 598. 599. 600. 601. 602. 603. 604. 605. 606. 607. 608. 609. 610. 611. 612. 613. 614. 615. 616. 617. 618. 619. 620. 621. 622. 623. 624. 625. 626. 627. 628. 629. 630. 631. 632. 633. 634. 635. 636. 637. 638. 639. 640. 641. 642. 643. 644. 645. 646. 647. 648. 649. 650. 651. 652. 653. 654. 655. 656. 657. 658. 659. 660. 661. 662. 663. 664. 665. 666. 667. 668. 669. 670. 671. 672. 673. 674. 675. 676. 677. 678. 679. 680. 681. 682. 683. 684. 685. 686. 687. 688. 689. 690. 691. 692. 693. 694. 695. 696. 697. 698. 699. 700. 701. 702. 703. 704. 705. 706. 707. 708. 709. 710. 711. 712. 713. 714. 715. 716. 717. 718. 719. 720. 721. 722. 723. 724. 725. 726. 727. 728. 729. 730. 731. 732. 733. 734. 735. 736. 737. 738. 739. 740. 741. 742. 743. 744. 745. 746. 747. 748. 749. 750. 751. 752. 753. 754. 755. 756. 757. 758. 759. 760. 761. 762. 763. 764. 765. 766. 767. 768. 769. 770. 771. 772. 773. 774. 775. 776. 777. 778. 779. 780. 781. 782. 783. 784. 785. 786. 787. 788. 789. 790. 791. 792. 793. 794. 795. 796. 797. 798. 799. 800. 801. 802. 803. 804. 805. 806. 807. 808. 809. 810. 811. 812. 813. 814. 815. 816. 817. 818. 819. 820. 821. 822. 823. 824. 825. 826. 827. 828. 829. 830. 831. 832. 833. 834. 835. 836. 837. 838. 839. 840. 841. 842. 843. 844. 845. 846. 847. 848. 849. 850. 851.

1/2 in cond.  $\sigma = 0 \sim \infty$  - Redf - var. - a/bly at

$$d \approx \text{const.} \sim \sigma^2 \sim \sigma \ll \delta \ll 2.0 \sim 10^{12} \sim \sigma = a + 2 + \sim$$

$$\frac{r}{r+r} = r$$

$\theta = 5 : H_2, O_2, N_2, CO, NO, HCl, HCN, H_2O$

$$= f : \alpha_2, \alpha_1, \gamma_1, \gamma_2, \omega_2, \omega_1, \nu_2, \nu_1, \mu_2, \mu_1, \lambda_2, \lambda_1, \kappa_2, \kappa_1, \eta_2, \eta_1, \zeta_2, \zeta_1, \beta_2, \beta_1$$

$\frac{v}{v'} = \frac{s}{s'}$

$\frac{2}{\sqrt{3}, C H_2}$  (i)  $\frac{a}{b} = 6$   $\frac{a}{b} = 0$   
 $\frac{1}{2} \sqrt{3} \sin \theta = \frac{1}{2} \sqrt{3} \sin \theta + \frac{1}{2} \sqrt{3} \sin \theta$



$$\frac{1}{\gamma} \frac{d\gamma}{d\theta} = \frac{1}{\gamma} \frac{\partial \gamma}{\partial \theta} + \left( \frac{v}{\gamma} \frac{\partial \gamma}{\partial v} \right) \cdot \left( \frac{\partial v}{\partial \theta} \frac{1}{v} \right)$$

$$= \frac{1}{\gamma} \frac{\partial \gamma}{\partial \theta} + \frac{1}{v} \frac{\partial v}{\partial \theta}$$

$$= \frac{\partial \gamma}{\partial \theta} \cdot \frac{\alpha}{\beta}$$

At  $\theta = 20^\circ$ :  $\frac{1}{\gamma} \frac{\partial \gamma}{\partial \theta} = 7.30 \cdot 10^{-4}$  / Ormed  $9.3 \cdot 10^{-4}$

f. Schurph

$$\begin{array}{r} 1.1139 \\ 2.4116 \\ - 3.5255 \\ + 1.5185 \\ \hline 0.9930 - 3 \end{array}$$

$$0.0098$$

$$\frac{1}{\gamma} \frac{d\gamma}{d\theta} =$$

$$\begin{array}{r} 0.001278 \\ 2.45 \\ \hline 33 \end{array}$$

for  $185^\circ$

$$: 13.258$$

Surgeat

$$\begin{array}{r} 254 \\ 13.5 \\ \hline 178 \end{array} \cdot 10^{-6} \quad \begin{array}{r} 190 \\ 168 \\ \hline 178 \end{array} \cdot 10^{-6} \quad \begin{array}{r} 178 \\ \hline 178 \end{array} \cdot 10^{-6} \quad (1.1)$$

$$\alpha = \begin{array}{r} 0.00148 \\ 13 \\ \hline 0.00161 \end{array}$$

$$\begin{array}{r} 350.12 \\ 105 \\ 11.91 \\ \hline 11.91 \end{array} \quad \begin{array}{r} 35.37 \\ 105 \\ 245 \\ \hline 1295 \end{array}$$

$$0.00739$$

$$561$$

$$178 : 18.645$$

$$pi \ 210$$

$$\begin{array}{r} 2.8096 \\ 1.2553 \\ - 4.0649 \\ + 2.2504 \\ \hline 0.1855 - 2 \end{array}$$

$$0.0153$$

$$\begin{array}{r} 6 : 83.0 \\ 15.4 : 87.1 \\ 17.9 : 91.7 \\ 50 : 111 \end{array}$$

$$94$$

$$90$$

$$92 \cdot 10^{-6}$$

$$\begin{array}{r} 0.00116 \\ 0.00008 \\ \hline 0.00124 \end{array}$$

$$\begin{array}{r} 9.3 \cdot 10^{-4} \cdot 0.00124 \\ \hline 0.92 \cdot 10^{-4} \end{array}$$

$$\begin{array}{r} 0.0125 \\ + 0.0018 \\ \hline 0.0107 \end{array}$$

$$0.0153 \text{ m.}$$

$$\begin{array}{r} 0.0018 \\ * 0.0066 \\ - 0.0048 \\ \hline 0.0098 \end{array}$$

$$\begin{array}{r} 7.3 \cdot 10^{-4} \cdot 0.0016 \\ \hline 1.78 \cdot 10^{-4} \end{array}$$

$$\begin{array}{r} 73 \\ 438 \\ \hline 1168 : 1.78 = 656 \end{array}$$

$$\text{Benzol} \quad \frac{286. (0.00116)^2 \cdot 39}{R} \quad 0.892$$

$$\begin{array}{r} 0645.2 \\ 0.1290 - 6 \\ 2.4564 \\ 1.5911 \\ \hline 0.1765 - 2 \end{array}$$

$$\begin{array}{r} 0.9504 - 1 \\ 6.5939 \\ \hline 6.5443 \end{array}$$

$$\text{dr. } 4.288 \cdot 10^{-9}$$

$$\begin{array}{r} - 6.5443 \\ \hline 0.6322 - 9 \end{array}$$

$$\text{zn. } 83 \cdot 10^{-11}$$

$$\text{Alk.} \quad \frac{293. (0.00111)^2 \cdot 23}{R} \quad 0.794$$

$$\begin{array}{r} 0.0453 - 3^2 \\ 0.0906 - 6 \\ 2.4669 \\ 1.3617 \\ \hline 0.4061 - 7 \end{array}$$

$$\begin{array}{r} - 6.5939 \\ \hline = 0.4061 - 7 \end{array}$$

$$2.66 \cdot 10^{-9}$$

$$\begin{array}{r} 0.3253 - 11.9 \\ - 0.8998 - 1 \\ \hline 0.4255 - 12.9 \end{array}$$

$$1. \cdot 10^{-10}$$

$$\text{Hg:} \quad \frac{273. (\frac{1}{550})^2 \cdot 100}{R} \quad 12.6$$

$$\begin{array}{r} 2.7404 \\ 5.4808 \\ 1.1335 \\ 6.4434 \\ \hline 13.0577 \end{array} \quad \begin{array}{r} 2.4362 \\ - 13.0577 \\ \hline 0.3785 - 11 \end{array}$$

$$2.39 \cdot 10^{-11}$$

$$\text{zn.} \quad 3.9 \cdot 10^{-12}$$

$$\text{Pent.} \quad \frac{288. (0.00159)^2 \cdot 36}{R} \quad 0.626$$

$$1.51 \cdot 10^{-8}$$

$$\text{zn.} \quad 2.9 \cdot 10^{-10}$$

$$\begin{array}{r} 0.2014 - 3.2 \\ 0.4028 - 6 \\ 1.5563 \\ 2.4594 \\ \hline 0.4185 - 2 \\ - 6.2400 \\ \hline 0.1785 - 8 \end{array}$$

$$\begin{array}{r} 0.7966 - 1 \\ 6.4434 \\ \hline 6.2400 \end{array}$$



$$\beta = -\frac{\alpha^2 \theta}{\sqrt{2} R \rho} = -\frac{\alpha^2 \theta}{\sqrt{2} \cdot \mu} \left(\frac{\mu}{\rho}\right)$$

$$\alpha = 0.00116$$

Desol. ca 130

$$\mu = 78, \rho = 0.892$$

$$\rho = 0.000085$$

$$0.00170$$

$$\text{Atkin } 0.50$$

$$\mu = 74, \rho = 0.736$$

$$0.000189$$

$$0.00111$$

$$\text{LS } 0.40$$

$$\mu = \frac{46}{2}$$

$$\rho = 0.794$$

$$0.000100$$

$$\text{Petroleum } 0.00099$$

$$0.000069$$

$$\rho = 0.76$$

$$\text{Renta } 0.00159$$

0.300

$$0.000292$$

$$\mu = \frac{72}{2}$$

$$\rho = 0.6263$$

$$98\% \text{ H}_2\text{SO}_4 : 0.00055 = \alpha$$

$$\beta = 0.0000462 \cdot 0.730$$

$$\rho = 1841$$

$$3.3726 \cdot 10^{-11}$$

$$\mu = \frac{32}{64}$$

$$R = \frac{\mu}{\rho}$$

$$= \frac{98}{2}$$

$$\text{Hy: } \frac{1}{5500}$$

$$(\text{Ampt}) 0.0000039$$

$$\rho = 13.6$$

$$\mu = \frac{200}{2}$$

$$\frac{1000}{\rho} = \frac{1116}{4362}$$

$$R = \frac{1116}{4362} \cdot 0.001293 \cdot 278$$

$$9912$$

$$5478$$

$$4434$$

$$\frac{1116}{4362} = \frac{5478}{5478}$$

$$= 2.776 \cdot 10^6$$

$$\text{Hy } R = 6.4434$$

$$+ \text{Hy } R = 0.1505$$

$$6.5939$$

$$0.00055^2 \cdot 294.49$$

$$2.78 \cdot 10^6 \cdot 1.84 \cdot 1.42$$

$$121.25 \cdot 87725.49$$

$$3025.29$$

$$6050$$

$$27225$$

$$87725$$

$$350900$$

$$789525$$

$$42985$$

$$2.78 \cdot 1.84$$

$$2224$$

$$111$$

$$5115.142$$

$$20460$$

$$102$$

$$7263$$

$$42985 : 7263 = 5.918 \cdot 10^{-11}$$

$$6670$$

$$133$$

$$60$$

$$CO_2: \quad \begin{array}{r} 0.000196 \\ 188 \\ \hline 8 \end{array}$$

$$\begin{array}{r} 403 \\ 326 \\ \hline 77 \\ 2.3056 \\ \hline 8:188 = \\ 2.47 = 0.042 \\ 2.1247 = 0.033 \\ 28 \end{array}$$

$$7.7: 611 = 0.0126$$

5

$$R + \frac{a}{v} = \frac{R\theta\sqrt{2}}{v-v_0}$$

$$1 - \frac{2a}{v^3} \frac{\partial v}{\partial \theta} = -\frac{R\theta\sqrt{2}}{(v-v_0)^2} \frac{\partial v}{\partial \theta}$$

$$\frac{\partial \theta}{\partial \theta} = \frac{1}{\frac{2a}{v^3} - \frac{R\theta\sqrt{2}}{(v-v_0)^2}}$$

$$= \frac{1}{\frac{2R\theta\sqrt{2}}{v(v-v_0)} - \frac{R\theta\sqrt{2}}{(v-v_0)^2}} = \frac{(v-v_0)^2}{\sqrt{2}R\theta} \left[ \frac{v}{2(v-v_0) - v} \right]$$

$$= \frac{(v-v_0)^2 v}{\sqrt{2}R\theta (v-2v_0)} = \frac{v^2}{\sqrt{2}R\theta} \quad v-v_0 = \delta$$

$$\rho = \frac{1}{v} \frac{\partial v}{\partial \theta}$$

$$v\beta = -\frac{\delta^2 (v_0 + \delta)}{\sqrt{2}R\theta \sqrt{v}}$$

$$-\frac{2a}{v^3} \frac{\partial v}{\partial \theta} = \frac{R\sqrt{2}}{v-v_0} - \frac{R\theta\sqrt{2}}{(v-v_0)^2} \frac{\partial v}{\partial \theta}$$

$$v\beta = -\frac{\delta^2}{\sqrt{2}R\theta} \quad \text{sub. } \delta \quad v\alpha = \frac{\delta}{\theta}$$

$$\left[ -\frac{2a}{v^3} + \frac{R\theta\sqrt{2}}{(v-v_0)^2} \right] \frac{\partial v}{\partial \theta} = \frac{R\sqrt{2}}{v-v_0}$$

$$\beta = -\frac{\theta \alpha^2 v}{\sqrt{2}R}$$

$$\left[ -\frac{2R\theta\sqrt{2}}{(v-v_0)v} + \frac{R\theta\sqrt{2}}{(v-v_0)^2} \right] \frac{\partial v}{\partial \theta} = \uparrow$$

$$R\theta\sqrt{2} \left[ \frac{-2(v-v_0) + v}{2v(v-v_0)} \right] \frac{\partial v}{\partial \theta} = R\sqrt{2} \frac{v}{v(v-v_0)}$$

$$\beta = -\frac{\alpha^2 \theta}{\sqrt{2}R\theta}$$

$$\frac{\partial v}{\partial \theta} = \frac{\delta}{\theta} = \frac{v-v_0}{\theta}$$



$$\int_{-\infty}^{\infty} \frac{1}{(a^2 + y^2)^{n+1}} e^{-h(a^2 + y^2)} dy \dots$$

$$\int_{-\infty}^{\infty} e^{-hx^2} dx = \sqrt{\frac{\pi}{h}} \quad a \int_{-\infty}^{\infty} x^2 e^{-hx^2} dx = a \int_{-\infty}^{\infty} \frac{x^2}{-2h} \frac{d}{dx} e^{-hx^2} dx + \int_{-\infty}^{\infty} \frac{e^{-hx^2}}{2h} dx$$

$$= \frac{1}{2h} \sqrt{\frac{\pi}{h}}$$

$$2h \left( \sqrt{\frac{\pi}{h}} \right)^n$$

$$\int_{-\infty}^{\infty} e^{-h(x^2 + y^2)} dx dy = \left( \sqrt{\frac{\pi}{h}} \right)^n$$

$$\frac{c}{A} \frac{d\theta}{dx} + \frac{p}{b} \frac{du}{dx} = \frac{f_p}{b}$$

$$\frac{1}{p} \frac{dp}{dx} = -g$$

$$p u = b$$

$$\frac{p}{\rho} = R\theta$$

$$\frac{p}{\rho u} \frac{du}{dx} = R\theta \cdot \frac{1}{u} \frac{du}{dx}$$

$$= -R\theta \frac{1}{p} \frac{dp}{dx}$$

$$\left[ \bar{p} = \frac{p}{R\theta} \right]$$

$$= -\frac{1}{\rho} \left( \frac{1}{\theta} \frac{dp}{dx} - \frac{p}{\theta^2} \frac{d\theta}{dx} \right)$$

$$= -\frac{1}{\rho} \frac{dp}{dx} + \frac{p}{\rho \theta} \frac{d\theta}{dx}$$

$$= g + R \frac{d\theta}{dx}$$

$$\frac{k-1}{k} = \frac{2}{7}$$

$$d(p b) = p g u_0 = p g \frac{dx}{u_0} = dp$$

$$b p = R p \frac{d\theta}{dx} \frac{dx}{u_0}$$

$$\delta \varphi = \alpha \cdot \phi \cdot \delta x$$

$$= c \cdot p \cdot \delta x \cdot \frac{R}{u_0} \cdot \frac{k-1}{k}$$

$$\frac{\delta x}{\delta \varphi} = \frac{\alpha}{c} \frac{R}{g}$$

$$B = \frac{2 \cdot p \cdot g \cdot \theta}{\sqrt{2} \cdot p \cdot R}$$

$$\frac{42.16 \cdot 0.00033}{p_{10^2} \cdot 20} \cdot \frac{10^6}{10^3} \frac{1}{b}$$

$$= \frac{0.6 \cdot 10^3}{b} \text{ cm} =$$

$$= \frac{0.6 \cdot 10^3}{0.001 \cdot u} \text{ cm} = \frac{6 \cdot 10^5}{u}$$

$$= \frac{6 \cdot 10^3 \text{ m}}{u_0} = \frac{6 \text{ km}}{u_0}$$

$$C_6H_6: 0.00093$$

$$C_6H_5O: 0.00073$$

$$\begin{array}{r} \text{Cmpn.} \\ \cancel{0.00018} \\ 0.00019 \end{array}$$

$$\begin{array}{r} 0.00064 \quad \beta \\ \cancel{0.00149} \\ 0.00118 \end{array}$$

$$\begin{array}{r} 0.00148 \quad \cancel{0.00093} \\ \cancel{0.00019} \end{array}$$

$$\begin{array}{r} 0.00072 \quad \beta \\ \cancel{0.00157} \\ 0.00085 \end{array}$$

$$13.59 \quad 18 =$$

$$\begin{array}{r} 1062 \\ 359 \end{array}$$

$$10.924 : 19 =$$

$$- 0.00577$$

$$C_6H_6$$

$$+ 0.00167$$

$$\frac{1}{300}$$

$$- 0.0041$$

$$42.9$$

$$31.5$$

$$10.9 : (37.20)$$

$$350 = 295$$

$$170$$

$$0.0147$$

$$- 10.0017$$

$$C_6H_5O$$

$$+ 0.0017$$

$$0.000$$







B. N. ....

Sygnatura: .....

Dzieło: (Autor) .....

(Tytuł) .....

(Stan dzieła) .....

tom

wol.

pożyczyłem z c. k. biblioteki uniwersyteckiej i zwrócę  
je w ciągu tygodni ..... przyjmując odpo-  
wiedzialność za wszelkie uszkodzenia.

We Lwowie dnia

Mieszkanie:

Podpis:



G. Cantoni: Su alcune condizioni fisiche dell'attività <sup>256</sup>  
 sul moto browniano. Rend. Lomb. (2) I, 56, Cimento  
 XXVII. 156.

cf e p. 256 Affinità eb  $\gamma$   $\leftarrow$   $\gamma$  p. 103 e H<sub>2</sub> e f. e p. 256  
 spec. 2.

P. Mol. e p. 256 e p. 256  $\gamma$  p. 103 e f. e p. 256. e 103 26  
 per 1 22 e p. 256. e p. 256 6 - e p. 256 2 10 22 per  
 103 2, e 2 256 e p. 256 2 103 2 256."

10. e H<sub>2</sub> ridotti e f. e p. 256 Fe | S | C  
 $\downarrow$   $\downarrow$   $\downarrow$   $\downarrow$   
 256 256 256 256  
 e 103 e p. 256 1 256 e p. 256. 256 103 256 256  
 e 256. e 256  $\frac{1}{1600}$  mm 103. 256 256 256  
 103 e p. 256 - 256 103. e 256 256. 256 103  
 e 103 e p. 256 256 - e p. 256 256 256

eb  $\gamma$  1  $\gamma$  256 1'



B. N. .... Sygnatura: .....

Dzieło : (Autor) .....

(Tytuł) .....

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tom

wol.

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je w ciągu tygodni ..... przyjmując odpo-  
wiedzialność za wszelkie uszkodzenia.

We Lwowie dnia

Mieszkanie :

Podpis :

.....

Tytuł dzieła:

Sygnatura :

\_\_\_\_\_

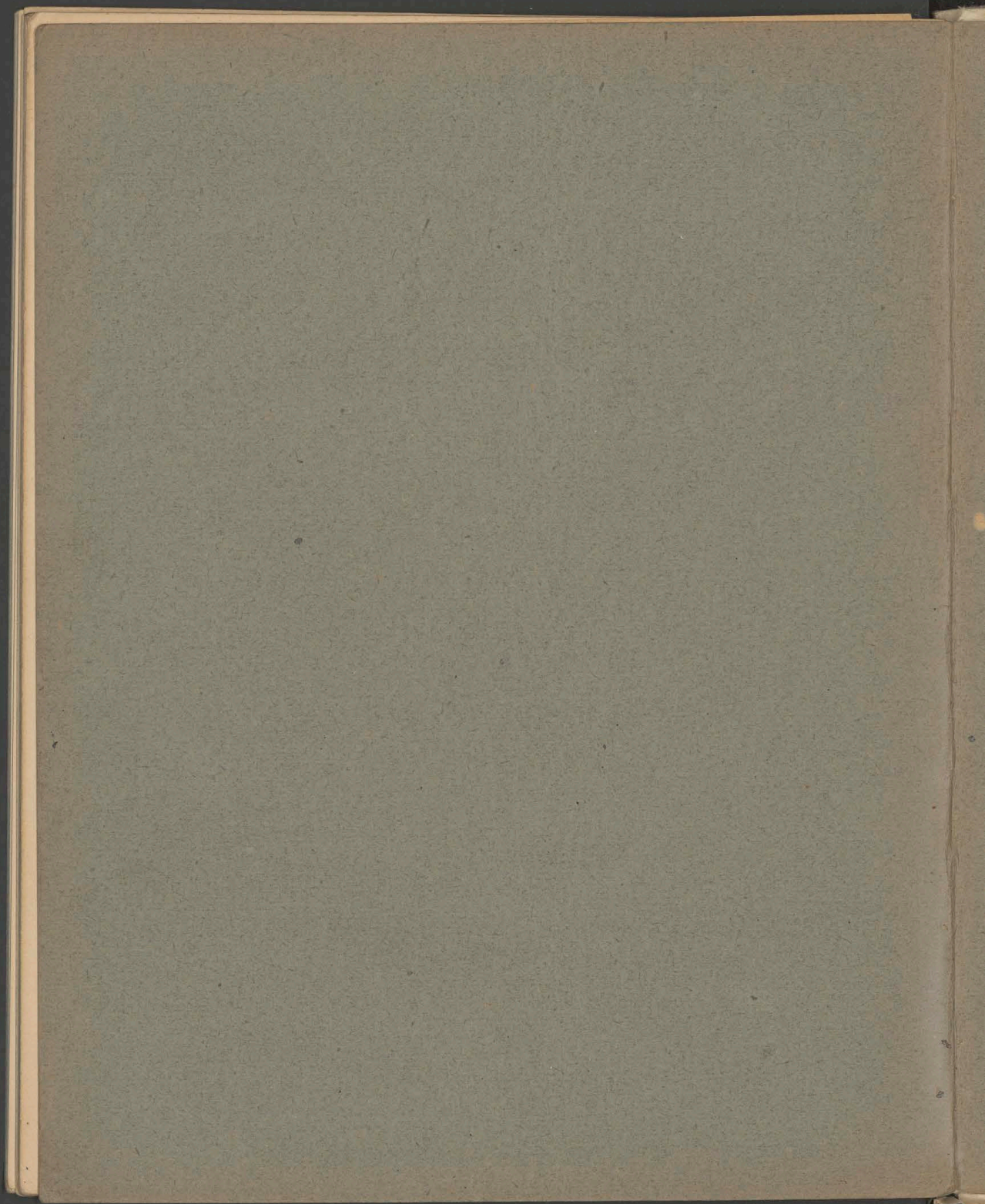
D a t a :

Nazwisko pożyczającego :



257



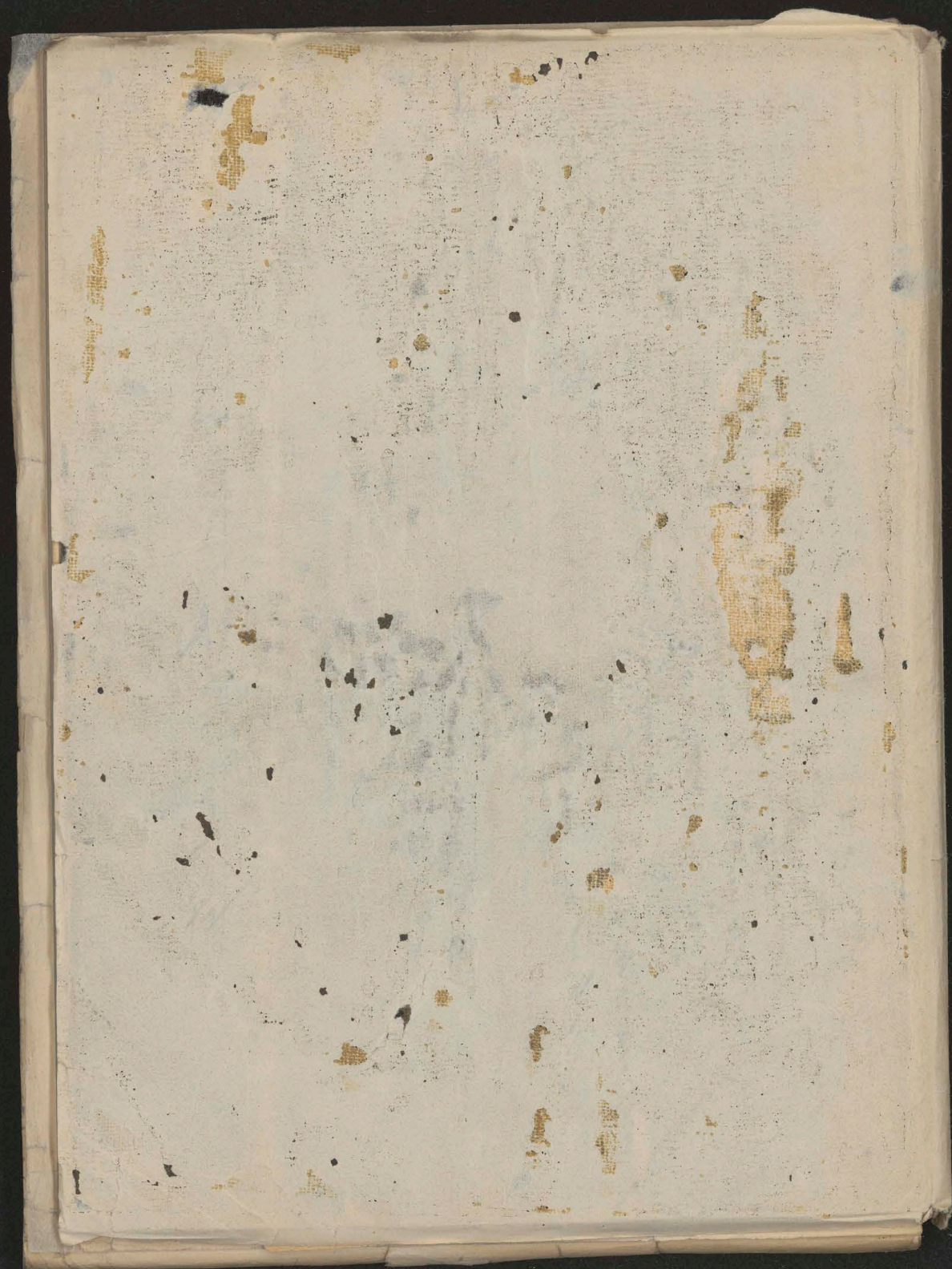




258









9408

II



259



50 pl. 0/15





$$u=0 \quad w=0 \quad v=f(x)$$

$$\frac{\partial u}{\partial t} + \frac{\partial v}{\partial x} + \frac{\partial w}{\partial y} = 0$$

$$0 = -\frac{\partial p}{\partial x} + \mu \nabla^2 v$$

$$p = f(y)$$

$$\rho \frac{\partial v}{\partial t} = -\frac{\partial p}{\partial y} + \mu \nabla^2 v$$

$$0 = -\frac{\partial p}{\partial z}$$

$$\rho \frac{\partial v}{\partial t} = -\frac{\partial p}{\partial y} + \mu \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial p}{\partial t} = 0$$

$$\rho \frac{\partial v}{\partial t} = \mu \frac{\partial^2 v}{\partial x^2}$$

$$v = e^{-\gamma x} \cos \alpha x$$

$$-\gamma p = -\alpha^2 \mu$$

$$\gamma = \frac{\alpha^2 \mu}{\rho}$$

$$v = e^{-\frac{\alpha^2 \mu}{\rho} t} \cos \alpha x$$

$$v = e^{-\gamma x} \sin(\alpha(x - \beta t))$$

$$\frac{\partial v}{\partial x} = -\gamma e^{-\gamma x} \sin + \alpha e^{-\gamma x} \cos$$

$$\frac{\partial v}{\partial x} = \gamma^2 e^{-\gamma x} \sin - 2\alpha \gamma e^{-\gamma x} \cos - \alpha^2 e^{-\gamma x} \sin$$

$$\frac{\partial v}{\partial t} = -\alpha \beta e^{-\gamma x} \cos$$

$$-\alpha \beta p = -\mu 2\alpha \gamma$$

$$0 = \gamma^2 - \alpha^2$$

$$\left. \begin{aligned} \gamma &= \alpha \\ \rho &= \frac{2\mu\alpha}{\beta} \end{aligned} \right\}$$

$$v = e^{-\alpha x} \sin \alpha \left[ x - \frac{2\mu\alpha}{\rho} t \right]$$

$$= e^{-x \sqrt{\frac{\rho}{2\mu}}} \sin \left[ x \sqrt{\frac{\rho}{2\mu}} - \epsilon t \right]$$

$$\rho = 0.0012$$

$$\mu = 0.00019$$

$$\text{N/m}^2 \cdot 10^{-6} \text{ s} =$$

$$\epsilon = \frac{2\pi}{T} = 2\pi n$$

$$\sqrt{\frac{2\pi n \cdot 12}{2 \cdot 0.18} \cdot 10^{-6}}$$

$$n = 500$$

$$\sqrt{\frac{1}{2} \cdot \frac{2 \cdot 12}{0.18} \cdot 10^{-6}}$$

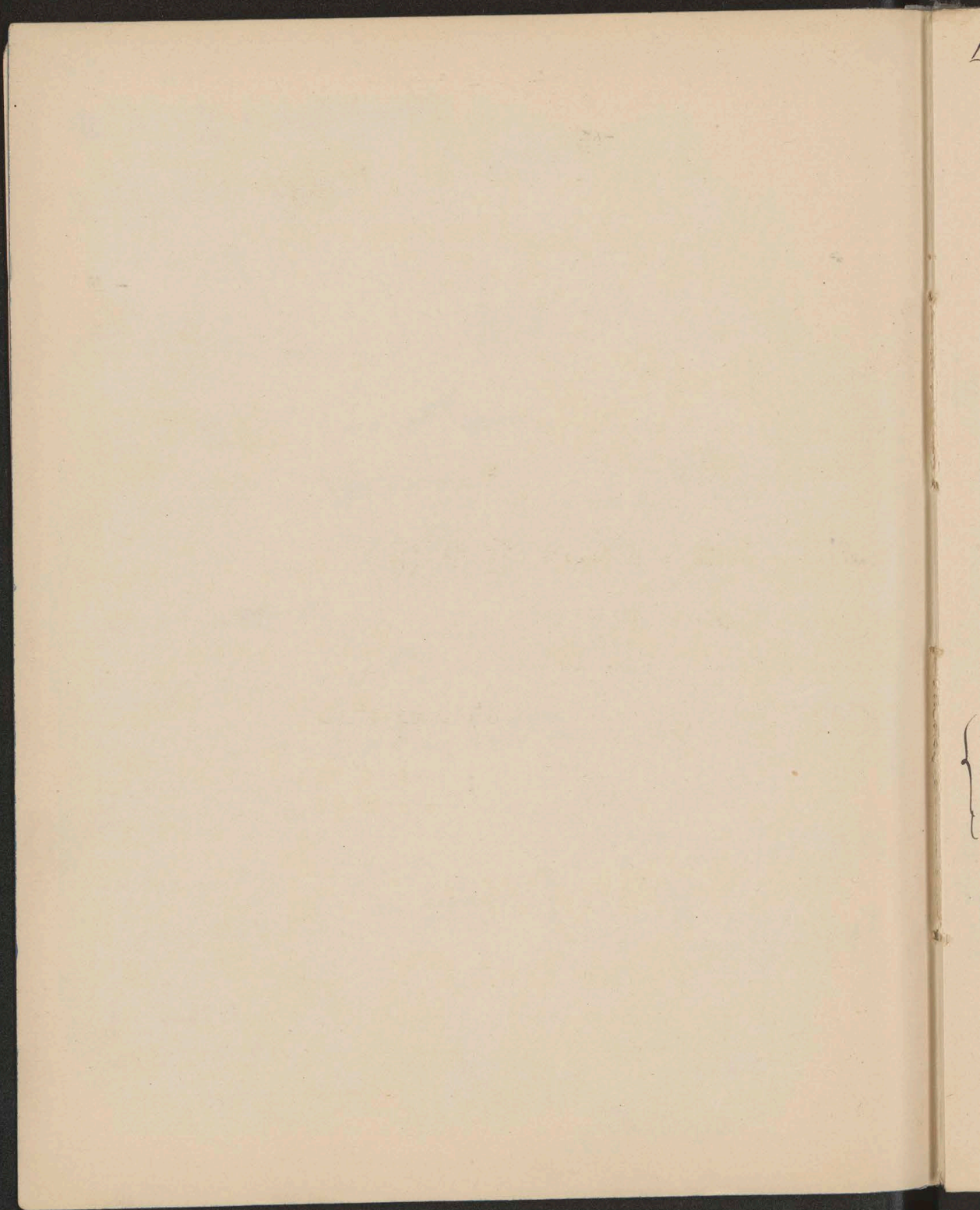
$$\sqrt{100} = 10^{-1}$$

$$\left[ e^{-\frac{x}{10}} \right]$$



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3  
—  
23  
24





$\Delta^2$  Putka czy  $\Delta^2 \sim \Delta^2$

$$\Delta^2 \left[ \frac{27}{32} \frac{a}{x^2} + \frac{3}{4} \left( \frac{x^2}{x^3} - \frac{15}{8} \frac{ax^2}{x^4} - \frac{1}{4} \frac{a^3 x^3}{x^6} \right) \right] =$$

$$\frac{27}{32} \frac{2a}{x^4} + \frac{3}{4} \left[ 2 \frac{1}{x^3} - \frac{15a}{8} \left( \frac{2}{x^4} - \frac{4x^2}{x^6} \right) - \frac{3a^3}{4} \left( \frac{2}{x^6} + 6 \frac{x^2}{x^8} \right) \right]$$

$$= \frac{27}{16} \frac{a}{x^4} + \frac{3}{2} \frac{1}{x^3} - \frac{45a}{16x^4} + \frac{45}{8} \frac{ax^2}{x^6} - \frac{3a^3}{8x^6} - \frac{9}{8} \frac{a^3 x^2}{x^8} - \frac{9x^2}{2x^5}$$

$$- \frac{18a}{16x^4}$$

$$= \frac{3}{2} \frac{1}{x^3} \left[ 1 - \frac{3}{4} \frac{a}{x} - \frac{1}{4} \frac{a^3}{x^3} \right] - \frac{9}{2} \frac{x^2}{x^5} \left[ 1 - \frac{5}{4} \frac{a}{x} + \frac{1}{4} \frac{a^3}{x^3} \right]$$

zatem  $k \operatorname{div}' = \Delta^2 \left\{ \mu c^2 a \left[ \frac{27}{32} \frac{a}{x^2} + \frac{3}{4} \left( - - - \right) \right] \right\}$

$$\operatorname{div}' = \Delta^2 \psi$$

Równanie systemu równań

$$\begin{cases} \frac{\partial \psi'}{\partial x} = \frac{1}{3} \frac{\partial \operatorname{div}'}{\partial x} + \mu \Delta^2 u' \\ \frac{\partial \psi'}{\partial y} = \frac{1}{3} \frac{\partial \operatorname{div}'}{\partial y} + \mu \Delta^2 v' \\ \frac{\partial \psi'}{\partial z} = \frac{1}{3} \frac{\partial \operatorname{div}'}{\partial z} + \mu \Delta^2 w' \end{cases}$$

$$\Delta^2 \psi' = \frac{4\mu}{3} \Delta^2 \operatorname{div}'$$

$$\underline{\underline{\psi' = \frac{4\mu}{3} \operatorname{div}' + \varphi}}$$

$$\Delta^2 \varphi = 0$$

$$\mu \frac{\partial \operatorname{div}'}{\partial x} + \frac{\partial \varphi}{\partial x} = \mu \Delta^2 u'$$

$$u' = \frac{\partial \varphi}{\partial x} + u$$

$$\begin{cases} \frac{\partial \varphi}{\partial x} = \mu \Delta^2 u \\ \frac{\partial \varphi}{\partial y} = \mu \Delta^2 v \\ \frac{\partial \varphi}{\partial z} = \mu \Delta^2 w \end{cases}$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

8.11 2. Summe für Potentiale

$$U = - \frac{27 \mu c^2 a}{32 k} \left[ -\frac{x}{2^3} + \frac{1}{3} \frac{x^3}{2^5} - \frac{q^2 x}{2^5} \left( 3 - 5 \frac{x^2}{2^2} \right) \right]$$

$$V = - \frac{27 \mu c^2 a}{32 k} \left[ -\frac{y}{2^3} + \frac{1}{3} \frac{x^2 y}{2^5} - \frac{q^2 y}{2^5} \left( 1 - 5 \frac{x^2}{2^2} \right) \right]$$

$$W =$$

$$\mu \Delta U = - \frac{27 \mu c^2 a}{32 k} \left( \frac{2x}{2^5} - \frac{10}{3} \frac{x^3}{2^7} \right) = \frac{\partial}{\partial x} \left[ - \frac{27 \mu c^2 a}{32 k} \frac{2}{3} \left( -\frac{1}{3x^3} + \frac{x^2}{2^5} \right) \right] = \frac{q}{16} \frac{\mu c^2 a}{k} \left[ \frac{1}{3x^3} - \frac{x^2}{2^5} \right]$$

$$\mu \Delta V = - \frac{27 \mu c^2 a}{32 k} \left( \frac{2}{3} \frac{y}{2^5} - \frac{10}{3} \frac{x^2 y}{2^7} \right) = \frac{\partial}{\partial y}$$

$$\left. \begin{aligned} \frac{2}{3} \frac{\partial}{\partial x} \left( \frac{x^2}{2^5} \right) &= \frac{4x}{3 \cdot 2^5} - \frac{10 x^3}{3 \cdot 2^7} \\ - \frac{2}{9} \frac{\partial}{\partial x} \left( \frac{1}{2^3} \right) &= - \frac{3x}{2^5} \cdot \frac{2}{9} \end{aligned} \right\} \begin{aligned} \frac{\partial}{\partial x} \left| \frac{2}{3} \left( -\frac{1}{3x^3} + \frac{x^2}{2^5} \right) \right| \\ \frac{\partial}{\partial y} = \frac{2}{3} \left( + \frac{y}{2^5} - \frac{5x^2 y}{2^7} \right) \end{aligned}$$

$$\varphi = \frac{q}{16} \frac{\mu c^2 a}{k} \left[ \frac{1}{3x^3} - \frac{x^2}{2^5} \right]$$

$$P = P_0 - \frac{3}{2} \mu c a \frac{x}{2^3} + \frac{1}{P} \left\{ \frac{4\mu}{3k} \left[ \frac{3}{2} \mu a c^2 \frac{1}{2^3} \left( 1 - \frac{2}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right) - \right. \right. \\ \left. \left. - \frac{q}{2} \mu c^2 a \frac{x^2}{2^5} \left( 1 - \frac{5}{4} \frac{a}{2} + \frac{1}{4} \frac{a^3}{2^3} \right) \right] + \frac{q}{16} \frac{\mu c^2 a}{k} \left[ \frac{1}{3x^3} - \frac{x^2}{2^5} \right] \right\}$$

$$\left\{ \right\} = \frac{\mu c^2 a}{k} \left| \begin{aligned} &\frac{2}{2^3} \left( 1 - \frac{2}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3} \right) + \frac{q}{16} \frac{1}{3x^3} \\ &- \frac{6x^2}{2^5} \left( 1 - \frac{5}{4} \frac{a}{2} + \frac{1}{4} \frac{a^3}{2^3} \right) - \frac{q}{16} \frac{x^2}{2^5} \end{aligned} \right|$$

$$\begin{aligned} &\frac{\partial}{\partial x} \\ &+ \frac{\partial}{\partial y} \\ &+ \frac{\partial}{\partial z} \end{aligned}$$



$$u_0 \frac{\partial u_0}{\partial x} + v_0 \frac{\partial u_0}{\partial y} + w_0 \frac{\partial u_0}{\partial z} = \frac{q}{16} \frac{c^2 a^2 x}{r^3} \left(1 - \frac{a^2}{r^2}\right) \left[ x^2 \left(11 + \frac{2}{r^3} - \frac{2a^2}{r^5}\right) + y^2 11 + z^2 11 \right]$$

$$- \frac{3}{4} \frac{c^2 a^2 x}{r^3} \left(1 - \frac{2}{r^3} - \frac{1}{4} \frac{a^2}{r^5}\right) \left(1 - \frac{3x^2}{r^2} - \frac{3a^2}{r^2} + \frac{5a^2 x^2}{r^4}\right)$$

$$= \frac{q}{16} \frac{c^2 a^2 x}{r^3} \left(1 - \frac{a^2}{r^2}\right) \left[ -\frac{1}{2} - \frac{3x^2}{r^3} - \frac{a^2}{r^3} + \frac{5a^2 x^2}{r^5} + \frac{2x^2}{r^3} - \frac{2a^2 x^2}{r^5} \right] - \uparrow$$

$$- \frac{1}{2} - \frac{x^2}{r^3} - \frac{a^2}{r^3} + \frac{3a^2 x^2}{r^5}$$

$$= \frac{3}{4} \frac{c^2 a^2 x}{r^3} \left\{ \frac{3}{4} \left[ -\frac{1}{2} - \frac{a^2}{r^3} - \frac{3x^2}{r^3} + \frac{3a^2 x^2}{r^5} + \frac{a^2}{r^3} + \frac{3x^2}{r^3} + \frac{a^2}{r^5} - \frac{3a^2 x^2}{r^7} \right] \right.$$

$$- 1 + \frac{3x^2}{r^2} + \frac{3a^2}{r^2} - \frac{5a^2 x^2}{r^4} + \frac{3}{4} \frac{a^2}{r^2} - \frac{9}{4} \frac{x^2 a^2}{r^3} - \frac{9a^3}{4r^3} + \frac{15a^3 x^2}{4r^5} + \frac{a^3}{4r^3} - \left. \frac{3a^3 x^2}{4r^5} - \frac{3a^3}{4r^5} + \frac{5a^3 x^2}{4r^7} \right\}$$

$$= \frac{3}{4} \frac{c^2 a^2 x}{r^3} \left\{ -1 + \frac{3x^2}{r^2} + \frac{3a^2}{r^2} - \frac{5a^2 x^2}{r^4} - \frac{3a^2 x^2}{r^3} - \frac{2a^3}{r^3} + \frac{6a^3 x^2}{r^5} - \frac{a^3 x^2}{r^7} \right\}$$

$$\left. \begin{aligned} & \frac{\partial}{\partial x} \left( u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) \\ & + \frac{\partial}{\partial y} \left( u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) \\ & + \frac{\partial}{\partial z} \left( u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} \right) \end{aligned} \right\} = \left( \frac{\partial u}{\partial x} \right)^2 + \frac{\partial v}{\partial x} \frac{\partial u}{\partial y} + \frac{\partial w}{\partial x} \frac{\partial u}{\partial z} + u \frac{\partial^2 u}{\partial x^2} + v \frac{\partial^2 u}{\partial y^2} + w \frac{\partial^2 u}{\partial z^2} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + \left( \frac{\partial v}{\partial y} \right)^2 + \frac{\partial v}{\partial y} \frac{\partial v}{\partial z} + \frac{\partial u}{\partial z} \frac{\partial w}{\partial x} + \frac{\partial v}{\partial z} \frac{\partial w}{\partial y} + \left( \frac{\partial w}{\partial z} \right)^2 + \frac{\partial w}{\partial z} \frac{\partial w}{\partial x} + \frac{\partial w}{\partial z} \frac{\partial w}{\partial y} = 0$$

$$= \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 + 2 \frac{\partial u}{\partial y} \frac{\partial v}{\partial x} + 2 \frac{\partial v}{\partial z} \frac{\partial w}{\partial y} + 2 \frac{\partial w}{\partial x} \frac{\partial u}{\partial z}$$

$$+ \frac{1}{2} \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right)^2 + \dots$$

$$= \frac{1}{2} \left[ \Phi - \{^2 - 4^2 - \{^2 \right]$$



$$\text{By } f_1 = \frac{\partial u}{\partial x}, \quad f_2 = \frac{\partial u}{\partial y} ?$$

W. Atkin's variational principle

$$\frac{\partial f_1}{\partial y} = \frac{\partial f_2}{\partial x}$$

$$\begin{aligned} & \frac{\partial}{\partial y} \left( u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} \right) - \frac{\partial}{\partial x} \left( u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} \right) = \\ & = u \left( \frac{\partial^2 u}{\partial x \partial y} - \frac{\partial^2 v}{\partial x^2} \right) + v \left( \frac{\partial^2 u}{\partial y^2} - \frac{\partial^2 v}{\partial x \partial y} \right) + w \left( \frac{\partial^2 u}{\partial x \partial z} - \frac{\partial^2 v}{\partial x \partial z} \right) \\ & + \frac{\partial u}{\partial x} \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + \frac{\partial v}{\partial y} \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + \frac{\partial w}{\partial y} \frac{\partial u}{\partial z} - \frac{\partial v}{\partial x} \frac{\partial v}{\partial z} \\ & = - \frac{\partial w}{\partial z} \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) \end{aligned}$$

$$\text{A.2.2. } \text{curl } (\nabla \phi) = 0 \quad \left\{ \begin{array}{l} \text{curl } \nabla \phi = 0 \\ \text{curl } \nabla \phi = 0 \end{array} \right. = \text{curl } \nabla \phi = 0$$

To derive equations in a kinetic variational principle with total energy  
by using the variational principle for the kinetic energy

$$u \frac{\partial \xi_1}{\partial x} + v \frac{\partial \xi_1}{\partial y} + w \frac{\partial \xi_1}{\partial z} - \left( \xi_1 \frac{\partial u}{\partial x} + \xi_2 \frac{\partial u}{\partial y} + \xi_3 \frac{\partial u}{\partial z} \right)$$

$$\xi_1 \frac{\partial u}{\partial y} + \xi_2 \frac{\partial u}{\partial z} = 0$$

$$u \frac{\partial \eta}{\partial x} + v \frac{\partial \eta}{\partial y} + w \frac{\partial \eta}{\partial z} - \left( \xi_1 \frac{\partial v}{\partial x} + \xi_2 \frac{\partial v}{\partial y} + \xi_3 \frac{\partial v}{\partial z} \right) =$$

$$\frac{\partial \eta}{\partial x} = + \frac{3}{2} \frac{c a x^2}{2^5}$$

$$\frac{\partial \eta}{\partial y} = + \frac{3}{2} \frac{c a y^2}{2^5}$$

$$\frac{\partial \eta}{\partial z} = - \frac{1}{2} \frac{c a}{2^3} + \frac{3}{2} \frac{c a^2}{2^5}$$



$$= \frac{\mu^2 c^2 a}{k} \left[ \frac{1}{n^3} \left( \frac{35}{16} - \frac{3}{2} \frac{a}{n} - \frac{1}{2} \frac{a^3}{n^3} \right) - \frac{3x^2}{n^5} \left( \frac{35}{16} - \frac{5}{2} \frac{a}{n} + \frac{1}{2} \frac{a^3}{n^3} \right) \right]$$

$$P = \frac{1}{2} \mu c a \frac{x}{n^3} + \frac{\mu^2 c^2 a}{k P} \frac{1}{2n^3} \left[ \frac{35}{8} - \frac{3a}{n} - \frac{a^3}{n^3} \right] - \frac{3x^2}{n^5} \left( \frac{35}{8} - \frac{5a}{n} + \frac{a^3}{n^3} \right)$$

Równanie  $P \sim \frac{\mu c}{a} \quad \mu c \propto a P$

Wskazano:  $\frac{\partial p}{\partial x} = \mu \frac{\partial u}{\partial x^2}$  zgodnie z

Równanie termiczne Poissona:

$$k \operatorname{div} \nabla u = - \left[ u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z} \right] + (k-1) \mu \left[ \left( \frac{\partial u_0}{\partial x} \right)^2 + \left( \frac{\partial v_0}{\partial y} \right)^2 + \left( \frac{\partial w_0}{\partial z} \right)^2 \right] + k \Delta \Phi$$

Jednocześnie woli  $k$  - stała izotermiczna to  $\Phi$  temperatury wyjdzie wielkość ... rotacji  
adibatyki rotacji mikrojonów!

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} c a \left[ \frac{2x}{n^3} - \frac{3x^3}{n^5} - \frac{2a^2 x}{n^5} + \frac{5a^2 x^3}{n^7} \right] + c \left[ \frac{1}{4} \frac{a x}{n^3} + \frac{3}{4} \frac{a^3 x}{n^5} \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} c a \left[ \frac{x}{n^3} - \frac{3x^3}{n^5} - \frac{3a^2 x}{n^5} + \frac{5a^2 x^3}{n^7} \right]$$

$$\frac{\partial v_0}{\partial y} = -\frac{3}{4} c a \left[ \frac{x}{n^3} - \frac{3x y^2}{n^5} - \frac{a^2 x}{n^5} + \frac{5a^2 x y^2}{n^7} \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} c a \left[ \frac{x}{n^3} - \frac{3x z^2}{n^5} - \frac{a^2 x}{n^5} + \frac{5a^2 x z^2}{n^7} \right]$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} c a \left[ -\frac{3x^2 y}{n^5} + \frac{5a^2 x^2 y}{n^7} \right] + c \left[ \frac{3a y}{4 n^3} + \frac{3a^3 y}{4 n^5} \right]$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} c a \left[ -\frac{3x^2 y}{n^5} + \frac{5a^2 x^2 y}{n^7} - \frac{y}{n^3} - \frac{a^2 y}{n^5} \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} c a \left[ -\frac{3x^2 z}{n^5} + \frac{5a^2 x^2 z}{n^7} - \frac{z}{n^3} - \frac{a^2 z}{n^5} \right]$$



$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \left[ \left(1 - \frac{a^2}{r^2}\right) \frac{y}{r^3} - \frac{3x^2 y}{r^5} \left(1 - \frac{a^2}{r^2}\right) + \frac{2a^2 x y}{r^7} \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \left[ \left(1 - \frac{a^2}{r^2}\right) \frac{y}{r^3} - \frac{3x^2 y}{r^5} + \frac{5a^2 x^2 y}{r^7} \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} ca \left[ \frac{2a^2 z x y}{r^7} - \frac{3x y z}{r^5} \left(1 - \frac{a^2}{r^2}\right) \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} ca \left[ -\frac{3x y z}{r^5} + \frac{5a^2 x y z}{r^7} \right] =$$

$$\frac{\partial u_0}{\partial y} =$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \left[ \left(1 - \frac{a^2}{r^2}\right) \frac{z}{r^3} - \frac{3x^2 z}{r^5} + \frac{5a^2 x^2 z}{r^7} \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \cdot x \left[ \frac{1}{r^3} - \frac{3x^2}{r^5} - \frac{a^2}{r^5} + \frac{5a^2 x^2}{r^7} \right] -$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} ca \cdot y \left[ -\frac{1}{r^3} - \frac{3x^2}{r^5} - \frac{a^2}{r^5} + \frac{5a^2 x^2}{r^7} \right]$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} ca \cdot z \left[ \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \cdot y \left[ \frac{1}{r^3} - \frac{3x^2}{r^5} - \frac{a^2}{r^5} + \frac{5a^2 x^2}{r^7} \right]$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} ca \cdot x \left[ \frac{1}{r^3} - \frac{3y^2}{r^5} - \frac{a^2}{r^5} + \frac{5a^2 y^2}{r^7} \right] -$$

$$\frac{\partial u_0}{\partial z} = -\frac{3}{4} ca \cdot \frac{x y z}{r^5} \left[ -3 + \frac{5a^2}{r^2} \right]$$

$$\frac{\partial u_0}{\partial y} = -\frac{3}{4} ca \cdot z \left[ \frac{1}{r^3} - \frac{3x^2}{r^5} - \frac{a^2}{r^5} + \frac{5a^2 x^2}{r^7} \right]$$

$$\frac{\partial u_0}{\partial x} = -\frac{3}{4} ca \cdot x \left[ \frac{1}{r^3} - \frac{3z^2}{r^5} - \frac{a^2}{r^5} + \frac{5a^2 z^2}{r^7} \right] -$$

$$\frac{\partial u_0}{\partial x} - \frac{\partial u_0}{\partial y} = -\frac{3}{4} ca \frac{y}{r^3}$$

$$\frac{\partial u_0}{\partial z} - \frac{\partial u_0}{\partial x} = +\frac{3}{4} ca \frac{z}{r^3}$$

$$\frac{\partial u_0}{\partial z} - \frac{\partial u_0}{\partial y} = 0$$



Uzblizanie warpladzinie inercji:

$\frac{\rho}{\rho_0} = R\theta$  csem wykre  $R$ , ten mniejsze  $\rho$  zatu te mniejszy uply  
inercji. ~~zatu~~ ~~R~~ zatu ravinizui oedly

$$\frac{\rho}{\rho_0} = \frac{\rho_0}{\rho_0} \quad \text{poty} \quad \rho \approx \frac{1}{R} \approx \rho_0$$

$$u = u_0 + \rho_0 u' + \frac{\rho_0^2}{2} u'' + \dots$$

$$\rho_0 \frac{\rho}{\rho_0} \left( u_0 \frac{\partial u_0}{\partial x} + \dots \right) + \rho_0 \left[ u_0 \frac{\partial u'}{\partial x} + u' \frac{\partial u_0}{\partial x} + \dots \right] \mu \left\{ + \frac{\partial \rho_0}{\partial x} + \rho_0 \frac{\partial u'}{\partial x} = \right. \\ \left. = \mu \left[ \Delta^2 u_0 + \rho_0 \Delta^2 u' + \dots \right] \right.$$

$$\rho_0 \operatorname{div}_0 + \rho_0 (\rho' \operatorname{div}_0 + \rho_0 \operatorname{div}') + k(u_0 \frac{\partial \rho_0}{\partial x} + \dots) + k \rho_0 \left[ u' \frac{\partial \rho_0}{\partial x} + u_0 \frac{\partial \rho'}{\partial x} + \dots \right] = \\ = (k-v) \Phi_0 + k \rho_0 \Psi$$

$$\begin{cases} \frac{\partial \rho_0}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \operatorname{div}_0 + \mu \Delta^2 u_0 \\ \rho_0 \operatorname{div}_0 + k(u_0 \frac{\partial \rho_0}{\partial x} + \dots) = (\Phi - 1) \Phi_0 \end{cases}$$

Poprawka:

$$\left. \begin{aligned} \frac{\partial \rho_0}{\partial x} &= \frac{\mu}{3} \frac{\partial}{\partial x} \operatorname{div}_0 + \mu \Delta^2 u_0 \\ \rho_0 \operatorname{div}_0 + k(u_0 \frac{\partial \rho_0}{\partial x} + \dots) &= (\Phi - 1) \Phi_0 \end{aligned} \right\}$$

$$\text{Istotni cznie: } f_1 + \frac{\partial f_1}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \operatorname{div}_0 + \mu \Delta^2 u_0$$

$$\rho' \operatorname{div}_0 + \rho_0 \operatorname{div}' + (u' \frac{\partial \rho_0}{\partial x} + \dots) + (u_0 \frac{\partial \rho'}{\partial x} + \dots) = 0$$

$$\Delta^2 \rho' + \left( \frac{\partial f_1}{\partial x} + \frac{\partial f_2}{\partial y} + \frac{\partial f_3}{\partial z} \right) = \frac{\mu}{3} \Delta^2 \operatorname{div}'$$

$$\operatorname{div} [\nabla \phi] = \operatorname{div} \left[ \nabla \frac{\phi^2}{2} + \nabla \phi \operatorname{curl} \phi \right] = \nabla^2 \frac{\phi^2}{2} + \phi \operatorname{curl}^2 \phi - (\operatorname{curl} \phi)^2$$

$$= \mathcal{F}$$

$$\rho' = \frac{\mu}{3} \operatorname{div}' + \int \frac{\mathcal{F} dv}{4\pi r^2} + \varphi$$

Sta uvaž, albo uvažle jini  $P$  <sup>lados</sup>  $P$   $\Delta u$  a  $\rho$   $\Delta u$   $\Delta u$   $\Delta u$ .

$$\left. \begin{aligned} f_1 + \frac{\partial f_1'}{\partial x} &= \mu \Delta^2 u' \\ f_2 + \frac{\partial f_2'}{\partial y} &= \mu \Delta^2 v' \\ f_3 + \frac{\partial f_3'}{\partial z} &= \mu \Delta^2 w' \end{aligned} \right\} \underbrace{\frac{\partial f_1}{\partial x} + \frac{\partial f_2}{\partial y} + \frac{\partial f_3}{\partial z}}_F + \Delta^2 p' = \mu \Delta^2 \text{div}' u' = 0$$

$$p' = \int \frac{F dv}{4\pi r^2} + \varphi$$

$$u' = u + U$$

$$f_1 = \mu \Delta^2 u$$

$$\frac{\partial f_1'}{\partial x} = \mu \Delta^2 U$$

$$\frac{\partial U}{\partial x} + \frac{\partial V}{\partial y} + \frac{\partial W}{\partial z} = -\left(\frac{\partial u}{\partial x} + \dots\right)$$

$$u = \frac{1}{\mu} \int \frac{f_1' dv}{4\pi r^2}$$

$$\frac{\partial f_1'}{\partial y} = \mu \Delta^2 V$$

$$\frac{\partial f_1'}{\partial z} = \mu \Delta^2 W$$

etc.

$$\mu \Delta^2 \text{div}' u' = \Delta^2 p' = -\mu \Delta^2 \text{div} u$$

$$p' = -\mu \text{div} u + \varphi \quad \parallel \quad \Delta^2 \varphi = 0$$

$$-\mu \frac{\partial}{\partial x} \text{div} u + \frac{\partial \varphi}{\partial x} = \mu \Delta^2 U$$

$$-\mu \frac{\partial}{\partial y} \text{div} u + \frac{\partial \varphi}{\partial y} = \mu \Delta^2 V$$

$$-\mu \frac{\partial}{\partial z} \text{div} u + \frac{\partial \varphi}{\partial z} = \mu \Delta^2 W$$

$$\Delta^2 \varphi = 0$$

$$-\mu \nabla \text{div} u + \nabla \varphi = \mu \Delta^2 \mathbf{u}$$

$$u' = \frac{1}{\mu} \frac{\partial}{\partial x} \text{div} u' + \dots$$

$$u' = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$$

$$\left. \begin{aligned} f_1 + f_1' &= \mu \Delta^2 u \\ f_2 + f_2' &= \mu \Delta^2 v \end{aligned} \right\}$$

$$\frac{\partial f_1}{\partial x} - \frac{\partial f_2}{\partial y} = \mu \Delta^2 \left\{ \begin{aligned} \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \end{aligned} \right\}$$

$$\left\{ \begin{aligned} \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} \end{aligned} \right\} = \int \frac{\partial u}{\partial x} - \frac{\partial v}{\partial y} + \dots$$

$$\left\{ \begin{aligned} f_1 + \frac{\partial f_1}{\partial x} + \frac{\partial f_2}{\partial y} &= \mu \Delta^2 u \\ f_2 + \frac{\partial f_2}{\partial y} + \frac{\partial f_3}{\partial z} &= \mu \Delta^2 v \\ f_3 + \frac{\partial f_3}{\partial z} + \frac{\partial f_4}{\partial x} &= \mu \Delta^2 w \end{aligned} \right\}$$



$$\frac{\partial w}{\partial y} + \frac{\partial v}{\partial z} = 2 \frac{y^2}{z^5} \left[ -3 + \frac{5a^2}{z^2} \right]$$

$$\frac{\partial u}{\partial z} + \frac{\partial w}{\partial x} = 2x \left[ -\frac{3x^2}{z^5} - \frac{a^2}{z^5} + \frac{5a^2 x^2}{z^7} \right] = 2x \left[ -\frac{a^2}{z^5} + \frac{x^2}{z^5} \left[ -3 + \frac{5a^2}{z^2} \right] \right]$$

$$\frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = 2y \left[ \begin{array}{c} \uparrow \\ M \end{array} \right]$$

$$\frac{\partial u}{\partial x} = x \left( M + \frac{1}{z^3} - \frac{2a^2}{z^5} \right)$$

$$\frac{\partial v}{\partial y} = x \left( M + \frac{1}{z^3} \right) \quad \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial v}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 =$$

$$\frac{x^2}{z^6} \left\{ \left[ \left( 1 - \frac{3a^2}{z^2} \right) - \frac{2}{z^2} \left( \frac{3}{z^2} - \frac{5a^2}{z^4} \right) \right]^2 + \left[ \left( -\frac{a^2}{z^2} \right) - x^2 \left[ \frac{3}{z^2} - \frac{5a^2}{z^4} \right] \right]^2 + \left[ \left( 1 - \frac{a^2}{z^2} \right) - z^2 \left( \quad \right) \right]^2 \right\}$$

$$= \frac{x^2}{z^6} \left\{ 1 - \frac{6a^2}{z^2} + \frac{9a^4}{z^4} - 2z^2 \left( \frac{3}{z^2} - \frac{5a^2}{z^4} \right) \left( 1 - \frac{3a^2}{z^2} \right) + \left( \frac{3a^2}{z^2} x^2 + \frac{a^2 y^2}{z^2} + \frac{a^2 z^2}{z^2} \right) \left( \frac{3}{z^2} - \frac{5a^2}{z^4} \right) + 1 - \frac{2a^2}{z^2} + \frac{a^4}{z^4} + (x^2 + y^2 + z^2) \left( \frac{3}{z^2} - \frac{5a^2}{z^4} \right)^2 \right\}$$

$$= \frac{x^2}{z^6} \left\{ \frac{3}{z^2} - \frac{10a^2}{z^2} + \frac{11a^4}{z^4} - \frac{6}{z^2} + \frac{10a^2}{z^2} + \frac{4a^2 x^2}{z^2} \left( \frac{3}{z^2} - \frac{5a^2}{z^4} \right) + \frac{6a^2}{z^2} - \frac{10a^4}{z^4} + (x^2 + y^2 + z^2) \left( \frac{3}{z^2} - \frac{5a^2}{z^4} \right)^2 \right\}$$

$$= \frac{x^2}{z^6} \left\{ + \frac{6a^2}{z^2} - \frac{10a^4}{z^4} + \frac{4a^2 x^2}{z^2} \left( \frac{3}{z^2} - \frac{5a^2}{z^4} \right) + (x^2 + y^2 + z^2) \left( \frac{3}{z^2} - \frac{5a^2}{z^4} \right)^2 \right\}$$

$$\left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial v}{\partial x} \right)^2 + \left( \frac{\partial w}{\partial z} \right)^2 = \frac{4}{z^6} \left\{ \frac{N^2 x^2 y^2 z^2}{z^4} + (z^2 + y^2) \left[ -\frac{a^2}{z^2} + \frac{x^2 N}{z^2} \right]^2 \right\}$$

$$= \frac{4}{z^6} \left\{ \frac{N^2 x^2 y^2 z^2}{z^4} + a^4 (z^2 + y^2) - 2a^2 x^2 (z^2 + y^2) N + x^4 (z^2 + y^2) N^2 \right\}$$



$$\Phi = \frac{2}{n^{10}} \left\{ \begin{aligned} & -3x^2z^4 \\ & a^4x^2 + 6a^2x^2 - 4a^2x^2N + x^2(z^4 + y^4 + z^4)N^2 + \\ & 2a^2(z^2 + y^2) - 4a^2x^2(z^2 + y^2)N + 2x^2(z^2 + y^2)N^2 + 2N^2x^2y^2z^2 \\ & - 4a^2Nx^2 \left[ \underbrace{x^2 + 2z^2 + y^2}_{(2a^2 + 2y^2)x^2} \right] + N^2x^2 \left\{ \underbrace{x^4 + y^4 + z^4 + 2x^2z^2 + 2x^2y^2 + 2y^2z^2}_{= N^2x^2z^4} \right\} \end{aligned} \right\}$$

$$= \frac{2}{n^{10}} \left\{ \begin{aligned} & -3x^2z^4 \\ & a^4(x^2 + 2z^2 - 2x^2) + 6a^2x^2x^2 - 4a^2Nx^2 \cancel{\dots} + N^2x^2z^4 = \\ & \underbrace{-3x^2z^4}_{-3x^2z^4} \\ & = 2n^2a^4 + a^4x^2 + 6a^2x^2x^2 - 4a^2x^2z^2N + \cancel{\dots} + x^2z^4N^2 \end{aligned} \right\}$$

$$N = -3 + 5 \frac{a^2}{n^2}$$

$$\begin{aligned} & -3x^2z^4 \\ & + 2a^4x^2 + a^4x^2 + 6a^2x^2x^2 + 12a^2x^2x^2 - 20a^4x^2 - \cancel{\dots} + \\ & + 9x^2z^4 - 30a^2x^2x^2 + 25a^4x^2 = \\ & \cancel{\dots} + 2a^4x^2 + 4a^4x^2 - 12a^2x^2x^2 - \cancel{\dots} + 6x^2z^4 \end{aligned}$$

$$\begin{aligned} \Phi &= 2 \cdot \frac{9}{16} \frac{c^2 a^2}{n^{10}} \left\{ \dots \right\} \\ &= \frac{9}{8} \frac{c^2 a^2}{n^4} \left\{ \left[ 2 \frac{a^4}{n^4} - 12 \frac{a^2 x^2}{n^4} + 4 \frac{a^4 x^2}{n^6} \right] - \cancel{\dots} + \cancel{\dots} \right\} \end{aligned}$$

$$k \operatorname{div}' + (u_0 \frac{\partial f_0}{\partial x} + \dots) = (k-1) \Phi_\mu$$

$$\operatorname{div}' = -\frac{1}{k} (u_0 \frac{\partial \eta_0}{\partial x} - \dots) + \frac{k-1}{k} \mu \Phi + u \Delta \eta$$

zatem doch o výrazu  $\Phi$  jako  $\Delta^2 \eta$



Do dymyści:

$$\alpha \Delta^2 \left( \frac{x^4}{2^{10}} \right) = 12 \frac{x^2}{2^{10}} + 10 \frac{x^4}{2^{12}}$$

$$\beta \Delta^2 \left( \frac{x^4}{2^8} \right) = 12 \frac{x^2}{2^8} - 8 \frac{x^4}{2^{10}}$$

$$\gamma \Delta^2 \left( \frac{x^2}{2^8} \right) = \frac{2}{2^8} + 24 \frac{x^2}{2^{10}}$$

$$\delta \Delta^2 \left( \frac{x^2}{2^6} \right) = \frac{2}{2^6} + 6 \frac{x^2}{2^8}$$

$$\varepsilon \Delta^2 \left( \frac{x^2}{2^4} \right) = \frac{2}{2^4} - 4 \frac{x^2}{2^6}$$

$$\zeta \Delta^2 \left( \frac{1}{2^4} \right) = \frac{12}{2^6}$$

$$\eta \Delta^2 \left( \frac{1}{2^2} \right) = \frac{2}{2^4}$$

$$\vartheta \Delta^2 \left( \frac{1}{2^6} \right) = \frac{30}{2^8}$$

$$\alpha = a^6$$

$$\beta = \frac{3}{4} a^4$$

$$\mu = -\frac{1}{8} a^6$$

$$\delta = -\frac{29}{6} a^4$$

$$\vartheta = \frac{3}{40} a^6$$

$$\varepsilon = -\frac{9}{4} a^2$$

$$\eta = +\frac{9}{4} a^2$$

$$\zeta = \frac{29}{36} a^4$$

~~10 a^6~~

$$10 \alpha = 10 a^6$$

$$+ 8 \beta = 6 a^4$$

$$12 \alpha + 24 \mu = 9 a^6$$

$$12 \beta + 6 \delta = -20 a^4$$

$$+ 30 \vartheta = 2 a^6$$

$$-4 \varepsilon = 9 a^2$$

$$2 \delta + 12 \zeta = 0$$

$$2 \varepsilon + 2 \eta = 0$$

$$4 \alpha + 8 \mu = 3 a^6$$

$$\mu = \frac{3 a^6 - 4 a^6}{8}$$

$$3 \delta = -10 a^4 - 6 \mu = -10 a^4 - \frac{9}{2} a^4 = -\frac{29}{2} a^4$$

$$30 \vartheta = 2 a^6 + \frac{1}{4} a^6 = \frac{9}{4} a^6$$

$$\phi = \Delta^2 \chi$$

$$\chi = \frac{a^2}{8} \left[ \frac{a^6 x^4}{2^{10}} + \frac{3}{4} \frac{a^4 x^4}{2^8} - \frac{1}{8} \frac{a^6 x^2}{2^8} - \frac{29}{6} \frac{a^4 x^2}{2^6} - \frac{9}{4} \frac{a^2 x^2}{2^4} + \frac{29}{36} \frac{a^4}{2^4} + \frac{9}{4} \frac{a^2}{2^2} + \frac{3}{40} \frac{a^6}{2^6} \right]$$



$$\frac{k-1}{k} \mu \chi = \frac{k-1}{k} \mu \frac{q c^2}{8} \left[ \frac{a^6 x^4}{2^{10}} + \frac{2}{4} \frac{a^4 x^4}{2^8} - \frac{1}{8} \frac{a^6 x^2}{2^8} - \frac{29}{6} \frac{a^4 x^2}{2^6} - \frac{9}{4} \frac{a^2 x^2}{2^5} \right. \\ \left. + \frac{3}{40} \frac{a^6}{2^6} + \frac{29}{26} \frac{a^4}{2^4} + \frac{9}{4} \frac{a^2}{2^2} \right]$$

$$\frac{\partial}{\partial x} = \frac{k-1}{k} \mu \frac{q c^2}{8} \left[ \frac{4 a^6 x^3}{2^{10}} + \frac{3 a^4 x^3}{2^8} - \frac{1}{4} \frac{a^6 x}{2^8} - \frac{29}{3} \frac{a^4 x}{2^6} - \frac{9}{2} \frac{a^2 x}{2^4} + \right. \\ \left. - \frac{10 a^6 x^5}{2^{12}} - 6 \frac{a^4 x^5}{2^{10}} + \frac{a^6 x^3}{2^{10}} + 29 \frac{a^4 x^3}{2^8} + 9 \frac{a^2 x^3}{2^6} \right. \\ \left. - \frac{9}{20} \frac{a^6 x}{2^8} - \frac{29}{9} \frac{a^4 x}{2^6} - \frac{9}{2} \frac{a^2 x}{2^4} \right]$$

$$a=a: \quad [ ] = -16 \frac{x^5}{a^6} + 46 \frac{x^3}{a^4} - \frac{2033}{90} \frac{x}{a}$$

$$\begin{array}{r} 3 \\ + 54 \\ \hline 116 \\ \frac{173}{12} + \frac{99}{20} + \frac{29}{9} = \\ \frac{173}{12} = \frac{865}{60} \\ \frac{865}{60} + \frac{2995}{60} = \frac{3860}{60} = \frac{2033}{30} \end{array}$$

$$\begin{array}{r} 2595 \\ 891 \\ \hline 580 \\ \frac{4066}{180} = \frac{2033}{90} \end{array}$$



(6D)  $\gamma =$

268

$$\cancel{-\frac{9}{8}} \frac{c^2 a^2 x^3}{2^8} \left(1 - \frac{a^2}{2^2}\right) + \frac{3}{2} \frac{c^2 a^2 x^2}{2^5} \left(1 - \frac{3}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3}\right) +$$

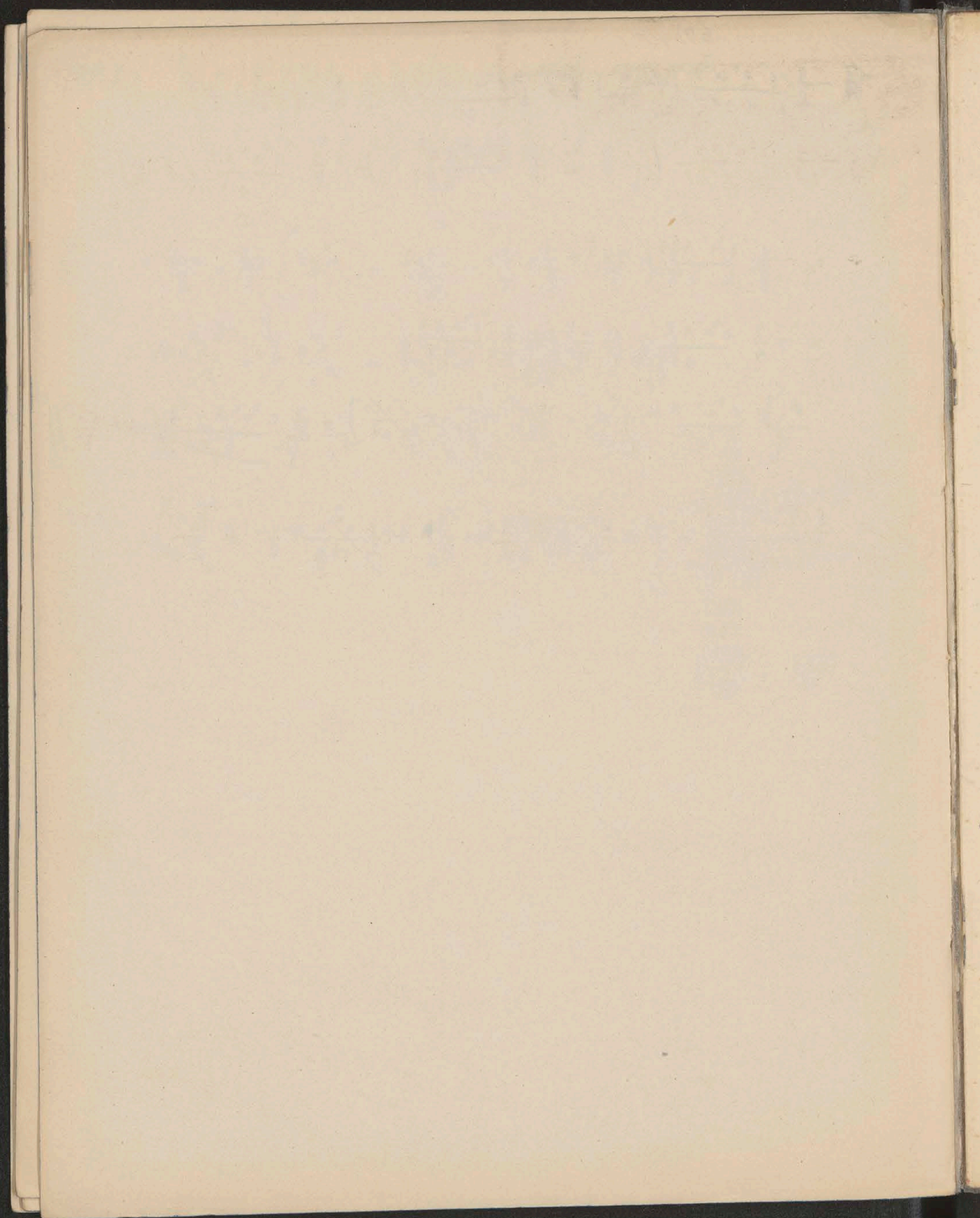
$$-\frac{9}{8} \frac{c^2 a^2 x y^2}{2^8} \left( \right) - \frac{9}{8} \frac{c^2 a^2 x^2}{2^8} \left( \right) + \frac{3}{8} \frac{c^2 a^2 x^2}{2^6} \left(1 - \frac{a^2}{2^2}\right)$$

$$= -\frac{9}{8} \frac{c^2 a^2 x^2}{2^6} \left( \right) + \frac{3}{8} \dots$$

$$= -\frac{3}{4} \frac{c^2 a^2 x^2}{2^6} \left(1 - \frac{a^2}{2^2}\right) + \frac{3}{2} \frac{c^2 a^2 x^2}{2^5} \left( \right)$$

$$\cancel{-\left\{ \frac{3}{8} \frac{c^2 a^2 x^2}{2^3} \left[ \frac{1}{2^3} - \frac{3y}{2^5} - \frac{a^2}{2^5} + \frac{5y^2}{2^7} \right] - \frac{3}{8} \frac{c^2 a^2 x y^2}{2^8} \left[ -3 + \frac{a^2}{2^2} \right] \right\}}$$

$$= \frac{3}{4} \frac{c^2 a^2 x^2}{2^6} \left\{ -1 + \frac{a^2}{2^2} + \frac{2x}{a} - \frac{3}{2} - \frac{1}{2} \frac{a^2}{2^2} - \frac{1}{2} + \frac{a^2}{2^2} \right\}$$





$$u \frac{\partial v}{\partial x} + v \frac{\partial u}{\partial y} + u \frac{\partial v}{\partial z} = \frac{9}{16} c^2 a^2 \left(1 - \frac{a^2}{2^2}\right) \frac{x}{2^3} \left\{ xy \left[ \frac{1}{2^3} - \frac{3x^2}{2^5} - \frac{a^2}{2^5} + \frac{5a^2 x^2}{2^7} \right] + \right. \quad 269$$

$$xy \left[ \frac{1}{2^3} - \frac{3x^2}{2^5} - \frac{a^2}{2^5} + \frac{5a^2 x^2}{2^7} \right] + \frac{xy z^2}{2^5} \left[ -3 + \frac{5a^2}{2^2} \right] \left. - \frac{3c^2 a}{4} y \right\} \uparrow \left(1 - \frac{3}{4} \frac{a^2}{2} - \frac{5}{4} \frac{a^2}{2^3}\right)$$

$$= \frac{9}{16} c^2 a^2 \left(1 - \frac{a^2}{2^2}\right) \frac{x}{2^3} \left\{ 2xy \left( \frac{1}{2^3} - \frac{a^2}{2^5} \right) - \frac{3xy}{2^3} + \frac{5a^2 xy}{2^5} \right\} - \uparrow$$

$$- \frac{xy}{2^3} + \frac{5a^2 xy}{2^5}$$

$$= \frac{9}{16} c^2 a^2 \left(1 - \frac{a^2}{2^2}\right) \frac{xy}{2^6} \left[ -1 + \frac{3a^2}{2^2} \right] - \frac{3}{4} c^2 a y \frac{1}{2^3} \left[ 1 - \frac{3}{4} \frac{a^2}{2} - \frac{1}{4} \frac{a^2}{2^3} \right] \left[ 1 - \frac{3a^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right]$$

$$= -\frac{3}{4} c^2 a y \frac{1}{2^3} \left[ 1 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right] + \frac{3}{4} c^2 a y \frac{1}{2^6} \left\{ \frac{3}{4} a x^2 \left( -1 + \frac{2a^2}{2^2} - \frac{6a^4}{2^4} \right) + \right.$$

$$\left. + \frac{3}{4} a \left( x^2 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right) + \frac{1}{4} a^3 \left( 1 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right) \right\}$$

$$\{ \} = +\frac{3}{4} a x^2 - 3a x^2 - \frac{1}{2} a^3 + \frac{a^3 x^2}{2^2} - \frac{1}{4} \frac{a^5}{2^2} - \frac{13}{4} \frac{a^5 x^2}{2^4}$$

$$= -\frac{3}{4} c^2 a y \frac{1}{2^3} \left[ 1 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right] + \frac{3}{4} c^2 a y \frac{1}{2^6} \{ \}$$

$$u \frac{\partial u}{\partial x} + \dots = -\frac{3}{4} c^2 a \frac{1}{2^3} \left[ 1 - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right] + \frac{3}{4} c^2 a \frac{1}{2^6} \{ \}$$

$$\Phi = \frac{1}{2} c^2 a^2 \left[ \frac{1}{2^6} + \frac{1}{2^6} \right] + \frac{3}{2} c^2 a \left[ \frac{1}{2^3} + \frac{3x^2}{2^5} + \frac{1}{2^3} - \frac{5a^2 x^2}{2^5} - \frac{3a^2}{2^3} - \frac{1}{2^6} + \frac{6a^2 x^2}{2^6} - \right.$$

$$- \frac{a^2}{2^{10}} - \frac{3x^2}{2^5} \left[ x + \frac{3x^2}{2^2} + \frac{3x^2}{2^2} - \frac{5a^2 x^2}{2^4} - \frac{3a^2}{2^2} - \frac{2a^2}{2^3} + \frac{6a^2 x^2}{2^5} - \frac{a^2 x^2}{2^7} \right] + \frac{x}{2^3} \left[ \frac{6x^2}{2^2} - \right.$$

$$- \frac{a^2}{2^4} - \frac{6a^2 x^2}{2^4} - \frac{10a^2 x^2}{2^4} + \frac{40a^2 x^2}{2^6} - \frac{6a^2 x^2}{2^3} + \frac{9a^2 x^2}{2^5} + \frac{6a^2 x^2}{2^5} + \frac{12a^2 x^2}{2^5} - \frac{30a^2 x^2}{2^7} - \frac{2a^2 x^2}{2^7} + \frac{7a^2 x^2}{2^9} \left. \right]$$

$$- \frac{2}{2^3} \left[ x - \frac{3x^2}{2^2} - \frac{a^2}{2^2} + \frac{5a^2 x^2}{2^4} \right] + \frac{2}{2^6} \left[ \frac{3}{4} x^2 - \frac{3a^2 x^2}{2^2} - \frac{1}{2} a^3 + \frac{a^3 x^2}{2^2} - \frac{1}{4} \frac{a^5}{2^2} - \frac{13}{4} \frac{a^5 x^2}{2^4} \right]$$

$$- (y^2 + z^2) \left[ \frac{15x^2}{2^7} + \frac{5a^2}{2^7} - \frac{35a^2 x^2}{2^9} + 3 \frac{a^2}{2^6} - 18 \frac{a^2 x^2}{2^8} + 3 \frac{a^2}{2^8} - 8 \frac{a^2 x^2}{2^{10}} + 2 \frac{a^5}{2^{10}} + \frac{65a^5 x^2}{2^{12}} \right]$$



$$\Phi = \frac{c^2 a^2}{4} \left( \frac{r^2 - x^2}{2b} \right) + \frac{3}{2} c^2 a$$

$$\frac{85}{2} \frac{x^4}{x^{12}} - 40 \frac{x^2}{x^{10}} - 56 \frac{x^4}{x^{10}} + 43 \frac{x^2}{x^8} - \cancel{\frac{11}{x^6}} - \frac{5}{2} \frac{1}{x^4} - 10 \frac{x^2}{x^6}$$

$$- 6 \frac{1}{x^6} - \frac{3}{2} \frac{1}{x^4} + \cancel{\frac{1}{x^2}} + \frac{3x^3}{x^5} - \frac{3}{x^3}$$

Any particular view to capt. cannot:

$$\rho \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) + \cancel{u \frac{\partial \rho}{\partial x}} + \cancel{v \frac{\partial \rho}{\partial y}} + \cancel{w \frac{\partial \rho}{\partial z}} = 0 \quad \underline{\underline{\text{div} = 0}}$$

isthmus diviso da  $x=0$

istotini di!  $\approx 0$  dla  $x \approx a$   
to energia; składowe  $x, y$  <sup>jako styczne do powierzchni</sup> <sub>(w kierunku przodu i wzdłuż)</sub>

$$\frac{\partial \psi}{\partial z} = 0 \quad \text{pour } v=0, \quad \frac{\partial v}{\partial x} = 0, \quad \frac{\partial w}{\partial z} = 0, \quad \frac{\partial w}{\partial y} = 0$$

$$u=0 \quad \frac{\partial u}{\partial x} = 0 \quad \frac{\partial u}{\partial y} = 0 \quad \frac{\partial u}{\partial z} \geq 0$$

$$u=0 \quad \frac{\partial u}{\partial x} \rightarrow 0 \quad \frac{\partial u}{\partial y} \rightarrow 0 \quad \frac{\partial u}{\partial z} \rightarrow 0$$

jinli jedné rostliny II:

Jediné řešení  $\frac{III}{k-1}$   
 $\frac{k-1}{k-1} + \left( \frac{\partial f}{\partial x} \right) = (k-1) \left[ \frac{\Phi}{1} + \kappa \Delta \theta \right]$

$$0 = \cancel{\left(\frac{\partial u}{\partial z}\right)^2} + \kappa \Delta^2 \theta$$

there is no product thus  $\kappa \frac{\partial^2 \theta}{\partial n^2} = \kappa \left( \frac{\partial u}{\partial n} \right)^2$

wie so wichtig ist Stern?

wie für die  $\frac{\partial u}{\partial n}$  ist  $\frac{\partial u}{\partial n} = 0$

K is inter mechanism :  $K = 0.00058 \cdot 42 \cdot 10^6 = \underline{42.58} = 24.9$



Nie zaniedbujcie  $\kappa$  strzegajcie się jego wartości III:

270  
 $\Phi$

$$\theta = \theta_0 + \frac{1}{\rho} \theta'$$

$$k \operatorname{div}' = -\left(u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z}\right) + (k-1) \left[\Phi_0 + \kappa \Delta^2 \theta_0\right]$$

$$\rho = \rho_0 + \frac{1}{\rho} \rho' + \frac{1}{2} \frac{1}{\rho^2} \rho'' + \dots$$

$$\left\{ \begin{array}{l} \frac{\partial \rho_0}{\partial x} = \frac{\mu}{\gamma} \frac{\partial \operatorname{div}_0}{\partial x} + \mu \Delta^2 u_0 \\ \dots \end{array} \right.$$

$$\operatorname{div}_0 = 0$$

wystarczy do oznaczenia  $\rho, u, v, w$

$$\frac{\partial}{\partial x} (\rho_0 u_0) + \frac{\partial}{\partial y} (\rho_0 v_0) + \frac{\partial}{\partial z} (\rho_0 w_0) = 0$$

$$\rho_0 \operatorname{div}_0 + u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z} = 0$$

bedzie spełnione przez  $\rho_0 = \text{const}$

~~zatem  $\rho_0 = \text{const}$~~

(ale czy koniecznie?)

Przebiegiem:

$$\frac{dx}{u_0} = \frac{dy}{v_0} = \frac{dz}{w_0} = \dots$$

określa położenie linii prądu

Zatem our równani wyraża, że wartości linii prądu  $\rho$  nie zmieniają, ale od położenia drugiego współrzędnej zmieniają, zatem  $\rho$  jest stałe, bo w każdym punkcie  $\rho$  będzie jednakowe względem

zatem względem  $\rho = \text{const}$

$$\left(\rho + \rho_0 + \frac{1}{\rho} \rho' + \dots\right) = R(\theta_0 + \frac{1}{\rho} \theta' + \dots) (\cos \theta + \frac{1}{\rho} \rho' + \dots)$$

$$\frac{\partial \rho'}{\partial x} = \frac{\mu}{\gamma} \frac{\partial \operatorname{div}'}{\partial x} + \mu \Delta^2 u'$$

$$k \operatorname{div}' = -\left(u_0 \frac{\partial \rho_0}{\partial x} + \dots\right) + (k-1) \Phi_0$$

$$\frac{\partial}{\partial x} (\rho_0 u' + \rho' u_0) + \frac{\partial}{\partial y} (\rho_0 v' + \rho' v_0) + \frac{\partial}{\partial z} (\rho_0 w' + \rho' w_0) = 0$$

to będzie oznaczanie dla  $\rho'$  i stażę wyznaczenie  $\rho'$

$$\rho_0 \operatorname{div}' + \rho' \operatorname{div}_0 + u' \frac{\partial \rho_0}{\partial x} + v' \frac{\partial \rho_0}{\partial y} + w' \frac{\partial \rho_0}{\partial z} = 0$$

$$u_0 \frac{\partial \rho'}{\partial x} + v_0 \frac{\partial \rho'}{\partial y} + w_0 \frac{\partial \rho'}{\partial z} = -\frac{\partial}{\partial x} (\rho_0 u_0) + \frac{\partial}{\partial y} (\rho_0 v_0) + \frac{\partial}{\partial z} (\rho_0 w_0) = 0$$

Rozwiązanie:

$$\frac{dx}{u_0} = \frac{dy}{v_0} = \frac{dz}{w_0} = \frac{d\rho'}{R}$$

to mi powiedz, bo jeżeli  $\frac{d\rho'}{R}$  ma być

to tożsamość  $\frac{d\rho}{\rho}$  ma być

$$\rho = \rho_0 + \frac{1}{\rho} \rho'$$

$$I. \quad u_0 \frac{\partial \rho_0}{\partial x} + v_0 \frac{\partial \rho_0}{\partial y} + w_0 \frac{\partial \rho_0}{\partial z} + \rho_0 \operatorname{div}_0 = 0$$

może wtedy  $\rho_0$  zatem  $\operatorname{div}_0 = 0$



Inna metoda: warunek zerowego izotermicznego potencjału (Izotermiczny potencjał temperatury)

Trzeci raz geometrycznie:

Złożenie fundamentalne: niech taki że  $\Delta p$  małe wobec  $p$

$$p = R\theta\rho$$

[Np. zamknięte naczynie]

$$\frac{dp}{p} = \frac{d\theta}{\theta} + \frac{d\rho}{\rho}$$

$$I. \frac{dp}{dx} = \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{\mu}{\partial x} + \frac{\mu}{\partial y} + \frac{\mu}{\partial z} \right) + \mu \nabla^2 u$$

$$IV. p = R\theta\rho$$

$$II. \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$III. k p \operatorname{div} + \left( u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z} \right) = (k-1) \left[ \mu \Phi + \kappa \Delta^2 \theta \right]$$

$$II. \rho \operatorname{div} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = 0$$

$$II. \operatorname{div} + \frac{u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z}}{p} = - \frac{u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z}}{\theta} = 0$$

$$III. (1-k) \left( u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z} \right) + k \frac{\mu}{\theta} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = (k-1) \left[ \mu \Phi + \kappa \Delta^2 \theta \right]$$

$$\frac{kR}{k-1} \rho \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = \mu \Phi + \kappa \Delta^2 \theta + \left( u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z} \right)$$



zicli  $\Delta p$  mato w powiazaniu dop, to taki div bardzo malo

$$\rho = \rho_0 + \rho' \quad \text{const} \quad 271$$

$$u \text{ or } p \dots \theta = u_0 + \frac{1}{\rho_0} u' + \dots$$

$$II). (\rho_0 + \rho')(\text{div}_0 + \frac{1}{\rho_0} \text{div}' + \dots) + (u_0 + \frac{1}{\rho_0} u' + \dots) \frac{\partial \rho'}{\partial x} + (v_0 + \frac{1}{\rho_0} v' + \dots) \frac{\partial \rho'}{\partial y} + \dots = 0$$

$$1). \text{div}_0 = 0$$

$$2). \cancel{\rho} \text{div}_0 + \text{div}' + u_0 \frac{\partial \rho'}{\partial x} + v_0 \frac{\partial \rho'}{\partial y} + \dots = 0$$

$$\text{div}' = - (u_0 \frac{\partial \rho'}{\partial x} + v_0 \frac{\partial \rho'}{\partial y} + \dots)$$

$$IV). \rho_0 + \frac{1}{\rho_0} \rho' + \dots = R (\theta_0 + \frac{1}{\rho_0} \theta' + \dots) (\rho_0 + \rho')$$

zicli znowa jest  $\frac{\rho_0}{\rho_0}$  tego samego rodzaju co  $\rho$  etc.

$$1). \rho_0 = R \theta_0 \rho_0$$

$$2). \rho' = R \theta' + R \theta_0 \rho'$$

$$I). 1). \frac{\partial \rho_0}{\partial x} = \frac{\mu}{\gamma} \frac{\partial \text{div}_0}{\partial x} + \mu \nabla^2 u_0$$

$$2). \frac{\partial \rho'}{\partial x} = \frac{\mu}{\gamma} \frac{\partial \text{div}'}{\partial x} + \mu \nabla^2 u'$$

$$II). k (\rho_0 + \frac{1}{\rho_0} \rho' + \dots) (\cancel{\text{div}_0} + \frac{1}{\rho_0} \text{div}' + \dots) + (u_0 + \frac{1}{\rho_0} u' + \dots) (\frac{\partial \rho_0}{\partial x} + \frac{1}{\rho_0} \frac{\partial \rho'}{\partial x} + \dots) =$$

$$= (k-1) \left[ \mu (\Phi_0 + \frac{1}{\rho_0} \Phi') + k (\Delta \theta_0 + \frac{1}{\rho_0} \Delta \theta') \right]$$

\* Mno:

$$\frac{kR}{k-1} (\rho_0 + \rho') \left[ (u_0 + \frac{1}{\rho_0} u' + \dots) \left( \frac{\partial \theta_0}{\partial x} + \frac{1}{\rho_0} \frac{\partial \theta'}{\partial x} + \dots \right) + \dots \right] = \mu \Phi_0 + \frac{1}{\rho_0} \Phi' + \dots$$

$$+ \mu (u_0 + \frac{1}{\rho_0} u' + \dots) (\nabla^2 u_0 + \frac{1}{\rho_0} \nabla^2 u' + \dots)$$

$$+ k \Delta \theta_0 + \frac{1}{\rho_0} \Delta \theta' + \dots$$

$$k \frac{\mu}{\rho_0} \text{div}' + u_0 \frac{\partial \rho_0}{\partial x} = (k-1) \left[ \mu \Phi_0 + k \Delta \theta_0 \right]$$

$$k R \theta_0 \text{div}' + u_0 \frac{\partial \rho_0}{\partial x} = \nearrow$$



wyz dla  $\theta$  równani formy:

$$\Delta^2 \theta + \theta \varphi(x, y, z) = \varphi(x, y, z)$$

$$p = \text{const}$$

$$= \text{const} \cdot f(\underbrace{P, \theta, x, y, z}_{\text{zmiennych } P: \text{ każdy z nich wybrany } p \text{ w } P = \text{parametr}})$$

$\frac{1}{P}$  zmiennych  $P$ : każdy z nich wybrany  $p$  w  $P = \text{parametr}$

Czy chodzi o równanie stare:

$$p = \text{const} + p_0 + \frac{1}{P} p' + \frac{1}{P^2} p'' + \dots$$

$$= f(0, \theta, x, y, z) + \frac{1}{P} \frac{\partial f}{\partial x} + \theta \frac{\partial f}{\partial \theta}$$

możemy więc napisać II dla  $\theta$ :

stąd na równani dla  $\theta$  a 2 typy równań II dla  $\theta$

określmy dla 2 II III:

$$IV. (1-k) \left( u \frac{\partial \theta}{\partial x} + \dots \right) + k \frac{1}{\theta} \left( u \frac{\partial \theta}{\partial x} + \dots \right) = (k-1) \left[ \mu \Phi \sin \theta \right]$$

obliczmy jego pierwsze wyrażenie wybrany odpowiednio:

$$\mu \Phi + k \Delta^2 \theta = 0$$

2 typy  $\theta'$  a 2 typy równań I dla  $\theta$

obliczmy jego pierwsze wyrażenie wybrany odpowiednio

$$\mu \Phi + k \Delta^2 \theta' = - \left( u_0 \frac{\partial \theta}{\partial x} + \dots \right)$$

Która z powyższych typów jest właściwa?

$P = \text{równanie w określonej dziedzinie}$   
 $\theta = \text{stała całkowa}$

zmienna mechaniczna  
 $= 0.000057, 42, 10^6$



Metoda:

Próbna przybliżenie  $\text{div} = 0$ 

I).  $\int \frac{\partial \Phi_0}{\partial x} = \mu \nabla^2 u_0$

$$\left\{ \begin{array}{l} \text{div}_0 = 0 \end{array} \right.$$

Drugie przybliżenie:  $u_0 \frac{\partial \Phi_0}{\partial x} + v_0 \frac{\partial \Phi_0}{\partial y} + w_0 \frac{\partial \Phi_0}{\partial z} = (k-1) [\mu \Phi_0 + \kappa \Delta^2 \Phi_0]$

2 typy  $\Phi_0$ 

Drugie przybliżenie:

IV).  ~~$\frac{dp}{\rho} = \frac{d\Phi}{\rho} - \frac{d\theta}{\theta}$~~

II).  $\text{div}' = - \frac{u_0 \frac{\partial \Phi_0}{\partial x} + v_0 \frac{\partial \Phi_0}{\partial y} + w_0 \frac{\partial \Phi_0}{\partial z}}{\rho_0} + \frac{u_0 \frac{\partial \theta_0}{\partial x} + \dots}{\theta_0}$

I).  $\frac{\partial \Phi'}{\partial x} = \frac{\mu}{\rho} \frac{\partial \text{div}'}{\partial x} + \mu \nabla^2 u'$

$$\nabla^2 \rho' = \frac{4}{3} \nabla^2 \text{div}'$$

$$\rho' = \frac{4}{3} \text{div}' + \text{const}$$

Pytanie jak poprawić rozwiązanie

II).  $\text{div} + \frac{u \frac{\partial \Phi}{\partial x} + v \frac{\partial \Phi}{\partial y} + \dots}{\rho} - \frac{u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + \dots}{\theta} = 0$

III).  $k \rho \text{div} + (u \frac{\partial \Phi}{\partial x} + \dots) = (k-1) [\mu \Phi + \kappa \Delta^2 \Phi]$

u drugie przybliżenie

umyślnie nie pominąć II.2  $\text{div} = 0$  stąd mamy  $\frac{d\rho}{\rho} = + \frac{d\theta}{\theta}$   
 $\rho \sim \theta$ 

2 typy poprawek II:

$$\text{div} = \dots$$

~~$(k-1) \mu \Phi + \kappa \Delta^2 \Phi = \dots$~~



obstępnym I i III:

$$(k-1) \mu \operatorname{div} = - \frac{1}{\theta} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + (k-1) \left[ \mu \Phi + \kappa \Delta \theta \right]$$

Wziąć A&S które charakteryzują błąd [przydane x etc.] przybliżenie takie:

Przy P: (H)

Najmniejszą wartość P bierze dźw: (H) bierze dźw: w porównaniu do  $\frac{\Delta P}{\Delta \theta}$

Wtedy II:  $\operatorname{div} = 0$

zatem ruch przez I i II wymaga skrócenia

0 jest wtedy obciążenie ~~istotnie nie problem dla przybliżenia~~

musi być obciążenie z III z uwzględnieniem przybliżenia wartości P 0:

$$(1-k) \left( u \frac{\partial \theta}{\partial x} + \dots \right) = - k \frac{P}{\theta} \left( u \frac{\partial \theta}{\partial x} + \dots \right) + (k-1) \left( \mu \Phi + \kappa \Delta \theta \right)$$

Sprowadzić równanie jeszcze raz

$$1. \frac{1}{\mu} \frac{\partial \theta}{\partial x} \ll \frac{1}{\theta} \frac{\partial \theta}{\partial x}$$

Wtedy: II przybliżony kształt:  $u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = 0$   
 $\theta = \text{const}$  istotnie.

$$2. \frac{1}{\mu} \frac{\partial \theta}{\partial x} \gg \frac{1}{\theta} \frac{\partial \theta}{\partial x}$$

$$(1-k) \left( u \frac{\partial \theta}{\partial x} + \dots \right) = (k-1) \left[ \mu \Phi + \kappa \Delta \theta \right]$$

$$u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} \approx \frac{\partial \theta}{\partial z} + \mu \Phi = - \kappa \Delta \theta$$

to same bytoby drugim  
 przybliżeniem z(1)

Pytanie czy składowe równania III składowe:

zatem oryginalnie było więcej  
 tego nie pisał



2.  $\theta$  is the total dimension minus right II. ~~straight line~~

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i.e.  $\theta$  as I noted previously

Zero derivative to  
 $\left\{ \frac{2a^4}{r^4} + \left(6 - \frac{12a^2}{r^2} + \frac{4a^4}{r^4}\right) \omega \right\}$   
 minimum at  $\theta = 0$   
 $= 6 \left[ 1 - \frac{a^2}{r^2} \right]^2 \geq 0$

$$\Phi = \frac{q}{8} \frac{c^2 a^2}{r^4} \left\{ 6 \frac{x^2}{r^2} + \frac{2a^4}{r^4} - \frac{12a^2 x^2}{r^4} + \frac{4a^4 x^4}{r^6} \right\}$$

$$\Delta^2 \left( \frac{x^2}{r^8} \right) = \frac{2}{r^8} + 24 \frac{x^2}{r^{10}}$$

$\alpha$

$$24\alpha = 4a^4$$

$$\alpha = \frac{a^4}{6}$$

$$\Delta^2 \left( \frac{x^2}{r^6} \right) = \frac{2}{r^6} + 6 \frac{x^2}{r^8}$$

$\beta$

$$30\beta + 2\alpha = 2a^4$$

$$15\beta = a^4 - \frac{2}{3}\alpha = \frac{a^4}{3} \quad \beta = \frac{a^4}{18}$$

$$\Delta^2 \left( \frac{x^2}{r^4} \right) = \frac{2}{r^4} - 4 \frac{x^2}{r^6}$$

$\gamma$

$$2\gamma + 12\delta = 0$$

$$\beta = -\frac{a^4}{2}$$

$$\Delta^2 \left( \frac{1}{r^4} \right) = \frac{12}{r^6}$$

$\delta$

$$-4\gamma = 6$$

$$\delta = \frac{a^4}{12}$$

$$\Delta^2 \left( \frac{1}{r^2} \right) = \frac{2}{r^4}$$

$\epsilon$

$$2\gamma + 2\epsilon = 0$$

$$\epsilon = \frac{3}{2}$$

$$\Delta^2 \left( \frac{1}{r^6} \right) = \frac{30}{r^8}$$

$\zeta$

$$\Phi_0 = \Delta^2 \left\{ \frac{q}{8} \frac{c^2 a^2}{r^4} \left[ \frac{1}{6} \frac{x^4}{r^8} - \frac{1}{2} \frac{a^2 x^2}{r^6} + \frac{1}{18} \frac{a^4}{r^4} - \frac{3}{2} \frac{x^2}{r^4} + \frac{1}{12} \frac{a^2}{r^2} + \frac{3}{2} \frac{1}{r^2} \right] \right\}$$

$$u_0 \frac{\partial^2}{\partial x^2} + v_0 \frac{\partial^2}{\partial y^2} + w_0 \frac{\partial^2}{\partial z^2} = \Delta^2 \left\{ -\mu c^2 a^2 \left[ \frac{27}{32} \frac{1}{r^2} + \frac{45}{32} \frac{x^2}{r^4} - \frac{3}{16} \frac{a^2 x^2}{r^6} \right] - \mu c^2 a^2 \cdot \frac{3}{4} \frac{x^2}{r^3} \right\}$$

$$\Delta^2 \theta = \Delta^2 \psi$$

$$\theta = \psi + u$$

$$\Delta^2 u = 0$$

$$r=a \quad \theta_0 = \psi_0 + u_0$$

$$r=\infty \quad u=0$$

$$u = \frac{\mu}{h} c^2 a^2 \left[ -\frac{27}{32} \frac{1}{r^2} + \frac{9}{32} \frac{x^2}{r^4} - \frac{3}{32} \frac{a^2}{r^4} - \frac{1}{162} \frac{a^4}{r^6} + \frac{3}{8} \frac{a^2 x^2}{r^6} - \frac{3}{16} \frac{a^4 x^2}{r^8} \right] + \frac{\mu}{h} c^2 a^2 \frac{3}{4} \frac{x^2}{r^3}$$



$$U_0|_{r=a} = -\frac{\mu}{\kappa} c^2 \left[ \underbrace{-\frac{27}{32} - \frac{3}{32} - \frac{3}{48}}_{-\frac{3}{8} \left( \frac{9}{4} + \frac{1}{4} + \frac{1}{6} \right)} + \underbrace{\left( \frac{9}{32} + \frac{1}{8} - \frac{2}{16} \right) \frac{x^2}{a^2} + \frac{2}{4} \frac{x^2}{a^2}}_{\frac{9+12-6+24}{32} = \frac{39}{32}} \right]$$

$$-\frac{3}{8} \frac{64}{24} = -1$$

$$U_0|_{r=a} = +\frac{\mu}{\kappa} c^2 \left[ 1 - \frac{39}{32} \frac{x^2}{a^2} \right]$$

$$U = \theta_0 + \frac{A}{r} + B \left( \frac{1}{r^3} - \frac{3x^2}{r^5} \right)$$

$$\left. \begin{aligned} \frac{A}{a} + \frac{B}{a^3} &= \frac{\mu c^2}{\kappa} \\ \frac{3B}{a^5} &= -\frac{39}{32} \frac{\mu c^2}{\kappa} \end{aligned} \right\} \begin{aligned} 3 \frac{A}{a} &= \left( 2 - \frac{7}{32} \right) \frac{\mu c^2}{\kappa} \\ &= \frac{57}{32} \frac{\mu c^2}{\kappa} \\ \frac{A}{a} &= \frac{19}{32} \frac{\mu c^2}{\kappa} \\ \frac{B}{a^3} &= -\frac{13}{32} \frac{\mu c^2}{\kappa} \end{aligned}$$

$$U = \theta_0 + \frac{\mu c^2}{32\kappa} \left[ 19 \frac{a}{r} + 13 \left( \frac{a^3}{r^3} - \frac{3x^2 a^3}{r^5} \right) \right]$$

$$\theta = \theta_0 + \frac{\mu c^2}{\kappa} \left\{ \frac{3a^2}{32} \left[ -\frac{9}{r^2} + \frac{3x^2}{24} - \frac{a^2}{24} - \frac{2}{3} \frac{a^4}{r^6} + 4 \frac{a^2 x^2}{26} - 2 \frac{a^4 x^2}{28} \right] + \right.$$

$$\left. \frac{a}{r} \left[ \frac{19}{32} + \frac{13}{32} \frac{a^2}{r^2} + \frac{3}{4} \frac{x^2}{r^2} - \frac{39}{32} \frac{x^2 a^2}{r^4} \right] \right\}$$

Gdyby się to udało zmierz do III

po przynajmniej częściej wydan  $\frac{c\mu}{A\theta\kappa} = \frac{c}{42.273}$







$$(A). \Delta^2 \theta + u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = \psi$$

Jaké 2 proměnné  $\theta_1, \theta_2$ , to máme:

$$\Delta^2(\theta_1 + \theta_2) + u \frac{\partial(\theta_1 + \theta_2)}{\partial x} + v \frac{\partial(\theta_1 + \theta_2)}{\partial y} + w \frac{\partial(\theta_1 + \theta_2)}{\partial z} = 2\psi \quad \left. \begin{array}{l} \text{z toho indukce vyjde} \\ \text{takže zadání není} \end{array} \right\}$$

$$\text{vímco } \Delta^2(\theta_1 - \theta_2) + u \frac{\partial(\theta_1 - \theta_2)}{\partial x} + \dots = 0$$

Jaké máme proměnné zadání rovnice

$$(B). \Delta^2 \theta + u \frac{\partial \theta}{\partial x} + \dots = 0$$

$$\parallel \text{N. p. } \theta = e^{\varphi(x, y, z)}$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial \varphi}{\partial x} e^{\varphi}$$

$$\frac{\partial^2 \theta}{\partial x^2} = \frac{\partial^2 \varphi}{\partial x^2} e^{\varphi} + \left(\frac{\partial \varphi}{\partial x}\right)^2 e^{\varphi}$$

$$\Delta^2 \varphi + \left[ \left(\frac{\partial \varphi}{\partial x}\right)^2 + \left(\frac{\partial \varphi}{\partial y}\right)^2 + \left(\frac{\partial \varphi}{\partial z}\right)^2 \right] + u \frac{\partial \varphi}{\partial x} + v \frac{\partial \varphi}{\partial y} + w \frac{\partial \varphi}{\partial z} = 0$$

Jaké rovnice dle  $\theta$  na plosce  $\theta = \text{const}$ , to adgi je  $\theta = \text{const}$  je plynem

rovnice pro dle  $\theta$  rovnice rovnice  $\Delta^2 \theta + u \frac{\partial \theta}{\partial x} + \dots = 0$

Z toho vyjde že  $\theta_1 - \theta_2 = \text{const}$ , to je plynem rovnice rovnice

Stavíme  $\psi = \Delta^2 \chi$  rovnice (A).

i podobně  $\theta = \vartheta + \chi$  stavíme:

$$\Delta^2 \vartheta + u \frac{\partial \vartheta}{\partial x} + \dots = - \left( u \frac{\partial \chi}{\partial x} + v \frac{\partial \chi}{\partial y} + w \frac{\partial \chi}{\partial z} \right)$$

Pokud  $\Delta^2 \chi = 0$

Pokud  $\Delta^2 \chi = 0$ :  $\theta = \vartheta + \chi$ :

$$\Delta^2 \vartheta + u \frac{\partial \vartheta}{\partial x} + \dots + u \frac{\partial \chi}{\partial x} + v \frac{\partial \chi}{\partial y} + w \frac{\partial \chi}{\partial z} = 0$$

$$\boxed{\vartheta = \theta - \chi}$$



$$\rightarrow \psi = \frac{Ax^2}{2^6} + \frac{B}{2^8} + \frac{Cx^2}{2^8} + \frac{Dx^2}{2^{10}}$$

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$$\theta = \sum m_k \frac{x}{z^k} \quad \text{Ponieważ } \psi \text{ parzysta potęga, a } u, v$$

$$\theta = \sum \text{to } \theta \text{ musi zawierać mianownik parzystej nieparzystej}$$

Skąd  $\Phi=0$  to niedługoż jako jedno miejsce zerowe

$$\theta = \theta_0 + \alpha r$$

$$\left(u \frac{\partial \psi}{\partial x} + \dots\right) \left[1 - \frac{k}{k-1} \frac{P}{\theta} \alpha\right] + \frac{k \Delta^2}{r} = 0$$

$$\text{tzn. } \alpha = \frac{k-1}{k} \frac{\theta}{P}$$

$$\theta = \theta_0 + \frac{k-1}{k} \frac{\theta}{P} r \quad \text{to nie byłoby już ok, a spełniamy 2 warunki dla } z=9$$

zatem to mi trochę nie odpowiada

$$\text{Skąd } k=0 \text{ to musi być } \frac{\partial \psi}{\partial x} = 0$$

Czyli to już wystarczy do naszego rachunku?

Znajdźmy rozwiązanie

$$\Delta^2 \theta + u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + \dots = \Phi \quad \text{stąd wynika iż III przez podstawienie } \theta = \vartheta + \alpha r$$

$$u^2 + v^2 + w^2 = c^2 \left\{ \frac{9}{16} \frac{a^2}{2^4} \left(1 - \frac{a^2}{2^2}\right)^2 x^2 - \frac{3}{2} \frac{a^2}{2^3} \left(1 - \frac{a^2}{2^2}\right) \left(1 - \frac{3}{4} \frac{a^2}{2} - \frac{1}{4} \frac{a^3}{2^3}\right) x^2 + \left(1 - \frac{3}{4} \frac{a^2}{2}\right)^2 \right\}$$

$$x^2 \left[ \frac{9}{16} \left(1 - \frac{a^2}{2^2}\right) \left[ -\frac{3}{2} \frac{a^2}{2^3} + \frac{3}{2} \frac{a^2}{2^4} \left(\frac{3}{4} + \frac{1}{4} \frac{a^2}{2^2}\right) + \frac{9}{16} \frac{a^2}{2^4} \left(1 - \frac{a^2}{2^2}\right) \right] \right] +$$

$$\frac{3}{2^4} \left( \frac{27}{16} - \frac{3}{16} \frac{a^2}{2^2} \right)$$



Wskazujmy wyrażenie zadanie domygniawione; przy uw

$$u = -\frac{1}{\omega} \frac{\partial \psi}{\partial x}$$

$$v = \frac{1}{\omega} \frac{\partial \psi}{\partial y}$$

$$2 \frac{\partial^2 (\theta x)}{\partial x^2} + \frac{1}{\sin \phi} \frac{\partial}{\partial \phi} \left( \sin \phi \frac{\partial \theta}{\partial \phi} \right) +$$

$$\frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2}$$

$$y = \omega \sin \phi$$

$$z = \omega \cos \phi$$

$$\frac{\partial \psi}{\partial y} = \frac{\partial \psi}{\partial \omega} \frac{\partial \omega}{\partial y} = \frac{\partial \psi}{\partial \omega} \frac{1}{\sin \phi}$$

$$\frac{\partial \psi}{\partial y} = \frac{\partial \psi}{\partial \omega} \frac{\partial \omega}{\partial y} = \frac{\partial \psi}{\partial \omega} \frac{1}{\sin \phi}$$

$$\frac{\partial^2 \psi}{\partial y^2} = \frac{\partial}{\partial y} \left( \frac{\partial \psi}{\partial y} \right) = \frac{\partial}{\partial \omega} \left( \frac{\partial \psi}{\partial \omega} \frac{1}{\sin \phi} \right) \frac{\partial \omega}{\partial y} = \frac{\partial^2 \psi}{\partial \omega^2} \frac{1}{\sin^2 \phi} - \frac{\partial \psi}{\partial \omega} \frac{1}{\omega^3}$$

$$\frac{\partial \psi}{\partial y} + \frac{\partial \psi}{\partial \omega} = \frac{\partial \psi}{\partial \omega} - \frac{1}{\omega} \frac{\partial \psi}{\partial \omega}$$

$$\frac{\partial \psi}{\partial x^2} + \frac{\partial \psi}{\partial \omega^2} - \frac{1}{\omega} \frac{\partial \psi}{\partial \omega} = \frac{\partial \psi}{\partial \omega} - \frac{1}{\omega} \frac{\partial \psi}{\partial \omega} + \frac{1}{\omega} \frac{\partial \psi}{\partial \omega} \frac{\partial \omega}{\partial x} = \Phi$$

Schly is uprowadzile wyrażenie

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{\partial^2 \psi}{\partial \xi^2} \left( \frac{\partial \xi}{\partial x} \right)^2 + \frac{\partial^2 \psi}{\partial \eta^2} \left( \frac{\partial \eta}{\partial x} \right)^2 + 2 \frac{\partial^2 \psi}{\partial \xi \partial \eta} \frac{\partial \xi}{\partial x} \frac{\partial \eta}{\partial x} + \frac{\partial^2 \psi}{\partial \xi^2} \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial^2 \psi}{\partial \eta^2} \frac{\partial^2 \eta}{\partial x^2}$$

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{1}{2} \frac{\partial^2 \psi}{\partial \xi^2} - \frac{x^2}{2} \frac{\partial^2 \psi}{\partial \xi^2} + \frac{x^2}{2} \frac{\partial^2 \psi}{\partial \eta^2}$$

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{\partial^2 \psi}{\partial \xi^2} \left( \frac{\partial \xi}{\partial x} \right)^2 + \frac{\partial^2 \psi}{\partial \eta^2} \left( \frac{\partial \eta}{\partial x} \right)^2 + 2 \frac{\partial^2 \psi}{\partial \xi \partial \eta} \frac{\partial \xi}{\partial x} \frac{\partial \eta}{\partial x} + \frac{\partial^2 \psi}{\partial \xi^2} \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial^2 \psi}{\partial \eta^2} \frac{\partial^2 \eta}{\partial x^2}$$

$$\frac{\partial^2 \psi}{\partial x^2} = \frac{\partial^2 \psi}{\partial \xi^2} \frac{\partial^2 \xi}{\partial x^2} + \frac{\partial^2 \psi}{\partial \eta^2} \frac{\partial^2 \eta}{\partial x^2}$$

$$\frac{\partial \psi}{\partial x} = \frac{\partial \psi}{\partial \xi} \left( \frac{\partial \xi}{\partial x} \right) + \frac{\partial \psi}{\partial \eta} \frac{\partial \eta}{\partial x}$$



$$\frac{\partial \theta}{\partial x} = \frac{\partial \theta}{\partial x} \frac{x}{2} + \frac{\partial \theta}{\partial \omega} \frac{\omega}{2}$$

$$\frac{\partial \theta}{\partial \omega} = \frac{\partial \theta}{\partial \omega} \frac{\omega}{2}$$

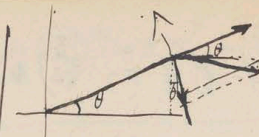
gdy gdy  $\omega \rightarrow 0$  to

$$\frac{dx}{u\Phi} = \frac{dy}{v\Phi} = \frac{dz}{w\Phi} = d\theta$$

$$2 \frac{\partial \theta}{\partial z} + \theta$$

$$i \frac{\partial \theta}{\partial z} + 2 \frac{\partial \theta}{\partial z} \cdot z$$

$$\omega \varphi \frac{\partial \theta}{\partial \varphi} + \omega \varphi \frac{\partial \theta}{\partial \varphi^2}$$



$$-u \cos \theta + \varphi \sin \theta =$$

$$= -u \frac{u}{2} + \varphi \frac{x}{2}$$

$$= + \frac{3}{2} \frac{c a}{2^3} \left(1 - \frac{a^2}{2^2}\right) \frac{x^2 \omega}{2} -$$

$$- \frac{c \omega}{2} \left(1 - \frac{3}{4} \frac{a^2}{2} - \frac{1}{4} \frac{a^2}{2^2}\right)$$

$$2^2 \frac{\partial^2 \theta}{\partial z^2} + 2z \frac{\partial \theta}{\partial z} + \frac{\partial \theta}{\partial \varphi^2} + \frac{\omega \varphi}{2^2} \frac{\partial \theta}{\partial \varphi} + \text{etc.}$$

$$\rightarrow \frac{\partial \theta}{\partial x^2} + \frac{\partial \theta}{\partial \omega^2} - \frac{1}{\omega} \frac{\partial \varphi}{\partial \omega} \frac{\partial \theta}{\partial x} + \frac{1}{\omega} \left( \frac{\partial \varphi}{\partial x} - 1 \right) \frac{\partial \theta}{\partial \omega} = \Phi$$

$$R=1$$

$$P = -\frac{1}{\omega} \frac{\partial \varphi}{\partial \omega}$$

$$Q$$

$$S=0$$

$$T=1$$

$$k^2 + 1 = 0$$

$$k = \pm i$$

$$\frac{\partial \xi}{\partial x} = i \frac{\partial \xi}{\partial \omega}$$

$$\frac{\partial \eta}{\partial x} = -i \frac{\partial \eta}{\partial \omega}$$

$$\xi = x + i\omega$$

$$\eta = x - i\omega$$

$$4 \frac{\partial \xi}{\partial \omega} \frac{\partial \eta}{\partial \omega} = +4$$

$$r^2 = \xi \eta \quad \parallel \quad x = \frac{\xi + \eta}{2}$$

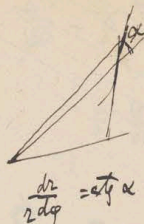
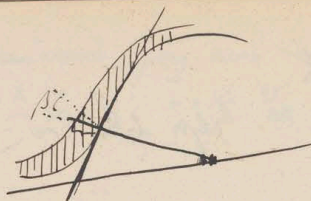
$$\frac{\partial^2 \theta}{\partial \xi \partial \eta} + \frac{1}{4\omega} \frac{\partial \varphi}{\partial \omega} \frac{\partial \theta}{\partial \xi} = \frac{1}{4\omega} \left(1 - \frac{\partial \varphi}{\partial x}\right) \frac{\partial \theta}{\partial \eta} = + \frac{\Phi}{4}$$

$$\text{Cy solution: } LM + \frac{\partial L}{\partial \xi} = 0 \quad ?$$



$$\psi = -\frac{c}{2} \left( 1 - \frac{3}{2} \frac{a}{2} + \frac{1}{2} \frac{a^3}{r^3} \right) r^2 \sin^2 \theta$$

$$\delta\psi = \frac{\partial\psi}{\partial r} \delta r + \frac{\partial\psi}{\partial \theta} \delta\theta$$



$$0 = \frac{\partial\psi}{\partial r} \delta r + \frac{\partial\psi}{\partial \theta} \delta\theta$$

$$\frac{1}{2} \frac{dr}{d\theta} = -\frac{\frac{\partial\psi}{\partial \theta}}{\frac{\partial\psi}{\partial r}} = -\frac{1}{2} \beta$$

$$\delta = \frac{\partial\psi}{\partial r} \delta r \cdot \cos\theta$$

$$\delta\psi \int_0^\infty \omega \frac{\partial\omega}{\partial\psi} \bar{\Phi}(x, \omega) dx = \delta\psi \int_0^\infty \omega \frac{\Phi}{\frac{\partial\psi}{\partial\omega}} dx$$

$$= \delta\psi \int_0^\infty \frac{\bar{\Phi}(x, \omega)}{\frac{\partial\psi}{\partial\omega}} dx$$

$$\psi = -\frac{c}{2} \left( 1 - \frac{3}{2} \frac{a}{\sqrt{x^2 + \omega^2}} + \frac{1}{2} \frac{a^3}{(x^2 + \omega^2)^{3/2}} \right) \omega^2$$

$$\frac{\partial\psi}{\partial\omega^2} = -\frac{c}{2} \left[ 1 - \frac{3}{2} \frac{a}{\sqrt{x^2 + \omega^2}} + \frac{1}{2} \frac{a^3}{(x^2 + \omega^2)^{3/2}} \right]$$

$$- \frac{c}{2} \omega^2 \left[ \frac{3}{4} \frac{a}{\sqrt{x^2 + \omega^2}^3} - \frac{3}{4} \frac{a^3}{(x^2 + \omega^2)^{5/2}} \right]$$

$$= -\frac{c}{2} \left[ 1 - \frac{3}{2} \frac{a}{2} + \frac{1}{2} \frac{a^3}{2^3} + \frac{3}{4} \frac{a\omega^2}{2^3} - \frac{3}{4} \frac{a^3\omega^2}{2^5} \right]$$

$$\omega^2 = r^2 - x^2$$

$$= -\frac{c}{2} \left[ 1 - \frac{3}{2} \frac{a}{2} + \frac{1}{2} \frac{a^3}{2^3} + \frac{3}{4} \frac{a}{2} - \frac{3}{4} \frac{a x^2}{2^3} - \frac{3}{4} \frac{a^3}{2^3} + \frac{3}{4} \frac{a^3 x^2}{2^5} \right]$$

$$1 - \frac{3}{4} \frac{a}{2} - \frac{1}{4} \frac{a^3}{2^3} + \frac{3}{4} \frac{a x^2}{2^3} - \frac{3}{4} \frac{a^3}{2^3} + \frac{3}{4} \frac{a^3 x^2}{2^5} = -\frac{11}{2}$$



$$\Phi = \frac{q}{8} \frac{c^2 a^2}{r^2} \left\{ \frac{2a^4}{r^4} + 6 - \frac{6a^2}{r^2} - \frac{12a^2}{r^2} + \frac{12a^2 r^2}{r^4} + \frac{4a^4}{r^4} - \frac{4a^4 r^2}{r^6} \right\} \quad 277$$

$$\left\{ 6 - \frac{12a^2}{r^2} + 6 \frac{a^4}{r^4} - \left( 6 - \frac{12a^2}{r^2} + \frac{4a^4}{r^4} \right) \frac{a^2}{r^2} \right\}$$

$$dx = \frac{x}{r} dr = \frac{dr}{r} \sqrt{r^2 - a^2}$$

$$\frac{q}{8} c^2 a^2 \frac{1}{2} \int_{\rho}^{\infty} dr \left[ \frac{1}{r^5} \left[ 6 \left( 1 - \frac{2a^2}{r^2} + \frac{a^4}{r^4} \right) + \left( 6 - \frac{12a^2}{r^2} + \frac{4a^4}{r^4} \right) \frac{24}{c r^2 \left( 1 - \frac{3}{2} \frac{a^2}{r^2} + \frac{1}{2} \frac{a^4}{r^4} \right)} \right] - \frac{c}{2} \left[ 1 - \frac{3}{2} \frac{a^2}{r^2} + \frac{1}{2} \frac{a^4}{r^4} + \frac{3}{4} \frac{a^2}{r^4} \left( 1 - \frac{a^2}{r^2} \right) \frac{24}{c \left( 1 - \frac{3}{2} \frac{a^2}{r^2} + \frac{1}{2} \frac{a^4}{r^4} \right)} \right] \right]$$

$$i \sqrt{r^2 - \frac{24}{c \left( 1 - \frac{3}{2} \frac{a^2}{r^2} + \frac{1}{2} \frac{a^4}{r^4} \right)}}$$

$\psi = \text{const}$

zrobić coś z tymi warunkami

$$\Delta \psi + u \frac{\partial \psi}{\partial x} + v \frac{\partial \psi}{\partial y} + w \frac{\partial \psi}{\partial z} = 0$$

zrobić potencjał taki jak ten funkcja  $\varphi: \left( \frac{\partial \psi}{\partial x} \right)^2 + \left( \frac{\partial \psi}{\partial y} \right)^2 + \left( \frac{\partial \psi}{\partial z} \right)^2 = 4$

stwierdzić  $\varphi = \log \psi$  i stało się  $\psi = e^{\varphi}$

$$\frac{\partial \varphi}{\partial x} = \frac{1}{\psi} \frac{\partial \psi}{\partial x} \quad \psi = e^{\varphi}$$

$$\Delta \psi + u \frac{\partial \psi}{\partial x} + v \frac{\partial \psi}{\partial y} + w \frac{\partial \psi}{\partial z} = 0$$

$$\Delta \psi = 0 \quad \text{zrobić to inaczej}$$

zrobić Partikulorne

warunek  $\Delta \psi = 0$

$$u \frac{\partial \psi}{\partial x} + \dots = 0$$

$$\psi = \frac{a}{2} + b \frac{\partial}{\partial x} \left( \frac{1}{2} \right) + c \frac{\partial}{\partial x} \left( \frac{1}{2} \right) + \dots$$



$$\theta = \frac{a}{2} + b \frac{\partial}{\partial x} \left( \frac{1}{2} \right) + c \frac{\partial}{\partial x} \left( \frac{1}{2} \right) + \dots$$

$$\frac{\partial \theta}{\partial x} = a \frac{\partial}{\partial x} \left( \frac{1}{2} \right) + b \frac{\partial^2}{\partial x^2} \left( \frac{1}{2} \right) + \dots = \frac{x}{2} \left[ a + b \frac{\partial}{\partial x} \left( \frac{1}{2} \right) + \dots \right] + F_2$$

$$\frac{\partial \theta}{\partial y} = a \frac{\partial}{\partial y} \left( \frac{1}{2} \right) + b \frac{\partial^2}{\partial x \partial y} \left( \frac{1}{2} \right) + \dots = \frac{y}{2} \left[ \dots \right]$$

$$\frac{\partial \theta}{\partial z} = a \frac{\partial}{\partial z} \left( \frac{1}{2} \right) + \dots = \frac{z}{2} \left[ \dots \right]$$

$$u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = - \frac{1}{4} \frac{\partial}{\partial x} \left( \frac{1}{2} \right) \times F_1 + \frac{1}{4} \frac{\partial}{\partial y} \left( \frac{1}{2} \right) \times F_2 = 0$$

$$= \frac{c x}{2} \left( 1 - \frac{3}{2} \frac{a}{2} + \frac{1}{2} \frac{a^3}{2^3} \right) F_1 + F_2 u$$

$$\frac{\partial}{\partial x} \left( \frac{1}{2} \right) = - \frac{x}{2^3} \quad \frac{\partial}{\partial y} \left( \frac{1}{2} \right) = - \frac{y}{2^3}$$

$$\frac{\partial^2}{\partial x^2} \left( \frac{1}{2} \right) = + \frac{3x^2}{2^5} - \frac{1}{2^3}$$

$$\frac{\partial^2}{\partial y \partial x} \left( \frac{1}{2} \right) = + \frac{3xy}{2^5}$$

$$\frac{\partial^3}{\partial x^3} = - \frac{15x^3}{2^7} + \frac{3x}{2^5} + \frac{6x}{2^5} \quad \frac{\partial^3}{\partial x^2 \partial y} = - \frac{15x^2 y}{2^7} + \frac{3y}{2^5}$$

$$F_1 = \left[ - \frac{ax}{2^3} + b \left[ \frac{3x^2}{2^5} - \frac{1}{2^3} \right] + c \left[ - \frac{15x^3}{2^7} + \frac{3x}{2^5} \right] + \dots \right]$$

$$F_2 = - \frac{b}{2^3} + \frac{6cx}{2^5}$$

$$\theta = \varphi \psi$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial \varphi}{\partial x} \psi + \varphi \frac{\partial \psi}{\partial x}$$

$$\frac{\partial^2 \theta}{\partial x^2} = \frac{\partial^2 \varphi}{\partial x^2} \psi + 2 \frac{\partial \varphi}{\partial x} \frac{\partial \psi}{\partial x} + \varphi \frac{\partial^2 \psi}{\partial x^2}$$

$$\Delta \varphi \cdot \psi + 2 \left[ \frac{\partial \varphi}{\partial x} \frac{\partial \psi}{\partial x} + \frac{\partial \varphi}{\partial y} \frac{\partial \psi}{\partial y} + \frac{\partial \varphi}{\partial z} \frac{\partial \psi}{\partial z} \right] + \varphi \Delta \psi + \varphi \left[ u \frac{\partial \psi}{\partial x} + \dots \right] + \varphi \left[ u \frac{\partial \psi}{\partial x} + \dots \right] = 0$$

Rezultă ecuația A în care  $\varphi$  și ecuația B se pot scrie sub forma  $\varphi =$



$$\Delta^2 \varphi + 2 \left[ \frac{\partial \varphi}{\partial x} \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial \varphi}{\partial y} \frac{\partial^2 \varphi}{\partial y^2} + \frac{\partial \varphi}{\partial z} \frac{\partial^2 \varphi}{\partial z^2} \right] + u \frac{\partial \varphi}{\partial x} + \dots = 0$$

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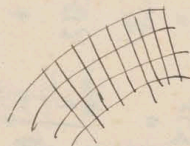
rotaci jisti s<sub>z</sub> da indukci toku  $\varphi$  cirkly

$$2 \frac{\partial \varphi}{\partial x} \frac{\partial^2 \varphi}{\partial x^2} + \dots = \Phi$$

$$\iint \Delta^2 \theta + u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = 0$$

$$\iint \frac{\partial \theta}{\partial n} dS + \iint \left[ u \theta \frac{\partial \omega}{\partial x} + v \theta \frac{\partial \omega}{\partial y} + w \theta \frac{\partial \omega}{\partial z} \right] - \iint \theta \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) dS$$

$$\iint \frac{\partial \theta}{\partial n} dS + \iint \theta v_n dS = 0$$



Zostrojme to do nach predn cirkly

$$\Delta^2 \theta + u \frac{\partial \theta}{\partial x} + \dots = 0$$

$$\Delta^2 \theta' + u \frac{\partial \theta'}{\partial x} + \dots = 0$$

$$\left. \begin{aligned} &= 0 \\ &= 0 \end{aligned} \right\} \text{  }$$

$$\Delta^2 (\theta + \theta') + u \frac{\partial (\theta + \theta')}{\partial x} + v \frac{\partial (\theta + \theta')}{\partial y} + \dots = 0$$

$$\Delta^2 (\theta + \theta') + u \frac{\partial (\theta + \theta')}{\partial x} + v \frac{\partial (\theta + \theta')}{\partial y} + \dots = 0$$

=0



Jednorodnizované rovnice

~~$$u \frac{du}{dx} + \frac{1}{p} \frac{dp}{dx} = \frac{1}{3} \frac{du}{dx} + \frac{1}{p} \frac{dp}{dx}$$~~

$$D. \rho u \frac{du}{dx} + \frac{dp}{dx} = \frac{\gamma p}{3} \frac{du}{dx}$$

$$II. \frac{\partial(\rho u)}{\partial x} = 0$$

$$\rho u = \text{const} = b$$

$$III. k p \frac{du}{dx} + u \frac{dp}{dx} = (k-1) \frac{\gamma p}{3} \left( \frac{du}{dx} \right) + k \frac{dp}{dx}$$

$$I. b \frac{du}{dx} + \frac{dp}{dx} = \frac{\gamma p}{3} \frac{du}{dx}$$

$$b u + p = \frac{\gamma p}{3} \frac{du}{dx} + a$$

$$\frac{du}{dx} = \frac{b u + p - a}{\frac{\gamma p}{3}}$$

~~$$k p \frac{b u + p - a}{\frac{\gamma p}{3}} + u \frac{dp}{du} = (k-1) \frac{\gamma p}{3} \left( \frac{du}{dx} \right) +$$~~

$$k p + u \frac{dp}{du} = (k-1) (b u + p - a)$$

$$u \frac{dp}{du} = \underbrace{(k-1) b u - p - (k-1) a}_{= z}$$

$$p = (k-1) b u - (k-1) a - z$$

$$\frac{dp}{du} = \frac{(k-1) b}{du} \frac{du}{du} - \frac{dz}{du}$$

$$u (k-1) b - u \frac{dz}{du} = z$$

$$\frac{dz}{du} + \frac{z}{u} = (k-1) b$$

$$u dz + z du = (k-1) b du u$$

~~$$u dz + z du = (k-1) b \frac{u^2}{2} + c$$~~

$$z = (k-1) \frac{b u}{2} + \frac{c}{u}$$

$$\frac{dp}{du} < 0 \quad z < 0$$

$$\text{tedy } c < 0$$



$$p = (k-1)bu - (k-1)a - (k-1)\frac{bu}{2} + -\frac{c}{u}$$

$$p = \frac{(k-1)b}{2}u - \frac{c}{u} - (k-1)a$$

$$\frac{u(k-1)b}{2} + \frac{c}{u} = \frac{(k-1)b}{2}u + \frac{c}{u} - (k-1)a$$

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$$\frac{4u}{3} \frac{du}{dx} = bu - a + \frac{(k-1)b}{2}u - \frac{c}{u} - (k-1)a$$

$$= (k+1)\frac{b}{2}u - \frac{c}{u} - ka$$

$$\frac{\frac{4u}{3} u du}{(k+1)\frac{b}{2}u^2 - ka u - c} = dx$$

quadratisches in  $u$  mit  $a$  ;  $c$  immer stell:

$$A = \frac{a k}{(k+1)\frac{b}{2}}$$

$$C = \frac{-c}{(k+1)\frac{b}{2}}$$

$$a = \frac{(k+1)b}{k} \frac{A}{2}$$

$$c = -(k+1)\frac{b}{2}C$$

$$\frac{u du}{u^2 - Au + C} = \frac{(k+1)\frac{b}{2}}{\frac{4u}{3}} dx = \underbrace{\left( u - \frac{A}{2} \right) du}_{\frac{1}{2} \log(u^2 - Au + C)} + \frac{\frac{A}{2} du}{u^2 - Au + C}$$

manipul.  $A > 0$   
 $C > 0$

$$\int \frac{du}{u^2 - Au + C} = \frac{2}{\sqrt{4C - A^2}} \operatorname{arctg} \frac{2u - A}{\sqrt{4C - A^2}} \quad 4C > A^2$$

$$= \frac{1}{\sqrt{A^2 - 4C}} \log \left\{ \frac{2u - A - \sqrt{A^2 - 4C}}{2u - A + \sqrt{A^2 - 4C}} \right\} \quad A^2 > 4C$$

$$= \frac{1}{\sqrt{A^2 - 4C}} \log \frac{\left( u - \frac{A}{2} - \sqrt{\left(\frac{A}{2}\right)^2 - C} \right) \left( u - \frac{A}{2} + \sqrt{\left(\frac{A}{2}\right)^2 - C} \right)}{\left( u - \frac{A}{2} + \sqrt{\left(\frac{A}{2}\right)^2 - C} \right)^2}$$

$$= \frac{1}{\sqrt{A^2 - 4C}} \left[ \log(u^2 - uA + \frac{A^2}{4} - \frac{A^2}{4} + C) - 2 \log(u - \frac{A}{2} + \sqrt{\left(\frac{A}{2}\right)^2 - C}) \right]$$

W prędkością hyponeracyjną:

$$u^2 - Au + C > 0$$

$$\frac{A^2}{4} > C$$

$$(1a) \quad \frac{(k+1) \frac{b}{2}}{\frac{4\mu}{3}} x + \text{const} = \left[ \frac{1}{2} + \frac{\frac{A}{2}}{\sqrt{A^2 - 4C}} \right] \log \left( u - \frac{A}{2} - \sqrt{\frac{A^2}{4} - C} \right) \\ + \left[ \frac{1}{2} - \frac{\frac{A}{2}}{\sqrt{A^2 - 4C}} \right] \log \left( u - \frac{A}{2} + \sqrt{\frac{A^2}{4} - C} \right)$$

arcty:

$$u^2 - Au + C > 0$$

$$\frac{A^2}{4} < C$$

$$(1b) \quad \frac{(k+1) \frac{b}{2}}{\frac{4\mu}{3}} x + \text{const} = \frac{1}{2} \log(u^2 - Au + C) + \frac{A}{\sqrt{4C - A^2}} \arctan \frac{2u - A}{\sqrt{4C - A^2}}$$

$$(2) \quad p = \frac{b}{2} \left\{ (k-1)u + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\} \quad \parallel \text{energia mechaniczna p!}$$

$$(3) \quad \theta = \frac{pu}{Rpu} = \frac{pu}{Rb} = \frac{1}{2R} \left\{ (k-1)u^2 - \frac{(k^2-1)}{k} Au + (k+1)C \right\} \parallel \text{mischin o b!}$$

$$(1) : \frac{(k+1) \frac{b}{2}}{\frac{4\mu}{3}} x + \text{const} = \left[ f_1(u, A, C) - \text{const} \right] \frac{b}{2} \varphi(u, A, C)$$

$$(2) \quad px = \frac{4\mu}{3} \frac{1}{k+1} \left[ f(u, AC) - \text{const} \right] \varphi(u, AC)$$

Jako np.  $\theta$  dane przy danych parametrach to można obliczyć  $A, C$   
opisać typ wiatru  $px$  przy danym  $u$  to wynika z wartości  $\text{const}$



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$$\left. \begin{array}{lll} \text{N.p. dla } x=0 & u=u_0 & \theta=\theta_0 \\ & u=u_1 & \theta=\theta_1 \end{array} \right\} \text{ 2 typ rozprawy (3) otęgnięć i}$$

A i C

rozprawy (1): const

dalej: rozwiązanie (1/2):  $\mu x = \text{znana funkcja z B\&P}$   
 $R\&P x = \frac{4}{3} \mu \frac{1}{k+1} (f - \cos t) \varphi$

zatem 
$$\rho = \frac{\frac{4}{3} \mu \frac{1}{k+1} (f - \cos t) \varphi}{R\&P x} = \frac{\frac{4}{3} \mu \frac{1}{k+1} (f - \cos t)}{\frac{1}{2} \mu x}$$

zatem 
$$b = \rho u = \frac{\frac{4}{3} \mu \frac{1}{k+1} (f - \cos t)}{\frac{1}{2} x}$$

$\frac{dp}{dx}$  musi w każdej chwili być ujemne, inaczej by nam nie wystąpiło

$$\begin{aligned} \frac{dp}{dx} &= \frac{dp}{du} \frac{du}{dx} = \frac{b}{2} \left\{ (k-1) - \frac{(k+1)C}{u^2} \right\} \frac{(k+1) \frac{b}{2}}{\frac{4\mu}{3}} \frac{u^2 - Au + C}{u} \\ &= \frac{b^2}{4} \frac{k+1}{\frac{4\mu}{3}} \frac{\left[ k-1 - \frac{(k+1)C}{u^2} \right] [u^2 - Au + C]}{u} < 0 \end{aligned}$$

wyca albo  $k-1 < \frac{(k+1)C}{u^2}$

albo  $u^2 - Au + C < 0$

} stanowi o każdej chwili prędkości dla u

Pierwsza: warunki oraz ograniczenia do I II III

$$\begin{aligned} & b \frac{(k+1) \frac{b}{2}}{\frac{4\mu}{3}} \frac{u^2 - Au + C}{u} + \frac{b^2}{4} \frac{(k+1)}{\frac{4\mu}{3}} \frac{\left[ k-1 - \frac{(k+1)C}{u^2} \right] [u^2 - Au + C]}{u} \\ & \frac{4\mu}{3} \left\{ \frac{2u - A}{u} - \frac{u^2 - Au + C}{u^2} \right\} \frac{u^2 - Au + C}{u} \rightarrow \frac{k u^2 - Au - u^2 + Au - C}{u^2} \end{aligned}$$



$$\frac{\frac{b^2}{2}(k+1)}{\frac{4\mu}{3}} + \frac{\frac{b^2}{4}(k^2-1)}{\frac{4\mu}{3}} - \frac{\frac{b^2}{4}(k+1)^2}{\frac{4\mu}{3}} \frac{C}{u^2} = \frac{4\mu}{3} \left(1 - \frac{C}{u^2}\right)$$

Spektrum tyho železa:

$$\frac{b^2}{2}(k+1) + \frac{b^2}{4}(k^2-1) = \left(\frac{4\mu}{3}\right)^2 = \frac{b^2}{4} [k^2-1 + 2(k+1)] = \frac{b^2}{4} [k^2 + 2k + 1] = \frac{b^2}{4} (k+1)^2$$

$$\frac{b^2}{4} (k+1)^2 = \left(\frac{4\mu}{3}\right)^2$$

Identity case !!

$$\frac{b(k+1)}{2} = \frac{4\mu}{3}$$

$$b = \frac{8\mu}{3(k+1)}$$

Dva rovnania prijímame kontroli:

$$(1) a \quad x + \text{const} = \left[ \frac{1}{2} + \frac{1}{\sqrt{}} \right] \dots$$

=

$$(2) \quad \mu = \frac{4\mu}{3(k+1)} \left\{ (k-1)u + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\}$$

$$(3) \quad \theta = \frac{1}{2R} \left\{ (k-1)u^2 + (k+1)C - \frac{(k^2-1)}{k} A u \right\}$$

$$\rho = \frac{b}{u} = \frac{8\mu}{3(k+1)} \frac{1}{u}$$

$$u = \frac{8\mu}{3(k+1)} \frac{1}{\rho}$$

Sk.f.  $\mu = 0.00019$   
 $\rho = 0.0012$

$$u = \frac{1}{10} \text{ ?}$$



Wiederholen 1a - 3 u III:

$$k \frac{b}{2} \left\{ (k-1)u + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\} + u \frac{b^2}{4} \frac{k+1}{\frac{4u}{3}} \frac{\left[ k-1 - \frac{(k+1)C}{u^2} \right] \left[ u^2 - Au + C \right]}{u} =$$

$$= (k-1) \frac{4u}{3} \left[ \frac{(k+1) \frac{b}{2}}{\frac{4u}{3}} \frac{u^2 - Au + C}{u} \right]^2$$

$$k \frac{4u}{3} \left\{ (k-1)u + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\} + \frac{b}{2} (k+1) \left\{ k-1 - \frac{(k+1)C}{u^2} \right\} \left\{ u^2 - Au + C \right\} =$$

$$= (k-1)(k+1)^2 \frac{b}{2} \left\{ u - A + \frac{C}{u} \right\}^2$$

$$\frac{4u}{3} k \left[ (k-1)u + \frac{(k-1)(k+1)}{k} A + (k+1) \frac{C}{u} \right] = \frac{b}{2} (k+1) \left[ u - A + \frac{C}{u} \right] \left\{ (k+1) \left( u - A + \frac{C}{u} \right) - u(k-1) + \frac{(k+1)C}{u} \right\}$$

$$= \frac{b}{2} (k+1) \left[ u - A + \frac{C}{u} \right] \left[ 2u - (k+1)A + \frac{2(k+1)C}{u} \right]$$

No more by induction!

$$I). \quad 8u \frac{du}{dp} + 1 = \frac{4u}{3} \frac{d^2 u}{dx dp} \quad II). \quad k p \frac{du}{dp} + u = (k-1) \frac{4u}{3} \frac{du}{dx} \frac{du}{dp}$$

$$\frac{dp}{du} = \frac{4u}{3} \frac{d^2 u}{dx dp}$$

Spitziere

$$I). \quad b \frac{du}{dp} + 1 = \frac{4u}{3} \frac{d}{dp} \left( \frac{du}{dx} \right)$$

$$bu + p = \frac{4u}{3} \frac{du}{dx} + a$$

$$2Au + \frac{1}{3} \left( \frac{4u}{3} \right) \left( \frac{4u}{3} \right) - \frac{(k-1)(k+1)}{k} A = \frac{4u}{3} \frac{k+1}{3} \frac{u^2 - Au + C}{u} + \frac{k+1}{k} A$$

II).



$$\text{II. } \left\{ k \frac{1}{2} \left\{ (k-1) + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\} - (k-1) \frac{1}{2} (k+1) \left[ u - A + \frac{C}{u} \right] \right\}$$

$$= -u \frac{1}{2} \left\{ (k-1) - (k+1) \frac{C}{u^2} \right\}$$

Wronskijska v III:

$$k \frac{1}{2} \left\{ (k-1)u + (k+1) \frac{C}{u} - \frac{(k-1)(k+1)}{k} A \right\} \frac{(k-1)}{2} \frac{u^2 - A_2 + C}{u} + u \frac{1}{2} \frac{(k-1)}{2} \left[ \frac{(k+1)C}{u^2} \right] \frac{(u^2 - A_2 + C)}{u}$$

$$= (k-1) \frac{1}{2} (k+1) \frac{1}{2} \left( \frac{u^2 - A_2 + C}{u} \right)$$

$$(k^2 - k)u + (k-1)u - (k^2 - k)u + k(k+1) \frac{C}{u} - \frac{(k+1)C}{u} - \frac{(k^2 - k)C}{u} +$$

$$= (k-1)(k+1)A + (k-1)(k+1)A = 0$$

$$\text{I. } \frac{1}{2} \frac{(k+1)}{2} \frac{u^2 - A_2 + C}{u} + \frac{1}{2} \frac{(k+1)}{2} \left[ \frac{(k-1)C}{u^2} \right] \frac{u^2 - A_2 + C}{u}$$

$$= \frac{1}{2} \frac{(k+1)}{2} \left( \frac{u^2 - C}{u^2} \right) \frac{u^2 - A_2 + C}{u}$$

$$\underbrace{2 + k-1}_{k+1} \frac{(k+1)C}{u^2} = (k+1) \left( 1 - \frac{C}{u^2} \right)$$

gubiny



jele motive beres me u to tan hidi  
i zagnje ~~u~~ i tanyd redovni x:

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lim u ..

$$\rho = \frac{b}{2} \frac{(k+1)C}{u}$$

$$\theta = \frac{(k+1)C}{2R}$$

$$\rho = \frac{b}{2R} = \frac{b}{u}$$

(1a) ni motive

$$(1b): \frac{(k+1)C}{2} \text{ and } = \frac{1}{2} \log C + \frac{A}{\sqrt{4C-A^2}} \arctan \frac{-A}{\sqrt{4C-A^2}}$$

(1a) najmanje motive predvi:

$$u > \frac{A}{2} + \sqrt{\frac{A^2}{4} - C}$$

zato:

$$u - \frac{A}{2} > \sqrt{\frac{A^2}{4} - C}$$

$$u^2 - Au + \frac{A^2}{4} > \frac{A^2}{4} - C$$

$$u^2 - Au + C > 0$$

(1a) wammek:  $\frac{A^2}{4} > C$

$$\theta < \frac{1}{2R} \left\{ (k-1)u^2 - \frac{(k-1)}{k} Au + (k+1) \frac{A^2}{4} \right\}$$

$$\rho < \frac{b}{2} \left\{ (k-1)u + \frac{(k+1)}{u} \frac{A^2}{4} - \frac{(k-1)}{k} \frac{(k+1)}{k} A \right\}$$

$$\rho < \frac{b}{2} \left\{ \frac{kA}{2} - \frac{k-1}{k} A + \frac{(k+1)A^2}{4(Au-C)} \right\}$$

$$\theta < \frac{1}{2R} \left\{ (k-1) \frac{A^2}{4} \frac{k+1}{k} + (k+1) \frac{A^2}{4} - \frac{(k-1)}{k} Au \right\}$$

$$< \frac{1}{2R} (k+1) \left\{ \frac{A^2}{2} - \frac{k-1}{k} Au \right\}$$

$$\frac{A^2}{4} > C > Au - u^2$$

$$\frac{A^2}{4} > Au - u^2$$

$$u^2 - Au + \frac{A^2}{4} > 0 \quad (u - \frac{A}{2})^2 > 0$$

najmanje motive i pored

ie  $\frac{d}{dx} \theta < 0$ :

$$u^2 < \frac{(k+1)C}{k-1}$$

$$Au - C < u^2 < \frac{k+1}{k-1} C < (1 + \frac{2}{k-1}) C$$

$$Au < (\frac{k+1}{k-1} + 1) C$$

$$Au < \frac{2k}{k-1} C$$

$$u < (\frac{2k}{k-1}) \frac{C}{A}$$

$$\frac{C}{A} < \frac{A}{4}$$

$$u < \frac{k}{2(k-1)} A$$

$$u^2 < \frac{k+1}{k-1} \frac{A^2}{4}$$

$$u < \frac{A}{2} \sqrt{\frac{k+1}{k-1}}$$

$$\frac{k}{k-1} = \frac{1.4}{0.4} = \frac{7}{2} = 3.5$$

$$\sqrt{\frac{k+1}{k-1}} = \sqrt{\frac{2.4}{0.4}} = \sqrt{6} = 2.5$$



W (1a) i (1b) warunki konieczne  $u^2 - Au + C > 0$

zatem  $\frac{du}{dx} > 0$  prędkość wzrasta z  $x$

zatem siły były ujemne  $\frac{dy}{dx} < 0$

musi być  $\frac{dy}{dx} < 0$  w) ~~całkowicie~~  $u^2 < \frac{k+1}{k-1} C$

$$\text{const} = \left[ \frac{1}{2} \right] \log \left( u_1 - \frac{A}{2} + \sqrt{\frac{A^2}{4} - C} \right) + \left[ \frac{1}{2} \right] -$$

$$\frac{(k+1) \frac{b}{2} x}{\frac{u_1}{3}} = \left[ \frac{1}{2} + \frac{1}{\sqrt{A^2 - 4C}} \right] \log \left( \frac{u - \frac{A}{2} - \sqrt{\frac{A^2}{4} - C}}{u_1 - \frac{A}{2} - \sqrt{\frac{A^2}{4} - C}} \right) + \left[ \frac{1}{2} \right]$$

$$\frac{b}{2} (k+1) C = k p_0 \alpha \quad C = \frac{k p_0 \alpha}{(k+1) \frac{b}{2}}$$

$$\frac{b}{2} \frac{(k+1) \alpha}{k} A = p_0 \quad A = \frac{k p_0}{(k+1) \frac{b}{2}}$$

$$\frac{1}{2} \log \frac{u - A}{u_1 - A} = \frac{1}{2} \log \frac{1 - \frac{u}{A}}{1 - \frac{u_1}{A}} = \frac{1}{2} \frac{u_1 - u}{A} = \frac{1}{2} \frac{u_1 - u}{k p_0} \frac{b}{2}$$

$$\frac{1}{2} \log \frac{\frac{u}{A} - \frac{1}{2}}{\frac{u_1}{A} - \frac{1}{2}} \cdot \frac{\frac{u}{A} + \frac{A}{2} \left[ -1 + \left( 1 - \frac{4C}{A^2} \right)^{\frac{1}{2}} \right]}{\frac{u_1}{A} + \frac{A}{2} \left[ -1 + \left( 1 - \frac{4C}{A^2} \right)^{\frac{1}{2}} \right]} = \frac{1}{2} \log \frac{\frac{u}{A} + \frac{A}{2} \left[ -1 + \left( 1 - \frac{4C}{A^2} \right)^{\frac{1}{2}} \right]}{\frac{u_1}{A} + \frac{A}{2} \left[ -1 + \left( 1 - \frac{4C}{A^2} \right)^{\frac{1}{2}} \right]} =$$

$$= \frac{1}{2} \log \frac{\frac{u}{A} - \frac{C}{A^2}}{\frac{u_1}{A} - \frac{C}{A^2}} = \frac{1}{2} \log \frac{u - \frac{C}{A}}{u_1 - \frac{C}{A}} = \frac{1}{2} \log \frac{u - \alpha}{u_1 - \alpha}$$

$$\text{Zatem } \frac{(k+1) \frac{b}{2} x}{\frac{u_1}{3}} = \frac{1}{2} \left[ \frac{(u_1 - u) (k+1)}{k p_0} \frac{b}{2} + \log \frac{u - \alpha}{u_1 - \alpha} \right]$$



Co jeli  $u^2 - Au + C < 0$

Jeli  $\frac{C > 0}{A > u + \frac{C}{A}}$

$$\int \frac{u \, du}{u^2 - Au + C} = \int \frac{(u - \frac{A}{2}) \, du}{-(u^2 - Au + C)} + \int \frac{\frac{A}{2} \, du}{-(u^2 - Au + C)}$$

$$= -\frac{1}{2} \int \frac{du}{u^2 - Au + C} = -\int \frac{u \, du}{Au - u^2 - C}$$

$$= \int \frac{(\frac{A}{2} - u) \, du}{Au - u^2 - C} - \frac{A}{2} \int \frac{du}{Au - u^2 - C}$$

$$= \frac{1}{2} \ln(Au - u^2 - C) - \frac{A}{2} \int \frac{du}{\frac{A^2}{4} - C - (u - \frac{A}{2})^2}$$

$$\frac{A}{2} \ln \frac{\sqrt{\frac{A^2}{4} - C} - u - \frac{A}{2}}{\dots}$$

U granicy prigradka, gdje  $C = \frac{A^2}{4}$

$$\frac{(k+1) \frac{A}{2}}{\frac{A}{3}} x + \text{const} = \frac{1}{2} \ln(u - \frac{A}{2}) - \frac{A}{2(u - \frac{A}{2})}$$



dla  $x=0$  : u bardzo male  $\approx u_0$

$$\theta \approx \theta_0$$

$$r \approx r_0$$

$$\theta_0 = \frac{(k+1)C}{2R}$$

~~$$r_0 = \frac{(k+1)C}{2u_0}$$~~

$$C = \frac{2R\theta_0}{k+1}$$

~~$$b = \frac{r_0 u_0}{R\theta_0}$$~~

~~$$\text{const} = \frac{1}{2} \log C + \frac{A}{\sqrt{4C-A^2}} \operatorname{arctg} \frac{-A}{\sqrt{4C-A^2}}$$~~

Org wzrostu u:

arctg może tyłko dojść do  $\frac{\pi}{2}$  gdy u od 0 do  $\infty$ ; produjemy log. wzrostu stale z u  
zatem dla wilgotności u bierzemy jmi tyłko:

~~$$x = \frac{u_0}{2} \log u$$
  
~~$$u = \frac{b(k+1)}{2} \frac{x}{\frac{u_0}{2}}$$~~~~

$$\frac{(k+1) \frac{b}{2}}{\frac{u_0}{2}} x = \frac{1}{2} \log \frac{u^2 - Au + C}{C} + \frac{A}{\sqrt{4C-A^2}} \left[ \operatorname{arctg} \frac{2u-A}{\sqrt{4C-A^2}} + \operatorname{arctg} \frac{A}{\sqrt{4C-A^2}} \right]$$

$$\operatorname{tg}(\varphi + \psi) = \frac{\operatorname{tg} \varphi + \operatorname{tg} \psi}{1 - \operatorname{tg} \varphi \operatorname{tg} \psi}$$

$$\varphi + \psi = \operatorname{arctg} \frac{\operatorname{tg} \varphi + \operatorname{tg} \psi}{1 - \operatorname{tg} \varphi \operatorname{tg} \psi}$$

$$= \operatorname{arctg} \frac{\frac{2u}{\sqrt{4C-A^2}}}{1 - \frac{(2u-A)A}{4C-A^2}} = \operatorname{arctg} \frac{\frac{2u}{\sqrt{4C-A^2}}}{\frac{4C-2uA}{4C-A^2}}$$

$$= \operatorname{arctg} \frac{\sqrt{4C-A^2}}{2C-uA}$$

Dla u bardzo dużego:

$$\frac{u}{\sqrt{C}} = e \cdot e^{\frac{(k+1) \frac{b}{2}}{\frac{u_0}{2}} x}$$



dla miedz i potę przybliżenie:

$$\frac{(k+1)^{\frac{1}{2}}}{\frac{4\pi}{3}} x = \frac{A}{\sqrt{4C-A^2}} \cdot \frac{\sqrt{4C-A^2} \cdot u}{2C} = \frac{Au}{2C}$$

$$\frac{(k+1)^{\frac{1}{2}}}{\frac{4\pi}{3}} \frac{\rho_0 u_0}{2R_0} x = \frac{Au(k+1)}{2R_0}$$

$$\frac{du}{dx} = \frac{(k+1)^{\frac{1}{2}}}{\frac{4\pi}{3}} \frac{u - Au + C}{u} = \frac{(k+1)^{\frac{1}{2}}}{\frac{4\pi}{3}} \cdot \frac{C}{u_0} = \frac{(k+1)^{\frac{1}{2}}}{\frac{4\pi}{3}} \frac{\rho_0 u_0}{R_0} \frac{R_0}{k+1} = \frac{\rho_0 u_0}{\frac{4\pi}{3}}$$

Wz. tam gdzie:  $u = u_0 + \frac{\rho_0 u_0}{\frac{4\pi}{3}} x$

$$\frac{dx}{du} \Big|_{u=u_0} = \frac{1}{\frac{4\pi}{3}} \frac{1}{\frac{4\pi}{3}} \frac{[k+1 + \frac{4\pi}{3} \frac{R_0}{\sqrt{4C-A^2}}] [u_0 - Au_0 + \frac{4\pi}{3} \frac{R_0}{\sqrt{4C-A^2}}]}{u_0} \left( \frac{\rho_0 u_0}{R_0} \right)^2$$

$$= \frac{1}{\frac{4\pi}{3}} = \frac{\rho_0^2}{\frac{4\pi}{3} u_0}$$

$$\frac{(k+1)^{\frac{1}{2}}}{\frac{4\pi}{3}} x + \text{const} = \frac{1}{2} \log(u^2 - Au + C) + \frac{A}{2} \frac{1}{\sqrt{A^2 - 4C}} \log \left[ \frac{A + \sqrt{A^2 - 4C} - 2u}{A - \sqrt{A^2 - 4C} - 2u} \right]$$

Gdy u od miedz wartości porównywalnej dla której:  $\frac{(k+1)^{\frac{1}{2}}}{\frac{4\pi}{3}} x + \text{const} = \frac{1}{2} \log C + \frac{A}{2} \frac{1}{\sqrt{A^2 - 4C}} \log \frac{A + \sqrt{A^2 - 4C}}{A - \sqrt{A^2 - 4C}}$

związując do  $u = \frac{A}{2} - \sqrt{\frac{A^2}{4} - C}$  to równanie one przyjmie kształt:

$$\frac{(k+1)^{\frac{1}{2}}}{\frac{4\pi}{3}} x + \text{const} = -\infty + \Delta$$

Wtedy gdzie  $\frac{du}{dx} \rightarrow \infty$  rows - dla u

gdz A, C wielkości:

$$u = \frac{A}{2} \left[ 1 - \left( 1 - \frac{4C}{A^2} \right)^{\frac{1}{2}} \right] = \frac{A}{2} \left[ 1 - 1 + \frac{2C}{A^2} \right]$$

$$= \frac{C}{A} \quad // = \alpha$$



Obliczmy nową wartość  $-\infty + \infty$ :

$$\lim_{u \rightarrow \frac{A}{2} - \sqrt{\frac{A^2}{4} - C}} \left\{ \frac{1}{2} \log \left( (u^2 - Au + C) \frac{\left[ \frac{A}{2} + \sqrt{\frac{A^2}{4} - C} - u \right]}{\left[ \frac{A}{2} - \sqrt{\frac{A^2}{4} - C} - u \right]} \right)^{\frac{A}{\sqrt{A^2 - 4C}}} \right\}$$

$$\frac{A}{2} + \sqrt{\frac{A^2}{4} - C} - u = \delta + \sqrt{A^2 - 4C}$$

$$\frac{A}{2} - \sqrt{\frac{A^2}{4} - C} - u = \delta - \sqrt{A^2 - 4C}$$

$$\frac{\delta + \sqrt{A^2 - 4C}}{\delta - \sqrt{A^2 - 4C}} = \frac{1 + \frac{A}{\sqrt{A^2 - 4C}}}{\frac{A}{\sqrt{A^2 - 4C}} - 1}$$

wy- bzdni  $= +\infty$  ~~just~~ ponieważ  $A > \sqrt{A^2 - 4C}$

zatem dla  $x = \infty$  u osiąga wartości maksymalną  $u = \frac{A}{2} - \sqrt{\frac{A^2}{4} - C} = \alpha$   
 $u^2 = \frac{A^2}{4} - C - A\sqrt{\frac{A^2}{4} - C}$

~~Odczytanie z wykresu~~

Tam bzdni.

~~Wzrost~~  $x = \infty$   $u = \alpha$   
 $x \neq 0$   $u = u_0$

$$\theta = \frac{1}{2R} \left\{ (k-1) \left( \frac{A^2}{2} - C - A\sqrt{\frac{A^2}{4} - C} \right) - \frac{(k+1)}{k} \left( \frac{A^2}{2} - A\sqrt{\frac{A^2}{4} - C} \right) + (k+1) C \right\}$$

$$\theta = \frac{1}{2R} \left\{ \frac{1-k}{k} \frac{A^2}{2} + 2C + \frac{k-1}{k} A \sqrt{\frac{A^2}{4} - C} \right\}$$

$$\alpha^2 - \alpha A + C = 0$$

$$A = \frac{\alpha^2 + C}{\alpha}$$

$$\theta_\infty = \frac{1}{2R} \left[ -\frac{k-1}{k} A \left( \frac{A}{2} - \sqrt{\frac{A^2}{4} - C} \right) + 2C \right] = \frac{1}{2R} \left[ 2C - \frac{(k-1)}{k} (\alpha^2 + C) \right]$$

$$\theta_\infty = \frac{1}{2R} \left[ C \left( 2 - \frac{k-1}{k} \right) - \frac{k-1}{k} \alpha^2 \right] = \frac{1}{2kR} \left[ (k+1)C - (k-1)\alpha^2 \right]$$

$$f_\infty = \frac{R b \theta_\infty}{\alpha} = \frac{b}{2k\alpha} \left[ (k+1)C - (k-1)\alpha^2 \right]$$

$$\sqrt{A^2 - 4C} = \sqrt{\left( \frac{\alpha^2 + C}{\alpha} \right)^2 - 4C}$$

$$= \sqrt{\frac{\alpha^4 + 2\alpha^2 C + C^2 - 4\alpha^2 C}{\alpha^2}}$$

$$= \frac{\alpha^2 - C}{\alpha}$$



$$\frac{p}{p_0} = K \alpha \frac{[(k-1)u + (k+1)\frac{C}{u} - \frac{(k^2-1)}{k} \frac{\alpha^2+C}{\alpha}]}{(k+1)C - (k-1)\alpha^2}$$

$$\begin{aligned} \frac{(k+1)}{\frac{4\mu}{3}} \frac{b}{2} x + \text{const} &= \frac{1}{2} \log \left[ u^2 - \frac{\alpha^2+C}{\alpha} u + C \right] \\ &+ \frac{\alpha^2+C}{2\alpha} \frac{\alpha}{\alpha^2-C} \log \frac{\alpha + \frac{\alpha^2-C}{\alpha} - u}{\alpha - u} \\ &= \frac{1}{2} \log \left[ u^2 - \alpha u - \frac{C}{\alpha} u + C \right] + \frac{\alpha^2+C}{2(\alpha^2-C)} \log \left[ \frac{2 - \frac{C}{\alpha^2} - \frac{u}{\alpha}}{1 - \frac{u}{\alpha}} \right] \end{aligned}$$


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punkt für  $u=0$ :  $x=0$

$$\text{const} = \frac{1}{2} \log C + \frac{\alpha^2+C}{2(\alpha^2-C)} \log \left( 2 - \frac{C}{\alpha^2} \right)$$

$$\frac{(k+1)}{\frac{4\mu}{3}} \frac{b}{2} x = \frac{1}{2} \log \left[ \frac{u^2 - \alpha u}{C} - \frac{u}{\alpha} + 1 \right] + \frac{\alpha^2+C}{2(\alpha^2-C)} \log \left[ \frac{1 - \frac{u\alpha}{2\alpha^2-C}}{1 - \frac{u}{\alpha}} \right]$$

$$p_0 = \frac{b}{2} (k+1) \frac{C}{u_0} = \frac{(k+1)C}{2} p_0$$

tan tot  $\frac{du}{dx} = \infty$  punkt oszillierung

Praca przybliżeń:

$$\theta = \theta_0 + \frac{\mu c^2}{32K} \left\{ 3a^2 \left[ -\frac{q}{n^2} + \frac{3x^2}{n^4} - \frac{a^2}{n^4} - \frac{2}{3} \frac{a^4}{n^6} + \frac{4a^2 x^2}{n^6} - 2 \frac{a^4 x^2}{n^8} \right] + \right. \\ \left. + \frac{a}{n} \left[ 19 + 13 \frac{a^2}{n^2} + 24 \frac{x^2}{n^2} - 39 \frac{x^2 a^2}{n^4} \right] \right\}$$

dla  $x=a$ :

$$\left\{ \right\} = 3 \left[ -9 - 1 - \frac{2}{3} + 3 \frac{x^2}{a^2} + 4 \frac{x^2}{a^2} - 2 \frac{x^2}{a^2} \right] + \left[ 19 + 13 - 15 \frac{x^2}{a^2} \right] \\ - 32 + 15 \frac{x^2}{a^2} + 32 - 15 \frac{x^2}{a^2} = 0$$

dla  $x=0$ :

$$\theta = \theta_0 + \frac{\mu c^2}{32K} \left\{ -3a^2 \left[ \frac{q}{n^2} + \frac{a^2}{n^4} + \frac{2}{3} \frac{a^4}{n^6} \right] + \frac{a}{n} \left[ 19 + 13 \frac{a^2}{n^2} \right] \right\}$$

$$\frac{\partial \theta}{\partial x} = \frac{\mu c^2}{32K} \left\{ 3a^2 \left[ \frac{18}{n^3} + \frac{4a^2}{n^5} + \frac{4a^4}{n^7} \right] - \frac{a}{n^2} \left[ 19 + 39 \frac{a^2}{n^2} \right] \right\} \Big|_{x=0}$$

$$= \frac{\mu c^2}{32Ka} \left\{ \frac{18}{78} - 58 \right\} = \frac{5}{8} \frac{\mu c^2}{Ka}$$

$x=a$

$$\theta = \theta_0 + \frac{\mu c^2}{32K} \left\{ 3a^2 \left[ -\frac{q}{n^2} + \frac{3}{n^2} - \frac{a^2}{n^4} - \frac{2}{3} \frac{a^4}{n^6} + \frac{4a^2}{n^4} - 2 \frac{a^4}{n^6} \right] + \right. \\ \left. + \frac{a}{n} \left[ 19 + 13 \frac{a^2}{n^2} + 24 - 39 \frac{a^2}{n^2} \right] \right\}$$

$$\left\{ \right\} = \left\{ 3a^2 \left[ -\frac{6}{n^2} + \frac{3a^2}{n^4} - \frac{2}{3} \frac{a^4}{n^6} \right] + \frac{a}{n} \left[ 43 - 26 \frac{a^2}{n^2} \right] \right\}$$

$$\frac{\partial \theta}{\partial x} = 3a^2 \left[ \frac{12}{n^3} - \frac{12a^2}{n^5} + \frac{48}{3} \frac{a^4}{n^7} \right] - \frac{a}{n^2} \left[ 43 - \frac{78a^2}{n^2} \right]$$

$$\frac{\mu c^2}{2K} \left[ \frac{48}{32} + \frac{35}{32} \right] = \frac{\mu c^2}{2K} \frac{83}{32} = \frac{\mu c^2}{2K} \left( 2 + \frac{19}{32} \right)$$



$$\frac{\partial \theta}{\partial x} = \frac{\mu c^2}{32k} \left\{ 3a^2 \left[ +\frac{18x}{n^4} - \frac{12x^3}{n^6} + \frac{4a^2x}{n^6} + \frac{4a^4x}{n^8} - \frac{24a^2x^3}{n^8} + \frac{16a^4x^3}{n^{10}} + \right. \right.$$

$$\left. + \frac{6x}{n^4} + \frac{8a^2x}{n^6} - \frac{4a^4x}{n^8} \right] + \left[ -19\frac{ax}{n^3} - 39\frac{a^3x}{n^5} - 72\frac{ax^3}{n^5} + 5.39\frac{a^3x^3}{n^7} + \frac{48xa}{n^3} - 2.39\frac{a^3x}{n^5} \right] \right\}$$

$$= \frac{\mu c^2}{32k} \left\{ 3a^2 \left[ \frac{24x}{n^4} + \frac{12a^2x}{n^6} - \frac{12x^3}{n^6} - \frac{24a^2x^3}{n^8} + \frac{16a^4x^3}{n^{10}} \right] + \right.$$

$$\left. + \left[ 29\frac{ax}{n^3} - 9.13\frac{a^3x}{n^5} - 72\frac{ax^3}{n^5} + 15.13\frac{a^3x^3}{n^7} \right] \right\} = M_x + N_x$$

$$\frac{\partial \theta}{\partial y} = \frac{\mu c^2}{32k} \left\{ 3a^2 \left[ \frac{18}{n^4} - \frac{12x^2}{n^6} + \frac{4a^2}{n^6} + \frac{4a^4}{n^8} - \frac{24a^2x^2}{n^8} + \frac{16a^4x^2}{n^{10}} \right] y \right.$$

$$\left. + \left[ -\frac{19a}{n^3} - 39\frac{a^3}{n^5} - 72\frac{ax^2}{n^5} + 5.39\frac{a^3x^2}{n^7} \right] y \right\} = M_y$$

$$\frac{\partial \theta}{\partial z} = 2 \dots = M_z$$

$$\mu \frac{\partial \theta}{\partial x} + \nu \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = -\frac{3}{4} c a \left( 1 - \frac{a^2}{n^2} \right) \frac{x}{n} M + c \left( 1 - \frac{3}{4} \frac{a}{n} - \frac{1}{4} \frac{a^3}{n^3} \right) M_x$$

$$+ N_{ux}$$

$$= M c x \left[ 1 - \frac{3}{4} \frac{a}{n} - \frac{1}{4} \frac{a^3}{n^3} - \frac{3}{4} \frac{a}{n} + \frac{3}{4} \frac{a^3}{n^3} \right] + N_{ux}$$

$$= M c x \left[ 1 - \frac{3}{2} \frac{a}{n} + \frac{1}{2} \frac{a^3}{n^3} \right] + N_{ux}$$

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$$N = 3a^2 \left[ \frac{6}{n^4} + \frac{8a^2}{n^6} - \frac{4a^4}{n^8} \right] + \frac{48a}{n^3} - 2.39 \frac{a^3}{n^5}$$



$$\begin{aligned}
& \left[ \frac{18}{2^4} - \frac{12x^2}{2^6} + \frac{4x^4}{2^6} + \frac{4x^4}{2^8} - \frac{24x^4}{2^8} + \frac{16x^4}{2^{10}} \right] 3a^2 + \left[ -\frac{19a}{2^3} - \frac{39a^3}{2^5} - 72\frac{x^2a}{2^5} + 5.39\frac{x^2a^3}{2^7} \right] \\
& + 3a^2 \left[ \frac{19}{2^4} + \frac{36x^2}{2^6} + \frac{39a^2}{2^6} - \frac{5.39x^2a^2}{2^8} \right] - \frac{81a^3}{2^5} + \frac{54x^2a^3}{2^7} - \frac{18a^5}{2^7} - \frac{18a^7}{2^9} + \frac{108a^5x^2}{2^9} - \frac{72a^7x^2}{2^{11}} \\
& - \frac{19}{2} \frac{a^4}{2^6} - \frac{39}{2} \frac{a^6}{2^8} - 36\frac{x^2a^4}{2^8} + \frac{5.39}{2} \frac{a^6x^2}{2^{10}} + \frac{27a^5}{2^7} - \frac{18a^5x^2}{2^9} + \frac{6a^7}{2^9} + \frac{6a^9}{2^{11}} - \frac{36a^7x^2}{2^{11}} + \frac{24a^9x^2}{2^{13}} \\
& - 36\frac{a^4}{2^4} - 12\frac{a^4}{2^6} - 36\frac{a^2x^2}{2^6} + 36\frac{a^4x^2}{2^8} + 48\frac{a^3}{2^3} \\
& + 18\frac{a^4}{2^4} - \frac{27}{2}\frac{a^3}{2^5} - \frac{9}{2}\frac{a^5}{2^7} - \frac{27}{2}\frac{a^3x^2}{2^7} + \frac{27}{2}\frac{a^5x^2}{2^9} \\
& + 24\frac{a^4}{2^6} - 18\frac{a^5}{2^7} - 6\frac{a^7}{2^9} - 18\frac{a^5x^2}{2^9} + 18\frac{a^7x^2}{2^{11}} \\
& - 12\frac{a^6}{2^8} + 9\frac{a^9}{2^9} + 3\frac{a^9}{2^{11}} + 9\frac{a^7x^2}{2^{11}} - 9\frac{a^9x^2}{2^{13}} \\
& + \frac{9}{2}13\frac{a^4}{2^6} + \frac{3}{2}13\frac{a^6}{2^8} + \frac{9}{2}13\frac{a^4x^2}{2^8} - \frac{9}{2}13\frac{a^6x^2}{2^{10}} - 6.13\frac{a^3}{2^5}
\end{aligned}$$

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$$\begin{aligned}
& = \frac{a^2}{2^4} \left[ 3.18 + \frac{3.19}{2} - 36 + 18 \right] - \frac{a^2x^2}{2^6} \left[ 3.12 - 3.36 + 36 \right] + \frac{a^4}{2^6} \left[ 12 + \frac{3.39}{2} - \frac{19}{2} - 12 \right. \\
& \quad \left. + 24 + \frac{9}{2}13 \right] \\
& + \frac{a^6}{2^8} \left[ 12 - \frac{39}{2} - 12 + \frac{3}{2}13 \right] + \frac{a^4x^2}{2^8} \left[ -72 - \frac{3.5.39}{2} - 36 + 36 + \frac{9}{2}13 \right] + \\
& + \frac{a^6x^2}{2^{10}} \left[ 48 + \frac{5.39}{2} - 9 \cdot \frac{13}{2} \right] + \frac{a^2}{2^5} \left[ -19 \right] + \frac{a^3}{2^5} \left[ -39 - 81 - \frac{27}{2} - 6.13 \right] + \\
& + \frac{a^5x^2}{2^5} \left[ -72 \right] + \frac{a^3x^2}{2^7} \left[ 5.39 + 54 - \frac{27}{2} \right] + \frac{a^5}{2^7} \left[ -18 + 27 - \frac{9}{2} - 18 \right] + \\
& + \frac{a^7}{2^9} \left[ 18 + 6 - 6 + 9 \right] + \frac{a^5x^2}{2^9} \left[ 108 - 18 + \frac{27}{2} - 18 \right] + \frac{a^7x^2}{2^{11}} \left[ -72 - 36 + 18 + 9 \right] \\
& + \frac{a^9}{2^{11}} \left[ 6 + 3 \right] + \frac{a^9x^2}{2^{13}} \left[ 24 - 9 \right]
\end{aligned}$$



$$= \frac{a^2}{n^4} \frac{72}{2} + \frac{a^2 x^2}{n^6} \cdot 36 + \frac{a^4}{n^8} \frac{117}{24} - \frac{282}{19} = \frac{263}{2} + \frac{287}{2} + \frac{a^2 x^2}{n^{10}} \cdot 87$$

$$+ \frac{a}{n^3} \cdot 29 + \frac{a^3}{n^5} \frac{120}{78} \frac{306}{27} - \frac{a x^4}{n^5} \cdot 72 + \frac{a^3 x^2}{n^7} \left[ \frac{195}{54} \frac{249}{498} \left( + \frac{471}{2} \right) \right. \\ \left. + \frac{a^5}{n^7} \left( - \frac{27}{2} \right) + \frac{a^7}{n^9} (-9) + \frac{a^5 x^4}{n^9} \left( \frac{144}{27} \right) + \frac{a^7 x^2}{n^{11}} (-81) + 9 \frac{a^9}{n^{11}} + 15 \frac{a^9 x^2}{n^{13}} \right]$$

$$u \frac{\partial}{\partial x} + v \frac{\partial}{\partial y} + w \frac{\partial}{\partial z} = \frac{\mu c^3}{32 \kappa} \left[ \frac{129}{2} \frac{a^2}{n^4} + 36 \frac{a^2 x^2}{n^6} + \frac{263}{2} \frac{a^4}{n^8} - 306 \frac{a^2 x^4}{n^8} + 87 \frac{a^6 x^2}{n^{10}} \right. \\ \left. + 29 \frac{a}{n^3} - \frac{423}{2} \frac{a^3}{n^5} - 72 \frac{a x^4}{n^5} + \frac{471}{2} \frac{a^3 x^2}{n^7} - \frac{27}{2} \frac{a^5}{n^7} - 9 \frac{a^7}{n^9} + \frac{171}{2} \frac{a^5 x^2}{n^9} - 81 \frac{a^7 x^2}{n^{11}} \right. \\ \left. + 9 \frac{a^9}{n^{11}} + 15 \frac{a^9 x^2}{n^{13}} \right]$$

$$\frac{1}{n^2} = \frac{\mu c^3}{32 \kappa} \left[ \frac{129}{2} \frac{a^2}{n^4} + \frac{263}{2} \frac{a^4}{n^8} - 306 \frac{a^2 x^4}{n^8} - \frac{423}{2} \frac{a^3}{n^5} + \frac{471}{2} \frac{a^3 x^2}{n^7} - \frac{27}{2} \frac{a^5}{n^7} - 9 \frac{a^7}{n^9} + \frac{171}{2} \frac{a^5 x^2}{n^9} - 81 \frac{a^7 x^2}{n^{11}} + 9 \frac{a^9}{n^{11}} + 15 \frac{a^9 x^2}{n^{13}} \right]$$

$$\begin{array}{r} 196 \\ 129 \\ \hline 225 \end{array} \quad \begin{array}{r} 306 \\ 225 \\ \hline 531 \\ 225 \\ \hline -306 \\ \hline 153 \end{array}$$

$$\begin{array}{r} 42 \\ 15 \\ \hline +57 \\ \hline 222 \\ 57 \\ \hline -165 \end{array}$$

$$\frac{129}{2} \quad \frac{392}{2} = 196$$

$$\frac{263}{2} \quad 29 \quad -423 \quad 450 - 225$$

$$144 \quad -27 \quad 48$$

$$\text{do } \kappa = 0 \quad -43$$

$$u \frac{\partial}{\partial x} = \frac{\mu c^2}{32 \kappa} \left[ (29 - 72) \frac{a^2}{n^4} + \frac{a^3}{n^4} \left( - \frac{423}{2} + \frac{471}{2} \right) \right. \\ \left. + \frac{a^5}{n^6} \left( - \frac{27}{2} + \frac{171}{2} \right) + \frac{a^7}{n^8} (-9 - 81) + 24 \frac{a^9}{n^{10}} \right. \\ \left. + 72 \quad -90 \right]$$

$$n = a$$

$$\begin{array}{r} -60 \\ -120 \\ \hline +144 \\ 54 \\ \hline 258 \\ -198 \\ \hline -60 \end{array}$$

$$+9$$



$$u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} = \nabla \theta \cdot \frac{1}{r} \nabla r \cos(\alpha, \theta)$$

$$= \frac{\mu c^2}{32 \kappa} \left\{ \frac{129}{2} \frac{a^2 x}{r^4} + 36 \frac{a^2 x^3}{r^6} + \frac{263}{2} \frac{a^4 x}{r^6} - \frac{306 a^4 x^3}{r^8} + 87 \frac{a^6 x^3}{r^{10}} \right. \\ \left. + 29 \frac{a^8 x}{r^8} - \frac{423}{2} \frac{a^2 x^3}{r^8} - 72 \frac{a^2 x^3}{r^8} + \frac{471}{2} \frac{a^2 x^3}{r^8} - \frac{27}{2} \frac{a^5 x}{r^7} - 9 \frac{a^7 x}{r^9} + \frac{171}{2} \frac{a^5 x^3}{r^9} - \right. \\ \left. - 81 \frac{a^7 x^3}{r^{11}} + 9 \frac{a^9 x}{r^{11}} + 15 \frac{a^9 x^3}{r^{13}} \right\}$$

$$\Delta^2 \left( \frac{x}{r} \right) = -2 \frac{x}{r^3}$$

$$\Delta^2 \left( \frac{x}{r^2} \right) = \frac{x}{r^4}$$

$$\Delta^2 \left( \frac{x}{r^3} \right) = 0$$

$$\Delta^2 \left( \frac{x}{r^4} \right) = 4 \frac{x}{r^6}$$

$$\Delta^2 \left( \frac{x}{r^5} \right) = 10 \frac{x}{r^7}$$

$$\Delta^2 \left( \frac{x}{r^6} \right) = 18 \frac{x}{r^8}$$

$$\Delta^2 \left( \frac{x}{r^7} \right) = 28 \frac{x}{r^9}$$

$$\Delta^2 \left( \frac{x}{r^8} \right) = 40 \frac{x}{r^{10}}$$

$$\Delta^2 \left( \frac{x}{r^9} \right) = 54 \frac{x}{r^{11}}$$

$$\Delta^2 \left( \frac{x^3}{r^3} \right) = \frac{6x^3}{r^3} - 12 \frac{x^3}{r^5}$$

$$\Delta^2 \left( \frac{x^3}{r^4} \right) = \frac{6x^3}{r^4} - 12 \frac{x^3}{r^6}$$

$$\Delta^2 \left( \frac{x^3}{r^5} \right) = \frac{6x^3}{r^5} - 10 \frac{x^3}{r^7}$$

$$\Delta^2 \left( \frac{x^3}{r^6} \right) = \frac{6x^3}{r^6} - 6 \frac{x^3}{r^8}$$

$$\Delta^2 \left( \frac{x^3}{r^7} \right) = \frac{6x^3}{r^7} - 0$$

$$\Delta^2 \left( \frac{x^3}{r^8} \right) = \frac{6x^3}{r^8} - 8 \frac{x^3}{r^{10}}$$

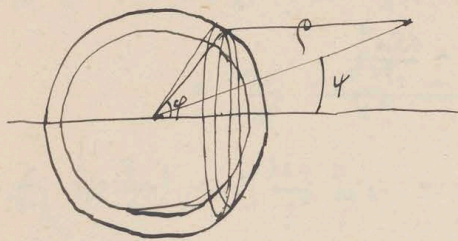
$$\Delta^2 \left( \frac{x^3}{r^9} \right) = \frac{6x^3}{r^9} - 18 \frac{x^3}{r^{11}}$$

$$\Delta^2 \left( \frac{x^3}{r^{11}} \right) = \frac{6x^3}{r^{11}} - 44 \frac{x^3}{r^{13}}$$

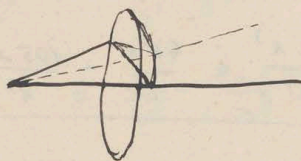


$$\text{pot}\left(\frac{x}{25}\right) = \text{pot} \frac{\cos \varphi}{24} = \text{pot} \frac{1}{24} \frac{\partial \left(\frac{1}{24}\right)}{\partial x}$$

$$\cos \chi = \cos \varphi \cos \varphi + \sin \varphi \sin \varphi \cos 2$$



$$\frac{1}{\rho} = \frac{1}{\sqrt{r^2 + R^2 - 2Rr \cos \alpha}}$$



$$\int_{\varphi=0}^{\varphi=2\pi} \int_{r=0}^r \int_{z=0}^z \frac{r^2 \sqrt{r^2 + R^2 - 2Rr(\cos\varphi \cos\psi + \sin\varphi \sin\psi \cos\epsilon)}}{r^2} dr d\varphi dz \cdot \cos\psi$$

$$\begin{aligned} a &= R^2 \\ b &= -2R \cos \gamma \\ c &= 1 \end{aligned}$$

$$\int_a^R \frac{dz}{z^2 \sqrt{z^2 + R^2 - 2Rz \cos \chi}} = -\frac{\sqrt{\quad}}{R^2 z} + \frac{2R \cos \chi}{2R^2} \int \frac{dz}{z \sqrt{\quad}} - \cancel{\quad}$$

$$= \frac{1}{R} \ln \frac{2R \sqrt{\quad} - (2R^2 - 2Rz \cos \chi)}{z}$$

$$\text{pot}\left(\frac{x}{2^n}\right) = -\frac{\text{pot}}{n-2} \frac{\partial}{\partial x} \left(\frac{1}{2^{n-2}}\right) = -\frac{1}{n-2} \frac{\partial}{\partial x} \cdot \text{pot}\left(\frac{1}{2^{n-2}}\right)$$

$$\int_0^R \frac{r^2 dr}{r^{n-2}} = \int_0^R r^{4-n} dr = \frac{r^{5-n}}{(5-n)} \Big|_0^R = \frac{R^{5-n}}{5-n}$$



$$\frac{\partial}{\partial x} \left( \frac{1}{x^2} \right) = -\frac{x}{x^3}$$

$$\frac{\partial^2}{\partial x^2} = -\frac{1}{x^3} + \frac{2x^2}{x^5}$$

$$\frac{\partial^3}{\partial x^3} = -\frac{3x}{x^5} + \frac{6x}{x^5} - \frac{15x^3}{x^7} = \frac{3x}{x^5} - \frac{15x^3}{x^7}$$

$$\frac{\partial}{\partial x} \left( \frac{1}{x^3} \right) = -\frac{3x}{x^5}$$

$$\frac{\partial^2}{\partial x^2} ( ) = -\frac{3}{x^5} + \frac{15x^2}{x^7}$$

$$\frac{\partial^3}{\partial x^3} = +\frac{15x}{x^7} + \frac{30x}{x^7} - \frac{3 \cdot 5 \cdot 7 \cdot x^3}{x^9} = \frac{45x}{x^7} - \frac{105x^3}{x^9}$$

$$105 \frac{x^3}{x^9} = -\frac{\partial^3}{\partial x^3} \left( \frac{1}{x^3} \right) + \frac{45}{5} \frac{\partial}{\partial x} \left( \frac{1}{x^5} \right)$$

$$\frac{x^3}{x^9} = -\frac{1}{105} \frac{\partial^3}{\partial x^3} \left( \frac{1}{x^3} \right) - \frac{3}{35} \frac{\partial}{\partial x} \left( \frac{1}{x^5} \right)$$

$$\text{put } \left( \frac{x^3}{x^9} \right) = -\frac{1}{105} \frac{\partial^3}{\partial x^3} \text{put } \left( \frac{1}{x^3} \right) - \frac{3}{35} \frac{\partial}{\partial x} \text{put } \left( \frac{1}{x^5} \right)$$

$$\int \frac{x^2 dx}{x^3} = \log R \quad \frac{\log x}{2}$$

$$\int \frac{x^2 dx}{x^5} = \int \frac{dx}{x^3} = -\frac{1}{2x^2}$$

$$\frac{\partial}{\partial x} \left( \log \frac{x}{2} \right) = \left( \frac{1}{x^2} - \frac{\log x}{x^2} \right) \frac{x}{2}$$

$$\frac{x}{x^4}$$

$$\frac{x}{x^3} \quad \frac{x}{x^4} \quad \frac{x}{x^3} \log x$$



$$\frac{\partial}{\partial x} \left( \frac{x}{2^5} y_2 \right) = \frac{1}{2^5} y_2 - \frac{3x^2}{2^5} y_2 + \frac{x^2}{2^5}$$

$$\begin{aligned} \frac{\partial}{\partial x} ( \quad ) &= -\frac{3x}{2^5} y_2 + \frac{x}{2^5} - \frac{6x}{2^5} y_2 + \frac{15x^3}{2^7} y_2 - \frac{3x^3}{2^7} + \frac{2x}{2^5} - \frac{5x^3}{2^7} \\ &= \frac{3x}{2^5} - \frac{8x^3}{2^7} - \frac{9x}{2^5} y_2 + \frac{15x^3}{2^7} y_2 \end{aligned}$$

$$\frac{\partial}{\partial y} \left( \frac{x}{2^5} y_2 \right) = -\frac{3xy}{2^5} y_2 + \frac{xy}{2^5}$$

$$\begin{aligned} \frac{\partial^2}{\partial y^2} &= -\frac{3x}{2^5} y_2 + \frac{15xy^2}{2^7} y_2 - \frac{3xy^2}{2^7} + \frac{x}{2^5} - \frac{5xy^2}{2^7} \\ &= \frac{x}{2^5} - \frac{8xy^2}{2^7} - \frac{3x}{2^5} y_2 + \frac{15xy^2}{2^7} y_2 \end{aligned}$$

$$\Delta^2 \left( \frac{x}{2^5} y_2 \right) = \frac{5x}{2^5} - \frac{8x}{2^5} - \frac{15x}{2^5} y_2 + \frac{15x}{2^5} y_2 = -\frac{3x}{2^5}$$

$$\frac{\partial^3}{\partial x^3} \left( \frac{x}{2^5} y_2 \right) = \dots + \frac{45x^2}{2^7} y_2 - \frac{9}{2^5} y_2 + \frac{45x^2}{2^7} y_2 - \frac{15 \cdot 7x^4}{2^9} y_2$$

$$\frac{\partial^2}{\partial x^2} \frac{x^2}{2^7} y_2 = \frac{2x}{2^7} y_2 - \frac{7x^3}{2^9} y_2 + \frac{x^3}{2^9} \quad \left| \frac{\partial}{\partial y} = -\frac{7x^2}{2^9} y_2 + \frac{x^2}{2^9} \right.$$

$$\begin{aligned} &\frac{2}{2^7} y_2 - \frac{35x^2}{2^9} y_2 - \frac{7x^2}{2^9} y_2 + \frac{63x^4}{2^{11}} y_2 + \frac{2x^2}{2^9} - \frac{7x^4}{2^{11}} + \frac{3x^2}{2^9} - \frac{9x^4}{2^{11}} \\ &- \frac{7x^2}{2^9} y_2 + \frac{63x^4}{2^{11}} y_2 \quad - \frac{7x^2}{2^{11}} + \frac{x^2}{2^9} - \frac{9x^4}{2^{11}} \end{aligned}$$

$$\Delta^2 \left( \frac{x^2}{2^7} y_2 \right) = \frac{2}{2^7} y_2 - \frac{49x^2}{2^9} y_2 + \frac{63x^2}{2^9} y_2 + \frac{2x^2}{2^9} - \frac{7x^2}{2^9} + \frac{5x^2}{2^9} - \frac{9x^2}{2^9}$$

$$= \frac{2}{2^7} y_2 + \frac{14x^2}{2^9} y_2 - \frac{9x^2}{2^9}$$



$$\frac{\partial}{\partial x} \left( \frac{x}{2^5} \log_2 \right)$$

$$\frac{1}{2^5} \log_2 - \frac{5x^4}{2^7} \log_2 + \frac{x^2}{2^7}$$

$$- \frac{5x^4}{2^7} \log_2 + \frac{x^4}{2^7}$$

$$\frac{\delta}{\delta x^2}$$

$$\frac{15x}{2^7} \log_2 + \frac{35x^3}{2^9} \log_2 + \frac{x}{2^7} - \frac{5x^3}{2^9} + \frac{2x}{2^7} - \frac{7x^3}{2^9}$$

$$- \frac{5x}{2^7} \log_2 + \frac{35x^3}{2^9} \log_2 + - \frac{5x^3}{2^9} + \frac{x}{2^7} - \frac{7x^3}{2^9}$$

$$- \frac{25x}{2^7} \log_2 + \frac{35x}{2^7} \log_2 + \frac{5x}{2^7} - \frac{12x}{2^7}$$

$$= \frac{10x}{2^7} \log_2 - \frac{7x}{2^7}$$

$$\frac{x^3}{2^7} \log_2$$

$$\frac{3x^2}{2^7} \log_2 - \frac{7x^4}{2^9} \log_2 + \frac{x^4}{2^9}$$

$$- \frac{7x^4}{2^9} \log_2 + \frac{x^4}{2^9}$$

$$\frac{\delta}{\delta x^2}$$

$$\frac{6x}{2^7} \log_2 - \frac{49x^3}{2^9} \log_2 + \frac{63x^5}{2^{11}} \log_2 + \frac{3x^3}{2^9} - \frac{7x^5}{2^{11}} + \frac{4x^3}{2^9} - \frac{9x^5}{2^{11}}$$

$$- \frac{7x^3}{2^9} \log_2 + \frac{63x^5}{2^{11}} \log_2 - \frac{7x^5}{2^{11}} + \frac{x^3}{2^9} - \frac{9x^5}{2^{11}}$$

$$\delta = \frac{6x}{2^7} \log_2 + \frac{x^3}{2^9} - \frac{x^3}{2^9} - \frac{7x^3}{2^9}$$

$$\frac{x^3}{2^9} = \frac{6x}{2^7} \log_2 - \Delta^2 \left( \frac{x^3}{2^7} \log_2 \right) \Big|_5$$

$$\frac{x}{2^7} = \frac{10x}{2^7} \log_2 - \Delta^2 \left( \frac{x}{2^5} \log_2 \right) \Big|_3$$

$$\frac{5x^3}{2^9} - \frac{3x}{2^7} = \Delta^2 \left( \frac{3x}{2^5} \log_2 - \frac{5x^3}{2^7} \log_2 \right)$$

$$\frac{x}{2^7} = \Delta^2 \left( \frac{x}{10 \cdot 2^5} \right)$$



$$\frac{5x^3}{2^9} = \Delta^2 \left( \frac{3}{10} \frac{x}{2^5} + \frac{3x}{7 \cdot 2^5} y_1 x - \frac{5x^3}{7 \cdot 2^7} y_1^2 \right)$$

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$$\frac{x^3}{2^9} = \Delta^2 \left\{ \frac{3}{50} \frac{x}{2^5} + \frac{3x}{35 \cdot 2^5} y_1 x - \frac{x^3}{7 \cdot 2^7} y_1^2 \right\} = \Delta^2 \left\{ \frac{3x}{5 \cdot 2^5} \left[ \frac{1}{10} + \frac{y_1^2}{7} \right] - \frac{x^3}{7 \cdot 2^7} y_1^2 \right\}$$

$$\frac{x}{2^5} = -\frac{1}{3} \Delta^2 \left( \frac{x}{2^5} y_1^2 \right)$$

$$\frac{9x^5}{2^{11}}$$

$$\frac{x^3 y_1^2}{2^{11}}$$

$$\rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x}$$

$$\frac{\partial \rho}{\partial t} + \rho \frac{\partial u}{\partial x} = 0$$

$$\rho \frac{\partial v}{\partial t} = -\frac{\partial p}{\partial x} + \mu \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial p}{\partial t} + k p \frac{\partial u}{\partial x} + \mu \frac{\partial^2 p}{\partial x^2} = (k-1) \left[ \mu \Phi + \kappa \frac{\partial^2 \Phi}{\partial x^2} \right]$$

$$v = A e^{-\alpha x} \cos(\rho x + y t)$$

$$\frac{\partial v}{\partial x} = A e^{-\alpha x} [-\alpha \cos - \rho \sin]$$

$$\frac{\partial v}{\partial t} = -A e^{-\alpha x} y \sin$$

$$\frac{\partial^2 v}{\partial x^2} = A e^{-\alpha x} [\alpha^2 \cos + \alpha \rho \sin - \rho^2 \cos]$$

$$\alpha x = \alpha \cdot y$$

$$\frac{dx}{dt} = \frac{dy}{dt}$$

$$-\rho y = \mu \alpha \rho$$

$$\alpha = \rho$$

$$\alpha = \sqrt{\frac{\rho y}{\mu}}$$

$$v = A e^{-x \sqrt{\frac{\rho y}{\mu}}} \cos(x \sqrt{\frac{\rho y}{\mu}} - y t)$$

epitrymnik samkani  $\sqrt{\frac{\mu}{\rho y}}$

$$\text{prędkość fali: } = \frac{y}{\sqrt{\frac{\mu}{\rho y}}} =$$

$$\frac{\partial p}{\partial t} + \mu \frac{\partial^2 p}{\partial x^2} + k p \frac{\partial u}{\partial x} = (k-1) \left[ \mu \left( \frac{\partial v}{\partial x} \right)^2 + \kappa \frac{\partial^2 \Phi}{\partial x^2} \right]$$

ten wykład nie wystarczy

$$\text{Kip. } y = 22 \text{ n} \quad \text{Kip. } n = 140$$

$$y = 1000$$

$$\mu = \frac{1000}{\frac{1000}{6 \cdot 00009}} = 10 \frac{\text{cm}}{\text{sec}}$$

$$\sqrt{\frac{\mu}{\rho y}} = 0.01$$

$$\frac{\partial p}{\partial t} + \rho \frac{\partial u}{\partial x} = 0$$

$$\text{Gdyby } u \text{ było } 0, \quad \frac{\partial p}{\partial t} = -\frac{\partial p}{\partial x} \quad \frac{\partial^2 \Phi}{\partial x^2} = A e^{-2\alpha x} [\cos + \sin(\alpha y t)]$$

$$= \alpha^2 A^2 e^{-2\alpha x} [1 + 2 \sin \alpha y t]$$

$$= \alpha^2 A^2 e^{-2\alpha x} [1 + \sin 2(\alpha y t)]$$

$$\Phi = B e^{-\alpha x} [1 + m \cos(2x + ct)]$$



$$\frac{\partial \theta}{\partial x} = B e^{-\alpha x} [a^2 + (a^2 - b^2) \cos \omega x + ab \sin \omega x] = \frac{\alpha^2 A^2}{4 \frac{\kappa}{\mu}} e^{-2\alpha x} [1 + \cos 2(\alpha x - \gamma t)] \quad 291$$

$$a = b$$

$$a = 2\alpha$$

$$bx + ct = 2\alpha x - \gamma t$$

$$b = 2\alpha$$

$$c = -\gamma$$

$$4\alpha^2 B \frac{\kappa}{\mu} = A^2$$

$$m = 1$$

$$B = \frac{A^2}{4 \frac{\kappa}{\mu}}$$

$$4\alpha^2 m B \frac{\kappa}{\mu} = A^2$$

$$\theta = M + \frac{A^2}{4 \frac{\kappa}{\mu}} e^{-2\alpha x} [1 + \cos 2(\alpha x - \gamma t)] + c$$

$$\theta_0 = F(t) + \frac{A^2}{4 \frac{\kappa}{\mu}} [1 + \cos 2\gamma t]$$

$$F(t) = \theta_0 - \frac{A^2}{4 \frac{\kappa}{\mu}} [1 + \cos 2\gamma t]$$

$$\theta = \theta_0 + \frac{A^2}{4 \frac{\kappa}{\mu}} \left\{ e^{-2\alpha x} [1 + \cos(2\alpha x - \gamma t)] - 1 - \cos 2\gamma t \right\}$$

$$\alpha = \sqrt{\frac{\rho}{\mu}} \gamma$$

$$\frac{1}{r} \frac{\partial \theta}{\partial t} = \frac{1}{r} \frac{\partial \theta}{\partial t} + \frac{1}{\theta} \frac{\partial \theta}{\partial t}$$

$$\frac{\partial \theta}{\partial t} = R(\theta \frac{\partial \theta}{\partial t} + \rho \frac{\partial \theta}{\partial t}) = -\rho \frac{\partial u}{\partial x} + R\rho \frac{\partial \theta}{\partial t}$$

$$\text{Zerlegung } u \frac{\partial u}{\partial x} = -\rho u \frac{\partial u}{\partial t}$$

$$(k-1) \rho \frac{\partial u}{\partial x} + R\rho \frac{\partial \theta}{\partial t} = (k-1) \left[ \mu \left( \frac{\partial u}{\partial x} \right)^2 + \kappa \frac{\partial \theta}{\partial x} \right]$$

$$\text{Zerlegung } \frac{\partial u}{\partial x} = 0 \quad \text{oder } k=1$$

$$\alpha' = \sqrt{\frac{\rho}{\mu}} \gamma$$

$$\alpha' = \sqrt{\frac{\rho}{\mu}} \gamma$$

$$\theta = \frac{A^2}{4 \frac{\kappa}{\mu}} \left\{ e^{-2\alpha x} [1 + \cos 2(\alpha x - \gamma t)] - 1 - \cos 2\gamma t \right\} + \theta_0$$

$$\frac{R}{\kappa} = \sqrt{\frac{\mu}{\rho}} = \sqrt{\frac{1}{0.0013 \cdot 243 \cdot 0.0006 \cdot 15}} = \sqrt{\frac{1}{0.0006 \cdot 15}} = \sqrt{\frac{1}{0.009}} = \frac{1}{0.03}$$

2. teiler  $\alpha'$  berechnen

0 ile wyrażenie ciepła wartości przodyanie:

$$\int_0^{\infty} \Phi dx = \alpha^2 A^2 \int_0^{\infty} e^{-2\alpha x} [1 + \sin 2(\alpha x - y t)] dx =$$

$$= \alpha^2 A^2 \int_0^{\infty} [e^{-2\alpha x} + e^{-2\alpha x} \sin 2\alpha x \cos y t - e^{-2\alpha x} \cos 2\alpha x \sin y t] dx$$

$$\int_0^{\infty} e^{-y} \sin y dy = -e^{-y} \sin y \Big|_0^{\infty} + \int_0^{\infty} e^{-y} \cos y dy = \frac{1}{2}$$

$$\int_0^{\infty} e^{-2\alpha x} \sin 2\alpha x dx = \frac{1}{2\alpha} \cdot \frac{1}{2} = \frac{1}{4\alpha}$$

$$\int_0^{\infty} e^{-2\alpha x} dx = \frac{1}{2\alpha}$$

$$\int \Phi = \alpha^2 A^2 \left[ \frac{1}{2\alpha} + \frac{1}{4\alpha} \cos y t - \frac{1}{4\alpha} \sin y t \right]$$

$$= \frac{\alpha A^2}{4} [2 + \cos y t - \sin y t] = \frac{\alpha A^2}{4} \left[ 2 + \frac{\cos y t + \sin y t}{2} - \frac{\cos y t - \sin y t}{2} \right]$$

Wielkość wyrażająca przód. granic



Tryblin - the magnet method very ~~interesting~~:

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$$\rho \frac{\partial u}{\partial t} = -\frac{\partial p}{\partial x} + \mu \frac{\partial \text{div}}{\partial x} + \mu \Delta^2 u$$

$$\rho \frac{\partial v}{\partial t} = -\frac{\partial p}{\partial y} + \mu \frac{\partial \text{div}}{\partial y} + \mu \Delta^2 v$$

$$= \dots$$

$$\frac{\partial \rho}{\partial t} + \rho \text{div} + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = 0$$

$$\frac{\partial \rho}{\partial t} + \rho \frac{\partial \text{div}}{\partial t} + \text{div} \frac{\partial \rho}{\partial t} + \frac{\partial \rho}{\partial x} \frac{\partial \rho}{\partial x} + \dots = 0$$

$$\rho \frac{\partial \text{div}}{\partial t} + \left( \frac{\partial \rho}{\partial x} \frac{\partial u}{\partial t} + \frac{\partial \rho}{\partial y} \frac{\partial v}{\partial t} + \dots \right) = -\nabla^2 p + \frac{\mu}{3} \nabla^2 \text{div} + \mu \nabla^2 \text{div}$$

$$= -\nabla^2 p + \frac{4}{3} \mu \nabla^2 \text{div}$$

$$\left[ \frac{\partial \rho}{\partial t} + \frac{\partial \rho}{\partial t} \text{div} + u \frac{\partial \rho}{\partial x} + \dots \right] = \dots$$

$$\rho \frac{\partial}{\partial t} \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right) + \frac{\partial \rho}{\partial y} \frac{\partial u}{\partial t} - \frac{\partial \rho}{\partial x} \frac{\partial v}{\partial t} = \mu \Delta^2 \left( \frac{\partial u}{\partial y} - \frac{\partial v}{\partial x} \right)$$

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$\frac{b}{h} = \frac{m}{h_0}$  2.  $\frac{1}{g} \approx \frac{1}{g_0} \approx \frac{1}{g_0} \approx \frac{1}{g_0}$

$$\left. \begin{aligned} b &\equiv \alpha \frac{m}{n} \equiv \frac{b n}{n} \\ m b &\equiv \cancel{\alpha m} \equiv \beta \frac{r}{n} \end{aligned} \right\} \begin{aligned} \alpha \frac{m^2}{n} &\equiv \beta \frac{r}{n} & \frac{r}{n} &\equiv 1 \\ \beta &= \alpha \frac{m^2}{n} & \underline{\underline{r=n}} & \\ b &= \frac{\beta}{m} & \underline{\underline{m}} &= \sqrt{\frac{n \beta}{\alpha}} \\ & & \underline{\underline{b}} &= \underline{\underline{\frac{\beta}{m}}} \end{aligned}$$

$$\frac{\partial L}{\partial x} = \frac{\partial L}{\partial x} + \mu \frac{\partial \tilde{L}}{\partial x}$$

$$k_f \frac{\partial u}{\partial x} = \mu \left( \frac{\partial u}{\partial x} \right)^2 + K \Delta u$$

$$\left. \begin{aligned} \frac{b}{n} &\equiv R \frac{b}{n} \equiv \alpha \frac{m}{n^2} \\ \frac{bm}{n} &\equiv \alpha \left( \frac{m}{n} \right)^2 \equiv \rho \frac{m}{n^2} \end{aligned} \right\} \frac{\alpha m^2}{n} = \rho \frac{m}{n} \quad n = \frac{R}{\rho}$$

$$\begin{aligned} \nabla^2 \psi &= -\epsilon \nabla^2 \psi - \left[ \frac{\partial^2 \psi}{\partial x^2} + \frac{\partial^2 \psi}{\partial y^2} + \frac{\partial^2 \psi}{\partial z^2} \right] + \epsilon \nabla^2 \psi \\ \int \frac{\partial^2 \psi}{\partial x^2} d\tau &= - \int \epsilon \frac{\partial^2 \psi}{\partial x^2} d\tau \end{aligned}$$

$\varepsilon$  mellem tykkelsen  $n$  //  $\frac{\partial \varepsilon}{\partial x} = \frac{\partial \varepsilon}{\partial n}$  ~~ikke~~  $\frac{\partial \varepsilon}{\partial x}$

" " " styrenz  
jubilant isolieren

$$\frac{\partial \mathcal{L}}{\partial x} \frac{\partial \mathcal{H}}{\partial x} + \dots = 0$$



$$\left. \begin{aligned} \frac{\partial \psi}{\partial x} &= X + \mu \nabla u &= -\varepsilon \frac{\partial u}{\partial x} + \mu \nabla u \\ \frac{\partial \psi}{\partial y} &= Y + \mu \nabla v &= -\varepsilon \frac{\partial u}{\partial y} + \mu \nabla v \\ \frac{\partial \psi}{\partial z} &= Z + \mu \nabla w &= -\varepsilon \frac{\partial u}{\partial z} + \mu \nabla w \end{aligned} \right\} \nabla \psi = -\varepsilon \nabla u + \mu \nabla^2 u$$

$u$  nie zmienia się znaczenie w składowe  $\delta$

$$\left[ \underbrace{\frac{\partial \psi}{\partial x} \cos nx + \frac{\partial \psi}{\partial y} \cos ny + \dots}_{\frac{\partial \psi}{\partial n}} \right] = -\varepsilon \left[ \frac{\partial u}{\partial x} \cos nx + \dots \right] + \mu \left[ \nabla u \cdot \cos nx + \dots \right]$$

~~$$u = u_0 + \varepsilon \frac{\partial u}{\partial x} + \frac{\varepsilon^2}{2} \frac{\partial^2 u}{\partial x^2} + \dots$$~~
~~$$v = v_0 + \varepsilon \frac{\partial v}{\partial x} + \frac{\varepsilon^2}{2} \frac{\partial^2 v}{\partial x^2} + \dots$$~~

nie tylko w punkcie  $0=0$  ale w poszukiwaniu albo niepełnym

$$\text{dla } \xi \cos nx + \eta \cos ny + \dots \cos nz = 0$$

$$\text{gdzie wtedy } u=v=w=0$$

podstawienie  $\delta$  do  $u$  i  $v$  do  $0$

$$u = u_0 + \xi \left( \frac{\partial u}{\partial x} \right)_0 + \eta \left( \frac{\partial u}{\partial y} \right)_0 + \zeta \left( \frac{\partial u}{\partial z} \right)_0 + \frac{\xi^2}{2} \left( \frac{\partial^2 u}{\partial x^2} \right)_0 + \dots$$

$$\xi \cos nx = -(\xi \cos nx + \eta \cos ny)$$

$$0 = \xi \left[ \underbrace{\frac{\partial u}{\partial x} \cos nz - \frac{\partial u}{\partial z} \cos nx}_{=0} \right] + \eta \left[ \underbrace{\frac{\partial u}{\partial y} \cos nz - \frac{\partial u}{\partial z} \cos ny}_{=0} \right]$$

$$\text{Zatem } \frac{\frac{\partial u}{\partial x}}{\cos nx} = \frac{\frac{\partial u}{\partial y}}{\cos ny} = \frac{\frac{\partial u}{\partial z}}{\cos nz} = \frac{\partial u}{\partial n}$$

$$\text{Zatem: } u = \left( \frac{\partial u}{\partial n} \right)_0 \left[ \xi \cos nx + \eta \cos ny + \zeta \cos nz \right] + \frac{\xi^2}{2} \left( \frac{\partial^2 u}{\partial x^2} \right)_0 + \dots$$

$$v =$$

$$w =$$

} z tego por. otrzymujemy



$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \quad \text{Zatem: } \left(\frac{\partial u}{\partial x}\right)_0 \omega_{n1} x + \left(\frac{\partial v}{\partial y}\right)_0 \omega_{n1} y + \left(\frac{\partial w}{\partial z}\right)_0 \omega_{n1} z = 0$$

Tzn. że wartości równoległe płaszczyźnie do powierzchni.

$$\Delta^2 u = \left(\frac{\partial^2 u}{\partial x^2}\right)_0 + \dots$$

$$\int \frac{\partial f}{\partial x} d\sigma = - \int \varepsilon \frac{\partial u}{\partial n} d\sigma + \mu \int \nabla^2 u d\sigma$$

$$\begin{aligned} \text{po } \omega_{n1} \text{ do} & \quad \cancel{\int \frac{\partial u}{\partial x} d\sigma} = \int \frac{\partial u}{\partial x} d\sigma \int \varepsilon d\sigma + \\ & \quad \cancel{\int \frac{\partial u}{\partial x} d\sigma} = \int \frac{\partial u}{\partial x} d\sigma \int \varepsilon d\sigma + \end{aligned}$$

o kierunku stycznym linii poprzecznej w stosunku do płaszczyzny w od powierzchni.

$$\frac{\partial f}{\partial s} = \varepsilon \frac{\partial u}{\partial s} + \mu \nabla^2 u_s$$

porównaj z pierwszym przybliżeniem w równoległej do powierzchni, tymże samym przybliżeniem (Lamellou)

$$\text{zatem } \nabla^2 u_s = \frac{\partial^2 u_s}{\partial n^2}$$

$$\frac{\partial u}{\partial s} \approx \text{tęże w styku}$$

$$\begin{aligned} \int \frac{\partial f}{\partial s} d\sigma &= \frac{1}{4\pi} \frac{\partial \varphi}{\partial r} \frac{\partial u}{\partial s} + \mu \frac{\partial u_s}{\partial r} + \text{ant} \\ &= \left(\frac{\partial f}{\partial s}\right)_{\text{ant}} = \text{przybliżenie} = 0 \end{aligned}$$

$$\varepsilon = \frac{1}{4\pi} \frac{\partial \varphi}{\partial r^2}$$

$$\text{zatem } \mu u_s = - \frac{1}{4\pi} (\varphi_1 - \varphi_2) \frac{\partial u}{\partial s}$$

ale gdzie tu istnieją  $u_s$ ! ?



ponieważ  $\nabla^2 u = 0$

(proporzadnie)  
zatem takie prędkości powierzchniowe jak gdyby  $u$  było potęgą cyfry prędkości  
w ruchu ciężej hydrodynamicznej

$$\frac{\partial u}{\partial x} = \mu \nabla^2 u$$

$$\frac{\partial u}{\partial y} = \mu \nabla^2 u$$

$$\frac{\partial u}{\partial z} = \mu \nabla^2 u$$

one hydrodynamiczne spełnione przez

$$\begin{aligned} u &\sim \frac{\partial u}{\partial x} \\ v &\sim \frac{\partial u}{\partial y} \text{ etc.} \\ w &\sim \frac{\partial u}{\partial z} \\ \mu &= \text{const.} \end{aligned}$$

zatem prędkościowe spełnione, bo  $\nabla^2 u = 0$

$u \sim \frac{\partial u}{\partial x}$  Napięciem: bo jeżeli to było przydałoby się uwzględnić  $\nabla^2 u$   
prędkości etc.

uważa  $u$  będzie zatem takie potęgą cyfry prędkości dla  $u, v, w$

$$\text{prędkości prop. } \frac{1}{4\pi\mu} \frac{\varphi_i - \varphi_e}{r}$$

Przejmując  $u \cdot \frac{\varphi_i - \varphi_e}{4\pi\mu}$  jako potęgę prędkości rotacyjnej otrzymujemy

prędkości odpowiednio (zostały styczne!) na powierzchni i spełniają

warunki hydro. kręgu  $\mu = \text{const.}$  [choć  $\mu_{xx}$  etc.  $\geq 0$ ]

Aby otrzymać jednak nierówności dla  $r \rightarrow \infty$  trzeba by superponować

rozprężanie: ruch  $= \frac{\varphi_i - \varphi_e}{4\pi\mu} \frac{\partial u}{\partial x}$  dla  $r \rightarrow \infty$  spoczynek dla  $r = a$

niezależnie  
t.j. (choć w decydującej mierze z prędkości)

$$\text{zatem ciśnienie: } p = \frac{\varphi_i - \varphi_e}{4\pi\mu} \left( \frac{\partial u}{\partial x} \right) \frac{x}{r^3}$$

" A



Energia i cięta:

$$\Phi = \mu \left[ 2 \left( \frac{\partial u}{\partial x} \right)^2 + \dots \right] + \left[ \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial z} \right)^2 + \dots \right]$$

$$u = \alpha \frac{\partial \psi}{\partial x}$$

$$\frac{\partial u}{\partial y} + \frac{\partial v}{\partial z} = 2 \frac{\partial^2 \psi}{\partial y \partial z}$$

potrzebujemy 519  
p. 51

$$\Phi = \mu \alpha^2 \left[ 2 \left\{ \left( \frac{\partial^2 \psi}{\partial x^2} \right)^2 + \left( \frac{\partial^2 \psi}{\partial y^2} \right)^2 + \dots \right\} + 4 \left\{ \left( \frac{\partial^2 \psi}{\partial y \partial z} \right)^2 + \dots \right\} \right] = -\mu \iint \frac{\partial(\nabla^2 \psi)}{\partial n} dS$$

$$p_{xx} = -p + 2\mu \frac{\partial u}{\partial x} = -p + 2\mu \alpha \frac{\partial^2 \psi}{\partial x^2}$$

$$p_{xy} = \mu \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial z} \right) = 2\mu \alpha \frac{\partial^2 \psi}{\partial x \partial y}$$

$$p_x = -p \cos \alpha + 2\mu \alpha \left[ \frac{\partial^2 \psi}{\partial x^2} \cos \alpha + \frac{\partial^2 \psi}{\partial x \partial y} \cos \alpha + \frac{\partial^2 \psi}{\partial x \partial z} \cos \alpha \right]$$

$$\int p_x = 2\mu \alpha \int \left[ \frac{\partial^2 \psi}{\partial x^2} \cos \alpha + \dots \right] d\omega$$

$$\int \frac{\partial}{\partial x} \cos \alpha + \frac{\partial}{\partial y} \cos \alpha = \int \frac{\partial}{\partial n} \frac{\partial \psi}{\partial x} d\omega$$

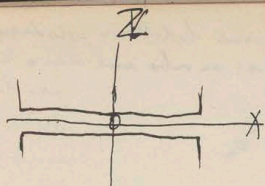
wypadkowe wartości na krawędzi i kierunku  $X = 2\mu \alpha \int \frac{\partial^2 \psi}{\partial x \partial n} d\omega$

ponieważ jeżeli  $\frac{\partial \psi}{\partial n} = 0$  wtedy cały poruszenie jest  $P=0$ ?

$$\int \psi \frac{\partial^2 \psi}{\partial n} d\omega = \int \psi \frac{\partial^2 \psi}{\partial n} d\omega - \int \left( \frac{\partial \psi}{\partial x} \right)^2 + \dots d\omega$$

$$\text{Praca poruszeniowa} = \int (p_x \cdot u + p_y \cdot v + p_z \cdot w) d\omega$$





Przebiegię na zbiegu nie w cięty lękoj

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Zadani domowosone :

$$u = u_m \cdot \frac{2}{\delta^2} ( \delta - z )$$

$$\int_0^\delta u \, dz = u_m \cdot \frac{2}{3} \delta$$

Niesionowii :  $2x \frac{d\delta}{dt} = \int_0^\delta u \, dz = \frac{2}{3} \delta u_m$

$$u_m = 3x \frac{d\delta}{dt} = \frac{3x}{\delta} \cdot c$$

$$u = \frac{12 \cdot x \cdot 2(\delta - z)}{\delta^3} \cdot c$$

$$\mu \nabla^2 u = \frac{\partial^2 u}{\partial x^2} = - \frac{24 \cdot x \cdot c}{\delta^3} \mu$$

$$p = -12 \frac{x^2 c \mu}{\delta^3} + \text{const}$$

$$p = -12 (b^2 - x^2) \frac{c \mu}{\delta^3} + p_0$$

$$\int_{-b}^{+b} p \, dx = \frac{12 c \mu}{\delta^3} \cdot 2 \left[ b^3 - \frac{b^3}{3} \right] = 16 \cdot \frac{b^3 c \mu}{\delta^3}$$

$$\begin{aligned}\frac{\partial \varphi}{\partial x} &= -\varepsilon \frac{\partial U}{\partial x} + \mu \Delta^2 U \\ \frac{\partial \varphi}{\partial y} &= -\varepsilon \frac{\partial U}{\partial y} + \mu \Delta^2 U \\ \frac{\partial \varphi}{\partial z} &= -\varepsilon \frac{\partial U}{\partial z} + \mu \Delta^2 U\end{aligned}$$

$$\left. \begin{aligned}\frac{\partial \varphi}{\partial x} &= -\varepsilon \frac{\partial U}{\partial x} + \mu \Delta^2 U \\ \frac{\partial \varphi}{\partial y} &= -\varepsilon \frac{\partial U}{\partial y} + \mu \Delta^2 U \\ \frac{\partial \varphi}{\partial z} &= -\varepsilon \frac{\partial U}{\partial z} + \mu \Delta^2 U\end{aligned} \right\}$$

2. warunki odnoscnie dodatkowej pochodnej 2  
sily wyznaczajacej potencjal na odcieku same mowi U mowi  
jako taki w  
określe S

$$\Delta^2 \varphi = \left[ \frac{\partial^2}{\partial x^2} \frac{\partial U}{\partial x} + \frac{\partial^2}{\partial y^2} \frac{\partial U}{\partial y} + \dots \right] = \left[ \text{przyjmuje się że } \varepsilon \text{ zmienne tylko w}$$

$$= \int \varepsilon \frac{\partial U}{\partial n} d\sigma + \dots \text{ [przyjmuje się że } \varepsilon \text{ zmienne tylko w}$$

$$= - \int \varepsilon \frac{\partial U}{\partial n} d\sigma + \int \varepsilon \Delta^2 U$$

zatem bierzemy to tylko wozniem, dopoki  
nie powinno V i v w porównaniu do U  
t.j. dla indukcyjnej elektry.

$$= 0$$

zatem p. ~~nie~~ może mieć Maxima i Minima tylko  
na powierzchni warstwy

A ponieważ  $\Delta^2 \varphi = 0$  także na granicy z z0 więc wogóle Maxima  
Minima tylko w niski albo na powierzchni (miej) wst.

$$\int_1^2 + \int_2^3 = \int_1^4 + \int_7^2$$

~~niepewne~~

Przy klatce w ciemności

$$\beta = \beta_0 - \frac{3}{2} \mu \frac{c q}{r^3} x = \beta_0 - \frac{3}{2} \mu \frac{c q}{r^3} \cos \vartheta$$

$$\frac{\partial \varphi}{\partial x} = \mu \Delta^2 U = + \frac{3}{2} \mu \frac{c q}{r^3} \cos \vartheta$$

$$\Delta^2 U = \frac{3}{2} \frac{c q}{r^3} \cos \vartheta$$



U flachungsmie:

$$v = f(n)$$

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$$\frac{\partial f}{\partial s} = -\varepsilon \frac{\partial u}{\partial s} + \mu \frac{\partial^2 v}{\partial s^2} = -\varepsilon \frac{\partial u}{\partial s} + \mu \frac{d^2 v}{ds^2}$$

$$\frac{\partial f}{\partial n} = -\varepsilon \frac{\partial u}{\partial n}$$

~~$$f_0 + \delta n \left[ \varepsilon \frac{\partial u}{\partial n} + \mu \frac{\partial^2 v}{\partial n^2} \right] = f_0 + \delta n \left[ \varepsilon \frac{\partial u}{\partial n} + \mu \frac{\partial^2 v}{\partial n^2} \right] + \delta n \varepsilon \frac{\partial u}{\partial n} + \delta n \mu \frac{\partial^2 v}{\partial n^2}$$~~

$$\frac{\partial f}{\partial s} = -\varepsilon \frac{\partial u}{\partial s} = -\varepsilon \frac{\partial u}{\partial s} + \mu \frac{\partial^3 v}{\partial s^3} - \frac{\partial \varepsilon}{\partial n} \frac{\partial u}{\partial s} !$$

$$\frac{\partial^3 v}{\partial s^3} = 0$$

$$\frac{d^2 v}{ds^2} = \text{const}$$

$$\frac{\partial f}{\partial s} = -\varepsilon \frac{\partial u}{\partial s} + c \mu$$

$$\frac{\partial f}{\partial n} = -\varepsilon \frac{\partial u}{\partial n}$$

$$f = -\int \varepsilon \frac{\partial u}{\partial n} dn + \int \varepsilon \frac{\partial u}{\partial s} ds + c \mu$$

$$f = f_0 + \mu c - \int \varepsilon \frac{\partial u}{\partial n} dn = f_0 + c \mu - \frac{1}{2n} \frac{\partial p}{\partial n} \frac{\partial u}{\partial n}$$

v wech mir h d k i e m e i n i e r e , U n i e s k r i e l e n

$$p = \int \varepsilon \left( \frac{\partial u}{\partial x} dx + \frac{\partial u}{\partial z} dz \right) + \mu \int \frac{d^2 v}{dz^2} dz$$

$$= f_0 + \int \left( \varepsilon \frac{\partial u}{\partial x} + \mu \frac{d^2 v}{dz^2} \right) dx$$

$$\frac{d^2 v}{dz^2} = -\varepsilon \frac{\partial u}{\partial x} = -\frac{1}{n} \frac{\partial p}{\partial z} \frac{\partial u}{\partial x}$$

$$v = \frac{1}{4n} (p_1 - p_2) \frac{\partial u}{\partial x} + \frac{c}{2} (z^2 - z \delta)$$

$$\frac{dv}{dz} = cz + a$$

$$v = \frac{cz^2}{2} + ax + b$$

$$0 = c \frac{d^2}{2} + a \delta$$

$$a = -c \frac{\delta}{2}$$

$$v = \frac{c}{2} (z^2 - z \delta)$$

$$\frac{\partial^2 v}{\partial z^2} = c = \frac{1}{n} \frac{\partial p}{\partial z} \frac{\partial u}{\partial x} = 0$$

= elektrische  
Endosmose

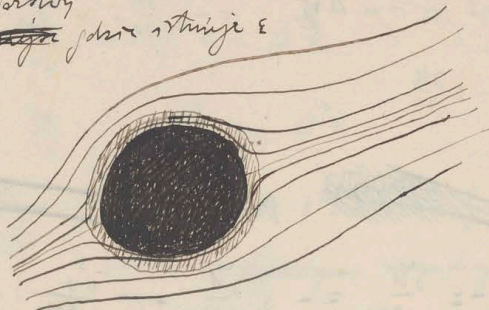


Potential zasednice dla rjavke odrotno: Strömungsströme

$\Delta^2 u = 0$  vzhodni z vzhodni <sup>vorsteh</sup> ~~strömung~~ <sup>strömung</sup> ~~strömung~~ <sup>strömung</sup>  $\varepsilon$

Na tej površini hodi

$$\lambda \frac{\partial u}{\partial n} = \lambda \frac{\partial u}{\partial n} + \varepsilon \cdot v_n$$



Opisne vzhodni vzhodni vzhodni:  
+  $\Delta u$  (= vzhodni kop)

$$\operatorname{div} [\lambda \nabla u + \varepsilon v] = 0$$

$$\lambda \nabla^2 u + \frac{\partial}{\partial x} (\varepsilon u) + \frac{\partial}{\partial y} (\varepsilon v) = 0$$

$$\lambda \nabla^2 u + u \frac{\partial \varepsilon}{\partial x} + v \frac{\partial \varepsilon}{\partial y} + w \frac{\partial \varepsilon}{\partial z} = 0$$

$$\frac{\partial u}{\partial x} = -\frac{1}{4\pi} \nabla^2 u \frac{\partial u}{\partial x} + \mu \Delta^2 u$$

$$= -4\pi\lambda \varepsilon + \mu \frac{\partial^2}{\partial x^2} + v \frac{\partial \varepsilon}{\partial y} = 0$$

$$= \frac{\partial \varepsilon}{\partial t} - \frac{\partial \varepsilon}{\partial t}$$

$$= \frac{\partial \varepsilon}{\partial t} \quad (\text{vzhodni strömung})$$

$$\frac{dx}{u} = \frac{dy}{v} = \frac{dz}{w} = \frac{d\varepsilon}{4\pi\lambda \varepsilon}$$

Strömungslinien

$$4\pi\lambda \log \varepsilon = \int \frac{dx}{u}$$

zatem z funkcion  $\log \varepsilon$   $\log \varepsilon$

$$\varepsilon = \varepsilon_0 \cdot e^{4\pi\lambda \int \frac{dx}{u}}$$

$$x - \frac{x^3}{2v^3} \quad (x - \frac{x^3}{2v^3}) \cdot w \quad 1 - \frac{x^3}{2v^3}$$



Wir jüdis & stamm nachgeben  $\varepsilon'$  i. dem abgeleiteten  $U'$

stodt v. stamm nachgehen:

~~$$\lambda \nabla^2 U + \mu \frac{\partial \varepsilon}{\partial x} + \nu \frac{\partial \varepsilon}{\partial y} + \omega \frac{\partial \varepsilon}{\partial z} = 0$$~~

$$\text{div} [\lambda \nabla(U-U') + \varepsilon v] = 0$$

$$\lambda \nabla^2 U + \mu \frac{\partial \varepsilon}{\partial x} + \nu \frac{\partial \varepsilon}{\partial y} + \omega \frac{\partial \varepsilon}{\partial z} = \cancel{\lambda \nabla^2 U} = -4\pi\lambda \varepsilon'$$

jüdis problem in bewertete diese stodt, meine stadt  
zatum:

$$4\pi\lambda(\varepsilon' - \varepsilon) + \mu \frac{\partial \varepsilon}{\partial x} + \nu \frac{\partial \varepsilon}{\partial y} + \omega \frac{\partial \varepsilon}{\partial z} = 0$$

$$\varepsilon = \varepsilon' + v$$

$$4\pi\lambda v = \mu \frac{\partial \varepsilon'}{\partial x} + \nu \frac{\partial \varepsilon'}{\partial y} + \omega \frac{\partial \varepsilon'}{\partial z} + \underbrace{(\mu \frac{\partial v}{\partial x} + \nu \frac{\partial v}{\partial y} + \omega \frac{\partial v}{\partial z})}_{\neq 0}$$

pot  $\varepsilon = \text{pot } \varepsilon' + \text{pot } v + \Phi$  zatum:  $U = U' + V + \Phi$

$$\text{pot } v = \int \frac{v}{r} dv = \frac{1}{4\pi\lambda} \int \underbrace{\left[ \mu \frac{\partial \varepsilon'}{\partial x} + \nu \frac{\partial \varepsilon'}{\partial y} + \omega \frac{\partial \varepsilon'}{\partial z} \right]}_{v \cdot \nabla \varepsilon' = \cos(\varphi, \nabla \varepsilon') = \omega(n, \nabla \varepsilon') = v_n \cdot \nabla \varepsilon'} dv$$

potenz v. plenum  
magnetismus  
 $v = \frac{z}{r} \left( \frac{\partial u}{\partial r} \right)$

$$= \frac{1}{4\pi\lambda} \int \frac{v_n}{r} \frac{\partial \varepsilon'}{\partial n} dv = \frac{1}{4\pi\lambda} \int \frac{dv}{r} \int \frac{\partial \varepsilon'}{\partial n} d\Omega \cdot \frac{\partial \varepsilon'}{\partial n}$$

$$v_n = v_{n0} + \frac{\partial v_n}{\partial z} \frac{\partial^2 v_n}{\partial n^2} = \frac{\partial v_n}{\partial z} \frac{\partial^2 v_n}{\partial n^2}$$

$$\int \frac{z}{r} \frac{\partial \varepsilon'}{\partial z} dz$$

$$= \int \frac{\partial^3 U}{\partial z^3} \frac{z^2 dz}{2}$$

$$= \frac{\partial U}{\partial z} \frac{z^2}{2} - \int \frac{\partial^2 U}{\partial z^2} z dz = \cancel{\frac{\partial U}{\partial z} \frac{z^2}{2} - \int \frac{\partial^2 U}{\partial z^2} z dz}$$



$$U = U' + V + \Phi$$

$$V = \frac{\rho_i - \rho_0}{4\pi\lambda} \iint \frac{\partial^2 v_n}{\partial n^2} \cdot \frac{d\sigma}{2}$$

$$\frac{\partial \Phi}{\partial n} = -\varepsilon \frac{\partial U}{\partial n} + \mu \Delta \frac{\partial v_n}{\partial n}$$

$$\frac{\partial^2 v_n}{\partial n^2} + \frac{\partial^2 v_n}{\partial n^2} + \frac{\partial^2 v_n}{\partial n^2}$$

$$\neq \frac{\rho_i - \rho_0}{4\pi\lambda\mu} \iint \frac{1}{2} \frac{\partial \Phi}{\partial n} d\sigma$$

matricen  
sætnen  $V$  tilføjer ikke noget værdi:  $V = \frac{\rho_i - \rho_0}{4\pi\lambda\mu} \mu$

at den transformerede tykke jern:  $\frac{\partial^2 v_n}{\partial n^2} = \frac{\partial \Phi}{\partial n}$

i. j. jern:  $\frac{\partial U}{\partial n} = 0$

Især: Na for den hvi: jern:  $\frac{\partial U}{\partial n} = 0$

$$\lambda \frac{\partial (U - U')}{\partial n} = 0$$

$$\text{sætnen } \frac{\partial (U - U')}{\partial n} = 0$$

$$\mu \frac{\partial U}{\partial n} = \frac{\partial U'}{\partial n}$$

potentialet i  $\Delta v_n = \frac{\partial^2 v_n}{\partial n^2} \dots$

sætnen:  $\frac{\partial^2 v_n}{\partial n^2} = \frac{1}{\mu} \frac{\partial \Phi}{\partial n} + \varepsilon \frac{\partial U'}{\partial n}$    
 ~~at den transformerede tykke jern~~  $\Delta v_n$ , men at  $s, t$

$$V = \frac{\rho_i - \rho_0}{4\pi\lambda\mu} \iint \frac{1}{2} \frac{\partial \Phi}{\partial n} d\sigma + \underbrace{\frac{\rho_i - \rho_0}{4\pi\lambda} \iint \frac{1}{2} \varepsilon \frac{\partial U'}{\partial n} d\sigma}_{f(2)}$$

matricen matricen.

$$V = \frac{\rho_i - \rho_0}{4\pi\lambda\mu} \mu + f(2)$$

$$\frac{\partial v_n}{\partial n} = c \cos \theta \left[ \frac{3}{2} \frac{a}{r^3} + \frac{3}{2} \frac{a^3}{r^5} \right]$$

$$v_n = -u \frac{a}{r} + v \frac{a}{r} = -u \sin \theta + v \cos \theta$$

$$= -c \cos \theta \left[ 1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right]$$

$$\frac{\partial v_n}{\partial r} = -c \cos \theta \left[ \frac{3}{4} \frac{a}{r^2} + \frac{3}{4} \frac{a^3}{r^4} \right]$$

$$\frac{\partial^2 v_n}{\partial r^2} = +c \sin \theta \left[ \frac{3}{2} \frac{a}{r^3} + 3 \frac{a^3}{r^5} \right]$$



W tanty rozkladze  $U = U' + V + \Phi$

analogicznie  $U'$  to pot. wstępnego polu. (w sobie)

$\Phi$  = zewnętrzny potencjał

$V$  = energia składowa ruchu mechanicznego.

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$$u = -\frac{3}{4} \frac{ca}{r^2} \left(1 - \frac{a^2}{r^2}\right) \cos \theta + c \left(1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3}\right)$$

$$q = -\frac{3}{4} \frac{ca}{r^2} \left(1 - \frac{a^2}{r^2}\right) \sin \theta \cos \theta$$

$$v_r = u \frac{r}{r} + v \frac{a}{r} = u \cos \theta + v \sin \theta$$

$$= -\frac{3}{4} \frac{ca}{r^2} \left(1 - \frac{a^2}{r^2}\right) \cos \theta + c \cos \theta \left(1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3}\right)$$

$$= c \cos \theta \left[1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} - \frac{3}{4} \frac{a}{r} + \frac{3}{4} \frac{a^3}{r^3}\right]$$

$$v_r = c \cos \theta \left[1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3}\right]$$

$$\frac{\partial v_r}{\partial r} = c \cos \theta \left[\frac{3}{2} \frac{a}{r^2} - \frac{3}{2} \frac{a^3}{r^4}\right]$$

$$\frac{\partial v_r}{\partial r} \Big|_{r=a} = 0$$

$$\frac{\partial^2 v_r}{\partial r^2} = c \cos \theta \left[-\frac{3a}{r^3} + \frac{6a^3}{r^5}\right]$$

$$\frac{\partial^2 v_r}{\partial r^2} \Big|_{r=a} = \frac{3ac \cos \theta}{a^2}$$

$$\mu = \mu_0 - \frac{3}{2} \frac{\mu ca}{r^2} \cos \theta$$

$$\frac{\partial \mu}{\partial r} = 3\mu \frac{ca}{r^3} \cos \theta$$

$$\frac{\partial \mu}{\partial r} \Big|_{r=a} = 3\mu \frac{c}{a^2} \cos \theta$$

$$\Delta^2 \mu = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial \mu}{\partial r} \right) = \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial \mu}{\partial r} \right)$$

$$= \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial \mu}{\partial r} \right) = \frac{3}{2} \frac{ca}{r^3} \sin \theta$$

$$\therefore \frac{\partial \mu}{\partial r} = \mu \frac{\partial^2 v_r}{\partial r^2}$$

Równanie mechanizmu

Doński mech : ionowy  
molekularny

W stanie spoczynku :

~~$\frac{\partial f}{\partial x} = \dots$~~   $u = v = w = 0$   
 $U = U' + \Phi$  ← jeżeli to się zgodzi z warunkiem  $u = v = w = 0$  !]

$$\varepsilon = \varepsilon'$$

$$\frac{\partial f}{\partial x} = \varepsilon' \frac{\partial U'}{\partial x} = \varepsilon \frac{\partial U}{\partial x}$$

$$\left. \begin{aligned} \frac{\partial f}{\partial x} &= -\varepsilon \frac{\partial U}{\partial x} + \mu \Delta^2 u \\ \frac{\partial f}{\partial y} &= -\varepsilon \frac{\partial U}{\partial y} + \mu \Delta^2 v \\ \frac{\partial f}{\partial z} &= -\varepsilon \frac{\partial U}{\partial z} + \mu \Delta^2 w \end{aligned} \right\}$$

$$\Delta^2 f = -\left[ \varepsilon \frac{\partial}{\partial x} \frac{\partial U}{\partial x} + \varepsilon \frac{\partial}{\partial y} \frac{\partial U}{\partial y} + \varepsilon \frac{\partial}{\partial z} \frac{\partial U}{\partial z} \right] - \varepsilon \Delta^2 U$$

$$\begin{aligned} \int \Delta^2 f \cdot d\omega &= - \int \dots - \int \varepsilon \Delta^2 U \cdot d\omega \\ &= - \int \varepsilon \frac{\partial U}{\partial n} \cdot d\omega + \int \varepsilon \Delta^2 U \cdot d\omega = - \int \varepsilon \frac{\partial U}{\partial n} \cdot d\omega \\ &= - \int \varepsilon \frac{\partial U'}{\partial n} \cdot d\omega \end{aligned}$$

Rozłogi :  $f = f_1 + f_2$

~~$$\begin{aligned} \frac{\partial f_1}{\partial x} &= -\varepsilon \frac{\partial U'}{\partial x} + \mu \Delta^2 u \\ \frac{\partial f_1}{\partial y} &= -\varepsilon \frac{\partial U'}{\partial y} + \mu \Delta^2 v \\ \frac{\partial f_1}{\partial z} &= -\varepsilon \frac{\partial U'}{\partial z} + \mu \Delta^2 w \end{aligned}$$

$$\begin{aligned} \frac{\partial f_2}{\partial x} &= -\varepsilon \frac{\partial (U + \Phi)}{\partial x} + \mu \Delta^2 u \\ \frac{\partial f_2}{\partial y} &= -\varepsilon \frac{\partial (U + \Phi)}{\partial y} + \mu \Delta^2 v \\ \frac{\partial f_2}{\partial z} &= -\varepsilon \frac{\partial (U + \Phi)}{\partial z} + \mu \Delta^2 w \end{aligned}$$~~



~~$$\Delta^2 \psi = -\epsilon \Delta^2 u' \left[ \frac{\partial \psi}{\partial x} \frac{\partial u'}{\partial x} + \frac{\partial \psi}{\partial y} \frac{\partial u'}{\partial y} \right]$$~~

~~$$\Delta^2 \psi =$$~~

~~$$\Delta^2 \psi =$$~~

~~$$\epsilon \Delta^2 u + \frac{\partial \epsilon}{\partial x} \frac{\partial u}{\partial x} + \frac{\partial \epsilon}{\partial y} \frac{\partial u}{\partial y} + \frac{\partial \epsilon}{\partial z} \frac{\partial u}{\partial z} = \Delta^2 \psi$$~~

2 drugi stromy presedy miedosmy:

~~$$\epsilon \Delta^2 u + \frac{\partial \epsilon}{\partial x} \cdot u \epsilon + \frac{\partial \epsilon}{\partial y} \cdot v \epsilon + \frac{\partial \epsilon}{\partial z} \cdot w \epsilon = -4\pi \lambda \epsilon' \epsilon$$~~

Czy nie mogemy stawić:

~~$$\frac{\partial \psi}{\partial x} = \frac{1}{\epsilon} u \epsilon$$~~

~~$$\Delta^2 \psi = -4\pi \lambda \epsilon'$$~~

~~$$\Delta^2 u = \frac{1}{\epsilon} \left( \frac{\partial \epsilon}{\partial x} u + \frac{\partial \epsilon}{\partial y} v + \frac{\partial \epsilon}{\partial z} w \right)$$~~

$$\psi = \psi_1 + \psi_2$$

$$u = u' + v + \bar{v}$$

$$\begin{cases} \frac{\partial \psi_1}{\partial x} = -\epsilon \frac{\partial u'}{\partial x} \\ \frac{\partial \psi_1}{\partial y} = - \end{cases}$$

$$\frac{\partial \psi_2}{\partial x} = -\epsilon \frac{\partial (v + \bar{v})}{\partial x} + \epsilon \Delta^2 u$$

$$\frac{\partial \psi_2}{\partial y} =$$

$$\Delta^2 \psi_2 = - \left[ \frac{\partial \epsilon}{\partial x} \frac{\partial (v + \bar{v})}{\partial x} + \dots \right] - \epsilon \Delta^2 (v + \bar{v})$$

~~$$\psi_2 = \int \frac{1}{\epsilon} \frac{\partial \epsilon}{\partial x} u \epsilon$$~~

$$\int_0 \Delta^2 \psi_2 d\sigma = - \int \epsilon \frac{\partial (v + \bar{v})}{\partial n} d\sigma + \int \epsilon \Delta^2 (v + \bar{v}) d\sigma$$

$$= 0$$

$$\frac{\partial (v + \bar{v})}{\partial n} = 0$$

$$\Delta^2 (v + \bar{v}) = u \frac{\partial \epsilon}{\partial x} + v \frac{\partial \epsilon}{\partial y} + w \frac{\partial \epsilon}{\partial z}$$

Jaka jest wartość  $\Delta^2 v_s$  przy założeniu  $\sim$  czy wynosi  $\frac{\partial^2 v_s}{\partial t^2}$ ?

$$\Delta^2 v_s = \left( \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right) v_s$$

$$r = r_0 - \frac{3\mu c a}{2^2} \cos \theta \quad \left| \quad v_r = c \left[ 1 - \frac{3}{2} \frac{a}{r} + \frac{1}{2} \frac{a^3}{r^3} \right] \cos \theta \right.$$


---


$$v_{\theta} = -c \sin \theta \left[ 1 - \frac{3}{4} \frac{a}{r} - \frac{1}{4} \frac{a^3}{r^3} \right]$$

$$\frac{\partial}{\partial r} v_{\theta} = -c \sin \theta \left[ \frac{3}{4} \frac{a}{r^2} + \frac{3}{4} \frac{a^3}{r^4} \right] \quad \left| \quad \frac{v_{\theta}}{r} = -\frac{1}{2} \frac{c \sin \theta}{a} \right.$$

$$\frac{\partial^2}{\partial r^2} v_{\theta} = +c \sin \theta \left[ \frac{3}{2} \frac{a}{r^3} + \frac{3}{2} \frac{a^3}{r^5} \right] = \frac{9}{2} \frac{c \sin \theta}{a^2}$$

$$v = \sqrt{v_r^2 + v_{\theta}^2} = c \sqrt{\left( 1 + \frac{9}{4} \frac{a^2}{r^2} + \frac{1}{4} \frac{a^6}{r^6} - \frac{3}{2} \frac{a}{r} - \frac{3}{4} \frac{a^4}{r^4} + \frac{1}{2} \frac{a^3}{r^3} \right) \cos^2 \theta + \left( 1 + \frac{9}{16} \frac{a^2}{r^2} + \frac{1}{16} \frac{a^6}{r^6} - \frac{3}{4} \frac{a}{r} - \frac{3}{16} \frac{a^4}{r^4} - \frac{1}{4} \frac{a^3}{r^3} \right) \sin^2 \theta}$$

$$= c \sqrt{1}$$

$$\frac{\partial^2 f}{\partial x \partial y} = \left( \frac{\partial}{\partial x} \right) \left( \frac{\partial f}{\partial y} \right) = \frac{\partial}{\partial x} \left( \frac{\partial f}{\partial y} \right) = \frac{\partial^2 f}{\partial y \partial x}$$

$$\mu \Delta^2 f = \dots$$

$$\mu \Delta^2 \text{curl } v = \begin{vmatrix} 1 & \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial x} & \frac{\partial}{\partial y} \end{vmatrix}$$

*Wzrost wartości*



Uprone z one zadani:

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$$\varepsilon \frac{\partial u}{\partial x} = \mu \Delta u$$

$$\varepsilon \frac{\partial u}{\partial y} = \mu \Delta u$$

$$\varepsilon \frac{\partial u}{\partial z} = \mu \Delta u$$

$$u = \int \frac{\varepsilon \frac{\partial u}{\partial x}}{4\pi x} dx + \psi$$

$$= \frac{1}{4\pi} \int \frac{\partial u}{\partial x} dx \int \frac{\varepsilon}{x} dx + \frac{1}{4\pi} \int \frac{\partial u}{\partial x} dx \int \frac{\varepsilon}{x} dx$$

u prostoru usredniny  $u, v, w$  tak jak ciez i delna min'ono



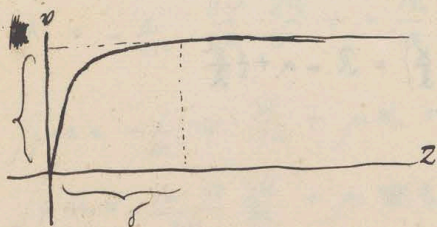
Tonik ~~mat~~ moze si zjednat  
z rovnici  $\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} = 0$   
to moze imunitely vyjde byt: ?  
 $\varepsilon \Delta u + \left( \frac{\partial \varepsilon}{\partial x} \frac{\partial u}{\partial x} + \dots \right) = 0$

$$\varepsilon \frac{\partial u}{\partial x} = \mu \Delta^2 u = \mu \left[ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right]$$

$$\int dx z : \frac{\partial u}{\partial x} = \frac{\partial u}{\partial x} \frac{1}{4\pi} \int \frac{\partial^2 u}{\partial x^2} z dx = \frac{1}{4\pi} \frac{\partial u}{\partial x} \int \frac{\partial^2 u}{\partial x^2} z dx = \mu \left[ \int z \frac{\partial^2 u}{\partial x^2} dz + \int z \frac{\partial^2 u}{\partial y^2} dz + \int z \frac{\partial^2 u}{\partial z^2} dz \right]$$

$$= \frac{1}{4\pi} \frac{\partial u}{\partial x} \left[ \frac{\partial^2 u}{\partial x^2} z - \int \frac{\partial^2 u}{\partial x^2} dz \right] = \frac{1}{4\pi} \frac{\partial u}{\partial x} (\varphi_1 - \varphi_2) =$$

$$\int_0^{\delta} \varphi f dx = f_m \int_0^{\delta} \varphi dx$$



$$\int_0^{\delta} z \frac{\partial^2 u}{\partial x^2} dz = \left[ \frac{1}{2} z^2 \frac{\partial^2 u}{\partial x^2} - \int \frac{1}{2} z^2 \frac{\partial^3 u}{\partial x^3} dz \right]$$

$$= \frac{1}{2} \delta^2 \frac{\partial^2 u}{\partial x^2} - \int_0^{\delta} \frac{1}{2} z^2 \frac{\partial^3 u}{\partial x^3} dz$$

$$= \frac{1}{2} \delta^2 \frac{\partial^2 u}{\partial x^2} - \frac{1}{2} \int_0^{\delta} z^2 \frac{\partial^3 u}{\partial x^3} dz$$

$$= \frac{\partial v}{\partial z} \bigg|_0^{\delta} M(z) = \frac{\partial v}{\partial z} \bigg|_0^{\delta} M(z)$$



czyli 1:  $\frac{\partial U}{\partial x}$  może być wyliczone ze statki i porównanie ze statką

2: wynika z tego, że mamy w dyfuzji  $\delta$  że  $r = f(\rho, t)$

$$u = \frac{1}{4\pi} \frac{\partial U}{\partial x} \int_0^{\infty} d\omega \int \frac{\varepsilon}{x} d\omega + \frac{1}{4\pi} \int_0^{\infty} \frac{1}{r} \frac{\partial U}{\partial x} d\omega \int \varepsilon d\omega + \psi$$

~~zobacz rysunek~~

~~zobacz rysunek~~

$$\frac{\partial \varphi}{\partial x} \int_0^{\infty} \frac{1}{r} \frac{\partial U}{\partial x} d\omega$$

$$\int_0^R \frac{2\pi \rho d\rho}{\sqrt{x^2 + \rho^2}} = \left[ 2\pi \sqrt{x^2 + \rho^2} \right]_0^R = 2\pi \sqrt{x^2 + R^2} - 2\pi x$$

$$2\pi \int_0^x (\sqrt{R^2 + x^2} - x) \frac{dx}{4\pi} \frac{\partial \varphi}{\partial x}$$

$$= \frac{1}{2} \frac{\partial \varphi}{\partial x} \left[ \sqrt{R^2 + x^2} - x \right]_0^x - \frac{1}{2} \int_0^x \frac{\partial \varphi}{\partial x} \left[ \frac{x}{\sqrt{R^2 + x^2}} - 1 \right] dx$$

$$= \frac{1}{2} \left[ \frac{\partial \varphi}{\partial x} (\sqrt{R^2 + x^2} - x) - R \frac{\partial \varphi}{\partial x} \right] - \uparrow$$

$$+ \frac{\partial \varphi}{\partial x}$$

$$\sqrt{R^2 + x^2} - x = R \left[ \left( 1 + \frac{x^2}{R^2} \right)^{\frac{1}{2}} - \frac{x}{R} \right] = R \left( 1 + \frac{1}{2} \frac{x^2}{R^2} - \frac{x}{R} \right) = R - x + \frac{1}{2} \frac{x^2}{R}$$



W koroidze musi waznac:

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$$\frac{\partial \mathcal{U}}{\partial n} = \mu \frac{\partial^2 v_n}{\partial n^2} = \frac{1}{4\pi} \frac{\partial \varphi}{\partial n} \frac{\partial \mathcal{U}}{\partial n} \quad \left\| \quad \mu \frac{\partial v_n}{\partial n} \right|_S = \frac{1}{4\pi} \frac{\partial \varphi}{\partial n} \bigg|_0 \frac{\partial \mathcal{U}}{\partial n}$$

$$\int n \, dn =$$

$$\mu v_n \big|_S = \frac{1}{4\pi} (\varphi_i - \varphi_o) \frac{\partial \mathcal{U}}{\partial n}$$

$$\left( \frac{\partial \varphi}{\partial n} \bigg|_S - \frac{\partial \varphi}{\partial n} \bigg|_0 \right) dn = \varphi_o - \varphi_i = \delta \cdot \frac{\partial \varphi}{\partial n}$$

To wystarczy do oznaczenia pominięci w razie prostowania będzie

$$\Delta^2 \varphi = 0$$

$$\frac{\partial \varphi}{\partial n} \bigg|_S = \begin{cases} \Delta^2 \varphi = 0 \\ \frac{\partial \varphi}{\partial n} \bigg|_S = \frac{\varphi_i - \varphi_o}{4\pi\mu} \frac{\partial \mathcal{U}}{\partial n} \end{cases}$$

$$u = \frac{\partial \varphi}{\partial x}$$

$$v =$$

$$w =$$

Me to waznac tylko jedyne rozpoznanie statice rozpoznanie jednorodnoscia moze to nie widziac jawnie czy stajane składowe odpowiedni.

Byc moze moze tego samego rozpoznanie waznac i w ogolnym przypadku

$$\frac{\partial \varphi}{\partial n} = -\varepsilon \frac{\partial \mathcal{U}}{\partial n} + \mu \Delta^2 v_n$$

$$\Delta^2 v_n = \frac{\partial^2 v_n}{\partial x^2} + \left( \frac{1}{x^2} \right) \frac{\partial v_n}{\partial x}$$

$$\frac{\partial \varphi}{\partial x} = -\frac{1}{4\pi} \frac{\partial \varphi}{\partial x} \frac{\partial \mathcal{U}}{\partial n} + \mu \frac{\partial^2 v_n}{\partial x^2}$$

$$\int dx \quad \mu = -\frac{1}{4\pi} \frac{\partial \varphi}{\partial x} \frac{\partial \mathcal{U}}{\partial n} + \mu \frac{\partial v_n}{\partial x} + \text{const}$$

$$\int dx \quad \int p \, dz = -\frac{1}{4\pi} \varphi \cdot \frac{\partial \mathcal{U}}{\partial n} + \mu v_n + 2 \cdot \text{const} + \text{const}'$$

$$\int_0^S p \, dz = -\frac{\varphi_o - \varphi_i}{4\pi} \frac{\partial \mathcal{U}}{\partial n} + \mu (v_n \big|_S - v_{n0}) + \delta \cdot \text{const}$$

$$= p_m \cdot \delta$$

$$\mu v_n \big|_S = \frac{\varphi_o - \varphi_i}{4\pi} \frac{\partial \mathcal{U}}{\partial n}$$

To nie wystarczy jednak do oznaczenia ruchu to teraz mamy  $p \cdot \Delta^2 u = -\frac{\partial \varphi}{\partial x}$  etc.

$$v_n = \frac{\varphi_o - \varphi_i}{4\pi\mu} \frac{\partial \mathcal{U}}{\partial n}$$



Czy mialoby rozklad

$$u = u_1 + u_2$$

$$v = v_1 + v_2$$

$$w = w_1 + w_2$$

$$\frac{\partial \phi_1}{\partial x} + z \frac{\partial \psi}{\partial x} = \mu \Delta^2 u_1$$

$$\frac{\partial \phi_2}{\partial x} = \mu \Delta^2 u_2$$

$$\frac{\partial \phi_1}{\partial y} + z \frac{\partial \psi}{\partial y} = \mu \Delta^2 v_1$$

$$\frac{\partial \phi_2}{\partial y} = \mu \Delta^2 v_2$$

$$\frac{\partial \phi_1}{\partial z} + z \frac{\partial \psi}{\partial z} = \mu \Delta^2 w_1$$

$$\frac{\partial \phi_2}{\partial z} = \mu \Delta^2 w_2$$

Takie, że  $p_1 = 0$  poza warstwą

du

poza warstwę musiałoby to

istniać

być ruch potencjalny; będzie on równy jeżeli prędkości na powierzchni takiej jakiej

$$\Delta^2 \psi = 0$$

$$u = \frac{\partial \psi}{\partial x}$$

odpowiedzą za dany potencjał.

Co do prędkości normalnych ~~nie da się wyznaczyć~~ mamy

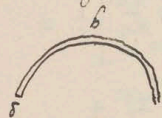
$$v_n = \frac{\partial \psi}{\partial n} = \frac{p_2 - p_1}{4\pi\mu} \frac{\partial \psi}{\partial n}$$

Stąd otrzymujemy  $\frac{\partial \psi}{\partial n} = 0$

to by było  $v_n = 0$

~~nie da się wyznaczyć prędkości normalnych~~ To prawda bo  $v_n$  będzie do zwrócenia w porównaniu z prędkościami stycznymi jeżeli  $\delta$  dotychczas nie ma

$$v_n = v_{n0} + z \left( \frac{\partial v_n}{\partial z} \right)_0 + \frac{z^2}{2} \left( \frac{\partial^2 v_n}{\partial z^2} \right)_0$$

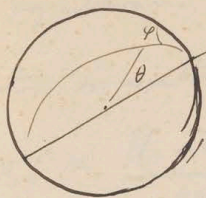


$v_n$  do  $v_s$  będzie w stosunku  $\delta : b$

porównani równani węglów :  $v_n \cdot b = v_s \cdot \delta$

$$v_n : v_s = \delta : b$$





$$\Delta^2(u) = \frac{1}{r} \left[ \frac{\partial^2(ru)}{\partial r^2} + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \left[ \sin \theta \frac{\partial u}{\partial \theta} \right] + \frac{1}{r \sin^2 \theta} \frac{\partial^2 u}{\partial \phi^2} \right] \quad 302$$

$$r = a + z$$

$$\Delta^2(v) = \frac{1}{a} \left[ \frac{\partial^2}{\partial z^2} (a+z)v \right] + \frac{1}{a \sin \theta} \frac{\partial}{\partial \theta} \left[ \sin \theta \frac{\partial v}{\partial \theta} \right] + \frac{1}{a \sin^2 \theta} \frac{\partial^2 v}{\partial \phi^2}$$

$$\left[ \sin \theta \frac{\partial^2 v}{\partial \theta^2} + \cos \theta \frac{\partial v}{\partial \theta} \right]$$

$$\frac{\partial}{\partial z} [(a+z)v]$$

$$= \frac{\partial v}{\partial z} (a+z) + v$$

$$\frac{\partial^2}{\partial z^2} = \frac{\partial^2 v}{\partial z^2} (a+z) + 2 \frac{\partial v}{\partial z}$$

$$\Delta^2(v) = \left(1 + \frac{2}{a}\right) \frac{\partial^2 v}{\partial z^2} + \frac{2}{a} \frac{\partial v}{\partial z} + \frac{1}{a} \frac{\partial^2 v}{\partial \theta^2} + \frac{1}{a} \frac{1}{\sin \theta} \frac{\partial v}{\partial \theta}$$

$$v_{z\theta} = -c \cos \theta \left[ 1 - \frac{2}{3} \frac{a}{z} - \frac{1}{3} \frac{a^2}{z^3} \right]$$

$$\frac{\partial}{\partial \theta} v_{\theta} = \sin \theta \left[ - \frac{1}{3} \frac{a}{z} - \frac{1}{3} \frac{a^2}{z^3} \right]$$

$$\frac{\partial^2}{\partial \theta^2} v_{\theta} = \cos \theta \left[ \frac{1}{3} \frac{a}{z} + \frac{1}{3} \frac{a^2}{z^3} \right]$$

$$\left. \begin{array}{l} 1=9 \\ \end{array} \right\} = 0$$

$$\Delta^2(v)_{\theta} = \frac{\partial^2 v_{\theta}}{\partial z^2} + \frac{2}{a} \frac{\partial v_{\theta}}{\partial z} = \frac{\partial^2 v_{\theta}}{\partial z^2} + \frac{2}{a} \frac{\partial v_{\theta}}{\partial z}$$

$$\text{integrate} \quad \left. \begin{array}{l} \Delta^2 = \frac{2}{3} \frac{c a \cos \theta}{z^3} \\ \frac{\partial^2}{\partial z^2} = -\frac{2}{3} \frac{c \cos \theta}{a} \\ \frac{\partial^2}{\partial z^2} = \frac{2}{3} \frac{c \cos \theta}{a^2} \end{array} \right\} \frac{\partial^2}{\partial z^2} + \frac{2}{3} \frac{2}{a} = \frac{2}{3} \frac{c \cos \theta}{a^2}$$

$$\text{Zatem, przyjmijmy dla } \Delta^2 v_{\theta} = \frac{\partial^2 v_{\theta}}{\partial z^2} + \frac{2}{a} \frac{\partial v_{\theta}}{\partial z}$$

$$\int \Delta^2 v_{\theta} dz = \int \frac{\partial^2}{\partial z^2} v_{\theta} dz + \frac{2}{a} \int \frac{\partial v_{\theta}}{\partial z} dz = v_{\theta} - v_{\theta} + \frac{2}{a} \frac{\partial v_{\theta}}{\partial z} \Big|_0^{\infty}$$

$$\lim_{z \rightarrow \infty} \frac{(v_{\theta} - v_{\theta})}{a} = 0$$



Zatem istotni:

$$\lim_{\delta \rightarrow 0} \int_0^{\delta} \frac{\partial \psi}{\partial s} z ds = -\frac{1}{4\pi} \frac{\partial U}{\partial s} \int_0^{\delta} \frac{\partial^2 \psi}{\partial s^2} z ds + \mu (V_0 - \psi_0)$$

$$V_0 = \frac{\psi_0 - \psi_0}{4\pi\mu} \frac{\partial U}{\partial s}$$

wezime pod zaliczenie:

1.  $\lim_{\delta \rightarrow 0} \frac{\delta}{a} = 0$

2.  $V_0 = 0$

5.  $z = \frac{\partial \psi}{\partial s}$

3.  $\frac{\partial U}{\partial s} = \text{const}$  w okolicy  $\delta$

4.  $\mu$  skończony

użyjłam następująco:

$$U = U' + V + \phi$$

przy pominięciu:  $\frac{\partial}{\partial n}(V + \phi) = 0$

$$\frac{\partial U}{\partial n} = \frac{\partial U'}{\partial n}$$

$$\frac{\partial U'}{\partial s} = 0$$

$$\frac{\partial U}{\partial s} = \frac{\partial (V + \phi)}{\partial s}$$

Zatem w prostokątnym obszarze:

$$V = \frac{\psi_0 - \psi_0}{4\pi\mu} \frac{\partial U}{\partial s}$$

$$\begin{cases} \frac{\partial^2 U}{\partial x^2} = \mu \Delta^2 U \\ \frac{\partial^2 U}{\partial y^2} = \mu \Delta^2 U \\ \frac{\partial^2 U}{\partial z^2} = \mu \Delta^2 U \end{cases}$$

Wskazując o powyższy rachunek:

$$z = \frac{1}{4\pi} \Delta^2 U = \frac{1}{4\pi} \left[ \frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \frac{\partial^2}{\partial z^2} \right]$$

Powyższy wywód daje:

$$\begin{aligned} \frac{\partial^2 U}{\partial s \partial n} &= 0 \quad \left\{ \begin{array}{l} \text{co odpowiada 2 poprzednim} \\ \text{warunkom} \end{array} \right. \quad \frac{\partial U'}{\partial s} = 0 \quad \frac{\partial}{\partial n}(V + \phi) = 0 \\ &= \frac{\partial^2 U'}{\partial s \partial n} + \frac{\partial^2 (V + \phi)}{\partial s \partial n} \end{aligned}$$



a przy założeniu  $\int z dz$  i lin. odpowiadającemu wyrażeniu  
 zatem nasz rezultat będzie ściśle weryfikowany.

$$v_{so} = \frac{U_i - U_o}{4\pi\mu} \frac{\partial U}{\partial s} = \frac{U_i - U_o}{4\pi\mu} \frac{\partial}{\partial s} (V + \Phi)$$

z warstwie  $\delta$  równo  $V, \Phi$  będą jednakowe i porównując  $\varphi_i - \varphi_o$

$$v_{so} = \frac{\varphi_i - \varphi_o}{4\pi\mu} \frac{\partial}{\partial s} (V + \Phi) = \frac{\varphi_i - \varphi_o}{4\pi\mu} \left[ \frac{\varphi_i - \varphi_o}{4\pi\mu} \frac{\partial \Phi}{\partial s} + \frac{\partial \Phi}{\partial s} \right]$$

$$V = \frac{\varphi_i - \varphi_o}{4\pi\mu} p + \text{sta}$$

Zatem zadanie :  $\nabla^2 \Phi = 0$  i właściwy wybór  $\frac{\partial \Phi}{\partial s} = 0$

$$\begin{cases} \frac{\partial^2 u}{\partial x^2} = \mu \nabla^2 u \\ \frac{\partial^2 u}{\partial y^2} = \mu \nabla^2 u \\ \frac{\partial^2 u}{\partial z^2} = \mu \nabla^2 u \end{cases}$$

$$v_{so} = \frac{\varphi_i - \varphi_o}{4\pi\mu} \left[ \frac{\varphi_i - \varphi_o}{4\pi\mu} \frac{\partial \Phi}{\partial s} + \frac{\partial \Phi}{\partial s} \right]$$

$$v_{so} = 0$$

$$\therefore \nabla^2 \Phi = 0$$

zatem  $\frac{\varphi_i - \varphi_o}{4\pi\mu} p + \Phi$  przez  $\Psi$   $\Delta^2 \Psi = 0$

jest warunkiem granicznym  $v_{so} = \frac{\varphi_i - \varphi_o}{4\pi\mu} \frac{\partial \Psi}{\partial s}$

$$\text{dotyczy } v_{no} = 0$$

zatem będzie rozwiązanie możliwe

$$v = \nabla \Psi \cdot \frac{\varphi_i - \varphi_o}{4\pi\mu}$$

$$\text{wynik : } \Phi = \frac{\varphi_i - \varphi_o}{4\pi\mu} \nabla \Psi + \text{sta}$$

$$\begin{aligned} v_{so} &= 0 \\ v_{no} &= 0 \end{aligned}$$

$$\begin{cases} \frac{\partial^2 \Psi}{\partial x^2} = \mu \nabla^2 \Psi \\ \dots \end{cases}$$

$$\Delta^2 \Psi = 0$$

czyli także

Zatem rozjdź do dany konstancie paramechi str. wzgłędnie  
~~potencjału~~ przewodnictwa elektrycznego  $\Psi$  i tarcia wewnętrzne  $v_0$   
 można wyrazić:

$$v = \frac{\Psi_i - \Psi_0}{4\pi\mu} \nabla \Psi + v_0$$

dane doświadczalne będą: ciśnieniu  $p_1, p_2$

potencjał obserwacji elektrometrycznej  $A_1, A_2$

lub potencjałometrycznej  $\phi_1, \phi_2$

przewodność  $\frac{1}{\mu}$  ~~potencjału~~

$$i = \lambda \nabla (U - U') + \epsilon v$$

$$= \lambda \nabla (V + \phi) + \epsilon v$$

$$\begin{aligned} \int i \, d\omega &= \lambda \int_{\partial \Omega} (V + \phi) \, d\omega + \underbrace{\int_{\Omega} \frac{1}{4\pi} \frac{\partial^2 \phi}{\partial z^2} v \, d\omega}_{\tilde{q}} \\ &= \int \frac{d\omega}{4\pi} \int \frac{\partial^2 \phi}{\partial z^2} z \left( \frac{\partial v_0}{\partial z} \right) dz \\ &= \int \frac{d\omega}{4\pi} (\Psi_i - \Psi_0) \left( \frac{\partial \Psi_0}{\partial z} \right) \end{aligned}$$

(A dane np. w dry - potencjał i tarcie w badano dany)



$$\rho w \frac{\partial w}{\partial z} = \rho g - \frac{\partial p}{\partial z} + \frac{\mu}{3} \frac{\partial}{\partial z} \Delta w + \mu \Delta w$$

$$\frac{\partial(\rho w)}{\partial z} = 0$$

$$w \frac{\partial p}{\partial z} + k p \frac{\partial w}{\partial z} = (k-1) \mu \left[ \frac{4}{3} \left( \frac{\partial w}{\partial z} \right)^2 + \left( \frac{\partial w}{\partial y} \right)^2 + \left( \frac{\partial w}{\partial x} \right)^2 \right] + (k-1) \kappa \left( \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} + \frac{\partial^2 \theta}{\partial z^2} \right)$$

$$\frac{\partial w}{\partial x} = \frac{dw}{dr} \frac{x}{r}$$

$$\frac{\partial w}{\partial x^2} = \frac{d^2 w}{dr^2} \frac{x^2}{r^2} + \frac{dw}{dr} \frac{1}{r} - \frac{dw}{dr} \frac{x^2}{r^3}$$

$$\frac{\partial w}{\partial y^2} = \frac{d^2 w}{dr^2} \frac{y^2}{r^2} + \frac{dw}{dr} \frac{1}{r} - \frac{dw}{dr} \frac{y^2}{r^3}$$

$$\Delta w = \frac{d^2 w}{dr^2} + \frac{1}{r} \frac{dw}{dr} = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial w}{\partial r} \right)$$

$$\frac{\partial}{\partial z} (r w) = w + r \frac{\partial w}{\partial z}$$

$$\rho w \frac{\partial w}{\partial z} = \rho g - \frac{\partial p}{\partial z} + \frac{4\mu}{3} \frac{\partial^2 w}{\partial z^2} + \mu \left( \frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} \right)$$

$$\frac{\partial(\rho w)}{\partial z} = 0$$

$$w \frac{\partial p}{\partial z} + k p \frac{\partial w}{\partial z} = (k-1) \mu \left[ \frac{4}{3} \left( \frac{\partial w}{\partial z} \right)^2 + \left( \frac{\partial w}{\partial r} \right)^2 \right] + (k-1) \kappa \left[ \frac{\partial^2 \theta}{\partial z^2} + \frac{\partial^2 \theta}{\partial r^2} + \frac{1}{r} \frac{\partial \theta}{\partial r} \right]$$

Pytanie, czy to może być rozwiązaniem pod założeniami

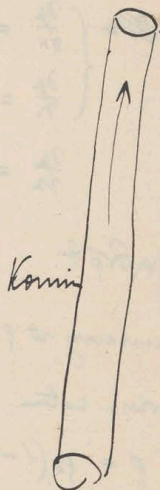
$$\frac{\partial p}{\partial r} = \frac{\partial p}{\partial \theta} = 0 \quad (u=v=0)$$

1). Pomijamy  $\frac{\partial^2 w}{\partial z^2}$  i  $\Delta \Phi$  i  $\frac{\partial^2 \theta}{\partial z^2}$  i  $v \frac{\partial w}{\partial z}$ :

$$\rho w = f_c(r)$$

$$\left( \rho w \frac{\partial w}{\partial z} \right) = \rho g - \frac{dp}{dz} + \mu \left( \frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} \right)$$

$$w \frac{\partial p}{\partial z} + k p \frac{\partial w}{\partial z} = (k-1) \kappa \left[ \frac{\partial^2 \theta}{\partial r^2} + \frac{1}{r} \frac{\partial \theta}{\partial r} \right]$$





W równaniu termicznym:

$$u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} + k \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = (k-1) \Phi + (k-1) \kappa \Delta^2 \theta$$

co pochodzi z ciepła właściwego?

$$c_p \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = c \left[ \frac{\partial}{\partial x} (\rho u \theta) + \frac{\partial}{\partial y} (\rho v \theta) + \dots \right] - c \theta \left[ \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} \right]$$

$$= \frac{c}{R} \left[ \frac{\partial}{\partial x} (p u) + \frac{\partial}{\partial y} (p v) + \frac{\partial}{\partial z} (p w) \right]$$

Wiadomo, że stała gazowa jest:  $\frac{c_p}{R} = \frac{1}{k-1}$

$$\text{zatem: } u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} + k \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right] = (k-1) \kappa \Delta^2 \theta$$

Wiadomo też, że:

$$k \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + k p \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right) = (k-1) \kappa \Delta^2 \theta$$

W tym tutaj przypadek pośredni, między cv i cp.

$$\begin{cases} \frac{\partial p}{\partial x} = \frac{\rho}{3} \frac{\partial}{\partial x} \text{div} + \mu \Delta^2 u \\ \frac{\partial p}{\partial y} = \end{cases} \quad \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0$$

$$\frac{\partial p}{\partial z} = \rho g + \frac{\rho}{3} \frac{\partial}{\partial z} \text{div} + \mu \Delta^2 w$$

~~Ważne~~ Zależy p od czasu to przy wszystkich przypadkach termodynamicznych

zmiany w p będą prawie wyłącznie pochodzący z zmiany w  $\theta$   
można zatem stwierdzić

$$p = p_0 (1 - \alpha \theta)$$



$$\rho \operatorname{div} \mathbf{u} = \alpha \rho_0 \left[ u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right]$$

$$\frac{\partial}{\partial x} \operatorname{div} = \alpha \left[ \frac{\partial u}{\partial x} \frac{\partial \theta}{\partial x} + \dots + u \frac{\partial^2 \theta}{\partial x^2} + \dots \right]$$

Supozujeme tým spôsobom, že to má byť v obli  $\Delta^2 u$  atď.

$$\frac{\partial p}{\partial x} = \mu \Delta^2 u$$

$$\frac{\partial p}{\partial y} = \mu \Delta^2 v$$

$$\frac{\partial p}{\partial z} = \rho g + \mu \Delta^2 w = f_z(x) + \mu \Delta^2 w$$

$$\Delta^2 p = \frac{\partial^2 f_z}{\partial z^2} + \mu \Delta^2 \operatorname{div} \mathbf{u}$$

$$\left[ \begin{array}{l} \text{Zjednotené rovnanie vypadá ako:} \\ \Delta^2 p = \frac{4}{3} \mu \Delta^2 \operatorname{div} + g \frac{\partial \rho}{\partial z} \\ \mu \frac{\partial^2 p}{\partial x^2} + \mu \frac{\partial^2 p}{\partial y^2} + \mu \frac{\partial^2 p}{\partial z^2} + k p \operatorname{div} = (k-1) \kappa \Delta^2 \theta \\ \mu = R \rho \theta \end{array} \right]$$

Divergenčné zadanie poďme:

1.1.

$$u \frac{\partial^2 p}{\partial x^2} + v \frac{\partial^2 p}{\partial y^2} + k p \left( \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} \right) = (k-1) \kappa \left( \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right)$$

$$\frac{\partial^2 p}{\partial x^2} + \frac{\partial^2 p}{\partial y^2} = g \frac{\partial \rho}{\partial y}$$

$$\frac{\partial p}{\partial x} = \mu \Delta^2 u$$

$$\frac{\partial p}{\partial y} = \mu \Delta^2 v + \rho g$$



Oplossing: ay mrie byt rorisatie  $\rho = \text{const}$  pny totale pnydash?

$$\rho = \frac{\mu}{3} \frac{\partial}{\partial x} \text{div} + \mu \Delta^2 u + \rho X$$

$$\rho_0 = R \rho \theta$$

$$\begin{aligned} 0 &= \frac{\mu}{3} \frac{\partial}{\partial y} \text{div} + \mu \Delta^2 v + \rho Y \\ 0 &= \frac{\mu}{3} \frac{\partial}{\partial z} \text{div} + \mu \Delta^2 w + \rho Z \end{aligned}$$

$$k \rho_0 \text{div} = (k-1) \Phi + (k-1) \kappa \Delta^2 \theta$$

$$0 = \frac{\mu}{3} \Delta^2 \text{div} + \frac{\partial}{\partial x} (\rho X + \frac{\partial}{\partial y} (\rho Y + \frac{\partial}{\partial z} (\rho Z)))$$

Van Poisson's  $\Phi$ :  $\text{div} = \frac{k-1}{k \rho_0} \kappa \Delta^2 \theta$

Stp. pny agrikohi:

$$0 = \frac{\mu}{3} \Delta^2 \text{div} + g \frac{\partial \rho}{\partial z}$$

$$\rho = \frac{\rho_0}{2 \theta}$$

$$\frac{\mu}{3} \cdot \frac{k-1}{k \rho_0} \cdot R \cdot \Delta^2 \theta = g \frac{\partial \rho_0}{\partial z} \frac{\partial \theta}{\partial z}$$

$$0 = \frac{\mu}{3} \frac{\partial}{\partial x} \text{div} + \mu \Delta^2 u$$

$$\frac{\partial \rho}{\partial z} g = - \frac{\mu}{3} \Delta^2 \text{div}$$

$$0 = \frac{\mu}{3} \frac{\partial}{\partial y} \text{div} + \mu \Delta^2 v$$

$$\frac{\partial \rho}{\partial y} g = - \mu \Delta^2 (\frac{\partial u}{\partial y} - \frac{\partial v}{\partial x})$$

$$0 = \frac{\mu}{3} \frac{\partial}{\partial z} \text{div} + \mu \Delta^2 w + \rho g$$

$$\frac{\partial \rho}{\partial x} g = - \mu \Delta^2 (\frac{\partial u}{\partial x} - \frac{\partial w}{\partial z})$$

$$\rho \text{div} + \mu \frac{\partial \rho}{\partial z} g \quad g \Delta^2 \rho = - \mu \Delta^2 \left[ \Delta^2 w - \frac{\partial}{\partial z} \text{div} + \frac{\mu}{3} \frac{\partial}{\partial z} \text{div} \right]$$

$$= - \mu \Delta^2 \left[ \Delta^2 w + \frac{\mu}{3} \frac{\partial}{\partial z} \text{div} \right]$$

notur div!



any just jahn mit molen v zw co

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~~$$\rho u \frac{\partial u}{\partial x} + \rho v \frac{\partial v}{\partial y} = \frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \mu \frac{\partial^2 u}{\partial y^2} + \mu \frac{\partial^2 u}{\partial z^2}$$~~

$$\rho u \frac{\partial u}{\partial x} + \frac{\partial p}{\partial x} = \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} \right) + \mu \Delta^2 u$$

$$\frac{\partial p}{\partial y} = \frac{\mu}{3} \frac{\partial}{\partial y} \left( \frac{\partial u}{\partial x} \right)$$

$$\frac{\partial p}{\partial z} = \frac{\mu}{3} \frac{\partial}{\partial z} \left( \frac{\partial u}{\partial x} \right)$$

$$\frac{\partial(\rho u)}{\partial x} = 0$$

$$u \frac{\partial p}{\partial x} + k \rho \frac{\partial u}{\partial x} = (k-1) \left[ \frac{\mu}{3} \mu \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 \right] + (k-1) \mu \Delta^2 u$$

any just molinuum  $\mu = \mu_0 + \frac{\mu}{3} \frac{\partial u}{\partial x}$

$$\rho u \frac{\partial u}{\partial x} = \mu \Delta^2 u$$

$$\rho u \frac{\partial u}{\partial x} = \mu \Delta^2 \frac{\partial u}{\partial x}$$

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$$u \frac{\partial p}{\partial x} + v \frac{\partial p}{\partial y} + w \frac{\partial p}{\partial z} = \frac{\mu}{3} \left[ \mu \frac{\partial}{\partial x} \left( \frac{\partial u}{\partial x} \right) + \dots \right] + \mu \left[ u \Delta^2 u + v \Delta^2 v + w \Delta^2 w \right]$$

$$= \frac{\partial}{\partial x} \left( u \frac{\partial u}{\partial x} \right) - \left( \frac{\partial u}{\partial x} \right)^2 + \frac{\partial}{\partial y} \left( u \frac{\partial u}{\partial y} \right) - \left( \frac{\partial u}{\partial y} \right)^2 + \dots$$

$$+ \frac{\partial}{\partial z} \left( u \frac{\partial u}{\partial z} \right) - \left( \frac{\partial u}{\partial z} \right)^2 + \dots$$

$$= \frac{\mu}{3} \frac{\partial}{\partial x} \left( \frac{u^2 + v^2 + w^2}{2} \right) - \left[ \left( \frac{\partial u}{\partial x} \right)^2 + \left( \frac{\partial u}{\partial y} \right)^2 + \left( \frac{\partial u}{\partial z} \right)^2 + \dots \right]$$


---

$$\left. \begin{aligned} \frac{\partial p}{\partial x} &= \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \\ \frac{\partial p}{\partial y} &= \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) \end{aligned} \right\} \quad \frac{\partial p}{\partial x} + \frac{\partial p}{\partial y} = 0$$

also  $\frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} = 0$



$$\left. \begin{aligned} \frac{\partial \lambda}{\partial x} &= \frac{\mu}{3} \frac{\partial}{\partial x} \operatorname{div} + \mu \Delta u \\ \text{II. } \frac{\partial \lambda}{\partial y} &= \dots \\ \frac{\partial \lambda}{\partial z} &= \rho g + \frac{\mu}{3} \end{aligned} \right\} \Delta \lambda = \frac{4\mu}{3} \Delta u \operatorname{div} + g \frac{\partial \rho}{\partial z}$$

$$\text{IV. } \frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} + \frac{\partial(\rho w)}{\partial z} = 0 \quad \rho = R \rho \theta \quad \rho = \frac{\lambda}{R \theta}$$

$$\text{III. } u \frac{\partial \lambda}{\partial x} + v \frac{\partial \lambda}{\partial y} + w \frac{\partial \lambda}{\partial z} + k \rho \operatorname{div} = (k-1) \Phi + (k-1) \kappa \Delta \theta$$

$$\frac{\partial}{\partial x} \left( \frac{\lambda u}{\theta} \right) + \dots = 0$$

$$\frac{\lambda}{\theta} \operatorname{div} + \frac{1}{\theta} \left( u \frac{\partial \lambda}{\partial x} + \dots \right) - \frac{\lambda}{\theta^2} \left( u \frac{\partial \theta}{\partial x} + \dots \right) = 0$$

$$\rho \operatorname{div} + \left( u \frac{\partial \rho}{\partial x} + \dots \right) = \frac{\rho}{\theta} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$$

$$\text{III. a. } \rho \operatorname{div} = \frac{-1}{k-1} \frac{\lambda}{\theta} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + \kappa \Delta \theta$$

$$\text{b. } u \frac{\partial \lambda}{\partial x} + v \frac{\partial \lambda}{\partial y} + w \frac{\partial \lambda}{\partial z} = \frac{-k}{k-1} \frac{\lambda}{\theta} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) + \kappa \Delta \theta$$

W koordynatach :  $\frac{1}{\rho} \frac{\partial \lambda}{\partial x}$  będzie miało postać  $\frac{1}{\theta} \frac{\partial \theta}{\partial x}$   
i ten ułamek oraz analogicznie  $\frac{1}{\rho} \frac{\partial \lambda}{\partial y}$ ,  $\frac{1}{\rho} \frac{\partial \lambda}{\partial z}$  z wielkimi przeliczeniami:

$$\rho \operatorname{div} = \frac{\lambda}{\theta} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$$

$$\text{IV. } \operatorname{div} = \frac{1}{\theta} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$$

$$u \frac{\partial \theta}{\partial x} - \theta \frac{\partial u}{\partial x} + v \frac{\partial \theta}{\partial y} - \theta \frac{\partial v}{\partial y} + w \frac{\partial \theta}{\partial z} - \theta \frac{\partial w}{\partial z} = 0$$

$$\frac{\partial}{\partial x} \left( \frac{u}{\theta} \right) + \frac{\partial}{\partial y} \left( \frac{v}{\theta} \right) + \frac{\partial}{\partial z} \left( \frac{w}{\theta} \right) = 0$$



$$\text{III b): } \frac{k}{k-1} \frac{1}{\theta} \left[ u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right] = k \Delta \theta = \frac{k}{k-1} \rho \operatorname{div}$$

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$$\text{I). } \Delta p = \frac{4\mu}{3} \Delta^2 \operatorname{div} + \underbrace{\frac{g\mu}{R\theta} \frac{\partial \theta}{\partial z} - \frac{g\mu}{R\theta^2} \frac{\partial \theta}{\partial z}}_{\text{mole perovani do } \uparrow} \neq \frac{4\mu}{3} \Delta^2 \operatorname{div} - \frac{g\mu}{R\theta^2} \frac{\partial \theta}{\partial z}$$

$$\mu = \frac{4\mu}{3} \operatorname{div} \mu - \operatorname{pot} \frac{g\mu}{R\theta} \frac{\partial \theta}{\partial z} + A$$

$$\nabla A = 0$$

$$\mu \frac{\partial}{\partial x} \operatorname{div} - \frac{g\mu}{R\theta} \frac{\partial \theta}{\partial z} + \frac{g\mu}{R\theta^2} \frac{\partial \theta}{\partial z} = \mu \Delta \mu$$

$$\text{I). } \frac{\partial \mu}{\partial x} = \frac{4\mu}{3} \frac{\partial}{\partial x} \operatorname{div} + \mu \Delta u$$

$$\frac{\partial \mu}{\partial y} = \frac{4\mu}{3} \frac{\partial}{\partial y} \operatorname{div} + \mu \Delta v$$

$$\frac{\partial \mu}{\partial z} = \frac{4\mu}{3} \frac{\partial}{\partial z} \operatorname{div} + \mu \Delta w - \frac{g\mu}{R\theta} \frac{\partial \theta}{\partial z}$$

$$\frac{b}{m} = \frac{2\mu}{m} = \frac{b_m}{R\theta} \quad b_m = \frac{p_m}{m}$$

$$\mu \Delta \xi = - \frac{g\mu}{R\theta} \frac{\partial \theta}{\partial x}$$

$$\mu \Delta \eta = - \frac{g\mu}{R\theta} \frac{\partial \theta}{\partial y}$$

$$\Delta \zeta = 0$$

Graniczny przypadek

$$1) \dots k = \infty$$

$$\text{II). } \Delta \theta = 0$$

$$\theta = f(x, y, z)$$

$$\left\{ \begin{array}{l} \text{II} \\ \text{I} \end{array} \right.$$

Rozwiązanie:

$$\frac{\partial \mu}{\partial x} = \mu \Delta u$$

$$\frac{\partial \mu}{\partial z} = \mu \Delta w - \frac{g\mu}{R\theta} \frac{\partial \theta}{\partial z}$$

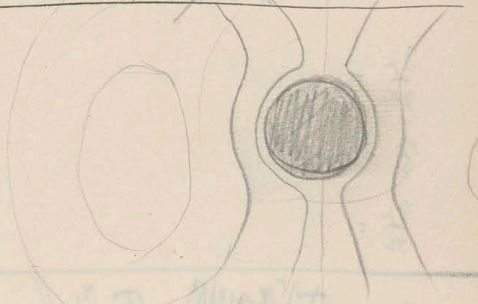
$$\operatorname{div} = \frac{1}{\theta} \left( \mu \frac{\partial \theta}{\partial z} + \dots \right)$$

$$\frac{\partial \mu}{\partial x} = \dots$$

$$\frac{\partial \mu}{\partial y} = \dots$$

$$\frac{\partial \mu}{\partial z} = \dots$$

$$\dots = \dots$$



$$\operatorname{div} = 0$$

$$\mu = A - \operatorname{pot} \left( \frac{g\mu}{R\theta} \frac{\partial \theta}{\partial z} \right) \quad \Delta \mu = 0$$



Laplace's:

I. Incompressible:  $\text{div} = 0$

$$\Delta \theta = 0$$

$$\frac{\partial \psi}{\partial x} = \mu \Delta u$$

$$\frac{\partial \psi}{\partial y} = \mu \Delta v$$

$$\frac{\partial \psi}{\partial z} = \mu \Delta w - \frac{\partial \psi}{\partial t}$$

$$\Delta \psi = - \frac{\partial \psi}{\partial t} - \frac{\partial \psi}{\partial z}$$

$$u, v, w = 0$$

II. Incompressible:

$$\text{div} = \frac{1}{\theta} \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$$

$$\kappa \Delta \theta = \frac{\kappa}{\kappa - 1} \mu \text{div}$$

$$\frac{\partial \psi}{\partial x} = \dots$$

$$\frac{\partial \psi}{\partial y} = \dots$$

$$\frac{\partial \psi}{\partial z} = \dots$$

$$\Delta (x^2 + y^2 + z^2) = 6$$

$$\Delta (x^2) = 6$$

$$\frac{\partial^2}{\partial x^2} = \frac{\partial^2}{\partial x^2}$$

$$\theta_0 = \dots T \frac{n_1}{n}$$

$$\alpha = -\beta T n_1$$

$$\Delta \psi_1 = -\beta T n_1 \frac{z}{n^3}$$

$$\mu_1 = \frac{\alpha z}{2n}$$

$$\mu_1 = \alpha z \left[ A + \frac{1}{2n} + \frac{B}{n^3} \right] + \frac{C}{n}$$



$$\begin{aligned} \Delta^2 u_1 &= -\alpha x \left[ \frac{1}{2r^3} + \frac{3B}{r^5} \right] - \frac{C_x}{r^3} \\ \Delta^2 v_1 &= -\alpha y \left[ \quad \right] - \frac{C_y}{r^3} \\ \Delta^2 w_1 &= +\alpha \left[ A + \frac{1}{2r} + \frac{B}{r^3} \right] - \frac{C_z}{r^3} - \alpha x^2 \left[ \frac{1}{2r^3} + \frac{3B}{r^5} \right] - \alpha \left[ \frac{1}{r} \right] \\ &= \alpha \left[ A + \frac{1}{2r} + \frac{B}{r^3} \right] - \frac{C_z}{r^3} - \alpha x^2 \left[ \frac{1}{2r^3} + \frac{3B}{r^5} \right] \end{aligned}$$

$$u_1 = \alpha x r \left[ \frac{1}{8r} + \frac{B}{2r^3} \right]$$

$$v_1 = \alpha y r \left[ \frac{1}{8r} + \frac{B}{2r^3} \right]$$

$$w_1 = \alpha \left[ \frac{A}{10} (2r^2 - r^2) + \frac{B}{2r^3} + \frac{1}{8} (r^2 - 3r) \right]$$

To hydroly dla  $r \rightarrow \infty$ :

$$\left. \begin{aligned} u_\infty &= \frac{\alpha}{8} r \cos \varphi \\ v_\infty &= \frac{\alpha}{8} r \sin \varphi \end{aligned} \right\} \begin{aligned} A &= 0 \\ \varphi &= \frac{\alpha}{8} r \cos \varphi \end{aligned}$$

$$w_\infty = \frac{\alpha}{8} r (\cos^2 \varphi - 3)$$

In spójnik przybliżenie dla  $r \rightarrow \infty$  w mierzniarce:  $u = v = w \rightarrow \infty$

Podaje to no opóźnienie w III wojnie:  $u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z}$

$$\cancel{u} \left( \frac{\partial \theta}{\partial x} + \frac{\partial \theta}{\partial y} + \frac{\partial \theta}{\partial z} \right) - a \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right) = 0$$

$$\frac{\partial}{\partial x} \left[ \frac{\partial \theta}{\partial x} - a u \theta \right] + \frac{\partial}{\partial y} [ \quad ] + \frac{\partial}{\partial z} [ \quad ] = \underbrace{-a \theta \left[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} \right]}_{= -\Delta \theta}$$

$$\cancel{\frac{\partial}{\partial x} (u \theta) + \frac{\partial}{\partial y} (v \theta) + \frac{\partial}{\partial z} (w \theta)}$$

$$\frac{\partial}{\partial x} \left[ 2 \frac{\partial \theta}{\partial x} - a u \theta \right] + \frac{\partial}{\partial y} \left[ 2 \frac{\partial \theta}{\partial y} - a v \theta \right] + \frac{\partial}{\partial z} \left[ 2 \frac{\partial \theta}{\partial z} - a w \theta \right] = 0$$

Check: o räumliche Kontrolle:  $\Delta \theta = a \left( u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z} \right)$

Stokes:  $\Delta^2 \varphi = 0 = \cancel{u \Delta^2 u} + \cancel{v \Delta^2 v} + 2 \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} \frac{\partial v}{\partial y}$

$$\varphi = \chi \cdot \chi$$

$$\frac{\partial \varphi}{\partial x} = u \frac{\partial v}{\partial x} + v \frac{\partial u}{\partial x}$$

$$\frac{\partial^2 \varphi}{\partial x^2} = u \frac{\partial^2 v}{\partial x^2} + 2 \frac{\partial u}{\partial x} \frac{\partial v}{\partial x} + v \frac{\partial^2 u}{\partial x^2}$$

$$\Delta^2 \varphi = \chi \Delta^2 \chi + \chi \Delta^2 \chi + 2 \left[ \frac{\partial \chi}{\partial x} \frac{\partial \chi}{\partial x} + \frac{\partial \chi}{\partial y} \frac{\partial \chi}{\partial y} + \frac{\partial \chi}{\partial z} \frac{\partial \chi}{\partial z} \right]$$

Ansatzgruppe setzen:

$$\cancel{\chi} \quad \chi = 0$$

$$u = \frac{\partial \varphi}{\partial x}$$

$$v = \frac{\partial \varphi}{\partial y}$$

$$w = \frac{\partial \varphi}{\partial z}$$

$$\Delta^2 \varphi = 0$$

$$u = \frac{\partial}{\partial x} (\log \varphi)$$

$$v = \frac{\partial}{\partial y} (\log \varphi)$$

$$w = \frac{\partial}{\partial z} (\log \varphi)$$

$$\Delta^2 \varphi = \frac{1}{\varphi} \Delta^2 \varphi - \frac{1}{\varphi^2} \left[ \left( \frac{\partial \varphi}{\partial x} \right)^2 + \left( \frac{\partial \varphi}{\partial y} \right)^2 + \left( \frac{\partial \varphi}{\partial z} \right)^2 \right]$$



Jedli' zatem  $u, v, w$  mogą być wyrażone przez taką funkcję  $\varphi$  że  
 $-\frac{a}{2}u = \frac{\partial}{\partial x}(\log \varphi); -\frac{a}{2}v = \frac{\partial}{\partial y}(\log \varphi); -\frac{a}{2}w = \frac{\partial}{\partial z}(\log \varphi) \quad \Delta^2 \varphi = 0$

to stąd  $\theta = \frac{\varphi}{4}$ , gdzie  $\Delta^2 \varphi = 0$

gdziemy mieć rozwiązanie równania:  $\Delta^2 \theta - a(u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + w \frac{\partial \theta}{\partial z}) = 0$

Zatem przypuszczamy  $\Delta^2 \theta = 0$

$$\text{div} = \frac{1}{\theta} \left[ u \frac{\partial \theta}{\partial x} + \dots \right]$$

Przy założeniu  $u=v=w=0 \quad \text{div} = 0 \quad \Delta^2 \theta = 0 \quad \frac{\partial \theta}{\partial x} = 0 \quad \frac{\partial \theta}{\partial y} = 0$

$$\theta = \theta_0 + n \left( \frac{\partial \theta}{\partial n} \right)_0 + \frac{n^2}{2} \left( \frac{\partial^2 \theta}{\partial n^2} \right)_0 + \frac{x^2}{2} \frac{\partial^2 \theta}{\partial x^2} + \frac{y^2}{2} \frac{\partial^2 \theta}{\partial y^2} + \dots$$

$$\Delta^2 \theta = a \nabla \cdot (\nabla \theta)$$

Specyficzny przykład:  $v=w=0 \quad u=u=0$

$$\text{div} = \frac{1}{\theta} \left[ v \frac{\partial \theta}{\partial y} \right] = \frac{\partial v}{\partial y} = \frac{1}{a} \Delta^2 \theta$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial v}{\partial y}$$

$$\frac{\partial \theta}{\partial x} = \frac{\partial v}{\partial y}$$

$$p = p_0$$

$$\frac{1}{\theta} \frac{\partial \theta}{\partial y} = \frac{1}{v} \frac{\partial v}{\partial y}$$

$$\frac{\partial \theta}{\partial x} = \frac{1}{3} \frac{\partial v}{\partial x} \text{ div} = \frac{1}{3} \frac{\partial v}{\partial x} \Delta^2 \theta$$

$$\frac{\partial \theta}{\partial z} = \frac{1}{3} \frac{\partial v}{\partial z} \Delta^2 \theta$$

$$\frac{\partial \theta}{\partial y} = \frac{1}{3} \frac{\partial v}{\partial y} \Delta^2 \theta + \mu \nabla^2 v + g p$$

$$\Delta^2 \theta = \frac{4\mu}{3} \Delta^2 \frac{\partial v}{\partial y} + g \frac{\rho_0}{\theta_0} \frac{\partial \theta}{\partial y}$$

Przybliżenie jedli  $\frac{\partial \theta}{\partial y} = \frac{\partial v}{\partial y} = 0$

$$p = p_0(y)$$

$$\frac{\partial \theta}{\partial x} = 0$$

$$\frac{\partial \theta}{\partial z} = \frac{\theta_1 - \theta_2}{s}$$

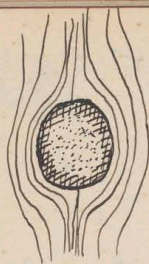
$$\frac{\partial \theta}{\partial y} \frac{d\theta}{dy} = \mu \frac{\partial^2 v}{\partial x^2} + g \rho_0 \left[ 1 + \frac{\theta}{\theta_0} \right]$$

$$\frac{\partial v}{\partial x} = \frac{\partial^2 v}{\partial x^2} = \rho_0 g \frac{\theta_1 - \theta_2}{s}$$

$$\frac{d\theta}{dy} = \mu \left( \rho_0 g \frac{\theta_1 - \theta_2}{s} + 2g \right) + g \rho_0 \left[ 1 + \dots \right]$$

$$v = \left[ \rho_0 g \frac{\theta_1 - \theta_2}{s} \frac{x^3}{6} + ax^2 + bx + c \right]$$





Pręgiem i ruch "lamellarny"

rośnie sponowat i tyłko warstwy i kupa i ruchy stymulacji  
i ruch zmiany w czasie temperatury

$$\Delta^2 \theta = \alpha \nabla^2 (\nabla \cdot \nabla \theta)$$

$\nabla \theta$  przyświeca  $\perp$  s  
i  $\parallel$  s

$$\left. \begin{array}{l} \Delta^2 \theta = 0 \\ \text{dla } z = 0 \end{array} \right\}$$

$$\frac{\partial \theta}{\partial z} = 0$$

$$\frac{\partial \theta}{\partial z} = \mu \frac{\partial^2 \theta}{\partial z^2} + \rho \rho_0 \left[ 1 - \frac{\rho}{\rho_0} \right] \frac{\partial \theta}{\partial z}$$

$$\mu \frac{\partial^2 \theta}{\partial z^2} = \rho \rho_0 \theta$$

$$\mu \frac{\partial^2 \theta}{\partial z^2} = \rho \rho_0 \frac{\partial \theta}{\partial z}$$

$$\text{div} = \alpha \left( \mu \frac{\partial^2 \theta}{\partial z^2} + \dots \right)$$

Zamroznienie ciepłoty wewnątrz p w kierunku poziomym:

$$\frac{\partial \theta}{\partial z} + \rho g = \frac{\theta}{\theta_0} \rho_0 g$$

$$0 = \mu \frac{\partial^2 \theta}{\partial z^2} + \mu \frac{\partial \theta}{\partial z}$$

$$0 = \mu \frac{\partial^2 \theta}{\partial z^2} + \mu \frac{\partial \theta}{\partial z}$$

$$0 = \mu \frac{\partial^2 \theta}{\partial z^2} + \mu \frac{\partial \theta}{\partial z} + \frac{\theta}{\theta_0} \rho_0 g$$

$$\frac{\partial \theta}{\partial z} = \kappa \left( \frac{\partial^2 \theta}{\partial x^2} \right)$$

$$0 = g \frac{\partial \theta}{\partial z} + \frac{\eta}{\rho} \frac{\partial^2 \theta}{\partial x^2}$$

$$\frac{\partial \theta}{\partial z} = \kappa \frac{\partial^2 \theta}{\partial x^2}$$

$$\mu \frac{\partial^2 \theta}{\partial x^2} = \kappa \frac{\partial^2 \theta}{\partial x^2}$$

$$\frac{\partial \theta}{\partial z} = \kappa \frac{\partial^2 \theta}{\partial x^2} = -\kappa \frac{\partial \theta}{\partial x} \frac{\partial \theta}{\partial x} = -\kappa \frac{\partial \theta}{\partial x} \frac{\partial \theta}{\partial x}$$

$$\alpha \left[ \mu \frac{\partial^2 \theta}{\partial z^2} + \mu \frac{\partial \theta}{\partial z} + \frac{\theta}{\theta_0} \rho_0 g \right] = \Delta^2 \theta$$

$$\theta = -\frac{\eta}{\rho} \frac{1}{g} \frac{\partial^2 \theta}{\partial x^2}$$

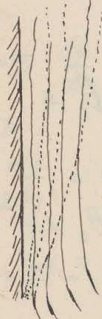
$$\begin{aligned} \frac{\partial \theta}{\partial z} &= \frac{\kappa}{\mu} \frac{\partial^2 \theta}{\partial x^2} \\ \frac{\partial \theta}{\partial z} &= \frac{\kappa}{\mu} \frac{\partial^2 \theta}{\partial x^2} \\ \frac{\partial \theta}{\partial z} &= \frac{\kappa}{\mu} \frac{\partial^2 \theta}{\partial x^2} \\ a &= 20 \text{ K} \end{aligned}$$



$$W = \frac{\kappa}{\theta} \frac{\partial \theta}{\partial x^2}$$

$$\frac{\partial W}{\partial x} = -\frac{\kappa}{\theta^2} \frac{\partial \theta}{\partial x} \frac{\partial \theta}{\partial x^2} + \frac{\kappa}{\theta} \frac{\partial^3 \theta}{\partial x^3}$$

$$\frac{\partial^2 W}{\partial x^2} = + \frac{2\kappa}{\theta^3} \left( \frac{\partial \theta}{\partial x} \right)^2 \frac{\partial \theta}{\partial x^2} - \frac{\kappa}{\theta^2} \left( \frac{\partial^2 \theta}{\partial x^2} \right)^2 - 2 \frac{\kappa}{\theta} \frac{\partial \theta}{\partial x} \frac{\partial^3 \theta}{\partial x^3} + \frac{\kappa}{\theta} \frac{\partial^4 \theta}{\partial x^4} = -\frac{\kappa}{\theta^2} \frac{\partial^4 \theta}{\partial x^4}$$



$$\frac{dW}{dx} = p$$

$$\frac{dW}{dx} = p \frac{dp}{dx}$$

$$\frac{d^3 W}{dx^3} = \frac{d}{dx} \left( \frac{d^2 W}{dx^2} \right)$$

$$\frac{d^3 W}{dx^3} = \left( \frac{dp}{dx} \right)^2 + p^2 \frac{d^2 p}{dx^2}$$

$$\frac{d^4 W}{dx^4} = p \left[ \left( \frac{dp}{dx} \right)^3 + 4p \frac{dp}{dx} \frac{d^2 p}{dx^2} + p^2 \frac{d^3 p}{dx^3} \right]$$

$$W \frac{dp}{dx} = \kappa \left[ p^2 \frac{d^3 p}{dx^3} + 4p \frac{dp}{dx} \frac{d^2 p}{dx^2} + \left( \frac{dp}{dx} \right)^3 \right]$$

$$u = \frac{\partial}{\partial x} (y^4) + u'$$

$$v = +v'$$

$$w = +w'$$

folgende:  $\psi = \frac{c}{2} \frac{a^2 z}{r^3} + cz + b$

$$\frac{\partial \psi}{\partial z} = \frac{c a^2}{2 r^3} + c = \frac{c a^2}{2 r^3} + c = \frac{c a^2}{2 r^3} + c = \frac{c a^2}{2 r^3} + c$$

$$\left. \frac{\partial \psi}{\partial z} \right|_{r=0} = -\frac{1}{2} \sin \varphi$$

$$\Delta \psi = 0$$

$$\varphi = \theta, \varphi$$

$$\left. \frac{\partial \psi}{\partial \omega} \right|_{r=0} = -\frac{1}{2} \cos \varphi \sim \varphi$$

$$\left. \begin{array}{l} r=a \\ r=\infty \end{array} \right\} \varphi = \theta, \left[ b + \frac{3c}{2} a \cos \varphi \right]$$

$$\psi = 0$$

$$2\psi = \psi$$

$$\psi = e^{\psi}$$

$$\left. \begin{array}{l} r=a \\ r=\infty \end{array} \right\} \varphi = \theta_1 e^{b + \frac{3c}{2} a \cos \varphi} = \theta_2 e^{\frac{3c a}{2} \cos \varphi} = \theta_2 e^{\frac{3c}{2} x}$$

Wiederum:  $\Delta \psi + a \left( \frac{\partial \psi}{\partial x} - \right) = 0$

mithin:  $\Delta \psi + a \left( \frac{\partial \psi}{\partial x} - \right) = 0$

$$\varphi = A_0 + A_1 P_1 + A_2 P_2 x^2 + \dots$$

$$+ \frac{B_0}{x} + \frac{B_1 P_1}{x^2} + \frac{B_2 P_2}{x^3} + \dots$$

$$\int_{-1}^{+1} e^{ax} P_n dx$$



I.  $\frac{\partial \theta}{\partial y} = \frac{\partial v}{\partial y} = 0$

$\frac{\partial v}{\partial x} = 0$   
 $\rightarrow \rho = \rho(y)$

$\text{div} = 0$

$v = f(x)$

~~$\rho \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} = 0$~~

$\theta = f(x)$

$\frac{d^2 \theta}{dx^2} = 0$

$\theta = \theta_1 + (\theta_2 - \theta_1) \frac{x}{\delta}$

$\frac{dp}{dy} = \mu \frac{dv}{dx^2} + g \rho_0 \left[ \frac{\theta}{\theta_1} \right] = \mu \frac{dv}{dx^2} + g \rho_0 \frac{\theta_2 - \theta_1}{\theta_1} \frac{x}{\delta} + g \rho_0$

$\frac{d^2 v}{dx^2} = 0$

$\rho = \rho_0 + \frac{\rho_1 - \rho_0}{h} y$

~~$0 = \mu \frac{d^3 v}{dx^3} + g \rho_0 \frac{\theta_2 - \theta_1}{\theta_1} \frac{x}{\delta}$~~

$\frac{dp}{dy} = \frac{\rho_1 - \rho_0}{h} =$

$\left( \frac{\rho_1 - \rho_0}{h} \right) x = \mu \frac{dv}{dx} + g \rho_0 \frac{\theta_2 - \theta_1}{\theta_1} \frac{x^2}{2\delta} + b$

$\frac{\rho_1 - \rho_0}{h} \frac{x^2}{2} = \mu v + \rho_0 g \frac{\theta_2 - \theta_1}{\theta_1} \frac{x^3}{6\delta} + b x + c$

$\left. \begin{matrix} x=0 \\ x=\delta \end{matrix} \right\} v=0$

$c=0$

$\frac{\rho_1 - \rho_0}{h} \frac{\delta^2}{2} = \rho_0 g \frac{\theta_2 - \theta_1}{\theta_1} \frac{\delta^3}{6} + b \delta$

$\left[ g \rho_0 - \frac{\rho_1 - \rho_0}{h} \right] \frac{x^2 - \delta x^2}{2} = \mu v + \rho_0 g \frac{\theta_2 - \theta_1}{\theta_1} \frac{x^3 - x \delta^2}{6}$

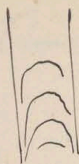
II).  $\mu \neq 0$   $v_0 = \uparrow ax + bx^2 + cx^3$

$\alpha^2 \Delta^2 \theta = (ax + bx^2 + cx^3) \frac{\partial \theta}{\partial y} = x^2 \left( \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) = \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2}$

$\rho = \rho(y)$

$\frac{dp}{dy} = \left( \mu \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) + \rho \rho_0 \frac{\theta}{\theta_1}$





$$\frac{\partial p}{\partial x} = \rho \frac{\partial v}{\partial x} + \rho \theta \neq 0$$

$$\frac{\partial p}{\partial y} = \rho \frac{\partial v}{\partial y} + \rho \Delta^2 v + \rho g \frac{\theta}{\theta_0}$$

$$p = p(y)$$

$$\theta = \theta(x, y)$$

$$\alpha^2 \Delta^2 \theta = u \frac{\partial \theta}{\partial x} + v \frac{\partial \theta}{\partial y} + \theta \operatorname{div}$$

$$u=0$$

$$\frac{dp}{dy} = \mu \frac{\partial^2 v}{\partial x^2} + \rho_0 g \frac{\theta}{\theta_0}$$

$$0 = \mu \frac{\partial^3 v}{\partial x^3} + \rho_0 g \frac{\partial \theta}{\partial x}$$

$$\alpha^2 \left( \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) = v \frac{\partial \theta}{\partial y} = \theta \frac{\partial v}{\partial y}$$

$$\theta = \frac{\mu \theta_0}{g \rho_0} \frac{\partial^2 v}{\partial x^2} + \varphi(y)$$

$$\alpha^2 \left[ \frac{\mu \theta_0}{g \rho_0} \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} \right) + \frac{\partial \varphi}{\partial y} \right] = \frac{\mu \theta_0}{g \rho_0} v \frac{\partial^3 v}{\partial x^2 \partial y} + v \frac{d\varphi}{dy}$$

$$\frac{\partial}{\partial y} \left( \frac{v}{\theta} \right) = 0$$

$$\frac{v}{\theta} = \psi(x)$$

$$v = \theta \cdot \psi(x)$$

$$\alpha^2 \left( \frac{\partial^2 \theta}{\partial x^2} + \frac{\partial^2 \theta}{\partial y^2} \right) = \theta \frac{\partial \theta}{\partial y} \psi(x)$$

$$\theta = \frac{\mu \theta_0}{g \rho_0} \left[ \frac{\partial^2 \theta}{\partial x^2} \psi + 2 \frac{\partial \theta}{\partial x} \frac{d\psi}{dx} + \theta \frac{d^2 \psi}{dx^2} \right] + \varphi(y)$$

Sta wiskony y w kazdej rownie  $\theta = \text{const}$   
 zatem  $\frac{d^2 \psi}{dx^2} = a$

$$\psi = a \frac{x^2}{2} + bx + c$$

$$\text{Wzrostki' rownie } \frac{\partial \theta}{\partial y} = \frac{\partial \theta}{\partial x} = 0$$

$$\varphi(y) = \text{const}$$



$$\theta = \frac{\mu \theta_0}{g \rho_0} \frac{\partial^2 v}{\partial x^2} + \text{const}$$

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$$\theta = \text{const}$$

W linij 'srodkowej':  $\frac{\partial \theta}{\partial x} = 0$   $\frac{dx}{dt} = a$

$$\theta \left[ 1 - \frac{\mu \theta_0}{g \rho_0} a \right] = \frac{\mu \theta_0}{g \rho_0} \left( a \frac{x^2}{2} + b x + c \right) \frac{\partial^2 v}{\partial x^2} + \text{const} \quad \left| \begin{array}{l} a^2 \\ 4 \frac{\mu \theta_0}{g \rho_0} \end{array} \right.$$

$$\theta \frac{\partial^2 v}{\partial x^2} 4 = a^2 \frac{\partial^2 v}{\partial x^2}$$

$$a^2 \theta \left[ 1 - \frac{\mu \theta_0}{g \rho_0} a \right] - \frac{\mu \theta_0}{g \rho_0} \theta \frac{d\theta}{dy} \left( 4 \frac{y^2}{2} \right) = a^2 \cdot \text{const}$$

$$\theta = m + n y$$

$$\theta \frac{d\theta}{dy} + A \theta = B$$

$$\frac{\theta d\theta}{B - A\theta} = dy$$

$$y =$$

0 stacionarni tokovi (dla cng)

Radi klasi je staly:

$$u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{1}{\rho} \frac{\partial p}{\partial x} + \mu \nabla^2 u$$

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} (u^2 + uv + uw) = -\frac{1}{\rho} \frac{\partial (p+P)}{\partial x} + \mu \nabla^2 (u+U)$$

$$\frac{\partial u}{\partial t} = -\frac{1}{\rho} \frac{\partial P}{\partial x} + \mu \nabla^2 u - \left[ u \frac{\partial u}{\partial x} + u \frac{\partial u}{\partial x} + u \frac{\partial u}{\partial y} + u \frac{\partial u}{\partial y} + u \frac{\partial u}{\partial z} + u \frac{\partial u}{\partial z} \right]$$

$$\frac{\partial v}{\partial t} + (v \nabla \cdot v) = \frac{1}{2} \nabla (v^2) + \nabla \cdot (v \text{ curl } v) = \frac{1}{\rho} \nabla P + \mu \nabla^2 v$$

$$\frac{\partial \text{curl } v}{\partial t} + \text{curl } (v \text{ curl } v) = \mu \nabla^2 \text{curl } v$$

$$\frac{\partial \text{curl}(v+v)}{\partial t} + \text{curl}(v+v) \text{ curl}(v+v) = \mu \nabla^2 \text{curl}(v+v)$$

$$\frac{\partial \text{curl } v}{\partial t} + \text{curl} [v \text{ curl } v + v \text{ curl } v] = \mu \nabla^2 \text{curl } v$$

$$\frac{\partial p_{xx}}{\partial x} + \frac{\partial p_{xy}}{\partial y} + \frac{\partial p_{xz}}{\partial z} = -\frac{\partial p}{\partial x} + \lambda \frac{\partial}{\partial x} \text{div} + 2\mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$= \mu \left[ 2 \frac{\partial^2 u}{\partial x^2} + \left( \frac{\partial^2 v}{\partial y \partial x} + \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial^2 u}{\partial z \partial x} + \frac{\partial^2 u}{\partial x \partial z} \right) \right]$$

$$= -\frac{\partial p}{\partial x} + (\lambda + \mu) \frac{\partial}{\partial x} \text{div} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$\lambda = -\frac{2}{3}\mu$$

$$= -\frac{\partial p}{\partial x} + \frac{1}{3} \frac{\partial}{\partial x} \text{div} +$$

$$p = p_0 \theta$$

$$\rho \text{div} + u \frac{\partial \rho}{\partial x} + \dots = 0$$

$$p = p_0 + \alpha \text{div}$$

$$-\mu + (2\mu + \lambda) \frac{\partial^2 u}{\partial x^2}$$

$$2\mu + \lambda = 3\mu \quad \text{OK Reyn}$$

$$\lambda = \mu$$



$$\rho \frac{\partial u}{\partial t} = - \frac{\partial p}{\partial x} + \nu \frac{\partial}{\partial x} \text{div} + \mu \nabla^2 u = - \frac{\partial p}{\partial x} + (k-1) \frac{\partial u}{\partial x} \quad \text{mm}$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial \rho}{\partial t} = 0$$

$$\frac{\partial p}{\partial t} + u \frac{\partial p}{\partial x} + k p \frac{\partial u}{\partial x} = (k-1) \Phi$$

$$\frac{\partial \rho}{\partial t} + \rho \frac{\partial u}{\partial x} = 0$$

$$\rho \frac{\partial u}{\partial t} = - \frac{\partial p}{\partial x} + (k-1) \frac{\partial u}{\partial x}$$

$$\frac{\partial p}{\partial t} + k p \frac{\partial u}{\partial x} = (k-1) \Phi$$

Wahrscheinlich meinst du dynamische Turbulenz?

$$I). \quad \frac{\partial \rho}{\partial t} = - \frac{\partial \rho}{\partial x} \frac{\partial u}{\partial x} - \rho \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial \rho}{\partial x} \frac{\partial u}{\partial t} + \rho \frac{\partial^2 u}{\partial x^2} = - \frac{\partial^2 p}{\partial x^2} + (k-1) \frac{\partial^3 u}{\partial x^3}$$

$$\frac{\partial^2 \rho}{\partial x^2} + \frac{\partial \rho}{\partial x} \frac{\partial u}{\partial x} + \rho \frac{\partial^2 u}{\partial x^2}$$

$$= - \frac{\partial^2 p}{\partial x^2} + (k-1) \frac{\partial^3 u}{\partial x^3}$$

2).

$$\frac{\partial u}{\partial t^2} = \alpha^2 \frac{\partial u}{\partial x^2} + (k-1) \frac{\partial u}{\partial x^3}$$

$$u = \sin(\alpha x + \beta t) e^{-\gamma t}$$

$$\frac{\partial u}{\partial t} = \beta \cos(\alpha x + \beta t) e^{-\gamma t} - \gamma \sin(\alpha x + \beta t) e^{-\gamma t}$$

$$\frac{\partial^2 u}{\partial t^2} = -\beta^2 \sin(\alpha x + \beta t) e^{-\gamma t} - 2\gamma \beta \cos(\alpha x + \beta t) e^{-\gamma t} + \gamma^2 \sin(\alpha x + \beta t) e^{-\gamma t}$$

$$(\beta^2 - \gamma^2) \sin(\alpha x + \beta t) - 2\gamma \beta \cos(\alpha x + \beta t) = \alpha^2 \sin(\alpha x + \beta t) + (k-1) \beta^2 \sin(\alpha x + \beta t) - \alpha^2 \beta \cos(\alpha x + \beta t)$$

$$\frac{k-1}{k} = \left( \frac{\rho}{\rho_0} \right)^{\frac{k-1}{k}}$$

≠

$$\beta^2 - \gamma^2 = -\alpha^2 \alpha^2 + (k-1) \alpha^2 \gamma^2$$

$$-2\gamma \beta = -\alpha^2 \beta (k-1)$$

$$\beta = \frac{\alpha^2}{2} (k-1)$$

$$\beta^2 = \alpha^2 \alpha^2 + \frac{\alpha^4 (k-1)^2}{4}$$

$$\beta = \alpha \alpha \sqrt{1 - \frac{(k-1)^2}{4} + \frac{(k-1)^2}{4 \alpha^2}}$$



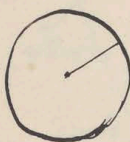
$$II). \rho \frac{\partial \tilde{u}}{\partial t} = - \frac{\partial \tilde{f}}{\partial x \partial t}$$

$$\frac{\partial \tilde{f}}{\partial t} = -k_p \frac{\partial u}{\partial x} + (k-1) \frac{4}{3} \mu \left( \frac{\partial u}{\partial x} \right)^2$$

$$\frac{\partial \tilde{f}}{\partial x \partial t} = -k_p \frac{\partial^2 u}{\partial x^2} - k \frac{\partial u}{\partial x} \frac{\partial u}{\partial x} + \frac{8}{3} (k-1) \frac{\partial u}{\partial x} \frac{\partial^2 u}{\partial x^2}$$

mało w tym celu

Kula porusza się



już równowaga inercji to statystyka

~~prędkości~~ hydrodynamicznej

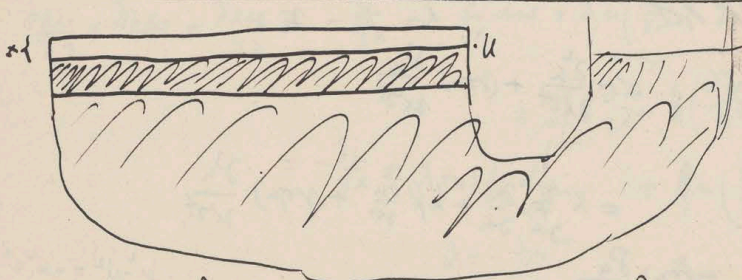
$$\frac{\partial \tilde{f}}{\partial x} = \frac{\partial \tilde{f}}{\partial x} - \frac{\partial \tilde{f}}{\partial x} \quad x = x_0 = a/2$$

$$\frac{dx}{dt} = u = \frac{x_0}{a} \frac{da}{dt} \quad u = x \frac{1}{a} \frac{da}{dt}$$

$$\frac{\partial u}{\partial x} = \frac{1}{a} \frac{da}{dt} = c$$

$$\frac{\partial u}{\partial y} = 0$$

$$\Phi = 0!$$



$$u = U \frac{x}{a}$$

$$\frac{\partial u}{\partial x} = \frac{U}{a}$$

$$p_{\text{eff}} = -p + 2\mu \frac{\partial u}{\partial x} - \frac{2}{3} \mu \left( \frac{\partial u}{\partial x} + \frac{\partial u}{\partial y} + \frac{\partial u}{\partial z} \right) = -p + \frac{4}{3} \mu \frac{\partial u}{\partial x} = -p + \frac{4}{3} \mu \frac{U}{a}$$

$$M \frac{d^2 x}{dt^2} = -2Q x + p_0 + p - \frac{4}{3} \mu \frac{dx}{dt}$$

$$p = p_0 \frac{a}{x}$$



$$M \frac{dx}{dt} = -p_0 - 2\varphi_{sg} \cdot x + \frac{p_0 a}{x} - \frac{4}{3} \frac{1}{x} \frac{dx}{dt}$$

$$\frac{dx}{dt} = 2 \quad \frac{dx}{dt} = \frac{dz}{dt} = \frac{dz}{dx} \cdot 2$$

$$M \cdot 2 \frac{dz}{dx} + \frac{4}{3} \mu \cdot \frac{z}{x} = \frac{p_0 a}{x} + 2\varphi_{sg} \cdot x + p_0 = 0$$

$$\frac{D}{Dt} \left[ \frac{c}{A} \theta + \frac{1}{2} (u^2 + v^2) + u \right] \left\{ \frac{\partial}{\partial x} (u \cdot p_{xx}) + \frac{\partial}{\partial y} (v \cdot p_{yy}) + \frac{\partial}{\partial z} (u \cdot p_{zz}) \right. \\ \left. + \frac{\partial}{\partial y} (u \cdot p_{xy}) + \frac{\partial}{\partial x} (v \cdot p_{yx}) + \dots \right\} dx dy dz$$

$$= -p_{xx} \frac{\partial u}{\partial x} + p_{yy} \frac{\partial v}{\partial y} + \dots + p_{xy} \left( \frac{\partial u}{\partial y} + \frac{\partial v}{\partial x} \right) + \dots \\ + u \frac{\partial p_{xx}}{\partial x} + v \frac{\partial p_{yy}}{\partial y} + u \frac{\partial p_{xy}}{\partial y} + v \frac{\partial p_{yx}}{\partial x} + \dots \\ = u \left( \rho \frac{\partial u}{\partial t} - \rho k \right) + v \left( \rho \frac{\partial v}{\partial t} - \rho k \right) + \dots - \rho \operatorname{div} + \Phi$$

$$\frac{D(u)}{Dt} = u \frac{D}{Dt}$$

$$2u \frac{\partial u}{\partial t} + 2u \frac{\partial u}{\partial x} + 2v u \frac{\partial u}{\partial y} + 2u u \frac{\partial u}{\partial z} \\ = 2u \left[ \frac{\partial u}{\partial t} + u \frac{\partial}{\partial x} + \dots \right]$$

$$\rho \frac{D\theta}{Dt} = -\rho \operatorname{div} + \Phi$$



$$\rho u = \frac{\partial \rho}{\partial x} \quad \rho v = \frac{\partial \rho}{\partial y} \quad \rho \omega = \frac{\partial \rho}{\partial z}$$

$$u = f(x, t)$$

$$v = 0$$

$$\text{div} = \frac{\partial u}{\partial x}$$

$$v = \varphi(x, t)$$

$$\rho \left[ \frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} \right] = - \frac{\partial p}{\partial x} + \frac{\mu}{3} \frac{\partial^2 u}{\partial x^2}$$

$$\rho \left[ \frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} \right] = \mu \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial p}{\partial x} + u \frac{\partial p}{\partial x} + (k \mu) \rho \frac{\partial u}{\partial x} = \Phi$$

$$= \frac{\mu}{3} \left( \frac{\partial u}{\partial x} \right)^2 + \mu \left( \frac{\partial v}{\partial x} \right)^2 + k \Delta \theta$$

$$\frac{\partial v}{\partial t} = \frac{\mu}{\rho_0} \frac{\partial^2 v}{\partial x^2}$$

$$\frac{\partial p}{\partial t} + (k \mu) \rho_0 \frac{\partial u}{\partial x} = \mu \left( \frac{\partial v}{\partial x} \right)^2 \quad \left\{ \begin{array}{l} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial t} \end{array} \right\} \left\{ \begin{array}{l} \frac{\partial u}{\partial t} - k \rho_0 \frac{\partial^2 u}{\partial x^2} = \mu \frac{\partial}{\partial x} \left( \frac{\partial v}{\partial x} \right)^2 + \mu \frac{\partial^3 \theta}{\partial x^3} \\ \frac{\partial u}{\partial t} = - \frac{1}{\rho_0} \frac{\partial p}{\partial x} \end{array} \right.$$

$$\frac{\partial^2 u}{\partial t^2} = a^2 \frac{\partial^2 u}{\partial x^2} + \frac{\mu}{\rho_0} \frac{\partial}{\partial x} \left( \frac{\partial v}{\partial x} \right)^2 + k \frac{\partial^3 \theta}{\partial x^3}$$

$$v = A e^{-\alpha x} \cos(\beta x + \gamma t)$$

$$\frac{\partial v}{\partial x} = A e^{-\alpha x} [-\alpha \cos + \beta \sin]$$

$$\left( \frac{\partial v}{\partial x} \right)^2 = A^2 e^{-2\alpha x} [\alpha^2 \cos^2 + \beta^2 \sin^2 - 2\alpha\beta \cos \sin]$$

$$v = A e^{-x \sqrt{\frac{\rho_0}{2\mu}}} \cos(2\alpha n t - x \sqrt{\frac{\rho_0}{2\mu}})$$

$$\left( \frac{\partial v}{\partial x} \right)^2 = A^2 e^{-2\alpha x} \cdot \underbrace{[1 - 2 \cos \sin]}_{[1 - \sin 2(\gamma t - \rho x)]}$$

$$x = \frac{\sqrt{\frac{\rho_0}{2\mu}}}{\gamma}$$

$$2\alpha n \sqrt{\frac{\rho_0}{2\mu}}$$

$$\begin{aligned} \gamma &= 2\alpha n \\ -\sin &= \left( \frac{\mu}{\rho_0} \right) [\alpha^2 \cos^2 - \beta^2 \sin^2 - 2\alpha\beta \cos \sin] \\ \alpha &= \beta \\ 1 &= 2 \sqrt{\frac{\mu}{\rho_0}} \alpha^2 \\ \alpha &= \sqrt{\frac{\rho_0}{2\mu}} \end{aligned}$$

$$u = \frac{\mu}{\rho_0} \frac{\partial^2 u}{\partial x^2}$$



$$\rho \frac{\partial v}{\partial t} + \rho \frac{\partial v}{\partial x} = \mu \frac{\partial v}{\partial x^2}$$

$$\frac{\partial v}{\partial t} = \left( \mu \left( \frac{\partial v}{\partial x} \right)^2 + \mu \frac{\partial v}{\partial x^2} \right)$$

$$\frac{\partial \rho}{\partial t} + \rho \frac{\partial v}{\partial x} = 0$$

$$\rho = \omega \mu t = \frac{\mu}{\lambda \theta}$$

$$\frac{\partial \rho}{\partial t} + \rho \frac{\partial v}{\partial x} = 0$$

$$\rho \frac{\partial v}{\partial t} = \mu \left( \frac{\partial v}{\partial x} \right)^2 + \mu \frac{\partial v}{\partial x^2}$$

$$\rho \frac{\partial v}{\partial t} = \mu \frac{\partial v}{\partial x^2}$$

$$\frac{\partial v}{\partial t} + \mu \frac{\partial v}{\partial x} + k \mu \frac{\partial v}{\partial x} = \left[ \frac{\mu}{3} \left( \frac{\partial v}{\partial x} \right)^2 + \mu \frac{\partial v}{\partial x^2} \right] (k-1)$$

$$u = f(t) x = x f$$

$$\mu x x = \mu \frac{4}{3} \mu \frac{\partial u}{\partial x} = a$$

$$f = a + \frac{4}{3} \mu \frac{\partial u}{\partial x} \mu$$

$$\frac{4}{3} \mu \frac{\partial f}{\partial t} + k f \left[ a + \frac{4}{3} \mu f \right] = \frac{4}{3} \mu f^2 (k-1)$$

$$\frac{4}{3} \mu \frac{\partial f}{\partial t} + a k f + \frac{4}{3} \mu f^2 = 0$$

$$\frac{\partial f}{\partial t} + \frac{3 a k}{4 \mu} f + 1 = 0$$

$$-\frac{\partial}{\partial t} \left( \frac{1}{f} \right) + \frac{3 a k}{4 \mu} \left( \frac{1}{f} \right) + 1 = 0$$

$$-A \alpha e^{\alpha t} + \frac{3 a k}{4 \mu} [A e^{\alpha t} + B] + 1 = 0$$

$$\frac{1}{f} = A e^{\alpha t} + B$$

$$\alpha = + \frac{3 a k}{4 \mu}$$

$$B = - \frac{4 \mu}{3 a k}$$

$$u = \frac{x}{A e^{\frac{3 a k}{4 \mu} t} - \frac{4 \mu}{3 a k}}$$

$$\frac{1}{A - \frac{4 \mu}{3 a k}} = \frac{1}{(a - \mu) \frac{3}{4 \mu}}$$

$$A = \frac{4 \mu}{3 a k} + \frac{4 \mu}{3 (a - \mu)}$$



$$\rho(u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z}) = - \frac{\partial p}{\partial x}$$

$$\rho(u \frac{\partial v}{\partial x} + \dots) = - \frac{\partial p}{\partial y}$$

$$\rho(u \frac{\partial w}{\partial x} + \dots) = - \frac{\partial p}{\partial z}$$

$$\frac{\partial \rho u}{\partial x} + \dots = 0$$

$$\rho_0 = (\frac{p_0}{k})^{\frac{1}{\gamma}}$$

$$\frac{1}{\rho} \frac{\partial \rho}{\partial x} = \frac{1}{k} \frac{1}{\rho} \frac{\partial p}{\partial x}$$

$$k_1 = k_0$$

$$k_2 = \sqrt{a - c \ell}$$

$$k_1^2 \cdot k_2^2 = c \ell$$

$$k = \sqrt{a - c x} = \sqrt{k_1^2 - \frac{x}{2} (k_1^2 \cdot k_2^2)}$$

$$u = \frac{(y^2 - y^2) c}{4\mu \sqrt{a - cx}}$$

$$\frac{\partial u}{\partial x} = + \frac{(y^2 - y^2) c^2}{8\mu \sqrt{(a - cx)^3}}$$

$$\frac{\partial^2 u}{\partial x^2} = \frac{3(y^2 - y^2) c^3}{16\mu \sqrt{(a - cx)^5}}$$

$$\frac{\partial u}{\partial y} = \frac{(2 - 2y) c}{4\mu \sqrt{a - cx}}$$

$$\frac{\partial^2 u}{\partial y^2} = \frac{-2c}{4\mu \sqrt{a - cx}}$$

$$\frac{\partial^2 u}{\partial x \partial y} = \frac{(2 - 2y) c^2}{8\mu \sqrt{(a - cx)^3}}$$

$$\frac{\partial^2 u}{\partial x^2} \sim \frac{c^2 y^2}{(a - cx)^2} \sim \frac{y^2}{x^2}$$

$$\frac{\partial f}{\partial x} = \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + \frac{1}{3} \frac{\partial^2 u}{\partial x^2}$$

$$\frac{\partial f}{\partial y} = \mu \frac{\partial^2 u}{\partial x \partial y}$$

$$0 = \mu \frac{\partial}{\partial y} \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$\frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} = f(x) = f(y)$$

$$\frac{\partial}{\partial x} (\mu u) = 0$$

$$\mu u = f(y) = \varphi(y)$$

$$\Delta^2 f = \mu \frac{\partial}{\partial x} \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) + \frac{1}{3} \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right)$$

$$= \frac{4\mu}{3} \frac{\partial}{\partial x} \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right) = \frac{4\mu}{3} \frac{\partial f}{\partial x}$$



$$\mu = \frac{4}{3} \frac{\partial u}{\partial x} + \varphi(x, y) \quad \parallel \quad \frac{\partial^2 \varphi}{\partial x^2} + \frac{\partial^2 \varphi}{\partial y^2} = 0$$

$$\frac{\partial \mu}{\partial y} = \frac{4}{3} \frac{\partial^2 u}{\partial x \partial y} + \frac{\partial \varphi}{\partial y}$$

$$\frac{\partial \varphi}{\partial y} = -\mu \frac{\partial^2 u}{\partial x \partial y} = -3 \frac{\partial \mu}{\partial y}$$

$$\varphi(x, y) = \chi(x) - 3\mu$$

$$\mu = \frac{\mu}{3} \frac{\partial u}{\partial x} + \frac{1}{4} \chi(x)$$

$$\Delta u = \frac{2}{3} \frac{d\chi}{dx} \parallel \mu u = \varphi(y)$$

$$\frac{\partial \mu}{\partial x} = \frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \frac{1}{4} \frac{d\chi}{dx} = \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{1}{3} \right) + \frac{1}{4} \frac{d\chi}{dx}$$

$$\Delta \mu = \frac{4}{3} \frac{\partial}{\partial x} \left( \frac{\partial^2 u}{\partial x^2} + \frac{1}{3} \right) = \frac{4}{3} \frac{d^2 \chi}{dx^2} = \frac{1}{12} \frac{d^2 \chi}{dx^2}$$

$$2 = \frac{1}{4} \quad \frac{d^2 \chi}{dx^2} = -\frac{1}{4} - \frac{d\chi}{dx}$$

$$\mu u = \frac{\mu}{3} \frac{\partial u}{\partial x} + \frac{1}{4} \mu \chi(x) = \varphi(y)$$

$$= \frac{\mu}{6} \frac{\partial^2 u}{\partial x^2} + \frac{1}{4} \mu \chi(x)$$

$$2 \frac{dz}{dx} + zX = a$$

$$-\frac{1}{4} \frac{dz}{dx} + \frac{1}{4} X = a$$

$$\frac{\mu}{3} \left( \frac{\partial u}{\partial x} \right)^2 + \frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} + \frac{1}{4} \frac{\partial u}{\partial x} \chi(x) + \frac{\mu}{4} \frac{d\chi}{dx} = 0$$

$$\frac{dy}{dx} + ay^3 - Xy^2 = 0$$

$$\frac{\partial \mu}{\partial x} + \mu \frac{\partial \varphi}{\partial x} = 0$$

$$\frac{\varphi(y)}{\mu} = \frac{\mu}{3} \frac{\partial u}{\partial x} + \frac{1}{4} \chi(x)$$

$$\frac{\mu}{3} \frac{\partial \chi}{\partial y} - \frac{\mu}{4} \chi(x) = \varphi(x)$$

$$\frac{\partial \mu}{\partial x} = 0$$

$$\left( \frac{\mu}{3} \mu \frac{\partial u}{\partial x} + \frac{1}{4} \mu \chi(x) = \varphi(y) \right)$$

$$\frac{1}{4} \frac{d\chi}{dx} = -\frac{\mu}{3} \frac{\partial^2 u}{\partial x^2} - \frac{\varphi(y)}{\mu} \frac{\partial u}{\partial x} = \mu \left[ \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} \right]$$

$$\frac{\partial^2 u}{\partial y^2} = -\frac{4}{3} \frac{\partial^2 u}{\partial x^2} - \frac{\varphi(y)}{\mu \mu} \frac{\partial u}{\partial x} = -\frac{2}{\partial x} \left[ \frac{4}{3} \frac{\partial u}{\partial x} \mu - \frac{\varphi(y)}{\mu \mu} \right]$$



$$\frac{\partial u}{\partial x} = \frac{1}{r} \frac{\partial}{\partial r} \left( r \frac{\partial u}{\partial r} \right) = \frac{du}{dx} \quad \left\| \quad \frac{\partial u}{\partial z} = 0 \right.$$

~~for  $\frac{\partial u}{\partial z} = 0$~~

$$\frac{\partial}{\partial z} \left( r \frac{\partial u}{\partial r} \right) = r \frac{du}{dx}$$

$$r \frac{\partial u}{\partial z} = \frac{r^2}{2} \frac{du}{dx} + \varphi(x)$$

$$\frac{\partial u}{\partial z} = \frac{r}{2} \frac{du}{dx} + \frac{1}{2} \varphi(x)$$

$$u = \frac{r^2}{4} \frac{du}{dx} + \varphi(x) \log(r) + \psi(x)$$

$$u = \frac{r^2 - \delta^2}{4} \frac{du}{dx}$$

$$\frac{r}{R \left\{ \theta_0 - \frac{(\delta^2 - r^2)^2}{128 \mu k} \left[ \frac{r^2 - \delta^2}{l} \right]^2 \frac{1}{r^2} \right\}} \cdot \frac{r^2 - \delta^2}{4} \frac{du}{dx} = f_c(r)$$

$$\frac{(r^2 - \delta^2) r^2 d(r^2)}{8R \left[ r^2 \theta_0 - \frac{(\delta^2 - r^2)^2}{128 \mu k} \left[ \frac{r^2 - \delta^2}{l} \right]^2 \frac{1}{r^2} \right]} = f_c(r) \cdot dx$$

$$\int \frac{z dz}{a z - b} = \frac{1}{a} \int \left\{ dz + \frac{b dz}{a z - b} \right\} = \frac{1}{a} \left[ z + \frac{b}{a} \log(a z - b) \right]$$

$$= \frac{1}{a} \left[ r^2 + \frac{b}{a} \log(a r^2 - b) \right]$$

$$\frac{1}{a} \left[ r^2 + \frac{b}{a} \log(a r^2 - b) \right] = \frac{\partial R}{\partial r^2} f_c(r) \cdot x + \text{const}$$

$$\frac{1}{a} \left[ r^2 + \frac{b}{a} \log(a r^2 - b) \right] = \text{const}$$

$$\frac{1}{a} \left[ r^2 + \frac{b}{a} \log(a r^2 - b) \right] = \frac{\partial R}{\partial r^2} f_c(r) \cdot l + \text{const}$$

$$\frac{\partial R}{\partial r^2} f_c(r) = \frac{1}{a} \left[ r^2 - \delta^2 + \frac{b}{a} \log\left(\frac{a r^2 - b}{a \delta^2 - b}\right) \right] \frac{\partial R}{\partial r^2} l$$





$$\frac{1}{2} \left( \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} \right) = 0$$

$$\frac{\partial \phi}{\partial x} = 0$$

$$\frac{\partial \phi}{\partial y} = 0$$

$$\frac{\partial \phi}{\partial x} = 0$$

$$\frac{\partial \phi}{\partial y} = 0$$

$$\frac{\partial \phi}{\partial x} = 0$$

$$p = \frac{1}{2} \rho v^2$$

$$\theta = \theta_0$$

$$\frac{1}{2} \rho v^2 = \frac{1}{2} \rho v_0^2 + \frac{1}{2} \rho v_1^2 + \frac{1}{2} \rho v_2^2 + \dots$$

$$p = \frac{1}{2} \rho v^2$$

$$\frac{1}{2} \rho v^2 = \frac{1}{2} \rho v_0^2 + \frac{1}{2} \rho v_1^2 + \frac{1}{2} \rho v_2^2 + \dots$$

$$(x, y) = (x_0, y_0)$$

$$\frac{1}{2} \rho v^2 = \frac{1}{2} \rho v_0^2 + \frac{1}{2} \rho v_1^2 + \frac{1}{2} \rho v_2^2 + \dots$$

$$\frac{1}{2} \rho v^2 = \frac{1}{2} \rho v_0^2 + \frac{1}{2} \rho v_1^2 + \frac{1}{2} \rho v_2^2 + \dots$$

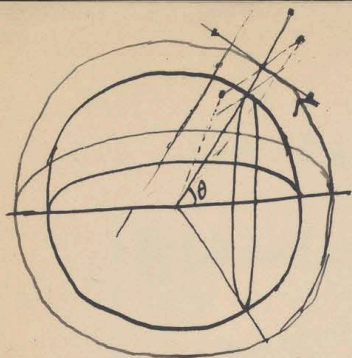
$$\frac{1}{2} \rho v^2 = \frac{1}{2} \rho v_0^2 + \frac{1}{2} \rho v_1^2 + \frac{1}{2} \rho v_2^2 + \dots$$

$$\frac{1}{2} \rho v^2 = \frac{1}{2} \rho v_0^2 + \frac{1}{2} \rho v_1^2 + \frac{1}{2} \rho v_2^2 + \dots$$

$$\frac{1}{2} \rho v^2 = \frac{1}{2} \rho v_0^2 + \frac{1}{2} \rho v_1^2 + \frac{1}{2} \rho v_2^2 + \dots$$

$$\frac{1}{2} \rho v^2 = \frac{1}{2} \rho v_0^2 + \frac{1}{2} \rho v_1^2 + \frac{1}{2} \rho v_2^2 + \dots$$





$v_n \quad v_s$

$$\cos \theta \cos \theta_1 - \sin \theta \sin \theta_1 = \cos(\theta + \theta_1)$$

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$$v_{\xi} = v_n \cos \alpha + v_s \cos \beta$$

$$v_{\xi} = v_n [\sin \theta_1 \cos \theta + \cos \theta_1 \sin \theta \cos \varphi] + v_s [\sin \theta_1 \sin \theta + \cos \theta_1 \cos \theta \cos \varphi]$$

$$v_{\xi} = v_n \cos \alpha + v_s \cos \beta$$

$$\cos \alpha = \cos \theta \cos \theta_1 + \sin \theta \sin \theta_1 \cos \varphi$$

$$\cos \beta = \cos \theta \sin \theta_1 + \sin \theta \cos \theta_1 \cos \varphi$$

$$= \cos \theta \sin \theta_1 - \sin \theta \cos \theta_1 \cos \varphi - \cos \theta_1$$

$$\sin \theta$$

$$\cos \beta = -\sin \theta \cos \theta_1 + \sin \theta_1 \cos \theta \cos \varphi$$

$$v_{\xi} = v_n (\cos \theta \cos \theta_1 + \sin \theta \sin \theta_1 \cos \varphi) + v_s (-\sin \theta \cos \theta_1 + \sin \theta_1 \cos \theta \cos \varphi)$$

$$v_{\xi} = \cos \theta_1 (v_n \cos \theta - v_s \sin \theta) + \sin \theta_1 (v_n \sin \theta + v_s \cos \theta) \cos \varphi$$

$$\Delta^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} + \frac{1}{r^2 \sin \theta} \frac{\partial^2}{\partial \theta^2} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} + \frac{\cos \theta}{r^2 \sin \theta} \frac{\partial}{\partial \theta}$$

$$\Delta^2 v_{\xi} = \cos \theta_1 \left[ \frac{\partial^2 v_n}{\partial r^2} \cos \theta - \frac{\partial^2 v_s}{\partial r^2} \sin \theta \right] + \sin \theta_1 \left[ \frac{\partial^2 v_n}{\partial r^2} \sin \theta + \frac{\partial^2 v_s}{\partial r^2} \cos \theta \right] \cos \varphi +$$

$$+ \frac{2}{r} \cos \theta_1 \left[ \frac{\partial v_n}{\partial r} \cos \theta - \frac{\partial v_s}{\partial r} \sin \theta \right] + \frac{2}{r} \sin \theta_1 \left[ \frac{\partial v_n}{\partial r} \sin \theta + \frac{\partial v_s}{\partial r} \cos \theta \right] \cos \varphi +$$

$$- \frac{1}{r^2 \sin \theta} \sin \theta_1 [v_n \sin \theta + v_s \cos \theta] \cos \varphi +$$

$$+ \frac{1}{r^2 \sin \theta} \cos \theta_1 [v_n \cos \theta - v_s \sin \theta] \cos \varphi$$



$$(q_1 \theta_1 + q_2 \theta_2 + \dots + q_n \theta_n) \omega = q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega$$

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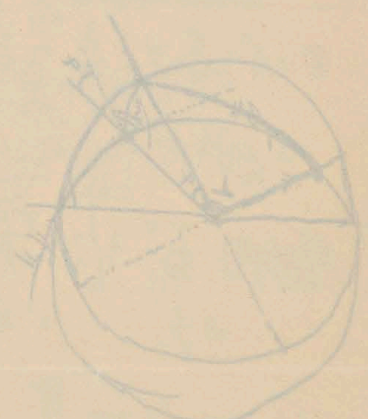


$$\frac{[q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega]}{[q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega]} = 1$$

$$q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega = q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega$$

$$q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega = q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega$$

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$$q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega = q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega$$

$$(q_1 \theta_1 \omega + q_2 \theta_2 \omega + \dots + q_n \theta_n \omega) \omega = q_1 \theta_1 \omega \omega + q_2 \theta_2 \omega \omega + \dots + q_n \theta_n \omega \omega$$

$$q_1 (\theta_1 \omega \omega + \theta_2 \omega \omega + \dots + \theta_n \omega \omega) = q_1 \theta_1 \omega \omega + q_2 \theta_2 \omega \omega + \dots + q_n \theta_n \omega \omega$$

$$\frac{q_1 \theta_1 \omega \omega}{\theta_1 \omega \omega} + \frac{q_2 \theta_2 \omega \omega}{\theta_2 \omega \omega} + \dots + \frac{q_n \theta_n \omega \omega}{\theta_n \omega \omega} = \frac{q_1 \theta_1 \omega \omega}{\theta_1 \omega \omega} + \frac{q_2 \theta_2 \omega \omega}{\theta_2 \omega \omega} + \dots + \frac{q_n \theta_n \omega \omega}{\theta_n \omega \omega}$$

$$+ q_1 \left[ \theta_1 \omega \frac{\omega \omega}{\omega \omega} + \theta_2 \omega \frac{\omega \omega}{\omega \omega} + \dots + \theta_n \omega \frac{\omega \omega}{\omega \omega} \right] = q_1 \left[ \theta_1 \omega \frac{\omega \omega}{\omega \omega} + \theta_2 \omega \frac{\omega \omega}{\omega \omega} + \dots + \theta_n \omega \frac{\omega \omega}{\omega \omega} \right]$$

$$+ q_2 \left[ \theta_1 \omega \frac{\omega \omega}{\omega \omega} + \theta_2 \omega \frac{\omega \omega}{\omega \omega} + \dots + \theta_n \omega \frac{\omega \omega}{\omega \omega} \right] = q_2 \left[ \theta_1 \omega \frac{\omega \omega}{\omega \omega} + \theta_2 \omega \frac{\omega \omega}{\omega \omega} + \dots + \theta_n \omega \frac{\omega \omega}{\omega \omega} \right]$$

$$+ q_n \left[ \theta_1 \omega \frac{\omega \omega}{\omega \omega} + \theta_2 \omega \frac{\omega \omega}{\omega \omega} + \dots + \theta_n \omega \frac{\omega \omega}{\omega \omega} \right] = q_n \left[ \theta_1 \omega \frac{\omega \omega}{\omega \omega} + \theta_2 \omega \frac{\omega \omega}{\omega \omega} + \dots + \theta_n \omega \frac{\omega \omega}{\omega \omega} \right]$$

~~Handwritten scribbles~~





$$v_n = -\cos\theta \left[ 1 - \frac{a^3}{r^3} \right]$$

$$\frac{\partial v_3}{\partial t} = -a_1 \theta \quad \frac{3a^3}{2^4}$$

$$\frac{\delta^2 v_1}{\delta \theta^2} = + \cot \theta \frac{12a^3}{25}$$

$$\frac{\partial v_n}{\partial \theta} = + \sin \theta \left[ 1 - \frac{\theta^2}{2} \right]$$

$$\frac{\partial^2 r_n}{\partial \theta^2} = + \omega^2 \left[ 1 - \frac{\sigma^2}{v^2} \right]$$

$$v_o = + \frac{3}{2} \sin \theta$$

$$\frac{\partial r_1}{\partial \theta} = \frac{3}{2} \cos \theta$$

$$\Delta^2 v_f = +12 \frac{\omega^2}{a^2} - \frac{6\omega^2}{a^2} - \frac{3\omega^2}{a^2} - \frac{3}{a^2} \omega^2 = 0$$

Względne ~~z~~ ~~na~~ ~~pr~~ ~~z~~ prędkości (gdzie  $v=0$ ):

$$\Delta^2 v \zeta = \frac{\partial^2 v_n}{\partial r^2} + \frac{2}{a} \frac{\partial v_n}{\partial r}$$

$$\Delta^2 v_{\xi} = \frac{\partial^2 v_{\xi}}{\partial r^2} + \frac{1}{a} \frac{\partial v_{\xi}}{\partial r}$$

$$v_s = \sin \theta \left[ \frac{r}{a} + \frac{a^2}{2r^2} \right]$$

$$\frac{\partial v_s}{\partial r} = \sin \theta \left[ \frac{1}{a} - \frac{2a^2}{r^3} \right]$$

$$\frac{\partial^2 v}{\partial x^2} = \kappa \theta \left[ \frac{3\sigma^2}{2^4} \right]$$

$$\frac{\partial v_s}{\partial \theta} = \cos \theta [ \quad ]$$

$$\frac{\partial^2 v_i}{\partial x^2} = -v_i \quad [ \quad ]$$

$$\Delta^2 v = \frac{3}{a^2} \sin \theta - \frac{3}{2a^2} \frac{\sin \theta}{\sin^2 \theta} = \frac{\sin \theta}{a^2} \frac{3}{2} + \frac{1}{a^2} \frac{3}{2} \frac{1}{\sin} \quad \text{✓}$$

$$= \frac{\sin \theta}{a^2} \left[ \cancel{\frac{3}{2}} - \frac{3}{2 \sin^2} + \frac{3}{2} \frac{\cos^2}{\sin^2} \right] = \cancel{\frac{3}{2} \frac{1}{a^2 \sin}} [0] = 0$$



$$\cos\theta_1 \left[ \frac{\partial v_n}{\partial\theta} \cos\theta - \frac{\partial v_s}{\partial\theta} \sin\theta \right] + \sin\theta_1 \left[ \frac{\partial v_n}{\partial\theta} \sin\theta + \frac{\partial v_s}{\partial\theta} \cos\theta \right] \cos\varphi$$

$$- v_n \sin\theta - v_s \cos\theta \quad + v_n \cos\theta + v_s \sin\theta$$

$$\frac{\cos\theta_1}{a^2 \sin\theta_1} \left[ \frac{\partial v_n}{\partial\theta} (\cos^2\theta_1 + \sin^2\theta_1 \cos\varphi) - \frac{\partial v_s}{\partial\theta} (1 - \cos\varphi) \sin\theta_1 \cos\theta_1 - v_n \sin\theta_1 \cos\theta_1 (1 - \cos\varphi) + v_s (\cos^2\theta_1 + \sin^2\theta_1 \cos\varphi) \right]$$

$$\cos\theta_1 \left[ \frac{\partial^2 v_n}{\partial\theta^2} \cos\theta - \frac{\partial^2 v_s}{\partial\theta^2} \sin\theta \right] + \sin\theta_1 \cos\varphi \left[ \frac{\partial^2 v_n}{\partial\theta^2} \sin\theta + \frac{\partial^2 v_s}{\partial\theta^2} \cos\theta \right]$$

$$- 2 \frac{\partial v_n}{\partial\theta} \sin\theta - 2 \frac{\partial v_s}{\partial\theta} \cos\theta \quad + 2 \frac{\partial v_n}{\partial\theta} \cos\theta - 2 \frac{\partial v_s}{\partial\theta} \sin\theta$$

$$- v_n \cos\theta + v_s \sin\theta \quad - v_n \sin\theta - v_s \cos\theta$$

$$\frac{1}{a^2} \left\{ \frac{\partial^2 v_n}{\partial\theta^2} (\cos^2\theta_1 + \sin^2\theta_1 \cos\varphi) - \frac{\partial^2 v_s}{\partial\theta^2} (1 - \cos\varphi) \sin\theta_1 \cos\theta_1 - 2 \frac{\partial v_n}{\partial\theta} \sin\theta_1 \cos\theta_1 (1 - \cos\varphi) - 2 \frac{\partial v_s}{\partial\theta} (\cos\theta_1 + \sin\theta_1 \cos\varphi) - v_n (\cos\theta_1 + \sin\theta_1 \cos\varphi) + v_s \sin\theta_1 \cos\theta_1 (1 - \cos\varphi) \right\}$$

$\varphi=0 \parallel \cos\varphi=1$

$$\cos\theta_1 + \sin\theta_1 \cos\varphi = 1$$

$$\Delta^2 v_z = \frac{\partial^2 v_n}{\partial r^2} + \frac{2}{a} \frac{\partial v_n}{\partial r} - \frac{v_n}{a^2} - \frac{v_s}{a^2} \cot\theta_1 + \frac{1}{a^2} \left( \frac{\partial^2 v_n}{\partial\theta^2} - 2 \frac{\partial v_n}{\partial\theta} - v_n \right)$$

$$+ \frac{1}{a^2} \cot\theta_1 \left[ \frac{\partial v_n}{\partial\theta} - v_s \right]$$

$$\Delta^2 v_z = \frac{\partial^2 v_n}{\partial r^2} + \frac{2}{a} \frac{\partial v_n}{\partial r} - \frac{2v_n}{a^2} + \frac{1}{a^2} \frac{\partial^2 v_n}{\partial\theta^2} + \frac{1}{a^2} \cot\theta_1 \frac{\partial v_n}{\partial\theta} - \frac{2v_s}{a^2} \cot\theta_1 - \frac{2}{a^2} \frac{\partial v_s}{\partial\theta}$$

$$\text{für } v_n=0 \quad \frac{\partial v_n}{\partial r} \odot \delta \quad \frac{\partial^2 v_n}{\partial r^2} \odot 1 = \frac{\partial^2 v_n}{\partial r^2} + \left( \frac{2}{a} + \frac{2v_n}{a^2} \right) \frac{\partial v_n}{\partial r} + \frac{2v_n}{a^2} + \frac{1}{a^2} \frac{\partial^2 v_n}{\partial\theta^2} + \frac{1}{a^2} \cot\theta_1 \frac{\partial v_n}{\partial\theta}$$

$$\Delta^2 v_z = \frac{\partial^2 v_n}{\partial r^2} - \frac{2v_s}{a^2} \cot\theta_1 - \frac{2}{a} \frac{\partial v_s}{\partial\theta}$$



$$\Delta^2 v_f = \frac{\partial^2 v_s}{\partial r^2} + \frac{2}{a} \frac{\partial v_s}{\partial r} + 1$$

$$= \frac{1}{a^2 \sin^2 \theta} [v_n \cos \theta, \sin \theta, + v_s \sin^2 \theta]$$

$$+ \frac{\cos \theta}{a^2 \sin^2 \theta} \left\{ \frac{\partial v_n}{\partial \theta} [-\sin \theta, \cos \theta + \cos \theta, \sin \theta \cos \theta] + \frac{\partial v_s}{\partial \theta} [\sin \theta, \cos \theta + \cos \theta, \sin \theta \cos \theta] \right. \\ \left. + v_n [\sin \theta, \sin \theta + \cos \theta, \cos \theta \cos \theta] + v_s [\sin \theta, \cos \theta - \cos \theta, \sin \theta \cos \theta] \right\}$$

$$+ \frac{1}{a^2} \left\{ \frac{\partial^2 v_s}{\partial \theta^2} + 2 \frac{\partial v_n}{\partial \theta} [\sin^2 \theta + \cos^2 \theta, \cos \theta] + \frac{\partial^2 v_s}{\partial \theta^2} + v_n \cos \theta + v_s (\sin^2 \theta + \cos^2 \theta \cos \theta) \right\}$$

$$= \frac{\partial^2 v_s}{\partial r^2} + \frac{2}{a} \frac{\partial v_s}{\partial r} - \frac{v_n}{a^2} \frac{d\theta}{dr} + \frac{v_s}{a^2} \frac{d\theta}{dr} + v_n \frac{d\theta}{dr} + \frac{\partial v_s}{\partial \theta} \frac{d\theta}{dr}$$

$$+ \frac{1}{a^2} \frac{\partial^2 v_s}{\partial \theta^2} + \frac{2}{a^2} \frac{\partial v_n}{\partial \theta} - \frac{v_s}{a^2}$$

$$1 + \frac{d\theta}{dr} = 1 + \frac{u}{r} = \frac{1}{r}$$

$$= \frac{\partial^2 v_s}{\partial r^2} + \frac{2}{a} \frac{\partial v_s}{\partial r} - \frac{v_s}{a^2 \sin^2 \theta} + \frac{1}{a^2} \frac{\partial^2 v_s}{\partial \theta^2} + \frac{1}{a^2} \frac{\partial v_n}{\partial \theta} \frac{d\theta}{dr} + \frac{2}{a^2} \frac{\partial v_s}{\partial \theta}$$

Ng. ~~...~~

$$\frac{\partial}{\partial r} (r^2 \frac{\partial v_n}{\partial r} + r^2 \frac{\partial v_s}{\partial r}) + \frac{\partial}{\partial \theta} (r^2 \sin \theta \frac{\partial v_n}{\partial \theta} + r^2 \sin \theta \frac{\partial v_s}{\partial \theta}) = 0$$

$$\sin \theta \frac{\partial}{\partial r} (r^2 \frac{\partial v_n}{\partial r}) + r^2 \frac{\partial}{\partial \theta} (v_n \sin \theta) = 0$$

$$2 \frac{v_n}{r} + r \frac{\partial v_n}{\partial r} + \frac{\partial v_s}{\partial \theta} + v_s \frac{d\theta}{dr} = 0 = \text{div}$$

$$\frac{\cos \theta}{r} = - \frac{u}{r} = -1$$

$$\frac{\partial}{\partial \theta} : \frac{2 \partial v_n}{a^2} + \frac{2}{a^2} \frac{\partial^2 v_n}{\partial \theta^2} + \frac{\partial^2 v_s}{a^2 \partial \theta^2} + \frac{\partial v_s}{a^2 \partial \theta} \frac{d\theta}{dr} - \frac{v_s}{a^2 \sin^2 \theta} = 0$$

$$\Delta^2 v_f = \frac{\partial^2 v_s}{\partial r^2} + \frac{2}{a} \frac{\partial v_s}{\partial r} - \frac{r}{a^2} \frac{\partial^2 v_n}{\partial \theta^2}$$



$$\frac{\partial u}{\partial x} = \mu \nabla u + \frac{\rho}{\kappa_1} \frac{x}{2}$$

$$\frac{\partial u}{\partial y} = \mu \nabla v + \frac{\rho}{\kappa_2} \frac{y}{2}$$

$$\nabla^2 u = \mu \nabla^2 u + \frac{\rho}{\kappa_1} \frac{x}{2}$$

$$\frac{\partial u}{\partial x} = \mu \nabla u + \frac{\rho}{\kappa_1} \frac{x}{2}$$

$$\rho \left( \frac{\partial u}{\partial x} + \right) + u \frac{\partial \rho}{\partial x} + v \frac{\partial \rho}{\partial y} + w \frac{\partial \rho}{\partial z} = 0 \quad 321$$

$$\left( u \frac{\partial}{\partial x} + \right) - \frac{k}{\kappa_1} \rho \left( u \frac{\partial}{\partial x} + \right) + \mu \phi + u \Delta \theta = 0$$

$$\frac{1}{a} \left[ r^2 + \frac{b}{a} \log(a r^2 - b) \right] = \frac{1}{a} \left[ r_1^2 - r_2^2 + \frac{b}{a} \log \left( \frac{a r_1^2 - b}{a r_2^2 - b} \right) \right] \frac{x}{l} + \frac{1}{a} \left[ r_1^2 + \frac{b}{a} \log(a r_1^2 - b) \right]$$

$$r^2 - r_1^2 + \frac{b}{a} \log \frac{a r^2 - b}{a r_1^2 - b} = \left[ r_1^2 - r_2^2 + \frac{b}{a} \log \frac{a r_1^2 - b}{a r_2^2 - b} \right] \frac{x}{l}$$

$$2r \int \rho u r dr = \frac{2r}{2} \int r^2 dr \quad \frac{2r}{2} \int \frac{r^2 - \delta^2}{4} \rho \frac{dr}{dx} r dr$$

$$= \frac{2r}{2} \int r dr \left[ \theta_0 - \frac{(\delta^2 - r^2)^2}{16 \mu \kappa} \left( \frac{r_1^2 - r_2^2}{l} \right) \frac{1}{r^2} \right] \frac{(r^2 - \delta^2)}{2r} + \frac{1}{\theta_0} \left[ r_1^2 - r_2^2 + \frac{b}{a} \log \left( \frac{a r_1^2 - b}{a r_2^2 - b} \right) \right]$$

$$\log(a r^2 - b) = \log a r^2 + \log \left( 1 - \frac{b}{a r^2} \right) = \log(a r^2) - \frac{b}{a r^2}$$

$$u^2 = \frac{(y \delta - y^2)^2 c^2}{16 \mu^2 (a - cx)}$$

$$\frac{(y \delta - y^2)^2 c^3}{16 \mu^2 (a - cx)^2 R u}$$

$$\frac{1}{\rho} \frac{\partial u}{\partial x} = \frac{R \theta}{\kappa} \frac{\partial u}{\partial x}$$

$$= \frac{R \theta (r^2 - \delta^2) c^2}{16 \mu \sqrt{\quad}^3 \sqrt{\quad}}$$

$$\frac{R \theta c^2 (r^2 - \delta^2)}{16 \mu (a - cx)^2} = \frac{(y \delta - y^2)^2 c^2}{4 \mu (a - cx)}$$

$$\frac{\partial (u^2)}{\partial x} = \frac{(r^2 - \delta^2)^2 c^3}{16 \mu^2 (a - cx)^2} \parallel r dr$$

$$\int \frac{\partial u}{\partial x} \cdot u r dr = \frac{r^2 - \delta^2 \cdot c^3}{(a - cx)^2}$$

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$$\int \rho u r dr = \frac{k}{\kappa_1} \frac{R \theta}{\theta} \frac{c \sqrt{r^2 - \delta^2} r dr}{\sqrt{\quad}}$$

